Scenario 3

For the last task, you are going to do an object handover with the robot.

Place a zone above the exchange area, then command the robot to move any object in the zone to the bottom shelf.

Hold the pringles, without covering the tracking markers.

Then, hold the pringles in the zone to trigger handing it to the robot, then let the robot grab the object.

Please make sure to watch your fingers, only placing the object within the grippers of the robot. But don't worry, we have a way of stopping the robot if anything goes wrong.