

/home/hrishikesh/Week6
/Lane-Line-Detection-System
/include/CameraModule.h

```
graph TD; A["/home/hrishikesh/Week6  
/Lane-Line-Detection-System  
/include/CameraModule.h"] --> B[iostream]; A --> C[vector]; A --> D[string]; A --> E[opencv2/opencv.hpp]; A --> F[opencv2/highgui.hpp];
```

The diagram illustrates the include relationships for the file `/home/hrishikesh/Week6/Lane-Line-Detection-System/include/CameraModule.h`. Five arrows originate from the bottom of the top box and point to the following headers: `iostream`, `vector`, `string`, `opencv2/opencv.hpp`, and `opencv2/highgui.hpp`.

`iostream`

`vector`

`string`

`opencv2/opencv.hpp`

`opencv2/highgui.hpp`