Cucumber Intelligence

An object counting tool for real-time cucumber harvest monitoring

DSR Demo Day, 01/10/2024

Outline:

- 1) Introduction:
 - a) How to pluck a pickle
 - b) Computer vision recap

- a) YOLOv8
 - b) Data and finetuning results

2) Training the model:

3) Application + Live demo

Cucumbers = Pickles = Gherkins





Harvesting close-up: Monitoring





CV recap (1): Classification



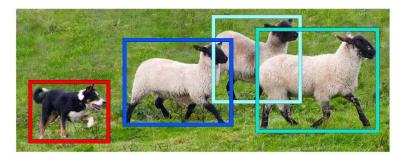
"This is an apple*."

(* unless you're Magritte)

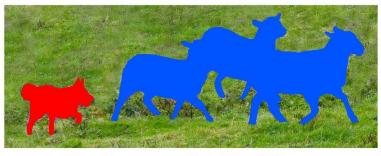
CV recap (2): Object detection, segmentation



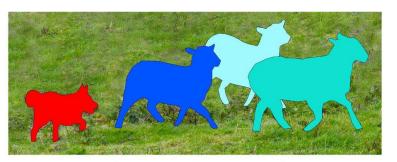
Image Recognition



Object Detection

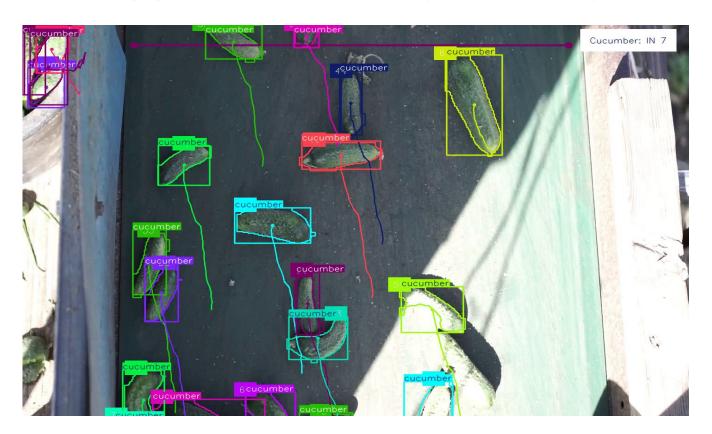


Semantic Segmentation



Instance Segmentation

CV recap (3): Instance tracking + counting



YOLO: "You only look once"

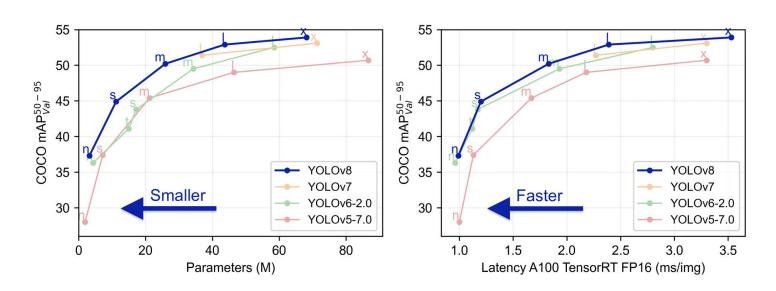


... works like a charm (and out of the box)

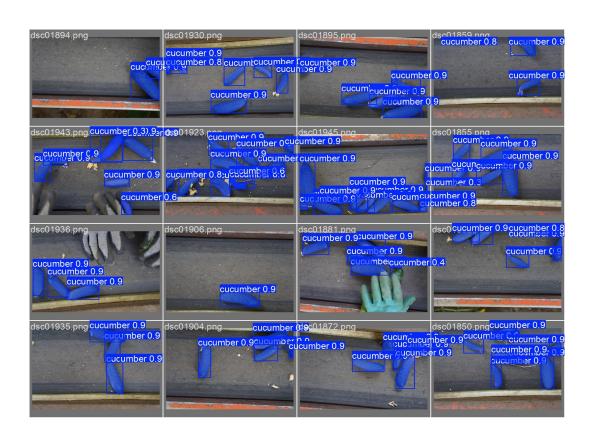
... for ~80 pretrained classes (COCO dataset).

YOLOv8 from <u>ultralytics.com</u>

Different pretrained models available for finetuning:



Finetuning the models



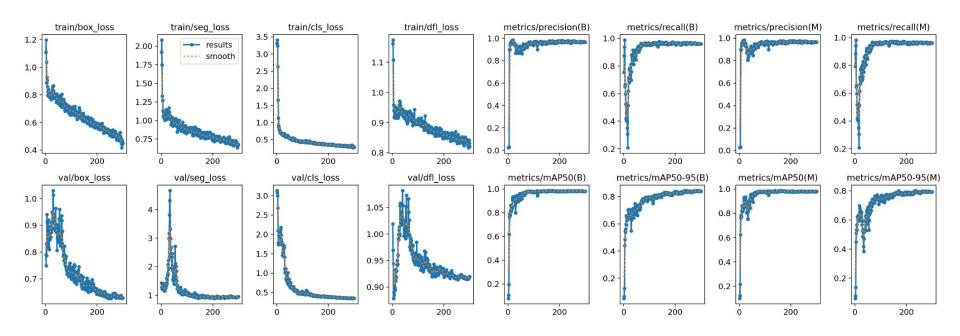
Data:

- ca. 350 photos
- hand-labelled segmentations

Two separate models:

- Detection
- Segmentation

Finetuning the model



Methods summary:

- Take pretrained YOLOv8 object detection/segmentation model from ultralytics
- 2) Train on hand-labelled cucumber photos
- Use finetuned model for tracking and counting cucumbers in video data
- Goal: Count the cucumbers and measure their sizes.

Results (1)

- Inference: Bounding boxes and segmentations
- "nano" model, quantized for speed
- ~0.3 sec per predicted frame (on my CPU)
- 43 -> 68!
- "68 cucumbers counted in 396 frames, i.e. 4.29 cucumbers per second."



Results (2)

Live* demo!

*(640x480 px, 4 fps)

Next steps:

- 1) Improve object counting algorithm
- 2) Cucumber area/volume integration:
 - a) NB: Segmentations change over time
 - b) Idea: Sum over pixels when the Bbox is counted
 - c) Calibration
- 3) Think about occlusion, i.e. cucumbers lying on top of each other
- 0) Have a pickle!

Thank you for your attention!



Questions?

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https://github.com/hrbjoern/CucumberIntelligence/

(will be made public soon)

Thanks to:

- Krzysztof for being my mentor
- My former colleague Berry for having the idea and writing the first software
- Secret Santa who gave me the data
- ... yes, also the interns who did the scrappy annotations
- Ultralytics
- Claude and ChatGPT (Liar!)
- Everybody at DSR and in Batch 39!

Backup

Live demo emergency replacement:



Backup: Object counter

```
# Count objects using line
elif len(self.reg pts) == 2:
    if prev position is not None and track id not in self.count ids:
        # Check if the object's movement segment intersects the counting line
        if LineString([(prev position[0], prev position[1]),(box[0], box[1])]
                      ).intersects(self.counting line segment):
            self.count ids.append(track id)
            # Determine the direction of movement (IN or OUT)
            dx = (box[0] - prev position[0]) * (self.counting region.centroid.x - prev position[0])
            dy = (box[1] - prev position[1]) * (self.counting region.centroid.y - prev position[1])
            if dx > 0 and dy > 0:
                self.in counts += 1
                self.class wise count[self.names[cls]]["IN"] += 1
            else:
                self.out counts += 1
                self.class wise count[self.names[cls]]["OUT"] += 1
```

Backup:

Training on Colab: roughly 1-2 h per run on an L4

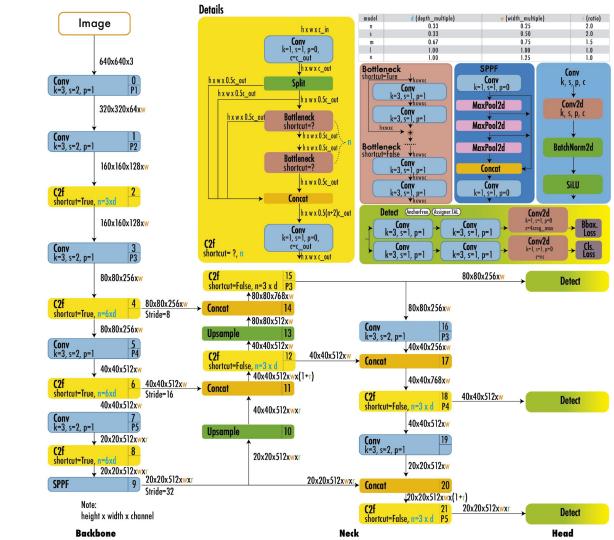
```
Finetuning YOLO with labeltype.ipynb 
       Datei Bearbeiten Anzeige Einfügen Laufzeit Tools Hilfe Alle Änderungen wurden gespeichert
     + Code + Text
       0
           Training date = 2024-09-28 2146
Q

    Setup = _alle

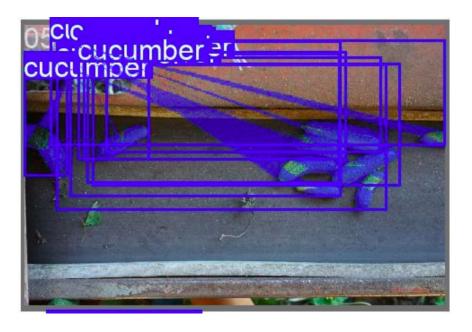
           Model = volov8n-seg.pt
\{x\}
           Labeltype = segs
           Batchsize = 120
           Imagesize = 640
C77
           Epochs = 300
Fetch the data:
       0
             1 # Mount Google Drive and copy data:
             2 if 'data loaded' not in globals():
                   from google.colab import drive
                  drive.mount('/content/drive')
                   !mkdir -v /content/Data
                   !cp -r /content/drive/MyDrive/setup 015/* /content/Data/ #| pv
                  print("setup015 copied")
```

Backup:

YOLOv8 architecture



Damn you, ChatGPT



```
# YOLO format:
```

<category_id> <x_center> <y_center> <width> <height> <x1> <y1> ... <xn> <yn>
... sounds convincing, isn't true.

Where the cucumbers grow





