

Q1)a)

	Regular Prices			Crash Prices		
Day	0	7	14	21	28	35
Stock Price	100	98	101	50	51	50

$$p(x) = a_1 + a_2x$$

$$p(7) = a_1 + a_27, p(14) = a_1 + a_214$$

$$\begin{bmatrix} 1 & 7 \\ 1 & 14 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} 98 \\ 101 \end{bmatrix}$$

$$\begin{bmatrix} a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} 95 \\ 0.428571428571429 \end{bmatrix}$$

$$p(x) = 95 + 0.428571428571429x$$

$$p(12) = 100.14285714285714285714285714286$$

Adding (0,100) data point:

$$p_2(x) = a_1 + a_2x + a_3x^2$$

$$p(7) = a_1 + a_27 + a_349, p(14) = a_1 + a_214 + a_3196, p(0) = a_1$$

$$\begin{bmatrix} 1 & 7 & 49 \\ 1 & 14 & 196 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} = \begin{bmatrix} 98 \\ 101 \\ 100 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 7 & 49 & 98 \\ 1 & 14 & 196 & 101 \\ 1 & 0 & 0 & 100 \end{bmatrix} \xrightarrow{-4R_1+R_2 \rightarrow R_2} \begin{bmatrix} 1 & 7 & 49 & 98 \\ -3 & -14 & 0 & -291 \\ 1 & 0 & 0 & 100 \end{bmatrix}$$

By using backward substitution:

$$\begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} = \begin{bmatrix} 100 \\ -0.642857142857143 \\ 0.0510204081632653 \end{bmatrix}$$

$$p_2(x) = 100 - 0.642857142857143x + 0.0510204081632653x^2$$

$$p_2(12) = 99.632653061224489795918367346939$$

Adding (21,50) data point:

$$p_3(x) = a_1 + a_2x + a_3x^2$$

$$p(7) = a_1 + a_27 + a_349, p(14) = a_1 + a_214 + a_3196, p(21) = a_1 + a_221 + a_3441$$

$$\begin{bmatrix} 1 & 7 & 49 \\ 1 & 14 & 196 \\ 1 & 21 & 441 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} = \begin{bmatrix} 98 \\ 101 \\ 50 \end{bmatrix}$$

$$\begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} = \begin{bmatrix} 41 \\ 12 \\ -0.5510 \end{bmatrix}$$

$$p_3(x) = 41 + 12x - 0.5510x^2$$

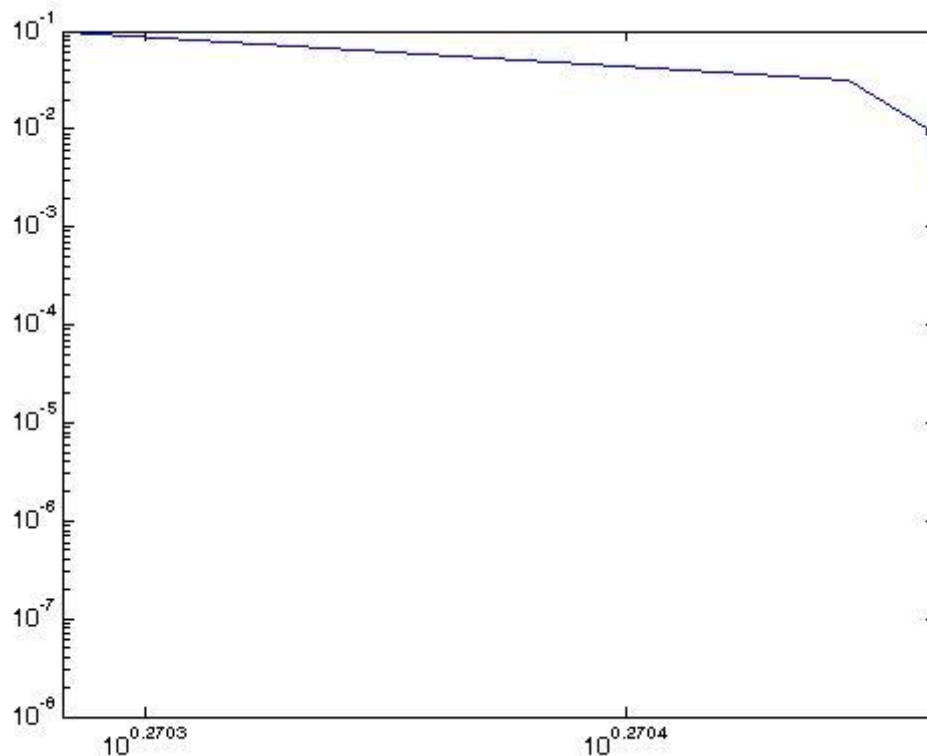
$$p_3(12) = 105.656$$

The most accurate interpolation is  $p_2(12) = 99.632653061224489795918367346939$  because it does not involve extreme data points (stock prices after crash) and it includes all the other data points.

b)

Matlab Code:

```
>> w=[0 7 14 21 28 35];
>> p=[100 98 101 50 51 50];
>> p2=100-0.642857142857143*w+0.0510204081632653*power(w,2);
>> p3=41+12*w-0.5510*power(w,2);
>> figure
>> plot(p,w,p1,w,p2,w)
```



$p_2(x)$  and  $p_3(x)$  is giving the right values before and after crash, in that order. But there is no function we can use for all data.

Q2)

a)

$$x_0 = 0, x_1 = 0.5, x_2 = 1$$

Using polynomial interpolation:

$$p_2(x) = a_1 + a_2x + a_3x^2$$

$$p_2(0) = a_1, p_2(0.5) = a_1 + a_2(0.5) + a_3(0.25), p_2(1) = a_1 + a_2 + a_3$$

$$p_2(0) = 1, p_2(0.5) = 1.64872127070013, p_2(1) = 2.71828182845905$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & 0.5 & 0.25 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 1.64872127070013 \\ 2.71828182845905 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & 1 \\ 1 & 0.5 & 0.25 & 1.64872127070013 \\ 1 & 1 & 1 & 2.71828182845905 \end{bmatrix} \xrightarrow{-0.25R_3 + R_2 \rightarrow R_2} \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0.75 & 0.25 & 0 & 0.969150813585367 \\ 1 & 1 & 1 & 2.71828182845905 \end{bmatrix}$$

By using backward substitution:

$$\begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} = \begin{bmatrix} 1 \\ -0.12339674565853 \\ 1.84167857411758 \end{bmatrix}$$

$$p_2(x) = 1 - 0.12339674565853x + 1.84167857411758x^2$$

We need to find the maximum point of  $|e^x - p_2(x)|$ , by using derivation the maximum point is:

$$\frac{d}{dx} e^x - p_2(x) = 0$$

$$e^x + 0.12339674565853 - 3.68335714823516x = 0$$

$$e^x = 3.68335714823516x - 0.12339674565853$$

$$x = \ln(3.68335714823516x - 0.12339674565853)$$

$$x = 0.46626767363798821250847017753463$$

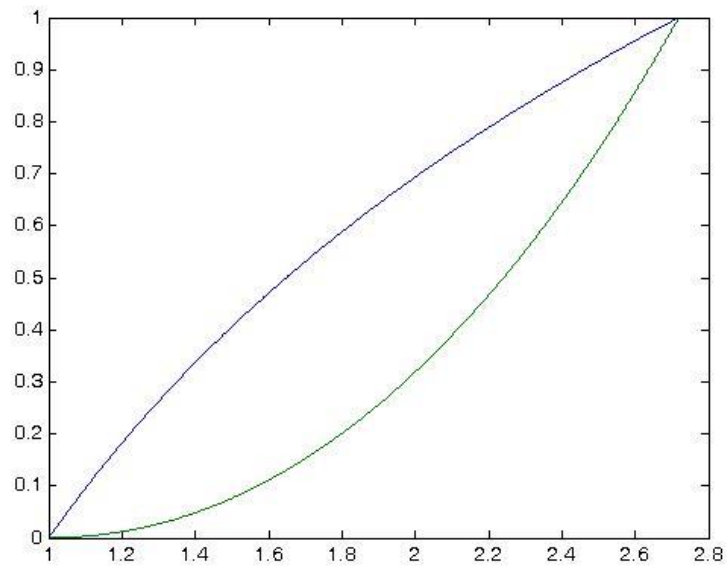
b)

$$p_2(x) = 1 - 0.12339674565853x + 1.84167857411758x^2$$

c)

Matlab code:

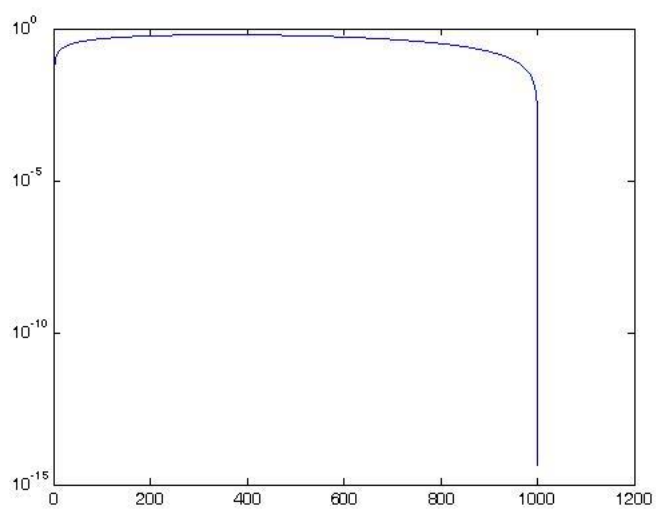
```
>> syms x;  
>> p(x)=1-0.12339674565853*x+1.84167857411758*x^2;  
>> x=0:0.001:1;  
>> p=1-0.12339674565853*x+1.84167857411758*sqrt(x);  
>> g=exp(x);  
>> plot(g,x,p,x)
```



d)

Matlab code:

```
>> syms x;
>> p(x)=1-0.12339674565853*x+1.84167857411758*x^2;
>> x=0:0.001:1;
>> p=1-0.12339674565853*x+1.84167857411758*sqrt(x);
>> g=exp(x);
>> d=abs(g-p);
>> semilogy(d)
```



Q3)a)

By using Taylor series:

$$f(x+h) = f(x) + f'(x)h + \frac{f''(x)}{2}h^2 + \frac{f'''(x)}{6}h^3 + \frac{f^{(4)}(x)}{24}h^4 + \frac{f^{(5)}(x)}{120}h^5 + \dots$$

$$f(x-h) = f(x) - f'(x)h + \frac{f''(x)}{2}h^2 - \frac{f'''(x)}{6}h^3 + \frac{f^{(4)}(x)}{24}h^4 - \frac{f^{(5)}(x)}{120}h^5 + \dots$$

$$f(x+h) - f(x-h) = 2f'(x)h + \frac{f'''(x)}{3}h^3 + \frac{f^{(5)}(x)}{60}h^5 + \dots$$

$$f(x+h) - f(x-h) - 2f'(x)h - \frac{f^{(5)}(x)}{60}h^5 - \dots = \frac{f'''(x)}{3}h^3$$

$$\frac{f(x+h) - f(x-h) - 2f'(x)h}{h^3} - \frac{f^{(5)}(x)}{60}h^2 - \dots = \frac{f'''(x)}{3}$$

$$f'''(x) \cong 3\left(\frac{f(x+h) - f(x-h)}{h^3} - \frac{2f'(x)}{h^2}\right)$$

Transaction error:  $\frac{f^{(5)}(x)}{60}h^2$  and error's order:  $O(h^2)$

b)

Matlab Code:

```
>> syms x;
>> f(x)=exp(x);
>> syms h;
>> d(x,h)=3*((f(x+h)-f(x-h))/h^3)-(2*f(x)/h^2));% f'(x)=f(x) for f(x)=e^x
>> for k=1:9
l=10^-k;
vpa(d(0,l))
l
end
ans =
1.0005001190641549423763011314301
l =
0.1
ans =
1.0000050000119047784391684704281
l =
0.01
```

ans =

1.0000000500000011904762070105818

l =

0.001

ans =

1.00000000500000001190476193302

l =

0.0001

ans =

1.00000000005000000000122870454

l =

1e-05

ans =

1.00000000000000499999999696164495

l =

1e-06

ans =

1.000000000000000498732999343332

l =

1e-07

ans =

1.0

l =

1e-08

ans =

1.0

l =

1e-09

For  $h = 0.1, x = 0,$

$$(e^x)''' - f'''(x) = 1 - 1.0005001190641549423763011314301 \\ = 0.0005001190641549423763011314301$$

Which is smaller than  $h^2 = 10^{-2}$ , this means that created formula is indeed second order accurate.  
For  $h = 10^{-8}$  and  $h = 10^{-9}$  formula gives the most accurate result, which is 1.

c) For very small  $h$  round-off error eliminates truncation error. Truncation error becomes so small and gets ignored because of the round-off error.

d) To get a fourth order formula for  $f'''(x)$ ,  $f(x+h) - f(x-h)$  can be used with Taylor series.

$$f(x+h) - f(x-h) = 2f'(x)h + \frac{f'''(x)}{3}h^3 + \frac{f^{(5)}(x)}{60}h^5 + \frac{f^{(7)}(x)}{2520}h^7 + \dots$$

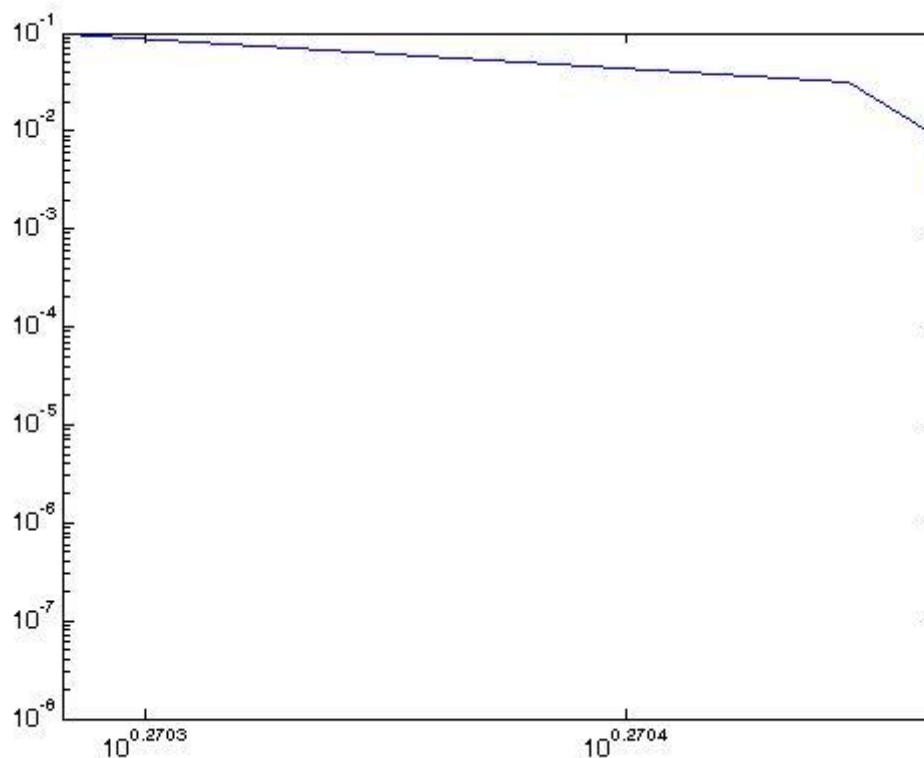
This method will require  $(x+h)$ ,  $f(x-h)$ ,  $f'(x)$  and  $f^{(5)}(x)$ , which means 4 points required.

Q4)

$$f''(x) = \frac{f(x_0+h) - 2f(x_0) + f(x_0-h)}{h^2}$$

Matlab code:

```
>> syms x;
>> syms h;
>> d(x,h)=(sin(x+h)-2*sin(x)+sin(x-h))/h^2;
>> k=[1:0.5:8];
>> figure
>> h=power(10,-k);
>> g=sin(1.2)-d(1.2,h);
>> loglog(g,h)Th
```



Sudden change in the plot caused by round-off error. The most optimal  $h$  is  $10^{-1.5}$ .