

PowerFactory 2021

Technical Reference

AEG/Alstom starting unit RelFdetaegalst, TypFdetaegalst

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1 General Description

The AEG/Alstom starting block implements the fault detection logic available in the following relay models

- AEG PD 521
- AEG PD 531
- AEG PD 532
- AEG PD 551
- AEG PD 552
- AEG PD 932
- · Alstom/Areva P437

The following logic of fault detection are available:

- · Overcurrent
- · Undervoltage
- · Underimpedance
- Earth

Accordingly with the relay manuals the following detection logic are active:

- AEG PD 521, AEG PD 531, AEG PD 551
 - 1. "Overcurrentl".
 - 2. "Undervoltage".
 - 3. Earth
- AEG PD 532, AEG PD 552, AEG PD 932, Alstom/Areva P437
 - 1. "Overcurrentl".
 - 2. "Undervoltage".
 - 3. Underimpedance
 - 4. Earth

1.1 Available settings

521 / 531 :

The 521 and the 531 starting block define:

- · An overcurrent starting with double current threshold.
- An undervoltage starting logic with single current release threshold.
- An earth detection logic with single neutral current threshold and stabilization slope.
- Loop preferences for single phase fault, 2 phase fault and 3 phase fault.

The underimpedance element must be manually set as *Disabled* in the AEG/Alstom type dialogue ("iimped" parameter).

551 / 552 :

The 521 and the 531 starting block define:

- · An overcurrent starting with double current threshold.
- An undervoltage starting logic with single current release threshold.
- An underimpedance starting logic with single current release threshold.
- An earth detection logic with single neutral current threshold and stabilization slope.
- Loop preferences for single phase fault, 2 phase fault and 3 phase fault.

532 / 932 :

The 532 and the 932 starting block define:

- An overcurrent starting with double current threshold.
- An undervoltage starting logic with single current release threshold.
- An underimpedance starting logic with single current release threshold.
- An earth detection logic with single neutral current threshold and stabilization slope.
- · Phase priority logic.

437 : The *521* and the *531* starting block define:

- An overcurrent starting with double current threshold.
- · An undervoltage starting logic with double current release threshold.
- An underimpedance starting logic with double current release threshold.
- · An earth detection logic with single neutral current threshold and stabilization slope.
- Loop preferences for single phase fault, 2 phase fault and 3 phase fault.

2 Features & User interface

2.1 AEG/Alstom Starting Logic (RelFdetaegalst)

The user can change the block settings using the "AEG/Alstom Starting" dialogue ("RelFdetaegalst" class). The dialogue consists of seven tab pages: *Basic Data, Overcurrent, Undervoltage, Underimpedance, Earth, Fault Loop Settings*, and *Description*.

2.1.1 Basic data

The "Basic Data" tab page contains the block name, a link to the relevant starting type object, up to four check buttons which allow to select the active starting logic between the logic available for the given model and three combo box which allow to define the power system grounding (*Solidly earthed, Compensated* or *Isolated*) and, only for the *437* type, which phase and ground current threshold value must be used (*High Values* or *Sensitive*). Multiple starting logic can be active at the same time. In Figure 2.1 the whole starting logic is showed. The *High range* and *Sense range* threshold logic is displayed in Figure 2.2

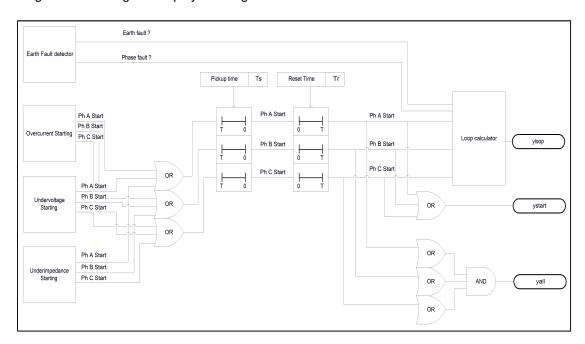
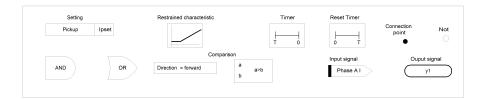


Figure 2.1: DIgSILENT AEG/Alstom starting logic



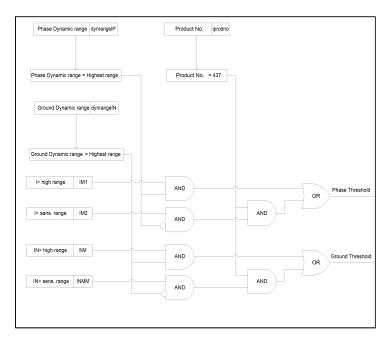


Figure 2.2: DIgSILENT AEG/Alstom 437 phase and ground threshold selection logic

2.1.2 Overcurrent

When the overcurrent starting is available and the *Overcurrent* checkbox is set, the phase currents are compared with the I>> ("IMM" parameter) and the I>>> ("IMMM" parameter) phase current threshold. If the system grounding is *Solidly earthed* a phase is declared to be in starting condition only if the relevant current is greater than 2/3 the greater phase current. Running a short circuit or a load flow the starting time is considered to be an half cycle if the current is greater than I>>> ("IMMM" parameter) or a cycle if the current is greater than I>>> ("IMMM" parameter).

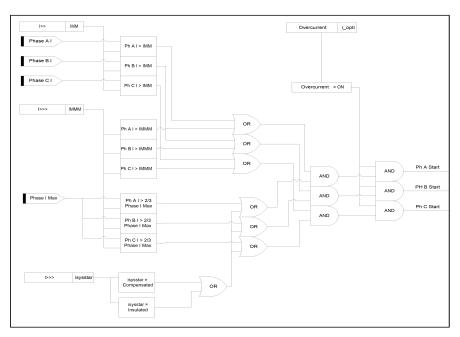


Figure 2.3: DIgSILENT AEG/Alstom Overcurrent starting logic

2.1.3 Undervoltage

When the undervoltage starting is available and the *Undervoltage* checkbox is set, the phase voltages are compared with the U_i ("Um" parameter)

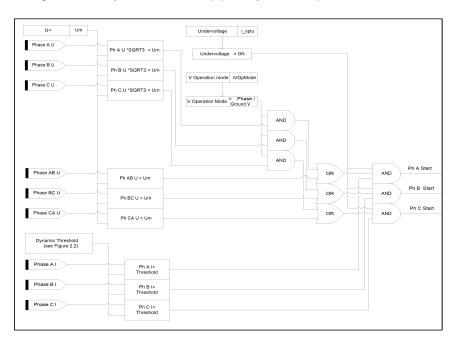
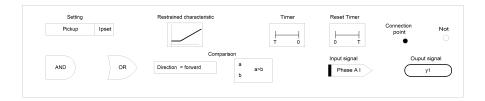


Figure 2.4: DIgSILENT AEG/Alstom Undervoltage starting logic



2.1.4 Underimpedance

When the underimpedance starting is available and the *Underimpedance* checkbox is set the phase currents must exceed a threshold value. Only for the *437* type, the user can select in the *Basic data* tab page if the *High Values* or the *Sensitive* phase current threshold must be used as enabling threshold.

The distance starting zone shape is shown in Figure 2.7.

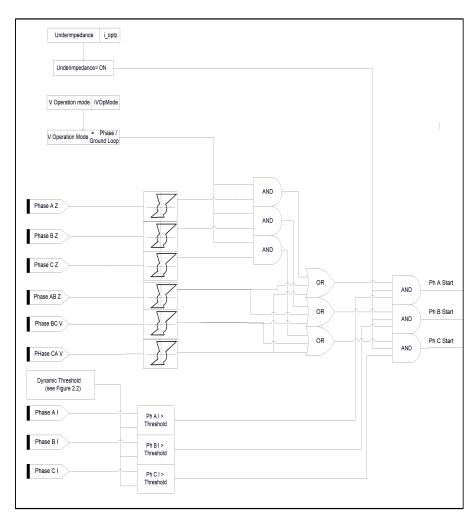


Figure 2.5: DIgSILENT AEG/Alstom Underimpedance starting logic

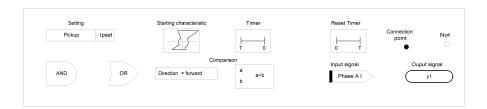


Figure 2.6: DIgSILENT The Underimpedance phase starting detection zone

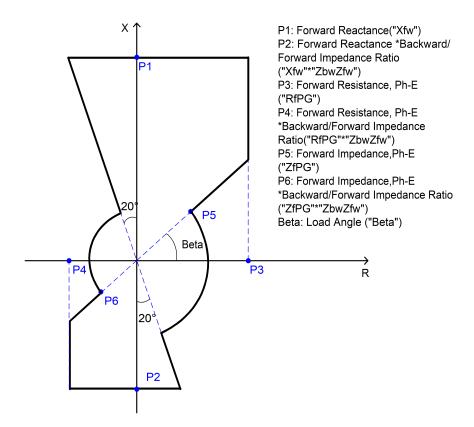


Figure 2.7: DIgSILENT The Underimpedance ground starting detection zone

2.1.5 Earth Fault Detection

The ground detection logic use one zero sequence current threshold with restrain characteristic and time delay and one zero sequence voltage threshold to detect the ground fault condition. Different logic are applied for a solidly earthed network and for a not earthed or a compensated network. When *Solidly Earthed* has been set in the "System Grounding" ("isysstar" parameter) an earth fault is detected if one of the following conditions is verified:

- the earth current is greater than than the earth threshold (which can be "IN > sens.range" or "IN > high range" depending up on the "Ground Dynamic range" ("dynrangeIN" parameter)).
- the zero sequence voltage is greater than "VNG>"

When *Compensated* or *Isolated* has been set an earth fault is detected if following conditions are verified at the same time:

- the earth current is greater than than the earth threshold (which can be "IN > sens.range" or "IN > high range" depending up on the "Ground Dynamic range" ("dynrangeIN" parameter)).
- the zero sequence voltage is greater than "VNG>".
- At least 2 phase currents are greater than the phase starting current or an *Underimpedance* starting has been declared or a *Undervoltage* starting has been declared or the "tIN>" time expired.

The lower zero sequence current threshold can be set to use a stabilization slope to avoid spurious trips. The earth detection logic is showed in the Figure 2.8

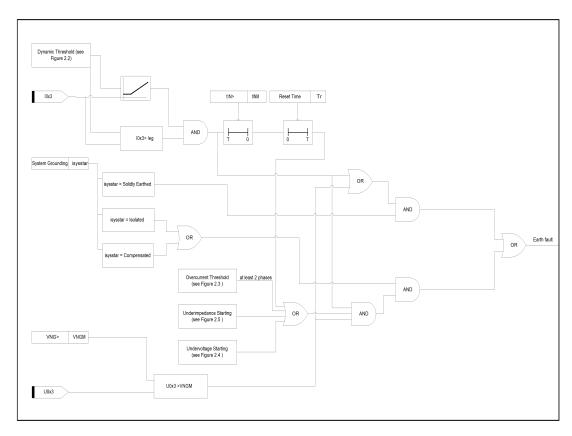


Figure 2.8: DIgSILENT AEG/Alstom Earth detection starting logic

2.1.6 Fault Loop Settings

The *Fault Loop* logic defines additional loop selection preferences in case of single Phase-Ground, Phase-Phase-Ground or three Phases-Ground faults. Function of the type id, two different groups of settings are active:

The "532" and the "932" type ids activate the following settings:

- Transfer for 1p ("itransf1p" parameter)
- Phase Priority 2pG ("iphpriority" parameter)

All other type ids activate the following settings:

- Meas. start. 1pG ("iStart1pG" parameter)
- Meas. start. 2pG ("iStart2pG" parameter)
- Meas. start. 3pG ("iStart3pG" parameter)
- Transfer for 1p ("itransf1p" parameter)

Meas. start. 1pG It's the logic applied when a Phase-Ground fault has been detected. One between the following options can be selected:

- None
- Ground Loops

When the *None* option is set the element doesn't start for single Phase-Ground fault and the protection doesn't operate. The *Ground Loops* option allows the starting logic to detect has expected a single Phase-Ground fault.

Meas. start. 2pG It's the logic applied when a Phase-Phase-Ground fault has been detected. One between the following options can be selected:

- Phase Loops
- Ground Loops

When the *Phase Loops* option is set and a Phase-Phase-Ground fault has been detected the relevant phase loop is declared as started. Example: if a B-C-Ground fault is applied and *Phase Loops* option is set, the "yloop" is set equal to 5, if the *Ground Loops* option is set, the "yloop" is set equal to 2.

Meas. start. 3pG It's the logic applied when a 3Phase-Ground fault has been detected. One between the following options can be selected:

- · Phase Loops
- Ground Loops

Example: if a A-B-C-Ground fault is applied and *Phase Loops* option is set, the "yloop" is set equal to 23, if the *Ground Loops* option is set, the "yloop" is set equal to 22.

Transfer for 1p It's the starting logic used when only a phase has been detected as started and no ground fault has been detected. One between the following options can be selected:

- · Ground
- P or G =f(Imed,Imax)

When the *Ground* option is set a phase-ground fault is declared if the zero sequence current has been greater than the "INM" setting for a time greater than the "tINM" setting.

When the P or G =f(Imed,Imax) option is set a phase-ground fault is declared if the average phase current is greater than $2/3maxI_{phase}$; if it's smaller a phase-ground fault is declared if the zero sequence current has been greater than the "INM" setting for a time greater than the "INM" setting.

Phase Priority 2pG It's the logic applied when a Phase-Phase-Ground fault has been detected and the type is *532* or *932*. One between the following options can be selected:

- · C before A acyclic
- · A before B before C cyclic
- · A before C acyclic
- C before B before A cyclic
- · B before A acyclic
- · A before B acyclic
- · C before B acyclic
- · B before C acyclic

Table 2.1: Started loop applying the Phase Priority logic to a Ph-Ph-Grnd fault

| FaultType | C before A acyclic | A before B before C cyclic | A before C acyclic | C before B before A acyclic | B before A acyclic | A before B acyclic | C before B acyclic | B before C acyclic |
|-----------|-----------------------------|-------------------------------------------|-----------------------------|--------------------------------------------|-----------------------------|-----------------------------|-----------------------------|-----------------------------|
| A-B-Grnd | Α | Α | Α | В | В | Α | В | В |
| A-C-Grnd | С | С | Α | Α | Α | Α | С | С |
| B-C-Grnd | С | В | С | С | В | В | С | В |

2.1.7 Description

The *Description* tab page can be used to insert some information to identify the Aeg/Alstom Starting protective element (both with a generic string and with an unique textual string similar to the *Foreign Key* approach used in the relational databases) and to identify the source of the data used to create it.

2.2 AEG/Alstom Starting Type(TypFdetaegalst)

The AEG/Alstom Starting block main characteristics must be configured in the "AEG/Alstom Starting Type" dialogue (*TypFdetaegalst* class). The dialogue contains six tab pages: Basic Data, Overcurrent, Undervoltage Ground Fault Detection, Impedance, and Common.

2.2.1 Basic Data

The *Basic data* tab page contains the combox which allow to select the active Aeg/Alstom starting type. The following types are available:

- 437
- 521
- 531
- 532
- 551
- 552
- 932

Four combo boxes (*Overcurrent*, *Undervoltage*, *Underimpedance*, and *Earth Fault*) allow to define which starting types are shown in the "AEG/Alstom Starting" dialogue ("RelFdetaegalst" class). Each combobox contains the following options

- Disabled
- Enabled
- · User Configurable

When the *Disabled* option is selected the relevant check box is hidden in the "Basic Data" tab page of the "AEG/Alstom Starting" dialogue. When the *Enabled* option is selected the relevant check box is showed checked and cannot be modified. When the *User Configurable* option is selected the relevant check box is showed and can be checked or unchecked.

2.2.2 Overcurrent

The *Overcurrent* tab page contains the range definition for the element parameters available in the "Overcurrent" tab page of the "AEG/Alstom Starting" dialogue.

2.2.3 Underimpedance

The *Underimpedance* tab page contains the range definition for the element parameters available in the "Underimpedance" tab page of the "AEG/Alstom Starting" dialogue.

2.2.4 Ground Fault Detection

The *Ground Fault Detection* tab page contains the range definition for the element parameters available in the "Earth Fault Detection" tab page of the "AEG/Alstom Starting" dialogue.

2.2.5 Undervoltage

The *Undervoltage* tab page contains the range definition for the element parameters available in the "Undervoltage" tab page of the "AEG/Alstom Starting" dialogue.

2.2.6 Common

The Common tab page defines the pickup delay (Pickup Time"Ts" parameter), the Reset Time ("Tr" parameter) and four separated Reset Ratios for the Overcurrent ("Krl" parameter), the Impedance ("KrRX" parameter), the Voltage ("KrU" parameter) and the Earth detection ("Kre" parameter) starting logic of the Aeg/Alstom starting element. Please notice that the Overcurrent "Krl" parameter and the Earth detection "Kre" parameter must be smaller than 1 and the Impedance Z "KrRX" parameter and the Voltage "KrU" parameter must be greater than 1.

3 Integration in the relay scheme

The AEG/Alstom starting type class name is TypFdetaegalst. The AEG/Alstom starting dialogue class name is RelFdetaegalst. In the relay scheme the AEG/Alstom starting element gets the voltage and the current signals from the measurement element. The signal with the ID(s) of the started loop(s) is used by the polygonal or the mho trip zones.

A complete connection scheme is showed here below.

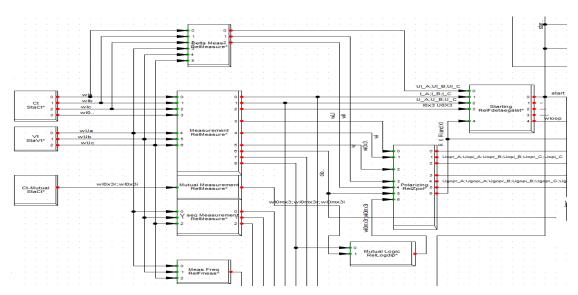


Figure 3.1: DIgSILENT Connection scheme of a AEG/Alstom starting "RelFdetaegalst" block.

A Parameter Definitions

A.1 AEG/Alstom starting block Type (TypFdetaegalst)

Table A.1: Input parameters of AEG/Alstom starting type (*TypFdetaegalst*)

| Parameter | Description | Unit |
|-----------|----------------------------------------------------------------------------------------------------------------------------------|-------------|
| loc₋name | Name assigned by the user to the block type | Text |
| iprodno | The AEG starting block type (supported number: 521, 531, 532, 551, 552, 932) | Integer |
| ioverc | Flag defining if the overcurrent starting is always <i>Enabled</i> , <i>Disabled</i> or is <i>User Configurable</i> | Integer |
| iimped | Flag defining how the impedance starting is always <i>Enabled</i> , <i>Disabled</i> or is <i>User Configurable</i> | Integer |
| iundu | Flag defining how the undervoltage starting is always <i>Enabled</i> , <i>Disabled</i> or is <i>User Configurable</i> | Integer |
| igrnd | Flag defining how the earth detection is always <i>Enabled</i> , <i>Disabled</i> or is <i>User Configurable</i> | Integer |
| rIMM | Range of the first phase overcurrent starting threshold | Text |
| rIMMM | Range of the second phase overcurrent starting threshold | Text |
| rIM1 | Range of the first ("I > high") phase overcurrent underimpedance starting threshold | Text |
| rIM2 | Range of the second ("I>sens.") phase overcurrent underimpedance starting threshold | Text |
| rXfw | Range of the Forward Reactance | Text |
| rZbwZfw | Range of the Backward/Foward Impedance Ratio | |
| rRfPP | Range of the Resistance Forward, Ph-Ph | Text |
| rRfPG | Range of the Resistance Forward, Ph-E | Text |
| rZfPP | Range of the Load Impedance Forward, Ph-Ph | Text |
| rZfPG | Range of the Load Impedance Forward, Ph-E | Text |
| rBeta | Range of the Load Impedance angle limit (I & III quadrant) | Text |
| rINMM | Range of the ("IN > high") neutral overcurrent starting threshold | Text |
| rINM | Range of the ("I > sens.") neutral overcurrent starting threshold | Text |
| rtINM | Range of the time delay applied to the ("IN > high") neutral overcurrent starting threshold | Text |
| rVNGMM | Range of the second neutral overvoltage threshold VNG>> | Text |
| rtVNGMM | Range of the delay of the second neutral overvoltage threshold VNG>> | Text |
| rVNGM | Range of the first neutral overvoltage threshold VNG > | Text |
| rEstabfac | Range of the stabilization factor applied to the earth threshold calculation | Text |
| rUm | Range of the phase undervoltage threshold U _i used by the undervoltage starting logic | Text |
| Ts | Pick up time, its the time spent measuring the currents in the load flow and short circuit calculation and in the RMS simulation | Seconds |
| Tr | Reset time, its the delay with which the block reset the trip outputs after that the start | Seconds |
| KrZ | Underimpedance reset ratio | Real number |
| Krl | Current reset ratio | Real number |
| KrU | Voltage reset ratio | Real number |
| kre | Earth current reset ratio | Real number |

A.2 AEG/Alstom starting Element (RelFdetaegalst)

Table A.2: Input parameters of AEG/Alstom starting element (RelFdetaegalst))

| Parameter | Description | Unit |
|-------------|------------------------------------------------------------------------------|-----------------|
| loc_name | Name assigned by the user to the block | Text |
| iopt_i | Flag to enable the current starting logic | Integer |
| iopt_u | Flag to enable the undervoltage starting logic | Integer |
| iopt_z | Flag to enable the underimpedance starting logic | Integer |
| iopt_ie | Flag to enable the earth fault detection starting logic | Integer |
| isysstar | Earthing system (Solidly Earthed, Compensated, Insulated) | Integer |
| dynrangeIP | Flag activating the phase high or sensitive current threshold (Highest | Integer |
| | Range, Sensitive) | |
| dynrangeIN | Flag activating the ground high or sensitive current threshold (Highest | Integer |
| | Range, Sensitive) | _ |
| IMM | First phase overcurrent starting threshold | pu |
| IMMM | Second phase overcurrent starting threshold | Multiple of IMM |
| iVOpMode | Operation mode of the undervoltage starting logic, it defines which loops | Integer |
| | are evaluated by the logic (Phase Voltage, Phase/Ground Voltage) | _ |
| iZOpMode | Operation mode of the underimpedance starting logic, it defines which | Integer |
| | loops are evaluated by the logic (Phase Loops, Phase/Ground Loops) | |
| IM1 | ("I > high") phase overcurrent underimpedance starting threshold | pu |
| IM2 | ("I > sens.") phase overcurrent underimpedance starting threshold | pu |
| Xfw | Forward Reactance | Sec Ohm |
| ZbwZfw | Backward/Foward Impedance Ratio | |
| RfPP | Resistance Forward, Ph-Ph | Sec Ohm |
| RfPG | Resistance Forward, Ph-E | Sec Ohm |
| ZfPP | Load Impedance Forward, Ph-Ph | Sec Ohm |
| ZfPG | Load Impedance Forward, Ph-E | Sec Ohm |
| Beta | Load Impedance angle limit (I & III quadrant) | Degrees |
| INMM | ("IN > high") neutral overcurrent starting threshold | pu |
| INM | ("I > sens.") neutral overcurrent starting threshold | pu |
| tINM | Time delay applied to the ("IN > high") neutral overcurrent starting thresh- | s |
| | old | |
| VNGMM | Second neutral overvoltage threshold VNG>> | pu |
| tVNGMM | Delay of the second neutral overvoltage threshold VNG >> | S |
| VNGM | First neutral overvoltage threshold VNG> | pu |
| Estabfac | Stabilization factor applied to the earth threshold calculation | % |
| rUm | Phase undervoltage threshold Ui used by the undervoltage starting logic | pu |
| iStart1pG | Loops used to detect a single phase fault (None, Ground Loops) | Integer |
| iStart2pG | Loops used to detect a double phase fault (Phase Loops, Ground Loops) | Integer |
| iStart3pG | Loops used to detect a three phase fault (Phase Loops, Ground Loops) | Integer |
| itransf1p | Special logic for single phase starting detection without earth fault detec- | Integer |
| | tion | • |
| iphpriority | Phase priority in case of a Ph-Ph-Ground fault | Integer |

Signal Definitions В

Table B.1: Input/output signals of the AEG/Alstom starting element (CalFdetaegalst)

| Name | Description | Unit | Type | Model |
|------------|----------------------------------------------------------|-------------------------------------|------|-------|
| I_A | Phase A current | Secondary Amperes | IN | Any |
| I_B | Phase B current | Secondary Amperes | IN | Any |
| I_C | Phase C current | Secondary Amperes | IN | Any |
| 10x3 | Zero sequence current | Secondary Amperes | IN | Any |
| 12x3 | Negative sequence current | Secondary Amperes | IN | Any |
| U0x3 | Zero sequence voltage | Secondary Volts | IN | Any |
| R₋A | Phase A loop resistance | Secondary Ohms | IN | Any |
| X_A | Phase A loop inductance | Secondary Ohms | IN | Any |
| R₋B | Phase B loop resistance | Secondary Ohms | IN | Any |
| X_B | Phase B loop inductance | Secondary Ohms | IN | Any |
| R₋C | Phase C loop resistance | Secondary Ohms | IN | Any |
| X_C | Phase C loop inductance | Secondary Ohms | IN | Any |
| RI_A | Phase A - Phase B loop resistance | Secondary Ohms | IN | Any |
| XI_A | Phase A Phase B loop inductance | Secondary Ohms | IN | Any |
| RI₋B | Phase B - Phase C loop resistance | Secondary Ohms | IN | Any |
| XI₋B | Phase B Phase C loop inductance | Secondary Ohms | IN | Any |
| RI₋C | Phase C - Phase A loop resistance | Secondary Ohms | IN | Any |
| XI_C | Phase C Phase A loop inductance | Secondary Ohms | IN | Any |
| U_A | Phase A voltage | Secondary Volts | IN | Any |
| U₋B | Phase B voltage | Secondary Volts | IN | Any |
| U₋C | Phase C voltage | Secondary Volts | IN | Any |
| UI_A | Phase A Phase B voltage | Secondary Volts | IN | Any |
| UI₋B | Phase B Phase C voltage | Secondary Volts | IN | Any |
| UI_C | Phase C Phase A voltage | Secondary Volts | IN | Any |
| yloop | ID of the loop from which the fault must be removed | | OUT | Any |
| ystart | Starting signal/ starting time | Seconds (or 1/0 RMS/EMT simulation) | OUT | Any |
| ysall | Starting signal/ starting time for all loops (3ph fault) | Seconds (or 1/0 RMS/EMT simulation) | OUT | Any |
| yfaulttype | Fault type ID | · | OUT | Any |

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