# Speaker Recognition SRT project of Signal Processing

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## Overview

## **Speaker Recognition**

Identification of the person who is speaking by characteristics of their voice biometrics.

#### **Primary Goal:**

• Accurate and Efficient Short utterance speaker recognition.

#### Additional Goal:

- Scalability over large number of speakers.
- Low Latency Real-Time recognition
- A working Real-Time recognition system.

## Content

## VAD

## **Voice Activity Detection** shall be applied for all signals as a pre-filter. We've tried 2 different approaches:

- Energy-Based:
  - Filter out the intervals with relatively low energy.
  - Work perfectly for high-quality recordings.
  - Sensitive to noise.
- Long-Term Spectral Divergence
  - Compare long-term spectral envelope with noise spectrum.
  - More robust to noise, used in our GUI
  - Efficient voice activity detection algorithms using long-term speech information, Ramırez, Javier, 2004



## VAD

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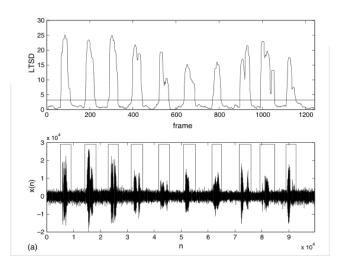
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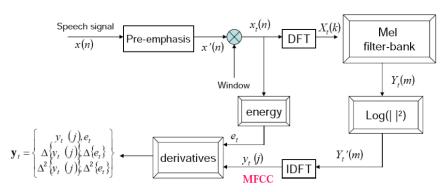
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## **LTSD**

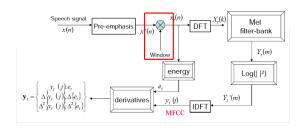


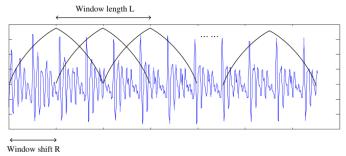
## **Mel-Frequency Cepstral Coefficients**

Cepstral feature which closely approximates human auditory system's response. Commonly used feature for Speech/Speaker Recognition.

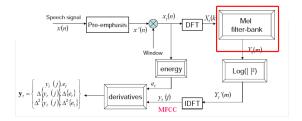


## Windowing

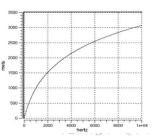




## Mel-Scale



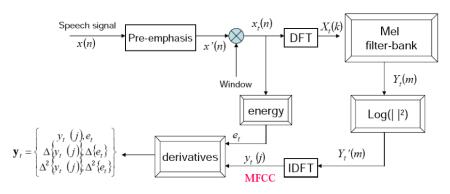
$$\mathit{Mel}(\mathit{f}) = 2595 \log_{10}(1 + \frac{\mathit{f}}{700})$$



#### **MFCC**

## **Mel-Frequency Cepstral Coefficients**

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## **LPC**

## **Linear Predictive Coding/Coefficients**

#### Assumption

In a short period, the nth signal is a linear combination of previous p

signals: 
$$\hat{x}(n) = \sum_{i=1}^{p} a_i x(n-i)$$

Minimize squared error  $\mathbb{E}\left[\hat{x}(n)-x(n)\right]$  using Levinson-Durbin algorithm.

Use  $a_1, \dots, a_p$  as features.

## **LPC**

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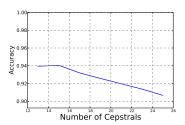
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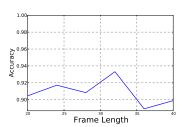
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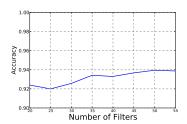
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## **MFCC Params**

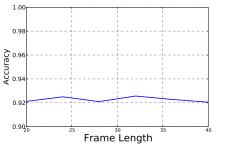


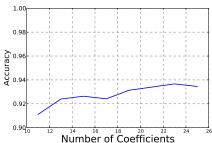




Best parameters in our cases: Number of cepstrals: 15 Number of filters: 55 Frame length: 32ms

## LPC Params





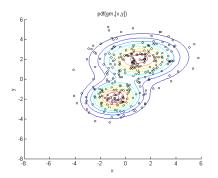
Best parameter in our cases: Number of coefficients: 23

Frame length: 32ms

## **GMM**

**Gaussian Mixture Model** is commonly used to model human's acoustic feature.

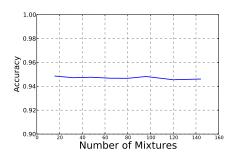
$$p(\theta) = \sum_{i=1}^{K} w_i \mathcal{N}(\mu_i, \Sigma_i)$$



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We use K = 32

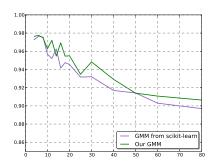
## Optimized GMM

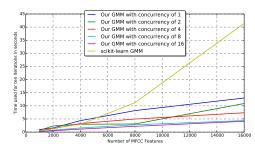
- Basic GMM training: random initialize, estimate parameters with EM.
- Improvment: initialize with a parallel KMeansII.
- Improvment: parallel training implementation in C++.
- Compared to GMM from scikit-learn:

Arthur, David, Sergei, 2007, k-means++: The advantages of careful seeding. Bahmani, et. al. 2012. Scalable K-means++

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#### **UBM**

**Universal Background Model** is a GMM trained on giant datasets. UBM can be used to:

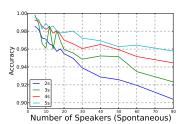
- Describe general acoustic feature of human.
- Reject the decision of GMM.
- Train adaptive GMM.

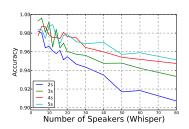
Reynolds, Douglas, et al, 2000, Speaker verification using adapted Gaussian mixture models

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## **GMM** Results







Train duration: 20s
Random selected test utterance: 50
Each value in the graph is an average
of 20 independent experiments.

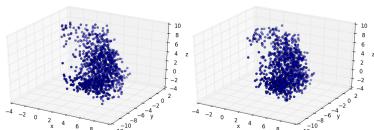
## **CRBM**

- Restricted Boltzmann Machine is a generative stochastic two-layer neural network.
- Continuous RBM extends RBM to real-valued inputs.
- RBM has the ability to reconstruct a layer similar to input layer. The
  difference between the two layers can be a used to measure the fitness
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- Therefore, RBM can be a substituion to GMM.

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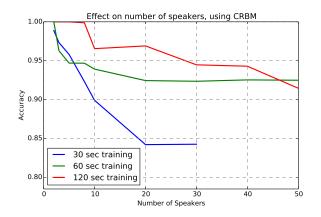
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## **RBM** Results

Results of CRBM, tested with 5 secs of utterance.



## **GUI** Demo

**CRBM** 

#### Conclusion

- We implemented a faster GMM, also with better performance.
- Accuracy is kept even under short training and testing utterance.
- Our system is highly accurate, can almost response in real-time.
- 97% accuracy for  $20\sim30$  speakers, 95% for  $70\sim80$  speakers.

CRBM

## Thanks!