Hazem Shehata

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# CSE 411: Artificial Intelligence (Elective Course #6)

400 Level, Mechatronics Engineering 2<sup>nd</sup> Term 2016/2017, Lecture #7

Hazem Shehata

Dept. of Computer & Systems Engineering Zagazig University

April 19th, 2017

Credits to Dr. Mohamed El Abd for the slides

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#### **Adminstrivia**

#### **Notes**

- Assignment #3:
  - Due: today.

#### Course Info:

- Website: http://hshehata.github.io/courses/zu/cse411/
- Office hours: Sunday 11:30am 12:30pm

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#### **Adminstrivia**

#### **Notes**

Assignment #3:

Due: today.

Midterm:

Date: Wednesday, Apr. 26, 2017.

• Time: 1:00pm - 2:30pm.

• Scope: lectures  $1 \rightarrow 6$ .

#### Course Info:

Website: http://hshehata.github.io/courses/zu/cse411/

Office hours: Sunday 11:30am - 12:30pm

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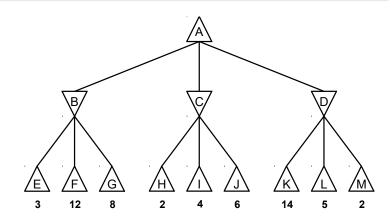
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#### **Adversarial search**

## Example: Effect of move ordering on $\alpha$ - $\beta$ pruning

Apply  $\alpha$ - $\beta$  pruning to calculate minimax value for node A.



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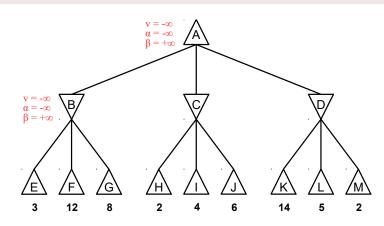
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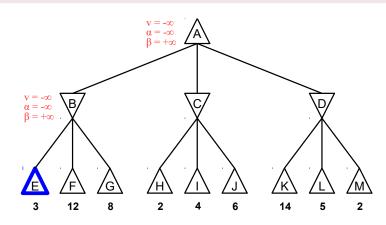
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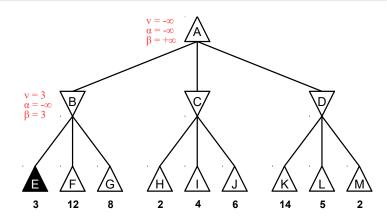
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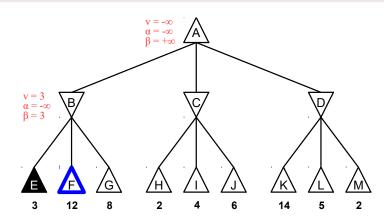
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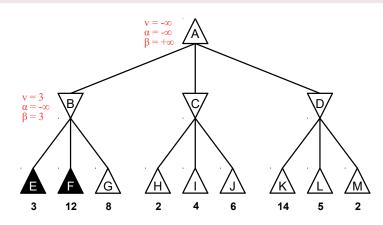
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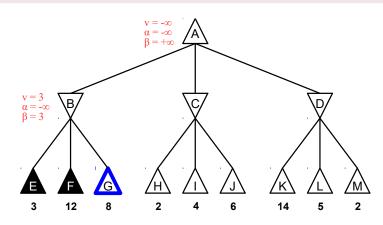
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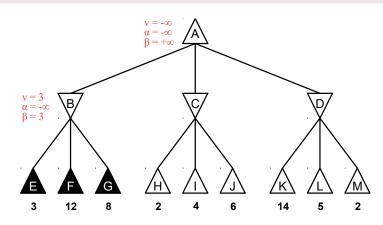
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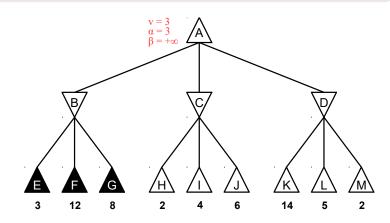
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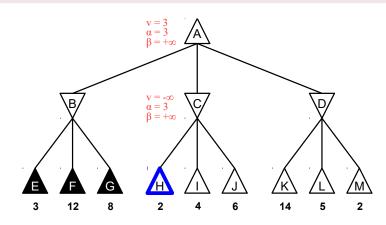
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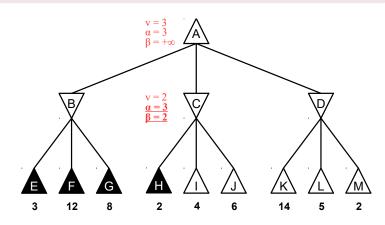
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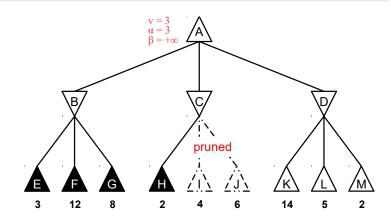
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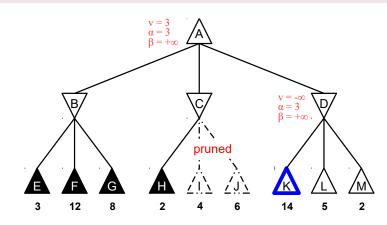
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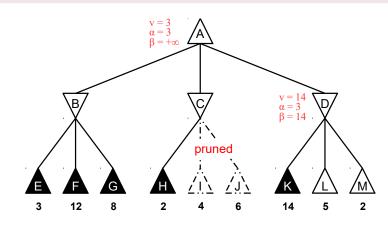
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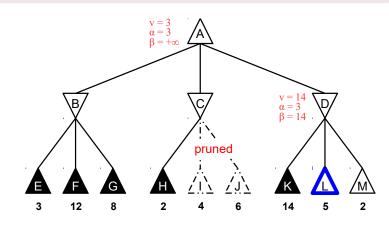
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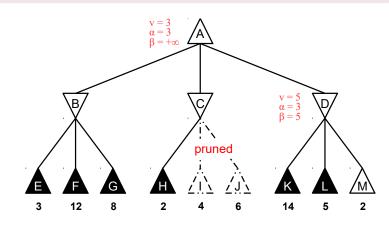
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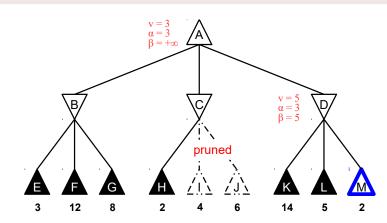
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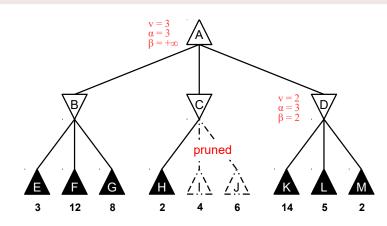
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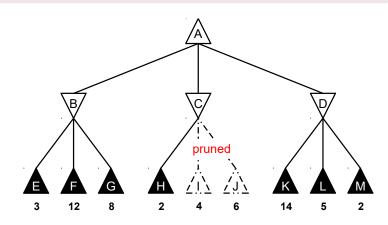
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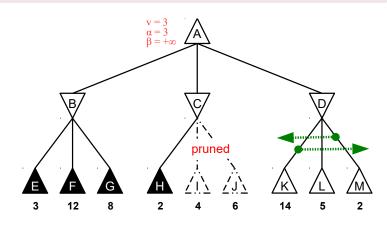
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# Example: Effect of move ordering on $\alpha$ - $\beta$ pruning

Reverse the order of the utility values for K, L, and M.



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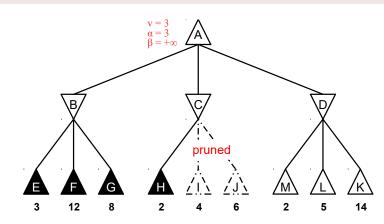
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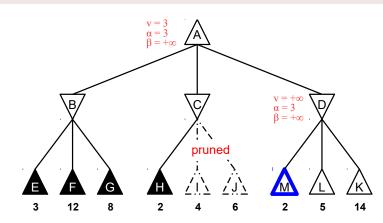
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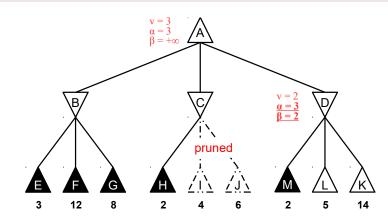
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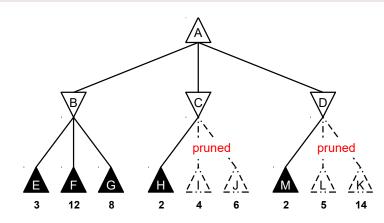
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# Effect of move ordering on $\alpha$ - $\beta$ pruning

 In the previous example, changing the order of nodes increases the efficiency of  $\alpha$ - $\beta$  pruning.

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#### **Adversarial search**

#### Effect of move ordering on $\alpha$ - $\beta$ pruning

- In the previous example, changing the order of nodes increases the efficiency of  $\alpha$ - $\beta$  pruning.
- Efficiency dependant on the ordering of children:
  - Checks each of MAX's children until finding one with a value higher than β.
  - Checks each of **MIN's** children until finding one with a value lower than  $\alpha$ .

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#### **Adversarial search**

#### Effect of move ordering on $\alpha$ - $\beta$ pruning

- In the previous example, changing the order of nodes increases the efficiency of  $\alpha$ - $\beta$  pruning.
- Efficiency dependant on the ordering of children:
  - Checks each of **MAX's** children until finding one with a value higher than  $\beta$ .
  - Checks each of **MIN's** children until finding one with a value lower than  $\alpha$ .
- Can use heuristics to order the nodes to check:
  - Check the highest-value children first for MAX.
  - Check the lowest-value children first for MIN.

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- Efficiency dependant on the ordering of children:
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- Can use heuristics to order the nodes to check:
  - Check the highest-value children first for MAX.
  - Check the lowest-value children first for MIN.
- Good ordering can reduce time complexity to  $O(b^{m/2})$ , random ordering gives roughly  $O(b^{3m/4})$ , remember that Minimax is  $O(b^m)$ .

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#### **Adversarial search**

#### Optimal decisions in multiplayer games

• Minimax can be extended to mutiplayer games:

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# Optimal decisions in multiplayer games

- Minimax can be extended to mutiplayer games:
  - The single value for each node is replaced with a vector.

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#### Adversarial search

#### Optimal decisions in multiplayer games

- Minimax can be extended to mutiplayer games:
  - The single value for each node is replaced with a vector.
  - For instance, a vector  $\langle v_a, a_b, v_c \rangle$  is associated with each node in a 3-palyer game with players A, B, and C.

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## **Adversarial search**

## Optimal decisions in multiplayer games

- Minimax can be extended to mutiplayer games:
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  - For instance, a vector  $\langle v_a, a_b, v_c \rangle$  is associated with each node in a 3-palyer game with players A, B, and C.
  - For a terminal state, UTILITY function returns a vector representing utility of that state from each player's viewpoint.

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# Optimal decisions in multiplayer games

- Minimax can be extended to mutiplayer games:
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  - For instance, a vector  $\langle v_a, a_b, v_c \rangle$  is associated with each node in a 3-palyer game with players A, B, and C.
  - For a terminal state, UTILITY function returns a vector representing utility of that state from each player's viewpoint.
- The multiplayer version of minimax (M-MAX) can be defined as follows:

```
 \begin{aligned} & \mathsf{M-Max}(s) = \\ & & \mathsf{UTILITY}(s) & & & \textbf{if } \mathsf{TERMINAL-TEST}(s) \\ & & max_{a \in \mathsf{ACTIONS}(s)}^p \mathsf{M-Max}(\mathsf{RESULT}(s,a)) & & \textbf{if } \mathsf{PLAYER}(s) = p \end{aligned}
```

where  $max^p$  is a function that chooses from among a group of vectors the one whose  $p^{th}$  element is the maximum.

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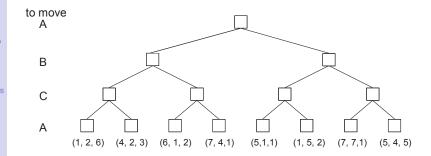
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## **Adversarial search**

## Example: multiplayer game tree

A partial game tree with 3 players (A, B, C).



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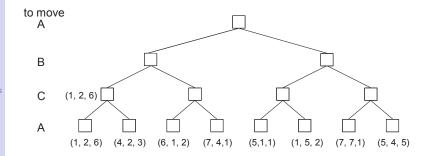
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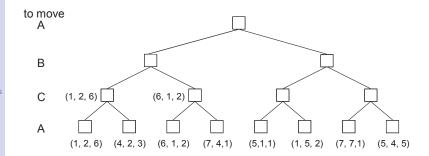
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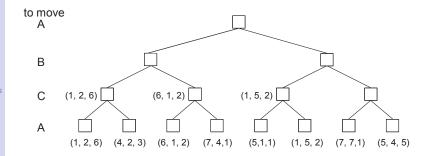
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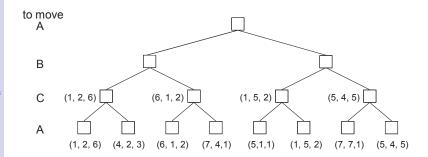
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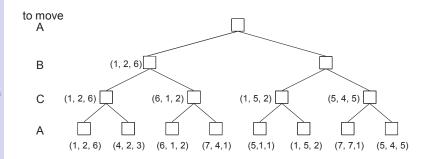
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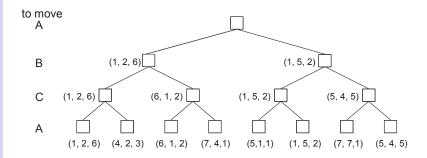
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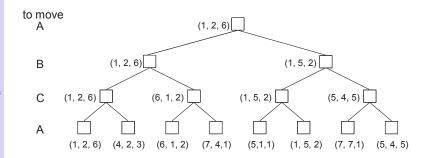
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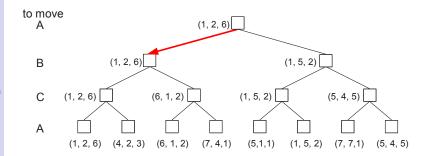
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## **Adversarial search**

## Imperfect real-time decisions

• How to reach a good decision when time is limited?

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## **Adversarial search**

## Imperfect real-time decisions

- How to reach a good decision when time is limited?
  - Cut off search earlier (before reaching terminal states).

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### Imperfect real-time decisions

- How to reach a good decision when time is limited?
  - Cut off search earlier (before reaching terminal states).
  - Apply a heuristic evaluation function to evaluate the desirability of states (instead of their utility values).

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## **Adversarial search**

### Imperfect real-time decisions

- How to reach a good decision when time is limited?
  - Cut off search earlier (before reaching terminal states).
  - Apply a heuristic evaluation function to evaluate the desirability of states (instead of their utility values).
- For inst., suppose we have 100 sec's to make a move in a chess game, and we explore 10<sup>4</sup> nodes/sec's:

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## **Adversarial search**

### Imperfect real-time decisions

- How to reach a good decision when time is limited?
  - Cut off search earlier (before reaching terminal states).
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- For inst., suppose we have 100 sec's to make a move in a chess game, and we explore 10<sup>4</sup> nodes/sec's:
  - We can explore  $10^6$  nodes per move  $\approx 35^{8/2}$ .

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### **Adversarial search**

### Imperfect real-time decisions

- How to reach a good decision when time is limited?
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  - Apply a heuristic evaluation function to evaluate the desirability of states (instead of their utility values).
- For inst., suppose we have 100 sec's to make a move in a chess game, and we explore 10<sup>4</sup> nodes/sec's:
  - We can explore  $10^6$  nodes per move  $\approx 35^{8/2}$ .
  - $\alpha$ - $\beta$  can reach depth of  $8 \Rightarrow$  pretty good chess program.

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### **Heuristic minimax**

• Need to alter minimax (or  $\alpha$ - $\beta$ ) in two ways:

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## **Adversarial search**

#### **Heuristic minimax**

- Need to alter minimax (or  $\alpha$ - $\beta$ ) in two ways:
  - Replace utility function (UTILITY) by heuristic evaluation function (EVAL)  $\Rightarrow$  estimates position's utility.

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## **Adversarial search**

#### **Heuristic minimax**

- Need to alter minimax (or  $\alpha$ - $\beta$ ) in two ways:
  - Replace utility function (UTILITY) by heuristic evaluation function (EVAL) ⇒ estimates position's utility.
  - ② Replace terminal test (TERMINAL-TEST) by cutoff test (CUTOFF-TEST) ⇒ decides when to apply EVAL.

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#### **Heuristic minimax**

- Need to alter minimax (or  $\alpha$ - $\beta$ ) in two ways:
  - Replace utility function (UTILITY) by heuristic evaluation function (EVAL) ⇒ estimates position's utility.
  - 2 Replace terminal test (TERMINAL-TEST) by cutoff test (CUTOFF-TEST)  $\Rightarrow$  decides when to apply EVAL.
- Modified version of minimax is called heuristic minimax:

```
\begin{aligned} & \text{H-MINIMAX}(s,d) = \\ & \begin{cases} & \text{EVAL}(s) & \text{if CUTOFF-TEST}(s,d) \\ & max_{a \in \text{ACTIONS}(s)} & \text{H-MINIMAX}( \\ & & \text{RESULT}(s,a),d+1) & \text{if PLAYER}(s) = \text{MAX} \\ & min_{a \in \text{ACTIONS}(s)} & \text{H-MINIMAX}( \\ & & \text{RESULT}(s,a),d+1) & \text{if PLAYER}(s) = \text{MIN} \\ \end{aligned}
```

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# **Adversarial search**

### Heuristic minimax

• To implement this modification in the minimax and  $\alpha$ - $\beta$  pruning algorithms, all that has to be done to is to replace the line:

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## **Adversarial search**

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if TERMINAL-TEST(s) then return UTILITY(s)

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• To implement this modification in the minimax and  $\alpha$ - $\beta$  pruning algorithms, all that has to be done to is to replace the line:

**if** TERMINAL-TEST(s) **then return** UTILITY(s) with the line:

if CUTOFF-TEST(s,d) then return EVAL(s)

 Also, some extra bookkeeping is needed to increment the depth on each recursive call of the algorithm.

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## **Adversarial search**

#### **Evaluation functions**

 Heuristic evaluation functions are functions to estimate the expected utility of a game from a non-leaf node.

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## **Adversarial search**

#### **Evaluation functions**

- Heuristic evaluation functions are functions to estimate the expected utility of a game from a non-leaf node.
- A good function:

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## **Adversarial search**

#### **Evaluation functions**

- Heuristic evaluation functions are functions to estimate the expected utility of a game from a non-leaf node.
- A good function:
  - Should order terminal states as true utility values do.

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## **Adversarial search**

#### **Evaluation functions**

- Heuristic evaluation functions are functions to estimate the expected utility of a game from a non-leaf node.
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  - Should not take too much time to compute.

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## Adversarial search

#### **Evaluation functions**

- Heuristic evaluation functions are functions to estimate the expected utility of a game from a non-leaf node.
- A good function:
  - Should order terminal states as true utility values do.
  - Should not take too much time to compute.
  - For non-leaf nodes, it should be strongly correlated with the actual chances of winning.

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## **Adversarial search**

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- Heuristic evaluation functions are functions to estimate the expected utility of a game from a non-leaf node.
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- Mostly work by calculating various features of state.

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## **Adversarial search**

#### **Evaluation functions**

- Heuristic evaluation functions are functions to estimate the expected utility of a game from a non-leaf node.
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  - Should order terminal states as true utility values do.
  - Should not take too much time to compute.
  - For non-leaf nodes, it should be strongly correlated with the actual chances of winning.
- Mostly work by calculating various *features* of state.
  - Chess example: features could be number of white queens, black queens, white pawns, black pawns, etc.

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## **Adversarial search**

### **Evaluation functions**

 A simple version is to set it up by calculating a weighted average of the numerical values of all the features.

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## **Adversarial search**

### **Evaluation functions**

- A simple version is to set it up by calculating a weighted average of the numerical values of all the features.
- In this case, the evaluation function takes the form of a weighted linear function expressed as follows:

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## **Adversarial search**

#### **Evaluation functions**

- A simple version is to set it up by calculating a weighted average of the numerical values of all the features.
- In this case, the evaluation function takes the form of a weighted linear function expressed as follows:

$$EVAL(s) = w_1 f_1(s) + w_2 f_2(s) + ... + w_n f_n(s)$$

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#### **Adversarial search**

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- In this case, the evaluation function takes the form of a weighted linear function expressed as follows:

$$EVAL(s) = w_1 f_1(s) + w_2 f_2(s) + ... + w_n f_n(s)$$

• Chess example:  $f_i$  could be number of each kind of piece on board,  $w_i$  could represent strength of that kind.

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#### Adversarial search

#### **Evaluation functions**

- A simple version is to set it up by calculating a weighted average of the numerical values of all the features.
- In this case, the evaluation function takes the form of a weighted linear function expressed as follows:

$$EVAL(s) = w_1 f_1(s) + w_2 f_2(s) + ... + w_n f_n(s)$$

- Chess example: f<sub>i</sub> could be number of each kind of piece on board, w<sub>i</sub> could represent strength of that kind.
- Evaluation function need not return actual expected values as long as the ordering of states is the same.

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#### **Adversarial search**

#### **Stochastic games**

• In some games, there are many unpredictable external events that could affect the course of the game.

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#### **Adversarial search**

#### Stochastic games

- In some games, there are many unpredictable external events that could affect the course of the game.
- These games have stochastic environments, and hence, called stochastic games.

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#### **Adversarial search**

#### Stochastic games

- In some games, there are many unpredictable external events that could affect the course of the game.
- These games have stochastic environments, and hence, called stochastic games.
- Typical sources of unpredictability in stochastic games include events such as: roll of a dice, toss of a coin, withdrawal of a card, etc.

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#### **Adversarial search**

#### Stochastic games

- In some games, there are many unpredictable external events that could affect the course of the game.
- These games have stochastic environments, and hence, called stochastic games.
- Typical sources of unpredictability in stochastic games include events such as: roll of a dice, toss of a coin, withdrawal of a card, etc.
- Due to such uncertainty, we cannot construct a complete/exact game tree for a stochastic game.

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#### **Adversarial search**

#### Stochastic games

- In some games, there are many unpredictable external events that could affect the course of the game.
- These games have stochastic environments, and hence, called stochastic games.
- Typical sources of unpredictability in stochastic games include events such as: roll of a dice, toss of a coin, withdrawal of a card, etc.
- Due to such uncertainty, we cannot construct a complete/exact game tree for a stochastic game.
- Minimax strategy becomes inapplicable to such games!

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#### **Adversarial search**

### Stochastic games

 To model such uncertainty in stochastic games, a game tree would include chance nodes in addition to MAX and MIN nodes.

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#### Adversarial search

#### Stochastic games

- To model such uncertainty in stochastic games, a game tree would include chance nodes in addition to MAX and MIN nodes.
  - Branches leading from each chance node denote the possible outcomes of an unpredictable event (e.g., dice roll).

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#### **Adversarial search**

#### Stochastic games

- To model such uncertainty in stochastic games, a game tree would include chance nodes in addition to MAX and MIN nodes.
  - Branches leading from each chance node denote the possible outcomes of an unpredictable event (e.g., dice roll).
  - Each branch is labeled with an outcome r and its probability P(r).

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#### **Adversarial search**

#### Stochastic games

- To model such uncertainty in stochastic games, a game tree would include chance nodes in addition to MAX and MIN nodes.
  - Branches leading from each chance node denote the possible outcomes of an unpredictable event (e.g., dice roll).
  - Each branch is labeled with an **outcome** r and its **probability** P(r).
  - Average expected utility of a chance node  $= \sum_r P(r) * \mathsf{NEXT}(r)$ , where  $\mathsf{NEXT}(r)$  represents the average expected utility of the node reached as a consequence of the outcome r.

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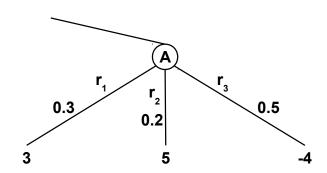
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#### **Adversarial search**

#### **Example: chance nodes**

The expected utility of the chance node given below = 0.3 \* 3 + 0.2 \* 5 + 0.5 \* (-4) = -0.1.



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#### **Adversarial search**

#### Stochastic games

 In single-player stochastic games (e.g., solitaire and minesweeper), the game tree has only two types of nodes:

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#### Adversarial search

#### Stochastic games

- In single-player stochastic games (e.g., solitaire and minesweeper), the game tree has only two types of nodes:
  - MAX nodes to model the player's behavior.

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#### **Adversarial search**

#### Stochastic games

- In single-player stochastic games (e.g., solitaire and minesweeper), the game tree has only two types of nodes:
  - MAX nodes to model the player's behavior.
  - 2 Chance nodes to model the stochastic environment.

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#### Stochastic games

- In single-player stochastic games (e.g., solitaire and minesweeper), the game tree has only two types of nodes:
  - MAX nodes to model the player's behavior.
  - 2 Chance nodes to model the stochastic environment.
- Average expected utility of a node in such tree is called expectimax.

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#### Stochastic games

- In single-player stochastic games (e.g., solitaire and minesweeper), the game tree has only two types of nodes:
  - MAX nodes to model the player's behavior.
  - 2 Chance nodes to model the stochastic environment.
- Average expected utility of a node in such tree is called expectimax.
- The expectimax value of a node is defined as follows:

```
 \begin{aligned} & \mathsf{EXPECTIMAX}(s) = \\ & & \mathbf{If} \ \mathsf{TERMINAL\text{-}TEST}(s) \\ & & max_a \ \mathsf{EXPECTIMAX}(\mathsf{RESULT}(s,a)) & & \mathbf{if} \ \mathsf{PLAYER}(s) = \mathsf{MAX} \\ & & \sum_r P(r) * \mathsf{EXPECTIMAX}(\mathsf{RESULT}(s,r)) & & \mathbf{if} \ \mathsf{PLAYER}(s) = \mathsf{CHANCE} \end{aligned}
```

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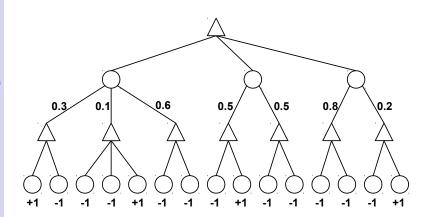
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### **Adversarial search**

#### **Example: expectimax calculation**

Calculate the expectimax value of the root node for the given game tree.



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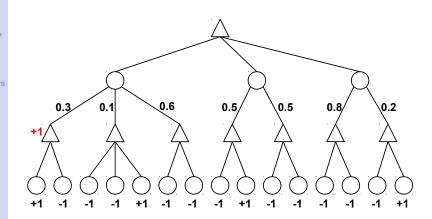
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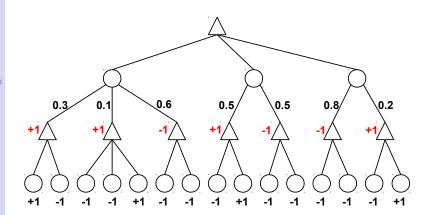
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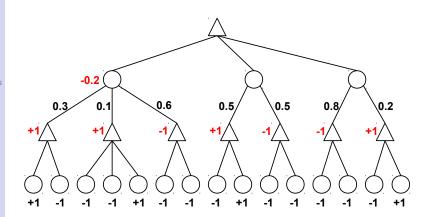
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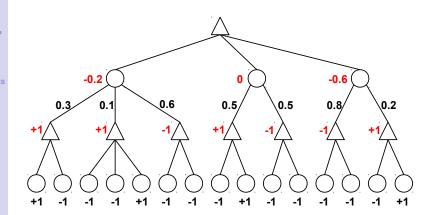
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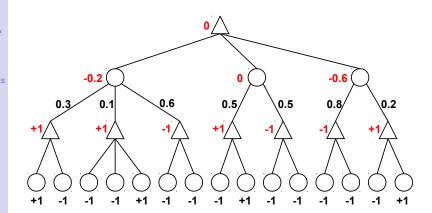
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### **Adversarial search**

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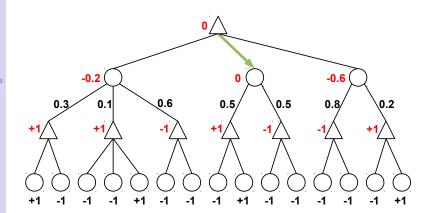
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#### Adversarial search

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#### **Adversarial search**

#### **Stochastic games**

 Notice that in expectimax, we choose the move that maximizes the average outcome of the game.

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#### **Adversarial search**

#### Stochastic games

- Notice that in expectimax, we choose the move that maximizes the average outcome of the game.
- The actual outcome (*i.e.*, utility value when game ends) may be **more or less** than the expectimax value.

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#### **Adversarial search**

#### Stochastic games

- Notice that in expectimax, we choose the move that maximizes the average outcome of the game.
- The actual outcome (*i.e.*, utility value when game ends) may be **more or less** than the expectimax value.
- Unlike minimax where the actual outcome is guaranteed to be no less than the minimax value.

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#### **Adversarial search**

#### Stochastic games

- Notice that in expectimax, we choose the move that maximizes the average outcome of the game.
- The actual outcome (*i.e.*, utility value when game ends) may be **more or less** than the expectimax value.
- Unlike minimax where the actual outcome is guaranteed to be no less than the minimax value.
- However, expectimax may still be applicable to 2-player deterministic games (e.g., tic-tac-toe and chess) if a probability distribution for opponent's actions is known.

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#### **Adversarial search**

#### Stochastic games

 In two-player stochastic games (e.g., backgammon), aim is to minimize opponent's chances of wining in presence of a stochastic environment.

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#### Adversarial search

#### Stochastic games

- In two-player stochastic games (e.g., backgammon), aim is to minimize opponent's chances of wining in presence of a stochastic environment.
- The game tree would have three types of nodes:
  - MAX nodes to model the player's behavior.
  - 2 MIN nodes to model the opponent's behavior.
  - 3 Chance nodes to model the stochastic environment.

April 19<sup>th</sup>, 2017 21

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#### Adversarial search

#### Stochastic games

- In two-player stochastic games (e.g., backgammon), aim is to minimize opponent's chances of wining in presence of a stochastic environment.
- The game tree would have three types of nodes:
  - MAX nodes to model the player's behavior.
  - 2 MIN nodes to model the opponent's behavior.
  - Ohance nodes to model the stochastic environment.
- The average expected value in this case is called expectiminimax, and defined as follows:

```
 \begin{aligned} & \mathsf{EXPECTIMINIMAX}(s) = \\ & \begin{cases} & \mathsf{UTILITY}(s) & \mathsf{if} \ \mathsf{TERMINAL\text{-}TEST}(s) \\ & \mathit{max}_a \ \mathsf{EXPECTIMINIMAX}(\mathsf{RESULT}(s,a)) & \mathsf{if} \ \mathsf{PLAYER}(s) = \mathsf{MAX} \\ & \mathit{min}_a \ \mathsf{EXPECTIMINIMAX}(\mathsf{RESULT}(s,a)) & \mathsf{if} \ \mathsf{PLAYER}(s) = \mathsf{MIN} \\ & \sum_r P(r) * \\ & \mathsf{EXPECTIMINIMAX}(\mathsf{RESULT}(s,r)) & \mathsf{if} \ \mathsf{PLAYER}(s) = \mathsf{CHANCE} \end{aligned}
```

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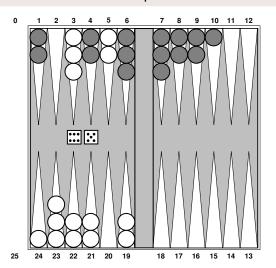
Stochastic games

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#### **Adversarial search**

#### **Example: Backgammon**

White has rolled 6-5 and has 4 possible moves.



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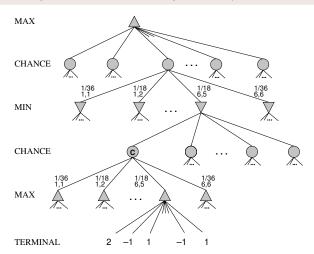
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### **Adversarial search**

#### **Example: Backgammon**

Schematic game tree for a backgammon position.



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# Requirements

#### What do I need from you

• When given a certain problem you should be able to:

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## Requirements

#### What do I need from you

- When given a certain problem you should be able to:
  - Build the game tree up to a given depth.

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### Requirements

#### What do I need from you

- When given a certain problem you should be able to:
  - Build the game tree up to a given depth.
  - Apply the expectimax and expectiminimax algorithms.

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## Requirements

#### What do I need from you

- When given a certain problem you should be able to:
  - Build the game tree up to a given depth.
  - Apply the expectimax and expectiminimax algorithms.
  - Propose a good heuristic evaluation function

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### Requirements

#### What do I need from you

- When given a certain problem you should be able to:
  - Build the game tree up to a given depth.
  - Apply the expectimax and expectiminimax algorithms.
  - Propose a good heuristic evaluation function
- Answer descriptive questions.

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# **Reading Material**

#### Which parts of the textbook are covered

- Russell-Norvig, Chapters 5:
  - Pages 171 173.
  - Pages 177 178