Analysis of Algorithms 1 (Fall 2016) Istanbul Technical University Computer Eng. Dept.

Chapter 2: Getting Started



Course slides from
Leiserson's @MIT
Edmonds@York Un.
Ruan @UTSA
have been used in
preparation of these slides.

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Analysis of Algorithms 1, Dr. Tosun & Dr. Ekenel, Dept. of Computer Engineering, ITU

Outline

- Chapter 2
 - Insertion Sort
 - Pseudocode Conventions
 - Analysis of Insertion Sort
 - Loop Invariants and Correctness
 - Merge Sort
 - Divide and Conquer
 - Analysis of Merge Sort
- Chapter 3: Growth of Functions
 - Asymptotic notation
 - Comparison of functions
 - Standard notations and common functions

- Insertion sort used an incremental approach to sorting: sort the smallest subarray (1 item), add one more item to the subarray, sort it, add one more item, sort it, etc.
- Let us think about how the merge sort works.
 Basically, it uses a divide-and-conquer approach, based on the concept of recursion.

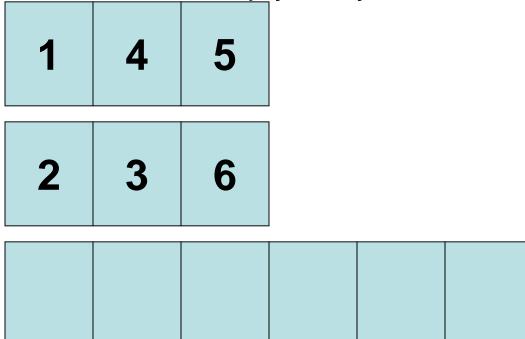
- Divide-and-conquer.
 - Divide the problem into several subproblems.
 - Conquer the subproblems by solving them recursively. If the subproblems are small enough, solve them directly.
 - Combine the solutions to the subproblems to get the solution for the original problem.

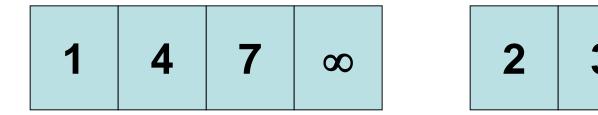
- Divide-and-conquer.
 - Divide the n-element sequence to be sorted into two subsequences of n/2 each.
 - Conquer by sorting the subsequences recursively by calling merge sort again. If the subsequences are small enough (of length 1), solve them directly. (Arrays of length 1 are already sorted.)
 - Combine the two sorted subsequences by merging them to get a sorted sequence.

- A is the (sub)array when the procedure is called.
- p, q, and r are indices numbering elements of the array such that p ≤ q ≤ r ; p is the lowest index and r is the highest index.

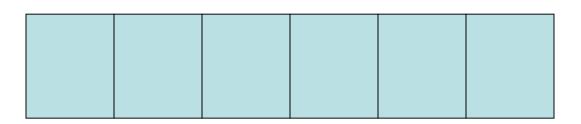
- Note that the merge sort basically consists of recursive calls to itself. The base case (which stops the recursion) occurs when a subsequence has a size of 1.
- The combine step is accomplished by a call to an algorithm called Merge.

 Without going into detail about how Merge-Sort works yet, let us take a look at the Merge part. Merge works by assuming you have two already-sorted sublists and an empty array:

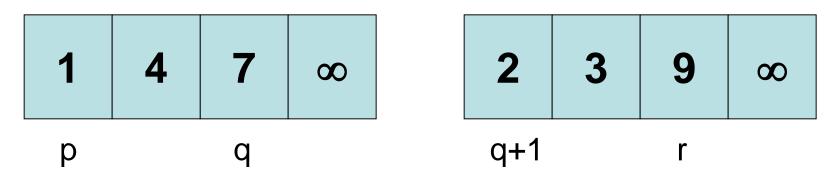




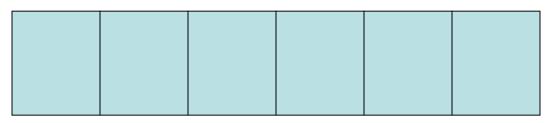
 Let us assume we have a sentinel (infinity, which is guaranteed to be larger than the last item) at the end of each sublist which lets us know when we have hit the end of the sublist.

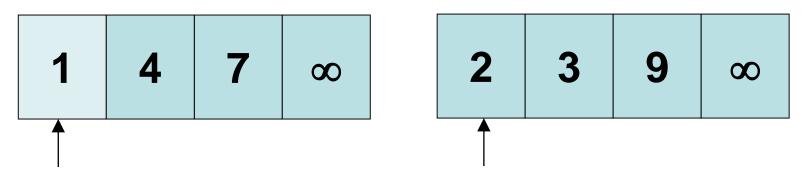


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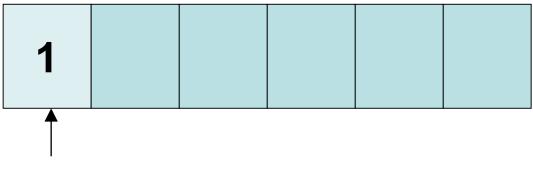


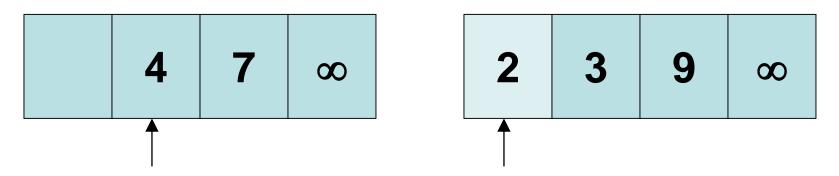
The two sublists are indexed from p to q (for the first sublist) and from q+1 to r for the second sublist.
 There are (r – p) + 1 items in the two sublists combined, so we will need an output array of that size.



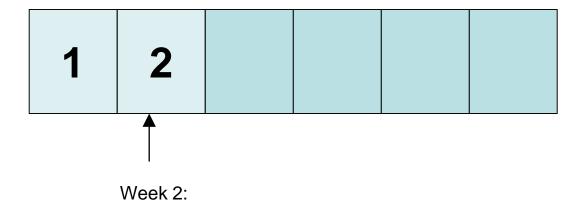


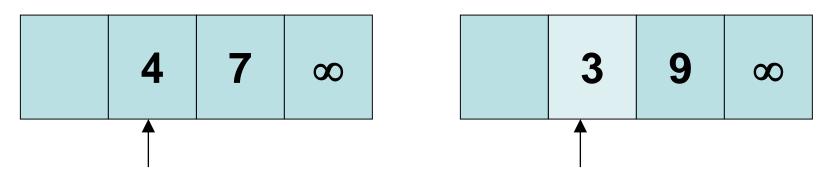
- Look at the first item in each subarray. Choose the smallest item.
- Move the chosen item to the output array.



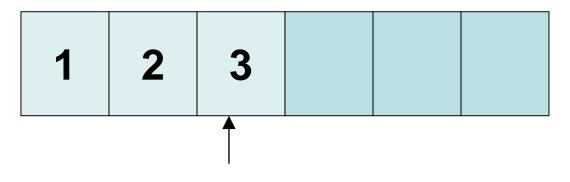


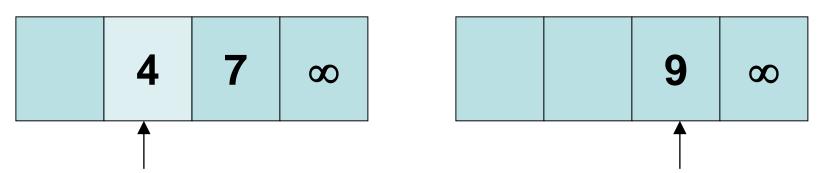
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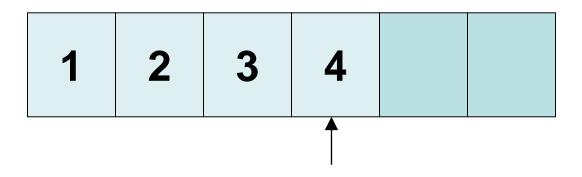


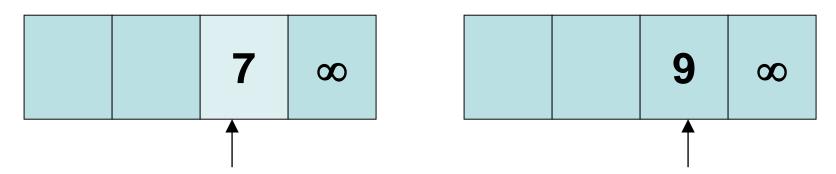
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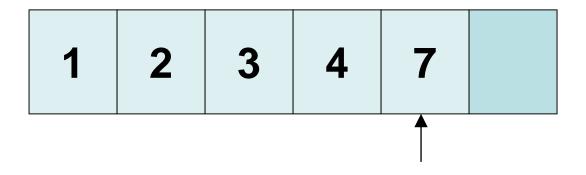


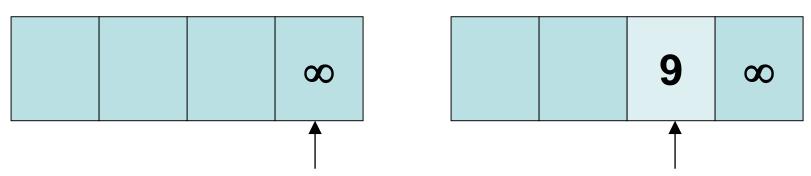
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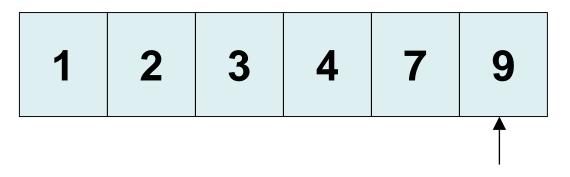


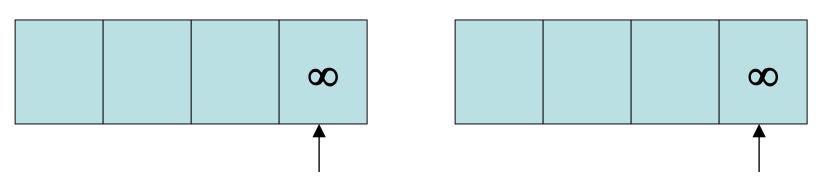
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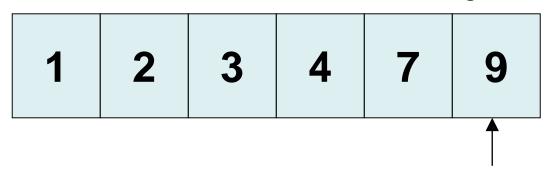


- Look at the first item in each subarray. Choose the smallest item.
- Move the chosen item to the output array.





- We know that we have only n = (r p) + 1 items. So, we will make only (r - p) + 1 moves.
- Here r = 1 and p = 6, and (6 1) + 1 = 6, so when we have made our 6^{th} move we are through.



- Assuming that the two sublists are in sorted order when they are passed to the Merge routine, is Merge guaranteed to output a sorted array?
- Yes. We can verify that each step of Merge preserves the sorted order that the two sublists already have.

Merge(A, p, q, r)

```
n_1 \leftarrow (q - p) + 1
1
2
     n_2 \leftarrow (r - q)
3
     create arrays L[1..n_1+1] and R[1..n_2+1]
4
     for i \leftarrow 1 to n_1 do
5
        L[i] \leftarrow A[(p+i)-1]
6
     for j \leftarrow 1 to n_2 do
     R[j] \leftarrow A[q + j]
     L[n_1 + 1] \leftarrow \infty
8
9
     R[n_2 + 1] \leftarrow \infty
10
    i \leftarrow 1
11
    j ← 1
12
    for k \leftarrow p to r do
13
        if L[i] <= R[j]
14
                then A[k] \leftarrow L[i]
15
                       i \leftarrow i + 1
16
                else A[k] \leftarrow R[j]
17
                       j \leftarrow j + 1
```

Analysis of Merge

- Line 1 computes the length n₁ of the subarray A[p..q].
- Line 2 computes the length n₂ of the subarray A[q+1..r].
- We create arrays L and R ("left" and "right"), of lengths n₁ + 1 and n₂ + 1, respectively, in line 3.
- The for loop of lines 4-5 copies the subarray A[p..q] into L[1..
 n₁], and the for loop of lines 6-7 copies the subarray A[q+1..r] into R[1..n2].
- Lines 8-9 put the sentinels at the ends of the arrays L and R.
- Lines 10-17, illustrated in Figure 2.3, perform the r p + 1 basic steps by maintaining the following loop invariant.

Analysis of Merge

- The loop in lines 12-17 of Merge is the heart of how Merge works. They maintain the loop invariant:
- At the start of each iteration of the for loop of lines 12-17, the subarray A[p..k-1] contains the k - p smallest elements of L[1..n₁+1] and R[1..n₂+1], in sorted order.
- Moreover, L[i] and R[j] are the smallest elements of their arrays that have not been copied back into A.

Analysis of Merge

- To prove that Merge is a correct algorithm, we must show that:
- Initialization: the loop invariant holds prior to the first iteration of the for loop in lines 12-17
- Maintenance: each iteration of the loop maintains the invariant
- Termination: the invariant provides a useful property to show correctness when the loop terminates

Initialization

- As we enter the for loop, k is set equal to p.
- This means that subarray A[p..k-1] is empty.
- Since k p = 0, the subarray is guaranteed to contain the k - p smallest elements of L and R.
- By lines 10 and 11, i = j = 1, so L[i] and R[j] are the smallest elements of their arrays that have not been copied into A.

Maintenance

- As we enter the loop, we know that A[p..k-1] contains the k p smallest elements of L and R.
- Assume L[i] <= R[j]. Then:
 - L[i] is the smallest element not copied into A.
 - Line 14 will copy L[i] into A[k].
 - At this point the subarray A[p..k] will contain the k p + 1 smallest elements.
 - Incrementing k (in line 12) and i (in line 15) reestablishes the loop invariant for the next iteration.
- Assume L[i] >= R[j]. Then:
 - Lines 16-17 maintain the loop invariant.

Termination

- The loop invariant states that subarray
 "A[p..k-1] contains the k p smallest elements
 of L[1..n₁+1] and R[1..n₂+1], in sorted order."
- When we drop out of the loop, k = r + 1.
- So r = k 1, and A[p..k-1] is actually A[p..r], which is the whole array.
- The arrays L and R together contain $n_1 + n_2 + 2$ elements. From lines 1 and 2 we know that $n_1 + n_2 = ((q p) + 1) + ((r q) = (r p) + 1$, and this is the number of all of the elements in the array. The extra 2 is the two sentinel elements.

Now let us look at Merge-Sort again:

 Line 1 is our base case; we drop out of the recursive sequence of calls when p >= r.

- Given our Merge routine, we can now see how Merge-Sort works.
 - Assume a list of length = 2^m
 - Take an unsorted list as input.
 - Split it in half. Now you have two sublists.
 - Split those in half, and so on, until you have lists of length 1.
 - Merge those into sublists of length 2, then merge those into sublists of length 4, etc. Keep going until you have just one list left.
 - That list is now sorted.

- Let us call Merge-Sort with an array of 4 elements: Merge-Sort(A, 1, 4), where p = 1 and r = 4.
- Line 1: p < r, so do the *then* part of the *if*
- Line 2: $q \leftarrow \lfloor (p+r)/2 \rfloor$, which is 2
- Line 3: we call Merge-Sort(A, 1, 2)
- WAIT HERE (let us call our place Z) until we return from this call

- Calling Merge-Sort(A, 1, 2)
- Line 1: p < r, so do the *then* part of the *if*
- Line 2: $q \leftarrow \lfloor (p+r)/2 \rfloor$, which is 1
- Line 3: we call Merge-Sort(A, 1, 1)
- WAIT HERE (let us call our place Y) until we return from this call

- Calling Merge-Sort(A, 1, 1)
- Line 1: p = r, so skip the *then* part of the *if*
- Return from this call to Y

- We called Merge-Sort(A, 1, 2)
- We have returned from our call in line 3
- Line 4: We call Merge-Sort(A, 2, 2)
- WAIT HERE (let us call our place X) until we return from this call

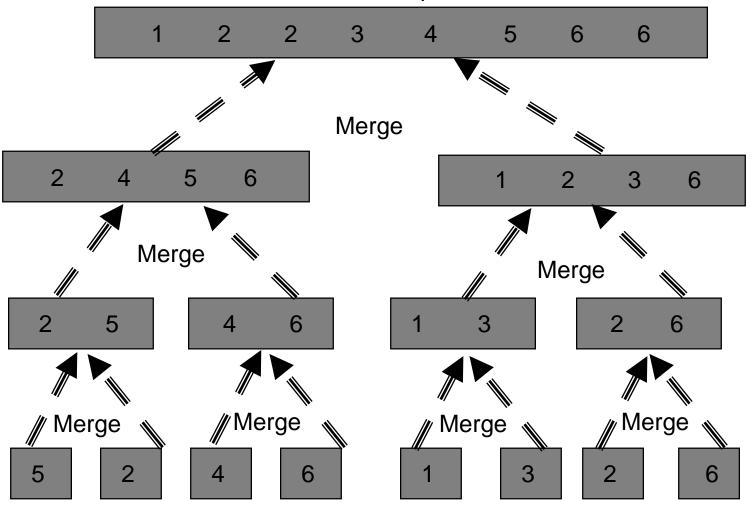
- Calling Merge-Sort(A, 2, 2)
- Line 1: p = r, so skip the *then* part of the *if*
- Return from this call to X

- We called Merge-Sort(A, 2, 2)
- We have returned from our call in line 4
- Line 5: We call Merge(A, 1, 2, 2)
- What does Merge do?

- Step 5: Merge(A, 1, 2, 2) :
- creates two temporary arrays of 1 element each
- copies A[1] and A[2] into these 2 arrays
- merges the elements in these two temporary arrays back into A[1..2] in sorted order
- returns from the call to Z

- Return from call to Merge-Sort(A, 1, 2) in Line 3. At this point half of our original array, A[1..2], is in sorted order.
- Next we call Merge-Sort(A, 3, 4). It will put A[3..4] into sorted order.
- Line 5 will merge A[1..2] and A[3..4] into A[1..4] in sorted order.

sorted sequence



initial sequence

Analysis of Divide-and-Conquer Algorithms

- The Merge-Sort algorithm contains a recursive call to itself. When an algorithm contains a recursive call to itself, its running time often can be described by a recurrence equation, or recurrence.
- The recurrence equation describes the running time on a problem of size n in terms of the running time on smaller inputs.
- We can use mathematical tools to solve the recurrence and provide bounds on the performance of the algorithm.

Analysis of Divide-and-Conquer Algorithms

- A recurrence of a divide-and-conquer algorithm is based on its 3 parts: divide, conquer, and combine.
- Let T(n) be the running time on a problem of size n.
- If the problem is small enough, say $n \le c$, we can solve it in a straightforward manner, which takes constant time, which we write as $\Theta(1)$.
- If the problem is bigger, we solve it by dividing the problem to get a subproblems, each of which is 1/b the size of the original. For Merge-Sort, both a and b are 2.

Analysis of Divide-and-Conquer Algorithms

- Assume it takes D(n) time to divide the problem into subproblems.
- Assume it takes C(n) time to combine the solutions to the subproblem into the solution for the original problem.
- We get the recurrence:

$$T(n) = \begin{cases} \Theta(1) &, \text{ if } n \le c \\ aT(n/b) + D(n) + C(n), \text{ otherwise} \end{cases}$$

- Base case: n = 1. Merge sort on an array of size 1 takes constant time, $\Theta(1)$.
- **Divide:** The Divide step of Merge-Sort just calculates the middle of the subarray. This takes constant time. So $D(n) = \Theta(1)$.
- Conquer: We make 2 calls to Merge-Sort. Each call handles ½ of the subarray that we pass as a parameter to the call. The total time required is 2T(n/2).
- Combine: Running Merge on an n-element subarray takes $\Theta(n)$, so $C(n) = \Theta(n)$.

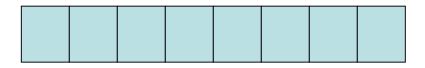
Here is what we get

$$T(n) = \begin{cases} \Theta(1) & , & \text{if } n = 1 \\ 2T(n/2) + \Theta(1) + \Theta(n), & \text{if } n > 1 \end{cases}$$

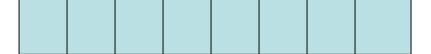
 By inspection, we can see that we can ignore the Θ(1) factor, as it is irrelevant compared to Θ(n). We can rewrite this recurrence as:

$$T(n) = \begin{cases} c & , & \text{if } n = 1 \\ 2T(n/2) + cn, & \text{if } n > 1 \end{cases}$$

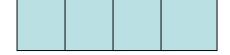
- How much time will it take for the Divide step?
- Let us assume that n is some power of 2.
- Then for an array of size n, it will take us log₂n steps to recursively subdivide the array into subarrays of size 1.
- Example: $8 = 2^3$

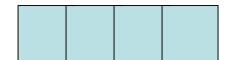


- Example: $8 = 2^3$
- Step 0:

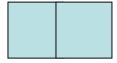


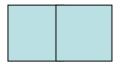
• Step 1:

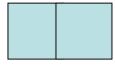


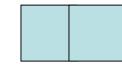


• Step 2:









• Step 3:

















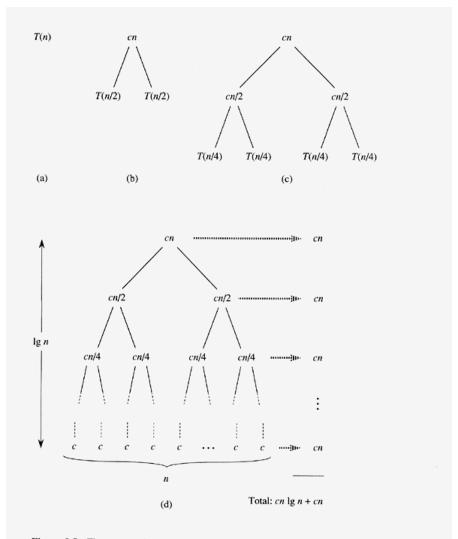


Figure 2.5 The construction of a recursion tree for the recurrence T(n) = 2T(n/2) + cn. Part (a) shows T(n), which is progressively expanded in (b)-(d) to form the recursion tree. The fully expanded tree in part (d) has $\lg n + 1$ levels (i.e., it has height $\lg n$, as indicated), and each level contributes a total cost of cn. The total cost, therefore, is $cn \lg n + cn$, which is $\Theta(n \lg n)$.

- So, it took us log₂n steps to divide the array all the way down into subarrays of size 1.
- As a result, we will have log₂n + 1 (sub)arrays to deal with. In our example, where n = 8 and log₂n = 3, we will have to deal with arrays of size 1, 2, 4, and 8.
- Every time we Merge the arrays, it takes us n steps, since we have to put each array item into its proper position within each array.

- Consequently, we will have log₂n + 1 recursive calls of the Merge-Sort function, and each time we call Merge-Sort the Merge function will cost us n steps, times a constant value.
- The total cost, then, can be expressed as:

$$cn(log_2n + 1)$$

Multiplying this out gives:

$$cn(log_2n) + cn$$

Ignoring the low-order term and the constant c gives:

$$\Theta(n \cdot \log_2 n)$$

Chapter 3: Growth of Functions

- Asymptotic notation
- Comparison of functions
- Standard notations and common functions

Asymptotic Notation

- What does asymptotic mean?
- Asymptotic describes behavior of function in the limit - for sufficiently large values of its parameter

Asymptotic Notation

- The order of growth of the running time of an algorithm is defined as the highest-order term (usually the leading term) of an expression that describes the running time of the algorithm
- We ignore the leading term's constant coefficient, as well as all of the lower order terms in the expression
- Example: The order of growth of an algorithm whose running time is described by the expression an²+ bn + c is simply n²

- Let us say that we have some function that represents the sum total of all the runningtime costs of an algorithm; call it f(n)
- For merge sort, the actual running time is:

$$f(n) = cn(log_2n) + cn$$

 We want to describe the running time of merge sort in terms of another function, g(n), so that we can say f(n) = O(g(n)), like this:

$$cn(log_2n) + cn = O(nlog_2n)$$

Big O: Definition

 For a given function g(n), O(g(n)) is the set of functions

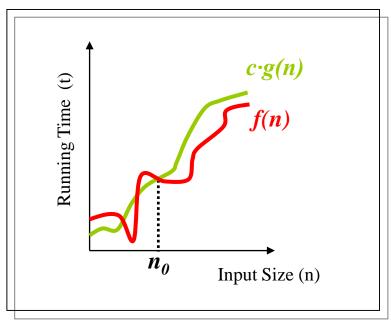
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O(g(n)) = \{ f(n): \text{ there exist positive } 

constants \ c \ and \ n_0 \ such that

0 \le f(n) \le c \cdot g(n) \text{ for all } n \ge n_0 \}
```

c is the multiplicative constant n_0 is the threshold

$$f(n) \in O(g(n))$$



- Big O is an <u>upper bound</u> on a function, to within a constant factor.
- O(g(n)) is a set of functions
- Commonly used notation

$$f(n) = O(g(n))$$

Correct notation

$$f(n) \in O(g(n))$$

Question:

How do you demonstrate that $f(n) \in O(g(n))$?

Answer:

Show that you can find values for c and n_0 such that $0 \le f(n) \le c g(n)$ for all $n \ge n_0$

Example: Show that 7n - 2 is O(n)

- •Find a real constant c > 0 and an integer constant $n_0 \ge 1$ such that $7n 2 \le cn$ for every integer $n \ge n_0$.
- •Choose c = 7 and $n_0 = 1$.
- •It is easy to see that $7n 2 \le 7n$ for every integer $n \ge 1$.
- •: 7n-2 is O(n)

Example: Show that $20n^3 + 10n \log n + 5$ is $O(n^3)$

- Find a real constant c > 0 and an integer constant $n_0 \ge 1$ such that $20n^3 + 10n \log n + 5 \le cn^3$ for every integer $n \ge n_0$.
- How do we find c and n₀?
- Note that $10n^3 > 10 \text{ n log n}$, and that $5n^3 > 5$.
- So, $15n^3 > 10n \log n + 5$
- And $20n^3 + 15n^3 > 20n^3 + 10n \log n + 5$
- Therefore, $35n^3 > 20n^3 + 10n \log n + 5$

- So we choose c = 35 and $n_0 = 1$
- An algorithm that takes $20n^3 + 10n \log n + 5$ steps to run cannot possibly take any more than $35n^3$ steps, for every integer $n \ge 1$
- Therefore $20n^3 + 10n \log n + 5$ is $O(n^3)$

Example: Show that $\frac{1}{2}n^2 - 3n$ is $O(n^2)$

- •Find a real constant c > 0 and an integer constant $n_0 \ge 1$ such that $\frac{1}{2}n^2 3n \le cn^2$ for every integer $n \ge n_0$
- •Choose $c = \frac{1}{2}$ and $n_0 = 1$
- •Now $\frac{1}{2}n^2 3n \le \frac{1}{2}n^2$ for every integer $n \ge 1$

Example: Show that $an(log_2n) + bn$ is $O(n \cdot log n)$

 Find a real constant c > 0 and an integer constant n₀ ≥ 1 such that

$$an(log_2n) + bn \leq cn \cdot log n$$

for every integer $n \ge n_0$.

- Choose c = a+b and $n_0 = 2$ (why 2?)
- Now $an(log_2n) + bn \le cn \cdot log n$ for every integer $n \ge 2$.

Example: Show that $an(log_2n) + bn$ is $O(n \cdot log n)$

 Find a real constant c > 0 and an integer constant n₀ ≥ 1 such that

 $an(log_2n) + bn \leq cn \cdot log n$

for every integer $n \ge n_0$.

- Choose c = a+b and $n_0 = 2$ (why 2?)
- $\log_2 1 = 0$, a •1•($\log_2 1$) + b•1 \leq c•1•log 1
- 0+b ≤ 0 => NOT TRUE!

Question:

Is
$$n = O(n^2)$$
?

Answer:

Yes. Remember that $f(n) \in O(g(n))$ if there exist positive constants c and n_0 such that

$$\{0 \le f(n) \le c \cdot g(n) \text{ for all } n \ge n_0\}$$

If we set c = 1 and $n_0 = 1$, then it is obvious that $c \cdot n \le n^2$ for all $n \ge n_0$.

- What does this mean about Big-O?
- When we write f(n) = O(g(n)) we mean that some constant times g(n) is an asymptotic upper bound on f(n); we are not claiming that this is a *tight* upper bound.

- Big-O notation describes an upper bound
- Assume we use Big-O notation to bound the worst case running time of an algorithm
- Now we have a bound on the running time of the algorithm on every input

- Is it correct to say "the running time of insertion sort is O(n²)"?
- Technically, the running time of insertion sort depends on the characteristics of its input.
 - If we have n items in our list, but they are already in sorted order, then the running time of insertion sort on this particular input is O(n).

- So what do we mean when we say that the running time of insertion sort is O(n²)?
- What we normally mean is:
 the worst case running time of insertion sort is O(n²)
- That is, if we say that "the running time of insertion sort is O(n²)", we guarantee that under no circumstances will insertion sort perform worse than O(n²).

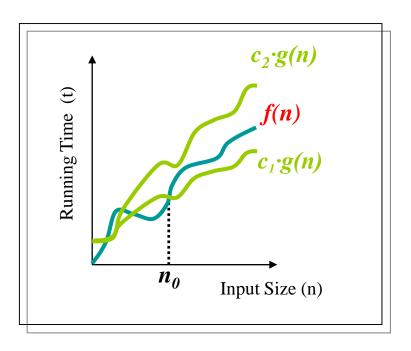
Big Theta: Definition

 For a given function g(n), Θ(g(n)) is the set of functions:

```
\Theta(g(n)) = \{f(n): \text{ there exist positive} \\ \text{constants } c_1, c_2, \text{ and } n_0 \\ \text{such that} \\ 0 \le c_1 g(n) \le f(n) \le c_2 g(n) \\ \text{for all } n \ge n_0 \}
```

- What does this mean?
- When we use Big-Theta notation, we are saying that function f(n) can be "sandwiched" between some *small* constant times g(n) and some *larger* constant times g(n).
- In other words, f(n) is <u>equal</u> to g(n) to within a constant factor.

 $f(n) \in \Theta(g(n))$



- If $f(n) = \Theta(g(n))$, we can say that g(n) is an asymptotically tight bound for f(n).
- Basically, we are guaranteeing that f(n) never performs any better than c₁ g(n), but also never performs any worse than c₂ g(n).
- We can see this visually by noting that, after n₀, the curve for f(n) never goes below c₁ g(n) and never goes above c₂ g(n).

- Let us look at the performance of the merge sort.
- We said that the performance of merge sort was cn(log₂n) + cn
- Does this depend upon the characteristics of the input for merge sort? That is, does it make a difference if the list is already sorted, or reverse sorted, or in random order?
- No. Unlike insertion sort, merge sort behaves exactly the same way for any type of input.

The running time of merge sort is:

```
cn(log_2n) + cn
```

 So, using asymptotic notation, we can discard the "+ cn" part of this equation, giving:

```
cn(log<sub>2</sub>n)
```

 And we can disregard the constant multiplier, c, which gives us the running time of merge sort:

 $\Theta(n(\log_2 n))$

- Why would we prefer to express the running time of merge sort as Θ(n(log₂n)) instead of O(n(log₂n))?
- Because Big-Theta more precise than Big-O
- If we say that the running time of merge sort is O(n(log₂n)), we are merely making a claim about merge sort's asymptotic upper bound, whereas if we say that the running time of merge sort is Θ(n(log₂n)), we are making a claim about merge sort's asymptotic upper and lower bounds

Big Theta

- Would it be incorrect to say that the running time of merge sort is O(n(log₂n))?
- No, not at all.
- It is just that we are not giving all of the information that we have about the running time of merge sort.
- But sometimes all we need to know is the worst-case behavior of an algorithm. If that is so, then Big-O notation is fine.

Big Theta

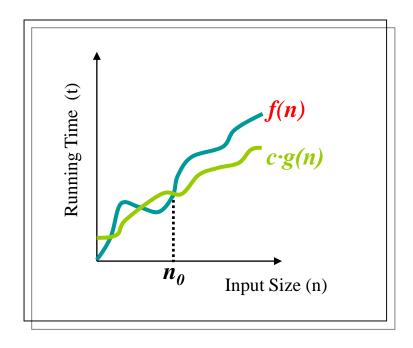
- One final note: the definition of $\Theta(g(n))$ technically requires that every member $f(n) \in \Theta(g(n))$ be asymptotically nonnegative that is, f(n) must be nonnegative whenever n is sufficiently large.
- We assume that every function used within Θ notation (and the other notations used in your textbook's Chapter 3) is asymptotically nonnegative

Big Omega: Definition

• For a given function g(n), $\Omega(g(n))$ is the set of functions:

```
\Omega(g(n)) = \{ f(n): \text{ there exist positive } constants \ c \text{ and } n_0 \text{ such that } 0 \le c \ g(n) \le f(n)  for all n \ge n_0 \}
```

 $f(n) \in \Omega(g(n))$



- We know that Big-O notation provides an asymptotic upper bound on a function.
- Big-Omega notation provides an asymptotic lower bound on a function.
- Basically, if we say that $f(n) = \Omega(g(n))$ then we are guaranteeing that, beyond n_0 , f(n) never performs any better than c g(n).

- We usually use Big-Omega when we are talking about the best case performance of an algorithm.
- For example, the best case running time of insertion sort (on an already sorted list) is Ω(n).
- But this also means that insertion sort never performs any better than $\Omega(n)$ on any type of input.
- So the running time of insertion sort is $\Omega(n)$.

- Could we say that the running time of insertion sort is $\Omega(n^2)$?
- No. We know that if its input is already sorted, the curve for merge sort will dip below n² and approach the curve for n.
- Could we say that the worst case running time of insertion sort is $\Omega(n^2)$?
- Yes.

• It is interesting to note that, for any two functions f(n) and g(n), $f(n) = \Theta(g(n))$ if and only if f(n) = O(g(n)) and $f(n) = \Omega(g(n))$.

Little o: Definition

 For a given function g(n), o(g(n)) is the set of functions:

```
o(g(n))= {f(n): for any positive constant c,
there exists a constant n_0
such that 0 \le f(n) < c g(n)
for all n \ge n_0}
```

Little o

 Note the < instead of ≤ in the definition of Little-o:

$$0 \le f(n) < c g(n)$$
 for all $n \ge n_0$

Contrast this to the definition used for Big-O:

$$0 \le f(n) \le c g(n)$$
 for all $n \ge n_0$

- Little-o notation denotes an upper bound that is not asymptotically tight. We might call this a loose upper bound.
- Examples: 2n ∈ o(n²) but 2n² ∉ o(n²)

Little o: Definition

- Given that f(n) = o(g(n)), we know that g grows strictly faster than f. This means that you can multiply g by a positive constant c and beyond n_0 , g will always exceed f.
- No graph to demonstrate little-o, but here is an example:

$$n^2 = o(n^3)$$
 but $n^2 \neq o(n^2)$.

Why? Because if c = 1, then f(n) = c g(n), and the definition insists that f(n) be less than c g(n).

Little omega: Definition

 For a given function g(n), ω(g(n)) is the set of functions:

```
\omega(g(n)) = \{f(n): \text{ for any positive constant } c, \text{ there exists a constant } n_0 \text{ such that } 0 \le c g(n) < f(n) \text{ for all } n \ge n_0 \}
```

Little omega: Definition

Note the < instead of ≤ in the definition:

$$0 \le c g(n) < f(n)$$

• Contrast this to the definition used for Big- Ω :

$$0 \le c g(n) \le f(n)$$

- Little-omega notation denotes a lower bound that is not asymptotically tight. We might call this a loose lower bound.
- Examples:

$$n \notin \omega(n^2)$$
 $n \in \omega(\sqrt{n})$ $n \in \omega(\lg n)$

Little omega

 No graph to demonstrate little-omega, but here is an example:

```
n^3 is \omega(n^2) but n^3 \neq \omega(n^3).
```

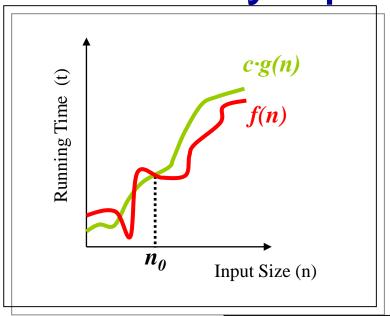
Why? Because if c = 1, then f(n) = c g(n), and the definition insists that c g(n) be strictly <u>less</u> than f(n).

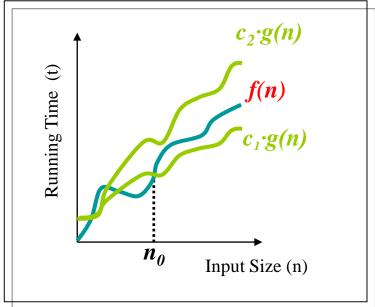
Comparison of Notations

$$f(n) = o(g(n)) \approx a < b$$

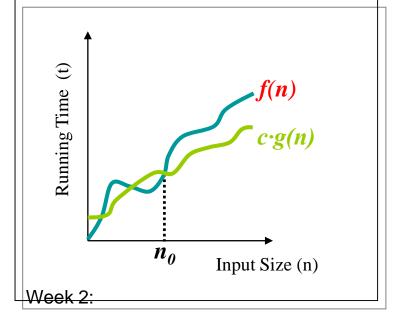
 $f(n) = O(g(n)) \approx a \le b$
 $f(n) = O(g(n)) \approx a = b$
 $f(n) = O(g(n)) \approx a \ge b$
 $f(n) = \omega(g(n)) \approx a > b$

Asymptotic Notation





Big O



Big Theta

Big Omega

Asymptotic Notation in Equations and Inequalities

- When asymptotic notation stands alone on right-hand side of equation, '=' is used to mean '∈'.
- In general, we interpret asymptotic notation as standing for some anonymous function we do not care to name.
- Example: $2n^2 + 3n + 1 = 2n^2 + \Theta(n)$ means that $2n^2 + 3n + 1 = 2n^2 + f(n)$ for some $f(n) \in \Theta(n)$. (In this case, f(n) = 3n + 1, which is in $\Theta(n)$.)

Asymptotic Notation in Equations and Inequalities

- This use of asymptotic notation eliminates inessential detail in an equation (e.g., we do not have to specify lower-order terms; they are understood to be included in anonymous function).
- The number of anonymous functions in an expression is the number of times asymptotic notation appears
 - Example: $\sum O(i)$ is one anonymous function
 - not the same as O(1)+O(2)+...+O(n), which has n hidden constants

Asymptotic Notation in Equations and Inequalities

- Appearance of asymptotic notation on lefthand side of equation means, no matter how the anonymous functions are chosen on the left-hand side, there is a way to choose the anonymous functions on the right-hand side to make the equation valid.
- Example: $2n^2 + \Theta(n) = \Theta(n^2)$ means that for any function $f(n) \in \Theta(n)$ there is some function $g(n) \in \Theta(n^2)$ such that $2n^2 + f(n) = g(n)$ for all n.

Transitivity:

```
f(n) = \Theta(g(n)) and g(n) = \Theta(h(n)) imply f(n) = \Theta(h(n))

f(n) = O(g(n)) and g(n) = O(h(n)) imply f(n) = O(h(n))

f(n) = \Omega(g(n)) and g(n) = \Omega(h(n)) imply f(n) = \Omega(h(n))

f(n) = o(g(n)) and g(n) = o(h(n)) imply f(n) = o(h(n))

f(n) = \omega(g(n)) and g(n) = \omega(h(n)) imply f(n) = \omega(h(n))
```

Reflexivity:

$$f(n) = \Theta(f(n))$$

$$f(n) = O(f(n))$$

$$f(n) = \Omega(f(n))$$

Symmetry:

$$f(n) = \Theta(g(n))$$
 iff $g(n) = \Theta(f(n))$

Transpose symmetry:

$$f(n) = O(g(n))$$
 iff $g(n) = \Omega(f(n))$
 $f(n) = o(g(n))$ iff $g(n) = \omega(f(n))$

Analogies:

$$f(n) = o(g(n)) \approx a < b$$

 $f(n) = O(g(n)) \approx a \le b$
 $f(n) = O(g(n)) \approx a = b$
 $f(n) = O(g(n)) \approx a \ge b$
 $f(n) = O(g(n)) \approx a \ge b$

- Asymptotic relationships:
- f(n) is asymptotically smaller than g(n) if
 f(n) = o(g(n))
- f(n) is asymptotically larger than g(n) if
 f(n) = ω(g(n))

- Asymptotic relationships:
- Not all functions are asymptotically comparable.
- That is, it may be the case that neither f(n) = o(g(n)) nor $f(n) = \omega(g(n))$ is true.

Using limit of ratio to show order of growth of a function

$$\lim_{n \to \infty} \frac{f(n)}{g(n)} = 0 \Rightarrow f(n) = o(g(n)) \Rightarrow f(n) = O(g(n))$$

$$\lim_{n \to \infty} \frac{f(n)}{g(n)} = c, c > 0, c < \infty \Rightarrow f(n) = \Theta(g(n)) \Leftrightarrow$$

$$f(n) = O(g(n)) \text{ and } f(n) = \Omega(g(n))$$

$$\lim_{n\to\infty} \frac{f(n)}{g(n)} = \infty \Rightarrow f(n) = \omega(g(n)) \Rightarrow f(n) = \Omega(g(n))$$

Standard Notation

- Pages 51 56 contain review material from your previous math courses
- Please read this section of your textbook and refresh your memory of these mathematical concepts
- The remaining slides in this section are for your aid in reviewing the material

Monotonicity

- A function f(n) is monotonically increasing if m ≤ n implies f(m) ≤ f(n).
- A function f(n) is monotonically decreasing if m ≤ n implies f(m) ≥ f(n).
- A function f(n) is strictly increasing if m < n implies f(m) < f(n).
- A function f(n) is strictly decreasing if m
 n implies f(m) > f(n).

Floor and Ceiling

- For any real number x, the floor of x is the greatest integer less than or equal to x.
- The floor function $f(x) = \lfloor x \rfloor$ is monotonically increasing.
- For any real number x, the ceiling of x is the least integer greater than or equal to x.
- The ceiling function $f(x) = \lceil x \rceil$ is monotonically increasing.

Modulo Arithmetic

- For any integer a and any positive integer n, the value of a modulo n (or a mod n) is the remainder we have after dividing a by n.
- a mod $n = a \lfloor a/n \rfloor n$
- if (a mod n) = (b mod n), then a ≡ b mod n (read as "a is equivalent to b mod n")

Polynomials

 Given a nonnegative integer d, a polynomial in n of degree d is a function p(n) of the form

$$p(n) = \sum_{i=0}^{d} a_i n^i$$

where the constants a_0 , a_1 , ..., a_d are the coefficients of the polynomial and $a_d \neq 0$.

Polynomials

- A polynomial is asymptotically positive if and only if a_d > 0.
- If a polynomial p(n) of degree d is asymptotically positive, then p(n) = Θ(n^d).
- For any real constant a ≥ 0, n^a is monotonically increasing.
- For any real constant a ≤ 0, n^a is monotonically decreasing.
- A function is polynomially bounded if f(n) = O(n^k) for some constant k.

Exponentials

- For all n and a ≥ 1, the function aⁿ is monotonically increasing in n.
- For all real constants a and b such that a > 1,

$$\lim_{n\to\infty}\frac{n^b}{a^n}=0$$

This means that $n^b = o(a^n)$, which means that any *exponential* function with a base strictly greater than 1 grows *faster* than any *polynomial* function.

Logarithms

- $lg n = log_2 n$ (binary logarithm)
- $ln n = log_e n$ (natural logarithm)
- $\lg^k n = (\lg n)^k$ (exponentiation)
- Ig Ig n = Ig (Ig n) (composition)
- Ig n + k means (Ig n) + k, not log (n + k)
- If b > 1 and we hold b constant, then, for n > 0, the function log_bn is strictly increasing.
- Changing the base of a logarithm from one constant to another only changes the value of the logarithm by a constant factor.

Logarithms

- A function is polylogarithmically bounded if f(n)
 = O(lg^k n) for some constant k.
- Igb n = o(na) for any constant a > 0
- This means that any positive polynomial function grows faster than any polylogarithmic function.

Factorials

N factorial is defined for integers ≥ 0 as:

$$n! = \begin{cases} 1 & \text{if } n = 0 \\ n \cdot (n-1)! & \text{if } n > 0 \end{cases}$$

A weak upper bound on n! is n! ≤ nⁿ

$$- n! = o(n^n)$$

$$- n! = \omega(2^n)$$

$$- \lg(n!) = \Theta(n \lg n)$$

Fibonacci Numbers

The Fibonacci numbers are defined by the recurrence:

$$F_0 = 0$$

 $F_1 = 1$
 $F_i = F_{i-1} + F_{i-2} \ge 2$

Fibonacci numbers grow exponentially