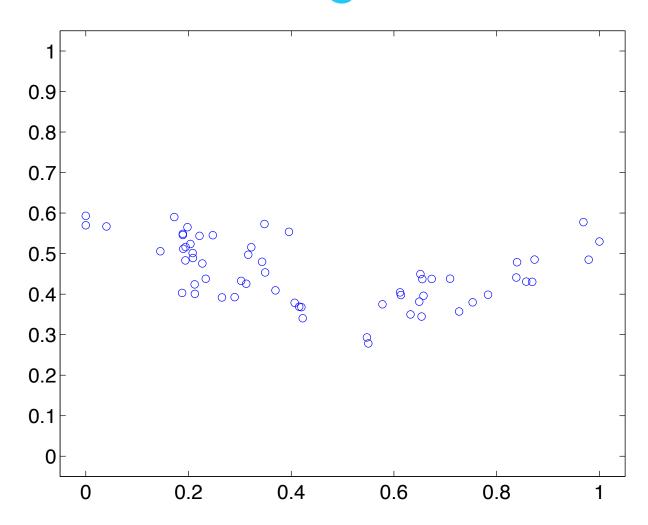
### Bias Variance Trade-Off, Regularization, Early Stopping, Dropout

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# Example 1: We want to fit a curve for the following data!



### **Example 1: continue**

Here we want to fit a polynomial of degree p as follows.

$$y = w_0 + w_1 x + w_2 x^2 + \ldots + w_p x^p$$

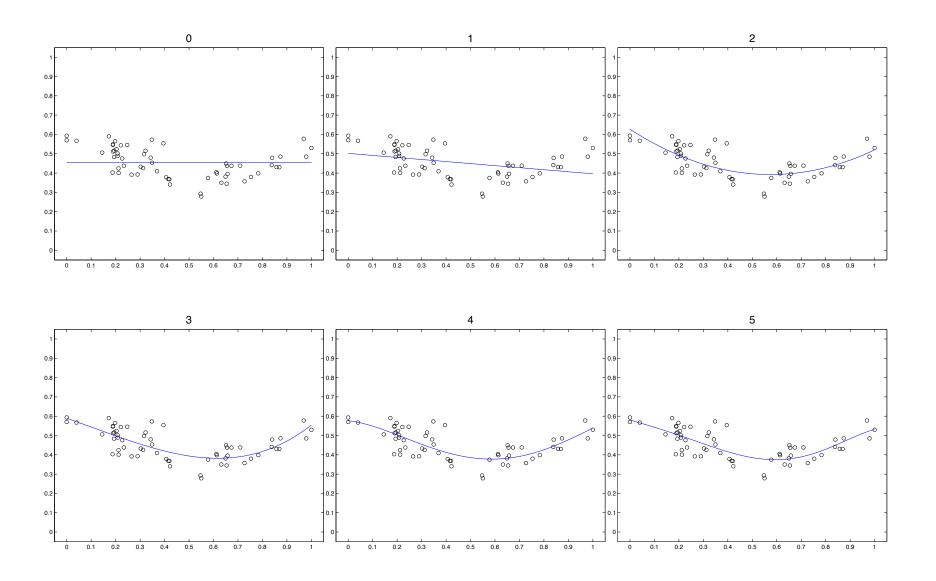
- Training data =  $\{(x_1,y_1),\ldots,(x_N,y_N)\}$
- Test data =  $\{(x_{N+1}, y_{N+1}), \dots, (x_M, y_M)\}$
- Objective function:

Training Error = 
$$\frac{1}{2} \sum_{i=1}^{N} (w_0 + w_1 x_i + w_2 x_i^2 + \ldots + w_p x_i^p - y_i)^2$$

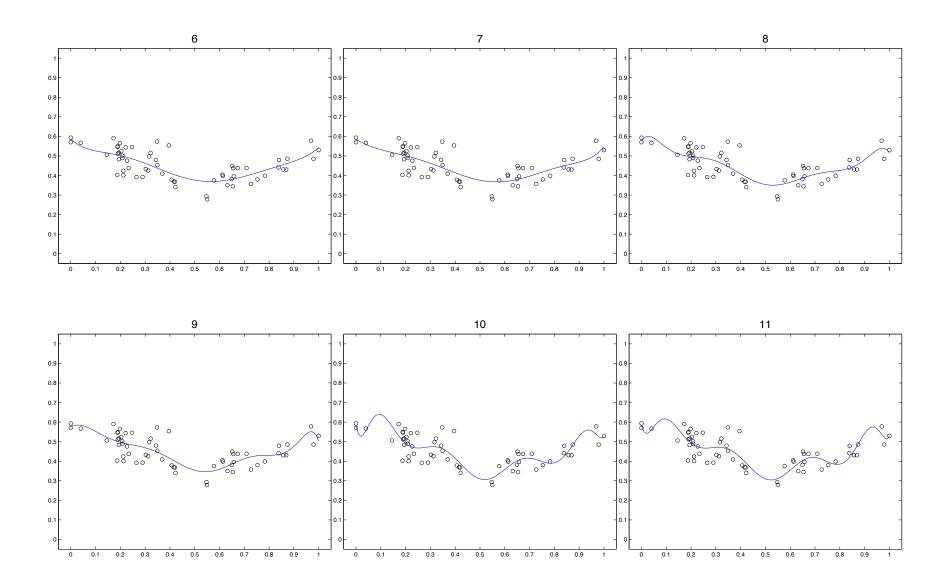
### Performance on unseen data

Test Error = 
$$\frac{1}{2} \sum_{i=N+1}^{M} (w_0 + w_1 x_i + w_2 x_i^2 + \dots + w_p x_i^p - y_i)^2$$

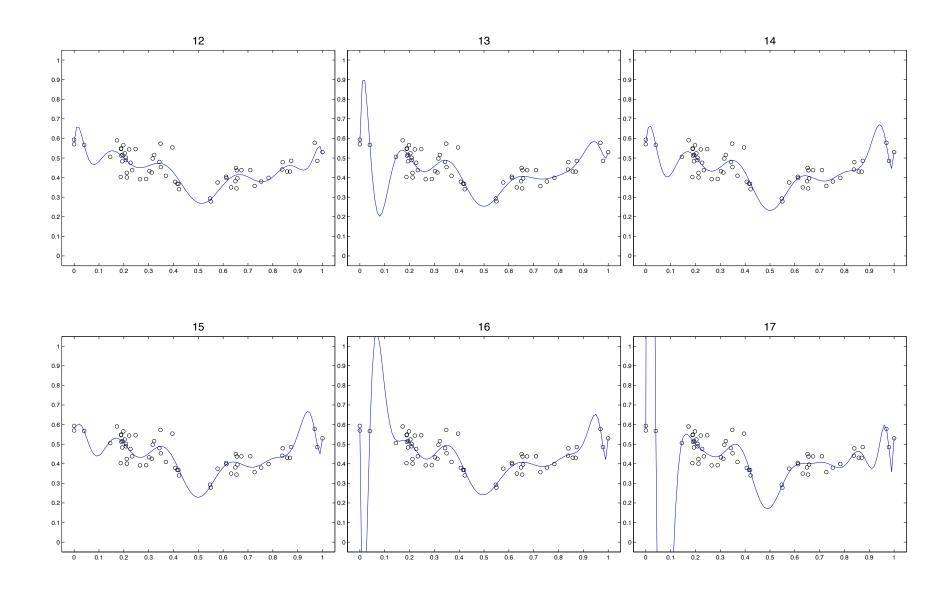
### Example 1: Fitted curve for p=0,1,2,3,4,5



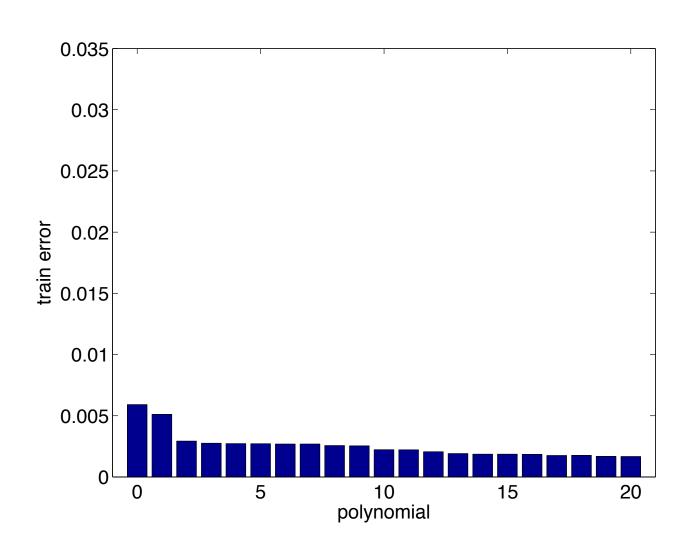
### Example 1: Fitted curve for p=6,7,8,9,10,11



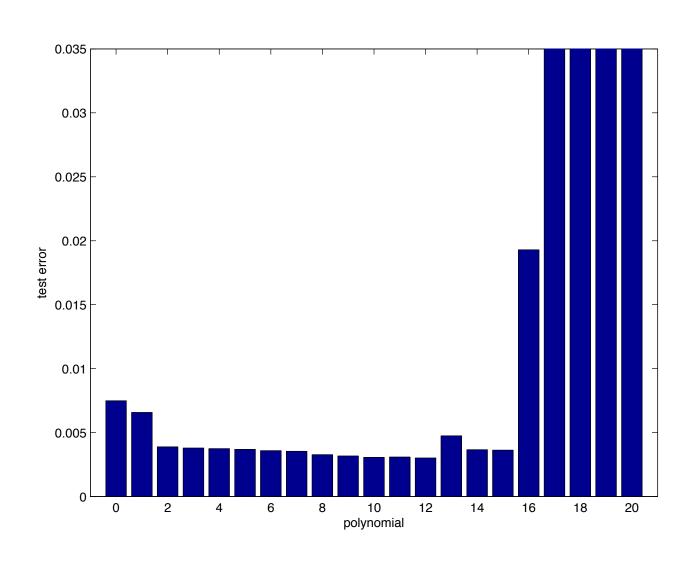
### Example 1: Fitted curve for p=12,13,14,15,16,17



### **Example 1: Training Error**



## **Example1: Test Error**



### **Bias Variance Tradeoff**

- For very low **p**, the model is very simple, and so can't capture the full complexities of the data. It "underfits" the data. This is called **bias**.
- For very high **p**, the model is complex, and so tends to "overfit" to spurious properties of the data. This is called **variance**.

### Formalizing Bias and Variance

#### Given data set

■ 
$$\mathbf{D} = \{(x_1, y_1), ..., (x_N, y_N)\}$$

And model built from data set,

•  $f(x; \mathcal{D})$ 

We can evaluate the effectiveness of the model using mean squared error:

• MSE = 
$$E_{p(x,y,\mathcal{D})} \left[ \left( y - f(x;\mathcal{D}) \right)^2 \right]$$

• with constant  $|\mathcal{D}| = N$ 

$$\mathbb{E}[L] = \iint L(t, y(\mathbf{x})) p(\mathbf{x}, t) \, d\mathbf{x} \, dt.$$
 (1.86)

A common choice of loss function in regression problems is the squared loss given by  $L(t, y(\mathbf{x})) = \{y(\mathbf{x}) - t\}^2$ . In this case, the expected loss can be written

$$\mathbb{E}[L] = \iint \{y(\mathbf{x}) - t\}^2 p(\mathbf{x}, t) \, d\mathbf{x} \, dt. \tag{1.87}$$

Our goal is to choose  $y(\mathbf{x})$  so as to minimize  $\mathbb{E}[L]$ . If we assume a completely flexible function  $y(\mathbf{x})$ , we can do this formally using the calculus of variations to give

$$\frac{\delta \mathbb{E}[L]}{\delta y(\mathbf{x})} = 2 \int \{y(\mathbf{x}) - t\} p(\mathbf{x}, t) \, \mathrm{d}t = 0.$$
 (1.88)

Solving for  $y(\mathbf{x})$ , and using the sum and product rules of probability, we obtain

$$y(\mathbf{x}) = \frac{\int tp(\mathbf{x}, t) dt}{p(\mathbf{x})} = \int tp(t|\mathbf{x}) dt = \mathbb{E}_t[t|\mathbf{x}]$$
(1.89)

$$\{y(\mathbf{x}) - t\}^2 = \{y(\mathbf{x}) - \mathbb{E}[t|\mathbf{x}] + \mathbb{E}[t|\mathbf{x}] - t\}^2$$
$$= \{y(\mathbf{x}) - \mathbb{E}[t|\mathbf{x}]\}^2 + 2\{y(\mathbf{x}) - \mathbb{E}[t|\mathbf{x}]\}\{\mathbb{E}[t|\mathbf{x}] - t\} + \{\mathbb{E}[t|\mathbf{x}] - t\}^2$$

### The Bias-Variance Decomposition (1)

Recall the expected squared loss,

$$\mathbb{E}[L] = \int \{y(\mathbf{x}) - \mathbb{E}[t|\mathbf{x}]\}^2 p(\mathbf{x}) d\mathbf{x} + \int \operatorname{var}[t|\mathbf{x}] p(\mathbf{x}) d\mathbf{x}$$

Lets denote, for simplicity:

$$h(\mathbf{x}) = \mathbb{E}[t|\mathbf{x}] = \int tp(t|\mathbf{x}) dt.$$

- We said that the second term corresponds to the noise inherent in the random variable t.
- What about the first term?

### The Bias-Variance Decomposition (2)

- Suppose we were given multiple data sets, each of size N.
- Any particular data set, D, will give a particular function y(x; D).
- Consider the error in the estimation:

$$\{y(\mathbf{x}; \mathcal{D}) - h(\mathbf{x})\}^{2}$$

$$= \{y(\mathbf{x}; \mathcal{D}) - \mathbb{E}_{\mathcal{D}}[y(\mathbf{x}; \mathcal{D})] + \mathbb{E}_{\mathcal{D}}[y(\mathbf{x}; \mathcal{D})] - h(\mathbf{x})\}^{2}$$

$$= \{y(\mathbf{x}; \mathcal{D}) - \mathbb{E}_{\mathcal{D}}[y(\mathbf{x}; \mathcal{D})]\}^{2} + \{\mathbb{E}_{\mathcal{D}}[y(\mathbf{x}; \mathcal{D})] - h(\mathbf{x})\}^{2}$$

$$+ 2\{y(\mathbf{x}; \mathcal{D}) - \mathbb{E}_{\mathcal{D}}[y(\mathbf{x}; \mathcal{D})]\}\{\mathbb{E}_{\mathcal{D}}[y(\mathbf{x}; \mathcal{D})] - h(\mathbf{x})\}.$$

### The Bias-Variance Decomposition (3)

$$\{y(\mathbf{x}; \mathcal{D}) - h(\mathbf{x})\}^{2}$$

$$= \{y(\mathbf{x}; \mathcal{D}) - \mathbb{E}_{\mathcal{D}}[y(\mathbf{x}; \mathcal{D})] + \mathbb{E}_{\mathcal{D}}[y(\mathbf{x}; \mathcal{D})] - h(\mathbf{x})\}^{2}$$

$$= \{y(\mathbf{x}; \mathcal{D}) - \mathbb{E}_{\mathcal{D}}[y(\mathbf{x}; \mathcal{D})]\}^{2} + \{\mathbb{E}_{\mathcal{D}}[y(\mathbf{x}; \mathcal{D})] - h(\mathbf{x})\}^{2}$$

$$+ 2\{y(\mathbf{x}; \mathcal{D}) - \mathbb{E}_{\mathcal{D}}[y(\mathbf{x}; \mathcal{D})]\}\{\mathbb{E}_{\mathcal{D}}[y(\mathbf{x}; \mathcal{D})] - h(\mathbf{x})\}.$$

Taking the expectation over D yields:

$$\mathbb{E}_{\mathcal{D}} \left[ \{ y(\mathbf{x}; \mathcal{D}) - h(\mathbf{x}) \}^{2} \right]$$

$$= \underbrace{\{ \mathbb{E}_{\mathcal{D}} [y(\mathbf{x}; \mathcal{D})] - h(\mathbf{x}) \}^{2}}_{\text{(bias)}^{2}} + \underbrace{\mathbb{E}_{\mathcal{D}} \left[ \{ y(\mathbf{x}; \mathcal{D}) - \mathbb{E}_{\mathcal{D}} [y(\mathbf{x}; \mathcal{D})] \}^{2} \right]}_{\text{variance}}.$$

### The Bias-Variance Decomposition (4)

#### Thus we can write

#### where

expected 
$$loss = (bias)^2 + variance + noise$$

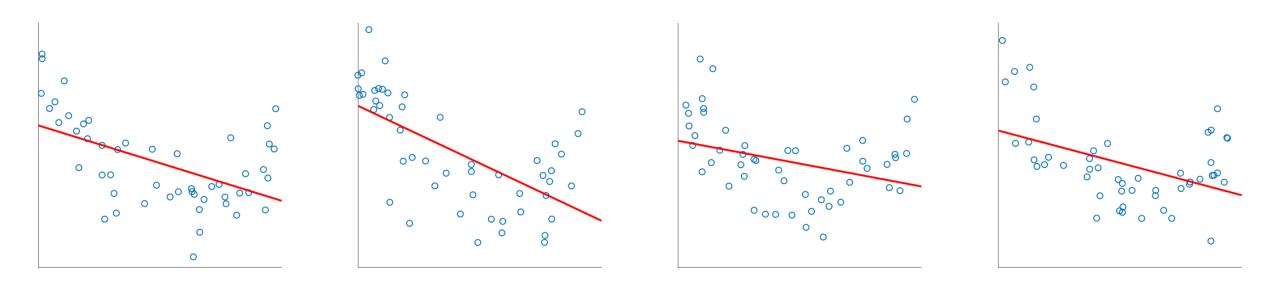
$$(\text{bias})^{2} = \int \{\mathbb{E}_{\mathcal{D}}[y(\mathbf{x}; \mathcal{D})] - h(\mathbf{x})\}^{2} p(\mathbf{x}) d\mathbf{x}$$

$$\text{variance} = \int \mathbb{E}_{\mathcal{D}} \left[ \{y(\mathbf{x}; \mathcal{D}) - \mathbb{E}_{\mathcal{D}}[y(\mathbf{x}; \mathcal{D})]\}^{2} \right] p(\mathbf{x}) d\mathbf{x}$$

$$\text{noise} = \iint \{h(\mathbf{x}) - t\}^{2} p(\mathbf{x}, t) d\mathbf{x} dt$$

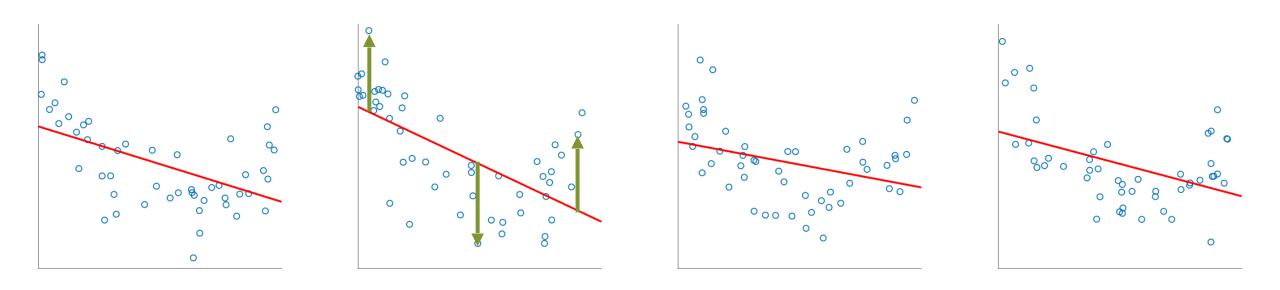
- W
  - Bias measures how much the prediction (averaged over all data sets) differs from the desired regression function.
  - Variance measures how much the predictions for individual data sets vary around their average.
  - There is a trade-off between bias and variance
  - As we increase model complexity,
  - bias decreases (a better fit to data) and
  - variance increases (fit varies more with data)

### **Example2: Bias**



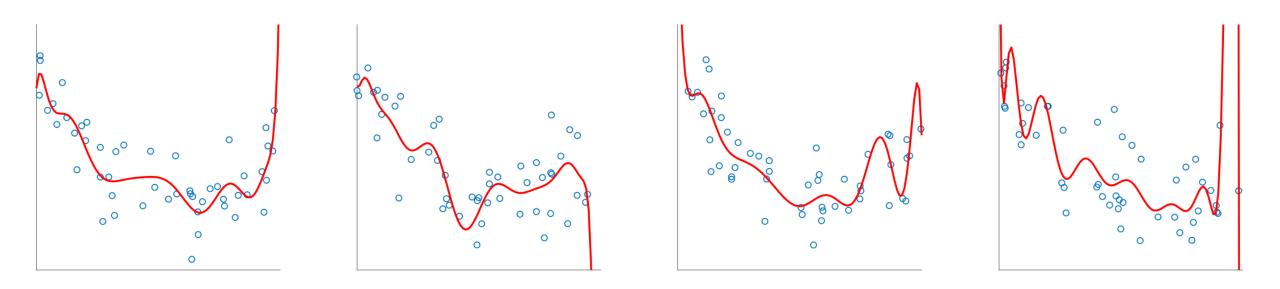
Linear model learnt on different training samples. Regardless of training sample, or size of training sample, model will produce consistent errors

### **Example2: Bias**



Linear model learnt on different training samples. Regardless of training sample, or size of training sample, model will produce consistent errors

### **Example2: Variance**



Keeping the degree p very high. Different samples of training data yield different model fits

$$MSE_{x} = E_{\mathcal{D}|x} \left[ (y - f(x; \mathcal{D}))^{2} \right]$$

$$= (E_{\mathcal{D}}[f(x; \mathcal{D})] - E[y|x])^{2}$$

$$+ E_{\mathcal{D}}[(f(x; \mathcal{D}) - E_{\mathcal{D}}[f(x; \mathcal{D})])^{2}]$$

$$+ E[(y - E[y|x])^{2}]$$

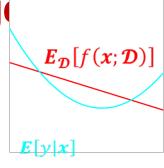
$$\text{MSE}_{x} = E_{\mathcal{D}|x} \left[ \left( y - f(x; \mathcal{D}) \right)^{2} \right]$$
 bias: 
$$= \left( E_{\mathcal{D}}[f(x; \mathcal{D})] - E[y|x] \right)^{2}$$
 difference 
$$+ E_{\mathcal{D}}[\left( f(x; \mathcal{D}) - E_{\mathcal{D}}[f(x; \mathcal{D})] \right)^{2} \right]$$
 between average model prediction 
$$+ E[\left( y - E[y|x] \right)^{2} \right]$$

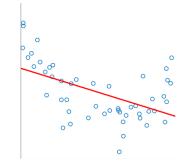
and the targe

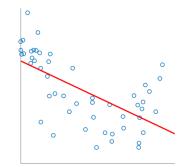
(across data sets)

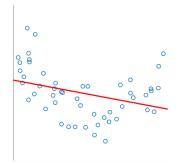
bias:

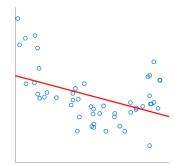
difference











$$\mathsf{MSE}_{x} = E_{\mathcal{D}|x} \left[ \left( y - f(x; \mathcal{D}) \right)^{2} \right]$$

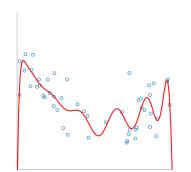
$$= \left( E_{\mathcal{D}} [f(x; \mathcal{D})] - E[y|x] \right)^{2}$$

$$\mathsf{variance of}$$

$$+ E_{\mathcal{D}} [\left( f(x; \mathcal{D}) - E_{\mathcal{D}} [f(x; \mathcal{D})] \right)^{2} \right]$$

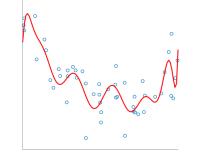
$$\mathsf{models (across}$$

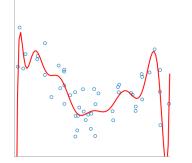
$$\mathsf{data sets) for a}$$

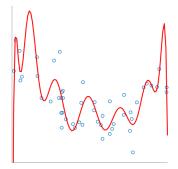


variance of

given point

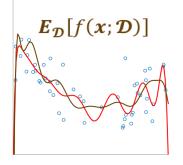


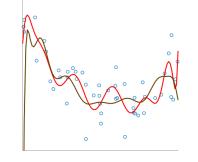


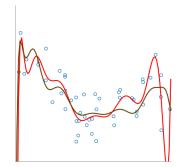


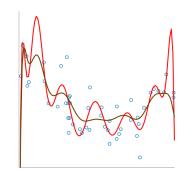
$$\begin{aligned} \text{MSE}_{\boldsymbol{x}} &= \boldsymbol{E}_{\mathcal{D}|\boldsymbol{x}} \left[ \left( \boldsymbol{y} - f(\boldsymbol{x}; \boldsymbol{\mathcal{D}}) \right)^2 \right] \\ &= \left( \boldsymbol{E}_{\mathcal{D}} [f(\boldsymbol{x}; \boldsymbol{\mathcal{D}})] - \boldsymbol{E}[\boldsymbol{y}|\boldsymbol{x}] \right)^2 \\ &+ \boldsymbol{E}_{\mathcal{D}} [(f(\boldsymbol{x}; \boldsymbol{\mathcal{D}}) - \boldsymbol{E}_{\mathcal{D}} [f(\boldsymbol{x}; \boldsymbol{\mathcal{D}})])^2] \\ &+ \boldsymbol{E}[(\boldsymbol{y} - \boldsymbol{E}[\boldsymbol{y}|\boldsymbol{x}])^2] \end{aligned}$$

variance of models (across data sets) for a given point









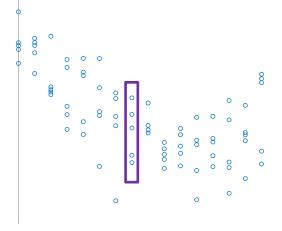
$$MSE_{x} = E_{\mathcal{D}|x} \left[ \left( y - f(x; \mathcal{D}) \right)^{2} \right]$$

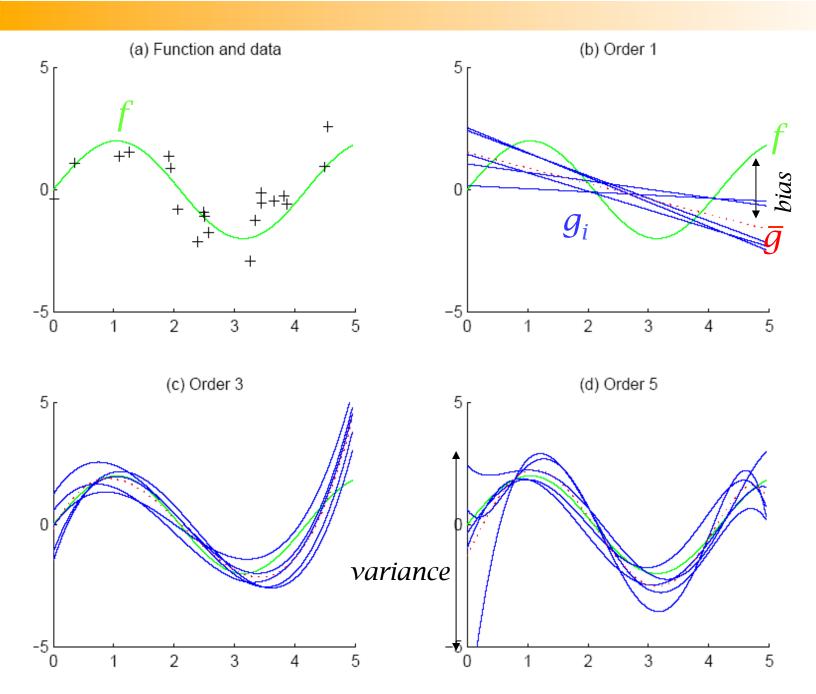
$$= \left( E_{\mathcal{D}} [f(x; \mathcal{D})] - E[y|x] \right)^{2}$$

$$+ E_{\mathcal{D}} \left[ \left( f(x; \mathcal{D}) - E_{\mathcal{D}} [f(x; \mathcal{D})] \right)^{2} \right]$$

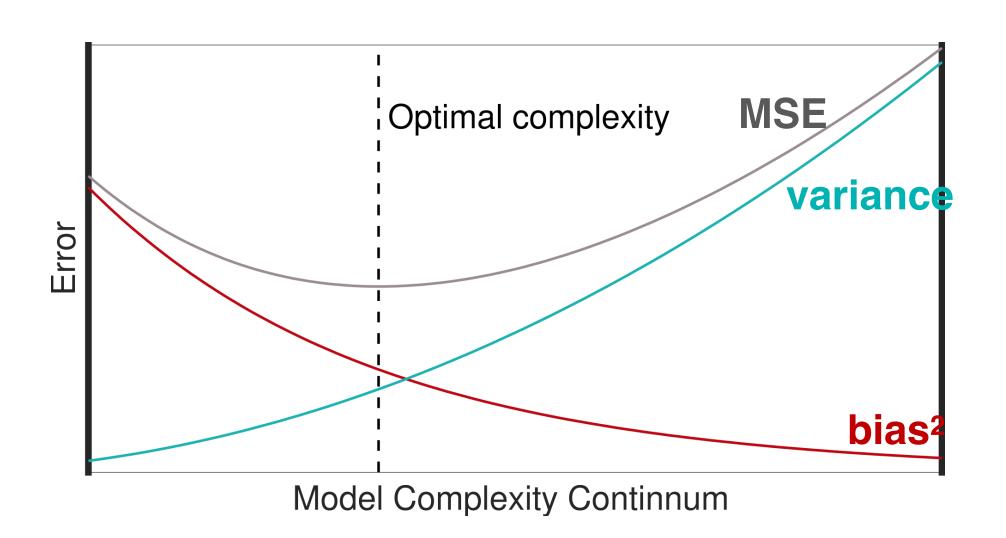
$$+ E[\left( y - E[y|x] \right)^{2}]$$

intrinsic noise in data set

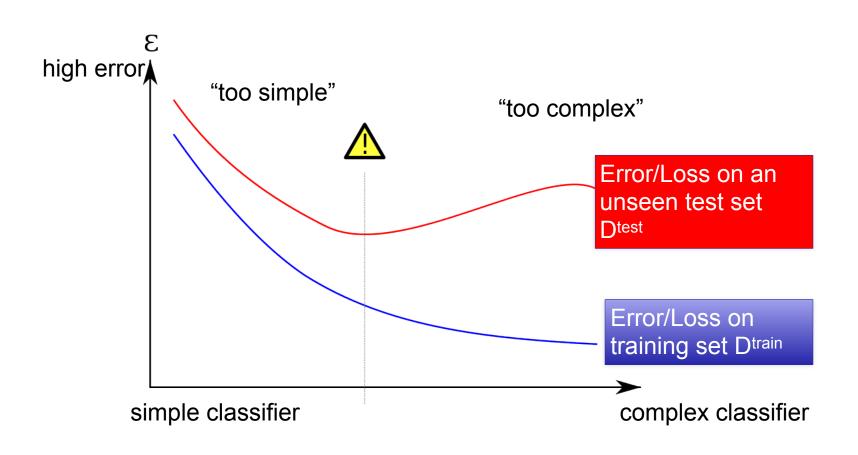




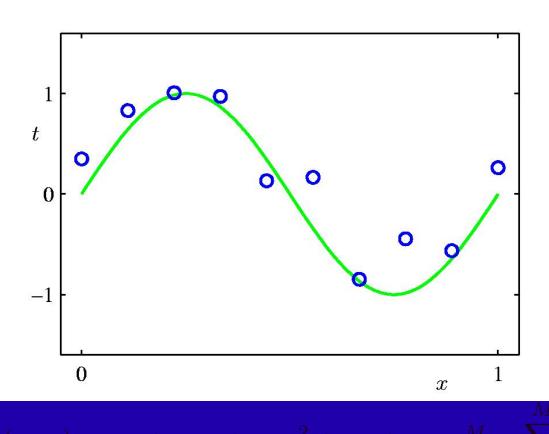
### **Bias-Variance Trade Off**



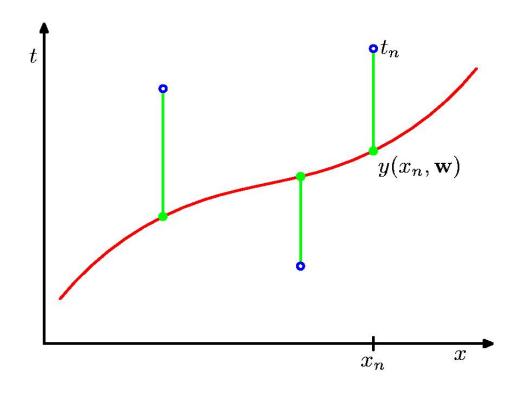
### Bias/Variance is a Way to Understand Overfitting and Underfitting



### **Polynomial Curve Fitting**

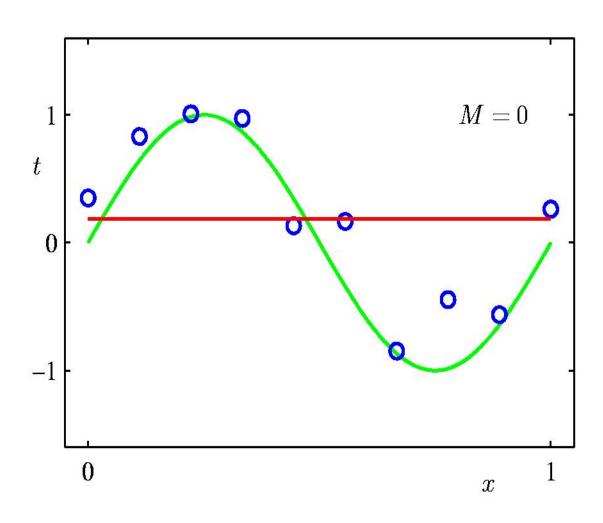


### **Sum-of-Squares Error Function**

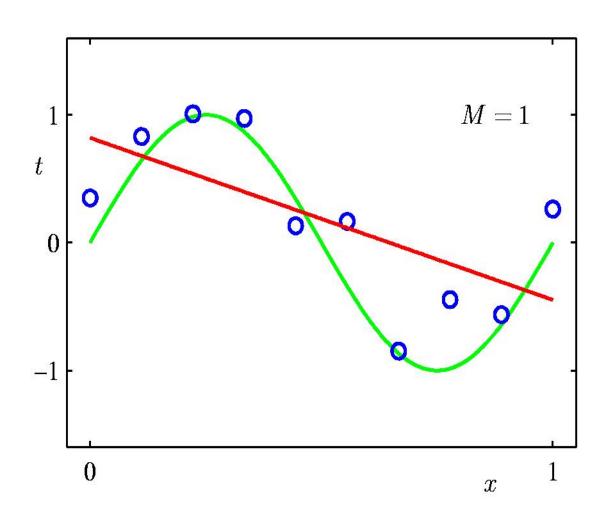


$$E(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^{N} \{y(x_n, \mathbf{w}) - t_n\}^2$$

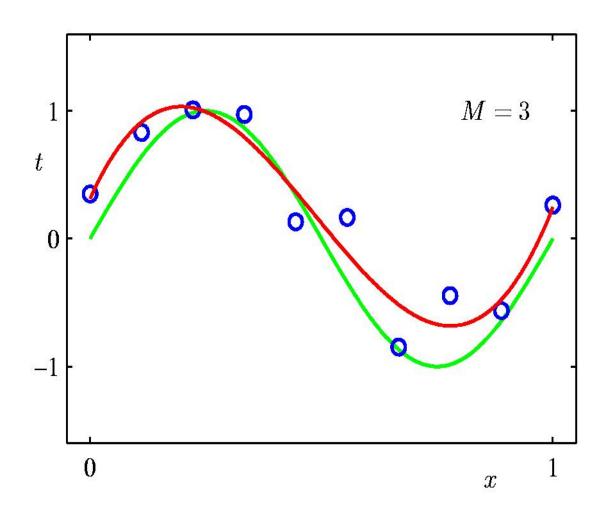
### Oth Order Polynomial



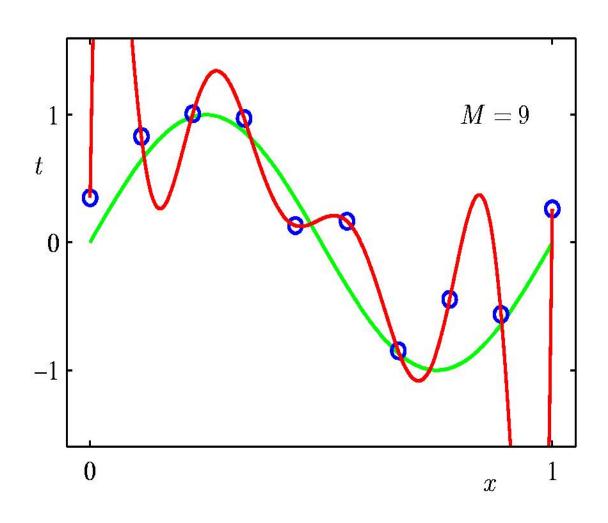
### 1st Order Polynomial



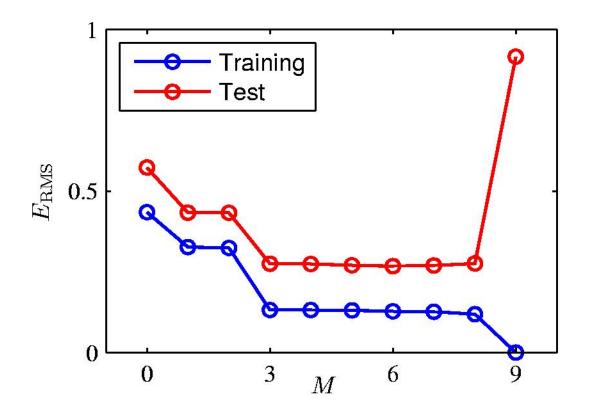
### 3<sup>rd</sup> Order Polynomial



### 9th Order Polynomial



### **Over-fitting**



Root-Mean-Square (RMS) Error:  $E_{\rm RMS} = \sqrt{2E(\mathbf{w}^\star)/N}$ 

# Polynomial Coefficients

	M=0	M = 1	M = 3	M = 9
$\overline{w_0^{\star}}$	0.19	0.82	0.31	0.35
$w_1^{\star}$		-1.27	7.99	232.37
$w_2^{\star}$			-25.43	-5321.83
$w_3^{\star}$			17.37	48568.31
$w_4^{\star}$				-231639.30
$w_5^{\star}$				640042.26
$w_6^{\star}$				-1061800.52
$w_7^\star$				1042400.18
$w_8^\star$				-557682.99
$w_9^{\star}$				125201.43