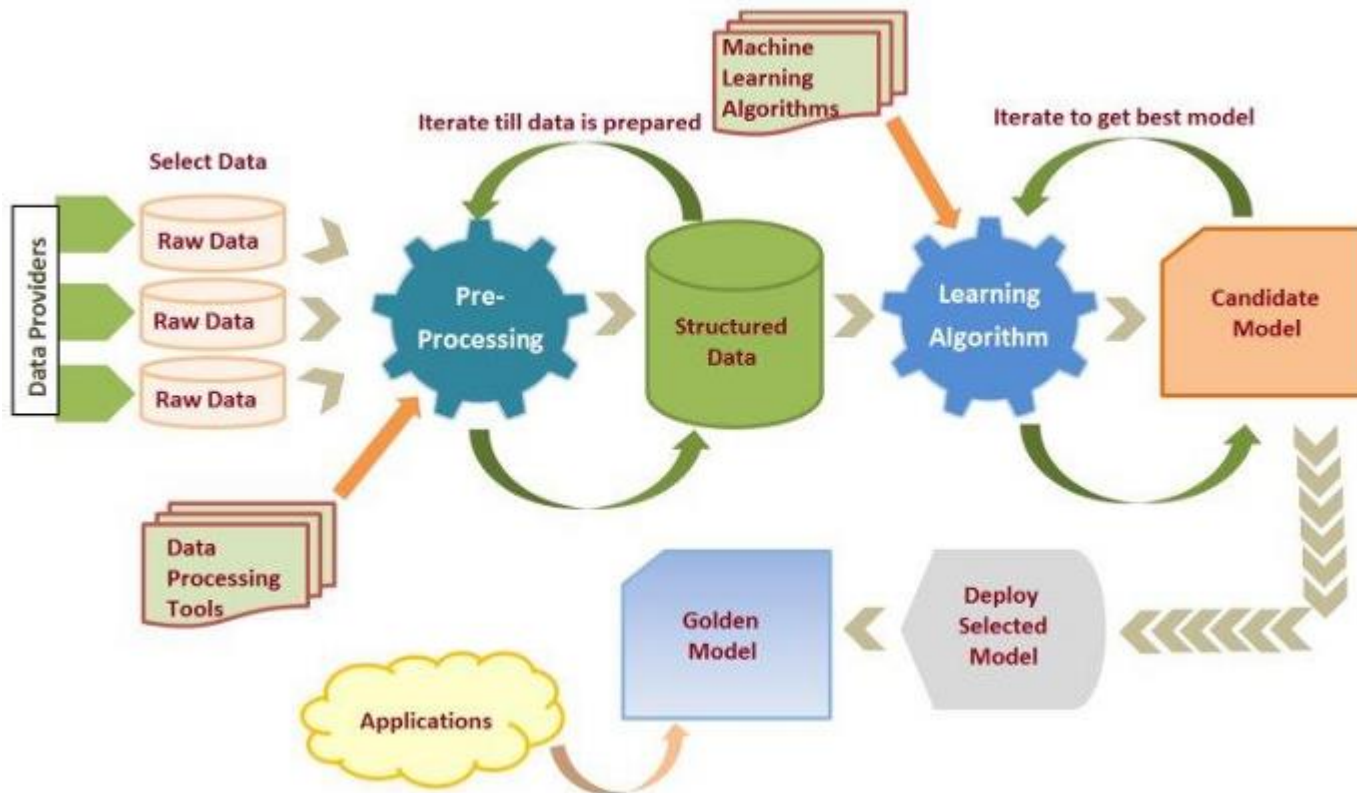




# Bayesian Optimization

# ML procedure



<https://ichi.pro/ko/meosin-leoning-ui-yuhyeong-gwa-jeolcha-9596720397791>

# Model Improvement (Model Tuning)

---

- Goal
  - Enhance the performance of the model
- Methods
  - Prepare and use more data: need cost
  - Try another (deep learning) model: very academic
  - Adjust hyperparameters: time consuming

# Hyperparameters

---

- Used for learning (training)
- Need to be set before training
  - Learning rate
  - Number of layers
  - Batch size
  - Optimizer: SGD, momentum, adam
  - Activation functions: sigmoid, tanh, ReLu

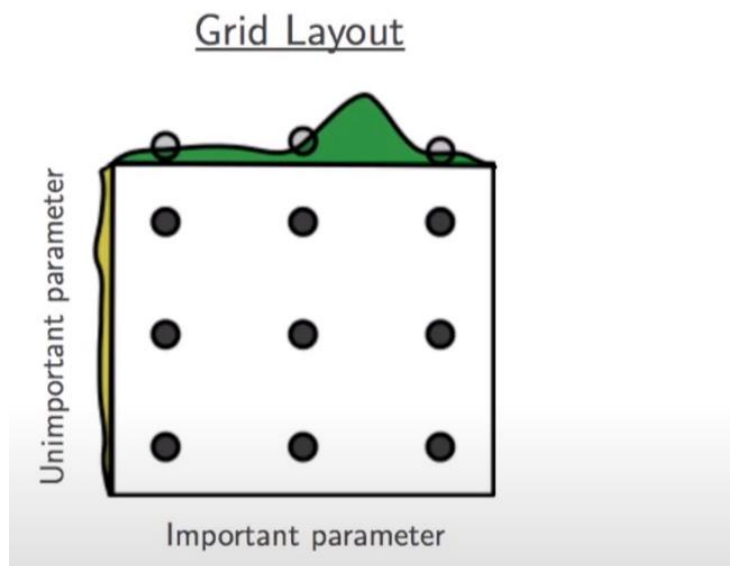
# Why tuning (optimizing) hyperparameter?

---

- Achieve high performance
- Reproducibility of published results
- Automatic tuning is required
- For non-expert users

# Searching parameters

- What if we search all



James Bergstra and Yoshua Bengio (2012)

```
model = KerasClassifier()

learning_rate = [0.001, 0.005, 0.01]
momentum = [0.9, 0.95, 0.97]

param_grid = dict(lr=learning_rate, m=momentum)

grid = GridSearchCV(model, param_grid)
grid.fit(X, Y)
```

# Hyper parameter Tuning Method based on Sampling for Optimal LSTM model(2019)

## ■ Hyperparameter List

- Learning rate (constant)
- Optimizer (categorical)
- Activation function of output layer (categorical)

### 1. Searching Order and searching space

- ① Learning rate  
: 0.01, 0.005, 0.001
- ② Optimizer  
: SGD, Adam

### 2. Do experiments with each combinations

- For one combination, do  $n$ -th experiments
- Sampling to get the distribution of combination

		Learning rate		
		0.01	0.005	0.001
Optimizer	SGD	Comb.1	Comb.2	Comb.3
	Adam	Comb.4	Comb.5	Comb.6

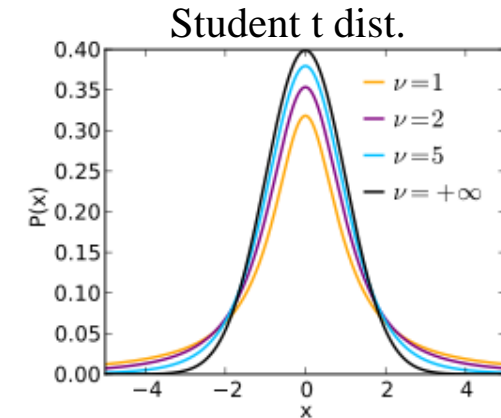
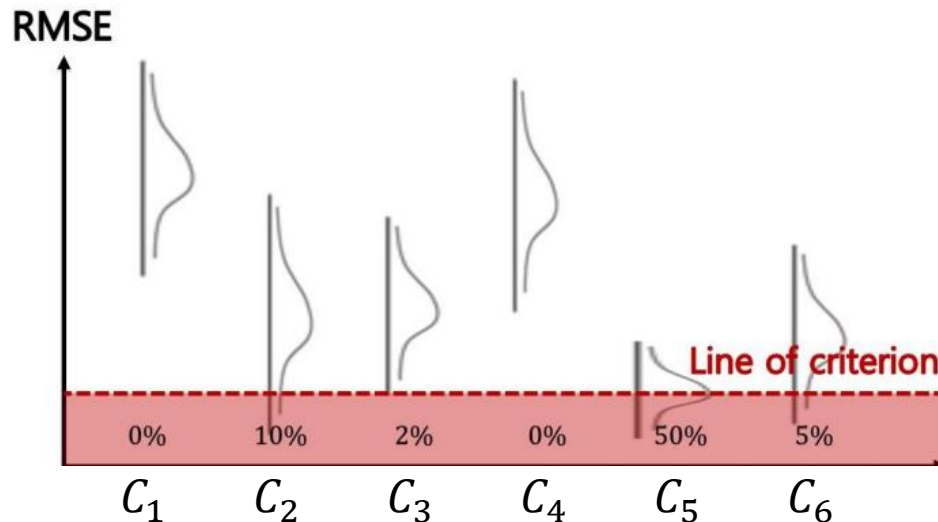
# Hyper parameter Tuning Method based on Sampling for Optimal LSTM model(2019)

## 3. Estimate a distribution of the combination

- Assume student  $t$ -distribution
- Use the RMSE(performance measure) as sample of dist.

## 4. Determine a criteria for selecting combinations

- Get set of means from the combination's distributions
- Determine a criteria as min value of the mean set



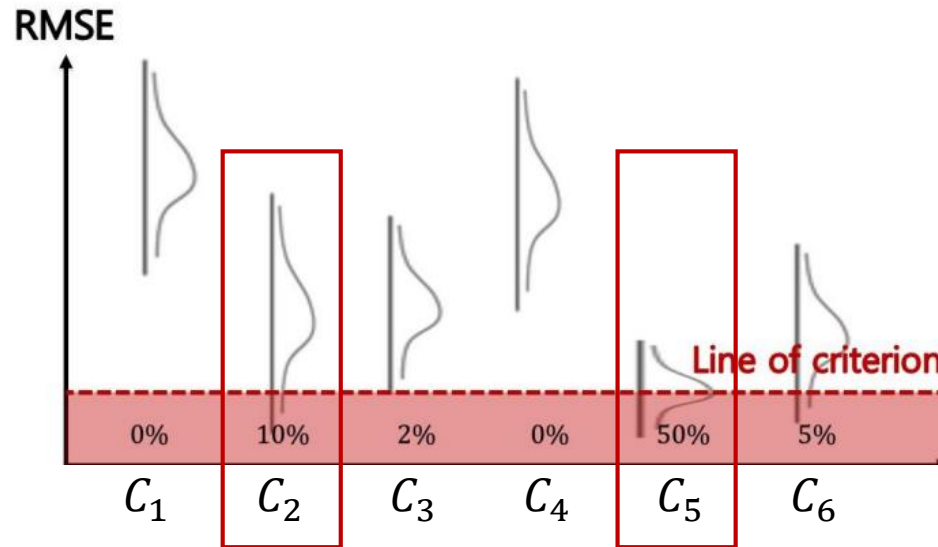
Ref.  
Wikipedia([https://ko.wikipedia.org/wiki/%EC%8A%A4%ED%8A%9C%EB%8D%98%ED%8A%B8\\_t\\_%EB%B6%84%ED%8F%AC](https://ko.wikipedia.org/wiki/%EC%8A%A4%ED%8A%9C%EB%8D%98%ED%8A%B8_t_%EB%B6%84%ED%8F%AC))



# Hyper parameter Tuning Method based on Sampling for Optimal LSTM model(2019)

## 5. Select the combinations for next step

- If the measure can exist under the criteria, use the combinations next step
- Measure can exist = the probability is over the  $\tau$  (for example, 10%) =  $C_2, C_5$



## 6. Consider one more hyperparameter

- Activation function of output layer  
: Relu, tanh, sigmoid

		Activation function		
		Relu	tanh	sigmoid
Combination	Comb.2	Comb2-1	Comb2-2	Comb2-3
	Comb.5	Comb2-4	Comb2-5	Comb2-6

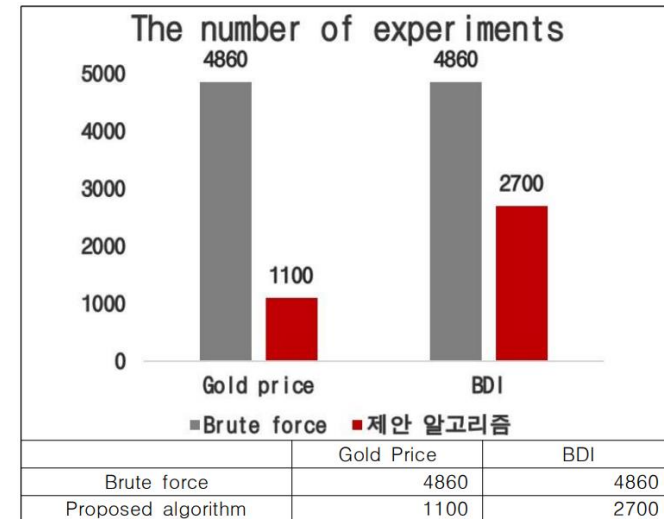
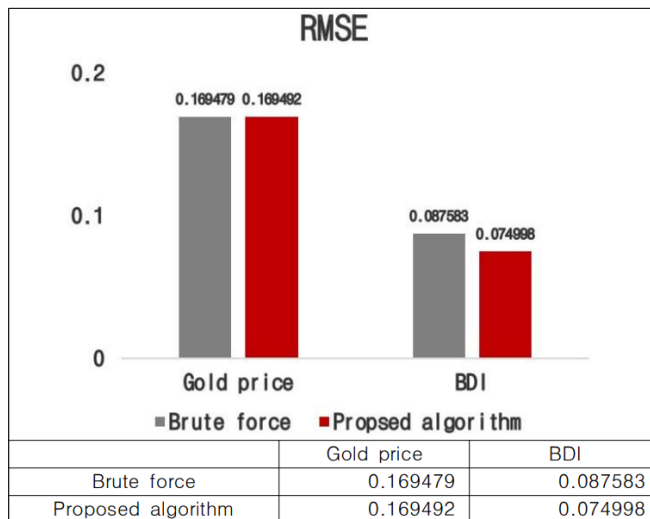
## 7. Repeat 2~6 until all hyperparameter is considered

**Demo 구현 영상**

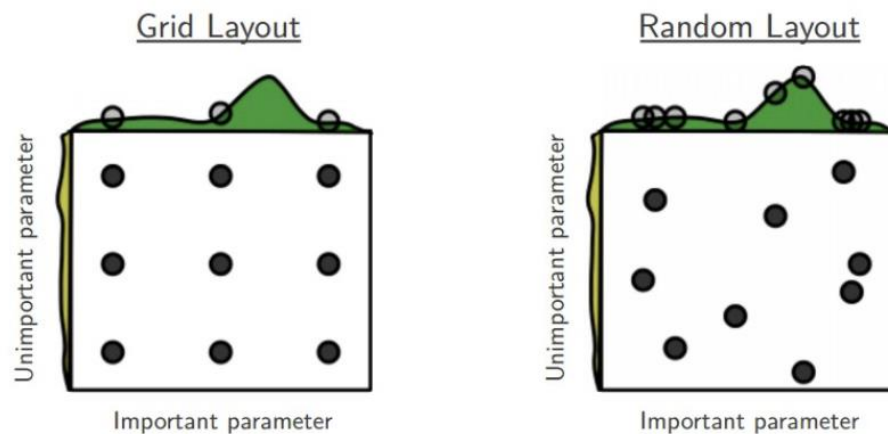
# Hyper parameter Tuning Method based on Sampling for Optimal LSTM model(2019)

## ■ Performance

- RMSE of the proposed method is similar with Brute force
  - Success to find the best combination of hyperparameters
- The number of experiments is quite smaller than Brute force
  - More efficiency than Brute force to find the best solution



- Random search



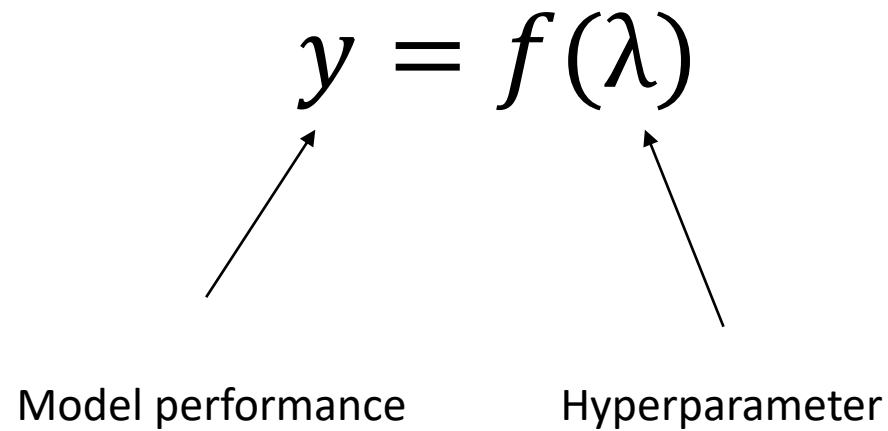
- James Bergstra and Yoshua Bengio (2012)
  - Shows that RS shows better performance than GS
- In order to get top 5% performance
  - How many time do we need to search?

$$1 - (1 - 0.05)^n = 0.95$$

# Optimizing hyperparameters

---

- Finding hyperparameter which optimizes the performance



# Black-box optimization

---

- Features
  - Objective function is unknown
  - Cannot use gradient (differentiation)
  - Costly



# Bayesian Optimization for hyper-parameter tuning

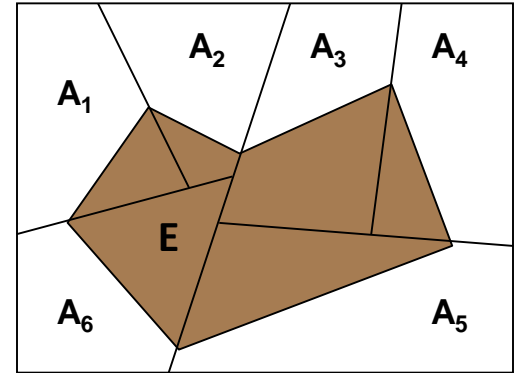
---

- Estimate  $f(x)$  from data
  - Using Bayes theorem
  - By Gaussian Process

# Bayes Rule

$$p(A|B) = \frac{p(A, B)}{p(B)} = \frac{p(B|A)p(A)}{p(B)}$$

$$p(A_i|E) = \frac{p(E|A_i)p(A_i)}{P(E)} = \frac{p(E|A_i)p(A_i)}{\sum_i p(E|A_i)p(A_i)}$$



- Based on the definition of conditional probability
  - $p(A_i|E)$  is posterior probability given evidence E
  - $p(A_i)$  is the prior probability
  - $P(E|A_i)$  is the likelihood of the evidence given  $A_i$
  - $p(E)$  is the preposterior probability of the evidence



# Bayesian inference

- Let's see the rule again

$$p(\theta|D) = \frac{p(D|\theta)p(\theta)}{p(D)}$$

Likelihood

Prior

Posterior



man or woman?

$p(\text{man}|\text{long hair})$



Source: <https://brunch.co.kr/@chris-song/59>

# Bayesian optimization

## ■ “베이지안스럽게 최적화하기”

$$p(\theta|D) = \frac{p(D|\theta)p(\theta)}{p(D)}$$

Likelihood      Prior

Posterior

- $P(\text{Model}|\text{Data}) \cong P(\text{Data}|\text{Model}) \times P(\text{Model})$

for i=1,2,... do

    estimate parameters from data

    recommend next input

    generate data from model and add

end for

bayes' theorem을 살펴보면

$$\text{posterior} \propto \text{likelihood} \times \text{prior}$$

이고

$$P(\text{Model} | \text{Data}) \propto P(\text{Data} | \text{Model}) \times P(\text{Model})$$

이 된다.

즉, 현재까지 얻어진 모델 (prior)과 추가적인 실험 정보 (likelihood)를 통해 데이터가 주어졌을 때의 모델(Posterior)을 추정해나가는 방식이며 알고리즘은 다음과 같다.

(몇가지 초기 입력-결과값 데이터가 주어졌을 때)

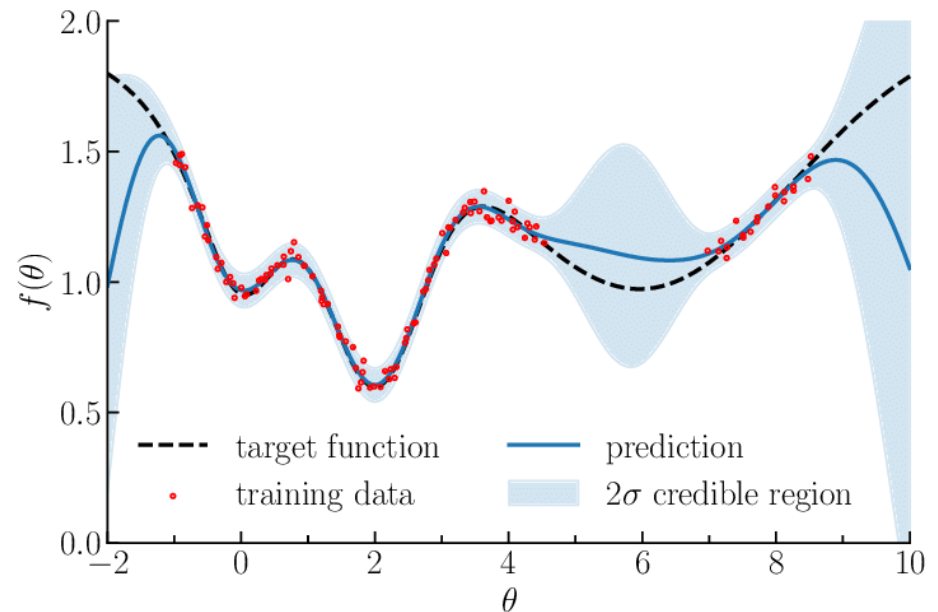
for t = 1, 2, ... do

1. 얻어진 데이터를 토대로 모델을 추정한다.
2. 추정된 모델을 토대로 '모델 추정에 가장 유용할만한' 다음 입력값을 추천한다.
3. 모델에 추천된 입력값을 넣어 결과값을 얻어내고, 이를 기존 데이터에 추가한다.

end for

# Gaussian Process

- Gaussian Distribution
  - Random variables
  - Mean, Variance(Standard deviation)
- Gaussian Process
  - Gaussian distribution for a function
  - Mean function:  $\mu(x)$
  - Covariance function:  $k(x, x')$



Sources: Florent Leclercq, “Bayesian optimization for likelihood-free cosmological inference”

# Gaussian Process Regression

- In a regression function,  $y=f(x)$ ,
  - If  $x_1$  and  $x_2$  are similar,  $y_1$  and  $y_2$  are similar too.

$$y' = \sum_{i=1}^N w(x', x_i) y_i$$

- Weight  $w$  is represented as kernel, which can be learned
  - Single-variate:  $Y \sim N(\mu, \sigma)$
  - Multi-variate:  $\mathbf{Y} \sim N(\boldsymbol{\mu}, \boldsymbol{\Sigma})$

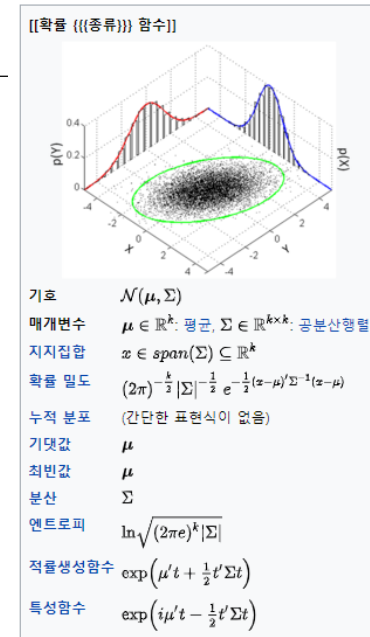
$$\boldsymbol{\Sigma} = \begin{bmatrix} K(X_1, X_1) & K(X_1, X_2) & \dots & K(X_1, X_N) \\ K(X_2, X_1) & K(X_2, X_2) & \dots & K(X_2, X_N) \\ \dots & \dots & \dots & \dots \\ K(X_N, X_1) & K(X_N, X_2) & \dots & K(X_N, X_N) \end{bmatrix}$$

- If  $\mu = 0$

$$\mu(X') = K(X', \mathbf{X}) \boldsymbol{\Sigma}^{-1} \mathbf{Y}$$

$$\sigma^2(X') = K(X', X') - K(X', \mathbf{X}) \boldsymbol{\Sigma}^{-1} K(\mathbf{X}, X')$$

$$K(x_i, x_j) = \exp(-1/2 \|x_i - x_j\|^2)$$



$$\begin{pmatrix} \mathbf{Y} \\ \mathbf{Y}' \end{pmatrix} \sim \mathcal{N}\left(\begin{pmatrix} \boldsymbol{\mu} \\ \boldsymbol{\mu}' \end{pmatrix}, \begin{bmatrix} \boldsymbol{\Sigma} & K(\mathbf{X}, \mathbf{X}') \\ K(\mathbf{X}', \mathbf{X}) & K(\mathbf{X}', \mathbf{X}') \end{bmatrix}\right)$$

$$\mathbf{Y}' | \mathbf{Y} \sim \mathcal{N}(\mu_{Y'|Y}, \sigma_{Y'|Y})$$

$$\begin{aligned} \mu_{Y'|Y} &= \boldsymbol{\mu}' + K(\mathbf{X}', \mathbf{X}) \boldsymbol{\Sigma}^{-1} (\mathbf{Y} - \boldsymbol{\mu}), \\ \sigma_{Y'|Y} &= K(\mathbf{X}', \mathbf{X}') - K(\mathbf{X}', \mathbf{X}) \boldsymbol{\Sigma}^{-1} K(\mathbf{X}, \mathbf{X}') \end{aligned}$$

# Training GP

- If we do not know the model (parameter)
  - The model is known to be quadratic,

$$f_x(x; \mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}} \quad \text{--- (1)}$$

$$L(\mu, \sigma^2; x) = \prod_{i=1}^n \left[ \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x_i-\mu)^2}{2\sigma^2}} \right] \quad \text{--- (2)}$$

$$\begin{aligned} \log L(\mu, \sigma^2; x) &= \sum_{i=1}^n \left[ -\frac{1}{2} \log(2\pi) - \frac{1}{2} \log(\sigma^2) - \frac{1}{2\sigma^2} (x_i - \mu)^2 \right] \\ &= -\frac{n}{2} \log(2\pi) - \frac{n}{2} \log(\sigma^2) - \frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \mu)^2 \quad \text{--- (3)} \end{aligned}$$

$$f \sim GP(m, k)$$

$$m(x) = ax^2 + bx + c, \text{ and } k(x, x') = \sigma_y^2 \exp\left(-\frac{(x-x')^2}{sl^2}\right) + \sigma_n^2 \delta_{ii'}$$

여기서 파라미터  $\theta = \{a, b, c, \sigma_y, \sigma_n, l\}$  입니다. 최적화는 Log-likelihood를 사용합니다.

$$L = \log p(\mathbf{y}|\mathbf{x}, \theta) = -\frac{1}{2} \log |\Sigma| - \frac{1}{2} (\mathbf{y} - \mu)^T \Sigma^{-1} (\mathbf{y} - \mu) - \frac{n}{2} \log(2\pi)$$

이 식을 각 파라미터에 대해 편미분을 할 수 있습니다.

$$\begin{aligned} \frac{\partial L}{\partial \theta_m} &= -(\mathbf{y} - \mu)^T \Sigma^{-1} \frac{\partial \mu}{\partial \theta_m} \\ \frac{\partial L}{\partial \theta_k} &= \frac{1}{2} \text{trace}(\Sigma^{-1} \frac{\partial \Sigma}{\partial \theta_k}) + \frac{1}{2} (\mathbf{y} - \mu)^T \frac{\partial \Sigma}{\partial \theta_k} \Sigma^{-1} \frac{\partial \Sigma}{\partial \theta_k} (\mathbf{y} - \mu) \end{aligned}$$

여기서  $\theta_m, \theta_k$ 는 각각 mean, covariance에 대한 파라미터를 의미합니다. 이 파라미터들을 conjugate gradient 방법을 사용하여 최적화하고, 이 때 위의 세 식이 활용될 것입니다.

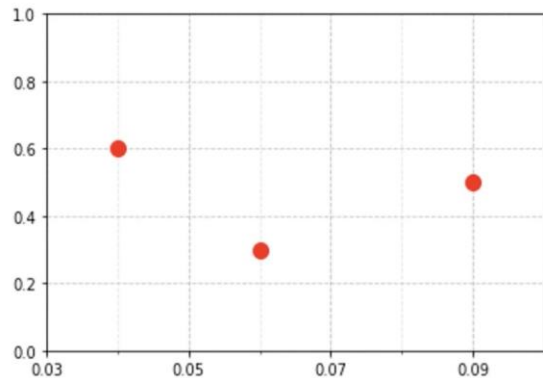
# Exploitation vs. Exploration

---

- Exploitation
  - 지금 탐색중인 곳을 더 면밀히 탐색
  - Risk of Local optima
- Exploration
  - 더 넓은 탐색

# Estimation by Bayesian Optimization

- Estimation of  $f(x)$  from data observed



$x$ : learning\_rate

$f(x)$  : accuracy

0.04

0.6

0.05

?

0.06

0.3

0.08

?

0.09

0.5

[https://www.youtube.com/watch?v=PTxqPfG\\_IXY&t=284s](https://www.youtube.com/watch?v=PTxqPfG_IXY&t=284s)

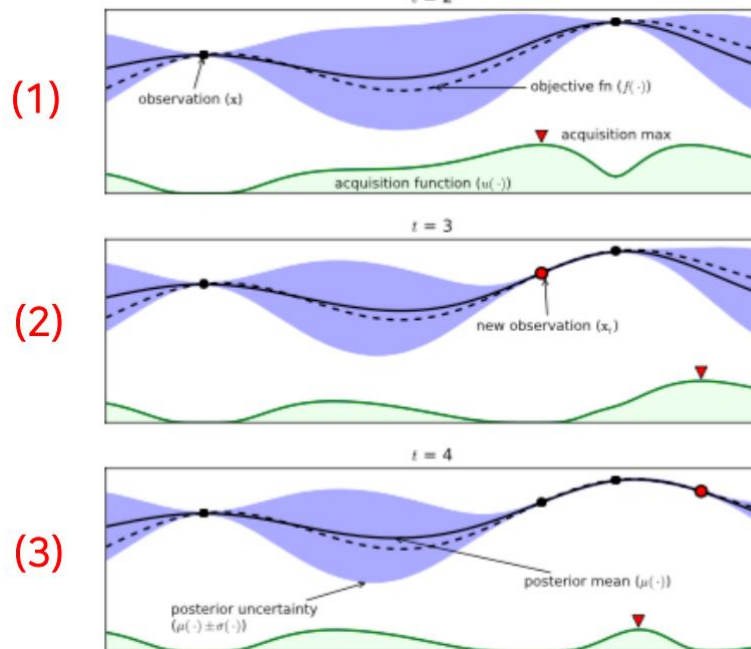
# Acquisition function

---

- How to get the next data?
- Exploitation
  - High mean
- Exploration
  - High variance



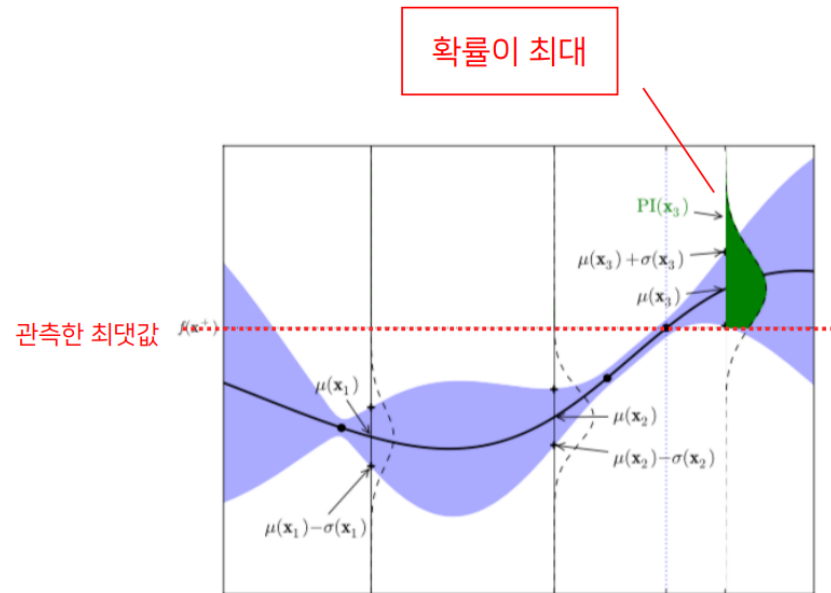
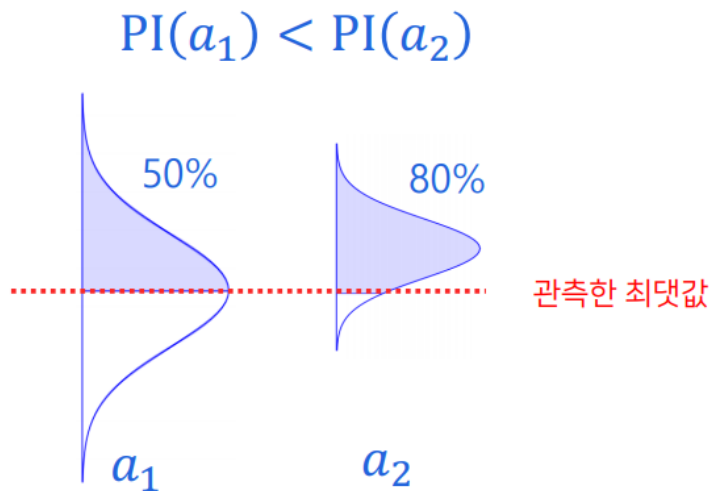
# Acquisition function



```
for i = 1, 2, 3, ... do
    find  $x_t$  over GP :  $x_t = \operatorname{argmax} u(x|D_{t-1})$ 
    sample the objective function:  $y_t = f(x_t) + \varepsilon_t$ 
    augment data  $D_t = \{D_{t-1}, (x_t, y_t)\}$  and update GP
end for
```

# Exploitation

- Probability of Improvement

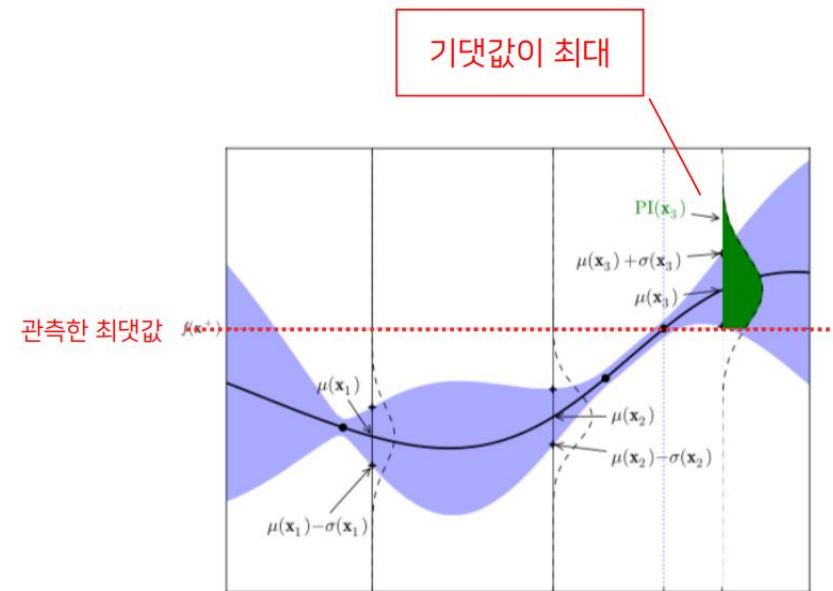
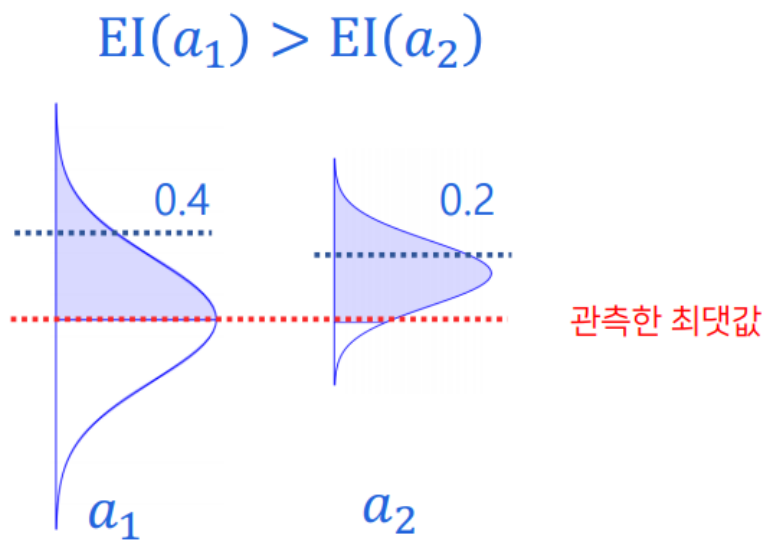


\*) Kushner 1964

\*\*) <https://arxiv.org/pdf/1012.2599.pdf>

[https://www.youtube.com/watch?v=PTxqPfG\\_IXY&t=284s](https://www.youtube.com/watch?v=PTxqPfG_IXY&t=284s)

- Expected Improvement

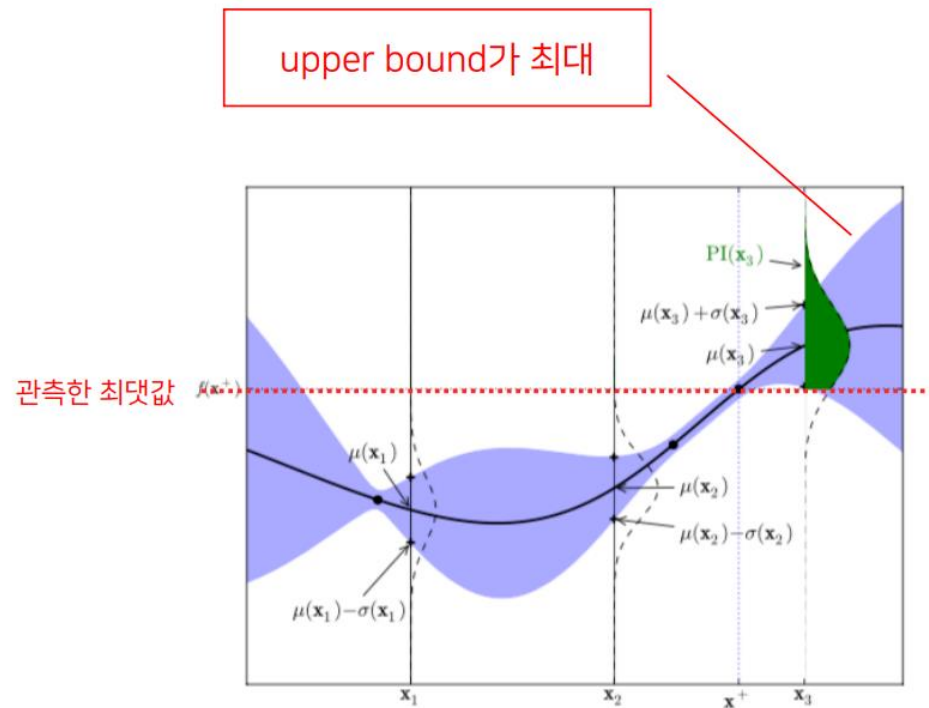


\*) Mockus et al, 1978

[https://www.youtube.com/watch?v=PTxqPfG\\_IXY&t=284s](https://www.youtube.com/watch?v=PTxqPfG_IXY&t=284s)

- Upper Confidence Bound

$$\operatorname{argmax}(\mu(x) + k \cdot \sigma(x))$$



\*) Srinivas et al, 2010, <https://arxiv.org/pdf/0912.3995.pdf>

[https://www.youtube.com/watch?v=PTxqPfG\\_IXY&t=284s](https://www.youtube.com/watch?v=PTxqPfG_IXY&t=284s)

## By GPR

---

- Estimation of mean and variance for a new  $x, x^*$

$$\mu(x^*) = k^T K^{-1} f_{1:t}$$

$$\sigma^2(x^*) = k(x^*, x^*) - k^T K^{-1} k$$

$$k(x_i, x_j) = \exp(-1/2 \|x_i - x_j\|^2)$$

```
gp = GaussianProcessRegressor ( )  
  
gp.fit (data)  
  
mean, std = gp.predict (data_new)
```

[https://www.youtube.com/watch?v=PTxqPfG\\_IXY&t=284s](https://www.youtube.com/watch?v=PTxqPfG_IXY&t=284s)

```

""" 1. Acquisition Function """
def expected_improvement(mean, std, max):
    z = (mean - max) / std
    return (mean-max)*norm.cdf(z) + std*norm.pdf(z)

""" 2. Objective Function """
def f(x):
    return x * np.sin(x)

""" 3. Hyper-Parameter Space """
min_x, max_x = -2, 10

""" 4. Observation Data """
X = np.random.uniform(min_x, max_x, 3).reshape(-1,1)
y = f(X).ravel()

""" 5. Instantiate Gaussian Process model """
model = GaussianProcessRegressor(kernel=RBF(1.0))

```

```

for i in np.arange(10):

    """ 6. Fit to Data """
    model.fit(X, y)

    """ 7. Acquisition Function """
    xs = np.random.uniform(min_x, max_x, 10000)
    mean, std = model.predict(xs.reshape(-1,1),
                             return_std=True)

    acq = expected_improvement(mean, std, y.max())

    """ 8. Query Objective Function """
    x_new = xs[acq.argmax()]
    y_new = f(x_new)

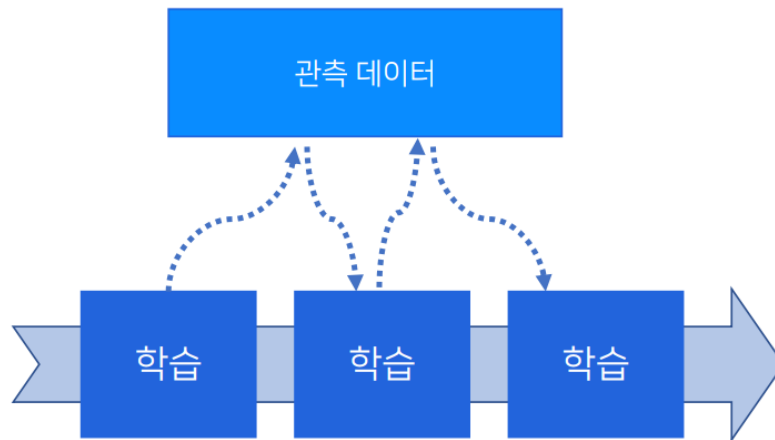
    """ 9. Augment Data """
    X = np.append(X, np.array([x_new])).reshape(-1,1)
    y = np.append(y, np.array([y_new]))

```

[https://www.youtube.com/watch?v=PTxqPfG\\_IXY&t=284s](https://www.youtube.com/watch?v=PTxqPfG_IXY&t=284s)

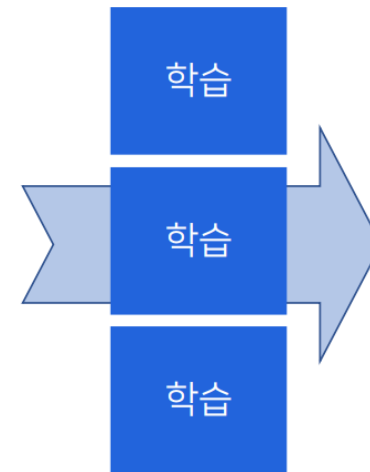
# Bayesian Optimization

- Drawback
  - Time Consuming



**Bayesian Optimization**

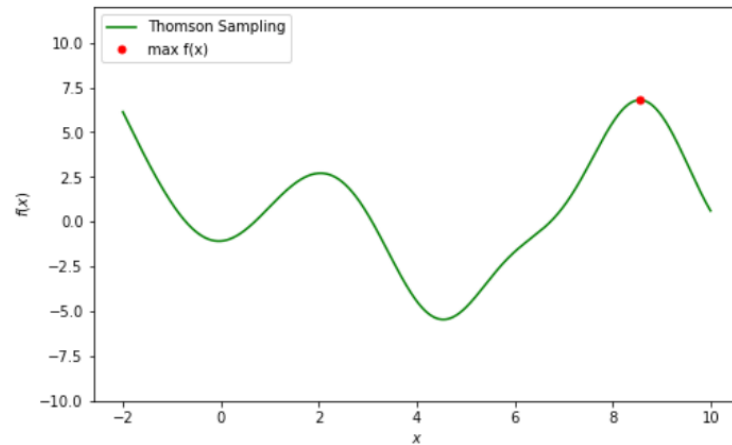
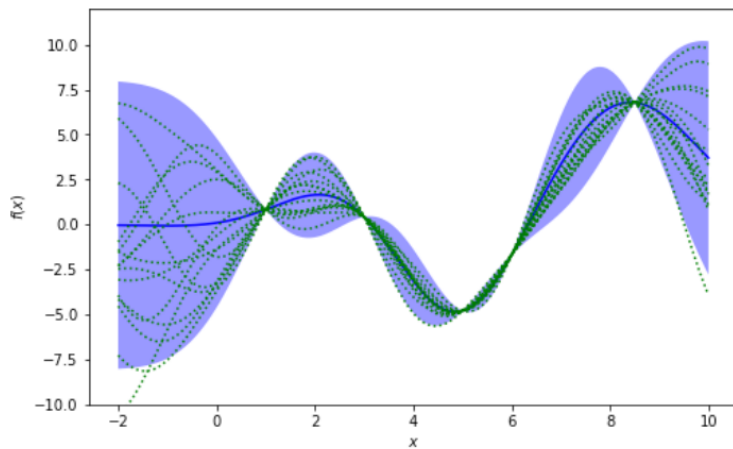
**VS**



**Random Search**

## Acquisition Function : Thompson Sampling

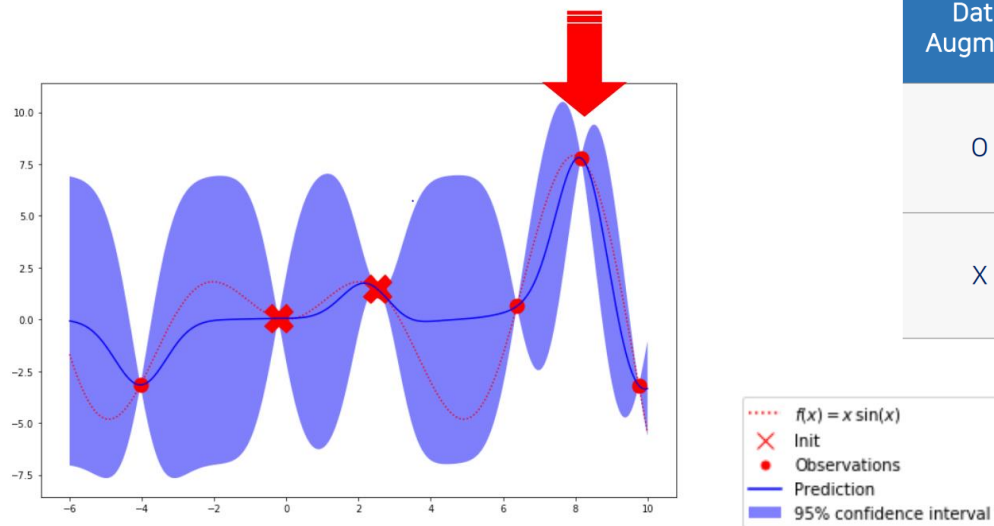
· 사후 분포를 기반으로 샘플링



[https://www.youtube.com/watch?v=PTxqPfG\\_IXY&t=284s](https://www.youtube.com/watch?v=PTxqPfG_IXY&t=284s)



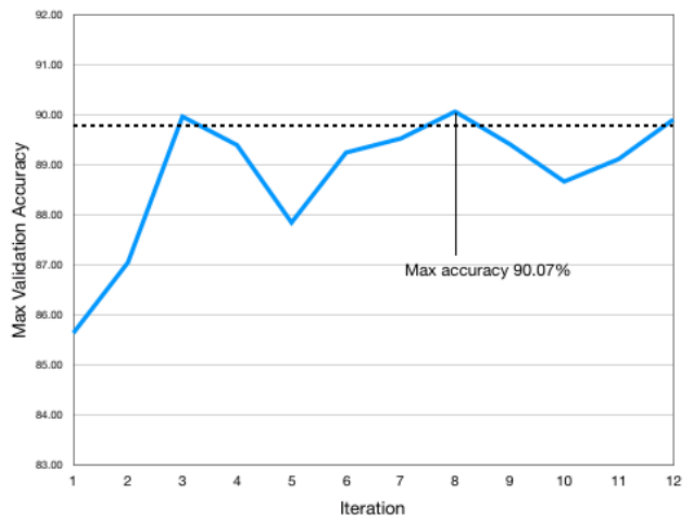
# Performance of BO



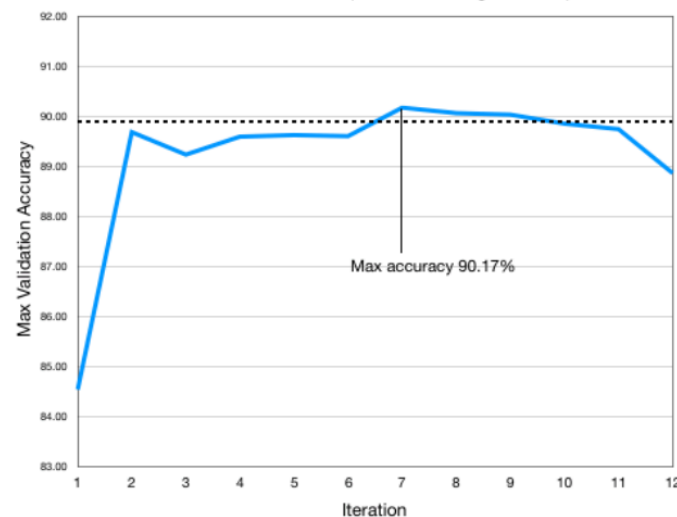
Accuracy on Cifar-10 with Resnet

Data Augment	Model	Random	BayesOpt	Baseline (paper)
O	Resnet-110	94.37	94.53	93.57
	Resnet-56	94.37	94.28	93.03
X	Resnet-110	90.09	90.17	-
	Resnet-56	90.01	90.07	-

Bayesian Search Max Accuracy Per Iteration  
Cifar-10, Resnet-56 (without data augmentation)



Bayesian Search Max Accuracy Per Iteration  
Cifar-10, Resnet-110 (without data augmentation)



[https://www.youtube.com/watch?v=PTxqPfG\\_IXY&t=284s](https://www.youtube.com/watch?v=PTxqPfG_IXY&t=284s)

## Reference

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- [https://www.youtube.com/watch?v=PTxqPfG\\_lXY&t=284s](https://www.youtube.com/watch?v=PTxqPfG_lXY&t=284s)
- <https://aistory4u.tistory.com/entry/%EA%B0%80%EC%9A%B0%EC%8B%9C%EC%95%88-%ED%94%84%EB%A1%9C%EC%84%B8%EC%8A%A4-%ED%9A%8C%EA%B7%80>