

Hsiang-Wei (Eddie) Huang

hsiangwei0903@gmail.com

Last update : March 22, 2025

SUMMARY

I am a Ph.D. student at the University of Washington. I work in the information processing lab advised by Prof. Jenq-Neng Hwang. My current research focuses on **Vision Language Models**, **Large Language Models** and **3D Understanding**. See more on my [website](#).

EDUCATION

University of Washington Mar 2023 – Expected 2026 | Seattle
PhD in Electrical and Computer Engineering

University of Washington Sep 2021 – Mar 2023 | Seattle
Master of Science in Electrical and Computer Engineering

National Chiao Tung University Sep 2017 – Dec 2020 | Taiwan
Bachelor of Science

WORK EXPERIENCE

Applied Scientist Intern Jun 2025 – Sep 2025
Amazon Lab 126 Bellevue, WA

- I will join the Amazon Lab 126 this summer for another year of applied scientist internship.

Applied Scientist Intern Jun 2024 – Sep 2024
Amazon Lab 126 Bellevue, WA

- Work on 3D scene understanding Large Language Models (LLMs) with the Visual Perception team.
- Proposed a LLM token compression method that achieve SOTA performance on various 3D understanding benchmarks.
- One first-author paper accepted at CVPR 2025.

Research Assistant Mar 2022 – Current
University of Washington Seattle, WA

- Work on various research topics and projects with multiple publication records in object detection, tracking, counting, human action recognition, pose estimation, diffusion model, vision-language model, 3D understanding, and video understanding.

Computer Vision Research Intern Feb 2023 – Apr 2023
Chimei Automotive Taiwan

- Developed a real-time multi-class FCWS (Forward Collision Warning System) for trucks and construction vehicles.
- Improve vehicle LDWS (Lane Departure Warning System) accuracy by 30% under poor visibility condition with auto encoder.

PUBLICATIONS

- Zero-shot 3D Question Answering via Voxel-based Dynamic Token Compression** 2025
Computer Vision and Pattern Recognition (CVPR)
Hsiang-Wei Huang, Fu-Chen Chen, Wenhao Chai, Che-Chun Su, Lu Xia, Sanghun Jung, Cheng-Yen Yang, Jenq-Neng Hwang, Min Sun, Cheng-hao Kuo
- MambaMOT: State-Space Model as Motion Predictor for Multi-Object Tracking** 2025
International Conference on Acoustics, Speech, and Signal Processing (ICASSP)
Hsiang-Wei Huang, Cheng-Yen Yang, Wenhao Chai, Zhongyu Jiang, Jenq-Neng Hwang
- 3D Visual Grounding with Reasoning LLM** 2025
In submission
Hsiang-Wei Huang, Kuang-Ming Chen, Wenhao Chai, Cheng-Yen Yang, Jenq-Neng Hwang
- ToSA: Token Merging with Spatial Awareness** 2025
In submission
Hsiang-Wei Huang, Wenhao Chai, Kuang-Ming Chen, Cheng-Yen Yang, Jenq-Neng Hwang
- Shot-Aware and Layout-Guided Personalized Vehicle Image Generation** 2025
In submission
Hsiang-Wei Huang, Cheng-Yen Yang, Yanting Zhang, Pyongkun Kim, Kwangju Kim, Jenq-Neng Hwang
- Packaging DiTs for Joint Motion-Text Generation** 2024
In Submission
Zhongyu Jiang, Wenhao Chai, Zhuoran Zhou, Cheng-Yen Yang, Hsiang-Wei Huang, Jenq-Neng Hwang

<ul style="list-style-type: none"> • Technical Report for ReID-SAM on SkiTB Visual Tracking Challenge 2025 <i>Technical Report</i> Kunjun Li, Cheng-Yen Yang, <u>Hsiang-Wei Huang</u>, Jenq-Neng Hwang 	2025
<ul style="list-style-type: none"> • Shot-Aware and Layout-Guided Personalized Vehicle Image Generation <i>In submission</i> <u>Hsiang-Wei Huang</u>, Cheng-Yen Yang, Yanting Zhang, Pyongkun Kim, Kwangju Kim, Jenq-Neng Hwang 	2025
<ul style="list-style-type: none"> • SAMURAI: Adapting SAM 2 for Visual Object Tracking with Motion Cues <i>In Submission</i> Cheng-Yen Yang, <u>Hsiang-Wei Huang</u>, Wenhao Chai, Zhongyu Jiang, Jenq-Neng Hwang 	2024
<ul style="list-style-type: none"> • Adapting SAM2 for Visual Object Tracking: 1st Place Solution for MMVPR Challenge Mutli-Modal Tracking <i>ICPR MMVPR Workshop</i> Cheng-Yen Yang*, <u>Hsiang-Wei Huang*</u>, Pyong-Kun Kim, Chien-Kai Kuo, Jui-Wei Chang, Jenq-Neng Hwang 	2024
<ul style="list-style-type: none"> • GTA: Global Tracklet Association for Multi-Object Tracking in Sports <i>ACCV MLCSA Workshop</i> Jiacheng Sun, <u>Hsiang-Wei Huang</u>, Cheng-Yen Yang, Zhongyu Jiang, Jenq-Neng Hwang 	2024
<ul style="list-style-type: none"> • RT-Pose: A 4D Radar Tensor-based 3D Human Pose Estimation and Localization Benchmark <i>European Conference on Computer Vision (ECCV)</i> Yuan-Hao Ho, Jen-Hao Cheng, Sheng Yao Kuan, Zhongyu Jiang, Wenhao Chai, <u>Hsiang-Wei Huang</u>, Chih-Lung Lin, Jenq-Neng Hwang 	2024
<ul style="list-style-type: none"> • ToddlerAct: A Toddler Action Recognition Dataset for Gross Motor Development Assessment <i>ECCV ABAW Workshop</i> <u>Hsiang-Wei Huang</u>, Jiacheng Sun, Cheng-Yen Yang, Zhongyu Jiang, Jenq-Neng Hwang 	2024
<ul style="list-style-type: none"> • An Online Approach and Evaluation Method for Tracking People Across Cameras in Extremely Long Video Sequences <i>CVPR AI City Challenge Workshop</i> Cheng-Yen Yang*, <u>Hsiang-Wei Huang*</u>, Pyong-Kun Kim, Zhongyu Jiang, Jenq-Neng Hwang 	2024
<ul style="list-style-type: none"> • Iterative Scale-up Expansion and Deep Features Association for Multi-Object Tracking in Sports <i>WACV RWS Workshop</i> <u>Hsiang-Wei Huang</u>, Cheng-Yen Yang, Jiacheng Sun, Pyong-Kun Kim, Kwang-Ju Kim, Chung-I Huang, Jenq-Neng Hwang 	2024
<ul style="list-style-type: none"> • Sea You Later: Metadata-Guided Long-Term Re-Identification for UAV-Based Multi-Object Tracking <i>WACV MaCVi Workshop</i> Cheng-Yen Yang, <u>Hsiang-Wei Huang</u>, Zhongyu Jiang, Heng-Cheng Kuo, Jie Mei, Jenq-Neng Hwang 	2024
<ul style="list-style-type: none"> • A Density-Guided Temporal Attention Transformer for Indiscernible Object Counting in Underwater Videos <i>IEEE ICASSP</i> Cheng-Yen Yang, <u>Hsiang-Wei Huang</u>, Zhongyu Jiang, Hao Wang, Farron Wallace, Jenq-Neng Hwang 	2024
<ul style="list-style-type: none"> • Boosting Online 3D Multi-Object Tracking through Camera-Radar Cross Check <i>IEEE Intelligent Vehicles Symposium</i> Sheng-Yao Kuan, Jen-Hao Cheng, <u>Hsiang-Wei Huang</u>, Jenq-Neng Hwang 	2024
<ul style="list-style-type: none"> • Enhancing Multi-Camera People Tracking with Anchor-Guided Clustering and ID Re-Assignment <i>CVPR AI City Challenge Workshop</i> <u>Hsiang-Wei Huang*</u>, Cheng-Yen Yang*, Zhongyu Jiang, Jenq-Neng Hwang 	2023
<ul style="list-style-type: none"> • Observation Centric and Central Distance Recovery for Athlete Tracking <i>WACV CV4WS Worksop</i> <u>Hsiang-Wei Huang</u>, Cheng-Yen Yang, Samartha Ramkumar, Chung-I Huang, Jenq-Neng Hwang 	2023

HONORS & AWARDS

<ul style="list-style-type: none"> • 2nd Place, 2025 WACV SkiTB Visual Tracking Challenge [URL] • Mentored a master student and secured the 2nd place of the competition with 87.0 F1 score. • Solution presented at the WACV CV4WS workshop. 	2025
<ul style="list-style-type: none"> • Taiwan Future Tech Award [URL] • Collaborated with Taiwan National Center for High-performance Computing and proposed a traffic monitoring framework. • Awarded with the proposed <i>Digital City-Smart Traffic Congestion Prediction and Police Service Support System</i>. 	2024
<ul style="list-style-type: none"> • 1st Place, 2024 ICPR Multi-modal Tracking Challenge [URL] • Secured the 1st place of the competition with 89.4 AUC among 53 participants. • Paper presented at the ICPR MMVPR workshop. 	2024

1st Place, 2024 WACV MaCVi Challenge - UAV-based Multi-Object Tracking and Re-Identification [URL] <ul style="list-style-type: none"> • Present a meta-data aided re-identification method for long-term multi-object tracking and re-identification. • Achieved the best performance with an HOTA of 69.5 in the 2024 WACV Maritime Computer Vision Challenge. 	2024
1st Place, 2024 WACV MaCVi Challenge - USV-based Multi-Object Tracking [URL] <ul style="list-style-type: none"> • Present a strong model ensemble method to conduct tracking on USV-based multi-object tracking. • Achieved the highest HOTA performance in the 2024 WACV Maritime Computer Vision Challenge. 	2024
1st Place, 2023 CVPR AI City Challenge in Multi-Camera People Tracking [URL] <ul style="list-style-type: none"> • Present a robust anchor-guided clustering method for multi-camera people tracking and re-identification. • Achieved the best performance with an IDF1 of 95.36, in the 2023 AI City Challenge Track 1 on the public testing set. 	2023
3rd Place, 2022 ECCV DeeperAction Challenge - SportsMOT Track on Multi-actor Tracking [URL] <ul style="list-style-type: none"> • Ranked 3rd place in HOTA among over 130 teams on the final leaderboard. • Achieved over 73.9% HOTA on sports player tracking in three different sports scenes. • Paper presented at the ECCV DeeperAction Workshop. 	2022

SKILLS

Programming Languages.

Python, SQL, C, Matlab

Software Tools.

Pytorch, Tensorflow, Numpy, Scikit-learn, Pandas, OpenCV, Open3D, Linux, Git, AWS, Azure, LaTeX

Languages.

English, Mandarin