

DESCRIPTION

BHS

$$\begin{aligned} & \text{unsteady} - \text{stocks} - 3D \\ & \mathbf{v}_t - \alpha \nabla^2 \mathbf{v} + \nabla p = \mathbf{f}, \quad \text{in } \Omega_T \\ & \nabla \cdot \mathbf{v} = 0, \quad \text{in } \Omega_T \\ & \mathbf{v}|_{\partial\Omega} = 0, \quad \text{on } \partial\Omega_T \\ & \mathbf{v}|_{t=0} = \mathbf{v}_0, \quad \text{on } \Omega \end{aligned}$$

$$\alpha = 0.025$$

$$\begin{aligned} & \mathbf{v} = [u_1(t, x), u_2(t, x), u_3(t, x)] \\ & x_1 \in [0, 1], x_2 \in [0, 1], x_3 \in [0, 1], t \in [0, 1] \\ & u_1(t, x) = \sin(t) \sin(\pi x_1)^2 (\sin(2\pi x_2) \sin(\pi x_3)^2 - \sin(\pi x_2)^2 \sin(2\pi x_3)) \\ & u_2(t, x) = \sin(t) \sin(\pi x_2)^2 (\sin(2\pi x_3) \sin(\pi x_1)^2 - \sin(\pi x_3)^2 \sin(2\pi x_1)) \\ & u_3(t, x) = \sin(t) \sin(\pi x_3)^2 (\sin(2\pi x_1) \sin(\pi x_2)^2 - \sin(\pi x_1)^2 \sin(2\pi x_2)) \\ & p(t, x) = \sin(t) \sin(\pi x_1) \sin(\pi x_2) \cos(\pi x_3) \end{aligned}$$

REFERENCES

- [1] Jing Yue, Jian Li. The Physics Informed Neural Networks for the unsteady Stokes problems[J]. International Journal for Numerical Methods in Fluids.