

# Camera System Training

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# Agenda

- Basics
- Line Camera
- Image Filters
- Edge Detection
- Stain Detection



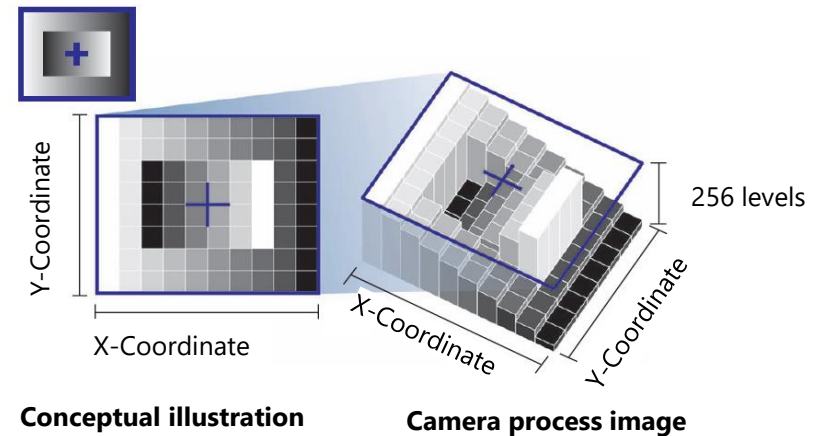
# Basics

- What is a digital image?
- How is a digital image produced?
- Lenses
- Light



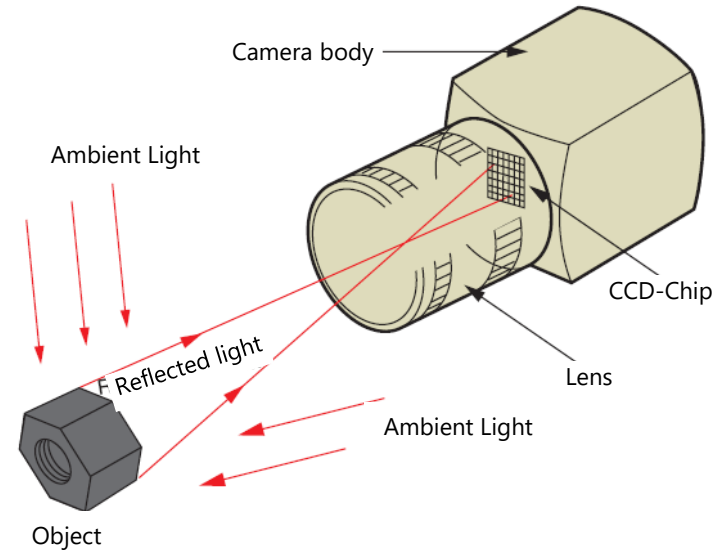
# What is a digital image?

- Defined number of picture elements (Pixels)
- Coordinate system of Pixels (X- and Y-Coordinates)
- Attribute the intensity to a Greyscale Pixel
- Attribute the intensity to Red-, Green- and Blue channel at Colour Pixel



# How is a digital Image produced?

- Incidence of ambient light to the object
- Partly or complete reflection
- Focusing of reflection in direction to camera (Lens)
- Imaging of reflection to CCD
- Illuminate the Pixel
- Saving the "Illumination pattern"



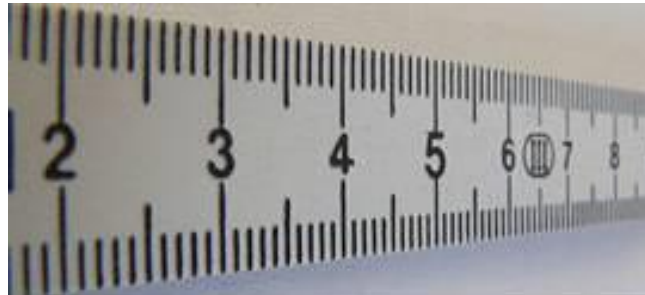
# Lenses: Configuration

- F-number ring controls the incident of light
- Focus distance ring controls the sharpness of the image
- Focal distance defined field of view / working distance ratio
- F-number expresses the diameter of the entrance pupil in terms of the focal distance of the lens



# Lenses: Depth of Focus

- Closed F-number ring:  
high depth of focus

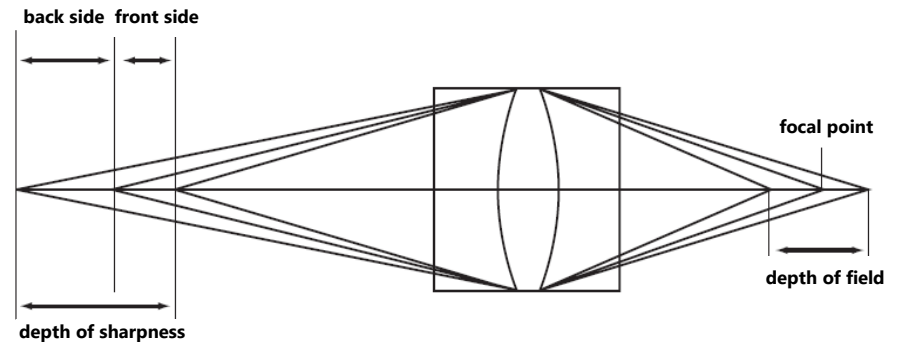


- Open F-number ring: low  
depth of focus



# Lenses: Focusing

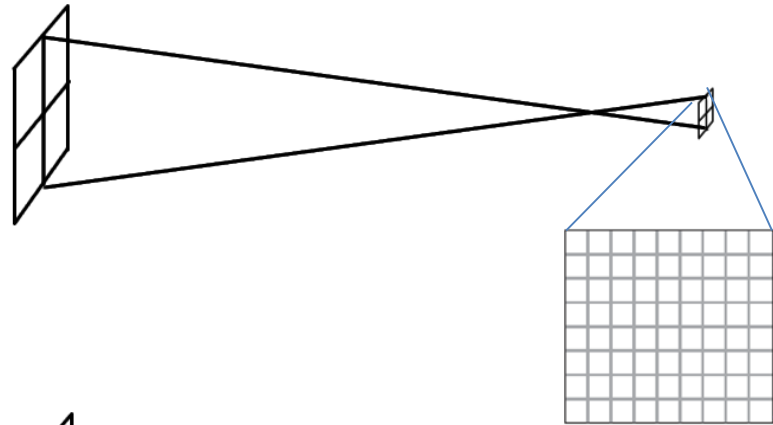
- Working distance from Near to Endless
- Different working distance needs different focus adjustments
- Only objects in the working distance are shown sharp



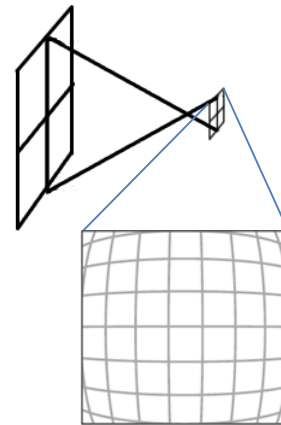


# Lenses: Focal distance

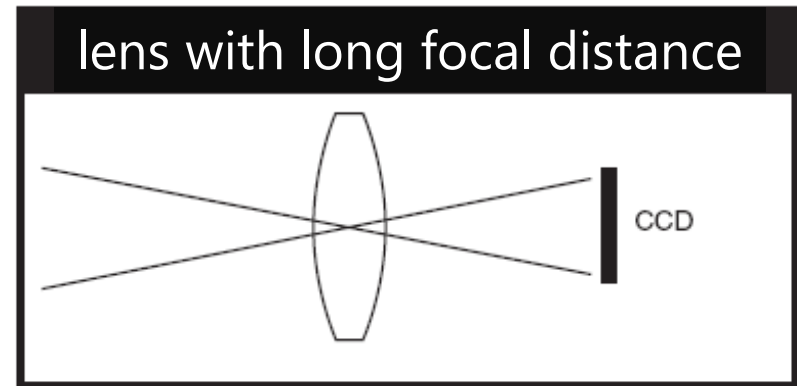
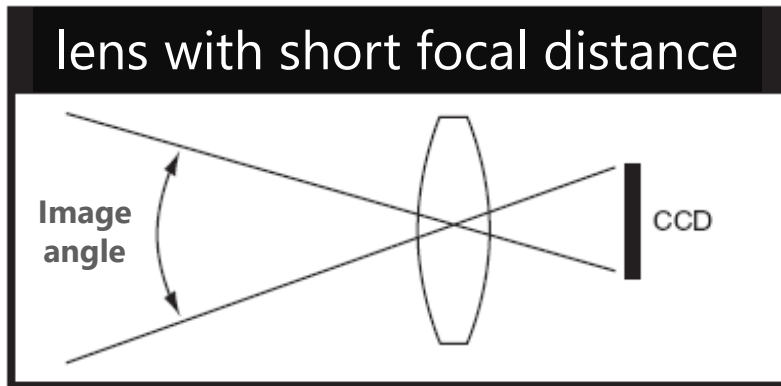
- High focal distance means small image angle and low distortion



- Low focal distance means big image angle and high distortion

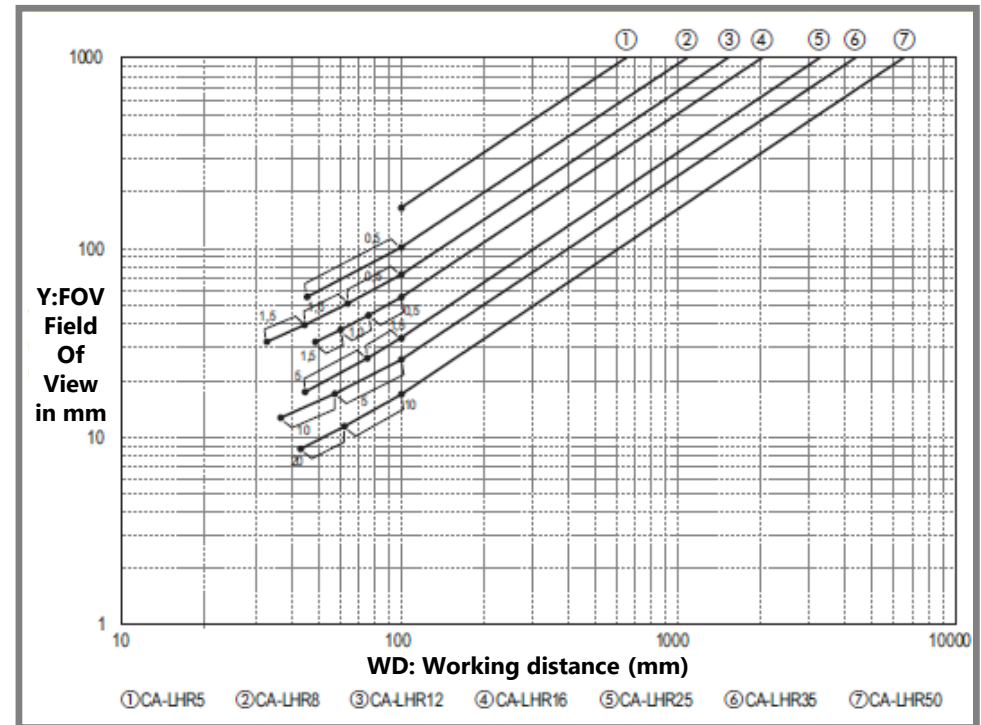


# Lenses: Focal distance



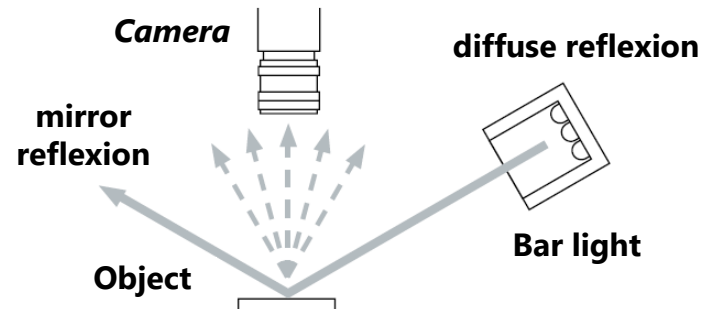
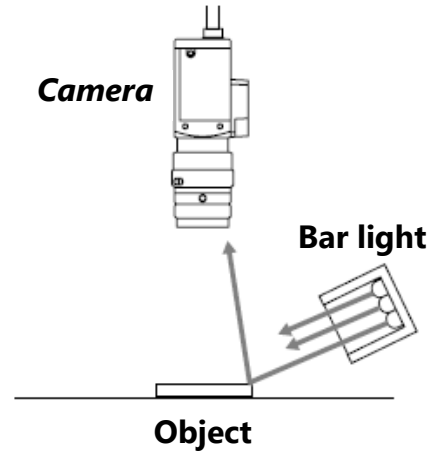
# Lenses: Focal distance

- Logarithmic diagram
- Based on CCD-Size
- Based on Lens type



# Bar Lights

Bar Light  
CA-DB



# Line Cameras

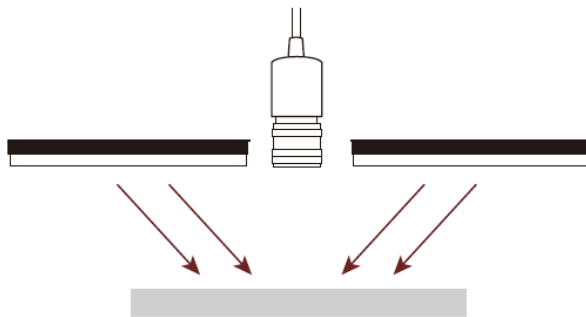
- Introduction
- Image Capture
- Encoder



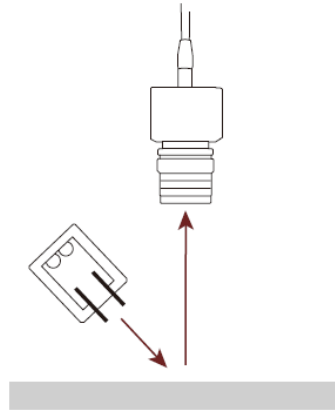
# Line Cameras - Introduction

## Difference between area cameras and line scan cameras: Size and cost reduction

An area camera will capture an entire 2D image area in one operation while the line scan camera will build a 2D image by capturing one line at a time.

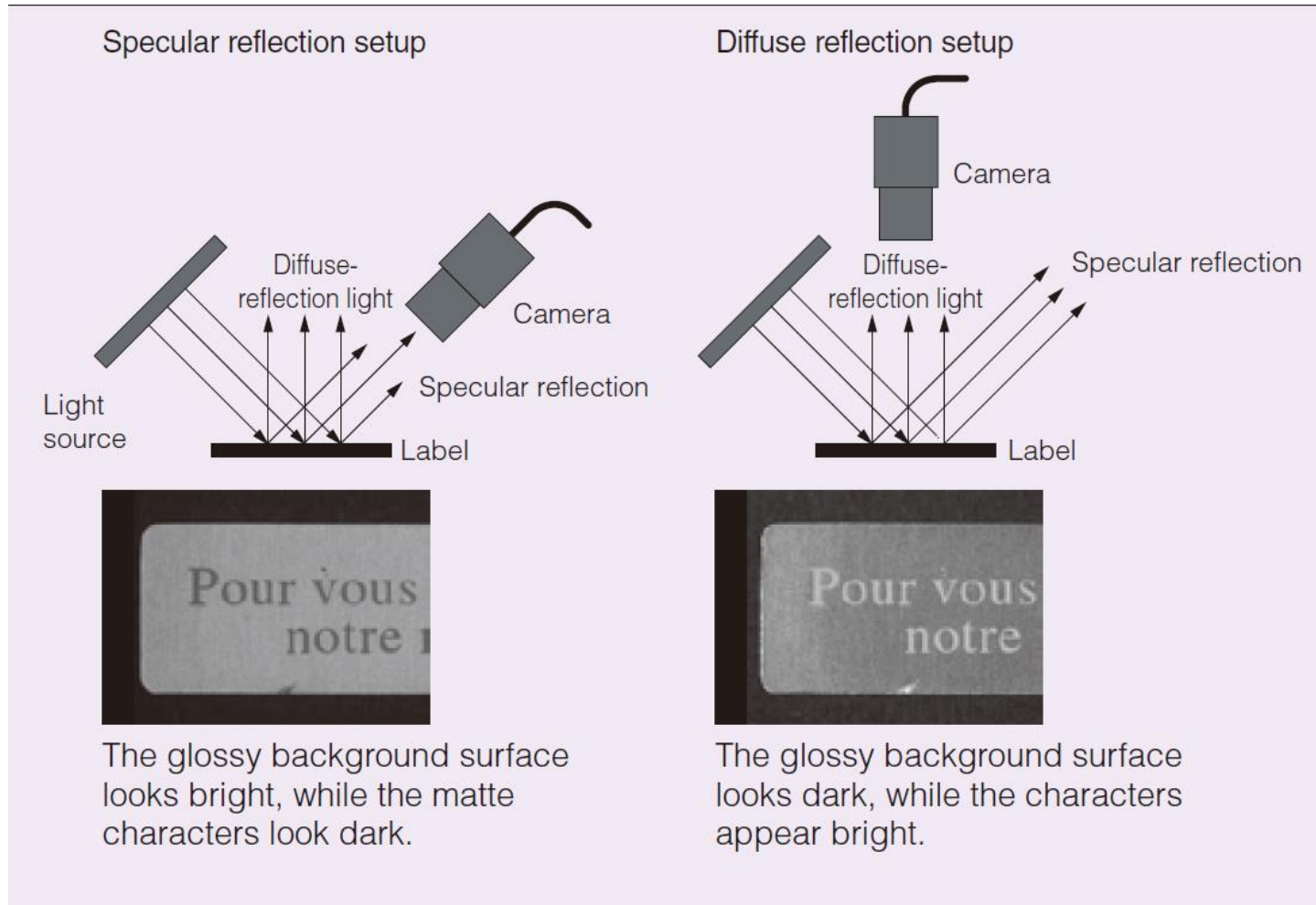


Larger sized lighting requires more costs and greater installation space.



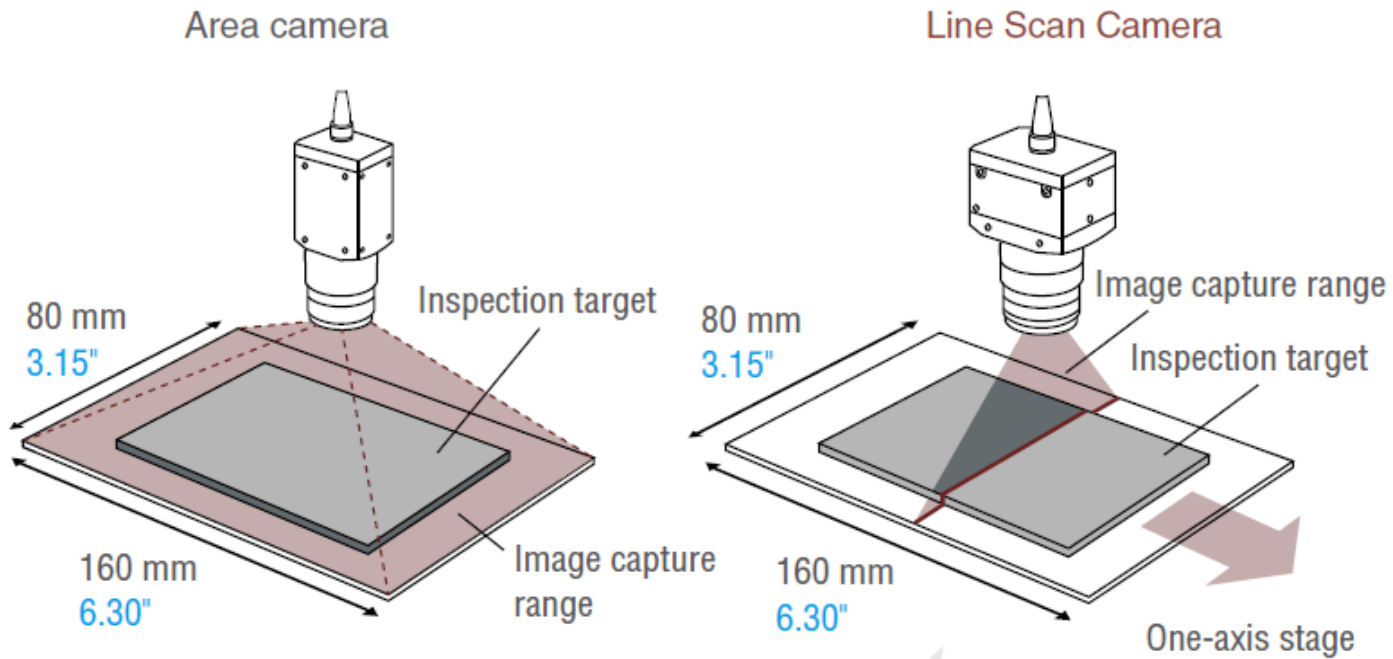
A bar light can be used to perform the inspection, which reduces installation space requirements and cost.

# Line Cameras – Image Capture



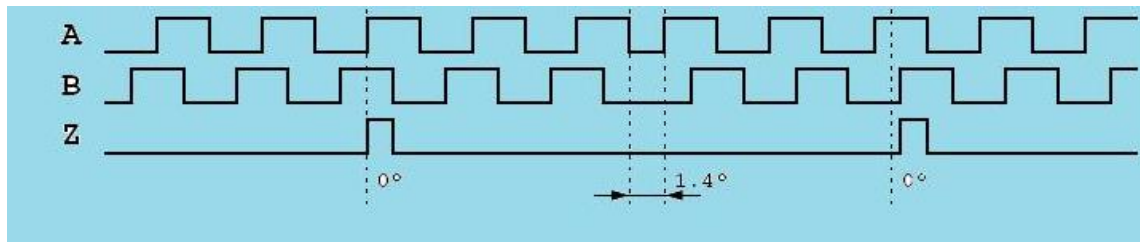
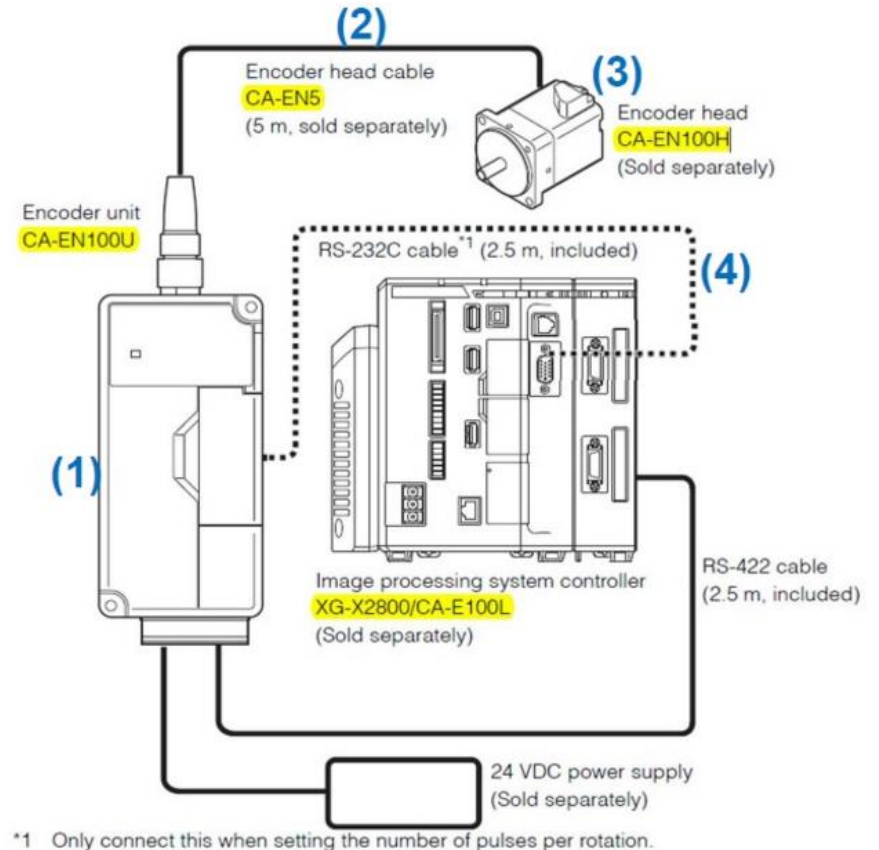
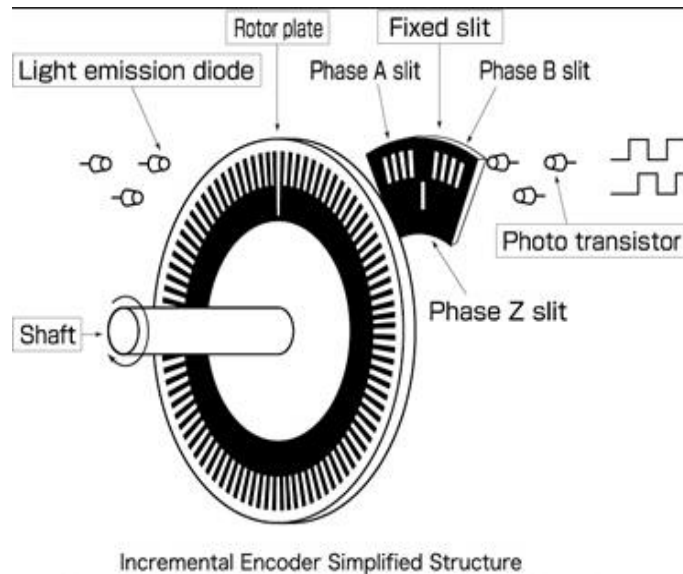
# Line Cameras – Image Capture

## Image capture range

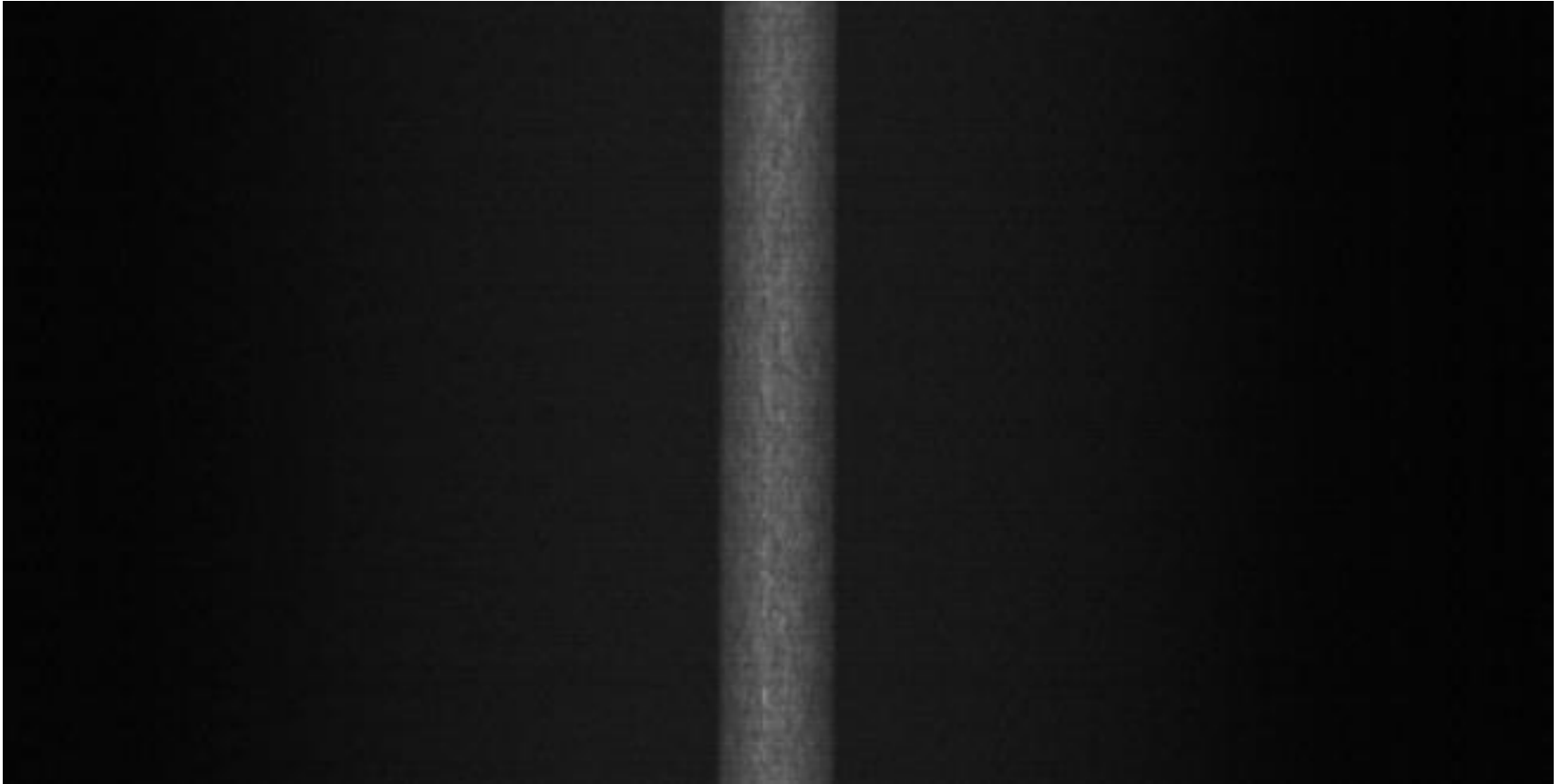




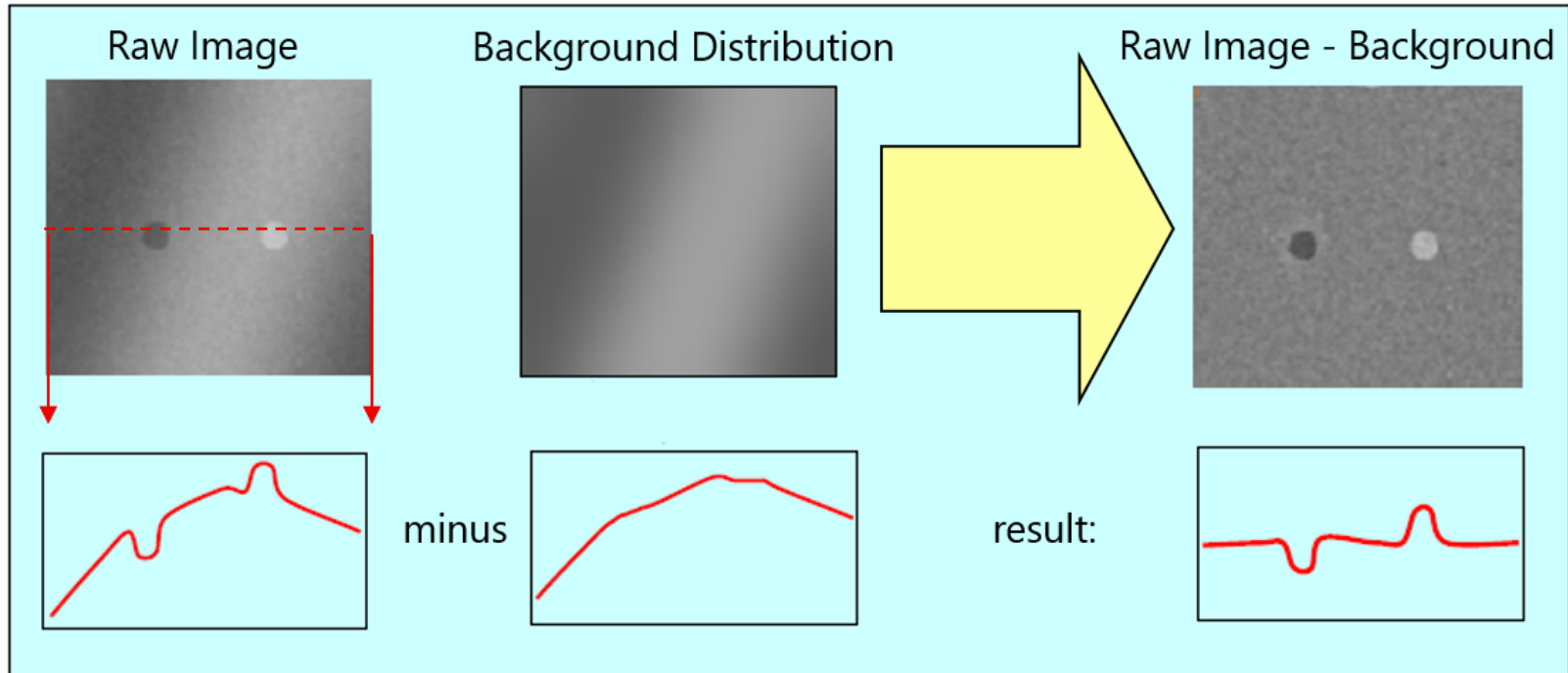
# Encoder



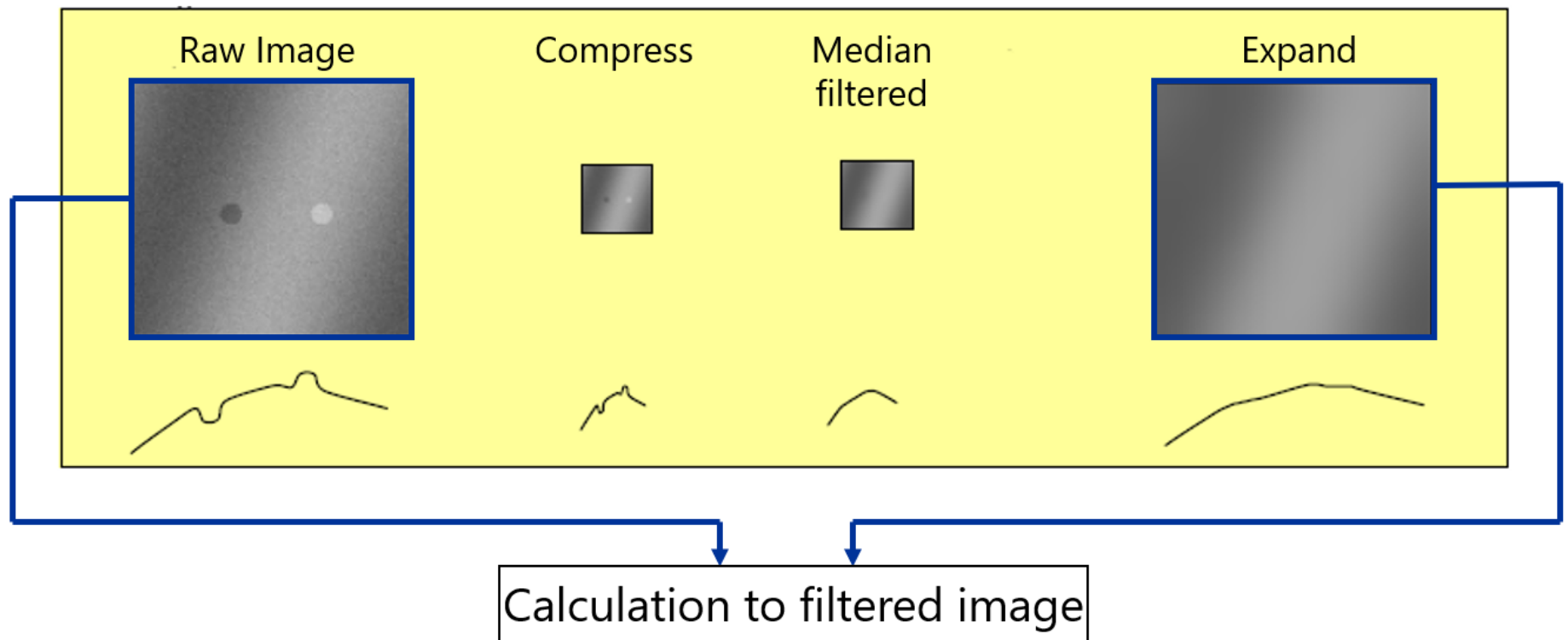
# Image Filters



# Image Filters – Shading Correction

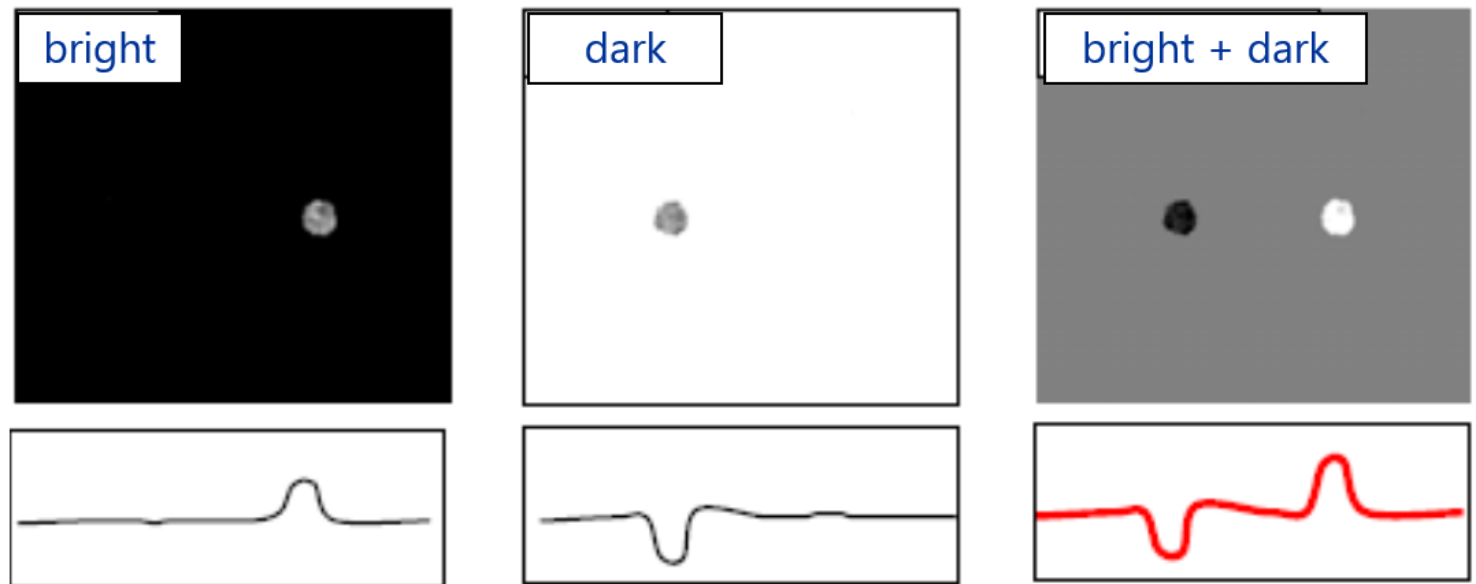


# Image Filters – Shading Correction



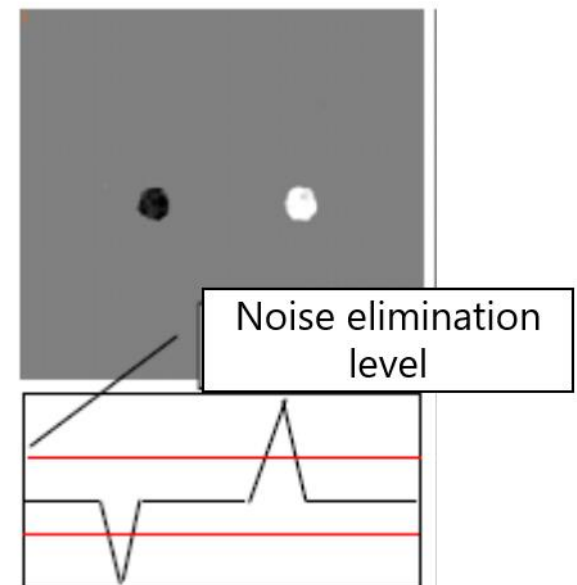
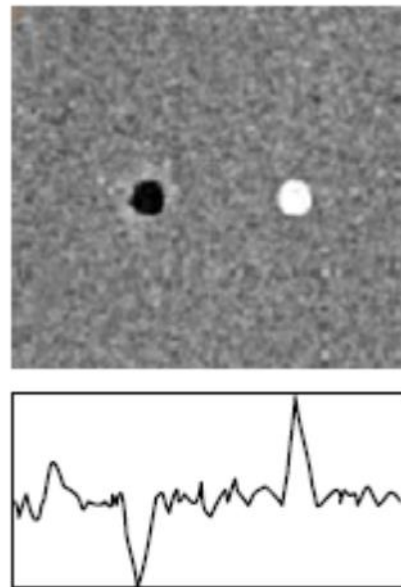
# Image Filters – Shading Correction

- Target orientated extraction (bright or dark)

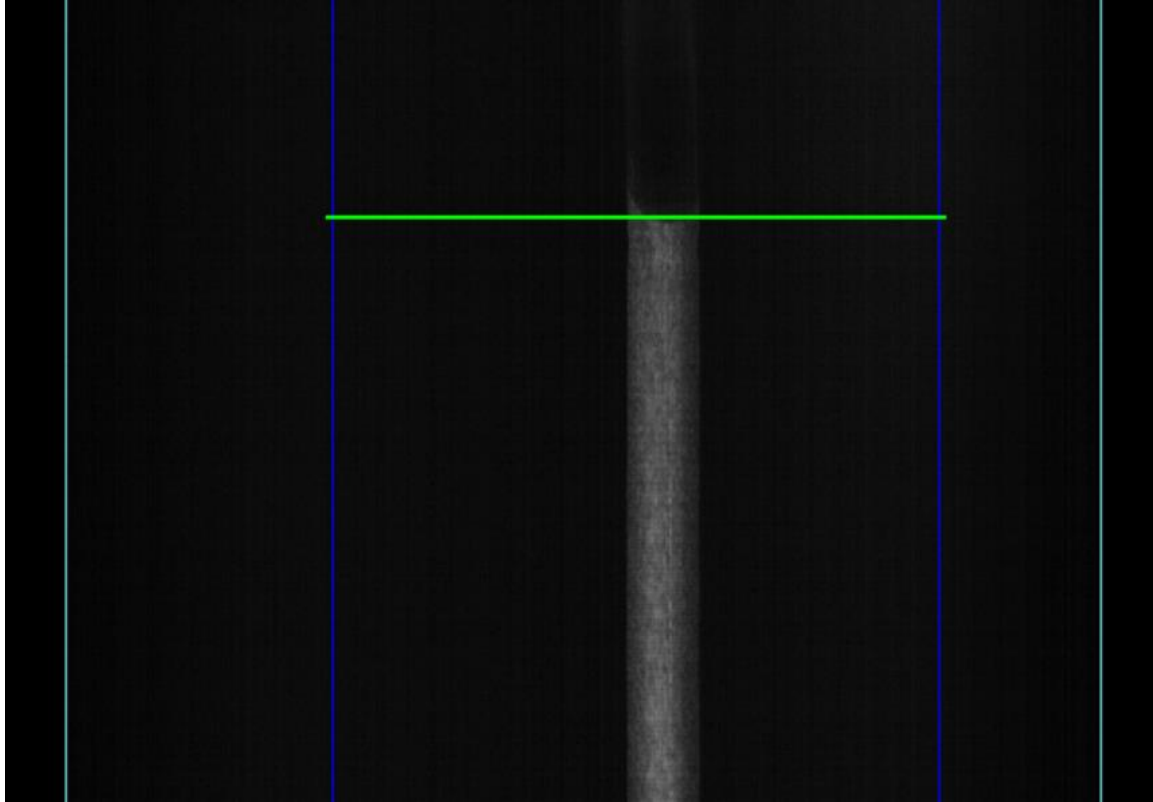


# Image Filters – Shading Correction

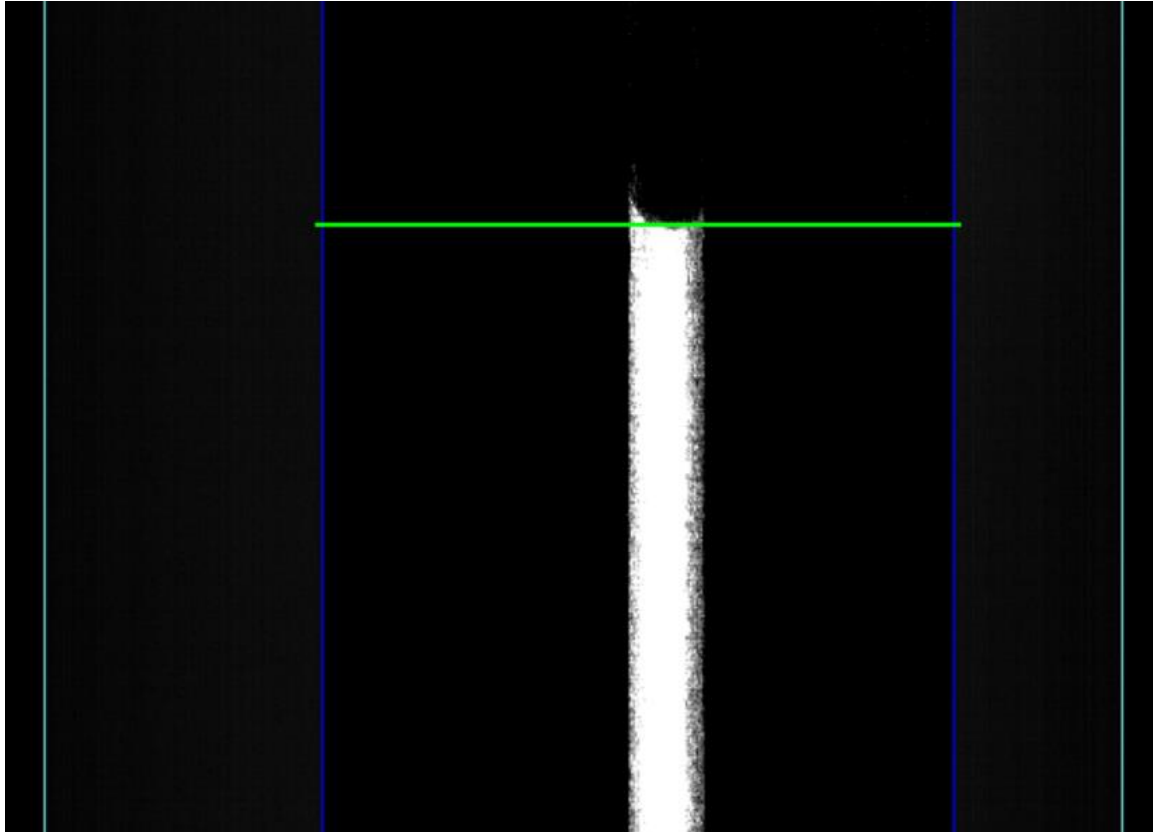
- Noise elimination



# Image Filters – Shading Correction



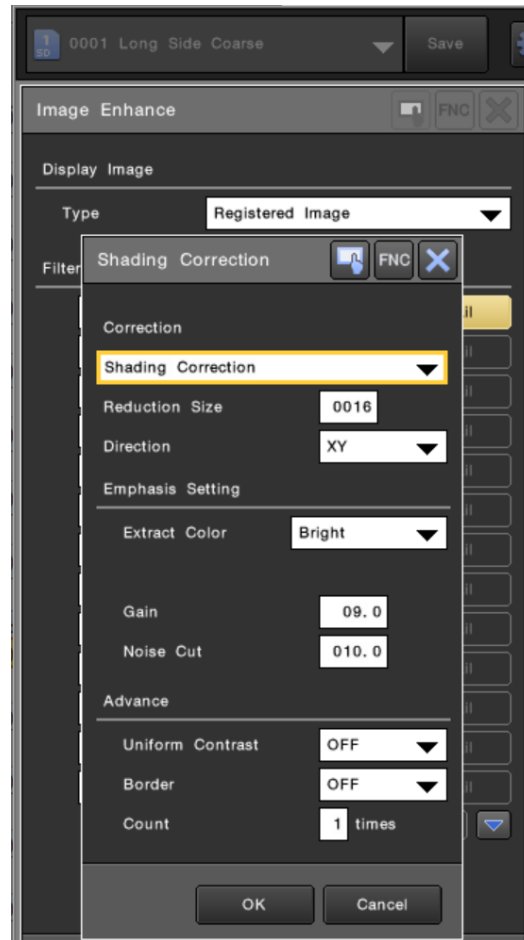
# Image Filters – Shading Correction



Median Correction – Bright – High Gain

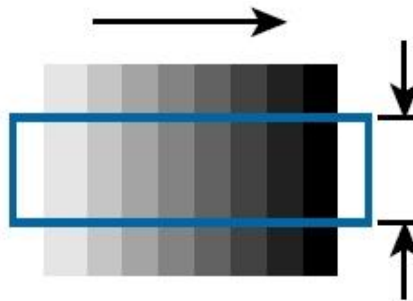


# Image Filters – Shading Correction



# Edge Detection

Direction of  
edge detection



Direction of  
projection

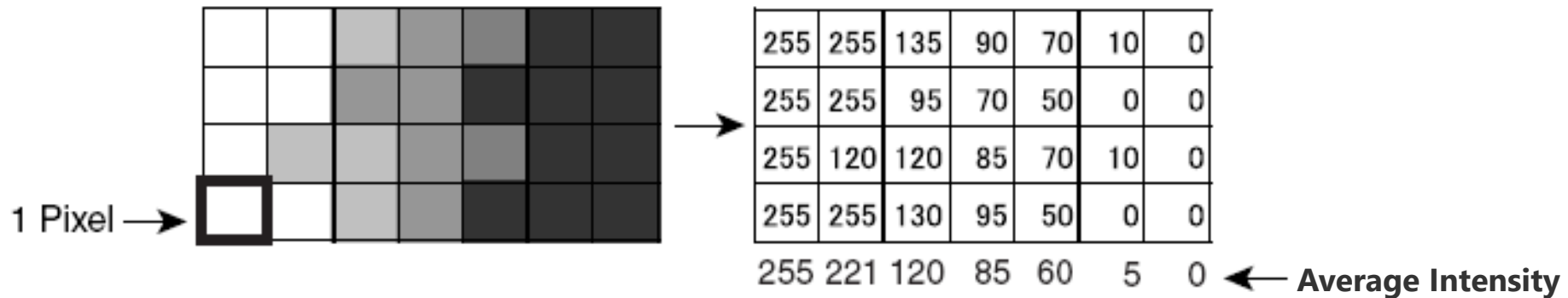
Projection waveform

light (255)



dark (0)

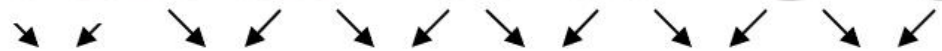
# Edge Detection



# Edge Detection

255	255	135	90	70	10	0
255	255	95	70	50	0	0
255	120	120	85	70	10	0
255	255	130	95	50	0	0

255 221 120 85 60 5 0



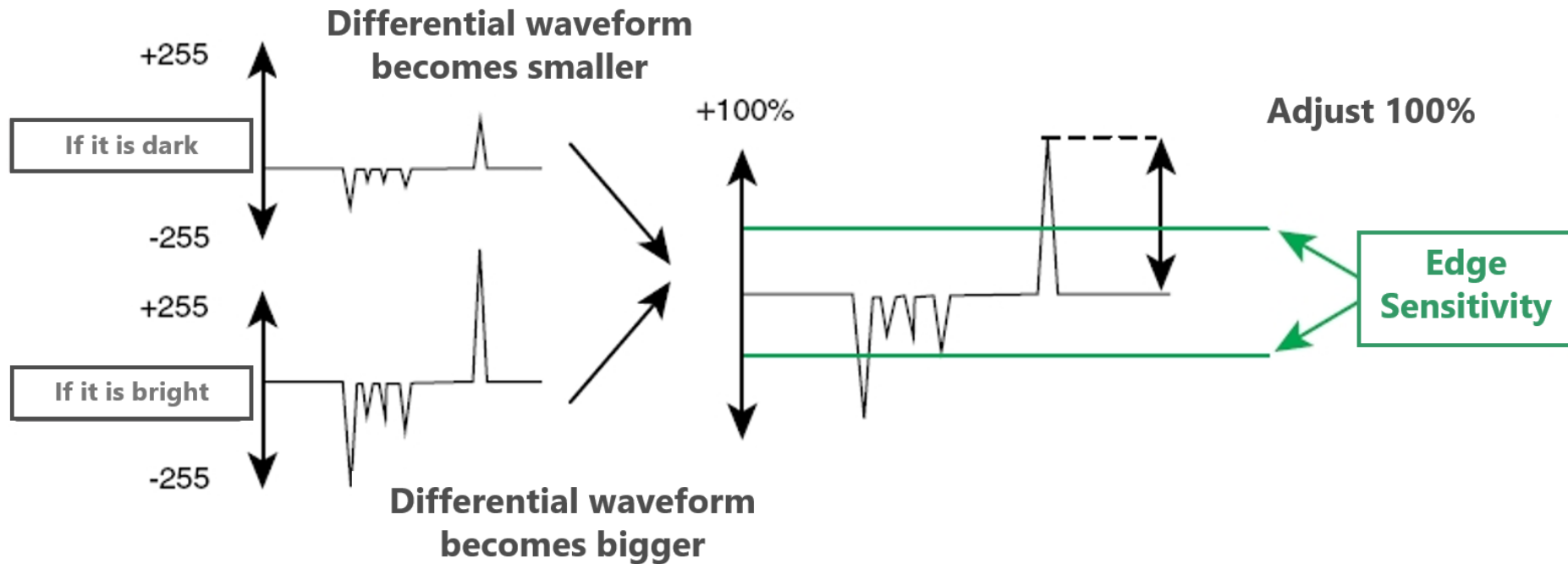
difference:

34 101 35 25 55 5

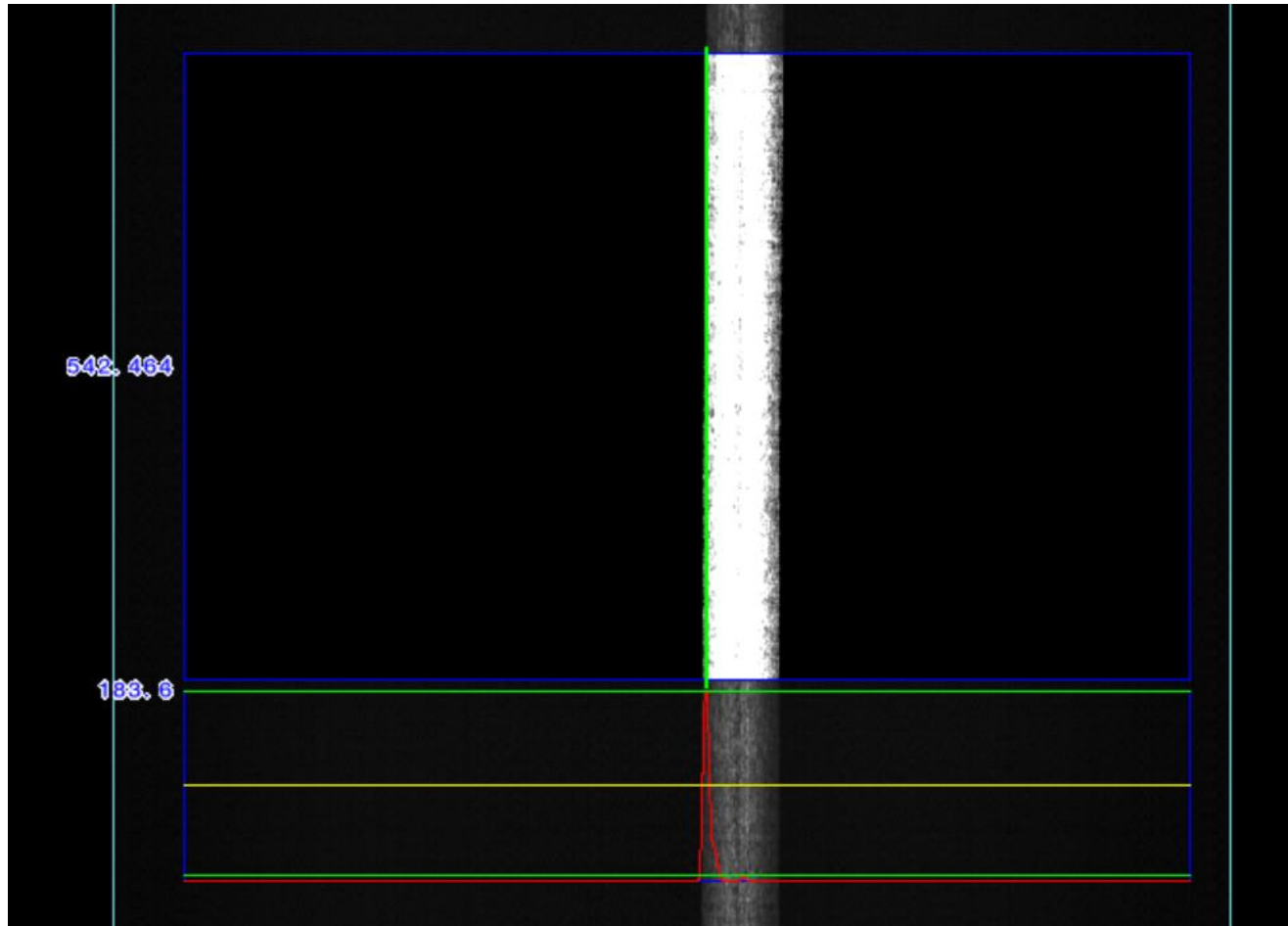
# Edge Detection



# Edge Detection

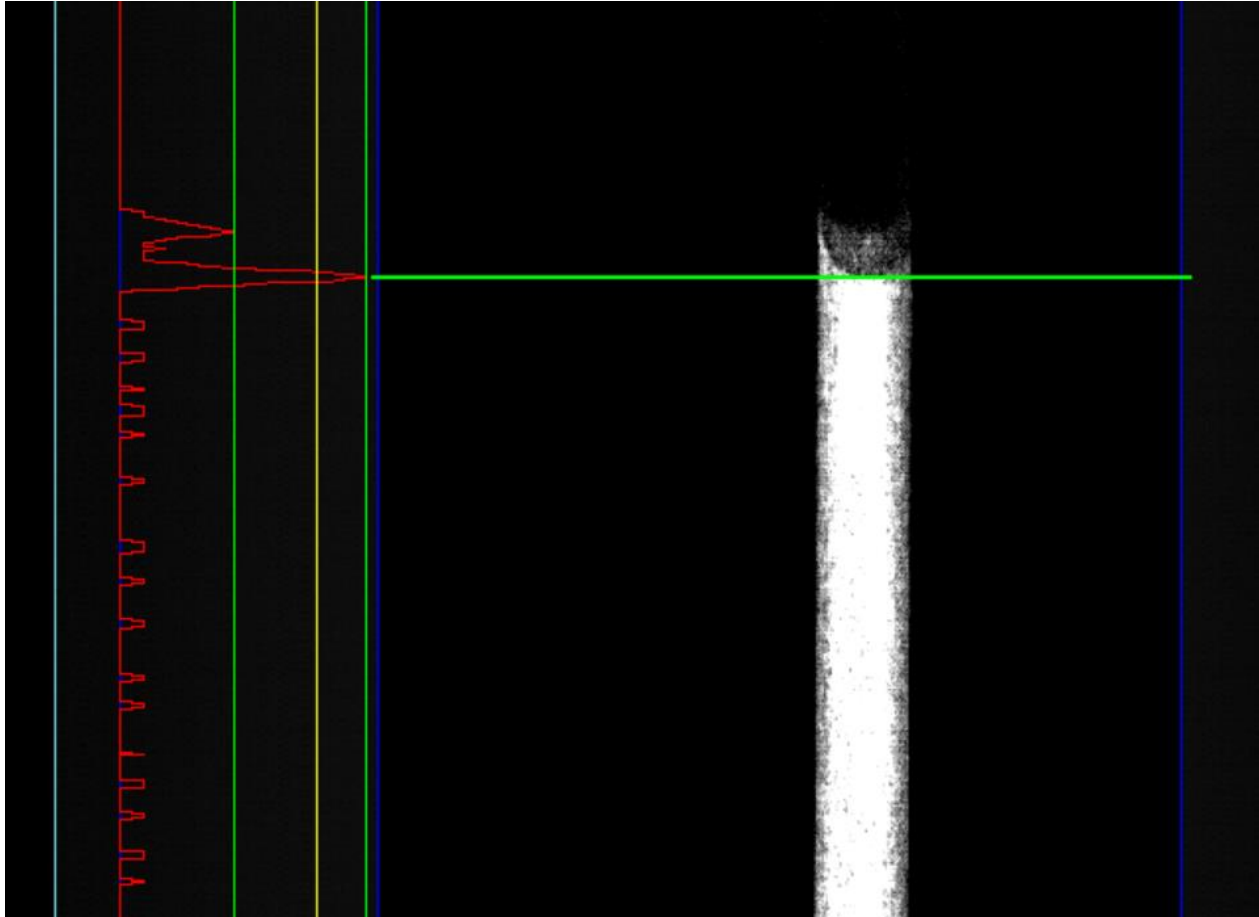


# Edge Detection



Sensitivity 50%

# Edge Detection



Sensitivity 80%



# Edge Detection

Detection Conditions

Display Image

Type: Registered Image

Direction

Scan Direction: ↓

Edge Direction: Dark to Light

Start Angle: 000.000

Edge Strength

Edge Sensitivity(%): 080

Edge Filter Width: 008

Upper Edge Intensity: 255.000

Lower Edge Intensity: 005.000

Conditions

Primary Target: 0000

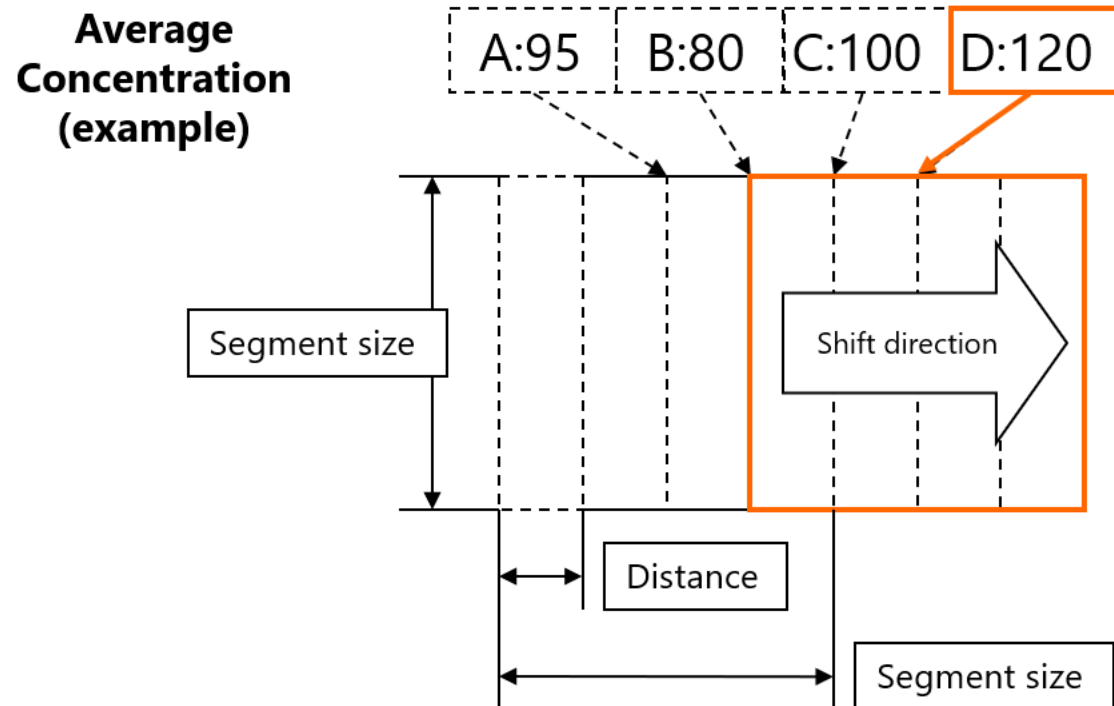
Count: 0001

Angled Edge Detection: OFF

OK Cancel

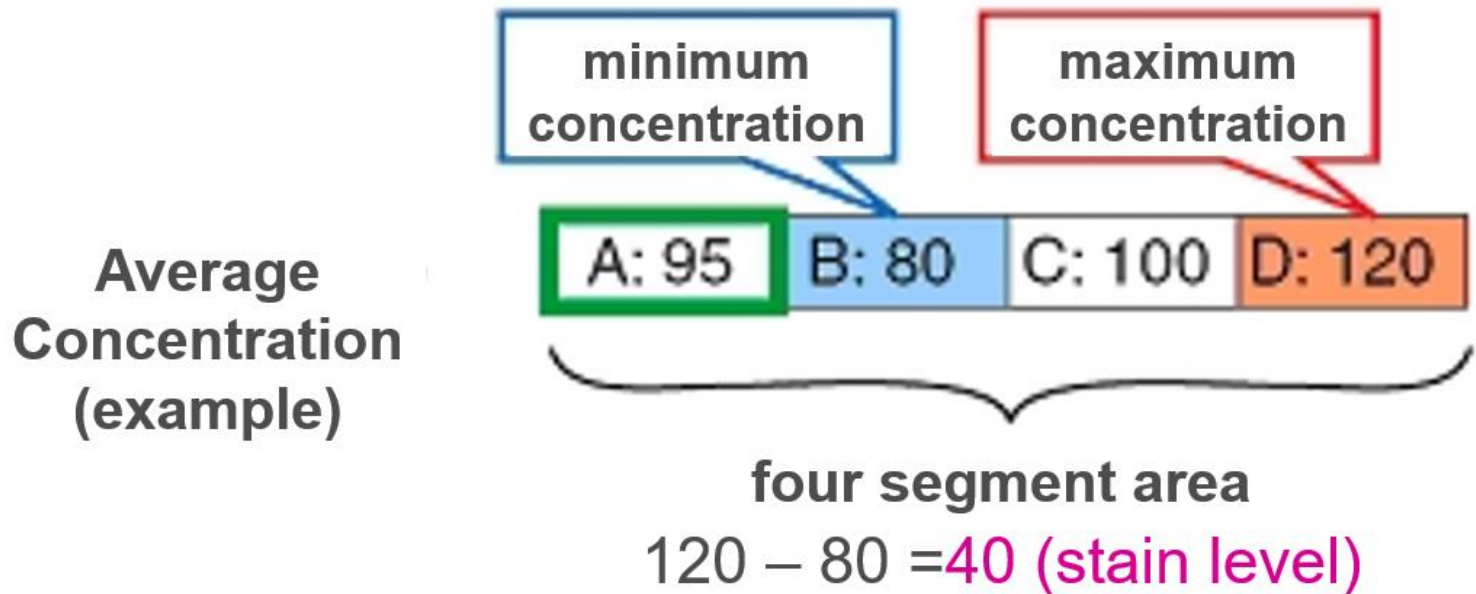
# Stain Detection

Intensity and segment shift:



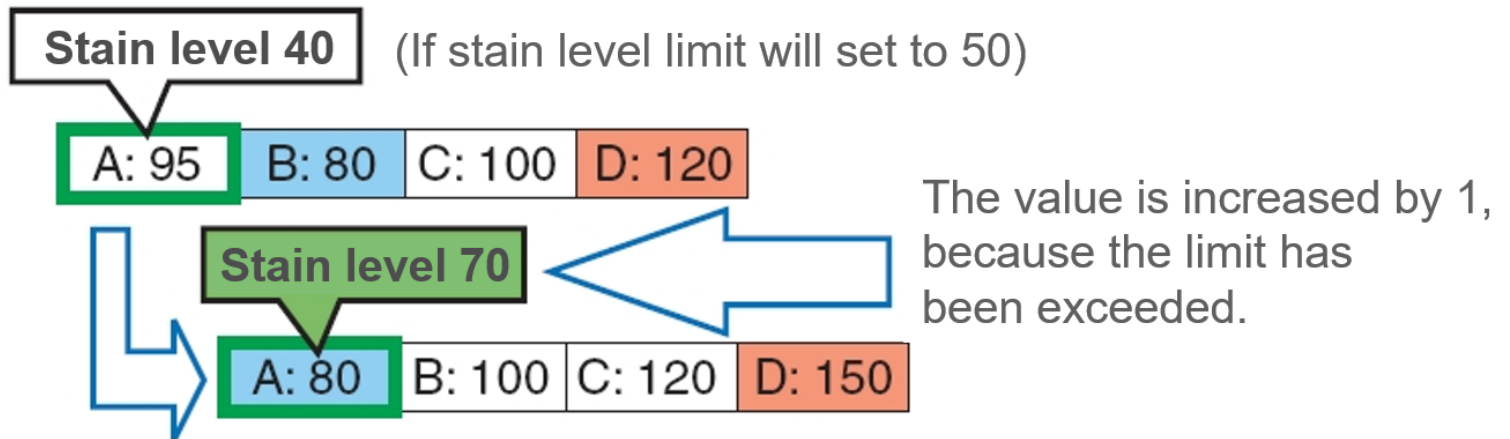
# Stain Detection

Difference maximum:



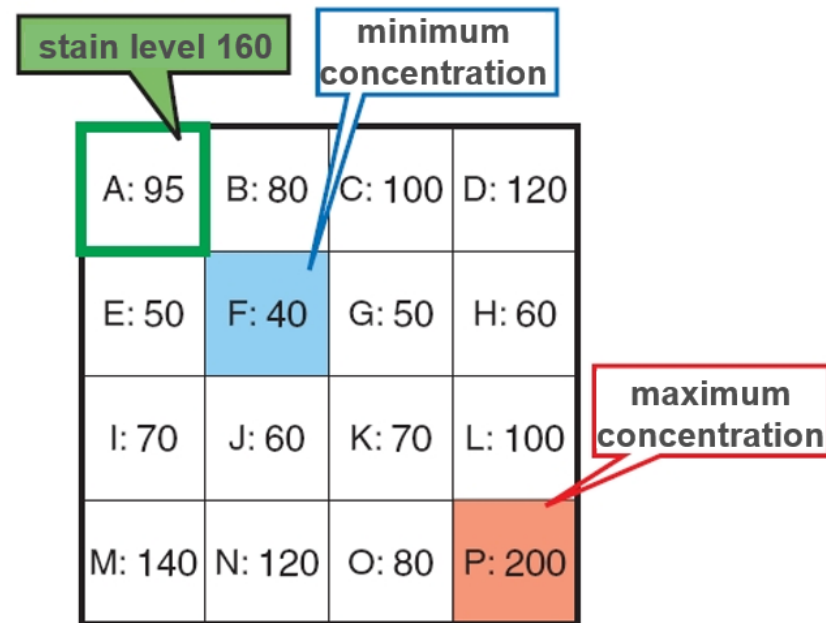
# Stain Detection

Stain level evaluation:



# Stain Detection

XY-direction detection:



4 x 4 = area with 16 segments  
 $200 - 40 = 160$  (stain level 160)

# Stain Detection

Detection Conditions

Display Image

Type: Registered Image

Detection Conditions

Direction: Y

Individual: OFF

High Speed Mode: OFF

Defect Level: 020

X/Y Common

Element Size: 020

Comparison: Auto

Element Shift: 0005

Compare Element Int.: 0001

Gain: 01.0

Ignore Intensity: OFF

Group Setting

Result

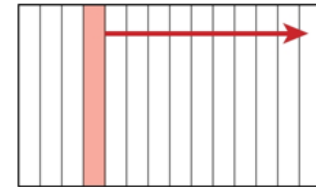
Detected Defect Level	0
Total Area	99999999
Groups	0

OK Cancel

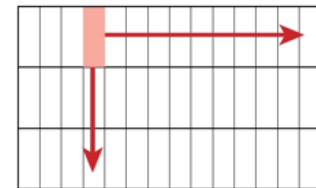
# Stain Detection

Direction detection:

- X-direction



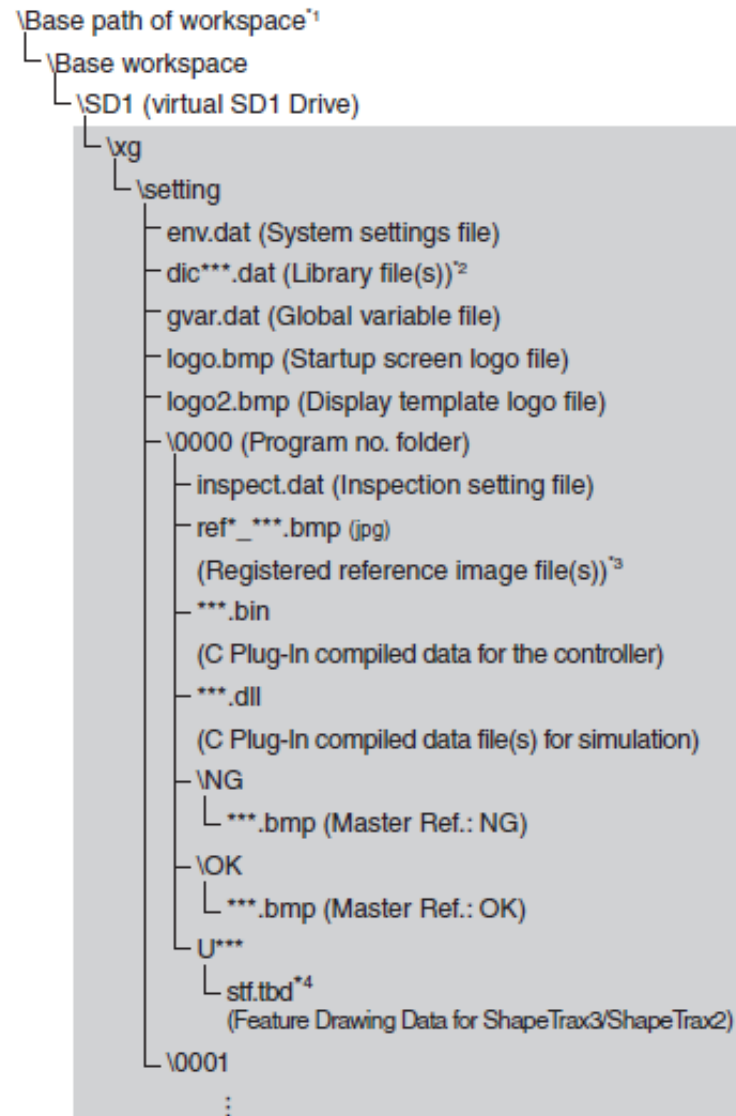
- XY-direction



# Interface

- Connecting to the system
- Setup and Run Modes
- Management data
- Saving/Loading Programs
- Flowchart





Management data in the controller

# Any Questions?



**Thank you for your attention**

