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61. linearalgebra

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61.1 Introduction to linearalgebra

linearalgebra is a collection of functions for linear algebra.

Example:

```
(%i1) M : matrix ([1, 2], [1, 2]);
(%o1)
      [ 1 2 ]
      [ 1 2 ]
(%i2) nullspace (M);
(%o2)
      [ 1 ]
      [ 1 ]
      span([ 1 ])
      [ - ]
      [ 2 ]
(%i3) columnspace (M);
(%o3)
      [ 1 ]
      span([ ])
      [ 1 ]
(%i4) ptriangularize (M - z*ident(2), z);
(%o4)
      [ 1 2 - z ]
      [ 0 3 z - z ]
      [ 0 3 z - z ]
(%i5) M : matrix ([1, 2, 3], [4, 5, 6], [7, 8, 9]) - z*ident(3);
(%o5)
      [ 1 - z 2 3 ]
      [ 4 5 - z 6 ]
      [ 7 8 9 - z ]
(%i6) MM : ptriangularize (M, z);
(%o6)
      [ 4 5 - z 6 ]
      [ 0 66 z 102 z 132 ]
      [ 0 49 7 49 49 ]
      [ 0 0 49 z 245 z 147 z ]
      [ 0 0 264 88 44 ]
(%i7) algebraic : true;
(%o7) true
(%i8) tellrat (MM [3, 3]);
(%o8)
      3 2
      [z - 15 z - 18 z]
(%i9) MM : ratsimp (MM);
(%o9)
      [ 4 5 - z 6 ]
```

```

[
[
2
]
]
(%o9)
[
66      7 z  - 102 z - 132
[ 0  --  - ----- ]
[ 49      49
[
]
[ 0      0      0
]
]
(%i10) nullspace (MM);

[
1
]
[
]
[
2
]
[
z  - 14 z - 16
]
[
-----
]
(%o10) span([
8
])
[
]
[
2
]
[
z  - 18 z - 12
]
[
- -----
]
[
12
]
(%i11) M : matrix ([1, 2, 3, 4], [5, 6, 7, 8], [9, 10, 11, 12],
[13, 14, 15, 16]);

[ 1  2  3  4 ]
[
]
[ 5  6  7  8 ]
[
]
(%o11) [ 9  10 11 12 ]
[
]
[ 13 14 15 16 ]
]
(%i12) columnSpace (M);

[ 1 ] [ 2 ]
[
] [
]
[ 5 ] [ 6 ]
(%o12) span([ ], [ ])
[ 9 ] [ 10 ]
[
] [
]
[ 13 ] [ 14 ]
]
(%i13) apply ('orthogonal_complement, args (nullspace (transpose (M))));

[ 0 ] [ 1 ]
[
] [
]
[ 1 ] [ 0 ]
(%o13) span([ ], [ ])
[ 2 ] [ - 1 ]
[
] [
]
[ 3 ] [ - 2 ]
]

```

`@ref{Category: Linear algebra} · @ref{Category: Share packages} · @ref{Category: Package linearalgebra}`

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61.2 Functions and Variables for linearalgebra

Function: `addmatrices` (f, M_1, \dots, M_n)

Using the function f as the addition function, return the sum of the matrices M_1, \dots, M_n . The function f must accept any number of arguments (a Maxima nary function).

Examples:

```
(%i1) m1 : matrix([1,2],[3,4])$
(%i2) m2 : matrix([7,8],[9,10])$
(%i3) addmatrices('max,m1,m2);
(%o3) matrix([7,8],[9,10])
(%i4) addmatrices('max,m1,m2,5*m1);
(%o4) matrix([7,10],[15,20])
```

•

@ref{Category: Package linearalgebra}

Function: blockmatrixp (M)

Return true if and only if M is a matrix and every entry of M is a matrix.

•

@ref{Category: Package linearalgebra} · @ref{Category: Predicate functions}

Function: columnop (M, i, j, θ)

If M is a matrix, return the matrix that results from doing the column operation $C_i \leftarrow C_i - \theta * C_j$. If M doesn't have a row i or j , signal an error.

•

@ref{Category: Package linearalgebra}

Function: columnswap (M, i, j)

If M is a matrix, swap columns i and j . If M doesn't have a column i or j , signal an error.

•

@ref{Category: Package linearalgebra}

Function: columnspace (M)

If M is a matrix, return $\text{span}(v_1, \dots, v_n)$, where the set $\{v_1, \dots, v_n\}$ is a basis for the column space of M . The span of the empty set is $\{\emptyset\}$. Thus, when the column space has only one member, return $\text{span}()$.

•

@ref{Category: Package linearalgebra}

Function: copy (e)

Return a copy of the Maxima expression e . Although e can be any Maxima expression, the copy function is the most useful when e is either a list or a matrix; consider:

```
(%i1) m : [1,[2,3]]$
(%i2) mm : m$
(%i3) mm[2][1] : x$
(%i4) m;
(%o4) [1,[x,3]]
(%i5) mm;
(%o5) [1,[x,3]]
```

Let's try the same experiment, but this time let mm be a copy of m

```
(%i6) m : [1,[2,3]]$
(%i7) mm : copy(m)$
(%i8) mm[2][1] : x$
(%i9) m;
(%o9) [1,[2,3]]
(%i10) mm;
(%o10) [1,[x,3]]
```

This time, the assignment to mm does not change the value of m .

.

@ref{Category: Package linearalgebra}

Function: **cholesky** (M)

Function: **cholesky** (M , $field$)

Return the Cholesky factorization of the matrix selfadjoint (or hermitian) matrix M . The second argument defaults to 'generalring.' For a description of the possible values for $field$, see `lu_factor`.

.

@ref{Category: Matrix decompositions} · @ref{Category: Package linearalgebra}

Function: **ctranspose** (M)

Return the complex conjugate transpose of the matrix M . The function `ctranspose` uses `matrix_element_transpose` to transpose each matrix element.

.

@ref{Category: Package linearalgebra}

Function: **diag_matrix** (d_1, d_2, \dots, d_n)

Return a diagonal matrix with diagonal entries d_1, d_2, \dots, d_n . When the diagonal entries are matrices, the zero entries of the returned matrix are zero matrices of the appropriate size; for example:

```
(%i1) diag_matrix(diag_matrix(1,2),diag_matrix(3,4));
```

```
(%o1)
      [ [ 1  0 ] [ 0  0 ] ]
      [ [      ] [      ] ]
      [ [ 0  2 ] [ 0  0 ] ]
      [ [      ] [      ] ]
      [ [ 0  0 ] [ 3  0 ] ]
      [ [      ] [      ] ]
      [ [ 0  0 ] [ 0  4 ] ]
```

```
(%i2) diag_matrix(p,q);
```

```
(%o2)
      [ p  0 ]
      [      ]
      [ 0  q ]
```

.

@ref{Category: Package linearalgebra}

Function: `dotproduct` (u, v)

Return the dotproduct of vectors u and v . This is the same as `conjugate (transpose (u)) . v`. The arguments u and v must be column vectors.

.

@ref{Category: Package linearalgebra}

Function: `eigens_by_jacobi` (A)

Function: `eigens_by_jacobi` ($A, field_type$)

Computes the eigenvalues and eigenvectors of A by the method of Jacobi rotations. A must be a symmetric matrix (but it need not be positive definite nor positive semidefinite). $field_type$ indicates the computational field, either `floatfield` or `bigfloatfield`. If $field_type$ is not specified, it defaults to `floatfield`.

The elements of A must be numbers or expressions which evaluate to numbers via `float` or `bfloat` (depending on $field_type$).

Examples:

```
(%i1) S: matrix([1/sqrt(2), 1/sqrt(2)],[-1/sqrt(2), 1/sqrt(2)]);
```

```
(%o1)
      [      1      1 ]
      [ ----- ]
      [ sqrt(2) sqrt(2) ]
      [      ]
      [      1      1 ]
      [ - ----- ]
      [ sqrt(2) sqrt(2) ]
```

```
(%i2) L : matrix ([sqrt(3), 0], [0, sqrt(5)]);
      [ sqrt(3)      0 ]
```

```
(%02)          [      0      sqrt(5) ]
(%i3) M : S . L . transpose (S);
          [ sqrt(5)  sqrt(3)  sqrt(5)  sqrt(3) ]
          [ ----- + -----  ----- - ----- ]
          [      2      2      2      2      ]
(%03)      [ ]
          [ sqrt(5)  sqrt(3)  sqrt(5)  sqrt(3) ]
          [ ----- - -----  ----- + ----- ]
          [      2      2      2      2      ]
(%i4) eigens_by_jacobi (M);
The largest percent change was 0.1454972243679
The largest percent change was 0.0
number of sweeps: 2
number of rotations: 1
(%o4) [[1.732050807568877, 2.23606797749979],
          [ 0.70710678118655  0.70710678118655 ]
          [ - 0.70710678118655  0.70710678118655 ]
(%i5) float ([[sqrt(3), sqrt(5)], S]);
(%o5) [[1.732050807568877, 2.23606797749979],
          [ 0.70710678118655  0.70710678118655 ]
          [ - 0.70710678118655  0.70710678118655 ]
(%i6) eigens_by_jacobi (M, bigfloatfield);
The largest percent change was 1.454972243679028b-1
The largest percent change was 0.0b0
number of sweeps: 2
number of rotations: 1
(%o6) [[1.732050807568877b0, 2.23606797749979b0],
          [ 7.071067811865475b-1  7.071067811865475b-1 ]
          [ - 7.071067811865475b-1  7.071067811865475b-1 ]
```

•

`@ref{Category: Matrix decompositions} · @ref{Category: Package linearalgebra}`

Function: **get_lu_factors** (x)

When $x = \text{lu_factor}(A)$, then `get_lu_factors` returns a list of the form $[P, L, U]$, where P is a permutation matrix, L is lower triangular with ones on the diagonal, and U is upper triangular, and $A = P L U$.

.

@ref{Category: Package linearalgebra}

Function: **hankel** (*col*)

Function: **hankel** (*col*, *row*)

Return a Hankel matrix H . The first column of H is col ; except for the first entry, the last row of H is row . The default for row is the zero vector with the same length as col .

•

@ref{Category: Package linearalgebra}

Function: `hessian` (f, x)

Returns the Hessian matrix of f with respect to the list of variables x . The (i, j) -th element of the Hessian matrix is `diff($f, x[i], 1, x[j], 1$)`.

Examples:

```
(%i1) hessian (x * sin (y), [x, y]);
      [ 0      cos(y)  ]
(%o1)  [          ]
      [ cos(y) - x sin(y) ]
(%i2) depends (F, [a, b]);
(%o2)  [F(a, b)]
(%i3) hessian (F, [a, b]);
      [ 2      2      ]
      [ d F    d F    ]
      [ ---    ----- ]
      [ 2      da db  ]
      [ da      ]
(%o3)  [          ]
      [ 2      2      ]
      [ d F    d F    ]
      [ -----    --- ]
      [ da db    2      ]
      [          db      ]
```

.

@ref{Category: Differential calculus} · @ref{Category: Package linearalgebra}

Function: `hilbert_matrix` (n)

Return the n by n Hilbert matrix. When n isn't a positive integer, signal an error.

.

@ref{Category: Package linearalgebra}

Function: `identfor` (M)

Function: `identfor` (M, fld)

Return an identity matrix that has the same shape as the matrix M . The diagonal entries of the identity matrix are the multiplicative identity of the field fld ; the default for fld is *generalring*.

The first argument M should be a square matrix or a non-matrix. When M is a matrix, each entry of M can be a square matrix - thus M can be a blocked Maxima matrix. The matrix can be blocked to any (finite) depth.

See also `zerofor`

•
@ref{Category: Package linearalgebra}

Function: `invert_by_lu` (M , (*rng generalring*))

Invert a matrix M by using the LU factorization. The LU factorization is done using the ring *rng*.

•
@ref{Category: Package linearalgebra}

Function: `jacobian` (f , x)

Returns the Jacobian matrix of the list of functions f with respect to the list of variables x . The (i , j)-th element of the Jacobian matrix is `diff(f[i], x[j])`.

Examples:

```
(%i1) jacobian ([sin (u - v), sin (u * v)], [u, v]);
      [ cos(v - u)  - cos(v - u) ]
(%o1)  [
      [ v cos(u v)   u cos(u v) ]
(%i2) depends ([F, G], [y, z]);
(%o2)  [F(y, z), G(y, z)]
(%i3) jacobian ([F, G], [y, z]);
      [ dF  dF ]
      [ --  -- ]
      [ dy  dz ]
(%o3)  [
      [ dG  dG ]
      [ --  -- ]
      [ dy  dz ]
```

•
@ref{Category: Differential calculus} · @ref{Category: Package linearalgebra}

Function: `kronecker_product` (A , B)

Return the Kronecker product of the matrices A and B .

•
@ref{Category: Package linearalgebra}

Function: `listp` (e , p)

Function: `listp` (e)

Given an optional argument p , return true if e is a Maxima list and p evaluates to true for every list element. When `listp` is not given the optional argument, return

true if e is a Maxima list. In all other cases, return false.

·
@ref{Category: Package linearalgebra} · @ref{Category: Predicate functions}

Function: `locate_matrix_entry` ($M, r_1, c_1, r_2, c_2, f, rel$)

The first argument must be a matrix; the arguments r_1 through c_2 determine a sub-matrix of M that consists of rows r_1 through r_2 and columns c_1 through c_2 .

Find a entry in the sub-matrix M that satisfies some property. Three cases:

(1) $rel = 'bool$ and f a predicate:

Scan the sub-matrix from left to right then top to bottom, and return the index of the first entry that satisfies the predicate f . If no matrix entry satisfies f , return false.

(2) $rel = 'max$ and f real-valued:

Scan the sub-matrix looking for an entry that maximizes f . Return the index of a maximizing entry.

(3) $rel = 'min$ and f real-valued:

Scan the sub-matrix looking for an entry that minimizes f . Return the index of a minimizing entry.

·
@ref{Category: Package linearalgebra}

Function: `lu_backsub` (M, b)

When $M = lu_factor(A, field)$, then `lu_backsub` (M, b) solves the linear system $A x = b$.

·
@ref{Category: Package linearalgebra}

Function: `lu_factor` ($M, field$)

Return a list of the form $[LU, perm, fld]$, or $[LU, perm, fld, lower-cnd, upper-cnd]$, where

(1) The matrix LU contains the factorization of M in a packed form. Packed form means three things: First, the rows of LU are permuted according to the list $perm$. If, for example, $perm$ is the list $[3, 2, 1]$, the actual first row of the LU factorization is the third row of the matrix LU . Second, the lower triangular factor of m is the lower triangular part of LU with the diagonal entries replaced by all ones. Third, the upper triangular factor of M is the upper triangular part of LU .

(2) When the field is either `floatfield` or `complexfield`, the numbers *lower-cnd* and *upper-cnd* are lower and upper bounds for the infinity norm condition number of M . For all fields, the condition number might not be estimated; for such fields, `lu_factor` returns a two item list. Both the lower and upper bounds can differ from their true values by arbitrarily large factors. (See also `mat_cond`.)

The argument M must be a square matrix.

The optional argument *fld* must be a symbol that determines a ring or field. The pre-defined fields and rings are:

(a) `generalring` - the ring of Maxima expressions, (b) `floatfield` - the field of floating point numbers of the type double, (c) `complexfield` - the field of complex floating point numbers of the type double, (d) `crering` - the ring of Maxima CRE expressions, (e) `rationalfield` - the field of rational numbers, (f) `runningerror` - track the all floating point rounding errors, (g) `noncommutingring` - the ring of Maxima expressions where multiplication is the non-commutative dot operator.

When the field is `floatfield`, `complexfield`, or `runningerror`, the algorithm uses partial pivoting; for all other fields, rows are switched only when needed to avoid a zero pivot.

Floating point addition arithmetic isn't associative, so the meaning of 'field' differs from the mathematical definition.

A member of the field `runningerror` is a two member Maxima list of the form $[x, n]$, where x is a floating point number and n is an integer. The relative difference between the 'true' value of x and x is approximately bounded by the machine epsilon times n . The running error bound drops some terms that of the order the square of the machine epsilon.

There is no user-interface for defining a new field. A user that is familiar with Common Lisp should be able to define a new field. To do this, a user must define functions for the arithmetic operations and functions for converting from the field representation to Maxima and back. Additionally, for ordered fields (where partial pivoting will be used), a user must define functions for the magnitude and for comparing field members. After that all that remains is to define a Common Lisp structure `mring`. The file `mring` has many examples.

To compute the factorization, the first task is to convert each matrix entry to a member of the indicated field. When conversion isn't possible, the factorization halts with an error message. Members of the field needn't be Maxima expressions. Members of the `complexfield`, for example, are Common Lisp complex numbers. Thus after computing the factorization, the matrix entries must be converted to Maxima expressions.

See also `get_lu_factors`.

Examples:

```
(%i1) w[i,j] := random (1.0) + %i * random (1.0);
(%o1)          w          := random(1.) + %i random(1.)
              i, j
(%i2) showtime : true$
Evaluation took 0.00 seconds (0.00 elapsed)
```

```
(%i3) M : genmatrix (w, 100, 100)$
Evaluation took 7.40 seconds (8.23 elapsed)
(%i4) lu_factor (M, complexfield)$
Evaluation took 28.71 seconds (35.00 elapsed)
(%i5) lu_factor (M, generalring)$
Evaluation took 109.24 seconds (152.10 elapsed)
(%i6) showtime : false$

(%i7) M : matrix ([1 - z, 3], [3, 8 - z]);
          [ 1 - z    3    ]
(%o7)      [          ]
          [    3    8 - z ]
(%i8) lu_factor (M, generalring);
          [ 1 - z    3    ]
          [          ]
(%o8)      [[    3          9    ], [1, 2], generalring]
          [ ----- - z - ----- + 8 ]
          [ 1 - z          1 - z    ]
(%i9) get_lu_factors (%);
          [    1    0 ] [ 1 - z    3    ]
          [ 1  0 ] [          ] [          ]
(%o9)      [[    ], [    3    ], [          9    ]]
          [ 0  1 ] [ ----- 1 ] [    0    - z - ----- + 8 ]
          [ 1 - z    ] [          1 - z    ]
(%i10) %[1] . %[2] . %[3];
          [ 1 - z    3    ]
(%o10)      [          ]
          [    3    8 - z ]
```

.

@ref{Category: Matrix decompositions} · @ref{Category: Package linearalgebra}

Function: **mat_cond** ($M, 1$)

Function: **mat_cond** (M, inf)

Return the p -norm matrix condition number of the matrix m . The allowed values for p are 1 and inf . This function uses the LU factorization to invert the matrix m . Thus the running time for **mat_cond** is proportional to the cube of the matrix size; **lu_factor** determines lower and upper bounds for the infinity norm condition number in time proportional to the square of the matrix size.

.

@ref{Category: Package linearalgebra}

Function: **mat_norm** ($M, 1$)

Function: **mat_norm** (M, inf)

Function: **mat_norm** ($M, frobenius$)

Return the matrix p -norm of the matrix M . The allowed values for p are 1, inf , and **frobenius** (the Frobenius matrix norm). The matrix M should be an unblocked matrix.

.

@ref{Category: Package linearalgebra}

Function: **matrixp** (e, p)

Function: **matrixp** (e)

Given an optional argument p , return `true` if e is a matrix and p evaluates to `true` for every matrix element. When **matrixp** is not given an optional argument, return `true` if e is a matrix. In all other cases, return `false`.

See also **blockmatrixp**

.

@ref{Category: Package linearalgebra} · @ref{Category: Predicate functions}

Function: **matrix_size** (M)

Return a two member list that gives the number of rows and columns, respectively of the matrix M .

.

@ref{Category: Package linearalgebra}

Function: **mat_fullunblocker** (M)

If M is a block matrix, unblock the matrix to all levels. If M is a matrix, return M ; otherwise, signal an error.

.

@ref{Category: Package linearalgebra}

Function: **mat_trace** (M)

Return the trace of the matrix M . If M isn't a matrix, return a noun form. When M is a block matrix, **mat_trace**(M) returns the same value as does **mat_trace**(**mat_unblocker**(m)).

.

@ref{Category: Package linearalgebra}

Function: **mat_unblocker** (M)

If M is a block matrix, unblock M one level. If M is a matrix, **mat_unblocker** (M) returns M ; otherwise, signal an error.

Thus if each entry of M is matrix, **mat_unblocker** (M) returns an unblocked matrix, but if each entry of M is a block matrix, **mat_unblocker** (M) returns a block matrix with one less level of blocking.

If you use block matrices, most likely you'll want to set `matrix_element_mult` to `"."` and `matrix_element_transpose` to `'transpose`. See also `mat_fullunblocker`.

Example:

```
(%i1) A : matrix ([1, 2], [3, 4]);
      [ 1 2 ]
(%o1) [ 3 4 ]
      [ 7 8 ]
(%i2) B : matrix ([7, 8], [9, 10]);
      [ 7 8 ]
(%o2) [ 9 10 ]
(%i3) matrix ([A, B]);
      [ [ 1 2 ] [ 7 8 ] ]
(%o3) [ [ 3 4 ] [ 9 10 ] ]
      [ [ 3 4 ] [ 9 10 ] ]
(%i4) mat_unblocker (%);
      [ 1 2 7 8 ]
(%o4) [ 3 4 9 10 ]
      [ 3 4 9 10 ]
```

.

@ref{Category: Package linearalgebra}

Function: **nonnegintegerp** (n)

Return true if and only if $n \geq 0$ and n is an integer.

.

@ref{Category: Package linearalgebra} · @ref{Category: Predicate functions}

Function: **nullspace** (M)

If M is a matrix, return `span (v_1, ..., v_n)`, where the set $\{v_1, \dots, v_n\}$ is a basis for the nullspace of M . The span of the empty set is $\{0\}$. Thus, when the nullspace has only one member, return `span ()`.

.

@ref{Category: Package linearalgebra}

Function: **nullity** (M)

If M is a matrix, return the dimension of the nullspace of M .

.

@ref{Category: Package linearalgebra}

Function: **orthogonal_complement** (v_1, \dots, v_n)

Return $\text{span}(u_1, \dots, u_m)$, where the set $\{u_1, \dots, u_m\}$ is a basis for the orthogonal complement of the set $\{v_1, \dots, v_n\}$.

Each vector v_1 through v_n must be a column vector.

·
@ref{Category: Package linearalgebra}

Function: **polynomialp** ($p, L, \text{coeffp}, \text{exponp}$)

Function: **polynomialp** (p, L, coeffp)

Function: **polynomialp** (p, L)

Return true if p is a polynomial in the variables in the list L , The predicate *coeffp* must evaluate to true for each coefficient, and the predicate *exponp* must evaluate to true for all exponents of the variables in L . If you want to use a non-default value for *exponp*, you must supply *coeffp* with a value even if you want to use the default for *coeffp*.

`polynomialp (p, L, coeffp)` is equivalent to `polynomialp (p, L, coeffp, 'nonnegintegerp)`.

`polynomialp (p, L)` is equivalent to `polynomialp (p, L, 'constantp, 'nonnegintegerp)`.

The polynomial needn't be expanded:

```
(%i1) polynomialp ((x + 1)*(x + 2), [x]);
(%o1) true
(%i2) polynomialp ((x + 1)*(x + 2)^a, [x]);
(%o2) false
```

An example using non-default values for *coeffp* and *exponp*:

```
(%i1) polynomialp ((x + 1)*(x + 2)^(3/2), [x], numberp, numberp);
(%o1) true
(%i2) polynomialp ((x^(1/2) + 1)*(x + 2)^(3/2), [x], numberp,
numberp);
(%o2) true
```

Polynomials with two variables:

```
(%i1) polynomialp (x^2 + 5*x*y + y^2, [x]);
(%o1) false
(%i2) polynomialp (x^2 + 5*x*y + y^2, [x, y]);
(%o2) true
```

·
@ref{Category: Package linearalgebra} · @ref{Category: Predicate functions}

Function: `polytocompanion` (p, x)

If p is a polynomial in x , return the companion matrix of p . For a monic polynomial p of degree n , we have $p = (-1)^n \text{charpoly}(\text{polytocompanion}(p, x))$.

When p isn't a polynomial in x , signal an error.

.

@ref{Category: Package linearalgebra}

Function: `ptriangularize` (M, v)

If M is a matrix with each entry a polynomial in v , return a matrix $M2$ such that

(1) $M2$ is upper triangular,

(2) $M2 = E_n \dots E_1 M$, where E_1 through E_n are elementary matrices whose entries are polynomials in v ,

(3) $|\det(M)| = |\det(M2)|$,

Note: This function doesn't check that every entry is a polynomial in v .

.

@ref{Category: Package linearalgebra}

Function: `rowop` (M, i, j, θ)

If M is a matrix, return the matrix that results from doing the row operation $R_i \leftarrow R_i - \theta R_j$. If M doesn't have a row i or j , signal an error.

.

@ref{Category: Package linearalgebra}

Function: `rank` (M)

Return the rank of that matrix M . The rank is the dimension of the column space.

Example:

```
(%i1) rank(matrix([1,2],[2,4]));
(%o1) 1
(%i2) rank(matrix([1,b],[c,d]));
Proviso: {d - b c # 0}
(%o2) 2
```

.

@ref{Category: Package linearalgebra}

Function: rowswap (M, i, j)

If M is a matrix, swap rows i and j . If M doesn't have a row i or j , signal an error.

.

@ref{Category: Package linearalgebra}

Function: toeplitz (col)**Function: toeplitz** (col, row)

Return a Toeplitz matrix T . The first column of T is col ; except for the first entry, the first row of T is row . The default for row is complex conjugate of col .

Example:

```
(%i1) toeplitz([1,2,3],[x,y,z]);
```

$$\begin{bmatrix} 1 & y & z \\ 2 & 1 & y \\ 3 & 2 & 1 \end{bmatrix}$$

```
(%i2) toeplitz([1,1+%i]);
```

$$\begin{bmatrix} 1 & 1 - \%I \\ \%I + 1 & 1 \end{bmatrix}$$

.

@ref{Category: Package linearalgebra}

Function: vandermonde_matrix ($[x_1, \dots, x_n]$)

Return a n by n matrix whose i -th row is $[1, x_i, x_i^2, \dots, x_i^{(n-1)}]$.

.

@ref{Category: Package linearalgebra}

Function: zerofor (M)**Function: zerofor** (M, fld)

Return a zero matrix that has the same shape as the matrix M . Every entry of the zero matrix is the additive identity of the field fld ; the default for fld is *generalring*.

The first argument M should be a square matrix or a non-matrix. When M is a matrix, each entry of M can be a square matrix - thus M can be a blocked Maxima matrix. The matrix can be blocked to any (finite) depth.

See also `identfor`

.

@ref{Category: Package linearalgebra}

Function: `zeromatrixp` (M)

If M is not a block matrix, return `true` if `is (equal (e, 0))` is true for each element e of the matrix M . If M is a block matrix, return `true` if `zeromatrixp` evaluates to `true` for each element of e .

.

@ref{Category: Package linearalgebra} · @ref{Category: Predicate functions}

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