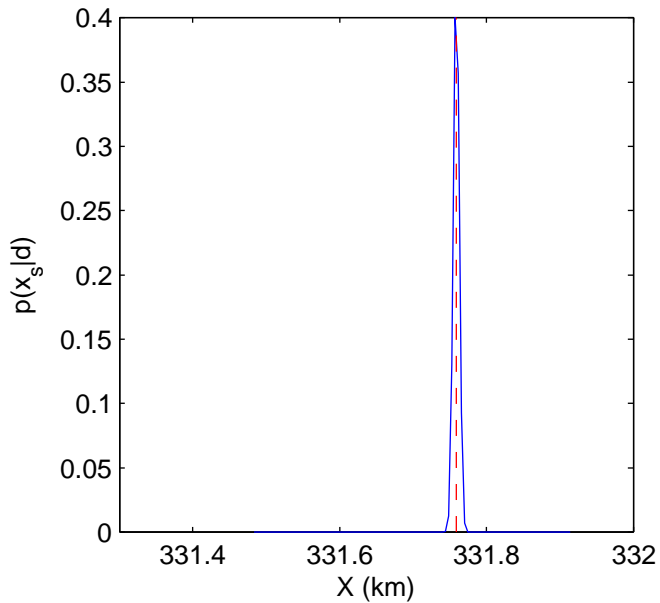


$x_s$  estimation $y_s$  estimation