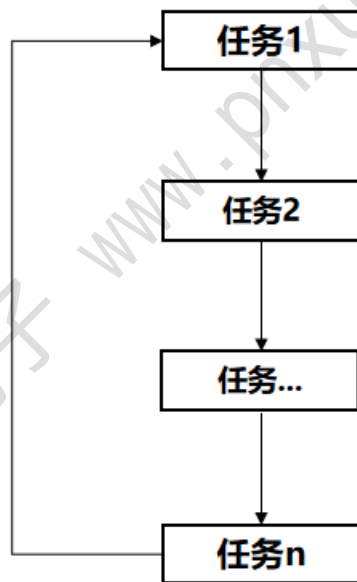


嵌入式C语言之- 函数指针和回调函数 裸机程序的任务调度

助力你成为优秀的电子工程师!

裸机任务调度方案1，大锅饭

```
int main(void)
{
    Init();
    while (1)
    {
        SensorTask();
        KeyScanTask();
        DisplayTask();
    }
}
```



裸机任务调度方案2，按需分配，效率更高

```
int main(void)
{
    Init();
    while (1)
    {
        if (period1sFlag)
        {
            SensorTask();
            period1sFlag = 0;
        }

        if (period20msFlag)
        {
            KeyScanTask();
            period20msFlag = 0;
        }
    }
}
```

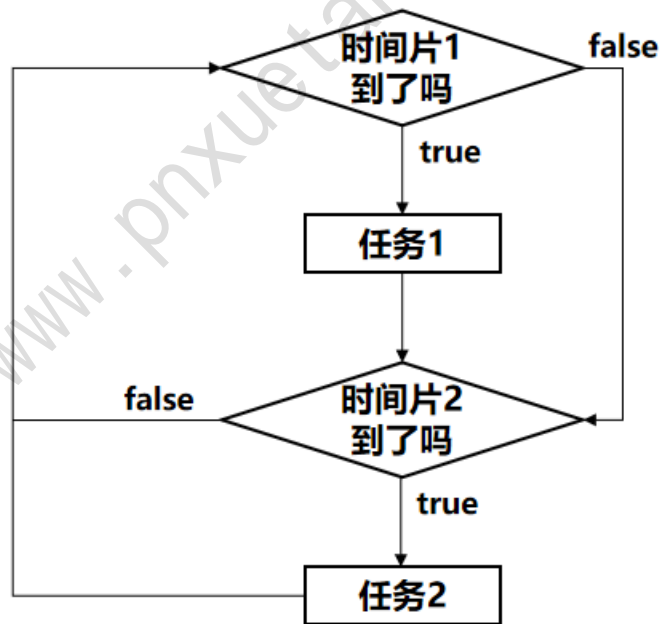
```
void TimerInterrupt(void)
{
    if (period1sNum)
    {
        period1sNum--;
        if (period1sNum == 0)
        {
            period1sFlag = 1;
            period1sNum = 1000;
        }
    }

    if (period20msNum)
    {
        period20msNum--;
        if (period20msNum == 0)
        {
            period20msFlag = 1;
            period20msNum = 20;
        }
    }
}
```

裸机任务调度方案2，按需分配，效率更高

```
int main(void)
{
    Init();
    while (1)
    {
        if (period1sFlag)
        {
            SensorTask();
            period1sFlag = 0;
        }

        if (period20msFlag)
        {
            KeyScanTask();
            period20msFlag = 0;
        }
    }
}
```



裸机任务调度方案3，按需分配，软件架构更优

```
int main(void)
{
    SYS_Init();

    while (1)
    {
        TaskHandler();
    }
}
```

```
void TaskHandler(void)
{
    uint8_t i;
    for(i=0; i<Tasks_Max; i++)
    {
        if(Task_Comps[i].Run) /* 判断任务时间片标记 */
        {
            Task_Comps[i].Run = 0; /* 标记清零 */
            Task_Comps[i].TaskHook(); /* 执行调度任务 */
        }
    }
}
```

裸机任务调度方案3，按需分配，软件架构更优

```
void TimerInterrupt(void)
{
    uint8_t i;
    for(i=0; i<Tasks_Max; i++)
    {
        if(Task_Comps[i].TIMCount) /* 判断时间片计数 */
        {
            Task_Comps[i].TIMCount--; /* 时间片计数递减 */
            if(Task_Comps[i].TIMCount == 0)
            {
                /*时间片标记为1，并重载计数初值 */
                Task_Comps[i].TIMCount = Task_Comps[i].TRITime;
                Task_Comps[i].Run = 1;
            }
        }
    }
}
```

裸机任务调度方案3，按需分配，软件架构更优

```
typedef struct
```

```
{  
  
    uint8_t Run;           //任务状态： Run/Stop  
    uint16_t TIMCount;     //时间片周期，用于递减计数  
    uint16_t TRITime;      //时间片周期，用于重载  
    void (*TaskHook) (void); //函数指针，保存任务函数地址  
} TASK_COMPONENTS;
```

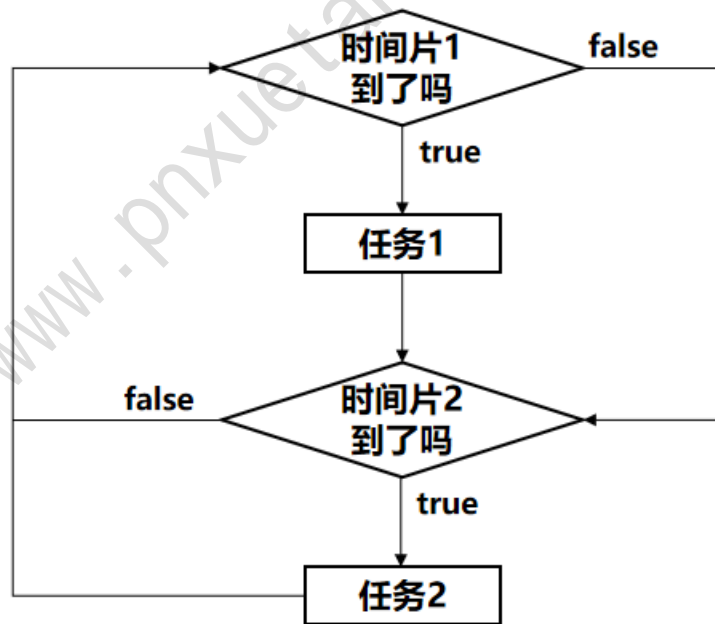
```
static TASK_COMPONENTS Task_Comps[] =
```

```
{  
  
    //状态 计数 周期 函数  
    {0, 1000, 1000, SensorTask}, /* task 1 Period: 1000ms */  
    {0, 20, 20, KeyScanTask}, /* task 2 Period: 20ms*/  
    /* Add new task here */  
};
```

裸机任务调度方案 VS RTOS

```
int main(void)
{
    Init();
    while (1)
    {
        if (period1sFlag)
        {
            SensorTask();
            period1sFlag = 0;
        }

        if (period20msFlag)
        {
            KeyScanTask();
            period20msFlag = 0;
        }
    }
}
```



FreeRTOS应用案例

```
BaseType_t xTaskCreate( TaskFunction_t pxTaskCode,  
                        const char * const pcName,  
                        const configSTACK_DEPTH_TYPE usStackDepth,  
                        void * const pvParameters,  
                        UBaseType_t uxPriority,  
                        TaskHandle_t * const pxCreatedTask )
```

```
typedef void (* TaskFunction_t)( void * );
```

```
xTaskCreate( vLCDTask, "LCD", configMINIMAL_STACK_SIZE, NULL, tskIDLE_PRIORITY, NULL );
```

RT-Thread应用案例

```
rt_thread_t rt_thread_create(const char *name,  
                             void (*entry)(void *parameter),  
                             void *parameter,  
                             rt_uint32_t stack_size,  
                             rt_uint8_t priority,  
                             rt_uint32_t tick);
```

```
rt_err_t rt_thread_init(struct rt_thread *thread,  
                        const char *name,  
                        void (*entry)(void *parameter),  
                        void *parameter,  
                        void *stack_start,  
                        rt_uint32_t stack_size,  
                        rt_uint8_t priority,  
                        rt_uint32_t tick);
```

```
rt_thread_create( "send", led_thread_entry, RT_NULL, 512, 2, 20);
```

应用案例

```
void UserProgram(void)
{
    lv_timer_t * timer = lv_timer_create(RefreshClockUI, 1000, NULL);
}
```

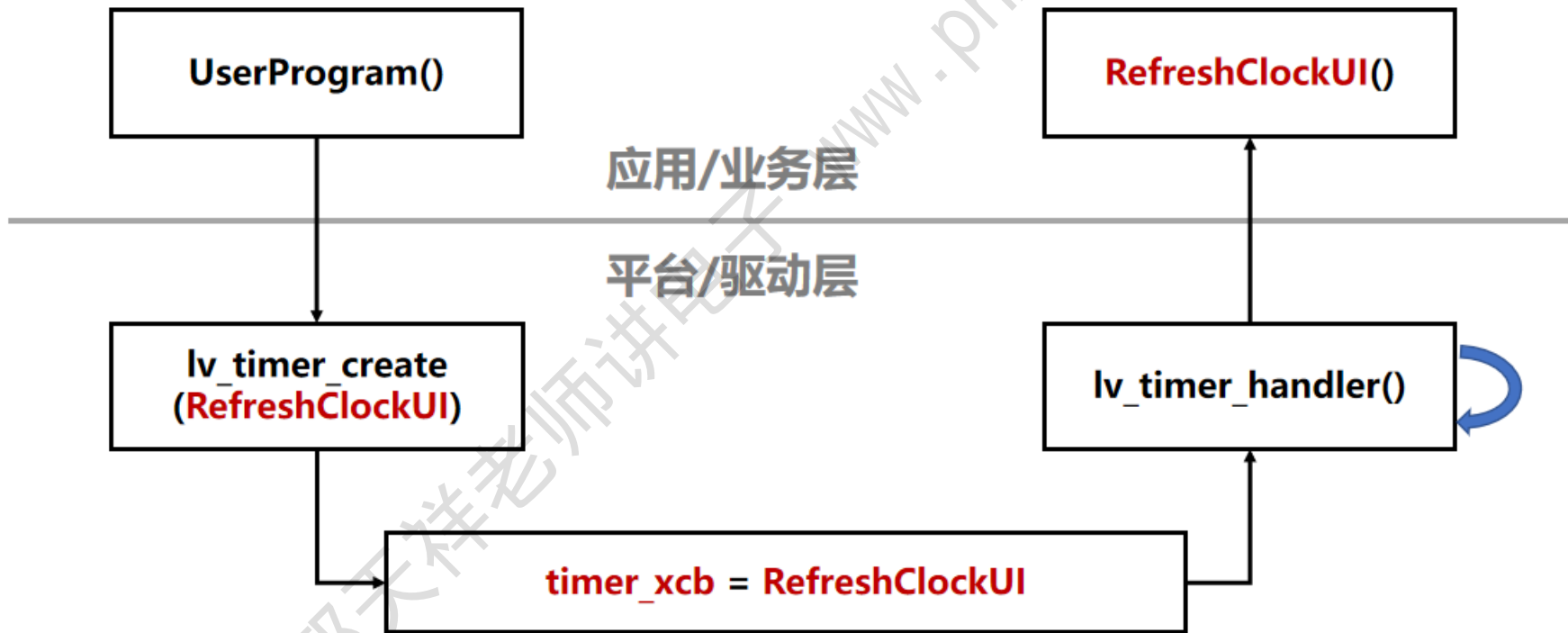
```
void RefreshClockUI(lv_timer_t *timer)
{
    time_t rawtime;
    struct tm *info;
    time(&rawtime);
    info = localtime(&rawtime);
    lv_label_set_text_fmt(label, "%02d:%02d:%02d",
        info->tm_hour, info->tm_min, info->tm_sec);
}
```

应用案例

```
void UserProgram(void)
{
    lv_timer_t * timer = lv_timer_create(RefreshClockUI, 1000, NULL);
}
```

```
void RefreshClockUI(lv_timer_t *timer)
{
    time_t rawtime;
    struct tm *info;
    time(&rawtime);
    info = localtime(&rawtime);
    lv_label_set_text_fmt(label, "%02d:%02d:%02d",
        info->tm_hour, info->tm_min, info->tm_sec);
}
```

```
void UserProgram(void)
{
    lv_timer_t * timer = lv_timer_create(RefreshClockUI, 1000, NULL);
}
```



回调函数和函数指针

```
void UserProgram(void)
{
    lv_timer_t * timer = lv_timer_create(RefreshClockUI, 1000, NULL);
}
```

- void RefreshClockUI(lv_timer_t *timer), 称为回调函数, 回调函数本身也是普通函数, 只是因为调用关系比较特别, 它的代码位于上层业务层, 却是由下层库代码去调用, 所以叫做回调函数;

```
lv_timer_t * lv_timer_create(lv_timer_cb_t timer_xcb, uint32_t period, void * user_data)
```

- lv_timer_cb_t timer_xcb, timer_xcb称为函数指针, 它用来保存回调函数的地址, 严谨一些, 应该称为函数指针类型的变量/函数指针变量;

函数指针变量

- 格式为:

函数返回值类型 (* 函数指针变量名) (函数参数列表);

- `int32_t (*pSum)(int32_t a, int32_t b);`

函数指针变量 `pSum`, 就像 `int32_t *ptr` 里的 `ptr` 一样;

- 函数名称就像数组名称一样保存了函数地址:

```
pSum = 0x0000070f, Sum = 0x0000070f
```

- `(*pSum)(1, 2)`, 表示间接访问并调用 `Sum` 函数。

```
int32_t Sum(int32_t x, int32_t y)
{
    return x + y;
}

int main(void)
{
    int32_t (*pSum)(int32_t a, int32_t b);
    pSum = Sum;
    printf("pSum = 0x%p, Sum = 0x%p\n",
           pSum, Sum);
    int32_t sum = (*pSum)(1, 2);
    printf("%d\n", sum);
    return 0;
}
```

单片机寻址范围

- 单片机通过地址来访问FLASH、内存和寄存器，ARM寻址范围4GB，分为多个块，FLASH对应地址范围是0x00000000-0x20000000。

0xFFFFFFFF	Cortex-M4 内核 寄存器
0xE0000000	没有使用
0xC0000000	
0xA0000000	EXMC
0x80000000	
0x60000000	片上外设
0x40000000	
0x20000000	SRAM
0x00000000	CODE

注：基于GD32F303单片机

函数指针和指针函数

- `int32_t (*pSum)(int32_t a, int32_t b);` 为什么`(*pSum)`要使用`()`?
- 如果不使用`()`, 变成了`int32_t *pSum(int32_t a, int32_t b);` 基于运算符优先级, `pSum`先结合`()`再结合`*`, 这种格式被称为指针函数, 表示返回值为指针类型的函数, 比如常见的:

`void *malloc(size_t size)`

`char *strcpy(char *dest, const char *src)`

- 使用`()`, 基于运算符优先级, `pSum`先结合`*`再结合后面的`()`, 这种格式用来定义函数指针变量, 变量是`pSum`。

函数指针

```
int32_t Sum(int32_t x, int32_t y)
{
    return x + y;
}

int main(void)
{
    int32_t (*pSum)(int32_t a, int32_t b);
    pSum = Sum;
    int32_t sum = (*pSum)(1, 2);
    printf("%d\n", sum);
    return 0;
}
```

```
int32_t Sum(int32_t x, int32_t y)
{
    return x + y;
}

void RegAndHandle(int32_t (*pSum)(int32_t a, int32_t b));

int main(void)
{
    RegAndHandle(Sum);
    return 0;
}

void RegAndHandle(int32_t (*pSum)(int32_t a, int32_t b))
{
    int32_t sum = (*pSum)(1, 2);
    printf("%d\n", sum);
}
```

函数指针类型和函数指针变量

```
void RegAndHandle(int32_t (*pSum)(int32_t a, int32_t b))
```

- 如果程序中很多地方都需要定义这种函数指针类型的变量，书写起来太繁琐，可以使用typedef重定义：

```
typedef int32_t (*PFUNC)(int32_t a, int32_t b);  
  
void RegAndHandle(PFUNC pSum)  
{  
    int32_t sum = (*pSum)(1, 2);  
    printf("%d\n", sum);  
}
```

函数指针类型和函数指针变量

```
typedef int32_t (*PFUNC)(int32_t a, int32_t b);
```

➤ 为什么函数指针类型的变量PFUNC还可以作为数据类型？

1. 这里typedef，和常规用法不太一样：

```
typedef signed char int8_t;
```

2. 当有typedef时，**PFUNC表示函数指针类型**，PFUNC pSum；当没有typedef时，int32_t (*pSum)(int32_t a, int32_t b)，**pSum表示变量**，pSum = Sum。

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                        const configSTACK_DEPTH_TYPE usStackDepth,  
                        void * const pvParameters,  
                        UBaseType_t uxPriority,  
                        TaskHandle_t * const pxCreatedTask )
```

```
typedef void (* TaskFunction_t)( void * );
```

```
xTaskCreate( vLCDTask, "LCD", configMINIMAL_STACK_SIZE, NULL, tskIDLE_PRIORITY, NULL );
```

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                             void (*entry)(void *parameter),  
                             void *parameter,  
                             rt_uint32_t stack_size,  
                             rt_uint8_t priority,  
                             rt_uint32_t tick);
```

```
rt_err_t rt_thread_init(struct rt_thread *thread,  
                        const char *name,  
                        void (*entry)(void *parameter),  
                        void *parameter,  
                        void *stack_start,  
                        rt_uint32_t stack_size,  
                        rt_uint8_t priority,  
                        rt_uint32_t tick);
```

```
rt_thread_create( "send", led_thread_entry, RT_NULL, 512, 2, 20);
```

函数指针扩展

```
int32_t Sum(int32_t x, int32_t y)
{
    return x + y;
}

int main(void)
{
    int32_t (*pSum)(int32_t a, int32_t b);
    pSum = Sum;
    printf("pSum = 0x%p, Sum = 0x%p\n", pSum, Sum);
    int32_t sum = (*pSum)(1, 2);
    printf("%d\n", sum);
    sum = pSum(1, 2);
    sum = (*Sum)(1, 2);
    return 0;
}
```

函数指针应用案例



时间设置



亮度调节



定时熄/亮屏



无线网络



有线网络



绑定设备



版本信息



设备管理

```
typedef struct desktop_interface
{
    const lv_img_dsc_t *app_icon;
    const char *app_name;
    void (*app_event_cb)(lv_event_t * event);
} AppInfo_t;
```

```
static AppInfo_t applInfo[] =
{
    {&img_set_time, "时间设置", set_time_event_cb},
    {&img_set_backlight, "亮度调节", set_backlight_event_cb},
    {&img_dev_manage, "设备管理", dev_manage_event_cb},
    ...
}

uint8_t APP_MAX = sizeof(applInfo)/sizeof(applInfo[0]);

...

for (uint8_t i = 0; i < APP_MAX; i++)
{
```


THANK YOU!