

Assignment 3

3.1 Defⁿ: a is a subgradient of f at x if
$$f(y) \geq f(x) + a^T(y-x) \quad \forall y$$

* Similarly, since the dual function g is concave,
 a is a supergradient of g at x if
$$g(y) \leq g(x) + a^T(y-x) \quad \forall y.$$

$$\begin{array}{ll} \text{minimize} & f(w) \\ \text{s.t} & Aw = b \end{array}$$

Then,
$$g(\lambda) = \inf_w L(w, \lambda) = f(w) + \lambda^T(Aw - b)$$

Then, for $\lambda_0 \in \mathbb{R}^n$,
$$g(\lambda_0) = \inf_w f(w) + \lambda_0^T(Aw - b)$$

Let $w_{\lambda_0} = \operatorname{argmin}_w f(w) + \lambda_0^T(Aw - b)$

$$\Rightarrow g(\lambda_0) = f(w_{\lambda_0}) + \lambda_0^T(Aw_{\lambda_0} - b) \quad \text{--- (1)}$$

Similarly, ~~let~~ for any $\lambda \in \mathbb{R}^n$ let
 $w_\lambda = \operatorname{argmin}_w f(w) + \lambda^T(Aw - b)$

$$\Rightarrow g(\lambda) = f(w_\lambda) + \lambda^T(Aw_\lambda - b) \quad \text{--- (2)}$$

Group 3: Good!

Group 3: Might be good with some elaboration, such as by mentioning that f is convex and that g is the dual function corresponding to f .

Note that

$$g(\lambda) = \inf_W f(W) + \lambda^T (AW - b)$$

$$\leq f(W) + \lambda^T (AW - b) \text{ for all } W \quad (3)$$

$\therefore (3)$ is true for $W = W_{\lambda_0}$

$$\Rightarrow g(\lambda) \leq f(W_{\lambda_0}) + \lambda^T (AW_{\lambda_0} - b) \quad (4)$$

Then, substituting $f(W_{\lambda_0})$ using (1) in (4) gives

$$\begin{aligned} g(\lambda) &\leq g(\lambda_0) - \lambda_0^T (AW_{\lambda_0} - b) + \lambda^T (AW_{\lambda_0} - b) \\ &= g(\lambda_0) + (\lambda - \lambda_0)^T (AW_{\lambda_0} - b) \\ &= g(\lambda_0) + (AW_{\lambda_0} - b)^T (\lambda - \lambda_0) \end{aligned}$$

$\Rightarrow (AW_{\lambda_0} - b)$ is a supergradient of g at λ_0

$\therefore (AW - b) \in \partial g(\lambda)$
 \uparrow set of supergradients of g at λ

Group 3: Nice work!

3.2

~~Since f is smooth and strongly convex, g is also smooth and strongly convex.~~

Since f is L -smooth and μ -strongly convex, g is also smooth and strongly concave with constants $L_g = \frac{\lambda_{\max}(AA^T)}{\mu}$ and

$$M_g = \frac{\lambda_{\min}^+(AA^T)}{L}, \text{ respectively, where}$$

λ_{\max} is the maximum eigenvalue of AA^T and λ_{\min}^+ is the minimum nonzero eigenvalue of AA^T

(Above is a well-known theorem)

* Let $l(\lambda) = -g(\lambda)$ (the negative dual f^*)
Then $\nabla l(\lambda) = -\nabla g(\lambda)$

since l is L_g smooth, we have

$$l(\lambda_2) \leq l(\lambda_1) + \nabla l(\lambda_1)^T (\lambda_2 - \lambda_1) + \frac{L_g}{2} \|\lambda_2 - \lambda_1\|^2 \quad (1)$$

Let $\lambda_2 = \lambda^{k+1}$ and $\lambda_1 = \lambda^k$. Then

$$\lambda_2 - \lambda_1 = \lambda^{k+1} - \lambda^k = -\alpha_k \nabla l(\lambda^k), \quad (\because \lambda^{k+1} = \lambda^k - \alpha_k \nabla l(\lambda^k))$$

$\therefore (1) \Rightarrow$

$$l(\lambda^{k+1}) \leq l(\lambda^k) + \nabla l(\lambda^k)^T (-\alpha_k \nabla l(\lambda^k)) + \frac{L_g}{2} \alpha_k^2 \|\nabla l(\lambda^k)\|^2$$

Group 3: Good that you mentioned f is L -smooth and μ -strongly convex! Better too detailed than unclear :)

$$\Rightarrow l(\alpha^{k+1}) \leq l(\alpha^k) - \alpha_k \|\nabla l(\alpha^k)\| + \frac{L_g}{2} \alpha_k^2 \|\nabla l(\alpha^k)\|^2$$

$$\leq l(\alpha^k) - \alpha_k \|\nabla l(\alpha^k)\| + \frac{L_g}{2} \alpha_k \times \frac{1}{L_g} \|\nabla l(\alpha^k)\|^2$$

$$\text{for all } \alpha_k \leq \frac{1}{L_g}$$

$$= l(\alpha^k) - \frac{\alpha_k}{2} \|\nabla l(\alpha^k)\|^2 \quad \text{--- (2)}$$

Since ~~$l(\alpha)$~~ $l(\alpha)$ is strongly convex with constant m_g , we have that

$$\|\nabla l(\alpha^k)\|^2 \geq 2m_g (l(\alpha^k) - l(\alpha^*))$$

Then (3) \Rightarrow

$$l(\alpha^{k+1}) \leq l(\alpha^k) - \frac{\alpha_k}{2} \times 2m_g (l(\alpha^k) - l(\alpha^*))$$

$$= (1 - \alpha_k m_g) l(\alpha^k) + \alpha_k m_g l(\alpha^*)$$

$$\Rightarrow l(\alpha^{k+1}) - l(\alpha^*) \leq (1 - \alpha_k m_g) (l(\alpha^k) - l(\alpha^*)) \quad \text{--- (3)}$$

Let $\alpha_k = \alpha$ (constant step size).

Then by using recursive application of (3) we get

$$l(\alpha^k) - l(\alpha^*) \leq (1 - \alpha m_g)^k [l(\alpha^0) - l(\alpha^*)] \quad \text{--- (4)}$$

Group 3: Good use of equation references!

~~Here $1 - \alpha \mu_g$~~

Here $0 < 1 - \alpha \mu_g < 1$, since $0 < \alpha < \frac{1}{L_g}$
and $\mu_g \leq L_g$.

\therefore (4) $\Rightarrow h(x^k)$ converges to the optimal value $h(x^*)$ with a linear rate.

* The solution $w_{k+1} = \arg \min_w (L w, x_k)$

is primal feasible only when the algorithm converges to its optimal value.

In the intermediate iterations, the solution w_{k+1} is not ~~primal~~ feasible.

3.3

(P₂): minimize $\frac{1}{N} \sum f_i(w_i)$
s.t. $w_i = w_j \quad \forall j \in N_i, i \in [N]$

Write P₂ equivalently as

minimize $\frac{1}{N} \sum_{i \in [N]} f_i(w_i)$

s.t. $A_{ij}(w_i - w_j) = 0 \quad \forall j \in N_i, i \in [N]$

where $A = [a_{ij}]$ is a doubly stochastic matrix.

Group 3: Nice!

Group 3: Would be great if you can elaborate this a little bit.

Group 3: I suggest using the mobile app Scannable for better images.

Write (P_2) equivalently as

$$\text{minimize } \frac{1}{N} \sum_{i \in [N]} f_i(w_i)$$

$$\text{s.t. } a_{ij}(w_i - w_j) = 0 \quad \forall i \in N_i, \text{ where}$$

$A = [a_{ij}]$ is a doubly stochastic matrix compatible with an arbitrary undirected and connected graph.

Then adding all the constraints associated with each $i \in N_i$ gives us

$$\sum_{j \in N_i} a_{ij}(w_i - w_j) = 0$$

$$\Rightarrow \sum_{j \in N_i} a_{ij} w_i = \sum_{j \in N_i} a_{ij} w_j$$

$$\Rightarrow \left(\sum_{j \in N_i} a_{ij} \right) w_i = \sum_{j \in N_i} a_{ij} w_j$$

$$\Rightarrow w_i = \sum_{j \in N_i} a_{ij} w_j \quad \forall i \in [N]$$

Then (P_2) can reformulate as

$$\text{minimize } \frac{1}{N} \sum_{i \in N} f_i(w_i)$$

$$\text{s.t. } w_i - \sum_{j \in N_i} a_{ij} w_j = 0 \quad ; i \in [N]$$

Then ~~the~~ the dual funcⁿ of (P2) is

$$g(\lambda) = \inf_W \left[\sum_{i \in [N]} \frac{f_i(w_i)}{N} + \sum_{i \in [N]} \lambda_i^T \left(w_i - \sum_{j \in N_i} a_{ij} w_j \right) \right]$$

$$= \inf_W \left[\sum_{i \in [N]} \left\{ \frac{f_i(w_i)}{N} + \lambda_i^T \left(w_i - \sum_{j \in N_i} a_{ij} w_j \right) \right\} \right]$$

$$= \sum_{i \in [N]} \inf_{w_i} \left(\frac{f_i(w_i)}{N} + \lambda_i^T \left(w_i - \sum_{j \in N_i} a_{ij} w_j \right) \right)$$

Subproblems.

$$\left(w_i - \sum_{j \in N_i} a_{ij} w_j \right)$$

Then the corresponding ~~distributed~~ distributed dual ascent algorithm is

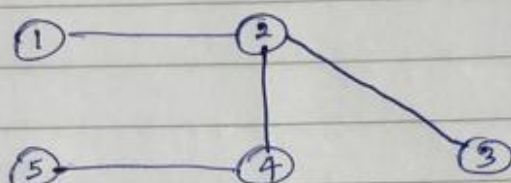
$$w_i^{(k+1)} = \underset{w_i}{\operatorname{argmin}} \frac{f_i(w_i)}{N} + \left(\lambda_i^T \right)^{(k)} \left(w_i - \sum_{j \in N_i} a_{ij} w_j \right)$$

Primal variable update $\Rightarrow w_i^{(k+1)} = \underset{w_i}{\operatorname{argmin}} \frac{f_i(w_i)}{N} + \left(\lambda_i^T \right)^{(k)} \left[(1 - a_{ii}) w_i - \sum_{j \in N_i - \{i\}} a_{ij} w_j^{(k)} \right]$

dual variable component update $\Rightarrow \lambda_i^{(k+1)} = \lambda_i^{(k)} + \alpha_k \left[\cancel{\lambda_i^T} (1 - a_{ii}) w_i^{(k+1)} - \sum_{j \in N_i - \{i\}} a_{ij} w_j \right]$

Comparison between the dual method and the primal method (numerically) ~~for~~ using a particular ~~→~~ connected and undirected graph.

We consider the following communication graph with 5 users.



We used:

* $f_i(W_i) = W_i^T B_i W_i + q_i^T W_i$, where $i=1,2,3,4,5$,
where B_i s are positive definite matrices.

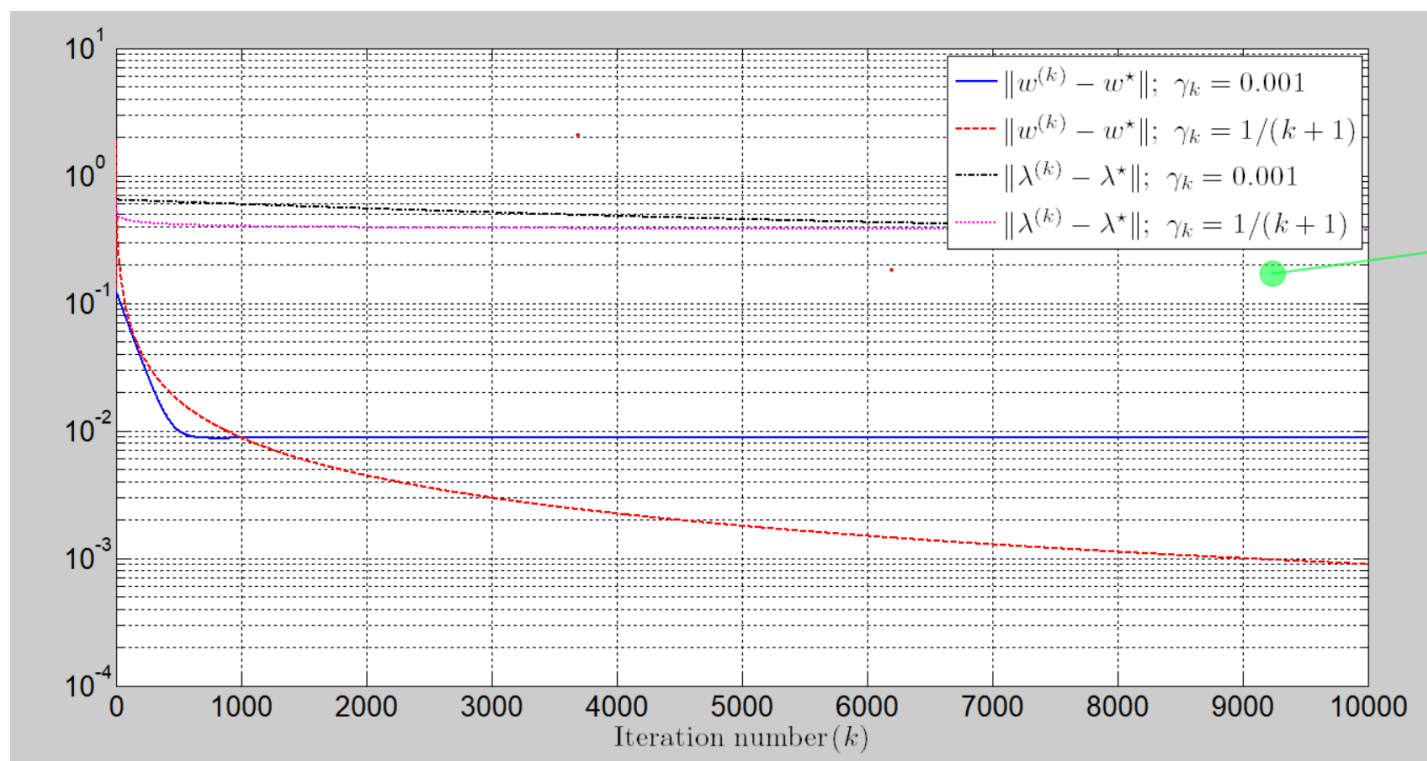
* $W_i \in \mathbb{R}$

* doubly stochastic matrix A is taken as

$$A = \begin{bmatrix} 0.75 & 0.25 & 0 & 0 & 0 \\ 0.25 & 0.25 & 0.25 & 0.25 & 0 \\ 0 & 0.25 & 0.75 & 0 & 0 \\ 0 & 0.25 & 0 & \frac{5}{12} & \frac{1}{3} \\ 0 & 0 & 0 & \frac{1}{3} & \frac{2}{3} \end{bmatrix}$$

Following figure shows the convergences of $\|W^{(k)} - W^*\|$ and $\|q^{(k)} - q^*\|$ using the primal method and the dual method, respectively.

Group 3: Would be great if you could add the code here.



Group 3: Would be great if you can add the name of each method in the legend!

According to the graph, for this particular case, the primal method shows better convergences than the dual method. For constant step size, the primal method ~~shows~~ clearly shows a linear rate of convergence. However, with constant stepsize, $w^{(k)}$ seems to converge into a neighbourhood of w^* , while with nonsummable and square summable stepsize ~~($\alpha_k = 1/(k+1)$)~~ ($\alpha_k = 1/(k+1)$) ~~$w^{(k)}$~~ $w^{(k)}$ converges more towards the optimal solution w^* .

In both methods, at every iteration, each ~~the~~ users ~~communication with~~ communicate only with ~~its~~ ~~its~~ its neighbours. \therefore the communication cost in both methods ~~per iteration~~ are same, per iteration.

Group 3: Good work in overall! :)