

Smart Traffic Sign Recognition Using Convolutional Neural Networks

Submitted by

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1. Summary

This project presents a **Smart Traffic Sign Recognition System** designed to accurately classify road signs using Deep Learning. The solution uses a **Convolutional Neural Network (CNN)** trained on 30 distinct traffic sign categories and is deployed using a **Streamlit web interface** for real-time predictions.

The model demonstrates strong performance, achieving **~86% validation accuracy**, and the deployed application allows users to upload an image and instantly receive predictions with confidence scores. The project builds a solid foundation for future advancements such as **real-time video detection, mobile deployment, and multilingual audio alerts**, making it highly relevant for autonomous vehicles and modern transportation systems.

2. Project Objectives

The project is designed with the following clear objectives:

2.1 Build a Robust Classification Model

Develop a CNN capable of identifying multiple traffic sign classes with high reliability.

2.2 Dataset Structuring & Preprocessing

Clean, organize, augment, and normalize image data to ensure high-quality training.

2.3 Model Evaluation

Assess accuracy, loss curves, confusion matrix, and generalization capability.

2.4 Application Deployment

Create an easy-to-use Streamlit interface for real-time traffic sign recognition.

2.5 Scalability & Future Integration

Design the system such that it can be extended to video streams, mobile apps, and voice-enabled outputs.

3. Technology Stack

| Category | Tools/ Frameworks | Purpose |
|-----------------|-----------------------|---|
| Deep Learning | CNN Architecture | Feature extraction & classification |
| Frameworks | TensorFlow, Keras | Model training & optimization |
| Interface | Streamlit | Deployment & real-time prediction |
| Data Processing | OpenCV, NumPy, Pandas | Image handling, transformations, array operations |
| Visualization | Matplotlib, Seaborn | Training curves, confusion matrix, error analysis |

4. Dataset & Preprocessing

4.1 Dataset Characteristics

- **Total Classes:** 30
- **Image Size:** 180×180 pixels
- **Normalization:** Pixel scaling to [0,1]
- **Format:** Folder-wise class-separated images

4.2 Dataset Distribution

| Dataset Type | Purpose | Images | Classes |
|--------------|-------------------------|--------|---------|
| Training | Learn model parameters | 504 | 30 |
| Validation | Tune hyperparameters | 149 | 30 |
| Testing | Evaluate final accuracy | 285 | 30 |

4.3 Preprocessing Steps

- **Data Augmentation**

- Random horizontal flip
- Random rotation ($\pm 10\%$)
- Random zoom (10%)

```
# Data Augmentation Layer
# -----
data_augmentation = tf.keras.Sequential([
    layers.RandomFlip("horizontal"),
    layers.RandomRotation(0.1),
    layers.RandomZoom(0.1)
])
```

- **Label Encoding**
Converts folder names → numerical class IDs
- **Image Resizing**
Maintains input shape consistency for CNN

5. CNN Model Architecture

5.1 Feature Extraction Layers

| Layer Type | Configuration | Purpose |
|--------------|----------------------|----------------------------------|
| Rescaling | Normalize to [0,1] | Standardizes input |
| Conv2D | 16 → 32 → 64 filters | Learns edges → textures → shapes |
| MaxPooling2D | Pool size 2×2 | Reduces spatial dimensions |

5.2 Classification Layers

| Layer | Details | Purpose |
|---------|--------------------------------|------------------------|
| Flatten | Convert feature maps to vector | Feed into dense layers |
| Dropout | 0.2 | Reduces overfitting |
| Dense | 128 units | Pattern learning |

| Layer | Details | Purpose |
|--------------|--------------------|--------------------------------|
| Output Dense | 30 units + Softmax | Class probability distribution |


```

model = Sequential([
    layers.Rescaling(1./255),
    layers.Conv2D(16, 3, padding='same', activation='relu'),
    layers.MaxPooling2D(),
    layers.Conv2D(32, 3, padding='same', activation='relu'),
    layers.MaxPooling2D(),
    layers.Conv2D(64, 3, padding='same', activation='relu'),
    layers.MaxPooling2D(),
    layers.Flatten(),
    layers.Dropout(0.2),
    layers.Dense(128),
    layers.Dense(len(road_type))
])

```

5.3 Model Training Details

| Parameter | Value | Description |
|-----------|---------------------------------|---------------------------------------|
| Optimizer | Adam | Adaptive learning rate |
| Loss | Sparse Categorical Crossentropy | Multi-class classification |
| Metric | Accuracy | Performance measure |
| Epochs | 15 | Early stopping applied |
| Callbacks | EarlyStopping, Checkpoint | Prevent overfitting & save best model |



5. Model Compilation and Training

```

model.compile(optimizer='adam',
              loss=tf.keras.losses.SparseCategoricalCrossentropy(from_logits=True),
              metrics=['accuracy'])

epochs_size = 15
history = model.fit(data_train, validation_data=data_validation, epochs=epochs_size)

```

Epoch 1/15
16/16 ————— 4s 154ms/step - accuracy: 0.1409 - loss: 3.8288 - val_accuracy:
Epoch 2/15

6. Model Performance Summary

- **Training Accuracy:** ~100%
- **Validation Accuracy:** 85.9% – 86.6%
- **Observation:**
 - Slight overfitting is noticed
 - Model performs strongly on unseen data

- **Confusion Matrix:**

Shows class-wise prediction distribution and misclassification points

```
# Evaluate model on test set
test_loss, test_accuracy = model.evaluate(data_test)
print(f"Test Accuracy: {test_accuracy:.4f}")

# Get predictions and true labels
y_true = []
y_pred = []
for images, labels in data_test:
    preds = model.predict(images)
    y_true.extend(labels.numpy())
    y_pred.extend(np.argmax(preds, axis=1))

# Classification report
print(classification_report(y_true, y_pred, target_names=road_type))

# Confusion matrix
cm = confusion_matrix(y_true, y_pred)
plt.figure(figsize=(12, 10))
sns.heatmap(cm, annot=True, fmt='d', cmap='Blues', xticklabels=road_type, yticklabels=road_type)
plt.xlabel('Predicted')
plt.ylabel('True')
plt.title('Confusion Matrix')
plt.show()
```

| | | | | |
|--------------|------|------|------|-----|
| accuracy | | | 0.54 | 285 |
| macro avg | 0.53 | 0.55 | 0.49 | 285 |
| weighted avg | 0.56 | 0.54 | 0.48 | 285 |

7. Prediction Pipeline & Deployment

7.1 Prediction Workflow

1. Upload or capture image
2. Resize to 180×180
3. Convert to NumPy array
4. Apply normalization

5. Run through CNN
6. Softmax applied for probability scores
7. Return predicted class + confidence

```
image = r"C:\Users\Ajay\Downloads\RoadSigns\TEST\16\016_1_0026_1_j.png"

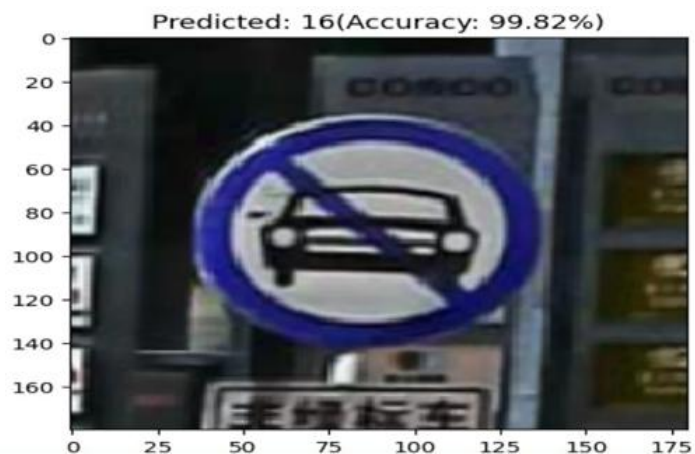
image = tf.keras.utils.load_img(image, target_size=(img_height,img_width))
img_arr = tf.keras.utils.array_to_img(image)
img_bat=tf.expand_dims(img_arr,0)

predict = model.predict(img_bat)

score = tf.nn.softmax(predict)

print('road type in image is {} with accuracy of {:.2f}'.format(road_type[np.argmax(score)],np.max(score)*100))

plt.imshow(image, cmap='gray')
plt.title('Predicted: {}(Accuracy: {:.2f}%)' .format(road_type[np.argmax(score)], np.max(score) * 100))
plt.show()
```



7.2 Hyperparameter Tuning (Random Search)

| Parameter | Best Value |
|---------------|-------------|
| Filters | 32, 96, 192 |
| Kernel Sizes | 5, 3 |
| Dropout | 0.4 |
| Dense Units | 256 |
| Learning Rate | 0.001 |
| Epochs | 30 |

Output Accuracy: ~14%

→ Indicates overfitting and insufficient dataset size during tuning run.

→ Further augmentation and tuning needed.

```
Trial 8 Complete [00h 04m 24s]
val_accuracy: 0.05999999865889549

Best val_accuracy So Far: 0.1400000059604645
Total elapsed time: 00h 25m 06s
Best hyperparameters: {'filters_1': 32, 'kernel_size_1': 5, 'filters_2': 96, 'kernel_size_2': 3, 'filters_3': 192}
Epoch 1/30
13/13 ————— 11s 769ms/step - accuracy: 0.0198 - loss: 3.4089 - val_accuracy: 0.0200 - val_loss: 3.
Epoch 2/30
13/13 ————— 10s 767ms/step - accuracy: 0.0272 - loss: 3.3982 - val_accuracy: 0.0200 - val_loss: 3.
```

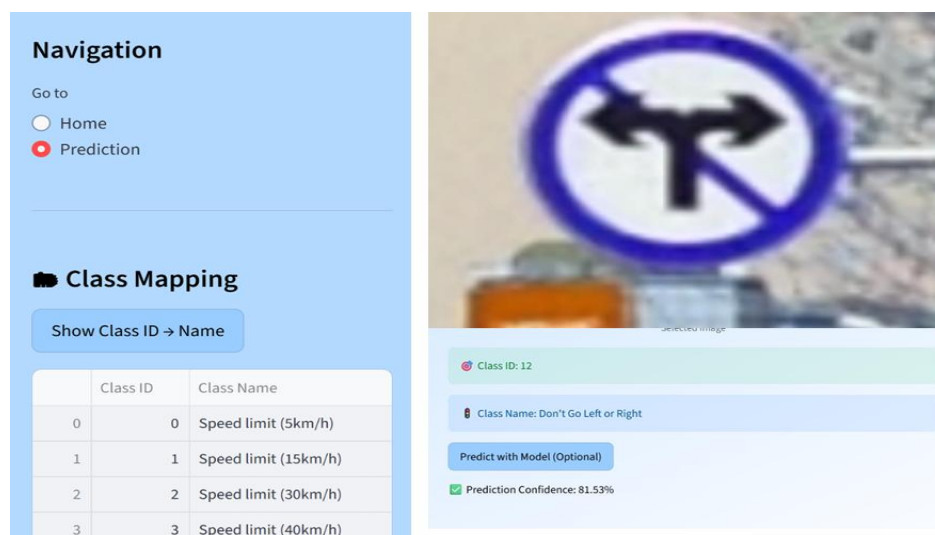
7.3 Streamlit Application

The Streamlit interface includes:

- Image upload section
- Real-time prediction output
- Probability confidence display
- Supports any traffic sign image format

Scalability options:

- Live webcam detection
- Batch processing
- Cloud hosting for global accessibility



8. Conclusion & Future Scope

8.1 Conclusion

- A CNN-based traffic sign classifier was successfully built and deployed.
- Achieved **~86% validation accuracy**, making it suitable for prototype-level real-time systems.
- The Streamlit dashboard adds strong usability and demonstrates practical deployment.

8.2 Future Enhancements

1. **Advanced Hyperparameter Tuning**
Use Bayesian tuning, AutoML, or larger datasets.
2. **Real-Time Video Processing**
Integrate OpenCV live stream detection.
3. **Voice-Based Feedback**
Provide sign warnings in multiple languages.
4. **Mobile/Edge Deployment**
Convert model to TensorFlow Lite for mobile devices.
5. **Cloud Deployment**
Host via AWS/GCP for global accessibility.