

multirobot map merge

map

map

robot_1

```
+<robot_namespace>/map_merge/init_pose_x: double
+<robot_namespace>/map_merge/init_pose_y: double
+<robot_namespace>/map_merge/init_pose_z: double
+<robot_namespace>/map_merge/init_pose_yaw: double
+<robot_namespace>/map(): nav_msgs::OccupancyGrid
```

robot_2

```
+<robot_namespace>/map_merge/init_pose_x: double
+<robot_namespace>/map_merge/init_pose_y: double
+<robot_namespace>/map_merge/init_pose_z: double
+<robot_namespace>/map_merge/init_pose_yaw: double
+<robot_namespace>/map(): nav_msgs::OccupancyGrid
```

