

## Simple and Deterministic Matrix Sketching

Presented by:

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<sup>&</sup>lt;sup>1</sup>Authored by Edo Liberty and and won the KDD-2013 best paper award[3].

#### **Content**

- Background
- Related work
- Frequent directions
- ► Experiments and Results
- Conclusion

## Matrices in the age of 'Big data'

#### What is a sketch?

- ► A sketch of a matrix A is another matrix B which is significantly smaller than A, but still approximates it well.
- A good sketch matrix is one on which some computations can be performed, without *much* loss of precision.
- Formally, consider a large matrix  $A \in \mathbb{R}^{n \times d}$  with n rows and d columns
  - ▶ a sketch matrix B is one s.t.  $B \in \mathbb{R}^{\ell \times d}$ ,
  - ► containing only  $\ell \ll n$  rows and  $A^T A \approx B^T B$ .

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#### How do we get a sketch?

#### Three existing main classes:

- Random-projection:
  - use a projection matrix for dimensionality reduction (approximately preserving the lengths of, the dot products between two original vectors on average, as well as the distances in the transformed space), or
  - (ii) randomly combine matrix rows.
- Hashing: use a subspace embedding S that embeds the column space of the original matrix into a lower-dimensional subspace
  - approximately preserving the norms of all vectors in that subspace
  - ▶ where  $A \in \mathbb{R}^{n \times d}$ ,  $S : \mathbb{R}^n \to \mathbb{R}^t$ , for all  $x \in \mathbb{R}^d$ , and
  - ►  $||SAx||_2 = (1 \pm \varepsilon) ||Ax||_2$

## How do we get a sketch? (cont.)

- Sampling: Column Subset Selection Problem
  - ▶ simple solution obtained by sampling rows with probability proportional to their squared  $\ell_2$  norms
  - aim is to recover a low rank matrix whose column space contains most of the space spanned by the top k singular vectors of the matrix.

Proposed fourth approach, Frequent-directions

#### **Proposed approach: Frequent-directions**

- Based on a well known existing algorithm for item frequency estimation.
- A pass-efficient algorithm, given the constraint:
  - data can be read only a constant number of times;
  - the streaming model: only one pass is permitted!

## Item frequency estimation

- Used to uncover frequent items in an item stream
- ► (Re-)Invented (at least!) four times [5, 1, 2, 4]²

Goal. Use  $O(\ell)$  space as opposed to O(d), where  $l \ll d$ 

- ▶ to produce estimates *g<sub>i</sub>*, s.t.
- ▶  $|f_i g_i| \le n/\ell$ , for all item types *i* simultaneously.

Matrix setting. Use Frequent-directions to uncover any direction in space *x* 

- for which  $||Ax||^2 \ge \varepsilon ||A||_2^2$ ,
- ▶ by taking  $\ell > 2r/\varepsilon$ , where r is the numerical rank of A.

<sup>&</sup>lt;sup>2</sup>[Misra and Gries, 1982; Demaine et al., 2002; Karp et al., 2003; Metwally, 2005]



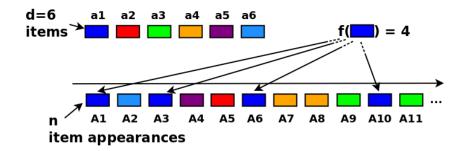
#### Item frequency estimation

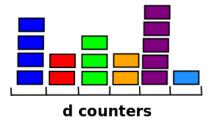
The algorithm:

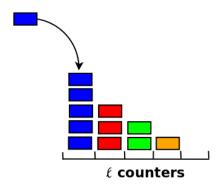
#### Input:

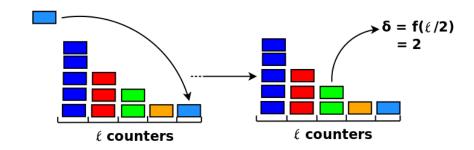
- ▶ d items a<sub>1</sub>, a<sub>2</sub>, ..., a<sub>d</sub>
   ▶ n item appearances A<sub>1</sub>, A<sub>2</sub>, ..., A<sub>n</sub>
- Repeat until there are less than ℓ unique items left {
  - ▶ Get item  $A_i$  from stream, for  $j = 1 \dots n$
  - If there are free slots among ℓ
    - Create new bucket for item type k and store the item there
  - ► Else
    - ▶ Find median count  $\delta_t = f_{\ell/2}$  of items, and
    - ▶ Remove exactly min  $(\delta_t, f_i)$  appearances from each bucket  $i = 1 \dots \ell$

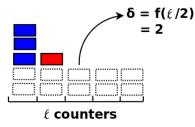
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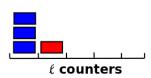


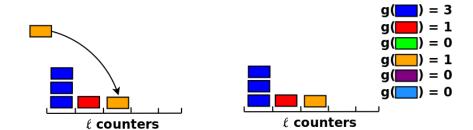












Claim. For each item type i,

- ▶  $g_i$  is a good approximation for its true frequency  $f_i$  (even in the case of  $g_i = 0$ ),
- ▶ 'Good':  $|f_i g_i| \le n/\ell$ .



#### Proof.

- ► Each item-type is deleted at most once per iteration:
  - $ightharpoonup q_i < f_i$
- ▶ Each counter is decreased by at most  $\delta_t$  at time t:

• 
$$g_i \ge f_i - \sum_t \delta_t \Leftrightarrow f_i - g_i \le \sum_t \delta_t$$

- Putting this together:
  - ▶  $0 \le \sum_i g_i \le \sum_t 1 (\ell/2) \cdot \delta_t = n (\ell/2) \cdot \sum_t \delta_t$
  - $\blacktriangleright \sum_t \delta_t \leq 2n/\ell$
- ▶ Set  $\ell = 2/\varepsilon$ :
  - ▶  $|f_i g_i| \le \varepsilon n$ .



- ... What is the intuition of the following? ...
  - ▶ If one sets  $\ell > 1/\varepsilon$ ,
    - Then any item that appears more than εn times in the stream must appear in the final sketch.

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#### The *Frequent-directions* algorithm

Represent the frequency of a direction (unit vector):

Assume the directions of A are indicator vectors of the items:

$$A = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix}$$

- ► Frequency of second item  $e_2 = (0, 1, 0, 0)^T$ :  $||Ae_2||^2 = ||(0, 1, 0, 1)^T||^2 = 0^2 + 1^2 + 0^2 + 1^2 = 2.$
- ► Generalize the directions to unit vector  $\{x : ||x|| = 1\}$  and the frequency of a direction is  $||Ax||^2$ .

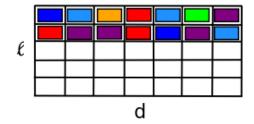
#### Connection to SVD of A:

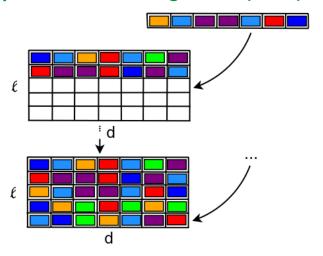
- $A = U\Sigma V^T \Leftrightarrow U^T A = \Sigma V^T \Leftrightarrow Au = \sigma v.$
- ►  $||Au||^2 = ||\sigma v||^2 = \sigma^2$ .

#### Change u to x:

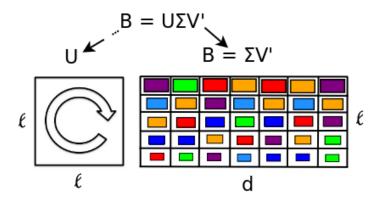
The frequency of a direction is indicated by the square of corresponding singular value  $\sigma^2$ .

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The algorithm:
   Input: \ell, A \in \mathbb{R}^{n \times d}
    B \leftarrow \text{all zeros matrix} \in \mathbb{R}^{\ell \times d}
   for i = 1, \ldots, n do
          Insert ith row of A into zero valued row of B
          if B has no zero valued rows then
                [U, \Sigma, V] \leftarrow SVD(B)
                C \leftarrow \Sigma V^T // for proof
               \delta \leftarrow \sigma_{\ell/2}^2
                \breve{\Sigma} \leftarrow \sqrt{\text{max}(\Sigma^2 - \textit{I}_{\ell}\delta, 0)}
                B \leftarrow \Sigma V^T
         end if
   end for
```

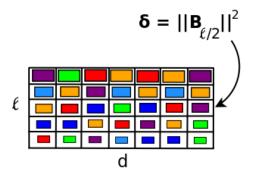




 $[U, \Sigma, V] \leftarrow SVD(B)$ .

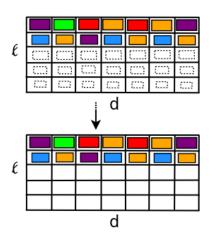


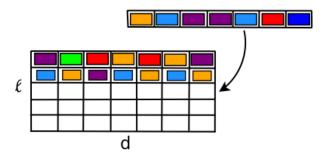
$$\delta \leftarrow \sigma_{\ell/2}^2$$
.



# The *Frequent-directions* algorithm (cont.) $\overset{\Sigma}{\Sigma} \leftarrow \sqrt{\max(\Sigma^2 - I_\ell \delta, 0)} \\ \mathcal{B} \leftarrow \overset{\Sigma}{\Sigma} \mathcal{V}^T$

$$\overset{\mathsf{\Sigma}}{\Sigma} \leftarrow \sqrt{\max(\Sigma^2 - I_{\ell}\delta, 0)} \\
B \leftarrow \overset{\mathsf{\Sigma}}{\Sigma} V^{\mathsf{T}}$$





## Properties of the sketch matrix B

#### In summary:

- ►  $A^TA \succeq B^TB \succeq 0$ .
- $||A^TA B^TB|| \le 2||A||_f^2/\ell.$
- ▶ Let  $A = [A_1; A_2]$  and  $B_1$ ,  $B_2$  is the sketches of  $A_1$  and  $A_2$ . A sketch C of  $B = [B_1; B_2]$  can be shown that:

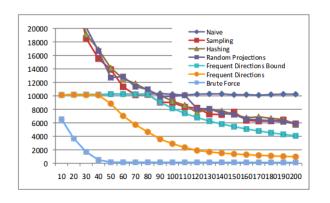
$$||A^T A - C^T C|| \le 2||A||_f^2/\ell.$$

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#### **Experiments**

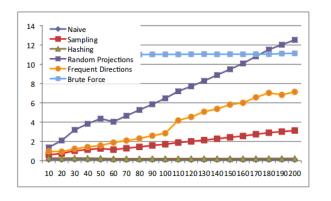
For a synthetic matrix n = 10000, m = 1000. Error  $||A^TA - B^TB||$  against sketch size  $\ell$  with.





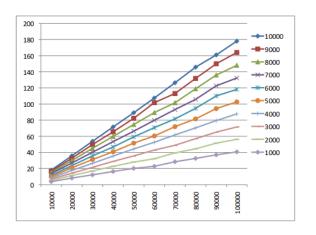
#### **Experiments (cont.)**

#### Running time.

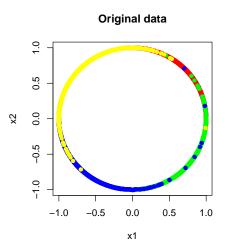


#### **Experiments (cont.)**

Linear in n and m ( $\ell$  fix to 100).



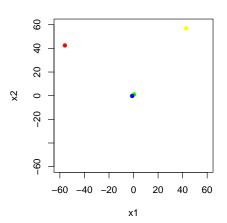
# **Clustering experiment**





## **Clustering experiment (cont.)**

#### K-means on Sketch



## Clustering experiment (cont.)

$$B = \begin{pmatrix} 43.0030 & 56.8110 \\ -55.9340 & 32.3390 \\ 0.5011 & 0.8654 \\ -0.9427 & -0.3336 \\ 0 & 0 \\ \vdots & \vdots \end{pmatrix}$$

$$A^{T}A = \begin{pmatrix} 4979.0 & 75.7 \\ 75.7 & 5021.0 \end{pmatrix}, B^{T}B = \begin{pmatrix} 4979.0 & 75.6 \\ 75.6 & 5020.9 \end{pmatrix}$$

#### **Conclusion**

- ▶ In terms of  $||A^TA B^TB||$ , the proposed sketching algorithm is more accurate than sampling, hashing and random projections.
- The proposed algorithm runs reasonably fast
  - ▶ in fact, faster than random projection, slower than sampling.
- The proposed algorithm is linear in the scale of the input size.
- Choose your sketching algorithm according to your task!

## Thank you!

Questions?

#### References



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