

# C4W2\_Assignment

March 18, 2023

## 1 Week 2: Predicting time series

Welcome! In the previous assignment you got some exposure to working with time series data, but you didn't use machine learning techniques for your forecasts. This week you will be using a deep neural network to create forecasts to see how this technique compares with the ones you already tried out. Once again all of the data is going to be generated.

Let's get started!

**NOTE:** To prevent errors from the autograder, you are not allowed to edit or delete some of the cells in this notebook. Please only put your solutions in between the **### START CODE HERE** and **### END CODE HERE** code comments, and also refrain from adding any new cells. **Once you have passed this assignment** and want to experiment with any of the locked cells, you may follow the instructions at the bottom of this notebook.

```
[1]: import numpy as np
import tensorflow as tf
import matplotlib.pyplot as plt
from dataclasses import dataclass
```

### 1.1 Generating the data

The next cell includes a bunch of helper functions to generate and plot the time series:

```
[2]: def plot_series(time, series, format="-", start=0, end=None):
    plt.plot(time[start:end], series[start:end], format)
    plt.xlabel("Time")
    plt.ylabel("Value")
    plt.grid(False)

def trend(time, slope=0):
    return slope * time

def seasonal_pattern(season_time):
    """An arbitrary pattern"""
    return np.where(season_time < 0.1,
                    np.cos(season_time * 6 * np.pi),
                    2 / np.exp(9 * season_time))
```

```
def seasonality(time, period, amplitude=1, phase=0):
    """Repeats the same pattern at each period"""
    season_time = ((time + phase) % period) / period
    return amplitude * seasonal_pattern(season_time)

def noise(time, noise_level=1, seed=None):
    rnd = np.random.RandomState(seed)
    return rnd.randn(len(time)) * noise_level
```

You will be generating time series data that greatly resembles the one from last week but with some differences.

Notice that this time all the generation is done within a function and global variables are saved within a dataclass. This is done to avoid using global scope as it was done in during the previous week.

If you haven't used dataclasses before, they are just Python classes that provide a convenient syntax for storing data. You can read more about them in the [docs](#).

```
[3]: def generate_time_series():
    # The time dimension or the x-coordinate of the time series
    time = np.arange(4 * 365 + 1, dtype="float32")

    # Initial series is just a straight line with a y-intercept
    y_intercept = 10
    slope = 0.005
    series = trend(time, slope) + y_intercept

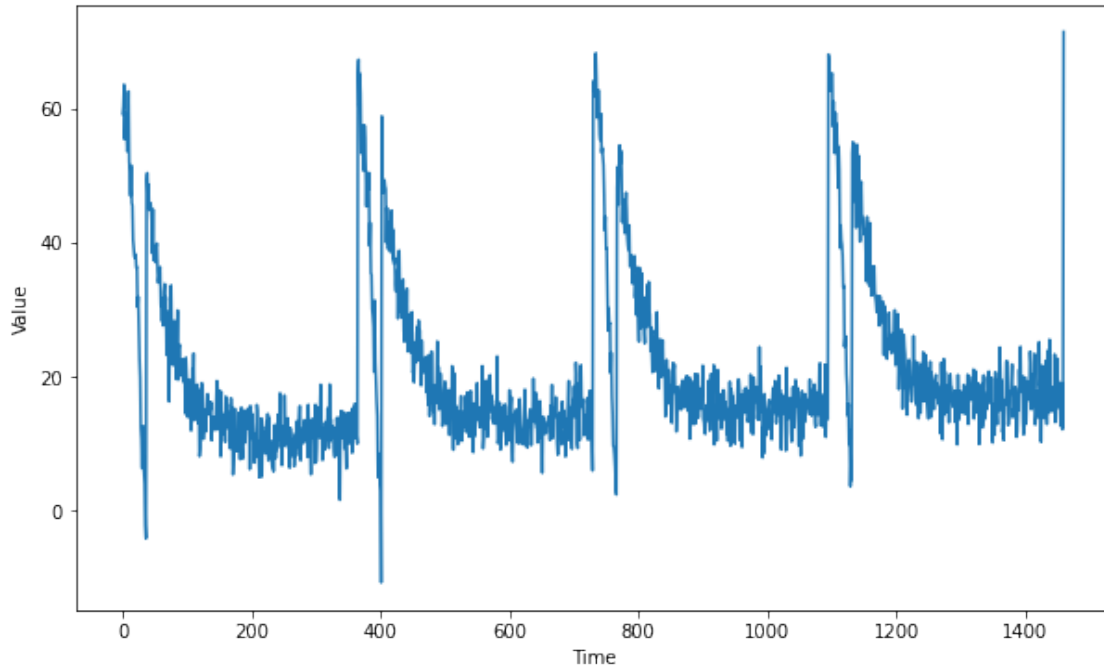
    # Adding seasonality
    amplitude = 50
    series += seasonality(time, period=365, amplitude=amplitude)

    # Adding some noise
    noise_level = 3
    series += noise(time, noise_level, seed=51)

    return time, series

# Save all "global" variables within the G class (G stands for global)
@dataclass
class G:
    TIME, SERIES = generate_time_series()
    SPLIT_TIME = 1100
    WINDOW_SIZE = 20
    BATCH_SIZE = 32
    SHUFFLE_BUFFER_SIZE = 1000
```

```
# Plot the generated series
plt.figure(figsize=(10, 6))
plot_series(G.TIME, G.SERIES)
plt.show()
```



## 1.2 Splitting the data

Since you already coded the `train_val_split` function during last week's assignment, this time it is provided for you:

```
[4]: def train_val_split(time, series, time_step=G.SPLIT_TIME):

    time_train = time[:time_step]
    series_train = series[:time_step]
    time_valid = time[time_step:]
    series_valid = series[time_step:]

    return time_train, series_train, time_valid, series_valid

# Split the dataset
time_train, series_train, time_valid, series_valid = train_val_split(G.TIME, G.
    ↪SERIES)
```

### 1.3 Processing the data

As you saw on the lectures you can feed the data for training by creating a dataset with the appropriate processing steps such as **windowing**, **flattening**, **batching** and **shuffling**. To do so complete the `windowed_dataset` function below.

Notice that this function receives a `series`, `window_size`, `batch_size` and `shuffle_buffer` and the last three of these default to the “global” values defined earlier.

Be sure to check out the [docs](#) about TF Datasets if you need any help.

```
[6]: def windowed_dataset(series, window_size=G.WINDOW_SIZE, batch_size=G.  
    ↪BATCH_SIZE, shuffle_buffer=G.SHUFFLE_BUFFER_SIZE):  
  
    ### START CODE HERE  
  
    # Create dataset from the series  
    dataset = tf.data.Dataset.from_tensor_slices(series)  
  
    # Slice the dataset into the appropriate windows  
    dataset = dataset.window(window_size + 1, shift=1, drop_remainder=True)  
  
    # Flatten the dataset  
    dataset = dataset.flat_map(lambda window: window.batch(window_size + 1))  
  
    # Shuffle it  
    dataset = dataset.shuffle(shuffle_buffer)  
  
    # Split it into the features and labels  
    dataset = dataset.map(lambda window: (window[:-1], window[-1]))  
  
    # Batch it  
    dataset = dataset.batch(batch_size).prefetch(1)  
  
    ### END CODE HERE  
  
    return dataset
```

To test your function you will be using a `window_size` of 1 which means that you will use each value to predict the next one. This for 5 elements since a `batch_size` of 5 is used and no shuffle since `shuffle_buffer` is set to 1.

Given this, the batch of features should be identical to the first 5 elements of the `series_train` and the batch of labels should be equal to elements 2 through 6 of the `series_train`.

```
[7]: # Test your function with windows size of 1 and no shuffling  
test_dataset = windowed_dataset(series_train, window_size=1, batch_size=5,  
    ↪shuffle_buffer=1)  
  
# Get the first batch of the test dataset
```

```

batch_of_features, batch_of_labels = next((iter(test_dataset)))

print(f"batch_of_features has type: {type(batch_of_features)}\n")
print(f"batch_of_labels has type: {type(batch_of_labels)}\n")
print(f"batch_of_features has shape: {batch_of_features.shape}\n")
print(f"batch_of_labels has shape: {batch_of_labels.shape}\n")
print(f"batch_of_features is equal to first five elements in the series: {np.
    ↳allclose(batch_of_features.numpy().flatten(), series_train[:5])}\n")
print(f"batch_of_labels is equal to first five labels: {np.
    ↳allclose(batch_of_labels.numpy(), series_train[1:6])}")

```

```

batch_of_features has type: <class
'tensorflow.python.framework.ops.EagerTensor'>

```

```

batch_of_labels has type: <class 'tensorflow.python.framework.ops.EagerTensor'>

```

```

batch_of_features has shape: (5, 1)

```

```

batch_of_labels has shape: (5,)

```

```

batch_of_features is equal to first five elements in the series: True

```

```

batch_of_labels is equal to first five labels: True

```

#### Expected Output:

```

batch_of_features has type: <class 'tensorflow.python.framework.ops.EagerTensor'>

```

```

batch_of_labels has type: <class 'tensorflow.python.framework.ops.EagerTensor'>

```

```

batch_of_features has shape: (5, 1)

```

```

batch_of_labels has shape: (5,)

```

```

batch_of_features is equal to first five elements in the series: True

```

```

batch_of_labels is equal to first five labels: True

```

## 1.4 Defining the model architecture

Now that you have a function that will process the data before it is fed into your neural network for training, it is time to define your layer architecture.

Complete the `create_model` function below. Notice that this function receives the `window_size` since this will be an important parameter for the first layer of your network.

Hint: - You will only need Dense layers. - Do not include Lambda layers. These are not required and are incompatible with the HDF5 format which will be used to save your model for grading. - The training should be really quick so if you notice that each epoch is taking more than a few seconds, consider trying a different architecture.

```
[14]: def create_model(window_size=G.WINDOW_SIZE):

    ### START CODE HERE

    model = tf.keras.models.Sequential([
        tf.keras.layers.Dense(100, input_shape=[window_size],
        ↪activation="relu"),
        tf.keras.layers.Dense(10, activation="relu"),
        tf.keras.layers.Dense(1)
    ])

    model.compile(loss="mse",
                  ↪optimizer=tf.keras.optimizers.SGD(learning_rate=1e-6,
        ↪momentum=0.9))

    ### END CODE HERE

    return model
```

```
[15]: # Apply the processing to the whole training series
dataset = windowed_dataset(series_train)

# Save an instance of the model
model = create_model()

# Train it
model.fit(dataset, epochs=100)
```

```
Epoch 1/100
34/34 [=====] - 0s 1ms/step - loss: 76.7906
Epoch 2/100
34/34 [=====] - 0s 866us/step - loss: 48.9106
Epoch 3/100
34/34 [=====] - 0s 1ms/step - loss: 43.0239
Epoch 4/100
34/34 [=====] - 0s 867us/step - loss: 38.6106
Epoch 5/100
34/34 [=====] - 0s 896us/step - loss: 37.3263
Epoch 6/100
34/34 [=====] - 0s 898us/step - loss: 36.2143
Epoch 7/100
34/34 [=====] - 0s 829us/step - loss: 34.7691
Epoch 8/100
34/34 [=====] - 0s 811us/step - loss: 34.0768
Epoch 9/100
34/34 [=====] - 0s 815us/step - loss: 34.9535
Epoch 10/100
```

```

34/34 [=====] - 0s 796us/step - loss: 33.1382
Epoch 11/100
34/34 [=====] - 0s 785us/step - loss: 33.0339
Epoch 12/100
34/34 [=====] - 0s 1ms/step - loss: 32.4080
Epoch 13/100
34/34 [=====] - 0s 855us/step - loss: 31.8706
Epoch 14/100
34/34 [=====] - 0s 856us/step - loss: 31.4413
Epoch 15/100
34/34 [=====] - 0s 930us/step - loss: 31.5729
Epoch 16/100
34/34 [=====] - 0s 891us/step - loss: 31.5443
Epoch 17/100
34/34 [=====] - 0s 809us/step - loss: 30.5861
Epoch 18/100
34/34 [=====] - 0s 812us/step - loss: 30.4374
Epoch 19/100
34/34 [=====] - 0s 806us/step - loss: 30.0316
Epoch 20/100
34/34 [=====] - 0s 800us/step - loss: 30.2791
Epoch 21/100
34/34 [=====] - 0s 1ms/step - loss: 30.2153
Epoch 22/100
34/34 [=====] - 0s 823us/step - loss: 29.5581
Epoch 23/100
34/34 [=====] - 0s 909us/step - loss: 29.7306
Epoch 24/100
34/34 [=====] - 0s 826us/step - loss: 29.6059
Epoch 25/100
34/34 [=====] - 0s 866us/step - loss: 29.3070
Epoch 26/100
34/34 [=====] - 0s 837us/step - loss: 29.1992
Epoch 27/100
34/34 [=====] - 0s 808us/step - loss: 29.0409
Epoch 28/100
34/34 [=====] - 0s 876us/step - loss: 29.1956
Epoch 29/100
34/34 [=====] - 0s 1ms/step - loss: 28.9901
Epoch 30/100
34/34 [=====] - 0s 878us/step - loss: 28.8776
Epoch 31/100
34/34 [=====] - 0s 842us/step - loss: 28.6670
Epoch 32/100
34/34 [=====] - 0s 856us/step - loss: 28.4101
Epoch 33/100
34/34 [=====] - 0s 866us/step - loss: 28.9921
Epoch 34/100

```

```

34/34 [=====] - 0s 822us/step - loss: 28.5195
Epoch 35/100
34/34 [=====] - 0s 794us/step - loss: 28.4032
Epoch 36/100
34/34 [=====] - 0s 766us/step - loss: 28.3367
Epoch 37/100
34/34 [=====] - 0s 815us/step - loss: 28.3260
Epoch 38/100
34/34 [=====] - 0s 859us/step - loss: 28.1118
Epoch 39/100
34/34 [=====] - 0s 1ms/step - loss: 28.2208
Epoch 40/100
34/34 [=====] - 0s 949us/step - loss: 28.1187
Epoch 41/100
34/34 [=====] - 0s 833us/step - loss: 28.2044
Epoch 42/100
34/34 [=====] - 0s 775us/step - loss: 28.3524
Epoch 43/100
34/34 [=====] - 0s 791us/step - loss: 28.2040
Epoch 44/100
34/34 [=====] - 0s 811us/step - loss: 27.7659
Epoch 45/100
34/34 [=====] - 0s 807us/step - loss: 27.8125
Epoch 46/100
34/34 [=====] - 0s 934us/step - loss: 27.7617
Epoch 47/100
34/34 [=====] - 0s 809us/step - loss: 27.6207
Epoch 48/100
34/34 [=====] - 0s 935us/step - loss: 27.8270
Epoch 49/100
34/34 [=====] - 0s 800us/step - loss: 27.6419
Epoch 50/100
34/34 [=====] - 0s 876us/step - loss: 27.8492
Epoch 51/100
34/34 [=====] - 0s 823us/step - loss: 27.4474
Epoch 52/100
34/34 [=====] - 0s 797us/step - loss: 27.3851
Epoch 53/100
34/34 [=====] - 0s 775us/step - loss: 27.2936
Epoch 54/100
34/34 [=====] - 0s 789us/step - loss: 27.5270
Epoch 55/100
34/34 [=====] - 0s 846us/step - loss: 27.5957
Epoch 56/100
34/34 [=====] - 0s 991us/step - loss: 27.4939
Epoch 57/100
34/34 [=====] - 0s 804us/step - loss: 27.1823
Epoch 58/100

```



```

34/34 [=====] - 0s 869us/step - loss: 27.3744
Epoch 59/100
34/34 [=====] - 0s 813us/step - loss: 27.3008
Epoch 60/100
34/34 [=====] - 0s 806us/step - loss: 26.9541
Epoch 61/100
34/34 [=====] - 0s 768us/step - loss: 27.2511
Epoch 62/100
34/34 [=====] - 0s 812us/step - loss: 27.1003
Epoch 63/100
34/34 [=====] - 0s 803us/step - loss: 27.0869
Epoch 64/100
34/34 [=====] - 0s 850us/step - loss: 26.8620
Epoch 65/100
34/34 [=====] - 0s 818us/step - loss: 27.4088
Epoch 66/100
34/34 [=====] - 0s 1ms/step - loss: 26.8738
Epoch 67/100
34/34 [=====] - 0s 832us/step - loss: 26.9642
Epoch 68/100
34/34 [=====] - 0s 803us/step - loss: 26.7449
Epoch 69/100
34/34 [=====] - 0s 849us/step - loss: 26.6154
Epoch 70/100
34/34 [=====] - 0s 887us/step - loss: 26.6287
Epoch 71/100
34/34 [=====] - 0s 807us/step - loss: 26.5193
Epoch 72/100
34/34 [=====] - 0s 841us/step - loss: 26.5774
Epoch 73/100
34/34 [=====] - 0s 805us/step - loss: 26.6168
Epoch 74/100
34/34 [=====] - 0s 824us/step - loss: 26.6886
Epoch 75/100
34/34 [=====] - 0s 807us/step - loss: 26.6523
Epoch 76/100
34/34 [=====] - 0s 993us/step - loss: 26.4989
Epoch 77/100
34/34 [=====] - 0s 913us/step - loss: 26.7046
Epoch 78/100
34/34 [=====] - 0s 842us/step - loss: 26.6001
Epoch 79/100
34/34 [=====] - 0s 827us/step - loss: 26.4586
Epoch 80/100
34/34 [=====] - 0s 833us/step - loss: 26.2786
Epoch 81/100
34/34 [=====] - 0s 770us/step - loss: 26.2457
Epoch 82/100

```

```

34/34 [=====] - 0s 868us/step - loss: 26.3300
Epoch 83/100
34/34 [=====] - 0s 779us/step - loss: 26.2070
Epoch 84/100
34/34 [=====] - 0s 905us/step - loss: 26.3616
Epoch 85/100
34/34 [=====] - 0s 1ms/step - loss: 26.1576
Epoch 86/100
34/34 [=====] - 0s 853us/step - loss: 26.4906
Epoch 87/100
34/34 [=====] - 0s 873us/step - loss: 26.2906
Epoch 88/100
34/34 [=====] - 0s 920us/step - loss: 26.0385
Epoch 89/100
34/34 [=====] - 0s 812us/step - loss: 26.2294
Epoch 90/100
34/34 [=====] - 0s 885us/step - loss: 26.0569
Epoch 91/100
34/34 [=====] - 0s 887us/step - loss: 26.5833
Epoch 92/100
34/34 [=====] - 0s 848us/step - loss: 26.1344
Epoch 93/100
34/34 [=====] - 0s 1ms/step - loss: 25.9677
Epoch 94/100
34/34 [=====] - 0s 837us/step - loss: 25.9609
Epoch 95/100
34/34 [=====] - 0s 845us/step - loss: 25.7998
Epoch 96/100
34/34 [=====] - 0s 887us/step - loss: 26.0411
Epoch 97/100
34/34 [=====] - 0s 930us/step - loss: 25.7497
Epoch 98/100
34/34 [=====] - 0s 908us/step - loss: 26.0697
Epoch 99/100
34/34 [=====] - 0s 880us/step - loss: 25.9810
Epoch 100/100
34/34 [=====] - 0s 843us/step - loss: 25.8642

```

```
[15]: <keras.callbacks.History at 0x7fe3402fca00>
```

## 1.5 Evaluating the forecast

Now it is time to evaluate the performance of the forecast. For this you can use the `compute_metrics` function that you coded in the previous assignment:

```
[16]: def compute_metrics(true_series, forecast):

    mse = tf.keras.metrics.mean_squared_error(true_series, forecast).numpy()
```

```

mae = tf.keras.metrics.mean_absolute_error(true_series, forecast).numpy()

return mse, mae

```

At this point only the model that will perform the forecast is ready but you still need to compute the actual forecast.

For this, run the cell below which uses the `generate_forecast` function to compute the forecast. This function generates the next value given a set of the previous `window_size` points for every point in the validation set.

```

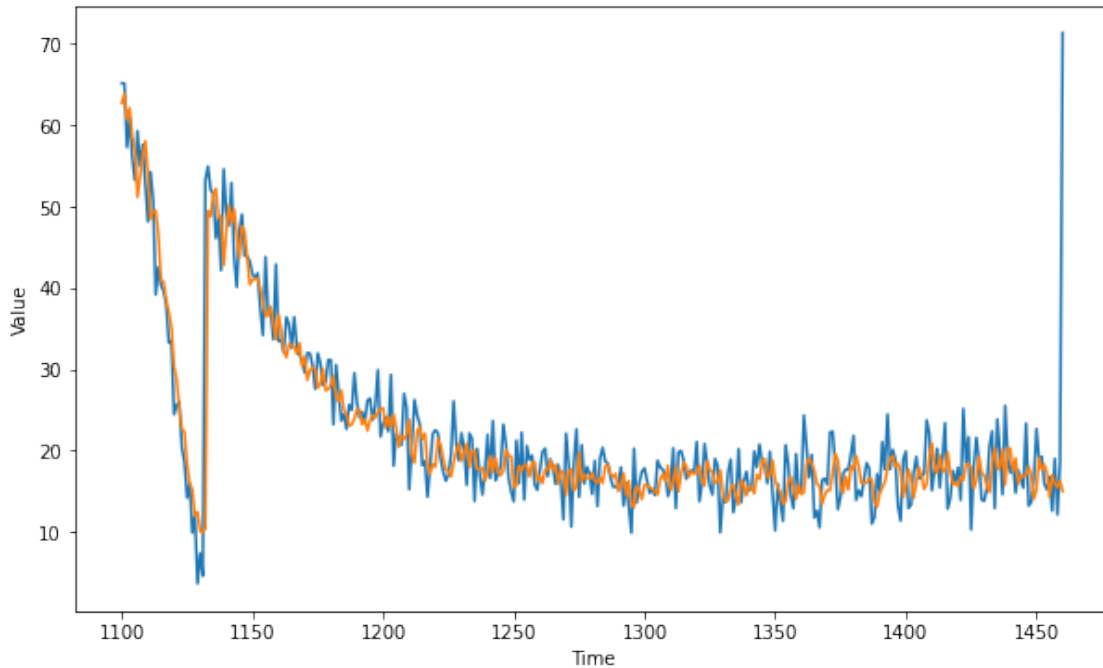
[17]: def generate_forecast(series=G.SERIES, split_time=G.SPLIT_TIME, window_size=G.
      ↪ WINDOW_SIZE):
        forecast = []
        for time in range(len(series) - window_size):
            forecast.append(model.predict(series[time:time + window_size][np.
            ↪ newaxis]))

        forecast = forecast[split_time-window_size:]
        results = np.array(forecast)[: , 0, 0]
        return results

# Save the forecast
dnn_forecast = generate_forecast()

# Plot it
plt.figure(figsize=(10, 6))
plot_series(time_valid, series_valid)
plot_series(time_valid, dnn_forecast)

```



### Expected Output:

A series similar to this one:

```
[18]: mse, mae = compute_metrics(series_valid, dnn_forecast)

print(f"mse: {mse:.2f}, mae: {mae:.2f} for forecast")
```

mse: 27.42, mae: 3.18 for forecast

To pass this assignment your forecast should achieve an MSE of 30 or less.

- If your forecast didn't achieve this threshold try re-training your model with a different architecture or tweaking the optimizer's parameters.
- If your forecast did achieve this threshold run the following cell to save your model in a HDF5 file which will be used for grading and after doing so, submit your assignment for grading.
- Make sure you didn't use `Lambda` layers in your model since these are incompatible with the HDF5 format which will be used to save your model for grading.
- This environment includes a dummy `my_model.h5` file which is just a dummy model trained for one epoch. **To replace this file with your actual model you need to run the next cell before submitting for grading.**

```
[19]: # Save your model in HDF5 format
model.save('my_model.h5')
```

**Congratulations on finishing this week's assignment!**

You have successfully implemented a neural network capable of forecasting time series while also learning how to leverage Tensorflow's Dataset class to process time series data!

### **Keep it up!**

Please click [here](#) if you want to experiment with any of the non-graded code.

Important Note: Please only do this when you've already passed the assignment to avoid problems with the autograder.

On the notebook's menu, click "View" > "Cell Toolbar" > "Edit Metadata"

Hit the "Edit Metadata" button next to the code cell which you want to lock/unlock

Set the attribute value for "editable" to:

"true" if you want to unlock it

"false" if you want to lock it

```
</li>
<li> On the notebook's menu, click "View" > "Cell Toolbar" > "None" </li>
</ol>
<p> Here's a short demo of how to do the steps above:
<br>

```