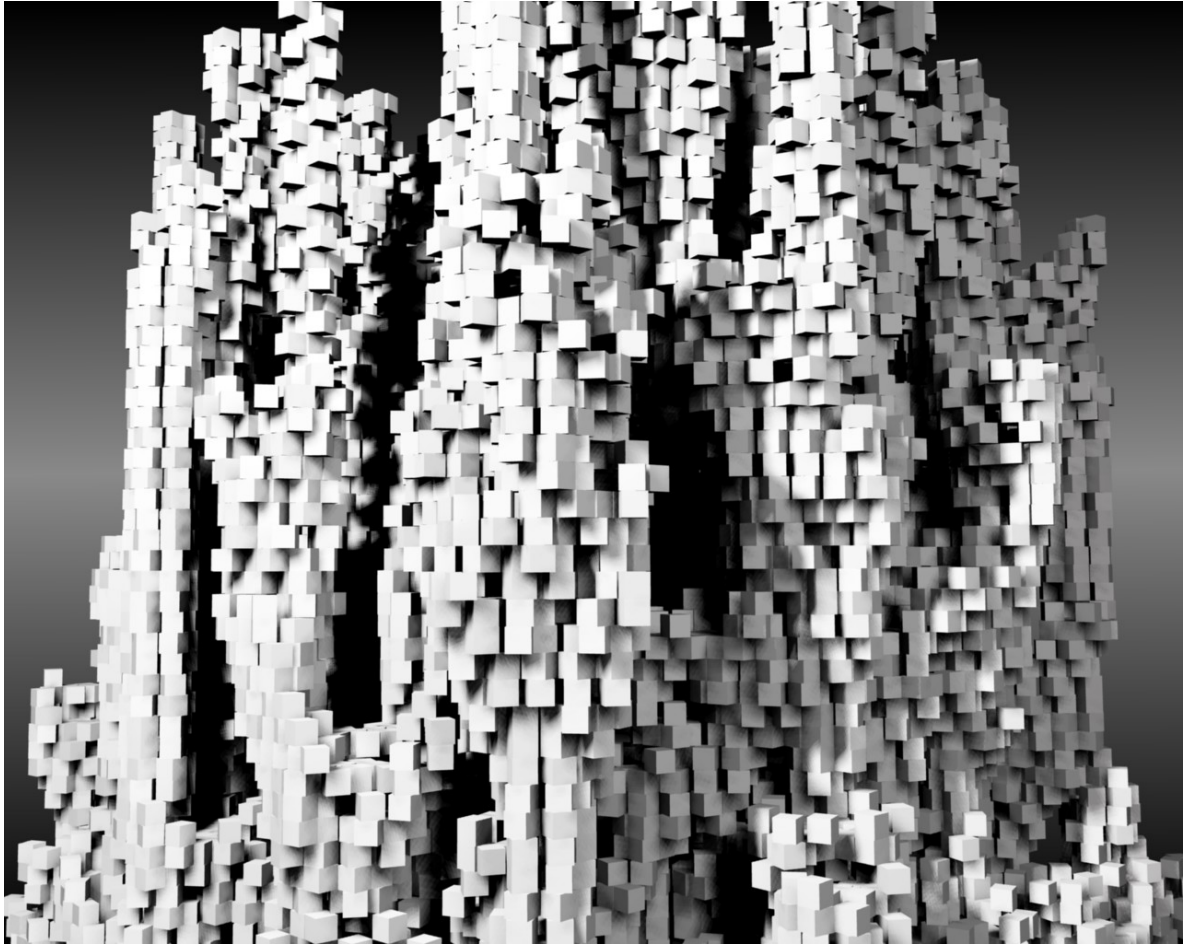


# Morphogenetic Programming

*Week 1: Cellular Automata*



```

// Simple Wolfram CA

int row = 1;
color black = color(0);

// rule 110
// 2 + 4 + 8 + 32 + 64 = 110
int [] response = { 0, 1, 1, 1, 0, 1, 1, 0 };

void setup()
{
    size(200,400);
    set(0,0,black);
}

void draw()
{
    for (int i = 0; i < width; i++)
    {
        color a = get( (i+width-1) % width, row-1);
        color b = get(i,row-1);
        color c = get( (i+width+1) % width, row-1);

        int number = 0;

        if (a == black) {
            number += 1;
        }
        if (b == black) {
            number += 2;
        }
        if (c == black) {
            number += 4;
        }

        if (response[number] == 1) {
            set(i,row,black);
        }
    }
    row++;
}

```

```

// Conway's game of life glider

boolean [][] cells;
boolean [][] nextcells;

void setup()
{
    size(400,400);
    cells = new boolean [100][100];
    nextcells = new boolean [100][100];
    for (int i = 0; i < 100; i++) {
        for (int j = 0; j < 100; j++) {
            cells[i][j] = false;
        }
    }
    // glider setup
    cells[50][50] = true;
    cells[49][50] = true;
    cells[51][50] = true;
    cells[51][49] = true;
    cells[50][48] = true;
    frameRate(6);
}

void draw()
{
    background(192);
    for (int i = 0; i < 100; i++) {
        for (int j = 0; j < 100; j++) {
            if (cells[i][j] == true) {
                rect(i*4,j*4,4,4);
            }
            // count up how many alive around us
            int number = 0;
            for (int m = -1; m <= 1; m++) {
                for (int n = -1; n <= 1; n++) {
                    if (!(m == 0 && n == 0)) {
                        if (cells[(i+m+100)%100][(j+n+100)%100] == true) {
                            number++;
                        }
                    }
                }
            }
            // counted up... now set state of cell for next generation
            if (number < 2 || number > 3) {
                nextcells[i][j] = false;
            }
            else if (number == 3) {
                nextcells[i][j] = true;
            }
            else {
                nextcells[i][j] = cells[i][j];
            }
        }
    }
    for (int i = 0; i < 100; i++) {
        for (int j = 0; j < 100; j++) {
            cells[i][j] = nextcells[i][j];
        }
    }
}

```

```

// Idealised Belousov-Zhabotinsky reaction

// An implementation note about this algorithm is available here:
// http://www.aac.bartlett.ucl.ac.uk/processing/samples/bzr.pdf

float [][][] a;
float [][][] b;
float [][][] c;

int p = 0, q = 1;

void setup()
{
    size(400,400);
    colorMode(HSB,1.0);
    a = new float [width][height][2];
    b = new float [width][height][2];
    c = new float [width][height][2];
    for (int x = 0; x < width; x++) {
        for (int y = 0; y < height; y++) {
            a[x][y][p] = random(0.0,1.0);
            b[x][y][p] = random(0.0,1.0);
            c[x][y][p] = random(0.0,1.0);
            set(x,y,color(0.5,0.7,a[x][y][p]));
        }
    }
}

void draw()
{
    for (int x = 0; x < width; x++) {
        for (int y = 0; y < height; y++) {
            float c_a = 0.0;
            float c_b = 0.0;
            float c_c = 0.0;
            for (int i = x - 1; i <= x+1; i++) {
                for (int j = y - 1; j <= y+1; j++) {
                    c_a += a[(i+width)%width][(j+height)%height][p];
                    c_b += b[(i+width)%width][(j+height)%height][p];
                    c_c += c[(i+width)%width][(j+height)%height][p];
                }
            }
            c_a /= 9.0;
            c_b /= 9.0;
            c_c /= 9.0;
            // adjust these values to alter behaviour
            a[x][y][q] = constrain(c_a + c_a * (c_b - c_c), 0, 1);
            b[x][y][q] = constrain(c_b + c_b * (c_c - c_a), 0, 1);
            c[x][y][q] = constrain(c_c + c_c * (c_a - c_b), 0, 1);
            set(x,y,color(0.5,0.7,a[x][y][q]));
        }
    }
    if (p == 0) {
        p = 1; q = 0;
    }
    else {
        p = 0; q = 1;
    }
}

```

