Bayesian Optimization

ML procedure

https://ichi.pro/ko/meosin-leoning-ui-yuhyeong-gwa-jeolcha-9596720397791

Model Improvement (Model Tuning)

- Goal
 - Enhance the performance of the model
- Methods
 - Prepare and use more data: need cost
 - Try another (deep learning) model: very academic
 - Adjust hyperparameters: time consuming

Hyperparameters

- Used for learning (training)
- Need to be set before training
 - Learning rate
 - Number of layers
 - Batch size
 - Optimizer: SGD, momentum, adam
 - Activation functions: sigmoid, tanh, ReLu

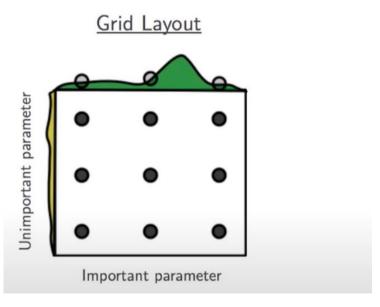
Why tuning (optimizing) hyperparameter?

- Achieve high performance
- Reproducibility of published results
- Automatic tuning is required
- For non-expert users

Prof. Hyerim Bae (nroae@pusa

Searching parameters

What if we search all



```
model = KerasClassifier()

learning_rate = [0.001, 0.005, 0.01]
momentum = [0.9, 0.95, 0.97]

param_grid = dict(lr=learning_rate, m=momentum)

grid = GridSearchCV(model, param_grid)
grid.fit(X, Y)
```

Prof. Hyerim Bae (hrbae@pusan.

Hyper parameter Tuning Method based on Sampling for Optimal LSTM model (2019)

- Hyperparameter List
 - Learning rate (constant)
 - Optimizer (categorical)
 - Activation function of output layer (categorical)
- 1. Searching Order and searching space
 - 1 Learning rate
 - : 0.01, 0.005, 0.001
 - Optimizer
 - : SGD, Adam
- 2. Do experiments with each combinations
 - For one combination, do n-th experiments
 - Sampling to get the distribution of combination

		Learning rate			
		0.01	0.005	0.001	
Optimizer	SGD	Comb.1	Comb.2	Comb.3	
	Adam	Comb.4	Comb.5	Comb.6	

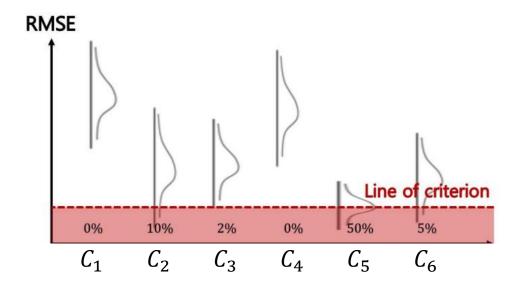
Hyper parameter Tuning Method based on Sampling for Optimal LSTM model (2019)

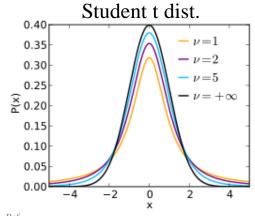
3. Estimate a distribution of the combination

- Assume student t distribution
- Use the RMSE(performance measure) as sample of dist.

4. Determine a criteria for selecting combinations

- Get set of means from the combination's distributions
- Determine a criteria as min value of the mean set



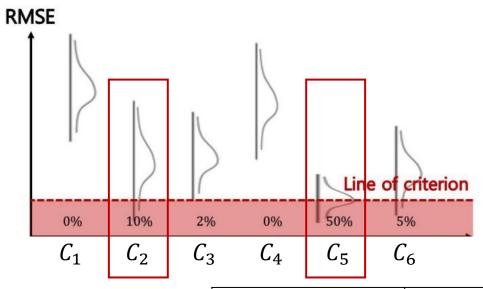


Net: Wikipedia(https://ko.wikipedia.org/wiki/%EC%8A%A4%ED%8A%9C%EB%8D%98%ED%8A%B8_t_%EB%B6%84%ED%8F%AC)

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Hyper parameter Tuning Method based on Sampling for Optimal LSTM model (2019)

- 5. Select the combinations for next step
 - If the measure can exist under the criteria, use the combinations next step
 - Measure can exist = the probability is over the 10% (arbitrary prob.) = C_2 , C_5



- 6. Consider one more hyperparameter
 - Activation function of output layer: Relu, tanh, sigmoid

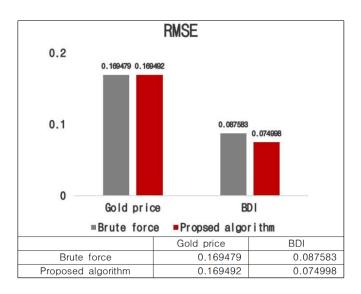
		Activation function		
		Relu	tanh	sigmoid
Combination	Comb.2	Comb2-1	Comb2-2	Comb2-3
	Comb.5	Comb2-4	Comb2-5	Comb2-6

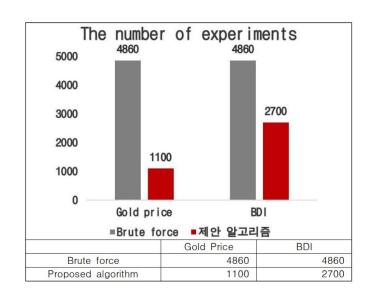
7. Repeat 2~6 until all hyperparameter is considered

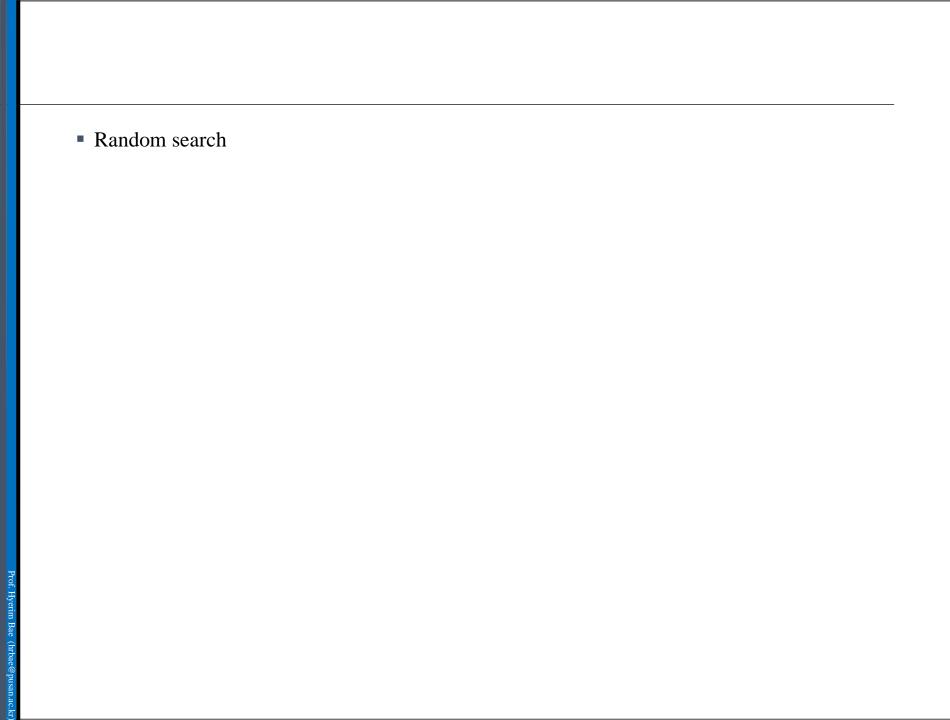
Hyper parameter Tuning Method based on Sampling for Optimal LSTM model (2019)

Performance

- RMSE is similar with Brute force
 - Success to find the best combination of hyperparameters
- The number of experiments is quite smaller than Brute force
 - More efficiency than Brute force to find the best solution

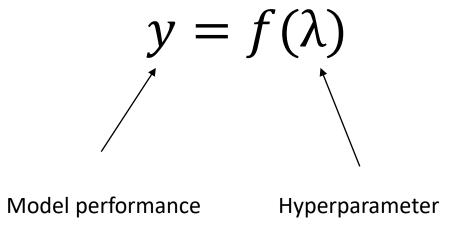






Optimizing hyperparameters

• Finding hyperparameter which optimizes the performance



Black-box optimization

Features

- Objective function is unknown
- Cannot use gradient (differentiation)
- Costly



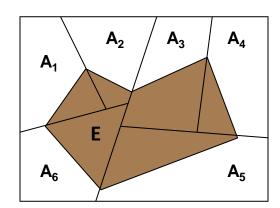
Bayesian Optimization for hyper-parameter tuning

- Estimate f(x) from data
 - Using Bayes theorem
 - By Gaussian Process

Bayes Rule

$$p(A|B) = \frac{p(A,B)}{p(B)} = \frac{p(B|A)p(A)}{p(B)}$$

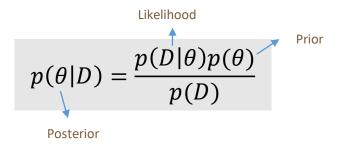
$$p(A_i|E) = \frac{p(E|A_i)p(A_i)}{P(E)} = \frac{p(E|A_i)p(A_i)}{\sum_i p(E|A_i)p(A_i)}$$



- Based on the definition of conditional probability
 - p(A_i|E) is posterior probability given evidence E
 - p(A_i) is the prior probability
 - $P(E|A_i)$ is the likelihood of the evidence given A_i
 - p(E) is the preposterior probability of the evidence

Bayesian inference

• Let's see the rule again





man or woman?

p(man|long hair)





Source: https://brunch.co.kr/@chris-song/59

Bayesian optimization

■ "베이지안스럽게 최적화하기"

$$p(\theta|D) = \frac{p(D|\theta)p(\theta)}{p(D)}$$
Posterior

• $P(Model|Data) \cong P(Data|Model) \times P(Model)$

for i=1,2,... do
estimate parameters from data
recommend next input
generate data from model and add
end for

bayes' theorem을 살펴보면

posterior ∝ likelihood × prior

이고

 $P(Model \mid Data) \propto P(Data \mid Model) \times P(Model)$

이 된다.

즉, 현재까지 얻어진 모델 (prior)과 추가적인 실험 정보 (likelihood)를 통해 데이터가 주어졌을 때의 모델(Posterior)을 추정해나가는 방식이며 알고리즘은 다음과 같다.

(몇가지 초기 입력-결과값 데이터가 주어졌을 때)

for t = 1, 2, ... do

- 1, 얻어진 데이터를 토대로 모델을 추정한다.
- 2. 추정된 모델을 토대로 '모델 추정에 가장 유용할만한' 다음 입력값을 추천한다.
- 3. 모델에 추천된 입력값을 넣어 결과값을 얻어내고, 이를 기존 데이터에 추가한다. end for

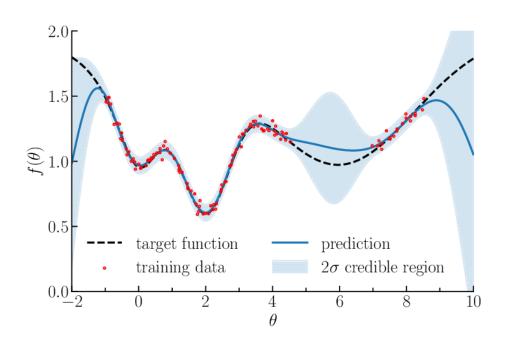
Gaussian Process

Gaussian Distribution

- Random variables
- Mean, Variance(Standard deviation)

Gaussian Process

- Gaussian distribution for a function
- Mean function: $\mu(x)$
- Covariance function: k(x, x')



Sources: Florent Leclercq, "Bayesian optimization for likelihood-free cosmological inference"

Gaussian Process Regression

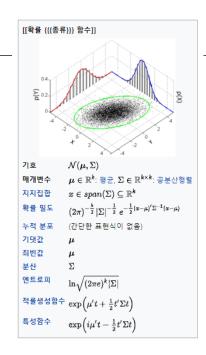
- In a regression function, y=f(x),
 - If x_1 and x_2 are similar, y_1 and y_2 are similar too.

$$y' = \sum_{i=1}^{N} w(x', x_i) y_i$$

- Weight w is represented as kernel, which can be learned
 - Single-variate: $Y \sim N(\mu, \sigma)$
 - Multi-variate: $Y \sim N(\mu, \Sigma)$

$$\boldsymbol{\Sigma} = \begin{bmatrix} K(X_1, X_1) & K(X_1, X_2) & \dots & K(X_1, X_N) \\ K(X_2, X_1) & K(X_2, X_2) & \dots & K(X_2, X_N) \\ \dots & \dots & \dots & \dots \\ K(X_N, X_1) & K(X_N, X_2) & \dots & K(X_N, X_N) \end{bmatrix}$$

- If $\mu = 0$ $\mu(X') = K(X', \mathbf{X}) \mathbf{\Sigma}^{-1} \mathbf{Y}$ $\sigma^{2}(X') = K(X', X') - K(X', \mathbf{X}) \mathbf{\Sigma}^{-1} K(\mathbf{X}, X')$ $K(x_{i}, x_{i}) = \exp(-1/2 ||x_{i} - x_{i}||^{2})$



$$\begin{split} \begin{pmatrix} \boldsymbol{Y} \\ Y' \end{pmatrix} &\sim \mathcal{N} \bigg(\begin{pmatrix} \boldsymbol{\mu} \\ \boldsymbol{\mu}' \end{pmatrix}, \begin{bmatrix} \boldsymbol{\Sigma} & K(\boldsymbol{X}, X') \\ K(X', \boldsymbol{X}) & K(X', X') \end{bmatrix} \bigg) \\ & Y' | \boldsymbol{Y} \sim \mathcal{N} (\mu_{Y'|\boldsymbol{Y}}, \sigma_{Y'|\boldsymbol{Y}}) \\ & \mu_{Y'|\boldsymbol{Y}} = \boldsymbol{\mu}' + K(X', \boldsymbol{X}) \boldsymbol{\Sigma}^{-1} (\boldsymbol{Y} - \boldsymbol{\mu}), \\ & \sigma_{Y'|\boldsymbol{Y}} = K(X', X') - K(X', \boldsymbol{X}) \boldsymbol{\Sigma}^{-1} K(\boldsymbol{X}, X') \end{split}$$

Training GP

- If we do not know the model (parameter)
 - The model is known to be quadratic,

$$f \sim GP(m,k)$$

$$m(x)=ax^2+bx+c, \ \mathrm{and} k(x,x')=\sigma_y^2\exp(-rac{(x-x')^2}{sl^2})+\sigma_n^2\delta_{ii'}$$

여기서 파라미터 $\theta = \{a,b,c,\sigma_y,\sigma_n,l\}$ 입니다. 최적화는 Log-likelihood를 사용합니다.

$$L = \log p(\mathbf{y}|\mathbf{x}, \theta) = -\frac{1}{2}\log|\Sigma| - \frac{1}{2}(\mathbf{y} - \mu)^T \Sigma^{-1}(\mathbf{y} - \mu) - \frac{n}{2}\log(2\pi)$$

이 식을 각 파라미터에 대해 편미분을 할 수 있습니다.

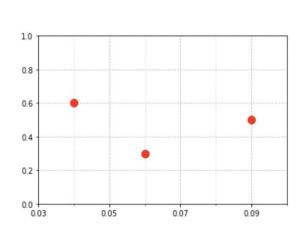
$$\frac{\partial L}{\partial \theta_m} = -(\mathbf{y} - \mu)^T \Sigma^{-1} \frac{\partial m}{\partial \theta_m}$$

$$\frac{\partial L}{\partial \theta_k} = \frac{1}{2} \mathrm{trace}(\Sigma^{-1} \frac{\partial \Sigma}{\partial \theta_k}) + \frac{1}{2} (\mathbf{y} - \mu)^T \frac{\partial \Sigma}{\partial \theta_k} \Sigma^{-1} \frac{\partial \Sigma}{\partial \theta_k} (\mathbf{y} - \mu)$$

여기서 θ_m, θ_k 는 각각 mean, covariance에 대한 파라미터를 의미합니다. 이 파라미터들을 conjugate gradient 방법을 사용하여 최적화하고, 이 때 위의 세 식이 활용될 것입니다.

Exploitation vs. Exploration

- Exploitation
 - 지금 탐색중인 곳을 더 면밀히 탐색
 - Risk of Local optima
- Exploration
 - 더 넓은 탐색



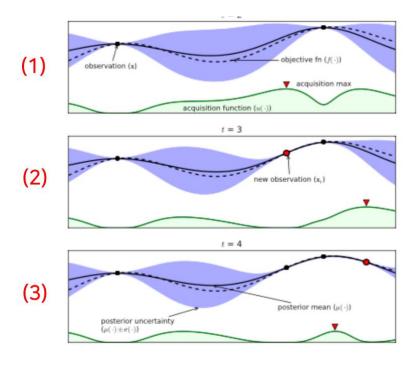


https://www.youtube.com/watch?v=PTxqPfG_IXY&t=284s

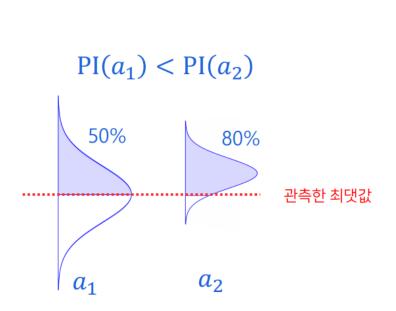
Acquisition function

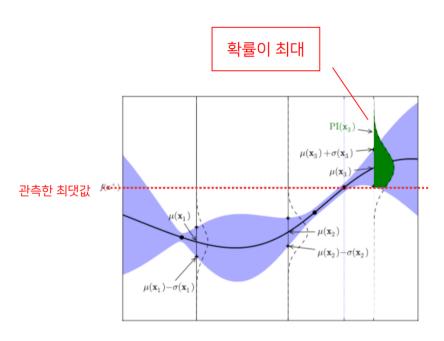
- How to get the next data?
- Exploitation
 - High mean
- Exploration
 - High variance

Acquisition function



```
for i = 1, 2, 3, ... do  find \ x_t \quad over \ GP : \ x_t = \textit{argmax} \ u(x | D_{t-1})  sample the objective function: y_t = f(x_t) + \varepsilon_t  augment data D_t = \{ D_{t-1}, \ (x_t, \ y_t) \} and update GP end for
```

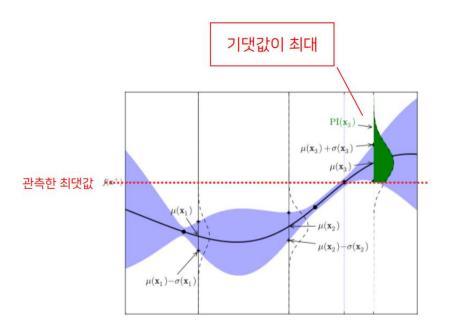




*) Kushner 1964

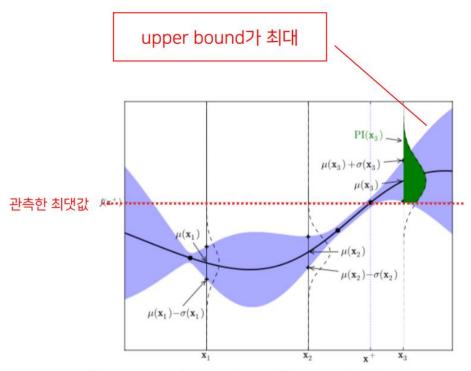
**) https://arxiv.org/pdf/1012.2599.pdf

https://www.youtube.com/watch?v=PTxqPfG_IXY&t=284s



*) Mockus et al, 1978

$$argmax(\mu(x) + k \cdot \sigma(x))$$



*) Srinivas et al, 2010, https://arxiv.org/pdf/0912.3995.pdf

https://www.youtube.com/watch?v=PTxqPfG_IXY&t=284s

$$\mu(x^*) = k^T K^{-1} f_{1:t}$$

$$\sigma^2(x^*) = k(x^*, x^*) - k^T K^{-1} k$$

$$k(x_i, x_j) = \exp(-1/2||x_i - x_j||^2)$$

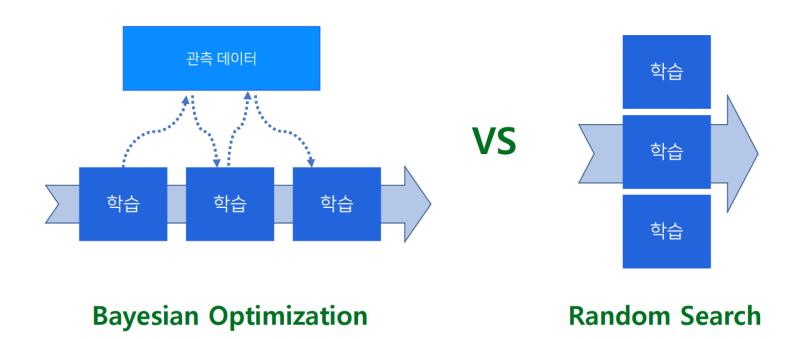
gp = GaussianProcessRegressor ()
gp.fit (data)
mean, std = gp.predict (data_new)

https://www.youtube.com/watch?v=PTxqPfG_IXY&t=284s

```
for i in np.arange(10):
def expected_improvement (mean, std, max):
    z = (mean - max) / std
                                                            model.fit(X, y)
    return (mean-max)*norm.cdf(z) + std*norm.pdf(z)
def f(x):
                                                            xs = np.random.uniform(min_x, max_x, 10000)
    return x * np.sin(x)
                                                            mean, std = model.predict(xs.reshape(-1,1),
                                                        return_std=True)
min_x, max_x = -2, 10
                                                            acq = expected_improvement(mean, std, y.max())
                                                            x \text{ new} = xs[acq.argmax()]
X = np.random.uniform(min_x, max_x, 3).reshape(-
1,1)
                                                            y_new = f(x_new)
y = f(X).ravel()
                                                            X = np.append(X, np.array([x_new])).reshape(-1,1)
model = GaussianProcessRegressor(kernel=RBF(1.0))
                                                            y = np.append(y, np.array([y new]))
```

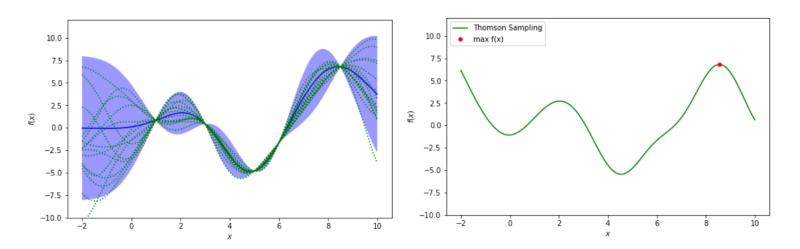
Bayesian Optimization

- Drawback
 - Time Consuming



Acquision Function : Thompson Sampling

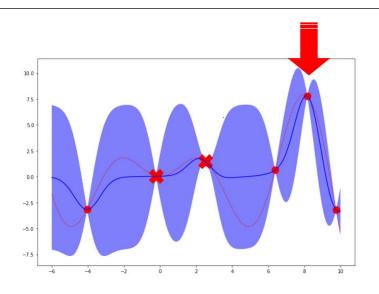
· 사후 분포를 기반으로 샘플링



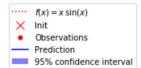
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Performance of BO

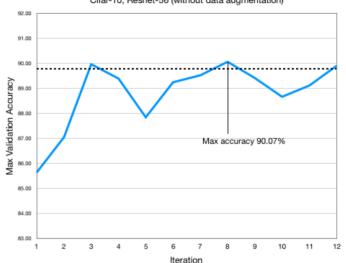
Accuracy on Cifar-10 with Resnet



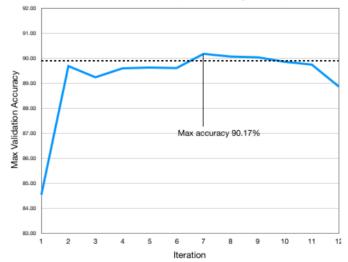
Data Augment	Model	Random	BayesOpt	Baseline (paper)
0	Resnet-110	94.37	94.53	93.57
	Resnet-56	94.37	94.28	93.03
X	Resnet-110	90.09	90.17	_
	Resnet-56	90.01	90.07	-



Bayesian Search Max Accuracy Per Iteration Cifar-10, Resnet-56 (without data augmentation)



Bayesian Search Max Accuracy Per Iteration Cifar-10, Resnet-110 (without data augmentation)



https://www.youtube.com/watch?v=PTxqPfG_IXY&t=284s

Reference

- https://www.youtube.com/watch?v=PTxqPfG_1XY&t=284s
- https://aistory4u.tistory.com/entry/%EA%B0%80%EC%9A%B0%EC%8B%9C%EC%95%88-%ED%94%84%EB%A1%9C%EC%84%B8%EC%8A%A4-%ED%9A%8C%EA%B7%80