

Basic Modelling

Helmut Simonis

email: `helmut.simonis@insight-centre.org`
homepage: `http://http://insight-centre.org/`

Insight SFI Centre for Data Analytics
School of Computer Science and Information Technology
University College Cork
Ireland

CRT-AI CP Week 2025

This work is licensed under the Creative Commons Attribution-Noncommercial-Share Alike 3.0 Unported License. To view a copy of this license, visit <http://creativecommons.org/licenses/by-nc-sa/3.0/> or send a letter to Creative Commons, 171 Second Street, Suite 300, San Francisco, California, 94105, USA.



Acknowledgments

This publication has emanated from research conducted with the financial support of Science Foundation Ireland under Grant number 12/RC/2289-P2 at Insight the SFI Research Centre for Data Analytics at UCC, which is co-funded under the European Regional Development Fund.

A version of this material was developed as part of the ECLiPSe ELearning course: <https://eclipseclp.org/ELearning/index.html>. Support from Cisco Systems and the Silicon Valley Community Foundation is gratefully acknowledged.

Example 2: Sudoku

- Global Constraints
 - Powerful modelling abstractions
 - Non-trivial propagation
 - Different consistency levels
- Example: Sudoku puzzle

1 Problem

Figure 1: Example Problem and Solution

[illegible]

Model

- A variable for each cell, ranging from 1 to 9
- A 9x9 matrix of variables describing the problem
- Preassigned integers for the given hints
- `alldifferent` constraints for each row, column and 3x3 block

Sudoku Models

- ECLiPSe Show
- MiniZinc Show
- NumberJack Show
- CPMpy Show
- Choco-solver Show

ECLiPSe Sudoku Model (from <https://eclipseclp.org/>)

```
:- lib(ic).
:- import alldifferent/1 from ic_global.

top :-
    problem(Board),
    print_board(Board),
    sudoku(Board),
    labeling(Board),
    print_board(Board).

sudoku(Board) :-
    dim(Board, [N,N]),
    Board :: 1..N,
    ( for(I,1,N), param(Board) do
        alldifferent(Board[I,*]),
        alldifferent(Board[*,I])
    ),
    NN is integer(sqrt(N)),
    ( multifor([I,J],1,N,NN), param(Board,NN) do
        alldifferent(concat(Board[I..I+NN-1, J..J+NN-1]))
    ).

print_board(Board) :-
    dim(Board, [N,N]),
    ( for(I,1,N), param(Board,N) do
        ( for(J,1,N), param(Board,I) do
            X is Board[I,J],
            ( var(X) -> write(" ") ; printf("%2d", [X]) )
        ), nl
    ), nl.
```

ECLiPSe Data Definition

```
problem([ (
    [ (4, _, 8, _, _, _, _, _),
    [ (_, _, 1, 7, _, _, _, _),
    [ (_, _, _, 8, _, 3, 2),
    [ (_, 6, _, 8, 2, 5, _),
    [ (_, 9, _, _, _, 8, _),
    [ (_, 3, 7, 6, _, 9, _),
    [ (2, 7, _, 5, _, _, _),
    [ (_, _, 1, 4, _, _, _),
    [ (_, _, _, _, 6, _, 4) ) ).
```

Continue

MiniZinc Sudoku Model

```
int: s;
int: n=s*s;
array[1..n,1..n] of var 1..n: puzzle;

include "sudoku.dzn";

predicate alldifferent(array[int] of var int: x) =
    forall(i,j in index_set(x) where i < j)
        (x[i] != x[j]);

constraint forall(i in 1..n)
    (alldifferent([puzzle[i,j] | j in 1..n]));
constraint forall(j in 1..n)
    (alldifferent([ puzzle[i,j] | i in 1..n]));
constraint forall(i,j in 1..s)
    (alldifferent([puzzle[s*(i-1)+p, s*(j-1)+q] |
        p,q in 1..s]));

solve satisfy;
```

MiniZinc Output

```
output [ "sudoku:\n" ] ++
[ show(puzzle[i,j]) ++
  if j = n then
    if i mod s = 0 /\ i < n then "\n\n"
    else "\n"
    endif
  else
    if j mod s = 0 then " "
    else " "
    endif
  endif
| i,j in 1..n ];
```

MiniZinc Data File (sudoku.dzn)

```
s=3;
puzzle=[
  4, _, 8, _, _, _, _, _|
  _, _, 1, 7, _, _, _, _|
  _, _, _, 8, _, 3, 2|
  _, 6, _, 8, 2, 5, _|
  _, 9, _, _, _, 8, _|
  _, 3, 7, 6, _, 9, _|
  2, 7, _, 5, _, _, _|
  _, _, 1, 4, _, _, _|
  _, _, _, _, 6, _, 4|
];
```

Continue

NumberJack Sudoku Model

```
from Numberjack import *

def get_model(N, clues):
    grid = Matrix(N*N, N*N, 1, N*N)

    sudoku = Model([AllDiff(row) for row in grid.row],
                   [AllDiff(col) for col in grid.col],
                   [AllDiff(grid[x:x + N, y:y + N]) for x in range(0, N*N, N)
                    for y in range(0, N * N, N)],
                   [(x == int(v)) for x, v in
                    zip(grid.flat, "".join(open(clues).split()) if v != '*')]
                  ])
    return grid, sudoku

def solve(param):
    N = param['N']
    clues = param['file']

    grid, sudoku = get_model(N, clues)

    solver = sudoku.load(param['solver'])
    solver.setVerbosity(param['verbose'])
    solver.setTimeLimit(param['tcutoff'])

    solver.solve()
```

NumberJack Data File

```
4 * 8 * * * * *
* * * 1 7 * * *
* * * * 8 * * 3 2
* * 6 * * 8 2 5 *
* 9 * * * * 8 *
* 3 7 6 * * 9 *
2 7 * * 5 * * *
* * * * 1 4 * *
* * * * * 6 * 4
```

Continue

CPMpy Sudoku Model(from <https://github.com/CPMpy/>)

```
import numpy as np
from cpmPy import *

# Variables
puzzle = intvar(1,9, shape=given.shape, name="puzzle")

model = Model(
    # Constraints on values (cells that are not empty)
    puzzle[given!=e] == given[given!=e], # numpy's indexing, vectorized equality
    # Constraints on rows and columns
    [AllDifferent(row) for row in puzzle],
    [AllDifferent(col) for col in puzzle.T], # numpy's Transpose
)

# Constraints on blocks
for i in range(0,9, 3):
    for j in range(0,9, 3):
        model += AllDifferent(puzzle[i:i+3, j:j+3]) # python's indexing

model.solve()
```

CPMpy Data Definition

```
e = 0 # value for empty cells
given = np.array([
    [4, e, 8, e, e, e, e, e, e],
    [e, e, e, 1, 7, e, e, e, e],
    [e, e, e, e, 8, e, e, 3, 2],
    [e, e, 6, e, e, 8, 2, 5, e],
    [e, 9, e, e, e, e, e, 8, e],
    [e, 3, 7, 6, e, e, e, 9, e],
    [2, 7, e, e, 5, e, e, e, e],
    [e, e, e, e, 1, 4, e, e, e],
    [e, e, e, e, e, e, 6, e, 4]
])
```

Continue

Choco-solver Sudoku Model

```
Model model = new Model("Sudoku");
int blockSize = 3;
int m = blockSize*blockSize;

IntVar[][] vars = new IntVar[m][m];
for(int i=0; i<m; i++){
    for(int j=0; j<m; j++){
        vars[i][j] = model.intVar("X"+i+"-"+j, 1, m);
        if (data[i][j]>0) {
            model.arithm(vars[i][j], "=", data[i][j]).post();
        }
    }
}
```

```

    }
}
for(int i=0;i<m;i++){
    model.allDifferent(row(i,m,vars)).post();
    model.allDifferent(column(i,m,vars)).post();
}
for(int i=0;i<m;i+=blockSize){
    for(int j=0;j<m;j+=blockSize){
        model.allDifferent(block(i,j,blockSize,vars)).post();
    }
}
}
Solver solver = model.getSolver();
solver.solve();

```

Choco-solver Data

```

int[][] data = new int[m][m]{
    {4, 0, 8, 0, 0, 0, 0, 0, 0, 0},
    {0, 0, 0, 1, 7, 0, 0, 0, 0, 0},
    {0, 0, 0, 0, 8, 0, 0, 3, 2},
    {0, 0, 6, 0, 0, 8, 2, 5, 0},
    {0, 9, 0, 0, 0, 0, 0, 0, 8, 0},
    {0, 3, 7, 6, 0, 0, 9, 0, 0},
    {2, 7, 0, 0, 5, 0, 0, 0, 0},
    {0, 0, 0, 0, 1, 4, 0, 0, 0},
    {0, 0, 0, 0, 0, 0, 6, 0, 4}
};

```

Choco-solver Utilities

```

IntVar[] row(int row, int size, IntVar[][] array){
    return array[row];
}

IntVar[] column(int col,int size,IntVar[][] array){
    IntVar[] column = new IntVar[size];
    for(int i=0; i<size; i++){
        column[i] = array[i][col];
    }
    return column;
}

IntVar[] block(int x,int y,int blockSize,IntVar[][] array){
    IntVar[] block = new IntVar[blockSize*blockSize];
    int k=0;
    for(int i=0;i<blockSize;i++){
        for(int j=0;j<blockSize;j++){
            block[k++] = array[x+i][y+j];
        }
    }
    return block;
}

```

Continue

Domain Visualizer

- Problem shown as matrix
- Each cell corresponds to a variable
- Instantiated: Shows integer value (large)
- Uninstantiated: Shows values in domain

2 Initial Propagation (Forward Checking)

Figure 2: Initial State (Forward Checking)

4	1 2 3 4 5 6 7 8 9	8	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9
1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 7	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9
1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	8	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	3	2	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9
1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	6	1 2 3 4 5 6 7 8 9	8	2	5	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9
1 2 3 4 5 6 7 8 9	9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	8	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9
1 2 3 4 5 6 7 8 9	3	7	6	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9
2	7	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	5	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9
1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1	4	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9
1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	6	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	4

Figure 3: Propagation Steps (Forward Checking)

4	1 2 3 4 5 6 7 8 9	8	2 3 5 6 9	2 3 5 6 9	2 3 5 6 9	1 5 7	1 6 7	1 5 6 7 9	1 5 6 7 9
3 6 9	2 5 6 9	3 5 9	1 7	2 3 5 6 9	2 3 5 6 9	4 5 8	4 6 9	5 6 8 9	5 6 8 9
6 7 9	1 5 6 7 9	1 5 9	4 5 9	8	5 6 9	4 5 7	3 2	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9
1 5 8	4 9 2	6 7 3	3 7 9	8	2	5	7 9	3 2	5 6
5 8 3	9 3 7	2 6 4	3 4 6	1 7 5	1 3 4	1 3 4	8 7 5	1 3 6	1 3 6
8 2 7	3 7 4	7 4 3	6 4 3	9	5 6 4	9 8 3	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9
3 6 7	2 5 6 8	3 5 9	2 3 5 6 9	1 4	3 5 7	2 6 9	3 6 9	5 6 8 9	5 6 8 9
3 7 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	2 3 5 6 9	2 3 5 6 9	1 2 3 4 5 6 7 8 9	6	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	4

Figure 4: After Setup (Forward Checking)

4	^{1 2} 5 6	8	^{2 3} 5 9	³ 6 9	^{2 3} 6 9	¹ 5 7	¹ 6 7	^{5 6} 7 9
³ 6 9	² 5 6	³ 5 9	1	7	^{2 3} 6 9	^{4 5} 8	⁶ 9	^{5 6} 8 9
¹ 6 7	^{1 5 6} 9	¹ 5 9	^{4 5} 9	8	¹ 6 7	^{4 5} 9	3	2
1	4	6	³ 7 9	³ 9	8	2	5	³ 7
5	9	2	⁴ 7	³ 4	^{3 1} 7	³ 7	8	³ 6 7
8	3	7	6	2	5	9	4	1
2	7	¹ 4	³ 9	³ 8 9	5	^{3 1} 6 9	³ 8	² 9
³ 6 9	^{5 6} 8	³ 5 9	^{2 3} 7 8 9	1	4	⁵ 7 8	² 7 9	³ 5 7 8 9
^{3 1} 9	⁵ 8	¹ 5 9	³ 7 8 9	^{2 3} 9	³ 7	^{2 3} 6 9	^{1 2} 7 9	4

3 Improved Reasoning

Can we do better?

- The alldifferent constraint is missing propagation
 - How can we do more propagation?
 - Do we know when we derive all possible information from the constraint?
- Constraints only interact by changing domains of variables

3.1 Bounds Consistency

A Simpler Example

```
include "alldifferent.mzn";

var 1..2:X;
var 1..2:Y;
var 1..3:Z;

constraint alldifferent([X,Y,Z]);

solve satisfy;
```

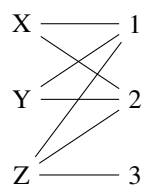
Using Forward Checking

- No variable is assigned
- No reduction of domains
- But, values 1 and 2 can be removed from Z
- This means that Z is assigned to 3

Visualization of alldifferent as Graph

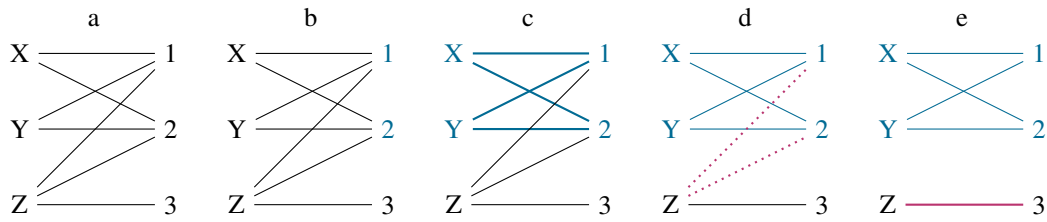
- Show problem as graph with two types of nodes
 - Variables on the left
 - Values on the right
- If value is in domain of variable, show link between them
- This is called a *bipartite* graph

Figure 5: Visualization of alldifferent as bipartite graph



A Simpler Example

Figure 6: A Simpler Example



Idea (Hall Intervals)

- Take each interval of possible values, say size N
- Find all K variables whose domain is completely contained in interval
- If $K > N$ then the constraint is infeasible
- If $K = N$ then no other variable can use that interval
- Remove values from such variables if their bounds change
- If $K < N$ do nothing
- Re-check whenever domain bounds change

Implementation

- Problem: Too many intervals ($O(n^2)$) to consider
- Solution:
 - Check only those intervals which update bounds
 - Enumerate intervals incrementally
 - Starting from lowest(highest) value
 - Using sorted list of variables
- Complexity: $O(n \log(n))$ in standard implementations
- Important: Only looks at min/max bounds of variables

Bounds Consistency

Definition

A constraint achieves *bounds consistency*, if for the lower and upper bound of every variable, it is possible to find values for all other variables between their lower and upper bounds which satisfy the constraint.

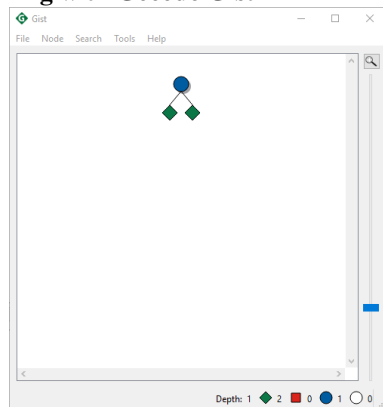
Annotation: :: bounds

```
include "alldifferent.mzn";

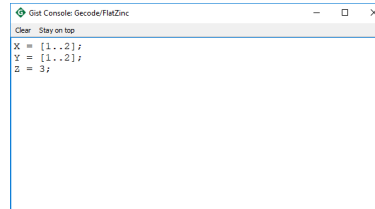
var 1..2:X;
var 1..2:Y;
var 1..3:Z;

constraint alldifferent([X,Y,Z]) :: bounds;
solve satisfy;
```

Running with Gecode Gist



All Solutions



Node Inspector (Root)

Can we do even better?

- Bounds consistency only considers min/max bounds
- Ignores “holes” in domain
- Sometimes we can improve propagation looking at those holes

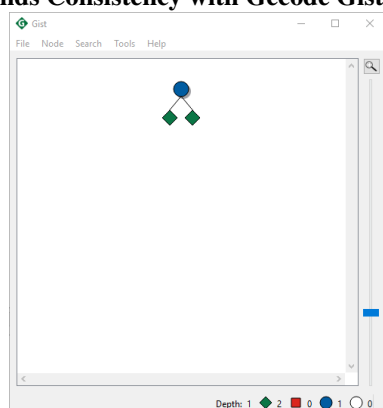
Another Simple Example

```
include "alldifferent.mzn";

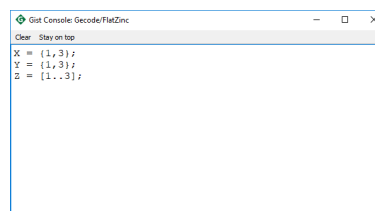
var {1,3}:X; % note enumerated domain
var {1,3}:Y;
var 1..3:Z; % note domain as interval

% annotated constraint
constraint alldifferent([X,Y,Z]) :: bounds;
solve satisfy;
```

Bounds Consistency with Gecode Gist: No Propagation



All Solutions



Node Inspector (Root)

Solutions and Maximal Matchings

- A *Matching* is subset of edges which do not coincide in any node
- No matching can have more edges than number of variables

Figure 7: Another Example

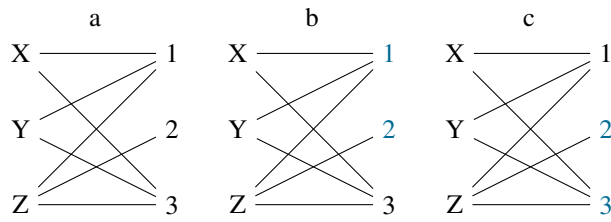
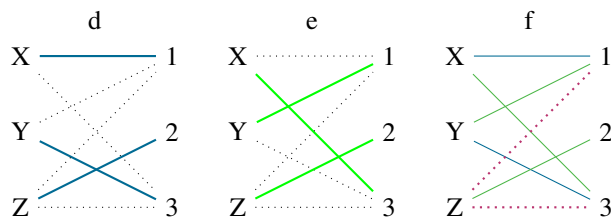


Figure 8: Another Example (Continued)



- Every solution corresponds to a *maximal matching* and vice versa
- If a link does not belong to some maximal matching, then it can be removed

Implementation

- Possible to compute all links which belong to some matching
 - Without enumerating all of them!
- Enough to compute **one** maximal matching
- Requires algorithm for *strongly connected components*
- Extra work required if more values than variables
- All links (values in domains) which are not supported can be removed
- Complexity: $O(n^{1.5}d)$

Domain Consistency

Definition

A constraint achieves *domain consistency*, if for every variable and for every value in its domain, it is possible to find values in the domains of all other variables which satisfy the constraint.

- Also called *generalized arc consistency (GAC)*
- or *hyper arc consistency*

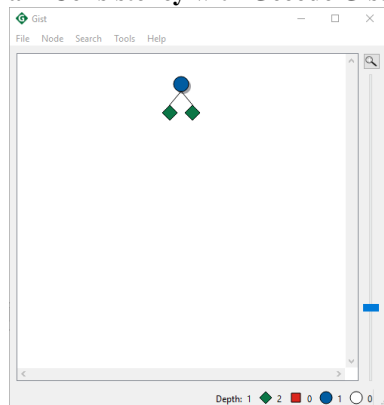
Simple Example Revisited

```
include "alldifferent.mzn";

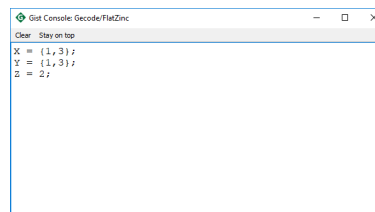
var {1,3}:X; % note enumerated domain
var {1,3}:Y;
var 1..3:Z; % note domain as interval

% note different annotation
constraint alldifferent([X,Y,Z]) :: domain;
solve satisfy;
```

Domain Consistency with Gecode Gist: Propagation



All Solutions



Node Inspector (Root)

Can we still do better?

- NO! This extracts all information from this one constraint
- We could perhaps improve speed, but not propagation
- But possible to use different model
- Or model interaction of multiple constraints

Should all constraints achieve domain consistency?

- Domain consistency is usually more expensive than bounds consistency
 - Overkill for simple problems
 - Nice to have choices
- For some constraints achieving domain consistency is NP-hard
 - We have to live with more restricted propagation

3.2 Domain Consistency

Modified MiniZinc Program

```
int: s;
int: n=s*s;
array[1..n,1..n] of var 1..n: puzzle;

include "sudoku.dzn";
```

Modified Choco-solver Sudoku Model

Figure 9: Initial State (Domain Consistency)

4	1 2 3 4 5 6 7 8 9	8	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9
1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1	7	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9
1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	8	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	3	2	
1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	6	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	8	2	5	1 2 3 4 5 6 7 8 9	
1 2 3 4 5 6 7 8 9	9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	8	1 2 3 4 5 6 7 8 9	
1 2 3 4 5 6 7 8 9	3	7	6	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	
1 2 3 4 5 6 7 8 9	2	7	1 2 3 4 5 6 7 8 9	5	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	
1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1	4	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	
1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	6	1 2 3 4 5 6 7 8 9	1 2 3 4 5 6 7 8 9	4

Typical?

- 13

Figure 10: Propagation Steps (Domain Consistency)

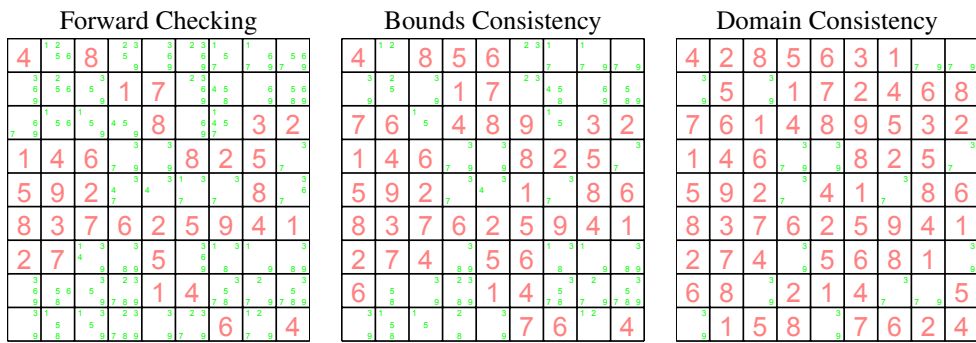
4	2	8	5	6	3	1	¹ _{7 9}	¹ _{5 6 7 9}
³ _{6 9}	5	³ _{5 9}	1	7	2	4	6	8
7	6	1	4	8	9	5	3	2
1	4	6	³ _{7 9}	³ ₉	8	2	5	³ _{7 9}
5	9	2	³ ₇	4	1	¹ _{4 7}	³ ₈	6
8	3	7	6	2	5	9	4	1
2	7	4	³ _{8 9}	5	6	8	1	¹ _{3 6 8 9}
6	8	³ _{5 9}	2	1	4	³ _{7 8}	² _{6 7 9}	5
³ ₉	1	5	8	² _{3 9}	7	6	2	4

Figure 11: After Setup (Domain Consistency)

4	2	8	5	6	3	1	⁷ ₉	⁷ ₉
³ ₉	5	³ ₉	1	7	2	4	6	8
7	6	1	4	8	9	5	3	2
1	4	6	³ _{7 9}	³ ₉	8	2	5	³ ₇
5	9	2	³ ₇	4	1	³ ₇	8	6
8	3	7	6	2	5	9	4	1
2	7	4	³ ₉	5	6	8	1	³ ₉
6	8	³ ₉	2	1	4	³ ₇	⁷ ₉	5
³ ₉	1	5	8	³ ₉	7	6	2	4

- In general, tradeoff between speed and propagation
- Not always fastest to remove inconsistent values early
- But often required to find a solution at all

Figure 12: Comparison



4 Search

Simple search routine

- Enumerate variables in given order
- Try values starting from smallest one in domain
- Complete, chronological backtracking
- Advantage: Results can be compared with each other
- Disadvantage: Usually not a very good strategy

Asking for Naive Search in MiniZinc

```
solve :: int_search(  
  puzzle,  
  input_order,  
  indomain_min)  
satisfy;
```

Figure 13: Search Tree (Forward Checking)

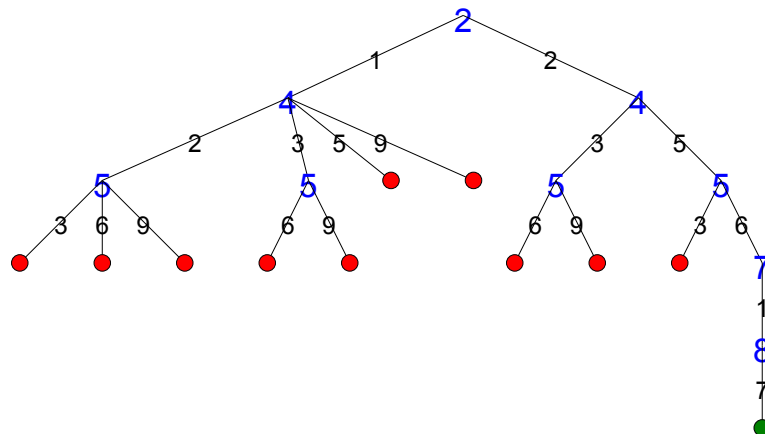
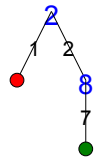


Figure 14: Search Tree (Bounds Consistency)



Trading Propagation Against Search

- If we perform more propagation, search is more constrained
- Fewer values left, fewer alternatives to explore in search
- Best compromise is not obvious
- But can be learned from examples or during search
- Annotations are optional
 - Some MiniZinc back-end solvers do the search they want, not the one you specify
 - Some solvers simply do not work in a way that these search annotations apply

5 Other Global Constraints

Are there other Global Constraints?

- alldifferent is the most commonly used constraint
- Propagation methods can be explained
- But there are many more

Figure 15: Search Tree (Domain Consistency)



Global Constraint Catalog

- <https://sofdem.github.io/gccat/>
- Description of 354 global constraints, 2800 pages
- Not all of them are widely used
- Detailed, meta-data description of constraints in Prolog

Families of Global Constraints

- Value Counting
 - alldifferent, global cardinality
- Scheduling
 - cumulative
- Properties of Sequences
 - sequence, no_valley
- Graph Properties
 - circuit, tree

Common Algorithmic Techniques

- Bi-Partite Matchning
- Flow Based Algorithms
- Automata
- Task Intervals
- Reduced Cost Filtering
- Decomposition