Kerr-Newman geometry in Boyer-Lindquist Coordinates:

x^{μ}
$x^0=t.$
$x^1=r. \ x^2= heta.$
$x^3 = \phi.$
$g_{\mu u}$
$g_{00} = \frac{a^2 + r^2 + q^2 - a^2 \sin(\theta)^2 - 2mr}{\cos(\theta)^2 a^2 + r^2}.$
$g_{01}=0. \ g_{02}=0.$
$2ma\sin(heta)^2r-aq^2\sin(heta)^2$
$g_{10} = 0.$ $\cos(\theta)^2 a^2 + r^2$
$g_{11} = -\frac{\cos(\theta)^2 a^2 + r^2}{a^2 + r^2 + q^2 - 2mr}.$
$g_{12}=0. \ g_{13}=0.$
$g_{20}=0.$
$g_{22} = -\cos(\theta)^2 a^2 - r^2.$
$g_{23}=-\cos(v)u^{2}-v^{2}.$
$2ma\sin(heta)^2r-aa^2\sin(heta)^2$
$g_{30} = \frac{3}{\cos(\theta)^2 a^2 + r^2}.$ $g_{31} = 0.$
$g_{32}=0.$
$g_{33} = \frac{a^4 \sin(\theta)^2 + a^2 q^2 \sin(\theta)^2 - a^2 \sin(\theta)^2 r^2 + a^2 \sin(\theta)^2 r^2 - 2ma^2 \sin(\theta)^2 r}{\cos(\theta)^2 a^2 + r^2}.$
$\sqrt{=\sqrt{-\det(g_{\mu u})}}$
$a^4q^2\sin(\theta)^4 + a^4\sin(\theta)^2 - a^2\sin(\theta)^2r^4 - 2ma^4\sin(\theta)^2r^2 + a^4\sin(\theta)^2r^2 + a^4$
$\sqrt{=\sqrt{-2mr}}$
$g^{\mu u}$
$(a^2a^2-a^2-r^2+a^2r^2-2ma^2r+a^4)(\cos(\theta)^2a^2+r^2)$
$g^{-r} = -\frac{1}{a^2q^2 - a^4\sin(\theta)^2 - 2a^4r^2 + 4m^2a^2\sin(\theta)^2 r^2 + a^2q^4\sin(\theta)^2 + 4ma^4r + a^6\sin(\theta)^2 - 4m^2a^2r^2 - a^2r^4 - 4ma^2q^2\sin(\theta)^2 r - 2a^2q^2r^2 + a^4\sin(\theta)^2 r - 2a^2q^2r^2 + a^2q^2\sin(\theta)^2 r - 2a^2q^2r^2 + a^2q^2r^2 + a^2q^2r$
$g^{01}=0. \ g^{02}=0.$
$(\cos(heta)^2a^2+r^2)(2mar-aq^2)$
$g^{-r} = \frac{1}{a^2q^2 - a^4\sin(\theta)^2 - 2a^4r^2 + 4m^2a^2\sin(\theta)^2 + 4ma^4r + a^6\sin(\theta)^2 - 4m^2a^2r^2 - a^2r^4 - 4ma^2q^2\sin(\theta)^2r - 2a^4q^2 + 4ma^2q^2r - 2ma^4\sin(\theta)^2r + 4ma^2q^2r - 2ma^4\sin(\theta)^2r - 2a^4q^2 + 4ma^2q^2r - 2ma^2r - 2ma$
$g^{10} = 0.$
$g^{11} = -\frac{a^2 + r^2 + q^2 - 2mr}{\cos(\theta)^2 a^2 + r^2}.$
$g^{12}=0.$
$g^{13} = 0. \ g^{20} = 0.$
$g^{21}=0.$
$g^{22} = -\frac{1}{\cos(\theta)^2 a^2 + r^2}.$
$g^{23}=0.$
$g^{30} = \frac{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)}{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)} = \frac{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)}{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)} = \frac{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)}{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)} = \frac{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)}{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)} = \frac{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)}{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)} = \frac{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)}{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)} = \frac{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)}{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)} = \frac{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)}{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)} = \frac{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)}{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)} = \frac{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)}{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)} = \frac{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)}{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)} = \frac{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)}{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)} = \frac{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)}{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)} = \frac{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)}{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)} = \frac{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)}{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)} = \frac{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)}{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)} = \frac{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)}{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)} = \frac{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)}{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)} = \frac{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)}{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)} = \frac{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)}{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)} = \frac{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)}{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)} = \frac{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)}{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)} = \frac{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)}{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)} = \frac{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)}{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)} = \frac{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)}{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)} = \frac{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)}{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)} = \frac{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)}{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)} = \frac{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)}{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)} = \frac{(\cos(\theta)^2 a^2 + r^2)(2mar - aq^2)}{(\cos(\theta)^2 a^2 + r^2)} = (\cos(\theta)^2 a^2 a^2 $
$\frac{g^{30}}{a^{2}q^{2}-a^{4}\sin(\theta)^{2}-2a^{4}r^{2}+4m^{2}a^{2}\sin(\theta)^{2}r^{2}+a^{2}q^{4}\sin(\theta)^{2}+4ma^{4}r+a^{6}\sin(\theta)^{2}-4m^{2}a^{2}r^{2}-a^{2}r^{4}-4ma^{2}q^{2}\sin(\theta)^{2}r-2a^{4}q^{2}+4ma^{2}q^{2}r-2ma^{4}\sin(\theta)^{2}r+4ma^{2}r^{3}+2a^{2}r^{2}-2mr^{3}-a^{2}q^{4}+a^{4}q^{2}\sin(\theta)^{2}-a^{6}-a^{2}\sin(\theta)^{2}r-2a^{4}q^{2}+4ma^{2}q^{2}r-2ma^{4}r-2a^{4}q^{2}+4ma^{2}q^{2}r-2ma^{4}r-2a^{4}q^{2}+4ma^{2}q^{2}r-2ma^{4}r-2a^{4}q^{2}+4ma^{2}q^{2}r-2ma^{4}r-2a^{4}q^{2}+4ma^{2}q^{2}r-2ma^{4}r-2a^{4}q^{2}+4ma^{2}q^{2}r-2ma^{4}r-2a^{4}q^{2}+4ma^{2}q^{2}r-2ma^{4}r-2a^{4}q^{2}+4ma^{2}q^{2}r-2ma^{4}r-2a^{4}q^{2}+4ma^{2}q^{2}r-2ma^{4}r-2a^{4}q^{2}+4ma^{2}q^{2}r-2ma^{4}r-2a^{4}q^{2}+4ma^{2}q^{2}r-2ma^{4}r-2a^{4}q^{2}+4ma^{2}q^{2}r-2ma^{4}r-2a^{4}q^{2}+4ma^{2}q^{2}r-2ma^{4}r-2a^{4}q^{2}+4ma^{2}q^{2}r-2ma^{4}r-2a^{4}q^{2}+4ma^{2}q^{2}r-2ma^{4}r-2a^{4}q^{2}+4ma^{2}q^{2}r-2ma^{4}r-2a^{4}q^{2}+4ma^{4}q^{2}r-2ma^{4}r-2a^{4}q^{2}+4ma^{4}q^{2}r-2ma^{4}r-2a^{4}q^{2}+4ma^{4}q^{2}r-2ma^{4}r-2a^{4}q^{2}+4ma^{4}q^{2}r-2ma^{4}r-2a^{4}q^{2}+4ma^{4}q^{2}r-2ma^{4}r-2a^{4}q^{2}+4ma^{4}q^{2}r-2ma^{4}r-2a^{4}q^{2}+4ma^{4}q^{2}+4ma^{4}q^{2}+4ma^{4}q^{2}+4ma^{4}q^{2}+4ma^{4}q^{2}+4ma$
$g^{32}=0.$
$g^{33} = -\frac{(\cos(\theta)^2 a^2 + r^2)(a^2 + r^2 + q^2 - a^2\sin(\theta)^2 - 2mr)}{(\cos(\theta)^2 a^2 + r^2)(a^2 + r^2)($
$g^{33} = -\frac{1}{a^4q^2\sin(\theta)^4 + a^4\sin(\theta)^2 - a^2\sin(\theta)^2r^4 - 2ma^4\sin(\theta)^2r - a^2\sin(\theta)^2r^2 + a^4a\sin(\theta)^2r - a^2\sin(\theta)^2r^2 + a^2q^2\sin(\theta)^2r - a^2\sin(\theta)^2r^2 + a^2q^2\sin(\theta)^2r^2 + a^2q^2\sin(\theta)^2r - a^2\sin(\theta)^2r^2 + a^2q^2\sin(\theta)^2r - a^2\sin(\theta)^2r - a$
$\Gamma^{\sigma}_{\mu u}$
$\Gamma^0_{00}=0.$
$\Gamma_{01}^{01} = -\cos(\theta)^2 ma^4 - 3ma^2q^2 \sin(\theta)^2r^2 + \cos(\theta)^2 a^4q^2r - \cos(\theta)^2 a^4q^2r - \cos(\theta)^2 a^4r^3 + a^4r + a^6 \sin(\theta)^2r - 2a^2q^2r^3 - 2a^4q^2r + a^4 \sin(\theta)^2r - 2a^2q^2r + a^2 \sin(\theta)^2r - 2a^2q$
$4\cos(\theta)ma^4q^2\sin(\theta)^3r - 4\cos(\theta)ma^4q^2\sin(\theta)^3r - 4\cos(\theta)ma^4\sin(\theta)r^2 - \cos(\theta)a^4q\sin(\theta)r^3 + \cos(\theta)ma^4\sin(\theta)r^2 - \cos(\theta)a^4q\sin(\theta)r^3 + \cos(\theta)ma^4\sin(\theta)r^2 - \cos(\theta)a^4q\sin(\theta)r^3 + \cos(\theta)ma^4\sin(\theta)r^3 + \cos(\theta)ma^4\cos(\theta)ma^4\cos(\theta)ma^4\cos(\theta)ma^4\cos(\theta)ma^4\cos(\theta)ma^4\cos(\theta)ma^4\cos(\theta)ma^4\cos(\theta)ma^4\cos(\theta)ma^4\cos(\theta)ma^4\cos(\theta)ma^4\cos(\theta)ma^4\cos(\theta)ma^4\cos(\theta)ma^4\cos(\theta)ma^$
$(\cos(\theta)^{2}a^{2} + r^{2})(a^{2}q^{2} - a^{4}\sin(\theta)^{2} - 2a^{4}r^{2} + 4ma^{2}q^{2}\sin(\theta)^{2} - 2a^{4}q^{2} + 4ma^{2}q^{2}\sin(\theta)^{2} - 4m^{2}a^{2}r^{2} - 2mr^{3} - a^{2}q^{2} + 4ma^{2}q^{2}\sin(\theta)^{2}r^{2} +$
$\Gamma_{03}^{0} = 0.$ $\Gamma_{03}^{0} = \frac{-\cos(\theta)^{2}ma^{4} - 3ma^{2}q^{2}\sin(\theta)^{2}r^{2} + \cos(\theta)^{2}a^{4}q^{2}r - \cos(\theta)^{2}ma^{4}q^{2} + a^{4}\sin(\theta)^{2}r - a^{2}q^{4}r +$
$(\cos(\theta)^2 a^2 + r^2)(a^2 q^2 - a^4 \sin(\theta)^2 - 2a^4 q^2 + 4ma^2 q^2 \sin(\theta)^2 - 4ma^2 4ma^2 q^2 \cos(\theta)^2 - 4ma^2$
$\Gamma^0_{11}=0.$
$\Gamma_{12}^{0} = 0.$ $ma^{5}\sin(\theta)^{2} - ma^{3}\sin(\theta)^{2}r^{2} + ma\sin(\theta)^{2}r^{2} - aq^{2}\sin(\theta)^{2}r + a^{3}q^{2}\sin(\theta)^{2}r - ma^{3}\sin(\theta)^{2}$
$\Gamma_{13}^{*} = -\frac{2a^{2} - a^{4} \sin(\theta)^{2} - 2a^{4}r^{2} + 4m^{2}a^{2} \sin(\theta)^{2} + 4ma^{4}r + a^{6} \sin(\theta)^{2} + 4ma^{4}r + a^{6} \sin(\theta)^{2} + 4ma^{2}a^{2}r^{2} - 2ma^{4} + a^{4}a^{2} \sin(\theta)^{2}r + a^{2}a^{4} \sin(\theta)^{2}r + a^{2}a^{2} \sin(\theta)^$
$\Gamma_{20}^{0} = -\frac{4\cos(\theta)ma^{4}q^{2}\sin(\theta)^{2} + 4ma^{2}q^{2}\sin(\theta)^{2} + $
$\Gamma^0_{21}=0.$
$\Gamma^0_{22}=0.$
$\Gamma^0_{23}=0. \ \Gamma^0_{30}=0.$
$ma^{5}\sin(\theta)^{2}-ma^{3}\sin(\theta)^{2}r^{2}+ma\sin(\theta)^{2}r^{2}-aa^{2}\sin(\theta)^{2}r+a^{3}a^{2}\sin(\theta)^{2}r-ma^{3}\sin(\theta)^{2}$
$\Gamma_{31}^{0} = -\frac{ma \sin(\theta)}{a^{2}q^{2} - a^{4}\sin(\theta)^{2} - 2a^{4}r^{2} + 4m^{2}a^{2}\sin(\theta)^{2}r^{2} + a^{2}q^{4}\sin(\theta)^{2} + 4ma^{4}r + a^{6}\sin(\theta)^{2} - 4m^{2}a^{2}r^{2} - a^{2}r^{4} - 4ma^{2}q^{2}\sin(\theta)^{2}r - 2a^{4}q^{2} + 4ma^{2}q^{2}r - 2ma^{4}\sin(\theta)^{2}r + 4ma^{2}r^{3} + 2a^{2}r^{2} - 2mr^{3} - a^{2}q^{4} + a^{4}q^{2}\sin(\theta)^{2} - a^{6} - a^{2}\sin(\theta)^{2}r^{2} + r^{4} + q^{2}r^{2} - 2ma^{2}r + a^{4}\sin(\theta)^{2}r - 2a^{4}q^{2} + 4ma^{2}q^{2}r - 2ma^{4}\sin(\theta)^{2}r - 2a^{4}q^{2} + 4ma^{2}q^{2}r - 2ma^{4}r + a^{4}q^{2}\sin(\theta)^{2}r - 2a^{4}q^{2}r - 2ma^{4}r + a^{4}q^{2}r - 2ma^{4}r + a^{4}q^$
$\Gamma^0_{32}=0. \ \Gamma^0_{33}=0.$
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(mr^2 - q^2r + \cos(\theta)^2a^2r + a^2\sin(\theta)^2r - a^2r - \cos(\theta)^2ma^2)(a^2 + r^2 + q^2 - 2mr)
              \Gamma_{01}^1 = 0.
              \Gamma_{02}^1 = 0.
                                                                  (ma\sin(\theta)^{2}r^{2} - aq^{2}\sin(\theta)^{2}r - \cos(\theta)^{2}ma^{3}\sin(\theta)^{2})(a^{2} + r^{2} + q^{2} - 2mr)
                                                                                                                                                                                                                     (\cos(\theta)^2 a^2 + r^2)^3
              \Gamma^{1}_{10} = 0.
                                                               mr^2 - q^2r + \cos(\theta)^2a^2r - a^2r - \cos(\theta)^2ma^2
                                                                                 (\cos(\theta)^2 a^2 + r^2)(a^2 + r^2 + q^2 - 2mr)
           \Gamma_{12}^{1} = -\frac{\cos(\theta)a^{2}\sin(\theta)}{\cos(\theta)^{2}a^{2} + r^{2}}.
              \Gamma^1_{13} = 0.
              \Gamma^1_{20} = 0.
              \Gamma_{21}^{1} = -\frac{\cos(\theta)a^{2}\sin(\theta)}{\cos(\theta)^{2}a^{2} + r^{2}}
     \Gamma^{1}_{22} = -\frac{(a^2 + r^2 + q^2 - 2mr)r}{r^2}
                                                                                  \cos(\theta)^2 a^2 + r^2
              \Gamma^1_{23} = 0.
                                                                  (ma\sin(\theta)^{2}r^{2} - aq^{2}\sin(\theta)^{2}r - \cos(\theta)^{2}ma^{3}\sin(\theta)^{2})(a^{2} + r^{2} + q^{2} - 2mr)
                                                                                                                                                                                                                       (\cos(\theta)^2 a^2 + r^2)^3
           \Gamma^1_{31} = 0.
              \Gamma_{32}^1 = 0.
                                                                  (\cos(\theta)^2 a^2 \sin(\theta)^2 r - \cos(\theta)^2 a^4 \sin(\theta)^2 r - ma^2 \sin(\theta)^2 r^2 + \cos(\theta)^2 ma^4 \sin(\theta)^2 - a^2 \sin(\theta)^2 r + a^2 q^2 \sin(\theta)^2 r + a^4 \sin(\theta)^2 r)(a^2 + r^2 + q^2 - 2mr)
                                                                  2\cos(\theta)ma^2\sin(\theta)r + \cos(\theta)^3a^4\sin(\theta) + \cos(\theta)a^4\sin(\theta)^3 - \cos(\theta)a^2q^2\sin(\theta) - \cos(\theta)a^4\sin(\theta)
           \Gamma_{01}^2 = 0.
           \Gamma_{02}^2 = 0.
                                                       2\cos(\theta)^3ma^3\sin(\theta)r - \cos(\theta)a^3q^2\sin(\theta)^3 + 2\cos(\theta)ma^3\sin(\theta)^3r - \cos(\theta)^3a^3q^2\sin(\theta) - \cos(\theta)aq^2\sin(\theta)r^2 + 2\cos(\theta)ma\sin(\theta)r^3
                                                                                                                                                                                                                                                                                                                                                                          (\cos(\theta)^2 a^2 + r^2)^3
              \Gamma_{10}^2 = 0.
                                                                                                                     \cos(\theta)a^2\sin(\theta)
        \Gamma_{11}^2 = \frac{\cos(\theta)^2 - \cos(\theta)}{(\cos(\theta)^2 - a^2 + r^2)(a^2 + r^2 + q^2 - 2mr)}.
\Gamma_{12}^2 = \frac{1}{\cos(\theta)^2 a^2 + r^2}.
           \Gamma_{13}^2 = 0.
           \Gamma_{20}^2 = 0.
\Gamma_{21}^2 = \frac{r}{\cos(\theta)^2 a^2 + r^2}.
                                                          \cos(\theta)a^2\sin(\theta)
                                                        -\frac{\cos(\theta)^2a^2+r^2}{\cos(\theta)^2a^2+r^2}
              \Gamma_{23}^2 = 0.
                                                    2\cos(\theta)^3ma^3\sin(\theta)r - \cos(\theta)a^3q^2\sin(\theta)^3 + 2\cos(\theta)ma^3\sin(\theta)^3r - \cos(\theta)^3a^3q^2\sin(\theta) - \cos(\theta)aq^2\sin(\theta)r^2 + 2\cos(\theta)ma\sin(\theta)r^3
           \Gamma_{31}^2 = 0.
              \Gamma_{32}^2 = 0.
                                                    \cos(\theta)a^2q\sin(\theta)r^2 - \cos(\theta)a^2\sin(\theta)r^2 - \cos(\theta)a^4\sin(\theta)r^2 - \cos(\theta)a^4\sin(\theta)r^2 - \cos(\theta)a^4\sin(\theta)r^2 + \cos(\theta)a^4\sin(\theta)r^2 - \cos(\theta
              \Gamma_{00}^3 = 0.
           \Gamma_{01}^{3} = -\frac{aq^{2}r - mar^{2} + ma^{3} - ma^{3}\sin(\theta)^{2}}{a^{2}q^{2} - a^{4}\sin(\theta)^{2} - 2a^{4}r^{2} + 4m^{2}a^{2}\sin(\theta)^{2}r^{2} + a^{2}q^{4}\sin(\theta)^{2} + 4ma^{4}r + a^{6}\sin(\theta)^{2} - 4m^{2}a^{2}r^{2} - a^{2}r^{4} - 4ma^{2}q^{2}r - 2ma^{4}\sin(\theta)^{2}r + 4ma^{2}r^{3} + 2a^{2}r^{2} - 2mr^{3} - a^{2}q^{4} + a^{4}q^{2}\sin(\theta)^{2} - a^{6} - a^{2}\sin(\theta)^{2}r^{2} + r^{4} + q^{2}r^{2} - 2ma^{2}r + a^{4}\sin(\theta)^{2}r^{2} + a^{4}q^{2}\sin(\theta)^{2}r^{2} + a^{4}
           \Gamma_{02}^{3} = -\frac{4\cos(\theta)maq^{2}r - \cos(\theta)aq^{2}r^{2} + 2\cos(\theta)ma^{3}r - 4\cos(\theta)m^{2}ar^{2} - \cos(\theta)aq^{4} - \cos(\theta)aq^{4}
           \Gamma_{03}^3 = 0.
          \Gamma_{10}^{3} = -\frac{a^{2}q^{2} - a^{4}\sin(\theta)^{2} - 2a^{4}r^{2} + 4m^{2}a^{2}\sin(\theta)^{2}r^{2} + a^{2}q^{4}\sin(\theta)^{2} + 4ma^{4}r + a^{6}\sin(\theta)^{2} - 4m^{2}a^{2}r^{2} - a^{2}r^{4} - 4ma^{2}q^{2}\sin(\theta)^{2}r - 2a^{2}q^{2}r^{2} + a^{4}\sin(\theta)^{2}r - 2a^{2}q^{2}r^{2} + a^{2}q^{2}r^{2} +
              \Gamma_{11}^3 = 0.
           \Gamma_{12}^3 = 0.
                                                    3ma^2q^2\sin(\theta)^2r^2 - \cos(\theta)^2a^4q^2r + \cos(\theta)^2a^4q^2r + \cos(\theta)^2a^4q^2r + \cos(\theta)^2a^4q^2r + \cos(\theta)^2a^4r^3 - a^4r - a^6\sin(\theta)^2r + a^2q^4r - \cos(\theta)^2a^4r^3 - a^4r - a^6\sin(\theta)^2r + a^2q^2r^3 - \cos(\theta)^2a^4r^3 - a^4r - a^6\sin(\theta)^2r + a^2q^2r^3 - \cos(\theta)^2a^4r^3 - a^4r - a^6\sin(\theta)^2r - a^2q^2r^3 + a^4q^2r + \cos(\theta)^2a^4r^3 - a^4r - a^6\sin(\theta)^2r - a^2q^2r^3 - \cos(\theta)^2a^4r^3 - a^4r - a^4r^3 - a^4r - a^4r^3 - a^4r - a^4r^3 -
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   (\cos(\theta)^2a^2 + r^2)(a^2q^2 - a^4\sin(\theta)^2 - 2a^4r^2 + 4m^2a^2\sin(\theta)^2 + a^2q^4\sin(\theta)^2 + 4ma^4r + a^6\sin(\theta)^2 - 4m^2a^2r^2 - a^2r^4 - 4ma^2q^2\sin(\theta)^2r - 2a^2q^2r^2 + a^4\sin(\theta)^2r - 2a^2q^2r^2 + a^2q^2\sin(\theta)^2r - a^2q^2r^2 + a^2q^2r^2 
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   4\cos(\theta)maq^{2}r - \cos(\theta)aq^{2}r^{2} + 2\cos(\theta)mar^{3} + 2\cos(\theta)ma^{3}r - 4\cos(\theta)m^{2}ar^{2} - \cos(\theta)aq^{4} - \cos(\theta)a^{3}q^{2}
          \Gamma_{20}^{3} = -\frac{1}{(a^{2}q^{2} - a^{4}\sin(\theta)^{2} - 2a^{4}r^{2} + 4m^{2}a^{2}\sin(\theta)^{2}r^{2} + a^{2}q^{4}\sin(\theta)^{2} + 4ma^{4}r + a^{6}\sin(\theta)^{2} - 4m^{2}a^{2}r^{2} - a^{2}r^{4} - 4ma^{2}q^{2}\sin(\theta)^{2}r - 2a^{2}q^{2}r^{2} + a^{4}\sin(\theta)^{2}r - 2a^{2}q^{2}r^{2} - a^{2}r^{2} - a^{2}r^{
           \Gamma_{21}^3 = 0.
              \Gamma_{22}^3 = 0.
        \Gamma_{23}^3 = \frac{\cos(\theta)a^2\sin(\theta)^2 + \cos(\theta)^3a^2 + \cos(\theta)r^2}{\sqrt{\cos^2(\theta)^2}}
                                                                                                (\cos(\theta)^2 a^2 + r^2)\sin(\theta)
              \Gamma_{30}^3 = 0.
           \Gamma_{31}^{3} = \frac{3ma^{2}q^{2}\sin(\theta)^{2}r^{2} - \cos(\theta)^{2}a^{4}q^{2}r + \cos(\theta)^{2}a^{4}q^{2}r + \cos(\theta)^{2}a^{4}r^{2} - \cos(\theta)^{2}a^{4}r^{2} + \cos(\theta)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                (\cos(\theta)^2a^2 + r^2)(a^2q^2 - a^4\sin(\theta)^2 - 2a^4r^2 + 4m^2a^2\sin(\theta)^2r + a^2q^4\sin(\theta)^2 + 4ma^4r + a^6\sin(\theta)^2 - 4m^2a^2r^2 - a^2r^4 - 4ma^2q^2\sin(\theta)^2r - 2a^2q^2r^2 + a^4\sin(\theta)^2r - 2a^2q^2r^2 + a^2q^2\sin(\theta)^2r - a^2q^2r^2 + a^2q
        \Gamma_{32}^{3} = \frac{\cos(\theta)a^{2}\sin(\theta)^{2} + \cos(\theta)^{3}a^{2} + \cos(\theta)r^{2}}{2}
                                                                                                (\cos(\theta)^2 a^2 + r^2)\sin(\theta)
              \Gamma_{33}^3 = 0.
G^{\mu}_{\ \nu:\mu}=0
              G^{\mu}_{1:\mu} = 0.
              G^{\mu}_{2:\mu} = 0.
              G^{\mu}_{3:\mu} = 0.
g^{\mu\nu} \, \Gamma^{\lambda}_{\mu\nu} = 0?
           g^{\mu\nu} \, \Gamma^0_{\mu\nu} = 0.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    mcos(\theta)\sin(\theta)d^4r\sin(\theta)^4r^2
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             a^6q^4\sin^6(\theta^4)\sin^4(\theta)^2r
                                                               (cos(\theta)s(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a+1)+(cos(\theta)+2a
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    \cos(	heta)a35(4);im(4))^4r\sin(	heta)^5 r^5
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               \cos(	heta) a \cos(	heta) a \sin(	heta) \sin(	heta) \sin(	heta)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              \cos(	heta) and \cos(	heta) from \cos(	heta) from \cos(	heta)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              \cos(\theta)a^4q^8 \sin(\theta)\theta^3 r^2 a^{10} \sin(\theta)^3 r^2
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 $+r^{2}+q^{2}-2mr^{2}\Gamma_{\mu\nu}^{14}8=8$ $g^{\mu\nu} \, \Gamma^3_{\mu\nu} = 0.$