

/home/hrg/Documents  
/ROS/ros\_ws/src/ros  
\_camera\_lib/include/cam  
\_stream/hal/cam\_stream  
\_hal.hpp

```
graph BT; A["/home/hrg/Documents/ROS/ros_ws/src/ros_camera_lib/src/cam_stream/api/cam_stream_api.cpp"] --> C["/home/hrg/Documents/ROS/ros_ws/src/ros_camera_lib/include/cam_stream/hal/cam_stream_hal.hpp"]; B["/home/hrg/Documents/ROS/ros_ws/src/ros_camera_lib/src/cam_stream/hal/cam_stream_hal.cpp"] --> C;
```

/home/hrg/Documents  
/ROS/ros\_ws/src/ros  
\_camera\_lib/src/cam\_stream  
/api/cam\_stream\_api.cpp

/home/hrg/Documents  
/ROS/ros\_ws/src/ros  
\_camera\_lib/src/cam\_stream  
/hal/cam\_stream\_hal.cpp