

/home/hrg/Documents
/ROS/ros_ws/src/ros
_camera_lib/src/cam_stream
/app/cam_stream.cpp

```
graph TD; A["/home/hrg/Documents  
/ROS/ros_ws/src/ros  
_camera_lib/src/cam_stream  
/app/cam_stream.cpp"] --> B["cam_stream/api/cam  
_stream_api.hpp"]; B --> C["string"];
```

cam_stream/api/cam
_stream_api.hpp

string