

EE367 Part 3

Theory

3.1) Eigenvalues

$$a) A = \begin{bmatrix} 3 & 1 \\ 2 & 2 \end{bmatrix}$$

$$i) \det(A - \lambda I) = 0 \Rightarrow \det \begin{pmatrix} 3-\lambda & 1 \\ 2 & 2-\lambda \end{pmatrix} = 0$$

$$(3-\lambda)(2-\lambda) - 2 = 0$$

$$6 - 3\lambda - 2\lambda + \lambda^2 - 2 = 0$$

$$\lambda^2 - 5\lambda + 4 = 0$$

$$(\lambda-4)(\lambda-1) = 0$$

$$\lambda_1 = 4 \text{ and } \lambda_2 = 1$$

$$ii) \begin{bmatrix} 3 & 1 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 4x \\ 4y \end{bmatrix} \quad \begin{bmatrix} 3 & 1 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix}$$

$$3x+y=4x \quad 2x+2y=4y$$

$$3x+y=x \quad 2x+2y=y$$

$$x=y$$

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x \\ x \end{bmatrix} = \alpha \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$E_{\lambda_1} = \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$$

$$y=-2x$$

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x \\ -2x \end{bmatrix} = \alpha \begin{bmatrix} 1 \\ -2 \end{bmatrix}$$

$$E_{\lambda_2} = \left\{ \begin{bmatrix} 1 \\ -2 \end{bmatrix} \right\}$$

$$iii) AM(\lambda=1) = GM(\lambda=1) = 1$$

$$AM(\lambda=4) = GM(\lambda=4) = 1$$

iv) It is indeed diagonalizable.

$$V = \begin{bmatrix} 1 & 1 \\ 1 & -2 \end{bmatrix}, \Delta = \begin{bmatrix} 4 & 0 \\ 0 & 1 \end{bmatrix} \Rightarrow A = V \Delta V^{-1}$$

$$b) A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$i) \det(A - \lambda I) = 0 \Rightarrow \det \begin{pmatrix} -\lambda & 1 \\ 1 & -\lambda \end{pmatrix} = 0$$

$$\lambda^2 - 1 = 0$$

$$(\lambda+1)(\lambda-1) = 0$$

$$\lambda_1 = 1, \lambda_2 = -1$$

$$ii) \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix} \quad \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -y \\ x \end{bmatrix}$$

$$y = x$$

$$x = y$$

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x \\ x \end{bmatrix} = \alpha \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$E_{\lambda_1} = \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$$

$$y = -x$$

$$x = -y$$

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x \\ -x \end{bmatrix} = \alpha \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$E_{\lambda_2} = \left\{ \begin{bmatrix} 1 \\ -1 \end{bmatrix} \right\}$$

$$iii) AM(\lambda) = GM(\lambda) = 1$$

$$AM(\lambda_1) = GM(\lambda_1) = 1$$

iv) It is indeed diagonalizable.

$$V = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}, \Delta = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$c) A = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

$$\text{i)} \det(A - 2I) = 0 \Rightarrow \det\left(\begin{bmatrix} -2 & 1 \\ -1 & -2 \end{bmatrix}\right) = 0$$

$$-7 = 1 + 0$$

$$\boxed{\lambda_1 = i, \lambda_2 = -i}$$

$$\text{ii)} \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} iy \\ -x \end{pmatrix}$$

$$\begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -y \\ -x \end{pmatrix}$$

$$y = ix \quad -x = iy$$

$$\begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} = \alpha \begin{bmatrix} i \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} = \alpha \begin{bmatrix} -i \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} = \alpha \begin{bmatrix} i \\ 1 \end{bmatrix}$$

$$\text{iii)} AM(\lambda_1) = GM(\lambda_1) = 1$$

$$AM(\lambda_2) = GM(\lambda_2) = 1$$

$$\text{iv)} V = \begin{bmatrix} 1 & 1 \\ i & -i \end{bmatrix}, \Delta = \begin{bmatrix} i & 0 \\ 0 & i \end{bmatrix}, A = V \Delta V^{-1}$$

$$d) A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\text{i)} \det(A - 2I) = 0 \Rightarrow \det\left(\begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 1 \\ 0 & 0 & -1 \end{bmatrix}\right) = 0$$

$$(-1)(-1)(-1)^2 = (-1)^3 = 0$$

$$\lambda_1 = 1$$

$$\text{ii)} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

$$x = y \quad y + z = 0$$

$$x + y + z = y \quad \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} x \\ y \\ -y \end{bmatrix} = x \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + y \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix}$$

$$\boxed{E_{21} = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} \right\}}$$

iii) $AM(\lambda_1) \neq GM(\lambda_1) \Rightarrow \text{NOT Diagonalizable}$

$$3.2) 1) A = pq^T + qp^T.$$

$$\text{i)} A(p+q) = (pq^T + qp^T)(p+q)$$

$$= pq^T p + p q^T q + qp^T p + qp^T q$$

$$(A-p^Tq + q^Tp) = cp + p(1) + q(1) + cq$$

$$= (c+1)(p+q)$$

$$\text{ii)} A(p-q) = (pq^T + qp^T)(p-q)$$

$$= pq^T p - pq^T q + qp^T p - qp^T q$$

$$(A-p^Tq - q^Tp) = cp - p - q - (c-1)$$

$$= (c-1)(p-q)$$

$$2) R(A) = (pq^T + qp^T)x = (q^Tx)p + (p^Tx)q$$

$$\dim R(A) = \dim \{(q^Tx)p + (p^Tx)q \mid x \in \mathbb{R}^n\} = 2$$

Nullspace: $p^Tx = 0$ and $q^Tx = 0$

$$\sum x_i q_i = 0 \quad \sum x_i p_i = 0$$

$$N(A) = \{x \in \mathbb{R}^n \mid \sum x_i q_i = 0 \text{ and } \sum x_i p_i = 0\}$$

i.e. nullspace is set of vectors orthogonal to p and q .

3) Eigenvectors across different eigenspaces are orthogonal. For $\lambda=0$, we can pick an orthonormal basis $\{a_3, a_4, \dots, a_n\}$ which allows $\{p^T q, p \cdot q, a_3, a_4, \dots, a_n\}$ to be a basis for \mathbb{R}^n . Now, let $a_i = \frac{p^T q}{\|p\| \|q\|}$ and $a_i' = \frac{p - q}{\|p - q\|}$. Then $\{a_i, a_i', a_3, a_4, \dots, a_n\}$ is an orthonormal basis. It follows that

$V = [a_1, a_2, \dots, a_n]$ is an orthogonal matrix with columns all eigenvectors

So, $V^{-1} = V^T$ and $A = V \Lambda V^T$, where $\Lambda = \text{diag}(c_1, c_2, 0, 0, \dots, 0)$

4) The nullspace of A is still given by:

$$N(A) = \{x \in \mathbb{R}^n \mid (pq^T + qp^T)x = 0 \Rightarrow (q^T x)p + (p^T x)q = 0 \Rightarrow q^T x = p^T x = 0\}, \text{ ie } x \text{ orthogonal to both } p \text{ and } q.$$

So $\lambda=0$ and we can select an orthonormal basis $\{a_3, a_4, \dots, a_n\}$

$$R(A) = \{Ax \mid x \in \mathbb{R}^3\} = \{(pq^T + qp^T)x \mid x \in \mathbb{R}^n\} = \{(q^T x)p + (p^T x)q \mid x \in \mathbb{R}^n\} = \text{span}\{p, q\}.$$

So $\text{rank } A = 2$. We will use this to find eigenvalues, and show they are different from part 3.

$$Ax = \lambda x$$

$$x \in \text{span}\{p, q\} \Rightarrow x = c_1 p + c_2 q$$

$$Ax = A(c_1 p + c_2 q) = (pq^T + qp^T)(c_1 p + c_2 q) = c_1 p q^T p + c_2 p q^T q + c_1 q p^T p + c_2 q p^T q = c_1 c_1 \|q\|^2 p + c_1 \|p\|^2 q + c_2 c_2 q$$

$$= (c_1(c_1 + c_2 \|q\|^2))p + (c_2(\|p\|^2 + c_2 c_2))q$$

$$\lambda = \frac{c_1(c_1 + c_2 \|q\|^2)}{c_1} = \frac{c_2(\|p\|^2 + c_2 c_2)}{c_2}$$

$$c_1 + \frac{c_2}{c_1} \|q\|^2 = c_1 + \frac{c_1}{c_2} \|p\|^2$$

$$\frac{c_2}{c_1} \|q\|^2 = \frac{c_1}{c_2} \|p\|^2$$

$$\frac{c_1}{c_2} = \pm \frac{\|q\|}{\|p\|}$$

$$\lambda = c_1 + \frac{c_2}{c_1} \|q\|^2 = c_1 \pm \frac{\|p\|}{\|q\|} \|q\|^2 = c_1 \pm \|p\| \|q\|$$

$$\lambda_1 = c_1 + \|p\| \|q\| \quad E_{\lambda_1} = \text{span}\{\|q\| p + \|p\| q\}$$

$$\lambda_2 = c_1 - \|p\| \|q\| \quad E_{\lambda_2} = \text{span}\{\|q\| p - \|p\| q\}$$

So we have $V = [a_1, a_2, \dots, a_n]$ where $a_i = \frac{v_i}{\|v_i\|}$ where $v_1 = \|q\| p + \|p\| q$,

$a_2 = \frac{v_2}{\|v_2\|}$ where $v_2 = \|q\| p - \|p\| q$ and a_3, \dots, a_n unchanged. This is orthogonal matrix so:

$$A = V \Lambda V^T \text{ where } V^{-1} = V^T \text{ and } \Lambda = \text{diag}(c_1 + \|p\| \|q\|, c_1 - \|p\| \|q\|, 0, 0, \dots, 0)$$

3.2) Affine approximation:

$$f(x) = f(\bar{x}) + \nabla f(\bar{x})^T (x - \bar{x})$$

$$f(x) = -\frac{1}{2}(x_1 x_2)^{\frac{1}{2}}, \quad x_1, x_2 > 0$$

$$a) \hat{f}_1(x) = f(\bar{x}) + \nabla f(\bar{x})^T (x - \bar{x})$$

$$\nabla f(x) = \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \end{bmatrix}$$

$$\frac{\partial f}{\partial x_1} = -\frac{1}{2}(x_1 x_2)^{-\frac{1}{2}}(x_2) = -\frac{1}{2} x_1^{-\frac{1}{2}} x_2^{\frac{1}{2}} = -\frac{1}{2} \sqrt{\frac{x_2}{x_1}}$$

$$\frac{\partial f}{\partial x_2} = -\frac{1}{2}(x_1 x_2)^{-\frac{1}{2}}(x_1) = -\frac{1}{2} \sqrt{\frac{x_1}{x_2}} = -\frac{1}{2} x_1^{\frac{1}{2}} x_2^{-\frac{1}{2}}$$

$$\hat{f}_1(x) = f(\bar{x}) + \left[-\frac{1}{2} \sqrt{\frac{x_2}{x_1}} \quad -\frac{1}{2} \sqrt{\frac{x_1}{x_2}} \right] \begin{bmatrix} x_1 - \bar{x}_1 \\ x_2 - \bar{x}_2 \end{bmatrix}$$

$$f_1(x) = -\sqrt{x_1 x_2} - \frac{1}{2} \sqrt{\frac{x_2}{x_1}} (x_1 - \bar{x}_1) - \frac{1}{2} \sqrt{\frac{x_1}{x_2}} (x_2 - \bar{x}_2)$$

$$x = \begin{bmatrix} 6 \\ 3 \end{bmatrix}, \quad \bar{x} = \begin{bmatrix} 9 \\ 1 \end{bmatrix} \quad x_1 = 6, \quad x_2 = 3, \quad \bar{x}_1 = 9, \quad \bar{x}_2 = 1$$

$$\begin{aligned} \hat{f}_1\left(\begin{bmatrix} 6 \\ 3 \end{bmatrix}\right) &= -\sqrt{(9)(1)} - \frac{1}{2} \sqrt{\frac{9}{4}} (2) - \frac{1}{2} \sqrt{\frac{4}{9}} (2) \\ &= -2 - \frac{1}{2} - 2 \end{aligned}$$

$$\boxed{\hat{f}_1\left(\begin{bmatrix} 6 \\ 3 \end{bmatrix}\right) = -4.5}$$

$$b) \hat{f}_2(x) = f(\bar{x}) + \nabla f(\bar{x})^T (x - \bar{x}) + \frac{1}{2} (x - \bar{x})^T \nabla^2 f(\bar{x})(x - \bar{x})$$

$$\nabla^2 f(x) = \begin{bmatrix} \frac{\partial^2 f}{\partial x_1 \partial x_1} & \frac{\partial^2 f}{\partial x_1 \partial x_2} \\ \frac{\partial^2 f}{\partial x_2 \partial x_1} & \frac{\partial^2 f}{\partial x_2 \partial x_2} \end{bmatrix}$$

$$\left. \begin{array}{l} \frac{\partial^2 f}{\partial x_1^2} = \frac{1}{4} x_1^{-\frac{3}{2}} x_2^{\frac{1}{2}} \\ \frac{\partial^2 f}{\partial x_1 \partial x_2} = -\frac{1}{4} x_1^{-\frac{1}{2}} x_2^{-\frac{1}{2}} \\ \frac{\partial^2 f}{\partial x_2 \partial x_1} = -\frac{1}{4} x_1^{-\frac{1}{2}} x_2^{-\frac{1}{2}} \\ \frac{\partial^2 f}{\partial x_2^2} = \frac{1}{4} x_1^{\frac{1}{2}} x_2^{-\frac{3}{2}} \end{array} \right\} \quad \nabla^2 f(x) = \frac{1}{4} \begin{bmatrix} x_1^{-\frac{3}{2}} x_2^{\frac{1}{2}} & -x_1^{-\frac{1}{2}} x_2^{-\frac{1}{2}} \\ -x_1^{-\frac{1}{2}} x_2^{-\frac{1}{2}} & x_1^{\frac{1}{2}} x_2^{-\frac{3}{2}} \end{bmatrix}$$

$$\hat{f}_2(x) = f(\bar{x}) + \left(-\frac{1}{2}\right) \begin{bmatrix} x_1^{-\frac{3}{2}} x_2^{\frac{1}{2}} & -x_1^{-\frac{1}{2}} x_2^{-\frac{1}{2}} \end{bmatrix} \begin{bmatrix} x_1 - \bar{x}_1 \\ x_2 - \bar{x}_2 \end{bmatrix} + \left(\frac{1}{2}\right) \left(\frac{1}{4}\right) \begin{bmatrix} x_1^{-\frac{3}{2}} x_2^{\frac{1}{2}} & -x_1^{-\frac{1}{2}} x_2^{-\frac{1}{2}} \end{bmatrix} \begin{bmatrix} x_1 - \bar{x}_1 \\ x_2 - \bar{x}_2 \end{bmatrix} \begin{bmatrix} x_1 - \bar{x}_1 \\ x_2 - \bar{x}_2 \end{bmatrix}$$

$$\hat{f}_2\left(\begin{bmatrix} 6 \\ 3 \end{bmatrix}\right) = -\sqrt{(9)(1)} + \left(-\frac{1}{2}\right) \begin{bmatrix} 1^{\frac{1}{2}} 4^{-\frac{1}{2}} & 4^{\frac{1}{2}} 1^{\frac{1}{2}} \end{bmatrix} \begin{bmatrix} 2 \\ 2 \end{bmatrix} + \frac{1}{8} \begin{bmatrix} 2 & 2 \end{bmatrix} \begin{bmatrix} 4^{-\frac{3}{2}} & -4^{\frac{1}{2}} \\ 4^{-\frac{1}{2}} & 4^{\frac{1}{2}} \end{bmatrix} \begin{bmatrix} 2 \\ 2 \end{bmatrix}$$

$$= -2 - \frac{1}{2} \left[\frac{1}{2} \quad 2 \right] \begin{bmatrix} ? \\ ? \end{bmatrix} + \frac{1}{8} \begin{bmatrix} 2 & 2 \end{bmatrix} \begin{bmatrix} \frac{1}{8} & -\frac{1}{2} \\ -\frac{1}{2} & 2 \end{bmatrix} \begin{bmatrix} ? \\ ? \end{bmatrix}$$

$$= -2 - \frac{1}{2} (5) + \frac{1}{8} [2 \ 2] \begin{bmatrix} -\frac{3}{16} \\ 3 \end{bmatrix}$$

$$= -2 - 2.5 + \frac{1}{8} \left(-\frac{3}{16} + \frac{3}{8} \right) = -9.5 + \frac{1}{8} \left(\frac{3}{8} \right) = \boxed{-9.5 + \frac{9}{16}}$$

$$\nabla^2 f(\bar{x}) = \frac{1}{4} \begin{bmatrix} \frac{y_2}{x_1^3} & -\frac{1}{x_1 x_2} \\ -\frac{1}{x_1 x_2} & \frac{y_1}{x_2^3} \end{bmatrix}$$

$$[a \ b] \begin{bmatrix} \frac{y_2}{x_1^3} & -\frac{1}{x_1 x_2} \\ -\frac{1}{x_1 x_2} & \frac{y_1}{x_2^3} \end{bmatrix} [a \ b]$$

$$[a \ b] \begin{bmatrix} a \frac{y_2}{x_1^3} - b \frac{1}{x_1 x_2} \\ -\frac{a}{x_1 x_2} + b \frac{y_1}{x_2^3} \end{bmatrix}$$

$$a^2 \int \frac{y_2}{x_1^3} - ab \frac{1}{x_1 x_2} - ab \frac{1}{x_1 x_2} + b^2 \sqrt{\frac{y_1}{x_2^3}}$$

$$a^2 \int \frac{y_2}{x_1^3} - 2ab \frac{1}{x_1 x_2} + b^2 \sqrt{\frac{y_1}{x_2^3}}$$

$$a^2 \frac{\sqrt{\frac{y_2}{x_1^3} + b^2 \frac{y_1}{x_2^3}}}{2} \geq \sqrt{a^2 b^2 \frac{\frac{y_2}{x_1^3} + \frac{y_1}{x_2^3}}{x_1 x_2}} = \sqrt{a^2 b^2 \frac{1}{x_1^2 x_2^2}} = \sqrt{a^2 b^2 \frac{1}{x_1 x_2}} = ab \frac{1}{\sqrt{x_1 x_2}}$$

$$\Rightarrow a^2 \sqrt{\frac{y_2}{x_1^3} + b^2 \sqrt{\frac{y_1}{x_2^3}}} \geq 2ab \frac{1}{\sqrt{x_1 x_2}}$$

$$\Rightarrow a^2 \sqrt{\frac{y_2}{x_1^3} - 2ab \frac{1}{x_1 x_2} + b^2 \sqrt{\frac{y_1}{x_2^3}}} \geq 0$$

d) $x = \bar{x} + \lambda v$

want second-order term = 0

$$(x - \bar{x})^\top \nabla^2 f(\bar{x}) (v - \bar{v}) = 0$$

$$(v - \bar{v})^\top \nabla^2 f(\bar{x}) (v - \bar{v}) = 0$$

$$v^\top \nabla^2 f(\bar{x}) v = 0$$

$$\stackrel{(v =)}{\Rightarrow} \frac{(v_1 \bar{x}_2 - v_2 \bar{x}_1)^2}{\sqrt{x_1^3 x_2^3}} = 0 \text{ from part C}$$

$$\Rightarrow v_1 \bar{x}_2 - v_2 \bar{x}_1 = 0$$

$$\text{Pick } \bar{x} = (\bar{x}_1, \bar{x}_2) = (1, 2)$$

$$\bar{x} = (1, 2)$$

$$2v_1 - v_2 = 0$$

$$v_1 = 1, v_2 = 2 \Rightarrow$$

$$v = (1, 2)$$

$$3.9) \text{ a)} f(x) = \prod_{\lambda} x = \left(\prod_{\lambda} (x - x^{(0)}) \right) + x^{(0)}$$

$$\prod_{\lambda} (x - x^{(0)}) = \frac{(v - v^{(0)}, v)}{\|v\|^2} v \Rightarrow \prod_{\lambda} v = \frac{(v, v^{(0)})^T v}{\|v\|^2} v + x^{(0)} = ((v, v^{(0)})^T v) v + x^{(0)}$$

$$= \frac{(v - x^{(0)})^T v}{\|v\|^2} v + x^{(0)}$$

$$f(x) = 2p(x) - x$$

$$\begin{aligned} &= 2((v - v^{(0)})^T v) v + 2x^{(0)} - x \\ &= 2((x^T - x^{(0)^T}) v) v + 2x^{(0)} - x \\ &= 2(x^T v - x^{(0)^T} v) v + 2x^{(0)} - x \\ &= 2v(v^T x) - 2v(v^T x^{(0)}) + 2x^{(0)} - x \\ &= 2vv^T x - x + 2x^{(0)} - 2vv^T x^{(0)} \\ &= (2vv^T - I)x + 2(I - vv^T)x^{(0)} \end{aligned}$$

$$f(x) = (2P-I)x + 2(I-P)x^{(0)}$$

b) The shift we have to make to obtain the reflection if instead of reflecting x on $A = \{x^{(0)} + \lambda v, \lambda \in \mathbb{R}\}$, we reflect $y - x^{(0)}$ across $S = \{\lambda v, \lambda \in \mathbb{R}\}$.

c) Linear function: $f(\alpha x) = \alpha f(x)$

$$f(\alpha_1 x_1 + \alpha_2 x_2) = \alpha_1 f(x_1) + \alpha_2 f(x_2)$$

$$f(\alpha x) = (2P-I)\alpha x + 2(I-P)x^{(0)} = \alpha[(2P-I)x] + 2(I-P)x^{(0)}$$

$$f(x_1 + x_2) = (2P-I)(x_1 + x_2) + 2(I-P)x^{(0)} = (2P-I)x_1 + (2P-I)x_2 + 2(I-P)x^{(0)}$$

If line passes through origin ($x^{(0)} = 0$):

$$f(\alpha x) = \alpha[(2P-I)x] = \alpha f(x)$$

$$f(x_1 + x_2) = [(2P-I)x_1] + [(2P-I)x_2] = f(x_1) + f(x_2)$$

If linear fn:

$$f(\alpha x) = \alpha[(2P-I)x] + 2(I-P)x^{(0)} = \alpha[(2P-I)x + 2(I-P)x^{(0)}] = \alpha(2P-I)x + 2\alpha(I-P)x^{(0)}$$

$$2(\alpha-1)(I-P)x^{(0)} = 0 \quad \forall x \in \mathbb{R}$$

$$2(1-\alpha)(I-P)x^{(0)} = 0 \quad \text{and } 1-\alpha \neq 0, \text{ so must have } x^{(0)} = 0.$$

$$\text{and } f(x_1 + x_2) = f(x_1) + f(x_2) \Rightarrow 2(I-P)x^{(0)} = 2(I-P)x^{(0)} \Rightarrow (I-P)x^{(0)} = 0$$

$$(I-P)x^{(0)} = 0 \Rightarrow x^{(0)} = Px^{(0)} \Rightarrow x^{(0)} = vv^T x^{(0)} = (v^T v^{(0)})v \Rightarrow x^{(0)} = 2v, \text{ i.e. } x^{(0)} \in L$$

$$L = \{x^{(0)} + \lambda v, \lambda \in \mathbb{R}\} = \{cv + \lambda v, \lambda \in \mathbb{R}\} = \{(c+\lambda)v, \lambda \in \mathbb{R}\}$$

$$d) f(x) = 2p(x) - x = (2P-I)x + 2(I-P)x^{(0)}$$

$$f(f(x)) = (2P-I)[(2P-I)x + 2(I-P)x^{(0)}] + 2(I-P)x^{(0)}$$

$$= (4PP - 2P - 2P + I)x + 2(2P - 2PP - I + P)x^{(0)} + 2(I-P)x^{(0)}$$

$$= PP - 2P + Ix + 2(2P - 2PP - I + P)x^{(0)} + 2(I-P)x^{(0)}$$

$$= (QP - 2P + I)x + 2(2P - 2PP - I + P)x^{(0)} + 2(I-P)x^{(0)}$$

$$= x + 2(P-I)x^{(0)} + 2(I-P)x^{(0)} = x$$

(geometrically, reflecting then reflecting back along same line leaves x unchanged)

3) Let $\{u^1, \dots, u^m\}$ be orthonormal basis for subspace orthogonal to U_1 .

For each of these vectors, $u^{(i)} \perp v$, we have:

$$Av = (2uv^T - I)v = 2uv^T v - v = 2(u^T v)v - v = 2(v^T v)v - v = 0 \Rightarrow v \perp Av.$$

Now, $\|v\|=1$, and

$$Av = (2uv^T - I)v = 2(u^T v)v - v = 2v - v = v \Rightarrow \lambda = 1$$

Now, let's prove A is symmetric. This is easy:

$$A = 2uv^T - I$$

$$A^T = (2uv^T - I)^T = 2(u^T)^T v^T - I^T = 2uv^T - I = A \Rightarrow A \text{ symmetric.}$$

Now, since A is symmetric, eigenvectors across eigenvalues are orthogonal. So,

$U = [v, u^1, \dots, u^m]$ is an orthogonal matrix (orthogonal and normalized columns).

So we can write spectral decomposition as:

$$A = U \Lambda U^T$$

where $U = [v, u^1, \dots, u^m]$ and $\Lambda = \text{diag}(1, -1, -1, \dots, -1)$

f) For any vector on line $\mathcal{I} = \mathbb{R}v$, reflecting will keep it unchanged, so $\lambda = 1$.

For any vector orthogonal to line, reflecting will flip it, so $\lambda = -1$.

3.5) $A \in \mathbb{S}_n^+$ PSD $\Rightarrow \lambda \geq 0$

$$A = U \Lambda U^T$$

$$= [v, u^1, \dots, u^m] \begin{bmatrix} -\lambda_1 & & \\ & -\lambda_2 & \\ & & \ddots \\ & & & -\lambda_m \end{bmatrix}$$

$$= \lambda_1 v v^T + \lambda_2 u^1 u^1 + \dots + \lambda_m u^m u^m$$

$$\text{trace}(U \Lambda U^T) = \|U\|^2$$

$$\text{trace}(A) = \lambda_1 \|v\|^2 + \lambda_2 \|u^1\|^2 + \dots + \lambda_m \|u^m\|^2$$

$= \lambda_1 + \lambda_2 + \dots + \lambda_m$ since $\|U\|=1$ (spectral decomposition, orthogonal matrix)

$$\text{trace}(A) = \sum_i \lambda_i = \|A\|_F$$

since $A \geq 0$

$$\|A\|_F^2 = \langle A, A \rangle = \text{trace}(A^T A) = \text{trace}((U \Lambda U^T)^T U \Lambda U^T) = \text{trace}(U \Lambda^2 U^T) = \text{trace}(U^T \Lambda^2 U)$$

$$= \text{trace}(U \Lambda^2 U^T)$$

$$= \|A\|_F^2 = \boxed{\text{trace}(U \Lambda^2 U^T) \Rightarrow \|A\|_F = \sqrt{\sum_{i=1}^n \lambda_i^2} = \|A\|_F}$$

② The family motto

1931年1月2日

Catching: 10 Aug 1965 (Kodak 35 mm)

Frauen

$$(U^T V)^2 \leq \|u\|_2^2 \|v\|_2^2$$

So we pick $u = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$ and $v = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$, i.e. $v_i = 1$ if $u_i > 0$, $v_i = 0$ if $u_i = 0$ (PSD \Rightarrow each $v_i \geq 0$)

$$\text{Then: } u^T v = \tilde{\Phi}^T v = [1, 1, \dots, 1, 1, 1, 1, \dots, 1] \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \sum_{i=1}^6 \lambda_i = \sum_{i=1}^6 \lambda_i \text{ (since } \lambda_{6+1} = \lambda_{7+1}) \\ = \|\tilde{\Phi}\|_1.$$

$$\text{And } \|u\|^2 = \sum_{i=1}^n x_i^2 = \|\vec{x}\|^2.$$

$$\|v\|^2 = \sum_{i=1}^k 1^2 = k$$

Now, notice that k , the number of non-zero eigenvalues, is same as $\text{rank}(A) = \# \text{non-zero eigenvalues (or be repeated)}$. So:

$$|U^T v|^2 \leq \|U\|_F^2 \|v\|^2$$

$$\|\vec{v}\|_1^2 \leq k \|\vec{v}\|^2$$

$\| \tilde{z} \|_1^2 \leq \text{rank}(A) \| \tilde{z} \|_1^2$, and we are done.

$$3.6) \text{ a) } X_c = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad P = \begin{bmatrix} 1.5 & -0.5 \\ -0.5 & 1.5 \end{bmatrix}$$

$$\det \begin{bmatrix} \frac{3}{2}\lambda & -\frac{1}{2} \\ -\frac{1}{2} & \frac{3}{2}\lambda - 1 \end{bmatrix} = \left(\frac{3}{2}\lambda\right)^2 - \frac{1}{4} =$$

$$(x - \frac{3}{2})^2 = \frac{1}{4}$$

$$\lambda - \frac{3}{2} = \pm \frac{1}{2} \Rightarrow \lambda = \frac{3}{2} \pm \frac{1}{2}$$

$$\lambda_1=2, \lambda_2=1$$

$$\begin{bmatrix} \frac{3}{2} & -\frac{1}{2} \\ -\frac{1}{2} & \frac{3}{2} \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix} \quad \frac{3}{2}x - \frac{1}{2}y = 2x \Rightarrow x = -y \quad \begin{bmatrix} 1 \\ -1 \end{bmatrix} \xrightarrow{\text{normalize}} \begin{bmatrix} 1 \\ -\frac{1}{\sqrt{2}} \end{bmatrix}$$

$$\text{If } \lambda = 1 \Rightarrow v = y \Rightarrow \begin{bmatrix} \frac{y_1}{y_1} \\ \frac{y_2}{y_2} \end{bmatrix}$$

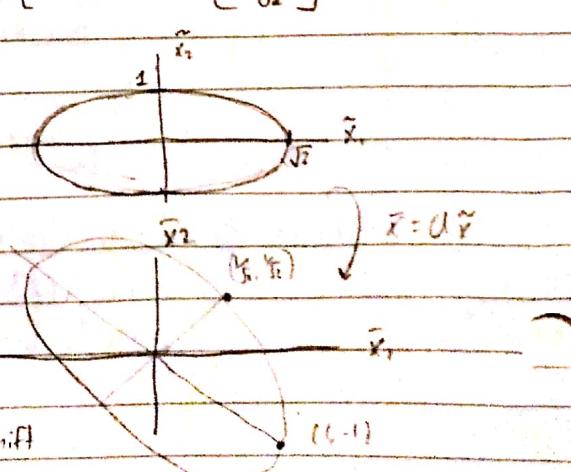
$$U = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{i}{\sqrt{2}} \\ -\frac{i}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \quad A = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\left(\frac{\tilde{x}_1}{\sqrt{s_1}} \right)^2 + \left(\frac{\tilde{x}_2}{\sqrt{s_2}} \right)^2 \leq 1 \Rightarrow \left(\frac{\tilde{X}_1}{\sqrt{2}} \right)^2 + \left(\frac{\tilde{X}_2}{\sqrt{1}} \right)^2 \leq 1$$

$$\tilde{X} = U \tilde{V}^T \quad \tilde{x} = \tilde{x}_1 + \tilde{x}_2, \quad \tilde{y} = \tilde{y}_1 u_1 + \tilde{y}_2 u_2$$

$$\hat{x} = \begin{bmatrix} \hat{x}_1 \\ \hat{x}_2 \end{bmatrix}; \quad \hat{x} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$Y_1 = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow \text{no shift}$$



$$b) \quad x = \begin{bmatrix} 1 \\ -1 \end{bmatrix} \quad p = \begin{bmatrix} 3 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\det \left(\begin{bmatrix} 3 & 2 & 0 \\ 0 & 1 & 2 \end{bmatrix} \right) = 0 \Rightarrow (2-3)(2-1) = 0 \quad 2+1, 2+3$$

$$\begin{bmatrix} 3 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

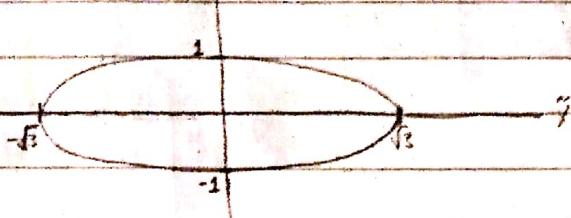
$$3x + y = 1$$

$$\begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 3 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 3 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

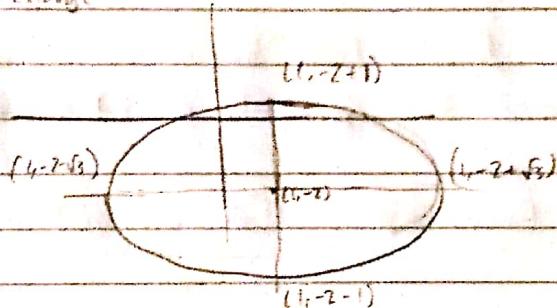
$$U = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \Rightarrow \Delta = \begin{bmatrix} 3 & 0 \\ 0 & 1 \end{bmatrix} \quad (2, 3, 2, 1)$$

$$\left(\frac{x_1}{\sqrt{3}}\right)^2 + \left(\frac{x_2}{\sqrt{1}}\right)^2 \leq 1$$



$$\tilde{v} = 0x = 1 \rightarrow no change$$

$$v_c = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \rightarrow shift$$



$$c) \quad x_c = \begin{bmatrix} -2 \\ 1 \end{bmatrix} \quad p = \begin{bmatrix} 9 & -2 \\ -2 & 6 \end{bmatrix}$$

$$\det \left(\begin{bmatrix} 9 & -2 \\ -2 & 6 \end{bmatrix} \right) = (9-9)(2-6) - 4 = 0$$

$$2^2 - 16 + 50 = 0$$

$$(2, 10)(2, 5) = 0$$

$$x_1 = 10 \quad \begin{bmatrix} 9 & -2 \\ -2 & 6 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 10 \\ 5y \end{bmatrix} \rightarrow 9x - 2y = 10x \rightarrow 3x = -2y$$

$$x_2 = 5 \quad \begin{bmatrix} 9 & -2 \\ -2 & 6 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 5 \\ 5y \end{bmatrix} \rightarrow 9x - 2y = 5x \rightarrow 2y = 4x \rightarrow y = 2x$$

$$U = \begin{bmatrix} -2\sqrt{5} & \sqrt{5} \\ \sqrt{5} & 2\sqrt{5} \end{bmatrix} \quad \Delta = \begin{bmatrix} 10 & 0 \\ 0 & 5 \end{bmatrix}$$

$$\left(\frac{x_1}{\sqrt{10}}\right)^2 + \left(\frac{x_2}{\sqrt{5}}\right)^2 \leq 1 \Rightarrow \left(\frac{x_1}{\sqrt{10}}\right)^2 + \left(\frac{x_2}{\sqrt{5}}\right)^2 \leq 1$$

$$\tilde{x} = U \tilde{v} \quad U \begin{bmatrix} 5 \\ 0 \end{bmatrix} = \sqrt{10} \begin{bmatrix} -2\sqrt{5} \\ \sqrt{5} \end{bmatrix} = \begin{bmatrix} -2\sqrt{2} \\ \sqrt{2} \end{bmatrix}$$

$$U \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \sqrt{5} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\begin{bmatrix} ? \\ ? \end{bmatrix}, \begin{bmatrix} ? \\ ? \end{bmatrix}, \begin{bmatrix} -2\sqrt{2} \\ \sqrt{2} \end{bmatrix}$$

$$\begin{bmatrix} -2 \\ 1 \end{bmatrix}$$



$$\begin{bmatrix} -2 \\ 1 \end{bmatrix} \xrightarrow{\text{normalize}} \begin{bmatrix} -2 \\ 1 \end{bmatrix}$$



$$\begin{bmatrix} 2\sqrt{5} \\ 0 \end{bmatrix}$$

shift

$$\begin{bmatrix} 1 \\ 2 \end{bmatrix} - \begin{bmatrix} -2\sqrt{2} \\ \sqrt{2} \end{bmatrix}$$

d) If any λ_i is $= 0$, then A is not invertible. Thus, there exists a mapping from \mathbb{R}^n to \mathbb{R} . If x is eigenvector with $\lambda=0$, then all points λx map to 0, since this dimension. The volume of a n -dimensional hypercube in n -dimensions is 0, so $\det A = 0$ when $\lambda = 0$.

3.7) a) $f_1 = 2x + 3y + 1$

$$\nabla f_1 = \begin{bmatrix} \frac{\partial f_1}{\partial x} \\ \frac{\partial f_1}{\partial y} \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

$$f_1: x^2 + y^2 - xy - 5$$

$$\frac{\partial f_1}{\partial x} = 2x - y$$

$$\frac{\partial f_1}{\partial y} = 2y - x$$

$$\nabla^2 f_1 = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$\nabla f_2 = \begin{bmatrix} 2x & y \\ 2y & x \end{bmatrix}$$

$$\nabla^2 f_2 = \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix}$$

$$f_2 = (x - 5) \cos(y - 5) - (y - 5) \sin(x - 5)$$

$$\frac{\partial f_2}{\partial x} = \cos(y - 5) - (y - 5) \cos(x - 5)$$

$$\frac{\partial f_2}{\partial y} = -(x - 5) \sin(y - 5) - \sin(x - 5)$$

$$\nabla f_3 = \begin{bmatrix} \cos(y - 5) - (y - 5) \cos(x - 5) \\ -(x - 5) \sin(y - 5) - \sin(x - 5) \end{bmatrix}$$

$$\nabla^2 f_3 = \begin{bmatrix} (y - 5) \sin(x - 5) & -\sin(y - 5) - \cos(x - 5) \\ -\sin(y - 5) - \cos(x - 5) & -(x - 5) \cos(y - 5) \end{bmatrix}$$

b) See Matlab code

c) See Matlab code

d) Approximations are perfect for f_1 and f_2 because they are linear and quadratic, respectively.

For f_3 , approximation is reasonable around approximation point, but not further away from approximation point.

3.8) a) Sum of transition probabilities from one page to all others must be 1. This makes sense. At every step we have to move to new page.

b) See MATLAB code

c) See MATLAB code

Generally speaking, my code matches Figure 7.1 in OptIM

d) See MATLAB

Mean: Average / resources / ips... -

Makes sense \rightarrow recent want tracers library resources ; shared value amongs people

Mr. things people don't commonly need

Maximum Indices: 303, 731, 732, 733, 735

Minimum Indices: 479, 7459, 930, 986, 987

I used indices of last method (Rayleigh Quotient) because it gave least error. It got negative ranks but maybe that's ok since it's a different method than power iteration

Mr. Page Ranks: 0.0431 (all)

Min Page Rnk: -0.4979, -0.7698, -0.7843, -0.7790, -0.7240

```

x = linspace(-2, 3.5, 50);
y = linspace(-2, 3.5, 50);
[X,Y] = meshgrid(x,y);
z = @(x,y) 2.*x+3.*y+1;
Z = z(X,Y);
[px,py] = gradient(Z);
figure
[c,h]=contour(X,Y,Z,-5:1:5);
hold on
fimplicit(@(x,y) 2.*x + 3.*y - 2, [-2 3.5 -2 3.5])
plot(1,0,'r.')
hold on
quiver(X,Y,px,py)

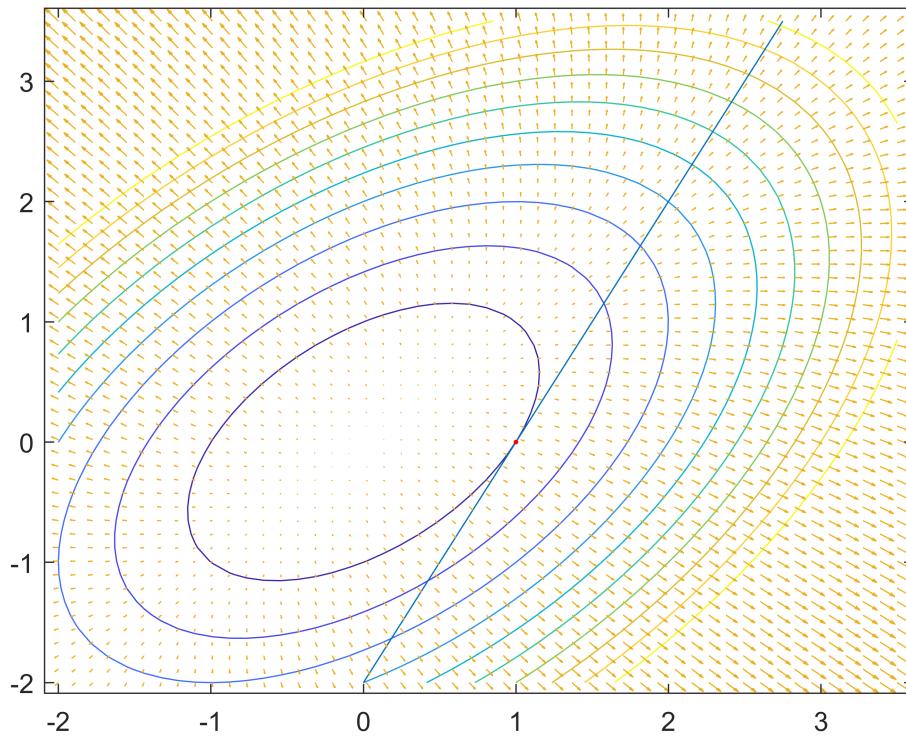
```



```

x = linspace(-2, 3.5, 50);
y = linspace(-2, 3.5, 50);
[X,Y] = meshgrid(x,y);
z = @(x,y) x.^2+y.^2-x.*y-5;
Z = z(X,Y);
[px,py] = gradient(Z);
figure
[c,h]=contour(X,Y,Z,-5:1:5);
hold on
fimplicit(@(x,y) 2.*x - y - 2, [-2 3.5 -2 3.5])
plot(1,0,'r.')
hold on
quiver(X,Y,px,py)

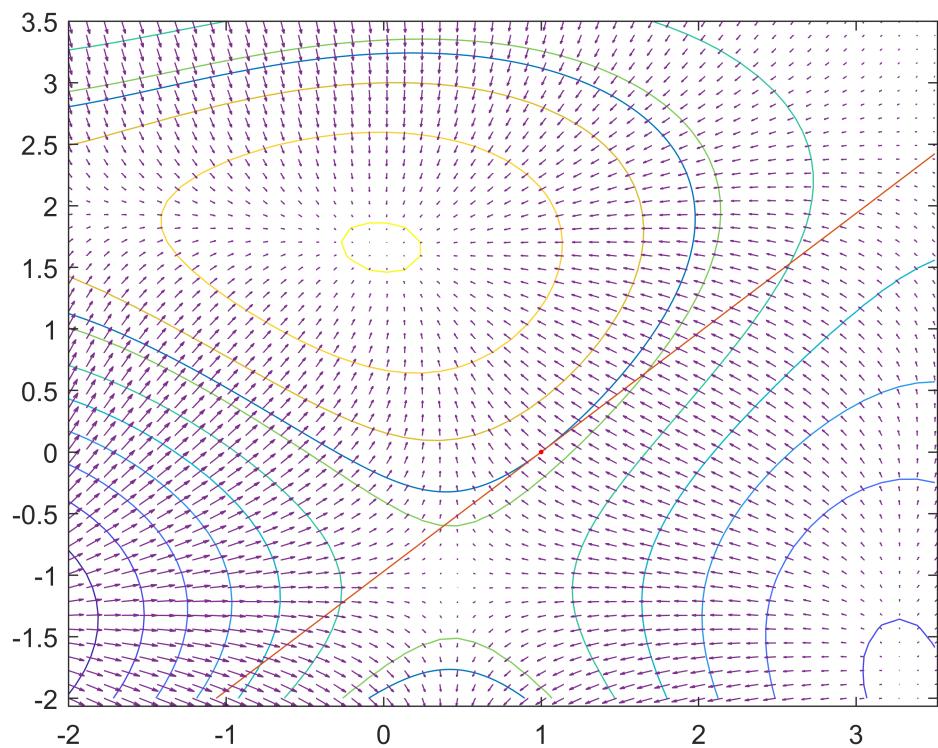
```



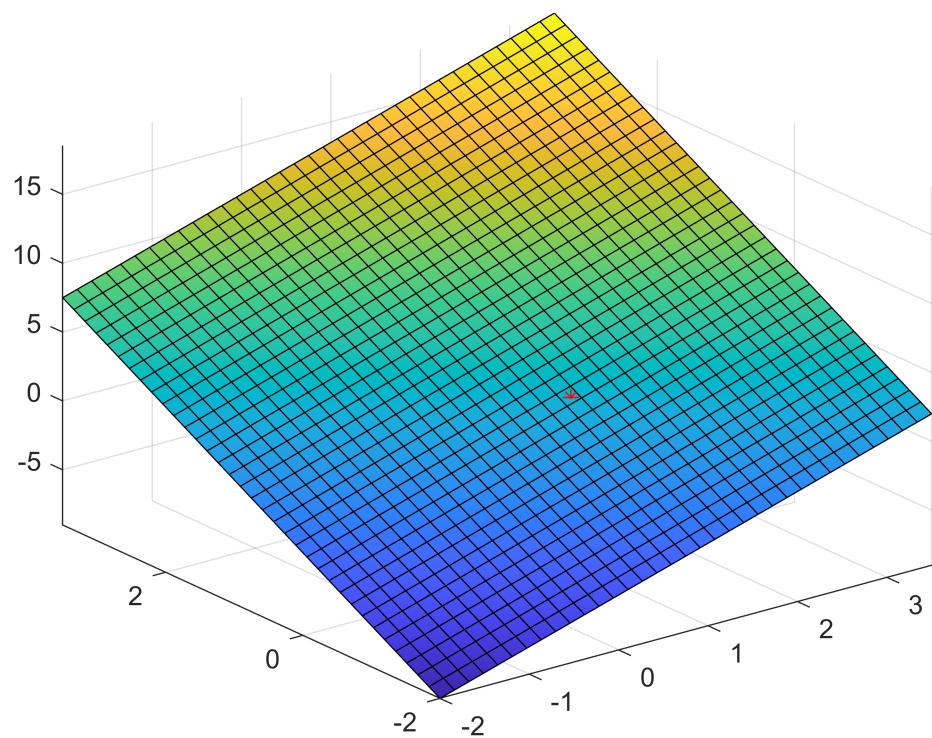
```

x = linspace(-2, 3.5, 50);
y = linspace(-2, 3.5, 50);
[X,Y] = meshgrid(x,y);
z = @(x,y) (x-5).*cos(y-5) - (y-5).*sin(x-5);
Z = z(X,Y);
[px,py] = gradient(Z);
figure
contour(X,Y,Z);
hold on
fimplicit(@(x,y) (x-5).*cos(y-5) - (y-5).*sin(x-5) + 4.*cos(5) + 5.*sin(4), [-2 3.5 -2 3.5])
fimplicit(@(x,y) (x-1)*(cos(5)+5*cos(4)) + y*(sin(4)-4*sin(5)), [-2 3.5 -2 3.5])
plot(1,0,'r.')
hold on
quiver(X,Y,px,py)

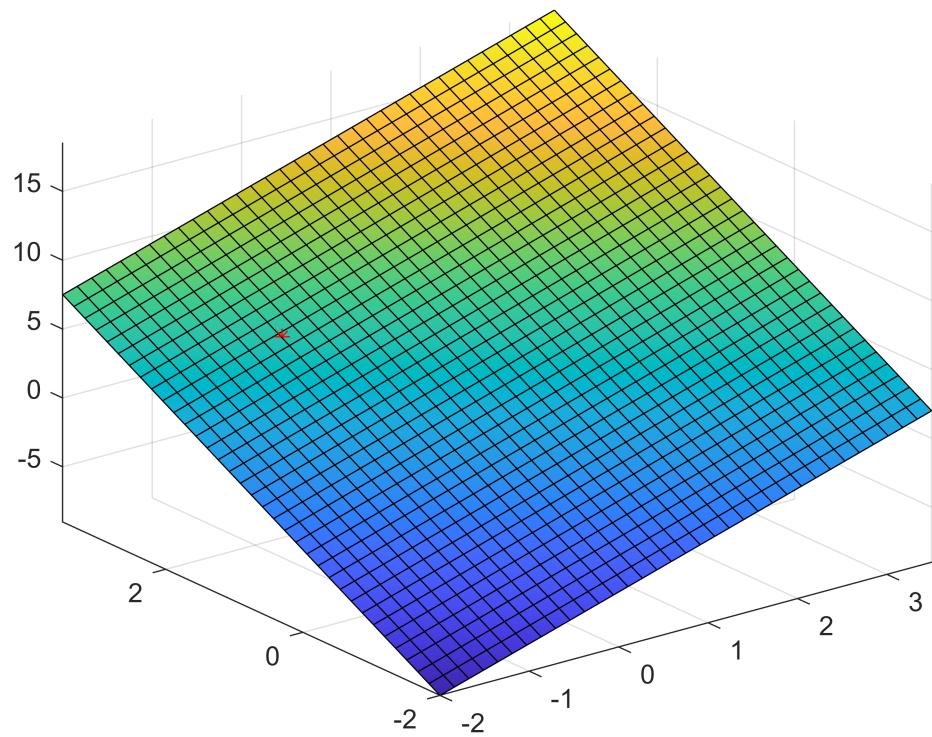
```



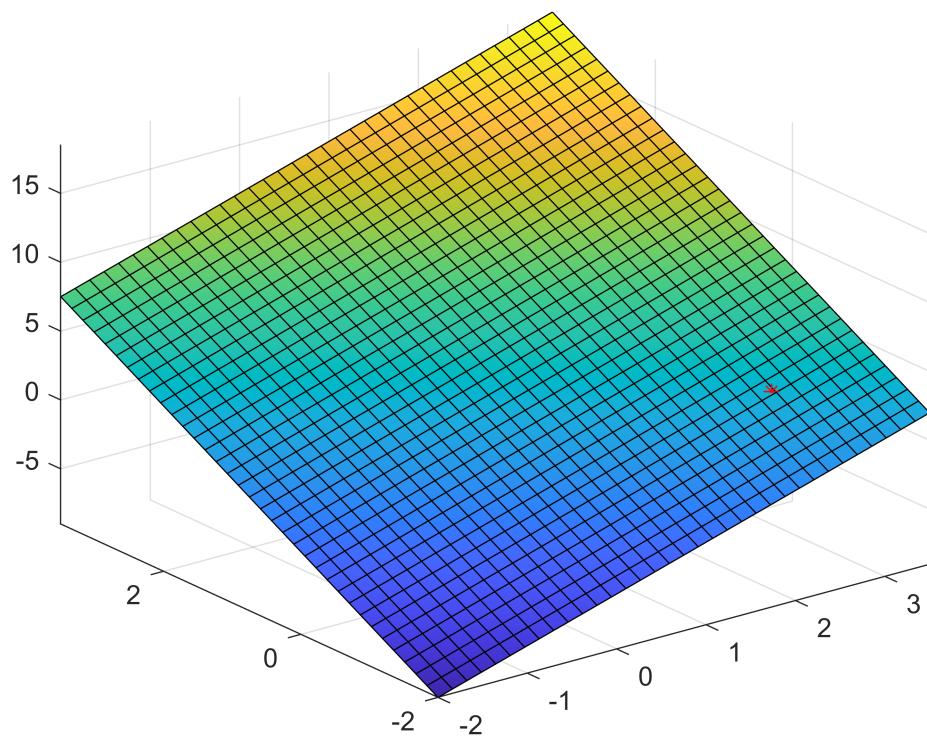
```
syms f1(x,y)
f1(x,y) = 2*x + 3*y + 1;
figure;
drawquadraticapprox(f1, 1, 0)
```



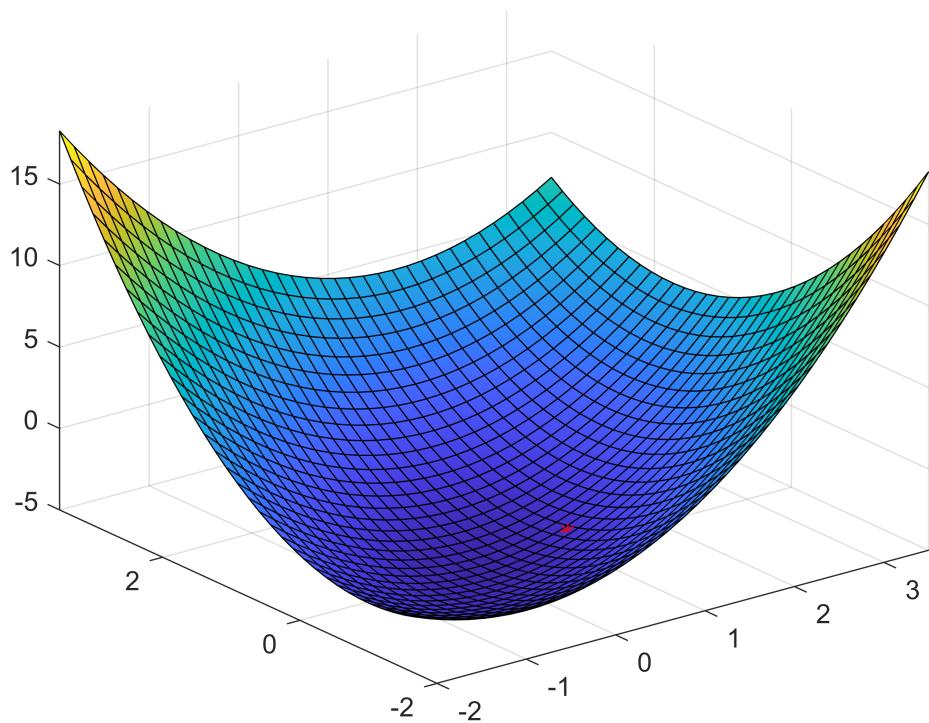
```
figure;
drawquadraticapprox(f1, -0.7, 2)
```



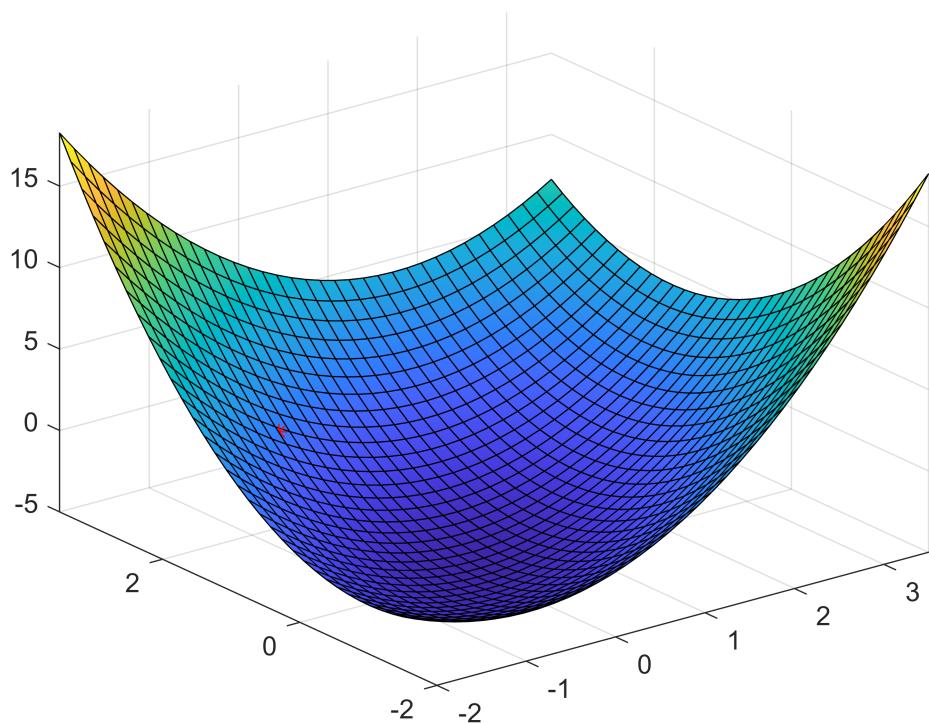
```
figure;  
drawquadraticapprox(f1, 2.5, -1)
```



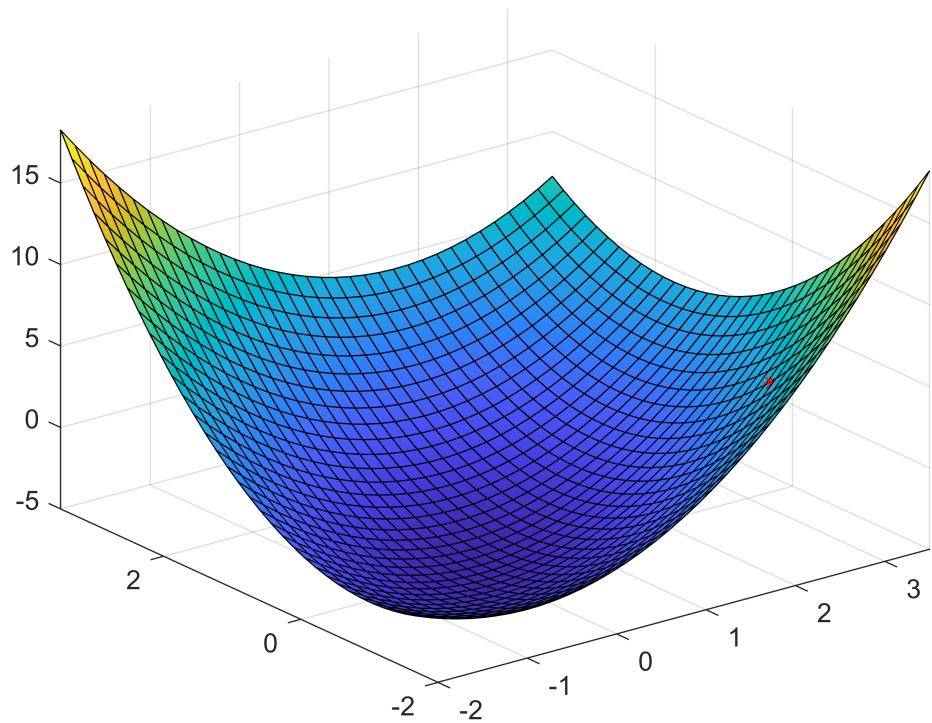
```
syms f2(x,y)  
f2(x,y) = x^2 + y^2 -x*y - 5;  
figure;  
drawquadraticapprox(f2, 1, 0)
```



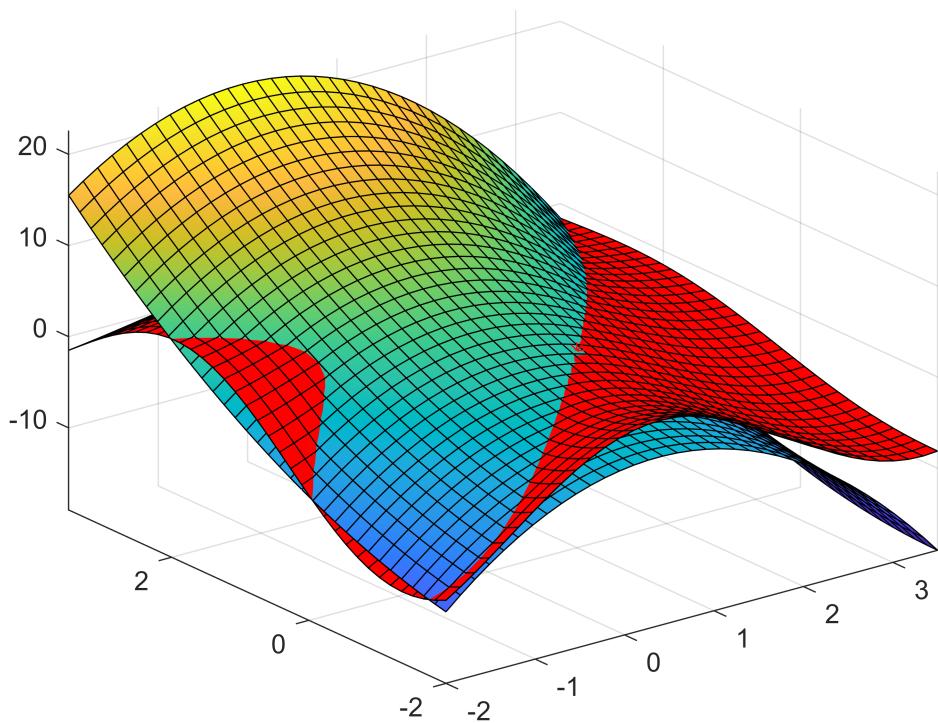
```
figure;
drawquadraticapprox(f2, -0.7, 2)
```



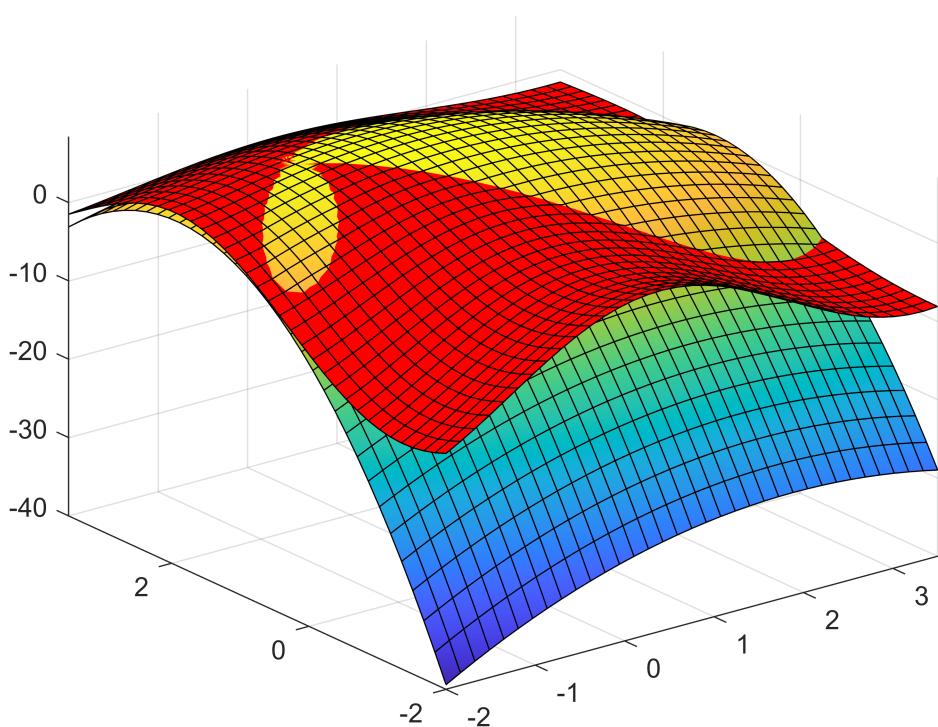
```
figure;
drawquadraticapprox(f2, 2.5, -1)
```



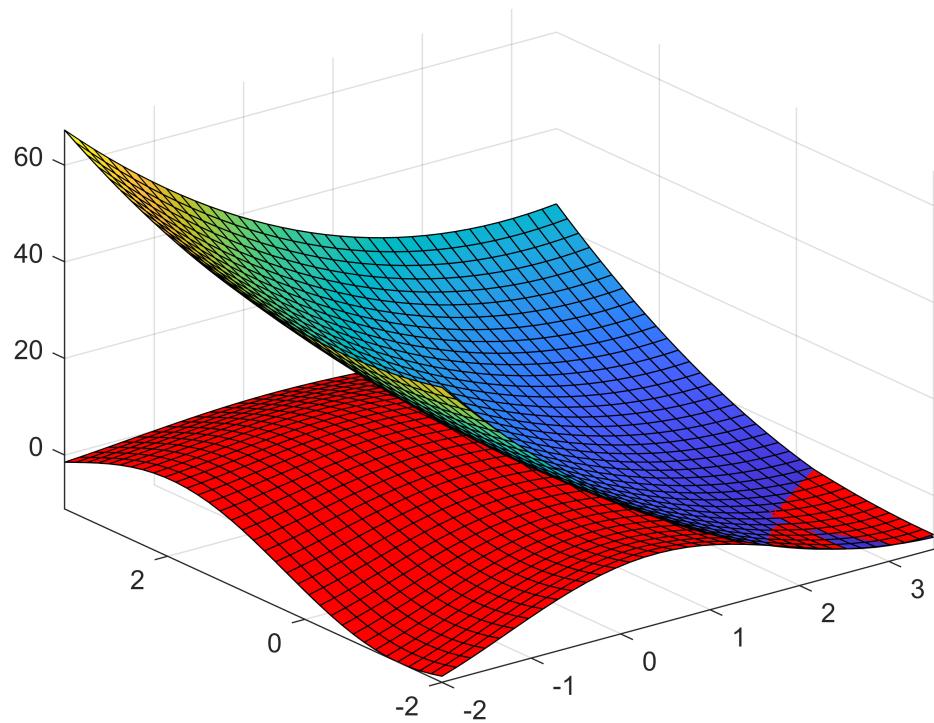
```
syms f3(x,y)
f3(x,y) = (x - 5).*cos(y - 5) - (y - 5).* sin(x - 5);
figure;
drawquadraticapprox(f3, 1, 0)
```



```
figure;  
drawquadraticapprox(f3, -0.7, 2)
```



```
figure;
drawquadraticapprox(f3, 2.5, -1)
```



```
function drawquadraticapprox(f, x0, y0)
grad = gradient(f);
hess = hessian(f);

syms approx(x, y)
approx(x,y) = f(x0,y0) + grad(x0, y0)' * [x-x0; y-y0] + 0.5 * [x-x0; y-y0]' * hess(x0, y0)

fsurf(f,[-2 3.5 -2 3.5], 'r')
hold on
fsurf(approx,[-2 3.5 -2 3.5])
plot3(x0,y0,f(x0,y0), 'r*')
end
```

```

load pagerank_adj.mat
A = zeros(size(J));
for i = 1:length(J)
    A(:,i) = J(:,i)/sum(J(:,i));
end

x1(:,1) = ones(length(A), 1);
k = 1;
x1(:,1) = x1(:,1)/norm(x1(:,1));
for i = 1:10
    y(:,k) = A*x1(:,k);
    x1(:,k+1) = y(:,k)/norm(y(:,k));
    lambda(k) = x1(:,k+1)' * A * x1(:,k+1);
    e1(k) = norm(A*x1(:,k)-x1(:,k));
    k = k + 1;
end
[maxis,maxidx] = maxk(x1(:,end),5)

```

```

maxis = 5x1
0.4394
0.3296
0.3073
0.2996
0.2751
maxidx = 5x1
2
35
36
58
49

```

```
[minis,minidx] = mink(x1(:,end),5)
```

```

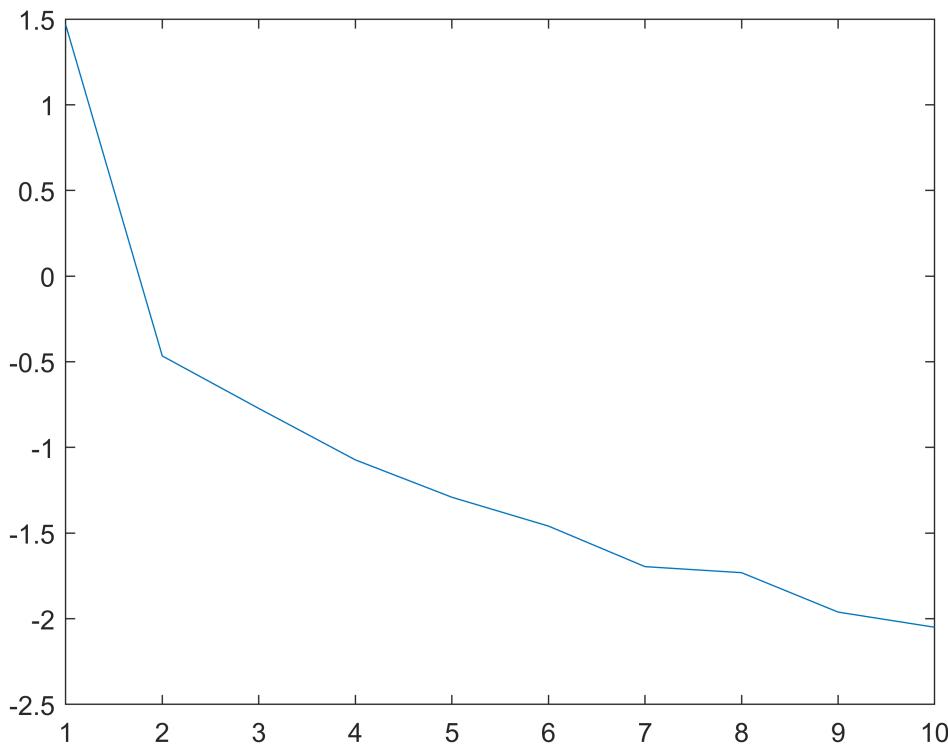
minis = 5x1
0
0
0
0
0
minidx = 5x1
1
3
4
5
10

```

```

figure;
plot(log(e1))

```



```

x2(:,1) = ones(length(A), 1);
k = 1;
sigma = 0.99;
x2(:,1) = x2(:,1)/norm(x2(:,1));
for i=1:10
    y(:,k) = (A-sigma*eye(length(A))) \ x2(:,k);
    x2(:,k+1) = y(:,k)/norm(y(:,k));
    lambda(k) = x2(:,k+1)' * A * x2(:,k+1);
    e2(k) = norm(A*x2(:,k)-x2(:,k));
    k = k + 1;
end
[maxis,maxidx] = maxk(x2(:,end),5)

```

```

maxis = 5×1
0.3711
0.3184
0.2975
0.2904
0.2637
maxidx = 5×1
2
35
36
58
49

```

```
[minis,minidx] = mink(x2(:,end),5)
```

```
minis = 5×1
```

```

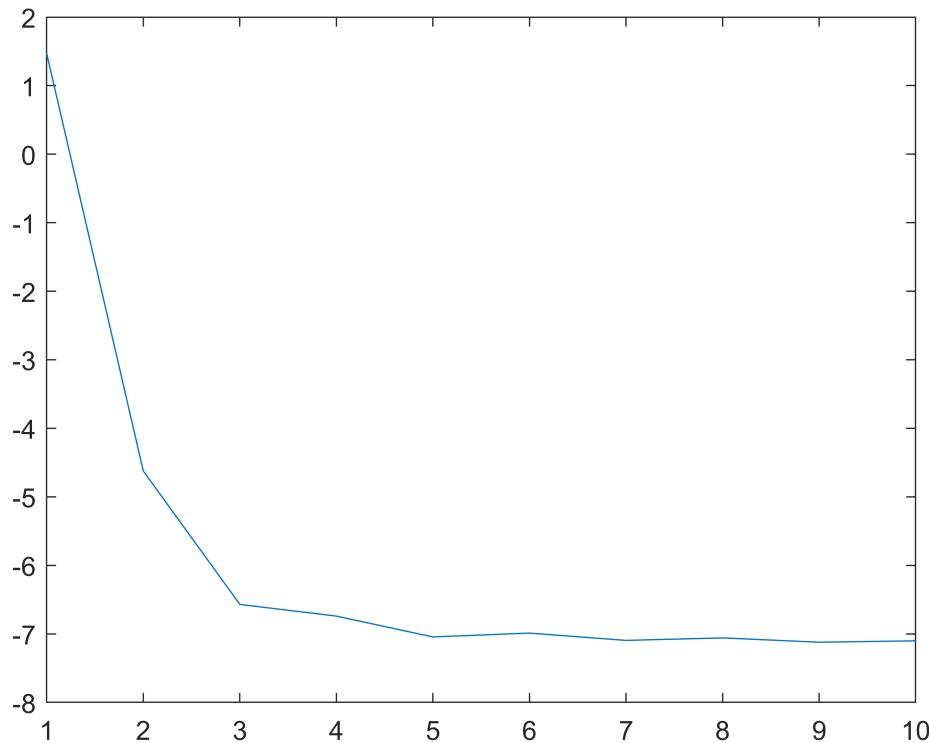
-0.3196
-0.1602
-0.1602
-0.1200
-0.0917
minidx = 5x1
424
987
986
985
930

```

```

figure;
plot(log(e2))

```



```

x3(:,1) = ones(length(A), 1);
k = 1;
x3(:,1) = x3(:,1)/norm(x3(:,1));
for i=1:10
    if i==1 || i==2
        sigma = 0.99;
    else
        sigma = (x3(:,k)' * A * x3(:,k))/(x3(:,k)' * x3(:,k));
    end
    y(:,k) = (A-sigma*eye(length(A))) \ x3(:,k);
    x3(:,k+1) = y(:,k)/norm(y(:,k));
    e3(k) = norm(A*x3(:,k)-x3(:,k));
    k = k + 1;
end

```

```
Warning: Matrix is close to singular or badly scaled. Results may be inaccurate. RCOND =  6.476301e-17.
Warning: Matrix is close to singular or badly scaled. Results may be inaccurate. RCOND =  6.021051e-18.
```

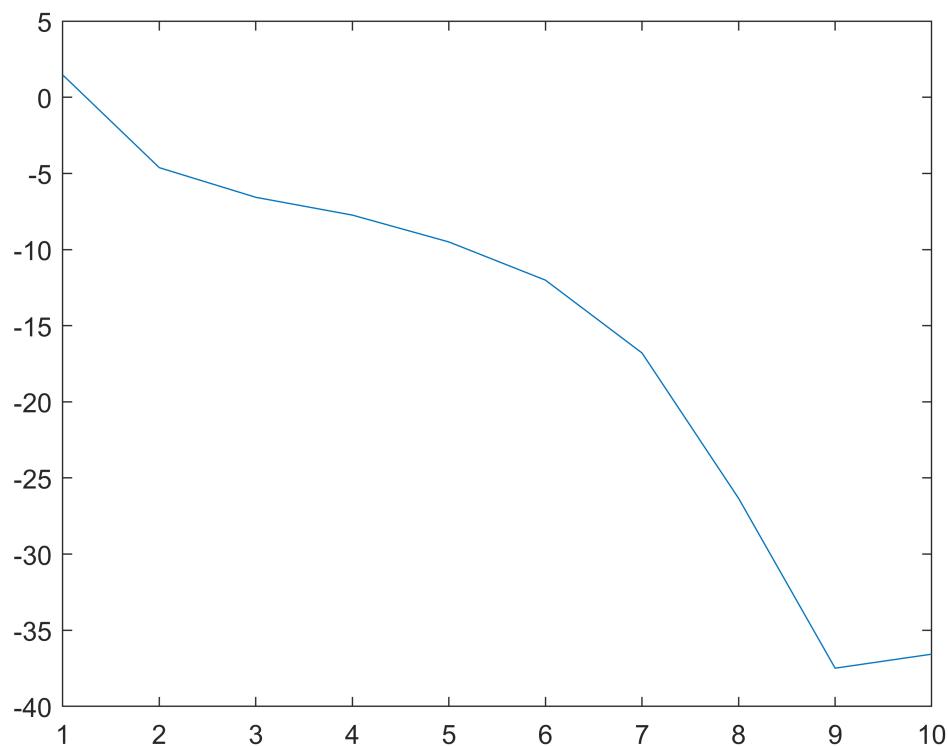
```
[maxis,maxidx] = maxk(x3(:,end),5)
```

```
maxis = 5x1
0.0432
0.0432
0.0432
0.0432
0.0432
maxidx = 5x1
303
731
732
733
735
```

```
[minis,minidx] = mink(x3(:,end),5)
```

```
minis = 5x1
-0.4479
-0.2648
-0.2593
-0.2240
-0.2240
minidx = 5x1
424
2459
930
986
987
```

```
figure;
plot(log(e3))
```



```
figure;
plot(log(e1))
hold on
plot(log(e2))
hold on;
plot(log(e3))
legend('power iteration', 'shift inversion', 'rayleigh quotient')
```

