

Non-local granular fluidity(NGF) model

Equations of motion

$$\frac{\partial \sigma_{ij}}{\partial x_j} + \phi \rho_s G_i = \phi \rho_s \dot{v}_i$$

with $\sigma_{ij} = -P\delta_{ij} + 2\frac{P}{g}D_{ij}$ and $D_{ij} = \frac{1}{2} \left(\frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} \right)$

Nonlocal rheology

Granular fluidity $\rightarrow g = g^{\text{loc}}(\mu, P) + \xi^2(\mu) \frac{\partial^2 g}{\partial x_j \partial x_j}$

Local rheology

$$g^{\text{loc}}(\mu, P) = \begin{cases} \frac{1}{\mu} \sqrt{\frac{P}{\rho_s d^2}} \left(\frac{\mu - \mu_s}{b} \right)^{1/\alpha} & \mu > \mu_s \\ 0 & \mu \leq \mu_s \end{cases}$$

Cooperativity length

$$\xi(\mu) = \begin{cases} \frac{A}{\sqrt{\alpha(\mu - \mu_s)}} d & \mu > \mu_s \\ \frac{A}{\sqrt{(\mu - \mu_s)}} d & \mu \leq \mu_s \end{cases}$$

with $\tau = (\sigma'_{ij} \sigma'_{ij} / 2)^{1/2}$, $\mu = \tau / P$, and $\dot{\gamma} = (2D_{ij} D_{ij})^{1/2}$

- Model parameters[†] are $\{\underbrace{\mu_s, b, \alpha}_{\text{Local parameters}}, \underbrace{A}_{\text{Non-local parameter}}\}$

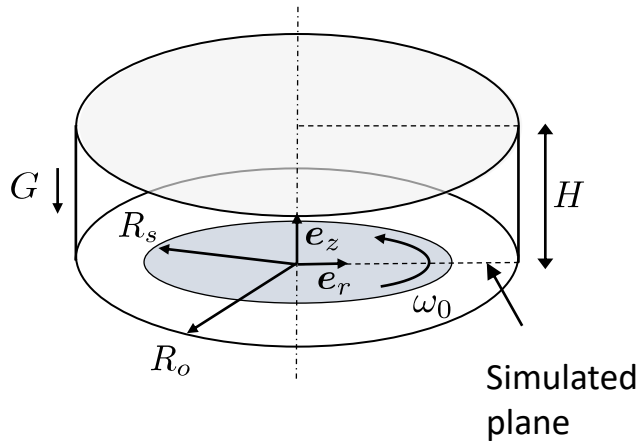
Local parameters

Non-local parameter

[†] Frictional glass beads:
 $\{\mu_s = 0.37, b = 1.0, \alpha = 0.7, A = 0.48\}$

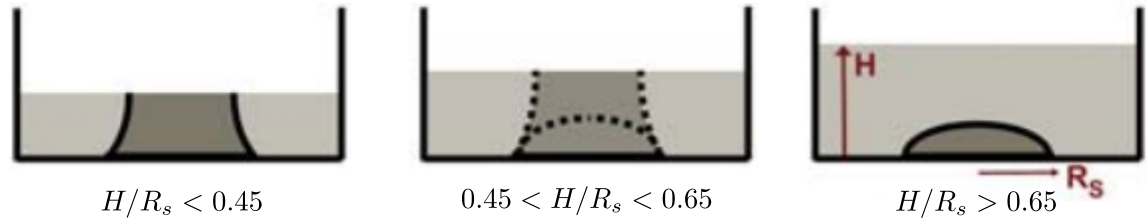
Polyacrylamide hydrogels:
 \rightarrow **Ongoing research**

Split-Bottom shear cell



Fenistein and Van Hecke, Nature(2003)

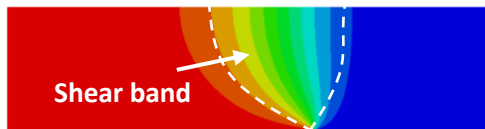
Fenistein et.al, PRL(2004), PRL(2006)



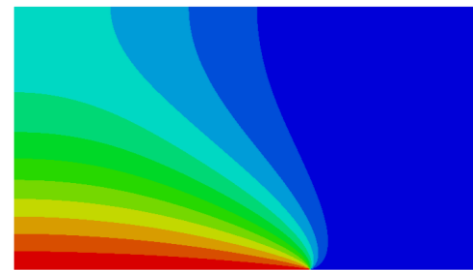
Hard frictional grains: Joshua and Van Hecke, Soft Matter(2010)

The two main factors that dictate the flow are

(1) H/R_s



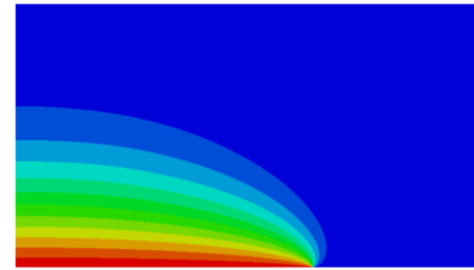
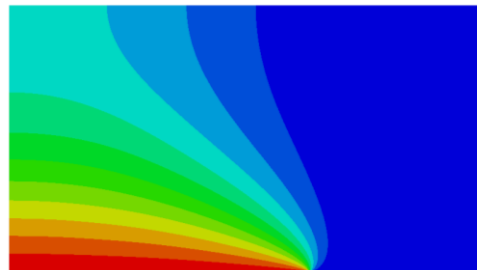
$H/R_s = 0.42$



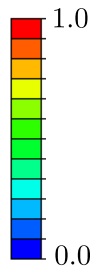
$H/R_s = 0.9$

$P \downarrow$

Free surface



ω/ω_0



(2) Confined pressure[†] P

[†] Recent experimental observations in soft polyacrylamide hydrogels

Finite deformation plasticity framework for dense granular flows

Free energy imbalance: $\dot{\psi} - \underbrace{\frac{1}{2}T^e : C^e}_{\text{Elastic power}} - \underbrace{M^e : L^P}_{\text{Plastic power}} \leq 0$

where $T^e = JF^{e-1}TF^{e-T}$ is the second Piola stress and $M^e = C^eT^e$ is the Mandel stress

Consequence of isotropy of elastic response

C^e and T^e have same eigenvalues $\Rightarrow M^e = JR^{eT}TR^e \rightarrow$ symmetric

Free energy and elastic response

$$\psi^\dagger = G|E_o^e|^2 + \frac{1}{2}K(tr E^e)^2 \quad \text{where } E^e = \sum_{i=1}^3 \ln \lambda_i^e r_i^e \otimes r_i^e \quad \leftarrow \text{Hencky strain}$$

$$\text{Mandel stress} \Rightarrow M^e = 2GE_o^e + K(tr E^e)I \quad \text{and} \quad \bar{p} = -\frac{1}{3}tr M^e$$

Define equivalent shear stress $\bar{\tau}$ and stress ratio μ

$$\bar{\tau} = \frac{1}{\sqrt{2}}|M_o^e| \quad \text{and} \quad \mu = \frac{\bar{\tau}}{\bar{p}}$$

Yield conditon

$$\mu = \mu_s \Rightarrow \begin{cases} \mu \geq \mu_s & \text{Plastic} \\ \mu < \mu_s & \text{Elastic} \end{cases}$$

† Since we are going to study the well developed granular flow which is the outcome of perfectly plastic deformations. Thus the elastic response does not really matter, so we adopt the simple quadratic expression for the free energy in terms of Hencky strain.

Flow rule

Evolution equation $\dot{F}^p = D^p F^p$

Define unit flow tensor $N^p = \frac{D^p}{|D^p|}$ and equivalent plastic shear $\dot{\gamma}^p = \sqrt{2} |D^p|$

Assume co-directionality $N^p = \frac{M_0^e}{|M_0^e|} \Rightarrow D^p = \frac{1}{2} \dot{\gamma}^p \frac{M_0^e}{\bar{\tau}}$

Rate-dependence $\dot{\gamma}^p = g\mu$

\uparrow
Granular fluidity

- Plastic response is rate-dependent and perfectly plastic with no hardening
- Local agitations can cause agitation in the far away material even if it's below yield

Local fluidity

$$g^{\text{loc}}(\bar{p}, \mu) = \begin{cases} \frac{1}{\mu} \sqrt{\frac{\bar{p}}{\rho_s d^2}} \left(\frac{\mu - \mu_s}{b} \right)^{1/\alpha} & \mu > \mu_s \\ 0 & \mu \leq \mu_s \end{cases}$$

Coperativity length

$$\xi(\mu) = \begin{cases} \frac{A}{\sqrt{\alpha(\mu - \mu_s)}} d & \mu > \mu_s \\ \frac{A}{\sqrt{(\mu - \mu_s)}} d & \mu \leq \mu_s \end{cases}$$

- NGF model can be implemented using user defined elements(UEL) in Abaqus

Constitutive update: Time integration procedure

Given F_n^P at time t_n and $\{F_{n+1}, g_{n+1}\}$ at time t_{n+1}

Determine $\{T_{n+1}, F_{n+1}^P, g_{n+1}^{loc}, \xi_{n+1}\}$

Begin by integrating the evolution equation for F^P via exponential map

$$F_{n+1}^p = \exp(\Delta t D_{n+1}^p) F_n^p \Rightarrow F_{n+1}^{p-1} = F_n^{p-1} \exp(-\Delta t D_{n+1}^p)$$

Recall Kroner-Lee decomposition $F_{n+1} = F_{n+1}^e F_{n+1}^p$

$$\Rightarrow F_{n+1}^e = F_{n+1} F_{n+1}^{p-1} \Rightarrow F_{n+1}^e = \underbrace{F_{n+1} F_n^{p-1}}_{F_{tr}^e} \exp(-\Delta t D_{n+1}^p) \quad (1)$$

Trial value of F^e assuming plastic flow is frozen

Polar Decomposition

$$F_{n+1}^e = R_{n+1}^e U_{n+1}^e \quad \text{and} \quad F_{tr}^e = R_{tr}^e U_{tr}^e$$

Using (1)

$$R_{n+1}^e U_{n+1}^e \exp(\Delta t D_{n+1}^p) = R_{tr}^e U_{tr}^e$$

$$\Rightarrow \begin{cases} R_{n+1}^e = R_{tr}^e \\ U_{n+1}^e = U_{tr}^e \exp(-\Delta t D_{n+1}^p) \end{cases}$$

Taking log

$$E_{n+1}^e = E_{tr}^e - \Delta t D_{n+1}^p \quad \text{with} \quad E_{tr}^e = \ln(U_{tr}^e)$$

Using stress strain relation

$$M_{n+1}^e = M_{tr}^e - 2G\Delta t D_{n+1}^p \quad \text{with} \quad M_{tr}^e = \mathbb{C}[E_{tr}^e] \quad (2)$$

with $\dot{\gamma}_{n+1}^p = \sqrt{2} |D_{n+1}^p|$ $N_{n+1}^p = D_{n+1}^p / |D_{n+1}^p|$, we write $D_{n+1}^p = \frac{1}{\sqrt{2}} \dot{\gamma}_{n+1}^p N_{n+1}^p$

$$\text{Also, } \dot{\gamma}_{n+1}^p = g_{n+1} \mu_{n+1} \quad \text{and} \quad N_{n+1}^p = \frac{M_{0,n+1}^e}{\sqrt{2} \bar{\tau}_{n+1}} \quad (3)$$

$$\text{where, } \bar{\tau}_{n+1} = \frac{1}{\sqrt{2}} |M_{0,n+1}^e|, \quad \bar{p}_{n+1} = -\frac{1}{3} \text{tr} M_{n+1}^e, \quad \text{and} \quad \mu_{n+1} = \frac{\bar{\tau}_{n+1}}{\bar{p}_{n+1}} \quad (4)$$

Using (2)

$$M_{n+1}^e = M_{tr}^e - \sqrt{2} G(\Delta t \dot{\gamma}_{n+1}^p) N_{n+1}^p \Rightarrow \begin{cases} M_{0,n+1}^e = M_{0,tr}^e - \sqrt{2} G(\Delta t \dot{\gamma}_{n+1}^p) N_{n+1}^p \\ \bar{p}_{n+1} = \bar{p}_{tr} \end{cases}$$

In terms of equivalent shear stress

$$(\bar{\tau}_{n+1} + G(\Delta t \dot{\gamma}_{n+1}^p)) N_{n+1}^p = \bar{\tau}_{tr} N_{tr}^p \Rightarrow \begin{cases} \bar{\tau}_{n+1} + G(\Delta t \dot{\gamma}_{n+1}^p) = \bar{\tau}_{tr} \\ N_{n+1}^p = N_{tr}^p \end{cases}$$

Using (3)₁ and (4)₃

$$\bar{\tau}_{n+1} = \frac{\tau_{tr} \bar{p}_{tr}}{\bar{p}_{tr} + G \Delta t g_{n+1}}$$

Updating Mandel stress

$$M_{n+1}^e = M_{tr}^e - \sqrt{2} (\tau_{tr} - \tau_{n+1}) N_{tr}^p \Rightarrow T_{n+1} = J_{n+1}^{-1} R_{tr}^e M_{n+1}^e R_{tr}^{eT}$$

Updating $\{\dot{\gamma}^p, D^p, F^p\}$

$$\dot{\gamma}_{n+1}^p = g_{n+1} \left(\frac{\bar{\tau}_{n+1}}{\bar{p}_{tr}} \right)$$

$$D_{n+1}^p = \frac{1}{\sqrt{2}} \dot{\gamma}_{n+1}^p N_{tr}^p$$

$$F_{n+1}^p = \exp \left(\Delta t D_{n+1}^p \right) F_n^p$$

Updating g^{loc} and ξ

$$g_{n+1}^{\text{loc}} = \begin{cases} \sqrt{\frac{\bar{p}_{tr}}{\rho_s d^2}} \left(\frac{\mu_{n+1} - \mu_s}{b \mu_{n+1}} \right)^{1/\alpha} & \mu_{n+1} > \mu_s \\ 0 & \mu_{n+1} \leq \mu_s \end{cases}$$

$$\xi_{n+1} = \begin{cases} \frac{A d}{\sqrt{\alpha} |\mu_{n+1} - \mu_s|} & \mu_{n+1} > \mu_s \\ \frac{A d}{\sqrt{|\mu_{n+1} - \mu_s|}} & \mu_{n+1} \leq \mu_s \end{cases}$$