

# EXAMPLES OF NUMERICAL ANALYSIS

1. Taylor Series
2. Square Root
3. Integration
4. Root Finding
5. Line Fitting

# Example 1: Taylor Series

## Example 1: Taylor Series

- Consider the Taylor series for computing  $\sin(x)$

$$\sin(x) = \frac{x^1}{1!} - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \frac{x^9}{9!} - \dots = \sum_{k=0}^{\infty} \frac{(-1)^k x^{2k+1}}{(2k+1)!}$$

- For a small  $x$  value, only a few terms are needed to get a good approximation result of  $\sin(x)$ .
- The rest of the terms ( ... ) are truncated.

$$\text{Truncation error} = f_{\text{actual}} - f_{\text{sum}}$$

- The size of the truncation error depends on  $x$  and the number of terms included in  $f_{\text{sum}}$ .

- Write a C program to read  $X$  and  $N$  from user, then calculate the  $\sin(X)$ .
- Test your program for  $X=150$  degree and following  $N$  values.
  - First run:  $N = 3$
  - Second run:  $N = 7$
  - Third run:  $N = 50$
- Also using the built-in  $\sin(x)$  function, calculate the  $f_{\text{actual}}$ , then compare with your results on right side.
- Which  $N$  value gives the most correct result?

# Program

```
#include <stdio.h>
#include <math.h>
#define PI 3.14

float factorial(int M)
{
    float result=1;
    int i;

    for (i=1; i<=M; i++)
        result *= i;
    return result;
}
```

```
int main()
{
    int N;           // Number of terms
    int i;           // Loop counter
    int x = 150;     // Angle in degrees
    float toplam = 0; // Sum of Taylor series
    float actual;    // Actual sinus
    int t;           // Term

    printf("Terim sayisini (N) veriniz :");
    scanf("%d", &N);

    for (i=0; i<= N-1; i++) {
        t = 2*i+1;
        toplam = toplam +
            ( pow(-1, i) * pow(x*PI/180 ,t) )
            / factorial(t);
    }

    printf("Calculated sum = %f\n", toplam);
    actual = sin(x*PI/180);
    // Angle is converted to radian

    printf("Actual sinus = %f\n", actual);
    printf("Truncation error = %f\n", toplam- actual);

} // end main
```

## Screen outputs of test cases

- The result will be more accurate for bigger N values.

Program Output 1

```
Terim sayisini (N) veriniz :3  
Calculated sum = 0.652897  
Actual sinus = 0.501149  
Truncation error = 0.151748
```

Program Output 2

```
Terim sayisini (N) veriniz :7  
Calculated sum = 0.501150  
Actual sinus = 0.501149  
Truncation error = 0.000001
```

Program Output 3

```
Terim sayisini (N) veriniz :20  
Calculated sum = 0.501149  
Actual sinus = 0.501149  
Truncation error = -0.000000
```

## Example 2: Square Root

## Example 2: Square Root Computing with Newton Method

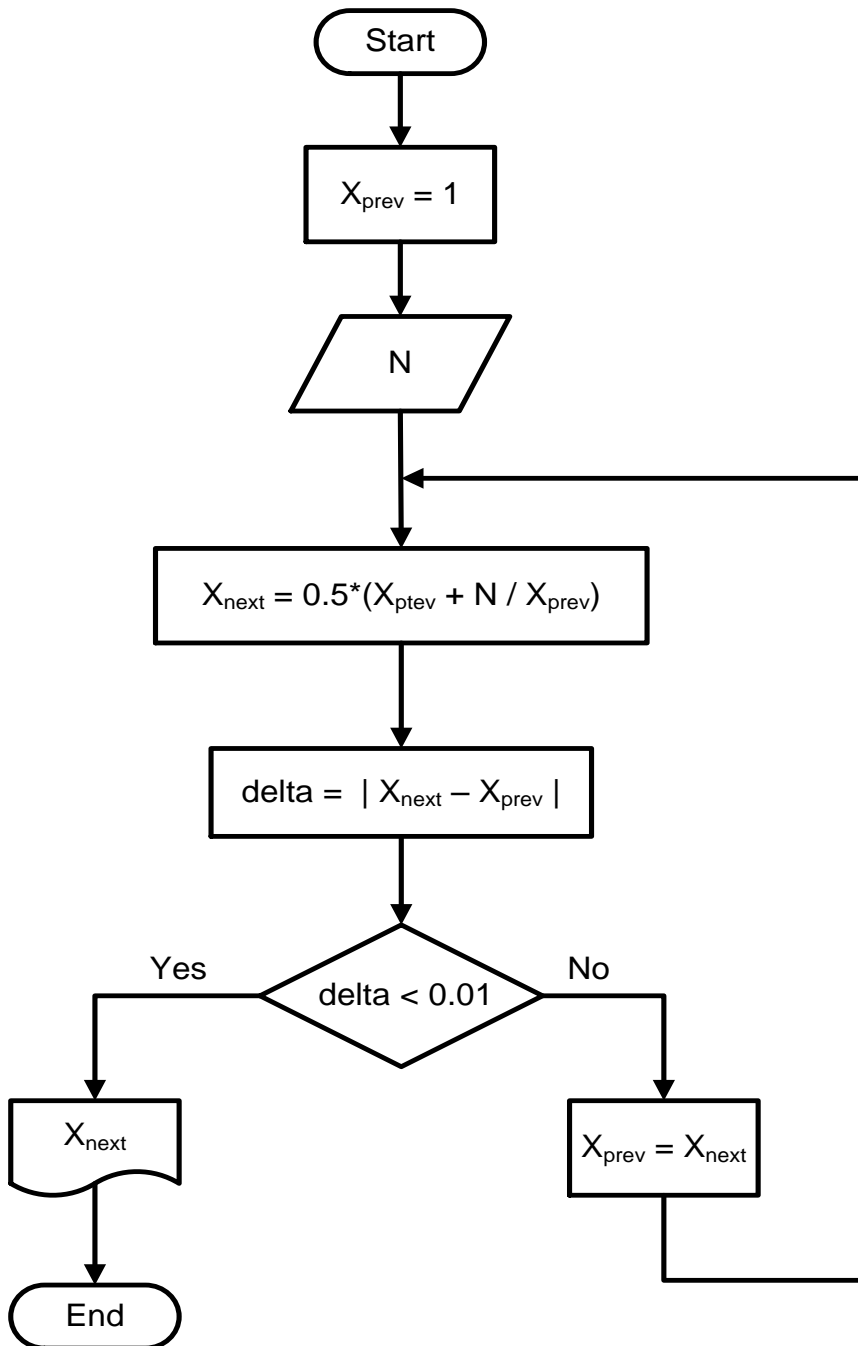
- Write a C program to compute the square root of N entered by user.
- The square root  $\sqrt{N}$  of a positive integer number N can be calculated by the following Newton iterative equation, where  $X_0 = 1$ .

$$X_{k+1} = \frac{1}{2} \left( X_k + \frac{N}{X_k} \right) \qquad \Delta = |X_{k+1} - X_k|$$

- When delta (i.e. tolerance)  $< 0.01$  , then the iterations (i.e. repetitions) must stop.
- The final value of  $X_{k+1}$  will be the answer.
- You should not use the built-in **sqrt()** function, but you can use the **fabs()** function.



# Program



```

#include <stdio.h>
#include <math.h>

int main()
{
    int N;
    float XPrev, XNext, delta;
    printf("Enter N :");
    scanf("%d", &N);

    XPrev = 1;
    while (1)
    {
        XNext = 0.5*(XPrev + N / XPrev);
        delta = fabs(XNext - XPrev);
        if (delta < 0.01) break;
        XPrev = XNext;
    } // end while

    printf("Square Root = %f \n", XNext);

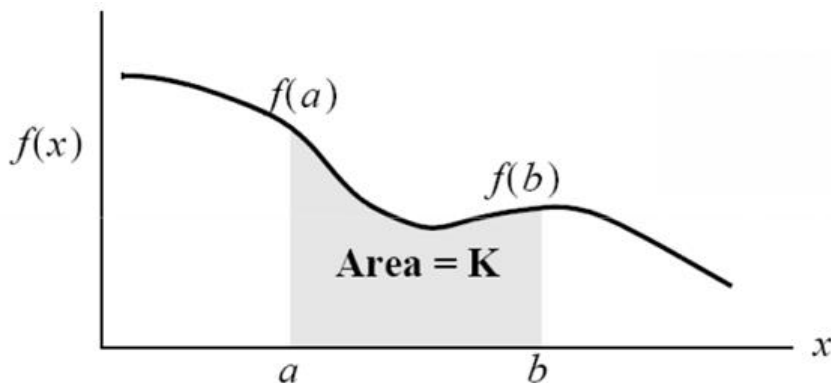
} // end main
  
```

Enter N :2  
Square Root = 1.414216

# Example 3: Integration

## Example 3: Integration Computing

- **Integration** : Common mathematical operation in science and engineering.
- Calculating area, volume, velocity from acceleration, work from force and displacement are just few examples where integration is used.
- Integration of simple functions can be done analytically.
- Consider an arbitrary mathematical function  $f(x)$  in the interval  $a \leq x \leq b$ .
- The definite integral of this function is equal to the area under the curve.
- For a simple function, we evaluate the integral in closed form.
- If the integral exists in closed form, the solution will be of the form  $K = F(b) - F(a)$  where  $F'(x) = f(x)$



$$K = \int_a^b f(x) dx$$

$$K = F(x) \Big|_a^b = F(b) - F(a)$$

# Analytical Integration Example

- Let's compute the following definite integral.

$$K = \int_0^2 x^2 dx = ?$$

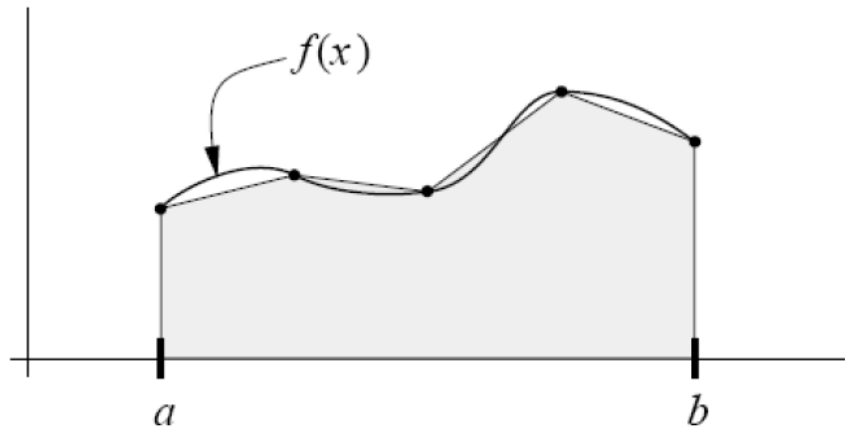
- Analytical Solution:

$$f(x) = x^2 \quad \Rightarrow \quad F(x) = \frac{1}{3}x^3$$

$$K = \int_0^2 x^2 dx = \left. \frac{1}{3}x^3 \right|_0^2 = F(2) - F(0) = \frac{8}{3} - \frac{0}{3} = 2.667$$

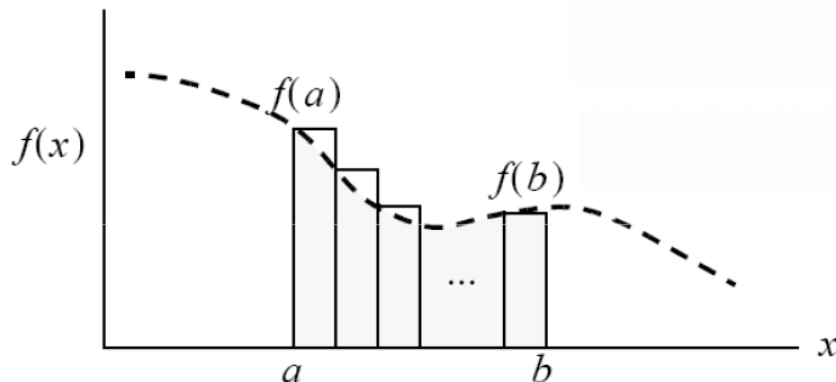
# Approximation of Numerical Integration

- Numerical solutions resort to finding the area under the  $f(x)$  curve through some approximation technique.
- The value of  $\int_a^b f(x)dx$  is approximated by the shaded area under the piecewise-linear interpolation of  $f(x)$ .



## Rectangular Rule

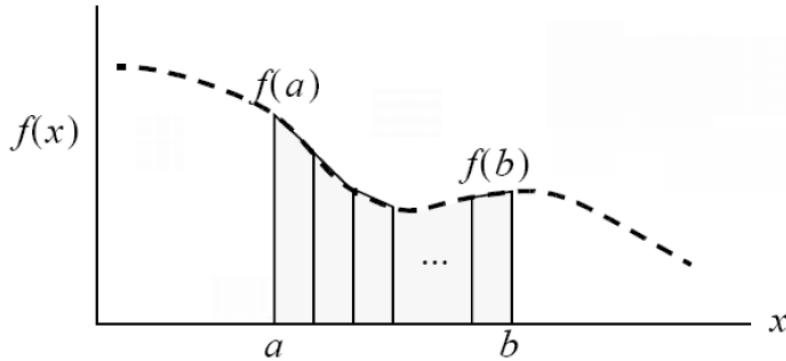
- Area under curve is approximated by sum of the areas of small rectangles.



$$K \approx \sum \text{Rectangular Areas}$$

# Trapezoidal Rule

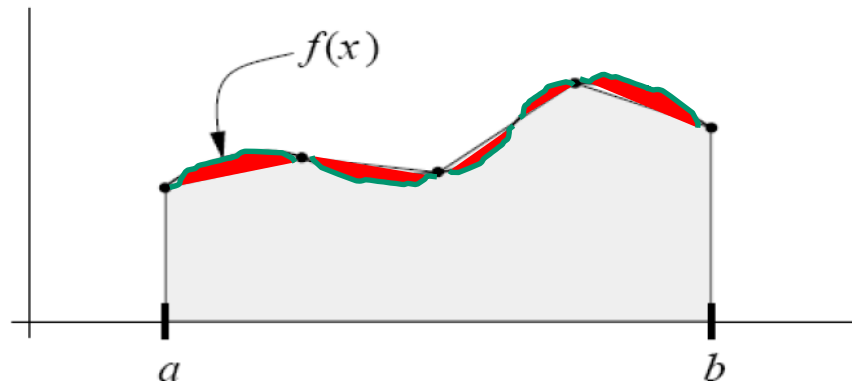
- Area under curve is approximated by sum of the areas of small trapezoids.



$$K \approx \sum \text{Trapezoidal Areas}$$

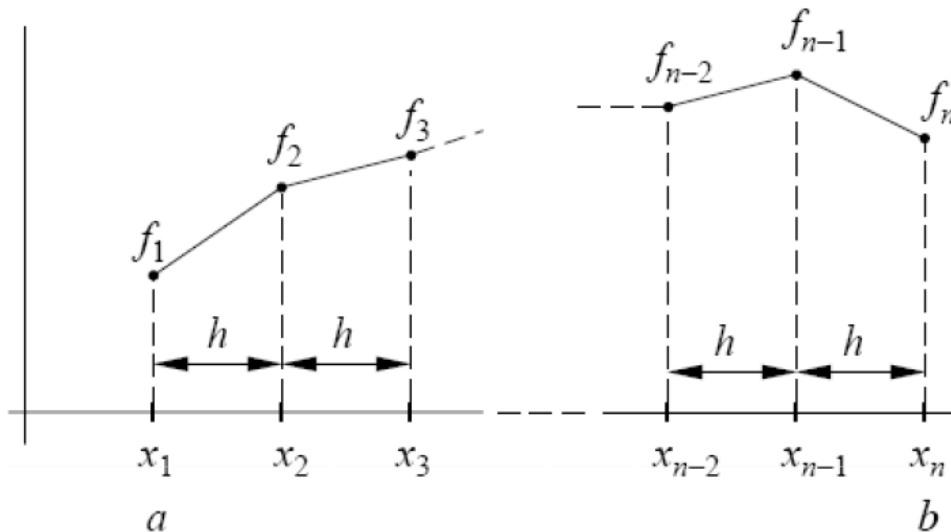
## Truncation Errors

- All numerical integral approximation methods may contain some small truncation errors, due to the uncalculated tiny pieces of areas in function curve boundaries.



# Numerical Integration with Composite Trapezoidal Rule

- The trapezoidal method divides the region under a curve into a set of panels. It then adds up the areas of the individual panels (trapezoids) to get the integral.
- The composite trapezoid rule is obtained summing the areas of all panels.
- The area under  $f(x)$  is divided into  $N$  vertical panels each of width  $h$ , called the step-length.
- $K$  is the estimate approximation to the integral, where  $x_i = a + ih$



$$K = \frac{h}{2} \left[ f(a) + f(b) + 2 \sum_{i=2}^{n-1} f(x_i) \right]$$

$$h = \frac{b - a}{n}$$

# Program

```
#include <stdio.h>

float func(float x)
{ // Curve function f(x)
    return x*x ;
}

int main() {
    float a, b; // Lower and upper limits of integral
    int N;      // Number of panels
    float h;    // Step size
    float x;    // Loop values
    float sum=0;
    float K;    // Resulting integral
    printf("Enter N :"); scanf("%d", &N);
    printf("Enter a and b :"); scanf("%f%f", &a, &b);

    h = (b-a)/N;
    for (x=a+h; x<=b-h; x+=h)
        sum += func(x);

    K = 0.5*h * (func(a) + 2*sum + func(b) );
    printf("Integration = %f \n", K);
} // end main
```



# Screen output

- Expected result  $\int_0^2 x^2 dx = 2.667$
- The result will be more accurate for bigger N values.

Program Output 1

```
Enter N :10  
Enter a and b : 0 2  
Integration = 2.032000
```

Program Output 2

```
Enter N :30  
Enter a and b : 0 2  
Integration = 2.418964
```

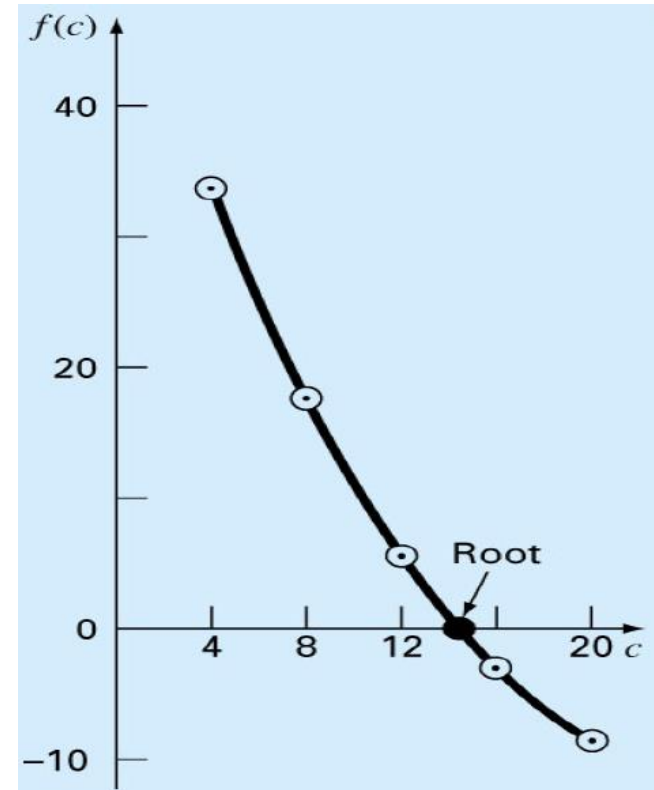
Program Output 3

```
Enter N :50  
Enter a and b : 0 2  
Integration = 2.667199
```

# Example 4: Root Finding

## Example 4: Root Finding for Nonlinear equations

- Nonlinear equations can be written as  $f(x) = 0$
- Finding the roots of a nonlinear equation is equivalent to finding the values of  $x$  for which  $f(x)$  is zero.



## Successive Substitution (Iteration)

- A fundamental principle in computer science is iteration.
- As the name suggests, a process is repeated until an answer is achieved.
- Iterative techniques are used to find roots of equations, solutions of linear and nonlinear systems of equations, and solutions of differential equations.
- A rule or function for computing successive terms is needed, together with a starting value .
- Then a sequence of values is obtained using the iterative rule  $V_{k+1}=g(V_k)$

## Roots of $f(x) = 0$

- Any function of one variable can be put in the form  $f(x) = 0$ .
- Example: To find the  $x$  that satisfies  
 $\cos(x) = x$
- Find the zero crossing of  
 $f(x) = \cos(x) - x = 0$

# The basic strategy for root-finding procedure

1. First, plot the function to see a rough outline.

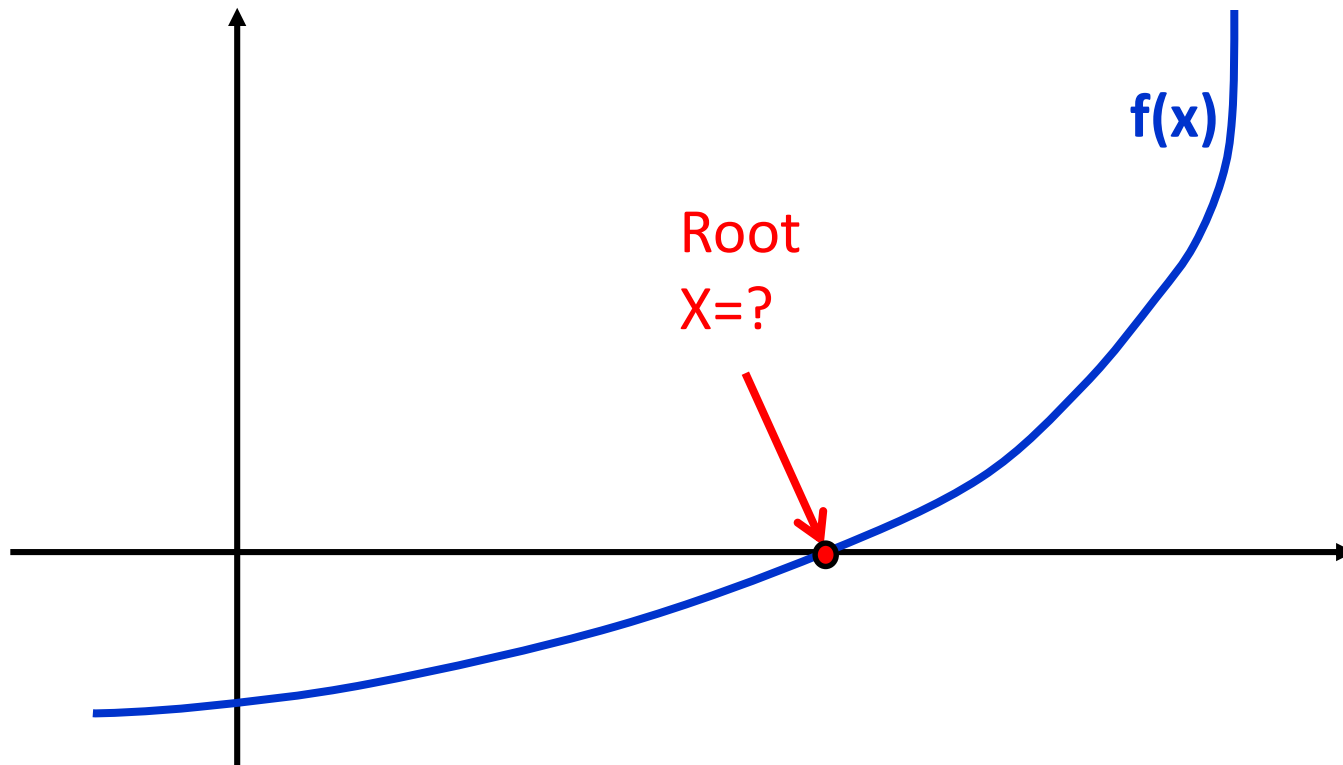
The plot provides an initial guess, and an indication of potential problems.

2. Then, select an **initial guess**.
3. Iteratively refine the initial guess with a root finding algorithm.

If  $x_k$  is the estimate to the root on the  $k^{\text{th}}$  iteration, then the iterations **converge**

# Example Function

- Assume the following is the graphics of  $f(x)$  function.
- We want to find the exact root where  $f(x) = 0$



# Newton-Raphson Method Algorithm

Step 1: Initially, user gives an  $X_1$  value as an estimated root.  
Plug  $X_1$  in the function equation and calculate  $f(X_1)$ .  
Start at the point  $(X_1, f(X_1))$

Step 2: The intersection of the tangent of  $f(X)$  function at this point  
and the  $X$ -axis can be calculated by following formula:  
$$X_2 = X_1 - f(X_1) / f'(X_1)$$

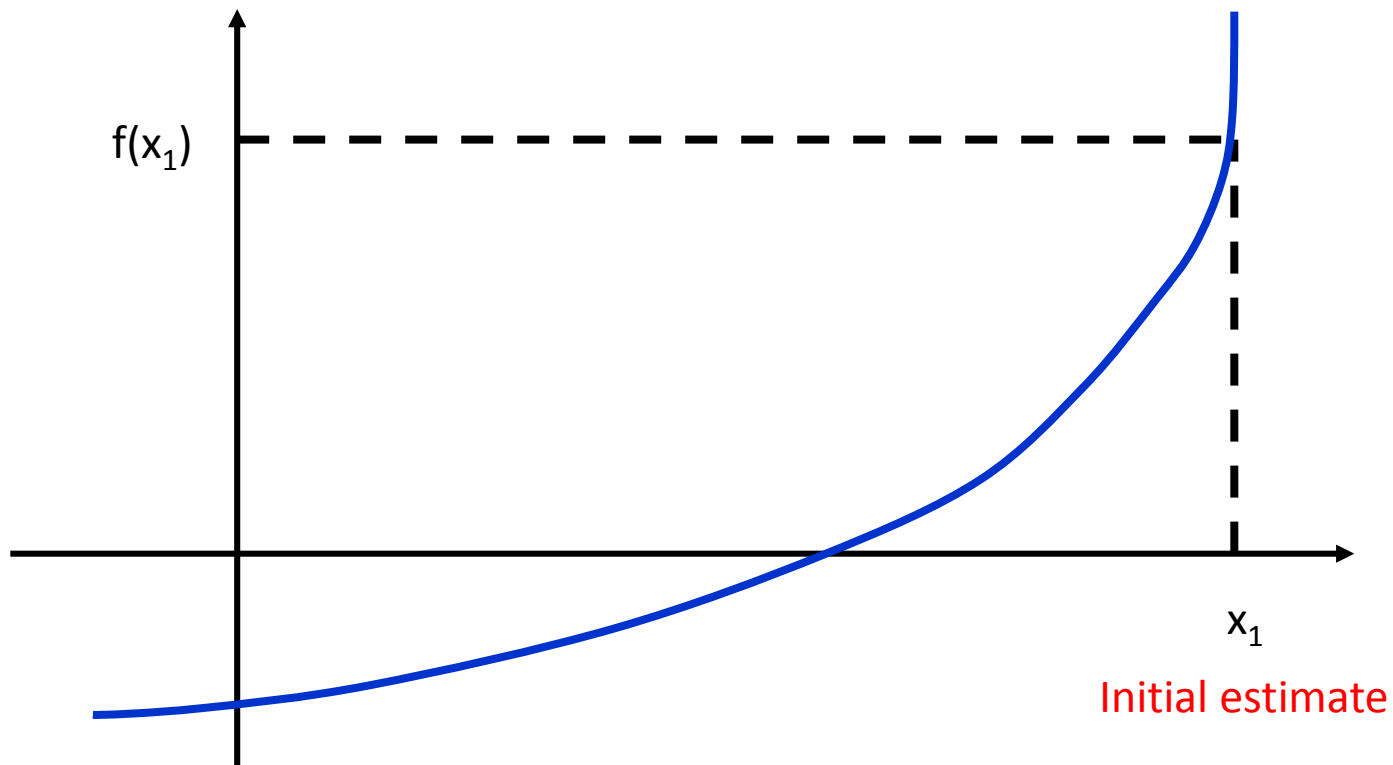
Step 3: Examine if  $f(X_2) = 0$   
or  $\text{abs}(X_2 - X_1) < \text{Tolerance}$

Step 4: If yes, solution  $X_{\text{root}} = X_2$   
If not, assign  $X_2$  to  $X_1$  ( $X_1 \leftarrow X_2$ ), then  
repeat the iteration above.



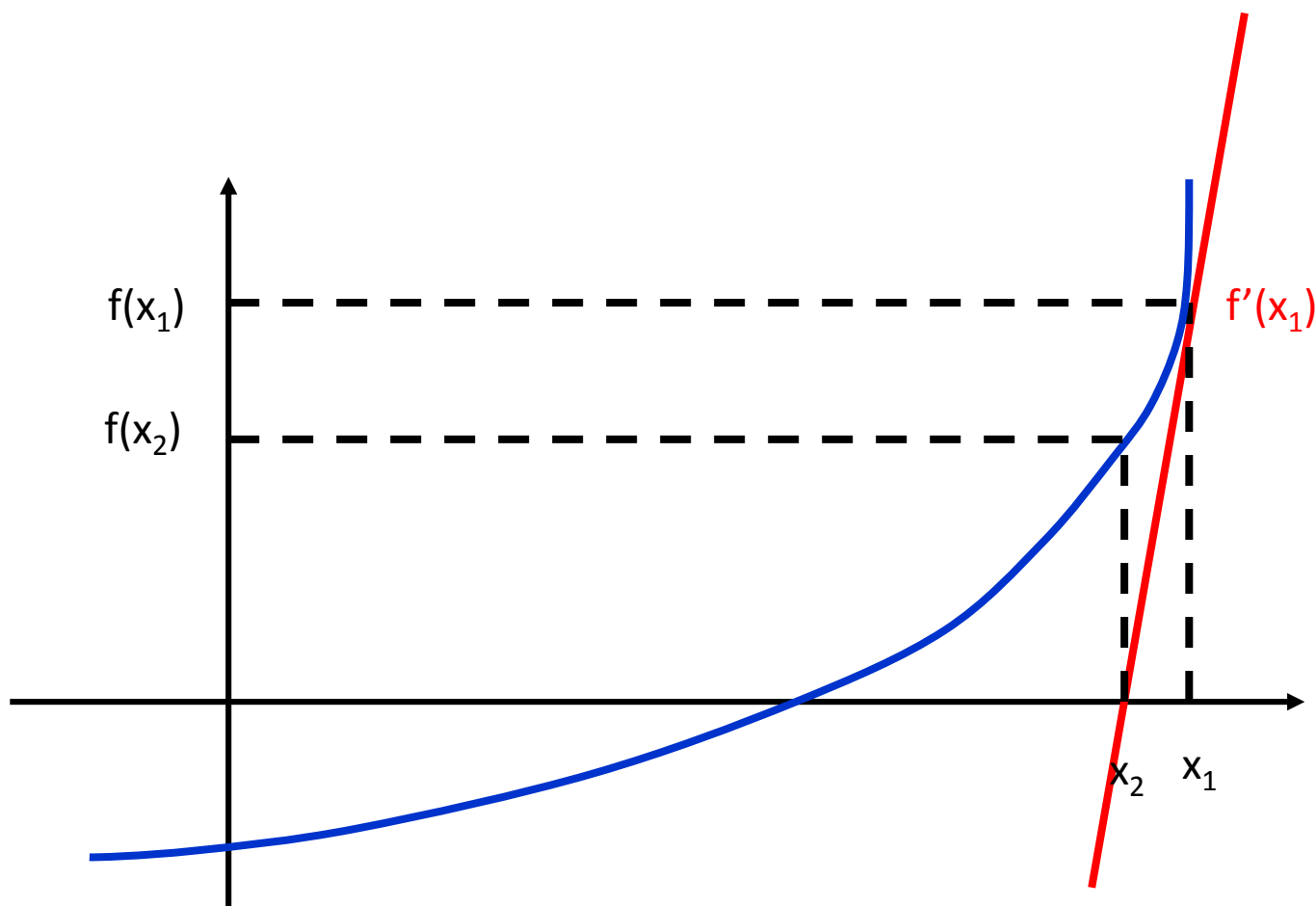
# Initial Root Estimation

- Initially, user gives an  $X_1$  value as an estimated root.
- Plug  $X_1$  in the function equation and calculate  $f(X_1)$ .



# Iteration-1

- Calculate  $X_2$  by using the tangent (teĝet) formula.
- Plug  $X_2$  in the function equation and calculate  $f(X_2)$ .
- Test if  $f(X_2)$  is zero OR Tolerance  $> \text{abs}(X_2 - X_1)$  for stopping.



# Finding $X_2$ by using the Slope Formula

- The slope (tangent) of function  $f$  at point  $X_1$  is the derivative of  $f$ .

$$\text{Slope} = f'(x_1) = \frac{f(x_1) - f(x_2)}{x_1 - x_2}$$

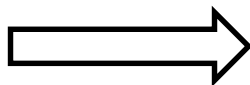
$$f'(x_1) \cdot (x_1 - x_2) = f(x_1) - f(x_2)$$

$$f'(x_1) \cdot x_1 - f'(x_1) \cdot x_2 = f(x_1) - f(x_2)$$

$$f'(x_1) \cdot x_2 = f'(x_1) \cdot x_1 - f(x_1) + f(x_2)$$

$$x_2 = \frac{f'(x_1) \cdot x_1 - f(x_1) + f(x_2)}{f'(x_1)}$$

$$x_2 = x_1 - \frac{f(x_1) - f(x_2)}{f'(x_1)}$$

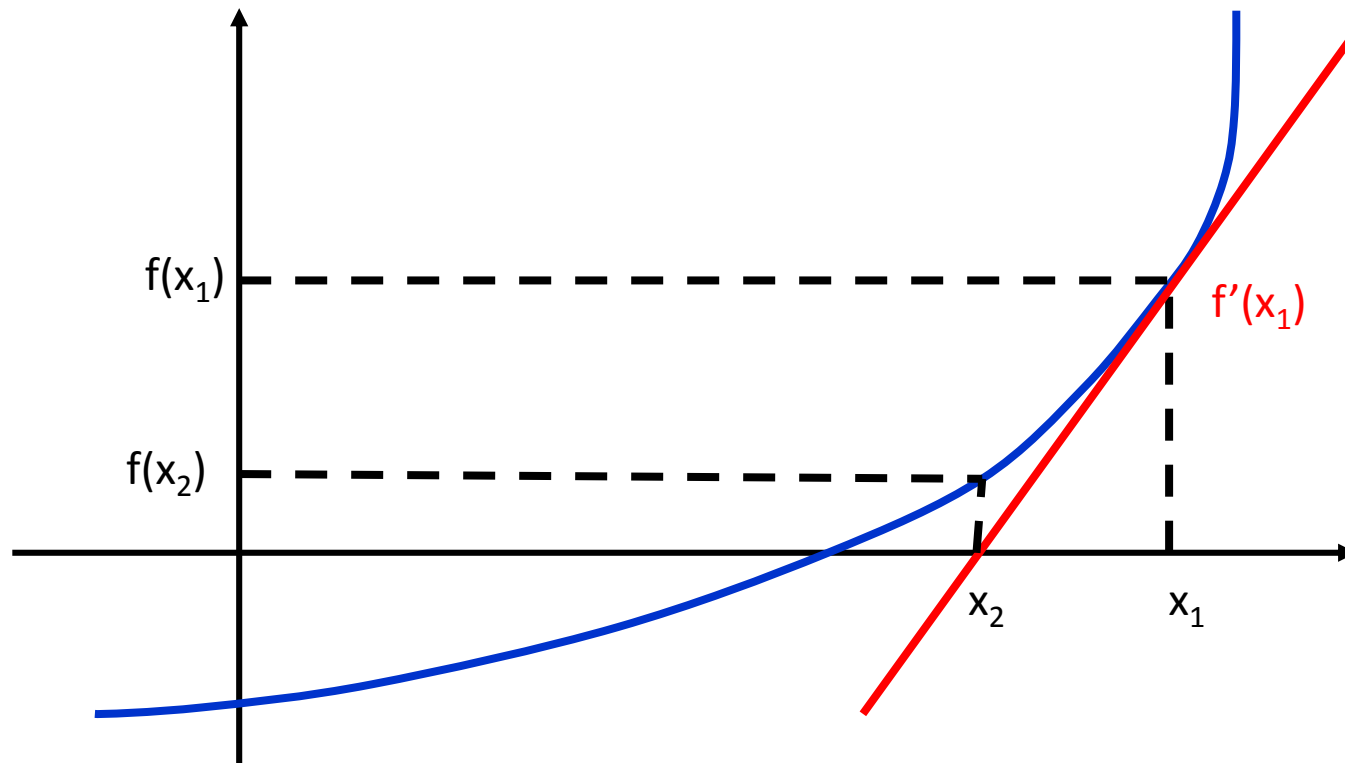


General iteration formula:

$$x_{k+1} = x_k - \frac{f(x_k) - f(x_{k+1})}{f'(x_k)}$$

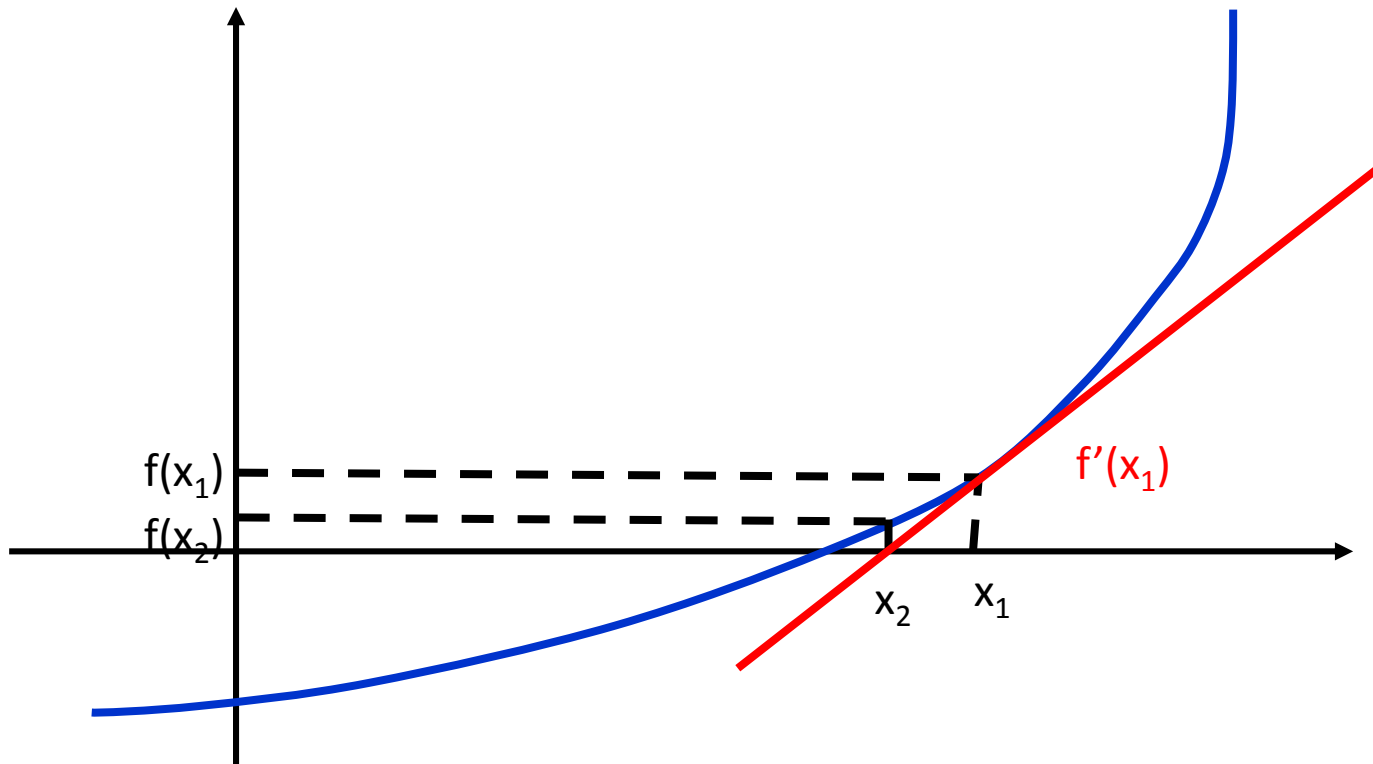
## Iteration-2

- Previous  $X_2$  has now become the new  $X_1$ .
- Calculate new  $X_2$  by using tangent formula again.
- Plug  $X_2$  in function equation and calculate  $f(X_2)$ .
- Test for iteration stopping again.



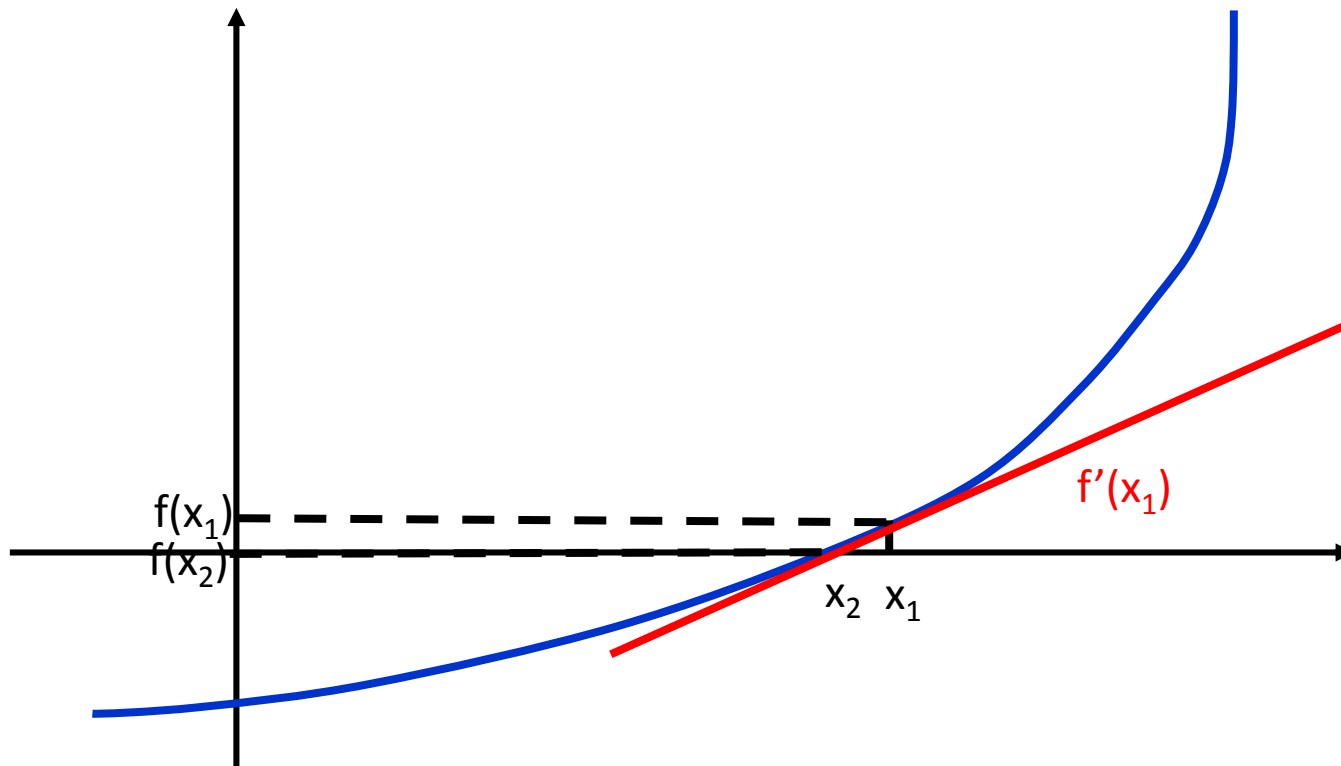
## Iteration-3

- Calculate new  $X_2$  by using tangent formula.
- Plug  $X_2$  in function equation and calculate  $f(X_2)$ .
- Test for iteration stopping.



## Iteration-4

- Calculate new  $X_2$  by using tangent formula.
- Plug  $X_2$  in function equation and calculate  $f(X_2)$ .
- Stopping condition succeeds, iterations stop. The root is the last  $X_2$ .



## Example function

- Find the root of the following function.

$$f(x) = x - \sqrt[3]{x} - 2 = x - x^{\frac{1}{3}} - 2 = 0$$

- First derivative is:

$$f'(x) = 1 - \frac{1}{3}x^{-\frac{2}{3}} = 0$$

- The iteration formula is:

$$x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k)}$$

# Program

```
// Root finding for a nonlinear equation using Newton-Raphson method.
#include <stdio.h>
#include <stdlib.h>
#include <math.h>

float fonk(float x) { // Nonlinear function
    return x - pow(x, 1.0/3) - 2 ;
}

float dfonk(float x) { // Derivative of function
    return 1 - (1.0/3) * pow(x, -2.0/3) ;
}

int main() {
    int n=5; // Set as default limit.
    int k;
    float x0,x1,x2,f,dfdxdx;

    printf("Enter initial guess of root : ");
    scanf("%f", &x0);
    x1 = x0;
```



(continued)

```
printf("  k  f(x)          f'(x)          x(k+1) \n");

for (k=1; k<=n; k++)
{
    f = fonk(x1);
    dfdx = dfonk(x1);
    x2 = x1 -f/dfdx;

    printf("%3d %12.3e %12.3e %18.15f \n", k-1, f, dfdx, x2);

    if (fabs(x2-x1) <= 1.0E-3) { // Tolerance (Convergence testing)
        printf("\nRoot found = %.2f\n", x2);
        return 0; // Stop program
    }
    else
        x1 = x2; // Update x1 (Copy x2 to x1)
} // end for

printf("WARNING: No convergence on root after %d iterations! \n", n);
} // end main
```

# Screen output

Enter initial guess of root : 3.0

k	f(x)	f'(x)	x(k+1)
0	-4.422e-001	8.398e-001	3.526644229888916
1	4.507e-003	8.561e-001	3.521380186080933
2	4.103e-007	8.560e-001	3.521379709243774

Root found = 3.5214

# Example 5: Line Fitting

## Example 5: Line Fitting

- A data file contains set of values  
 $(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)$
- X is independent variable, Y is dependent variable
- Write a program to do the followings:
  - Read data into X and Y arrays, and display them on screen.
  - Perform a Linear Line Fitting  
 (also known as **Regression Analysis**)
- This means calculating the followings for  
 $y = mx + c$  equation.  
**Slope = m**  
**Intercept = c**

istatistik\_veri.txt File

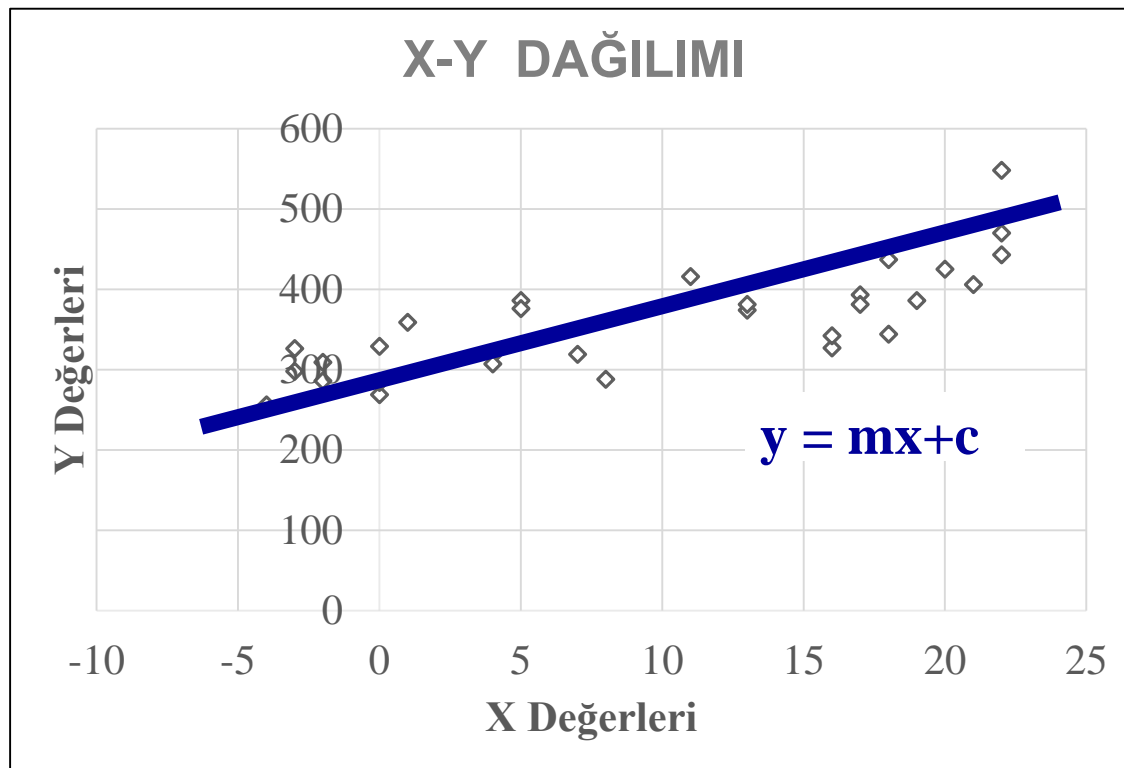
5	386
13	374
17	393
20	425
21	406
18	344
16	327
....	
....	
....	
-2	309
1	359
5	376
11	416
18	437
22	548

# Line Fitting formulas

- Calculate and display the m and c values.

$$\bar{x} = \frac{\sum x}{N}$$

$$\bar{y} = \frac{\sum y}{N}$$



$$m = \frac{\frac{\sum xy}{N} - \bar{x} \bar{y}}{\frac{\sum x^2}{N} - \bar{x}^2}$$

$$c = \bar{y} - m\bar{x}$$

# Program

```
// Line Fitting (Regression Analysis)
#include <stdio.h>
#include <stdlib.h>

int main()
{
    int X[100], Y[100];
    int N, I=0;           // Count of numbers
    float M, C;           // Line slope and intercept
    float XBAR, YBAR;     // Mean x and y values
    float XSUM=0, YSUM=0, XYSUM=0, XXSUM; // Sum values

    FILE * dosya = fopen("istatistik_veri.txt", "r");
    if (!dosya) {
        printf("File can not be opened!\n");
        return 0;
    }
}
```

## (continued)

```
while (!feof(dosya))
{
    fscanf(dosya, "%d %d", &X[I], &Y[I] );
    //printf("%d %d %d \n", I, X[I], Y[I]);
    XSUM += X[I];
    YSUM += Y[I];
    XXSUM += X[I]*X[I];
    XYSUM += X[I]*Y[I];
    I++;
}

fclose(dosya);
N = I-1;

// Calculate best-fit straight line
XBAR = XSUM / N;
YBAR = YSUM / N;
M = ( XYSUM / N - XBAR * YBAR ) / ( XXSUM / N - XBAR * XBAR);
C = YBAR - M * XBAR;
printf("Line Equation : Y = MX + C \n");
printf("Slope = M = %.2f \n", M);
printf("Intercept = C = %.2f \n", C);

} // end main
```

## Screen output

Line Equation :  $Y = MX + C$

Slope =  $M = 4.35$

Intercept =  $C = 329.04$