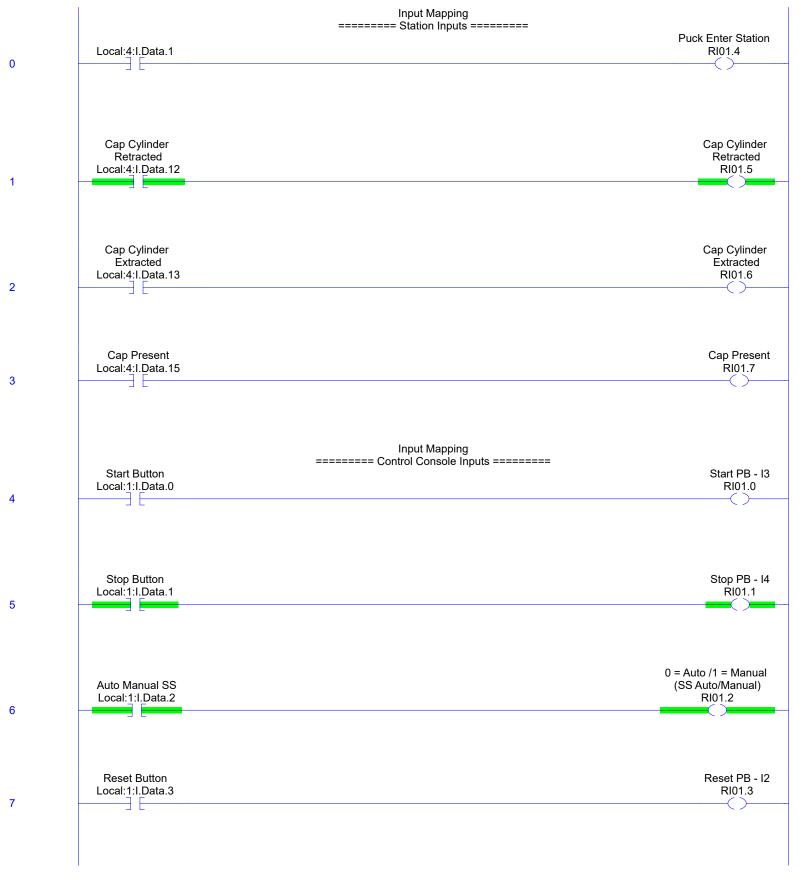
IO\_Mapping - Ladder Diagram
Robot Station:MainTask:MainProgram

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Page 1

Total number of rungs in routine: 11

... LAB\\_3 - ROBOT STATION\FINAL\_LAB\_ROBOT\_AB\_L24ER.ACD



IO\_Mapping - Ladder Diagram
Robot Station:MainTask:MainProgram

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Page 2

Total number of rungs in routine: 11

... LAB\\_3 - ROBOT STATION\FINAL\_LAB\_ROBOT\_AB\_L24ER.ACD



Robot Station:MainTask:MainProgram Total number of rungs in routine: 6



Panel\_Lights - Function Block Diagram
Robot\_Station:MainTask:MainProgram
1 of 1 total sheets in routine

**Page 1** 2021-04-29 6:37:40 PM D:\OneDrive - Conestoga College\ELEC2280\FINAL LAB\ 3 - ROBOT STATION\FINAL LAB ROBOT AB L24ER.ACD

1 of 1 total sheets in rou			2	lestoga Conege LLLC2200	THATE END (3 Ref	301 21111101(411(11)		EZ :ER:: ICB
A	В	С	D	E	F	G	Н	
A	В	C	Б		Г	G	п	
Station Ready Bit  BIT.0 0  Robot Running  BIT.1 0		Out 0	TONR_02 TONR mer On Delay with Reset merEnable ACC DO CRE DN D	BOR_01  BOR  Boolean Or  In1 Out  In2	Control console – Start (LED) RO01.0			2
3		Station Ready Bit  BIT.0  Robot Running  BIT.1  0	BAND_01  BAND  Boolean And  In Out 0  TONR_03  TONR					3
4		BIT.2 D C Timer C PRE G Reset	On Delay with Reset  Enable ACC  TT  DN  TONR_04  TONR  On Delay with Reset	Control console – Reset (LED) c( RO01.1				4
5		500 PRE C Reset	Enable ACC DODE					5
6								6

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Robot\_Station (Controller)

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<b>N</b> T	X7-1	D-4- T	C
Name BAND_01	Value	<b>Data Type</b> FBD BOOLEAN AND	Scope MainProgram
Constant	No	FBD_BOOLEAN_AND	MainFlograin
External Access:	Read/Write		
BAND 01.EnableIn	1	BOOL	
BAND 01.In1	0	BOOL	
BAND 01.In2	0	BOOL	
BAND_01.In3	1	BOOL	
BAND 01.In4	1	BOOL	
BAND 01.In5	1	BOOL	
BAND_01.In6	1	BOOL	
BAND_01.In7	1	BOOL	
BAND 01.In8	1	BOOL	
BAND_01.EnableOut	1	BOOL	
BAND_01.Out	0	BOOL	
BAND_02		FBD_BOOLEAN_AND	MainProgram
Constant	No		
External Access:	Read/Write		
BAND_02.EnableIn	1	BOOL	
BAND_02.In1	0	BOOL	
BAND_02.In2	1	BOOL	
BAND_02.In3	1	BOOL	
BAND_02.In4	1	BOOL	
BAND_02.In5	1	BOOL	
BAND_02.In6	1	BOOL	
BAND_02.In7	1	BOOL	
BAND_02.In8	1	BOOL BOOL	
BAND_02.EnableOut	1	BOOL	
BAND_02.Out BIT	0 4	DINT	MainProgram
Constant	No	DINI	MainFlograin
External Access:	Read/Write		
BIT.0	0	BOOL	
Station Ready Bit	O .	BOOL	
BIT.1	0	BOOL	
Robot Running	·	2002	
BIT.2	1	BOOL	
E-Stop Bit			
BIT.3	0	BOOL	
Part Ready (Entering Station)			
BIT.4	0	BOOL	
Reset Bit			
BNOT_01		FBD_BOOLEAN_NOT	MainProgram
Constant	No		
External Access:	Read/Write		
BNOT_01.EnableIn	1	BOOL	
BNOT_01.In	0	BOOL	
BNOT_01.EnableOut	1	BOOL	
BNOT_01.Out	1	BOOL	M ' D
BOR_01	N.	FBD_BOOLEAN_OR	MainProgram
Constant	No		
External Access:	Read/Write	BOOL	
BOR_01.EnableIn	0	BOOL	
BOR_01.In1 BOR_01.In2	0	BOOL	
BOR 01.In3	0	BOOL	
BOR_01.In4	0	BOOL	
BOR_01.In5	0	BOOL	
BOR_01.In6	0	BOOL	
BOR_01.In7	0	BOOL	
BOR 01.In8	0	BOOL	
BOR_01.EnableOut	1	BOOL	
BOR_01.Out	0	BOOL	
CCI01	32768	DINT	MainProgram
			<del>-</del>

Robot_Station - Program Tag Listing			Page 2
Robot_Station (Controller)	Canastaga Callaga\ELE(	C2280\FINAL LAB\ 3 - ROBOT STATION\FINAL LA	2021-04-29 6:35:46 PM
D:\\OHeDrive - C	ionestoga Conege\ellev	C2280\FINAL LAB\_5 - ROBOT 5TATION\FINAL_LA	B_ROBUT_AB_L24EK.ACD
CCI01 (Continued)	3.7		
Constant	No Read/Write		
External Access: CCI01.0	Read/Write 0	BOOL	
Start pushbutton	U	DOOL	
CCI01.1	0	BOOL	
Stop pushbutton (normally closed)			
CCI01.2	0	BOOL	
Auto/Manual Swtich	^	POOL	
CCI01.3  Reset pushbutton	0	BOOL	
CCI01.4	0	BOOL	
Next Station Working (I6) Right	O	Book	
CCI01.5	0	BOOL	
(I7) Right			
CCO01	0	DINT	MainProgram
Constant	No Dog 1/Waite		
External Access:	Read/Write	DOOL	
CCO01.0 Indicator light Start on	0	BOOL	
CC001.1	0	BOOL	
Indicator light (Reset)	U	DOOL	
CCO01.2	0	BOOL	
Station in Use (Q4) Left	V	Beel	
CCO01.3	0	BOOL	
Station in Use (Q5) Left			
CCO01.4	0	BOOL	
(Q6) Right			
CC001.5	0	BOOL	
(Q7) Right		EDD TIMED	3.6 ° D
LIGHT_OFF_5S	No	FBD_TIMER	MainProgram
Constant External Access:	No Read/Write		
LIGHT OFF 5S.EnableIn	1	BOOL	
LIGHT_OFF_5S.Enablem LIGHT_OFF_5S.TimerEnable	0	BOOL	
LIGHT OFF 5S.PRE	0	DINT	
LIGHT_OFF_5S.Reset	0	BOOL	
LIGHT_OFF_5S.EnableOut	0	BOOL	
LIGHT_OFF_5S.ACC	0	DINT	
LIGHT_OFF_5S.EN	0	BOOL	
LIGHT_OFF_5S.TT	0	BOOL	
LIGHT_OFF_5S.DN	0	BOOL	
LIGHT_OFF_5S.Status	16#0000_0000	DINT	
LIGHT_OFF_5S.InstructFault	0	BOOL BOOL	
LIGHT_OFF_5S.PresetInv ONS	2	BOOL DINT	MainProgram
Constant	No	DINI	Maiii 10graiii
External Access:	Read/Write		
ONS.0	0	BOOL	
Part Detect	v		
ONS.1	1	BOOL	
Reset First Time ON			
ONS.2	0	BOOL	
Cap Cylinder Extend		= - 0*	
ONS.3	0	BOOL	
Cap Present	22007	DIJT	M. '. D
RI01	32806 No	DINT	MainProgram
Constant External Access:	No Read/Write		
RI01.0	0	BOOL	
Start PB - I3	U	DOOL	
RI01.1	1	BOOL	
Stop PB - I4	•	20	
RI01.2	1	BOOL	

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RI01 (Continued)			
0 = Auto / 1 = Manual (SS Auto/M)			
RI01.3	0	BOOL	
Reset PB - I2 <b>RI01.4</b>	0	BOOL	
Puck Enter Station	U	BOOL	
RI01.5	1	BOOL	
Cap Cylinder Retracted			
RI01.6	0	BOOL	
Cap Cylinder Extracted	0	DOO!	
RI01.7 Cap Present	0	BOOL	
RI01.8	0	BOOL	
Nex Station Working			
RO01	0	DINT	MainProgram
Constant	No		
External Access:	Read/Write	Door	
RO01.0	0	BOOL	
Control console – Start (LED) <b>RO01.1</b>	0	BOOL	
Control console – Reset (LED)	O .	BOOL	
RO01.2	0	BOOL	
Extract Cylinder Cap Magazine			
RO01.3	0	BOOL	
Robot Station Working (Q4) - Lef		DOOL	
RO01.4 Ind Light Station Working Q1	0	BOOL	
TIMER_CAP		TIMER	MainProgram
Timer to Release Cap		THALL	Walli 10graffi
Constant	No		
External Access:	Read/Write		
TIMER_CAP.PRE	2000	DINT	
TIMER_CAP.ACC	0	DINT	
TIMER_CAP.EN	0	BOOL BOOL	
TIMER_CAP.TT TIMER CAP.DN	0	BOOL	
TONR_01	O .	FBD_TIMER	MainProgram
Constant	No		
External Access:	Read/Write		
TONR_01.EnableIn	1	BOOL	
TONR_01.TimerEnable	0	BOOL	
TONR_01.PRE	500 0	DINT BOOL	
TONR_01.Reset TONR_01.EnableOut	1	BOOL	
TONR_01.ACC	0	DINT	
TONR_01.EN	0	BOOL	
TONR_01.TT	0	BOOL	
TONR_01.DN	0	BOOL	
TONR_01.Status	16#0000_0000	DINT	
TONR_01.InstructFault TONR 01.PresetInv	0	BOOL BOOL	
TONR_02	O .	FBD TIMER	MainProgram
Constant	No	122_11.121	1/14/11/11 10 81 41/11
External Access:	Read/Write		
TONR_02.EnableIn	1	BOOL	
TONR_02.TimerEnable	0	BOOL	
TONR_02.PRE	500 0	DINT BOOL	
TONR_02.Reset TONR_02.EnableOut	1	BOOL	
TONK_02.EnableOut TONR_02.ACC	0	DINT	
TONR_02.EN	0	BOOL	
TONR_02.TT	0	BOOL	
TONR_02.DN	0	BOOL	
TONR_02.Status	16#0000_0000	DINT	

Robot Station (Controller) 2021-04-29 6:35:46 PM D:\OneDrive - Conestoga College\ELEC2280\FINAL LAB\ 3 - ROBOT STATION\FINAL LAB ROBOT AB L24ER.ACD TONR 02 (Continued) 0 TONR 02.InstructFault **BOOL** TONR 02.PresetInv 0 **BOOL** FBD\_TIMER TONR 03 MainProgram Constant No Read/Write External Access: TONR 03.EnableIn **BOOL** TONR 03.TimerEnable 1 **BOOL** 500 TONR 03.PRE DINT TONR\_03.Reset 0 **BOOL** TONR\_03.EnableOut 1 **BOOL** TONR 03.ACC 500 DINT TONR 03.EN 1 **BOOL** TONR 03.TT 0 **BOOL** TONR 03.DN 1 **BOOL** 16#0000 0000 TONR 03.Status DINT TONR 03.InstructFault 0 **BOOL** TONR 03.PresetInv 0 **BOOL** TONR 04 FBD TIMER MainProgram Constant No Read/Write External Access: TONR 04.EnableIn **BOOL TONR 04.TimerEnable** 1 **BOOL** TONR 04.PRE 500 DINT TONR\_04.Reset 0 **BOOL** TONR\_04.EnableOut 1 **BOOL** TONR 04.ACC 40 DINT TONR 04.EN 1 **BOOL** TONR 04.TT 1 **BOOL** TONR 04.DN 0 **BOOL TONR 04.Status** 16#0000 0000 DINT TONR 04.InstructFault 0 **BOOL** TONR 04.PresetInv 0 **BOOL** URI UR\_T2O\_Assembly\_Combined MainProgram No Constant **External Access:** Read/Write **URI.Robot** UR T2O Robot URI.Robot.Controller Major Version **SINT** URI.Robot.Controller\_Minor\_Version 5 **SINT** 0 INT URI.Robot.Rsvd1 URI.Robot.Robot Mode SINT URI.Robot.Real\_Time\_Machine\_sec **SINT** URI.Robot.Real\_Time\_Machine\_msec INT URI.Robot.Real\_Time\_Machine\_minutes **SINT** URI.Robot.Real\_Time\_Machine\_hours **SINT** URI.Robot.Real\_Time\_Machine\_days INT 0.6803396 URI.Robot.Robot Current mA **REAL** URI.Robot.PW **BOOL** 1 **BOOL** URI.Robot.PR 0 **BOOL** URI.Robot.TB **BOOL** URI.Robot.PB URI.Robot.Speed Slider Fraction 0.29 **REAL URI.Safety** UR T2O Safety 1 **URI.Safety.Safety Mode SINT** SINT URI.Safety.Rsvd1 0 URI.Safety.Rsvd2 0 **SINT** 0 URI.Safety.Rsvd3 SINT

URI.IO.Euromap67 input bits[26] 0

Robot Station (Controller)

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BOOL

**URI (Continued)** 1 **BOOL** URI.Safety.NO 0 URI.Safetv.RD **BOOL BOOL URI.Safety.PS** 0 **URI.Safety.RC** 0 **BOOL URI.Safety.SS** 0 BOOL **URI.Safety.SES** 0 **BOOL URI.Safety.RES** 0 **BOOL URI.Safety.ES** U **BOOL URI.Safety.VL** 0 **BOOL URI.Safety.FT** 0 **BOOL** 0 **URI.Safety.ST BOOL URI.IO** UR T2O IO **URI.IO.Standard Digital Inputs SINT URI.IO.**Configurable Digital Inputs **SINT** URI.IO.Standard Digital Outputs 0 **SINT URI.IO.Configurable Digital Outputs** 0 **SINT URI.IO.Analog IO Types** 3 SINT URI.IO.Rsvd1 0 SINT URLIO.Rsvd2 0 SINT URI.IO.Rsvd3 **SINT** URI.IO.Standard Analog Input mA or V REAL URI.IO.Standard Analog Input mA or V[0] 0.008056164 **REAL** URI.IO.Standard Analog Input mA or V[1] 0.004028082 **REAL** URI.IO.Standard Analog Output mA or V **REAL** URI.IO.Standard\_Analog\_Output\_mA\_or\_V[0] **REAL** URI.IO.Standard\_Analog\_Output\_mA\_or\_V[1] 0.004 **REAL** URI.IO.IO Current mA 0.2153428 **REAL** URI.IO.Euromap67 input bits **BOOL** 0 URI.IO.Euromap67 input bits[0] **BOOL** URI.IO.Euromap67\_input\_bits[1] **BOOL** URI.IO.Euromap67 input bits[2] **BOOL BOOL** URI.IO.Euromap67 input bits[3] URI.IO.Euromap67 input bits[4] BOOL URI.IO.Euromap67 input bits[5] **BOOL** URI.IO.Euromap67 input bits[6] **BOOL** URI.IO.Euromap67 input bits[7] **BOOL** URI.IO.Euromap67\_input\_bits[8] **BOOL** URI.IO.Euromap67\_input\_bits[9] **BOOL** URI.IO.Euromap67 input bits[10] 0 **BOOL** URI.IO.Euromap67 input bits[11] 0 **BOOL** URI.IO.Euromap67 input bits[12] 0 **BOOL** URI.IO.Euromap67\_input\_bits[13] 0 **BOOL** URI.IO.Euromap67\_input\_bits[14] 0 **BOOL** URI.IO.Euromap67\_input\_bits[15] 0 **BOOL** URI.IO.Euromap67\_input\_bits[16] 0 **BOOL** URI.IO.Euromap67 input bits[17] 0 **BOOL BOOL** URI.IO.Euromap67 input bits[18] 0 URI.IO.Euromap67 input bits[19] 0 **BOOL** URI.IO.Euromap67 input bits[20] 0 **BOOL** URI.IO.Euromap67 input bits[21] 0 **BOOL** URI.IO.Euromap67 input bits[22] 0 BOOL URI.IO.Euromap67\_input\_bits[23] 0 **BOOL** URI.IO.Euromap67\_input\_bits[24] 0 **BOOL** URI.IO.Euromap67 input bits[25] 0 **BOOL** 

Page 6

**URI (Continued)** URI.IO.Euromap67 input bits[27] 0 **BOOL** URI.IO.Euromap67\_input\_bits[28] 0 **BOOL** URI.IO.Euromap67 input bits[29] 0 **BOOL** URI.IO.Euromap67 input bits[30] 0 **BOOL** URI.IO.Euromap67 input bits[31] 0 BOOL URI.IO.Euromap67 output bits **BOOL** URI.IO.Euromap67 output bits[0] 0 **BOOL** URI.IO.Euromap67 output bits[1] 0 **BOOL** URI.IO.Euromap67\_output\_bits[2] 0 **BOOL** URI.IO.Euromap67\_output\_bits[3] 0 **BOOL** URI.IO.Euromap67\_output\_bits[4] 0 **BOOL** URI.IO.Euromap67 output bits[5] 0 BOOL URI.IO.Euromap67 output bits[6] 0 **BOOL** URI.IO.Euromap67 output bits[7] 0 **BOOL** URI.IO.Euromap67 output bits[8] 0 **BOOL** URI.IO.Euromap67 output bits[9] 0 BOOL URI.IO.Euromap67\_output\_bits[10] **BOOL** URI.IO.Euromap67 output bits[11] **BOOL** URI.IO.Euromap67\_output\_bits[12] **BOOL** URI.IO.Euromap67 output bits[13] **BOOL** URI.IO.Euromap67\_output\_bits[14] **BOOL** URI.IO.Euromap67 output bits[15] **BOOL** URI.IO.Euromap67\_output\_bits[16] **BOOL** URI.IO.Euromap67\_output\_bits[17] **BOOL** URI.IO.Euromap67\_output\_bits[18] **BOOL** URI.IO.Euromap67 output bits[19] **BOOL** URI.IO.Euromap67\_output\_bits[20] **BOOL** URI.IO.Euromap67 output bits[21] **BOOL** URI.IO.Euromap67 output bits[22] **BOOL** URI.IO.Euromap67\_output\_bits[23] **BOOL** URI.IO.Euromap67\_output\_bits[24] **BOOL** URI.IO.Euromap67\_output\_bits[25] **BOOL** URI.IO.Euromap67\_output\_bits[26] **BOOL** URI.IO.Euromap67 output bits[27] **BOOL** URI.IO.Euromap67 output bits[28] **BOOL** URI.IO.Euromap67 output bits[29] **BOOL** URI.IO.Euromap67\_output\_bits[30] **BOOL** URI.IO.Euromap67\_output\_bits[31] **BOOL** URI.IO.Euromap67 24V voltage V **REAL** URI.IO.Euromap67 current mA **REAL** 

Robot\_Station - Program Tag Listing
Robot\_Station (Controller)

D:\OneDrive - Conestoga College\ELEC2280\FINAL LAB\\_3 - ROBOT STATION\FINAL LAB\_ROBOT\_AB\_L24ER.ACD

D:\OneDrive -	Conestoga College\ELEC2280\FINAL L	<u> AB\_3 - ROBOT STATION\FINAL_LAB_ROBOT_AB_L2</u>
URI (Continued)		
URI.Tool		UR_T2O_Tool
URI.Tool.Mode	-3	SINT
URI.Tool.Rsvd1	0	SINT
URI.Tool.Rsvd2	0	SINT
URI.Tool.Rsvd3	0	SINT
URI.Tool.TDI	0	SINT
URI.Tool.TDO	0	SINT
	3	SINT
URI.Tool.TAIT		
URI.Tool.Rsvd4	0	SINT
URI.Tool.Analog_Input_mA_or_V		REAL
URI.Tool.Analog_Input_mA_or_V		
	0.036108334	REAL
URI.Tool.Analog_Input_mA_or_V		
	0.035485774	REAL
URI.Tool.Output Voltage V	24.0	REAL
URI.Tool.Current mA	0.003	REAL
URI.Joints		UR T2O Joints
URI.Joints.Position rad		REAL
URI.Joints.Position rad[0]	-0.8390334	REAL
URI.Joints.Position rad[1]	-1.3762697	REAL
URI.Joints.Position rad[2]	-2.1509993	REAL
URI.Joints.Position rad[3]	1.9211622	REAL
URI.Joints.Position_rad[4]	-1.5686744 -2.415120	REAL
URI.Joints.Position_rad[5]	-2.415129	REAL
URI.Joints.Velocity_rad_per_sec		REAL
URI.Joints.Velocity_rad_per_sec[0		
	0.0	REAL
URI.Joints.Velocity_rad_per_sec[1	-	
	0.0	REAL
URI.Joints.Velocity_rad_per_sec[2	2]	
	0.0	REAL
URI.Joints.Velocity_rad_per_sec[3	3]	
,	0.0	REAL
URI.Joints.Velocity rad per sec[4	Ŋ	
, - <del>-</del> - ·	0.0	REAL
URI.Joints.Velocity rad per sec[		
	0.0	REAL
URI.Joints.Current mA	•••	REAL
URI.Joints.Current mA[0]	-0.23090649	REAL
URI.Joints.Current mA[1]	0.7465229	REAL
URI.Joints.Current mA[2]	1.100729	REAL
	-0.13115354	REAL
URI.Joints.Current_mA[3]		
URI.Joints.Current_mA[4]	-0.17995486	REAL
URI.Joints.Current_mA[5]	0.13115354	REAL
URI.Joints.Temperature_C	••••••	REAL
URI.Joints.Temperature_C[0]	29.939991	REAL
URI.Joints.Temperature_C[1]	30.329992	REAL
URI.Joints.Temperature_C[2]	29.059992	REAL
URI.Joints.Temperature_C[3]	35.969982	REAL
URI.Joints.Temperature_C[4]	35.69998	REAL
URI.Joints.Temperature C[5]	37.619984	REAL
URI.Joints.Mode		SINT
URI.Joints.Mode[0]	-3	SINT
URI.Joints.Mode[1]	-3	SINT
URI.Joints.Mode[2]	-3	SINT
URI.Joints.Mode[3]	-3	SINT
URI.Joints.Mode[4]	-3	SINT
URI.Joints.Mode[5]	-3 -3	SINT
URI.TCP	5	UR T2O TCP
URI.TCP.Position_m	0.06674065	UR_Coordinate
URI.TCP.Position_m.X	-0.06674965 0.113087155	REAL
URI.TCP.Position_m.Y	-0.113087155	REAL
URI.TCP.Position_m.Z	0.10058678	REAL

		_
URI (Continued)		
URI.TCP.Position R		UR Coordinate
URI.TCP.Position R.X	0.012778099	REAL
_		REAL REAL
URI.TCP.Position_R.Y	-3.111728 0.02422445	
URI.TCP.Position_R.Z	-0.03423445	REAL
URI.TCP.Velocity_m_per_s	0.0	UR_Coordinate
URI.TCP.Velocity_m_per_s.X	0.0	REAL
URI.TCP.Velocity_m_per_s.Y	0.0	REAL
URI.TCP.Velocity_m_per_s.Z	0.0	REAL
URI.TCP.Velocity_R		UR_Coordinate
URI.TCP.Velocity_R.X	0.0	REAL
URI.TCP.Velocity_R.Y	0.0	REAL
URI.TCP.Velocity_R.Z	0.0	REAL
URI.TCP.Force_N		UR_Coordinate
URI.TCP.Force_N.X	8.939497	REAL
URI.TCP.Force_N.Y	-4.2990065	REAL
URI.TCP.Force_N.Z	9.962915	REAL
URI.TCP.Force_Scalar_N	0.60129786	REAL
URI.TCP.Torque_Nm		UR_Coordinate
URI.TCP.Torque_Nm.X	4.124037	REAL
URI.TCP.Torque_Nm.Y	1.6994612	REAL
URI.TCP.Torque Nm.Z	14.0590105	REAL
URI.Bit		UR BitRegisters
URI.Bit.Registers		BOOL
URI.Bit.Registers[0]	0	BOOL
URI.Bit.Registers[1]	0	BOOL
URI.Bit.Registers[2]	0	BOOL
Q4 Ouput		
URI.Bit.Registers[3]	0	BOOL
URI.Bit.Registers[4]	0	BOOL
URI.Bit.Registers[5]	0	BOOL
URI.Bit.Registers[6]	0	BOOL
URI.Bit.Registers[7]	0	BOOL
URI.Bit.Registers[8]	0	BOOL
URI.Bit.Registers[9]	0	BOOL
URI.Bit.Registers[10]	0	BOOL
URI.Bit.Registers[11]	0	BOOL
URI.Bit.Registers[12]	0	BOOL
URI.Bit.Registers[13]	0	BOOL
URI.Bit.Registers[14]	0	BOOL
URI.Bit.Registers[15]	0	BOOL
URI.Bit.Registers[16]	0	BOOL
URI.Bit.Registers[17]	0	BOOL
URI.Bit.Registers[18]	0	BOOL
URI.Bit.Registers[19]	0	BOOL
URI.Bit.Registers[20]	0	BOOL
URI.Bit.Registers[21]	0	BOOL
URI.Bit.Registers[22]	0	BOOL
URI.Bit.Registers[23]	0	BOOL
URI.Bit.Registers[24]	0	BOOL
URI.Bit.Registers[25]	0	BOOL
URI.Bit.Registers[26]	0	BOOL
URI.Bit.Registers[27]	0	BOOL
URI.Bit.Registers[28]	0	BOOL
	0	
URI.Bit.Registers[29]	0	BOOL BOOL
URI.Bit.Registers[30]		
URI.Bit.Registers[31]	0	BOOL
URI.Bit.Registers[32]	0	BOOL
URI.Bit.Registers[33]	0	BOOL
URI.Bit.Registers[34]	0	BOOL
URI.Bit.Registers[35]	0	BOOL
URI.Bit.Registers[36]	0	BOOL
URI.Bit.Registers[37]	0	BOOL
URI.Bit.Registers[38]	0	BOOL

Robot\_Station - Program Tag Listing
Robot\_Station (Controller)

D:\OneDrive - Conestoga College\ELEC2280\FINAL LAB\\_3 - ROBOT STATION\FINAL LAB\_ROBOT\_AB\_L24ER.ACD

D:\One	eDrive - Conestoga College\EI	LEC2280\FINAL LAB\_3 - ROBOT STAT
URI (Continued)	0	Door
URI.Bit.Registers[39]	0	BOOL
URI.Bit.Registers[40]	0	BOOL
URI.Bit.Registers[41]	0	BOOL
URI.Bit.Registers[42]	0	BOOL
URI.Bit.Registers[43]	0	BOOL
URI.Bit.Registers[44]	0	BOOL
URI.Bit.Registers[45]	0	BOOL
URI.Bit.Registers[46]	0	BOOL
URI.Bit.Registers[47]	0	BOOL
URI.Bit.Registers[48] URI.Bit.Registers[49]	0	BOOL BOOL
URI.Bit.Registers[50]	0	BOOL
URI.Bit.Registers[51]	0	BOOL
URI.Bit.Registers[52]	0	BOOL
URI.Bit.Registers[53]	0	BOOL
URI.Bit.Registers[54]	0	BOOL
URI.Bit.Registers[55]	0	BOOL
URI.Bit.Registers[56]	0	BOOL
URI.Bit.Registers[57]	0	BOOL
URI.Bit.Registers[58]	0	BOOL
URI.Bit.Registers[59]	0	BOOL
URI.Bit.Registers[60]	0	BOOL
URI.Bit.Registers[61]	0	BOOL
URI.Bit.Registers[62]	0	BOOL
URI.Bit.Registers[63]	0	BOOL
URI.Int		UR IntRegisters
URI.Int.Registers		DINT
URI.Int.Registers[0]	0	DINT
URI.Int.Registers[1]	0	DINT
URI.Int.Registers[2]	0	DINT
URI.Int.Registers[3]	0	DINT
URI.Int.Registers[4]	0	DINT
URI.Int.Registers[5]	0	DINT
URI.Int.Registers[6]	0	DINT
URI.Int.Registers[7]	0	DINT
URI.Int.Registers[8]	0	DINT
URI.Int.Registers[9]	0	DINT
URI.Int.Registers[10]	0	DINT
URI.Int.Registers[11]	0	DINT
URI.Int.Registers[12] URI.Int.Registers[13]	0	DINT DINT
URI.Int.Registers[13]	0	DINT
URI.Int.Registers[15]	0	DINT
URI.Int.Registers[16]	0	DINT
URI.Int.Registers[17]	$\overset{\circ}{0}$	DINT
URI.Int.Registers[18]	0	DINT
URI.Int.Registers[19]	0	DINT
URI.Int.Registers[20]	0	DINT
URI.Int.Registers[21]	0	DINT
URI.Int.Registers[22]	0	DINT
URI.Int.Registers[23]	0	DINT
URI.Float		UR_FloatRegisters
URI.Float.Registers		$\overline{\text{REAL}}$
URI.Float.Registers[0]	0.0	REAL
URI.Float.Registers[1]	0.0	REAL
URI.Float.Registers[2]	0.0	REAL
URI.Float.Registers[3]	0.0	REAL
URI.Float.Registers[4]	0.0	REAL
URI.Float.Registers[5]	0.0	REAL
URI.Float.Registers[6]	0.0	REAL
URI.Float.Registers[7]	0.0	REAL
URI.Float.Registers[8]	0.0	REAL
URI.Float.Registers[9]	0.0	REAL

Robot Running

URO.Bit.Registers[6]

URO.Bit.Registers[7]

URO.Bit.Registers[8] URO.Bit.Registers[9]

URO.Bit.Registers[10]

URO.Bit.Registers[11]

URO.Bit.Registers[12]

0

0

0

0

0

0

0

Robot Station (Controller) 2021-04-29 6:35:47 PM D:\OneDrive - Conestoga College\ELEC2280\FINAL LAB\ 3 - ROBOT STATION\FINAL LAB ROBOT AB L24ER.ACD **URI (Continued)** 0.0 URI.Float.Registers[10] **REAL** URI.Float.Registers[11] 0.0 **REAL** URI.Float.Registers[12] 0.0REAL **REAL URI.Float.Registers**[13] 0.0 URI.Float.Registers[14] 0.0**REAL** URI.Float.Registers[15] 0.0 **REAL** URI.Float.Registers[16] 0.0**REAL** URI.Float.Registers[17] 0.0 **REAL** URI.Float.Registers[18] 0.0 **REAL** URI.Float.Registers[19] 0.0 **REAL** 0.0 **REAL** URI.Float.Registers[20] **URI.Float.Registers**[21] 0.0 **REAL** URI.Float.Registers[22] 0.0 **REAL** URI.Float.Registers[23] 0.0 **REAL** URO UR O2T Assembly Combined MainProgram Constant No **External Access:** Read/Write **URO.Robot** UR O2T Robot 0 **URO.Robot.Speed Slider Mask BOOL URO.Robot.Speed Slider Fraction** 0.0 REAL **URO.Outputs** UR O2T Outputs URO.Outputs.Standard\_Digital\_Output\_Mask **SINT** URO.Outputs.Configurable\_Digital\_Output\_Mask **SINT URO.Outputs.Standard Digital Outputs SINT URO.Outputs.Configurable Digital Outputs SINT** URO.Outputs.Analog\_Output\_Mask **SINT** URO.Outputs.Analog\_Output\_Type **SINT URO.Outputs.Tool Digital Output Mask SINT** URO.Outputs.Tool Digital Output 0 SINT **URO.Outputs.Standard Analog Output REAL** URO.Outputs.Standard Analog Output[0] **REAL** URO.Outputs.Standard Analog Output[1] REAL **URO.Bit** UR BitRegisters **URO.Bit.Registers BOOL** URO.Bit.Registers[0] 0 **BOOL** Start Robot Process URO.Bit.Registers[1] 0 **BOOL** Puck/Part Present 0 URO.Bit.Registers[2] **BOOL** Reset Move Home 1 **BOOL** URO.Bit.Registers[3] E-stop Activated 0 **BOOL URO.Bit.Registers**[4] Cap Present 0 URO.Bit.Registers[5] **BOOL** 

**BOOL** 

**BOOL** 

**BOOL** 

**BOOL** 

**BOOL** 

**BOOL** 

BOOL

Robot\_Station - Program Tag Listing
Robot\_Station (Controller)

D:\OneDrive - Conestoga College\ELEC2280\FINAL LAB\\_3 - ROBOT STATION\FINAL\_LAB\_ROBOT\_AB\_L24ER.ACD

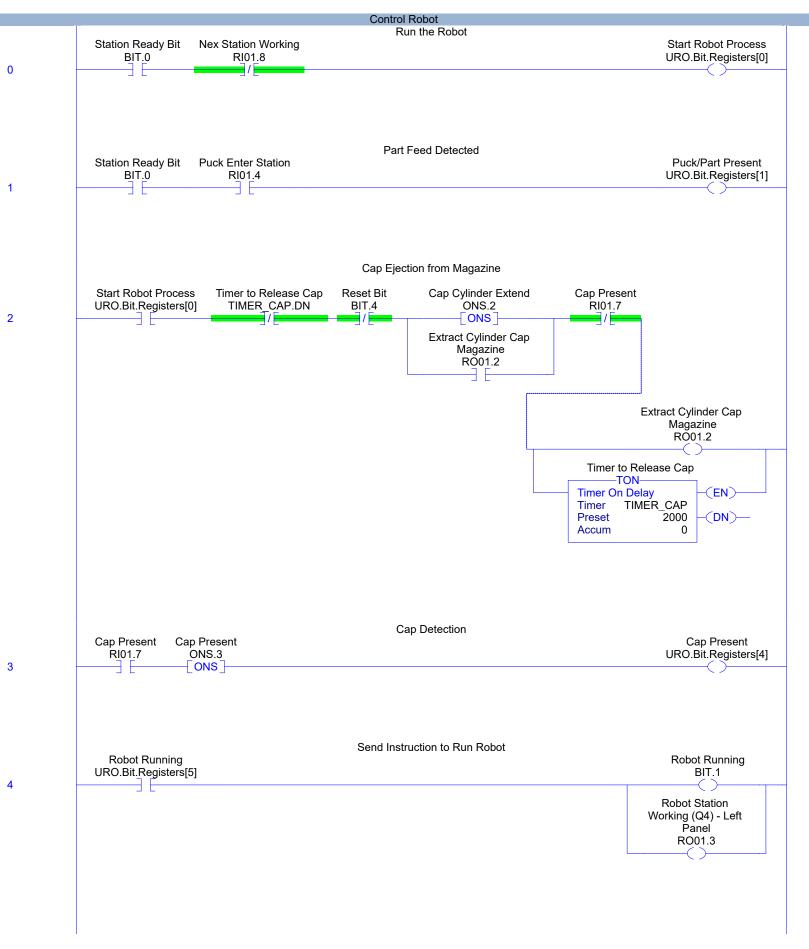
D:\O	neDrive - Conestoga College\EL	LEC2280\FINAL LAB\_3 - ROBOT STATIO
URO (Continued)		
URO.Bit.Registers[13]	0	BOOL
URO.Bit.Registers[14]	0	BOOL
URO.Bit.Registers[15]	0	BOOL
URO.Bit.Registers[16]	0	BOOL
URO.Bit.Registers[17]	0	BOOL
URO.Bit.Registers[18]	0	BOOL
URO.Bit.Registers[19]	0	BOOL
URO.Bit.Registers[20] URO.Bit.Registers[21]	0	BOOL BOOL
URO.Bit.Registers[21]	0	BOOL
URO.Bit.Registers[23]	0	BOOL
URO.Bit.Registers[24]	0	BOOL
URO.Bit.Registers[25]	0	BOOL
URO.Bit.Registers[26]	0	BOOL
URO.Bit.Registers[27]	0	BOOL
URO.Bit.Registers[28]	0	BOOL
URO.Bit.Registers[29]	0	BOOL BOOL
URO.Bit.Registers[30] URO.Bit.Registers[31]	0	BOOL
URO.Bit.Registers[31]	$\overset{\circ}{0}$	BOOL
URO.Bit.Registers[33]	0	BOOL
URO.Bit.Registers[34]	0	BOOL
URO.Bit.Registers[35]	0	BOOL
URO.Bit.Registers[36]	0	BOOL
URO.Bit.Registers[37]	0	BOOL
URO.Bit.Registers[38]	0	BOOL
URO.Bit.Registers[39] URO.Bit.Registers[40]	0	BOOL BOOL
URO.Bit.Registers[41]	0	BOOL
URO.Bit.Registers[41]	$\overset{\circ}{0}$	BOOL
URO.Bit.Registers[43]	0	BOOL
URO.Bit.Registers[44]	0	BOOL
URO.Bit.Registers[45]	0	BOOL
URO.Bit.Registers[46]	0	BOOL
URO.Bit.Registers[47]	0	BOOL
URO.Bit.Registers[48] URO.Bit.Registers[49]	0	BOOL
URO.Bit.Registers[49]	0	BOOL BOOL
URO.Bit.Registers[51]	0	BOOL
URO.Bit.Registers[52]	0	BOOL
URO.Bit.Registers[53]	0	BOOL
URO.Bit.Registers[54]	0	BOOL
URO.Bit.Registers[55]	0	BOOL
URO.Bit.Registers[56]	0	BOOL
URO.Bit.Registers[57]	0	BOOL BOOL
URO.Bit.Registers[58] URO.Bit.Registers[59]	0	BOOL
URO.Bit.Registers[60]	0	BOOL
URO.Bit.Registers[61]	0	BOOL
URO.Bit.Registers[62]	0	BOOL
URO.Bit.Registers[63]	0	BOOL
URO.Int		UR_IntRegisters
URO.Int.Registers	0	DINT
URO.Int.Registers[0]	0	DINT
URO.Int.Registers[1] URO.Int.Registers[2]	0	DINT DINT
URO.Int.Registers[2]	0	DINT
URO.Int.Registers[3]	0	DINT
URO.Int.Registers[5]	0	DINT
URO.Int.Registers[6]	0	DINT
URO.Int.Registers[7]	0	DINT
URO.Int.Registers[8]	0	DINT
URO.Int.Registers[9]	0	DINT

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URO (Continued)		
URO.Int.Registers[10]	0	DINT
URO.Int.Registers[11]	0	DINT
URO.Int.Registers[12]	0	DINT
URO.Int.Registers[13]	0	DINT
URO.Int.Registers[14]	0	DINT
URO.Int.Registers[15]	0	DINT
URO.Int.Registers[16]	0	DINT
URO.Int.Registers[17]	0	DINT
URO.Int.Registers[18]	0	DINT
URO.Int.Registers[19]	0	DINT
URO.Int.Registers[20]	0	DINT
URO.Int.Registers[21]	0	DINT
URO.Int.Registers[22]	0	DINT
URO.Int.Registers[23]	0	DINT
URO.Float		UR_FloatRegisters
URO.Float.Registers		REAL
URO.Float.Registers[0]	0.0	REAL
URO.Float.Registers[1]	0.0	REAL
URO.Float.Registers[2]	0.0	REAL
URO.Float.Registers[3]	0.0	REAL
URO.Float.Registers[4]	0.0	REAL
URO.Float.Registers[5]	0.0	REAL
URO.Float.Registers[6]	0.0	REAL
URO.Float.Registers[7]	0.0	REAL
URO.Float.Registers[8]	0.0	REAL
URO.Float.Registers[9]	0.0	REAL
URO.Float.Registers[10]	0.0	REAL
URO.Float.Registers[11]	0.0	REAL
URO.Float.Registers[12]	0.0	REAL
URO.Float.Registers[13]	0.0	REAL
URO.Float.Registers[14]	0.0	REAL
URO.Float.Registers[15]	0.0	REAL
URO.Float.Registers[16]	0.0	REAL
URO.Float.Registers[17]	0.0	REAL
URO.Float.Registers[18]	0.0	REAL REAL
URO.Float.Registers[19]	0.0 0.0	
URO.Float.Registers[20] URO.Float.Registers[21]	0.0	REAL REAL
URO.Float.Registers[21]	0.0	REAL REAL
URO.Float.Registers[22]	0.0	REAL REAL
OKO.Fivat.Registers[25]	0.0	NEAL

Robot Station:MainTask:MainProgram Total number of rungs in routine: 5

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Robot\_Ladder\_Logic - Ladder Diagram Robot\_Station:MainTask:MainProgram Total number of rungs in routine: 5

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	Control Robot	
(End)		
(End)		

Page 1

Robot Station:MainTask:MainProgram Total number of rungs in routine: 4

... LAB\ 3 - ROBOT STATION\FINAL LAB ROBOT AB L24ER.ACD

