

# **Lecture 03**

# **Rank of Matrix & Elementary Metrics**

MAT 121 - Introduction to Linear Algebra

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# Recall

- Systems of linear equations
- Homogeneous and non-homogeneous system
- Solution
- Consistent and Inconsistent System
- Gauss Elimination Method
- Elementary Row operations
- Row Echelon form

# Outline of lecture

- Reduced Row Echelon form
- Rank of Matrix
- Elementary matrix

Any matrix after a sequence of elementary row operations gets reduced to what is known as a *Row Echelon form*.

**[Row-Echelon Form (REF)]** A matrix is said to be in a **row echelon form** (or to be a row echelon matrix) if it has a staircase-like pattern characterized by the following properties:

- (a) The all-zero rows (if any) are at the bottom.
- (b) The first nonzero entry in a nonzero row is called a **pivot**. The pivot in any row is farther to the right than the pivots in rows above.
- (c) All entries in a column below a leading entry (pivot) is zero.

The first non-zero entry in the  $j^{\text{th}}$  row is known as the  $j^{\text{th}}$  **pivot**.

The matrix  $\begin{bmatrix} 3 & 2 & 1 & 3 \\ 0 & 1 & -1 & 6 \\ 0 & 0 & 0 & 12 \\ 0 & 0 & 0 & 0 \end{bmatrix}$  is in REF. The three pivots are indicated.

The matrix  $\begin{bmatrix} 3 & 2 & 1 & 3 \\ 0 & 1 & -1 & 6 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 12 \end{bmatrix}$  is NOT in REF.

# Reduced REF

- A matrix in REF can be further row-operated upon to ensure that (i) each pivot becomes 1 and (ii) all the entries above each pivot become 0. This is the *reduced* REF and it is unique.
- Reduced REF is mainly of theoretical interest only.

1

$$\begin{bmatrix} 2 & 3 & -2 & 4 \\ 0 & -9 & 7 & -8 \\ 0 & 0 & 0 & 20 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$
 is in REF, whereas

2

$$\begin{bmatrix} 1 & 0 & 0 & 4 \\ 0 & 1 & 0 & -8 \\ 0 & 0 & 1 & 20 \end{bmatrix}$$
 is in RREF.

# Reduced REF

\*

- The all-zero rows (if any) are at the bottom.
- The first nonzero entry in a nonzero row is called a **pivot** and each pivot becomes 1. The pivot in any row is farther to the right than the pivots in rows above.
- All entries in a column below and above of the pivot is zero

Note that: Reduced REF is mainly of theoretical interest only.

Ex. Reduce following matrix in RREF

1     $\begin{bmatrix} 5 & 3 & 1 & 4 \\ 0 & -1 & 4 & -8 \\ 3 & 2 & 1 & 20 \end{bmatrix}$  is in RREF.

# More Examples - REF, RREF

Determine whether the following matrices in REF, RREF :

① 
$$\begin{bmatrix} 1 & 2 & 3 & 4 & 5 \\ 0 & 0 & 1 & -1 & 2 \\ 0 & 0 & 0 & 1 & 5 \end{bmatrix}$$
 REF not RREF.

② 
$$\begin{bmatrix} 1 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 2 \\ 0 & 0 & 0 & 1 & 3 \end{bmatrix}$$
 is in RREF. Is it in REF?? YES.

③ The matrix 
$$\begin{bmatrix} 2 & -1 & 2 & 1 & 5 \\ 0 & 1 & 1 & -3 & 3 \\ 0 & 2 & 0 & 0 & 5 \\ 0 & 0 & 0 & 3 & 2 \end{bmatrix}$$
 is NOT in REF.

④ 
$$\begin{bmatrix} 1 & 0 & 0 & 1/2 & 0 & 1 \\ 0 & 0 & 1 & -1/3 & 0 & 2 \\ 0 & 0 & 0 & 0 & 1 & 3 \end{bmatrix}$$
 is in RREF and hence in REF.

Note that the left side of a matrix in RREF need not be identity matrix.

# Remarks

- ① Any reduced row-echelon matrix is also a row-echelon matrix.
- ② Any nonzero matrix may be row reduced into more than one matrix in echelon form. But the reduced row echelon form that one obtains from a matrix is unique.
- ③ A pivot is a nonzero number in a pivot position that is used as needed to create zeros with the help of row operations.
- ④ Different sequences of row operations might involve a different set of pivots.
- ⑤ Given a matrix  $A$ , its REF is NOT unique. However, the position of each of its pivots is unalterable.

# A quick quiz!

Determine whether the following statements are true or false.

- ① If a matrix is in row echelon form, then the leading entry of each nonzero row must be 1.
- ② If a matrix is in reduced row echelon form, then the leading entry of each nonzero row is 1.
- ③ Every matrix can be transformed into one in reduced row echelon form by a sequence of elementary row operations.
- ④ If the reduced row echelon form of the augmented matrix of a system of linear equations contains a zero row, then the system is consistent.
- ⑤ If the only nonzero entry in some row of an augmented matrix of a system of linear equations lies in the last column, then the system is inconsistent.
- ⑥ If the reduced row echelon form of the augmented matrix of a consistent system of  $m$  linear equations in  $n$  variables contains  $r$  nonzero rows, then its general solution contains  $r$  basic variables.  
**(number of free variables =  $n - r$ ).**

Observation from last Lecture: Examples = system  $\rightarrow$  RE form

$[A|B] \rightarrow$  Row Echelon forms were (suppose - diagonal  $\times$  are some non-zero entries)

$$\begin{array}{c} \left[ \begin{array}{ccc|c} x & x & x & x \\ 0 & x & x & x \\ 0 & 0 & x & x \end{array} \right], \quad \left[ \begin{array}{ccc|c} x & x & x & x \\ 0 & x & x & x \\ 0 & 0 & 0 & 0 \end{array} \right], \quad \left[ \begin{array}{ccc|c} x & x & x & x \\ 0 & x & x & x \\ 0 & 0 & 0 & x \end{array} \right] \\ \downarrow \qquad \qquad \qquad \downarrow \\ \text{Unique soln} \qquad \qquad \qquad \text{Infinite Many soln} \qquad \qquad \qquad \text{No solution} \end{array}$$

$$A_{m \times n} X_{n \times 1} = B_{m \times 1}$$

The  $m \times n$  coefficient matrix  $A$  of the linear system  $Ax = b$  is thus reduced to an  $(m \times n)$  row echelon matrix  $U$  and the augmented matrix  $[A|b]$  is reduced to

$$[U|c] = \left[ \begin{array}{ccccccccc|c} 0 & \dots & p_1 & * & * & * & * & * & * & \dots & * & c_1 \\ 0 & \dots & 0 & \dots & p_2 & * & * & * & * & \dots & * & c_2 \\ 0 & \dots & 0 & 0 & \dots & p_3 & * & * & * & \dots & * & c_3 \\ \vdots & \vdots & \vdots & \vdots & 0 & 0 & \dots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & \dots & 0 & 0 & 0 & 0 & 0 & p_r & * & \dots & * & c_r \\ 0 & \dots & 0 & 0 & 0 & 0 & 0 & 0 & 0 & \dots & 0 & c_{r+1} \\ \vdots & \vdots \\ 0 & \dots & 0 & 0 & 0 & 0 & 0 & 0 & 0 & \dots & 0 & c_m \end{array} \right].$$

The entries denoted by  $*$  and the  $c_i$ 's are real numbers; they may or may not be zero. The  $p_i$ 's denote the pivots; they are non-zero. Note that there is exactly one pivot in each of the first  $r$  rows of  $U$  and that any column of  $U$  has at most one pivot. Hence  $r \leq m$  and  $r \leq n$ .

# Consistent & Inconsistent Systems

If  $r < m$  (the number of non-zero rows is less than the number of equations) and  $c_{r+k} \neq 0$  for some  $k \geq 1$ , then the  $(r+k)$ th row corresponds to the self-contradictory equation  $0 = c_{r+k}$  and so the system has **no solutions** (inconsistent system).

If (i)  $r = m$  or (ii)  $r < m$  and  $c_{r+k} = 0$  for all  $k \geq 1$ , then there exists a solution of the system (consistent system).

## Definition (Basic & Free Variables)

If the  $j$ th column of  $U$  contains a pivot, then  $x_j$  is called a **basic variable**; otherwise  $x_j$  is called a **free variable**. (non-pivotal)

In fact, there are  $n - r$  free variables, where  $n$  is the number of columns (unknowns) of  $A$  (and hence of  $U$ ).

# Rank of matrix

## Definition (Rank)

Let  $A$  be an  $m \times n$  matrix and  $\hat{A}$  be any of its row echelon forms. The rank of  $A$  is the number of pivots in  $\hat{A}$ .

This definition is ad-hoc and not rigorously justified since REF is not unique.

The justification will be given in due course. We will denote the rank of  $A$  by  $\text{rank}(A)$ . Immediate to observe that

$$\text{rank}(A) \leq m \text{ and } \text{rank}(A) \leq n.$$

Observation from last Lecture: Examples = system  $\rightarrow$  RE form

$[A|b] \rightarrow$  Row Echelon forms were (suppose - diagonal  $x$  are some non-zero entries)

$$\left[ \begin{array}{ccc|c} x & x & x & x \\ 0 & x & x & x \\ 0 & 0 & x & x \end{array} \right]$$

$\Downarrow$   
Unique soln

$$\left[ \begin{array}{ccc|c} x & x & x & x \\ 0 & x & x & x \\ 0 & 0 & 0 & 0 \end{array} \right]$$

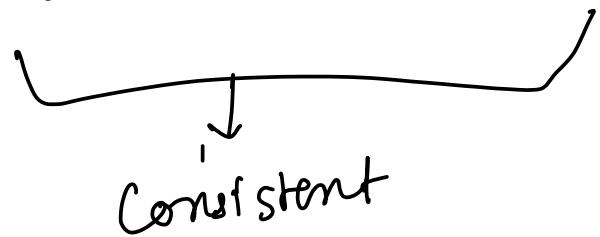
$\Downarrow$   
Infinite Many  
soln

$$\left[ \begin{array}{ccc|c} x & x & x & x \\ 0 & x & x & x \\ 0 & 0 & 0 & x \end{array} \right]$$

$\Downarrow$   
No solution

Rank  $A = 3$

Rank  $[A|b] = 3$



Rank  $A = 2$

Rank  $[A|b] = 2$

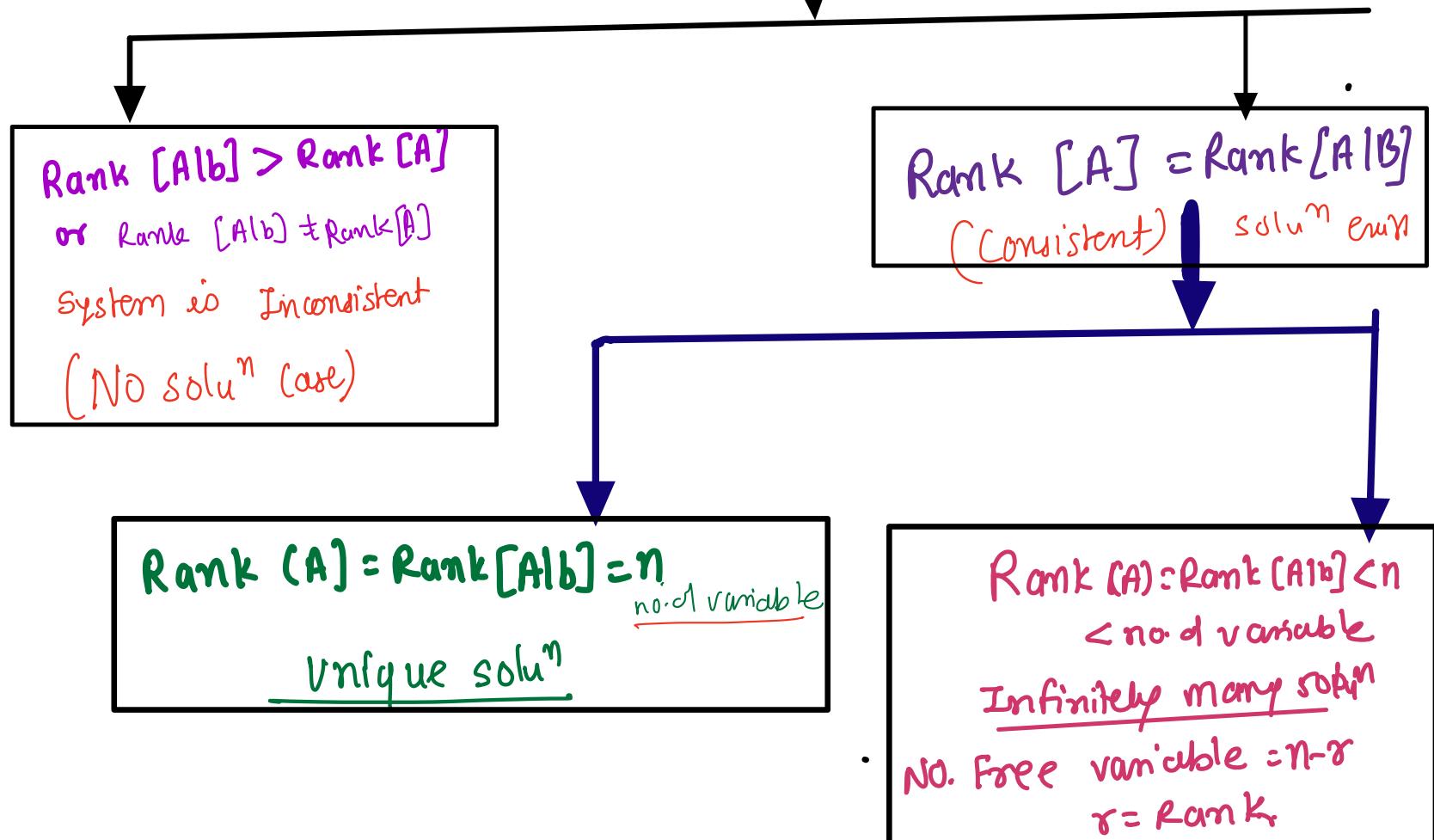
Rank  $A = 2$

Rank  $[A|b] = 3$

$\Downarrow$   
Inconsistent.

F

$$A_{m \times n} X_{n \times 1} = B_{m \times 1}$$



Homo. System

$$A_{m \times n} X_n x_1 = 0$$

Rank  $A = \text{Rank } [A|0]$   
(always consistent)

Rank  $A = n$   
unique solu<sup>n</sup>  
 $\Rightarrow$  trivial solu<sup>n</sup>

Rank  $A < n$   
infinitely many  
solut.

# Solvability of a linear system

## Theorem

Let  $Ax = \mathbf{b}$  be a given system of linear equations. Let  $\underline{A^+ = [A|\mathbf{b}]}$  denote the augmented matrix.

- ① **(Existence)** The solution set is non-empty if and only if  $\text{rank}(A) = \text{rank}(A^+)$ .
- ② **(Uniqueness)** The system has a unique solution if and only if  $\text{rank}(A) = \text{rank}(A^+) = n$ .
- ③ **(Non-uniqueness)** The system has infinitely many solutions if and only if  $\text{rank}(A) = \text{rank}(A^+) < n$ .
- ④ **(Gauss elimination or Completeness)** If  $\text{rank}(A) = \text{rank}(A^+)$ , Gauss elimination method gives the complete set of solutions.

# Proof of the theorem

Let  $A^+ = [A|\mathbf{b}]$  be the augmented matrix and  $\widehat{A}^+$  be a row-echelon form of  $A^+$ . Then  $\widehat{A}^+ = [\widehat{A}|\widehat{\mathbf{b}}]$  where perforce,  $\widehat{A}$  is a REF of  $A$ .

1. **(Existence):** If  $\text{rank}(A^+) = \text{rank}(A)$ , then there can be no pivot in the last column (augmented part) and we can solve the system by back substitutions.

Conversely, if  $\text{rank}(A^+) \neq \text{rank}(A)$ , then perforce  $\text{rank}(A^+) = \text{rank}(A) + 1$  and the last pivot is in the augmented column. The corresponding equation will read

$$0 = \text{last pivot} \neq 0$$

and hence the system is inconsistent.

# Proof of the theorem contd.

2. (Uniqueness): If  $\text{rank}(A) = \text{rank}(A^+) = n$ , then since the number of columns in  $A$  is  $n$ , the reduced REF will look like  $\widehat{A}^+ = \begin{bmatrix} \mathbf{I}_n & \widehat{\mathbf{b}} \\ [\mathbf{0}] & \mathbf{0} \end{bmatrix}$  and the unique solution is  $\mathbf{x} = \widehat{\mathbf{b}}$ . In the obvious notations,  $x_j = \widehat{b}_j$ .

3. (Non-uniqueness): If  $\text{rank}(A) = \text{rank}(A^+) = r < n$ ,  $n - r$  variables out of  $x_1, \dots, x_n$  will be free to take any values, thereby giving infinitely many solutions (non-uniqueness).

The  $(n - r)$  free variables correspond to the pivot-free columns.

4. (Gauss elimination or completeness): Since each row operation is reversible, the system in REF is equivalent to the original. Hence we get all the solutions by GEM.

# Solvability

Let  $Ax = \mathbf{b}$  be a given system of linear equations. Let  $A^+ = [A|\mathbf{b}]$  denote the  $m \times (n+1)$  augmented matrix.

Rank $A$	Rank $[A \mathbf{b}]$	Cases	Solution set
$r$	$r+1$		Empty
$r$	$r$	$r < n$	Infinite set
$r$	$r$	$r = n$	Singleton set
$r$	$r$	$r > n$	????

[1.5]

# Elementary Matrices

An  $m \times m$  elementary matrix is a matrix obtained from the  $m \times m$  identity matrix  $I_m$  by one of the elementary operations; namely,

- ① interchange of two rows,
- ② multiplying a row by a non-zero constant,
- ③ adding a constant multiple of a row to another row.

That is, an elementary matrix is a matrix which differs from the identity matrix by one single elementary row operation.

Ex. Elementary Matrix

$$\textcircled{1} \quad E_{23} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$

$$R_{23} \leftrightarrow R_2 + R_3 \quad I = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\textcircled{2} \quad E_{22} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$7 \times R_2 \leftarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\textcircled{3} \quad E = \begin{bmatrix} 1 & 0 & 0 \\ 5 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$R_2 + 5R_1 \leftarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = I$$

# 1. Row Switching Operation

**Interchange of two rows** -  $R_i \leftrightarrow R_j$ .

The elementary matrix  $P_{ij}$  corresponding to this operation on  $I_m$  is obtained by swapping row  $i$  and row  $j$  of the identity matrix.

$$P_{ij} = \begin{matrix} & C_1 & \dots & C_i & \dots & C_j & \dots & C_m \\ R_1 & 1 & & & & & & \\ \vdots & & \ddots & & & & & \\ R_i & & & 0 & \dots & 1 & & \\ \vdots & & & & \ddots & & & \\ R_j & & & 1 & \dots & 0 & & \\ \vdots & & & & & & \ddots & \\ R_m & & & & & & & 1 \end{matrix}$$

Example : Consider  $I_3$ .  $R_1 \leftrightarrow R_2$  gives  $P_{12} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ .

## 2. Row Multiplying Transformation

**Multiplying a row by a non-zero constant** -  $R_i \rightarrow kR_i$ . The elementary matrix  $M_i(k)$  corresponding to this operation on  $I_m$  is obtained by multiplying row  $i$  of the identity matrix by a non-zero constant  $k$ .

$$M_i(k) = \begin{matrix} & C_1 & C_2 & \dots & C_i & \dots & C_m \\ R_1 & 1 & & & & & \\ R_2 & & 1 & & & & \\ \vdots & & & \ddots & & & \\ R_i & & & & k & & \\ \vdots & & & & & \ddots & \\ R_m & & & & & & 1 \end{matrix}$$

**Example :** Consider  $I_3$ .  $R_3 \rightarrow 7R_3$  gives  $M_3(7) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 7 \end{bmatrix}$ .

### 3. Row Addition Transformation

$R_i \rightarrow R_i + kR_j$  : The elementary matrix  $E_{ij}(k)$  corresponding to this

operation on  $I_m$  is obtained by multiplying row  $j$  of the identity matrix by a non-zero constant  $k$  and adding with row  $i$ .

$$E_{ij}(k) = \begin{matrix} & C_1 & \dots & C_i & \dots & C_j & \dots & C_m \\ R_1 & 1 & & & & & & \\ \vdots & & \ddots & & & & & \\ R_i & & & 1 & & k & & \\ \vdots & & & & \ddots & & & \\ R_j & & & & & 1 & & \\ \vdots & & & & & & \ddots & \\ R_m & & & & & & & 1 \end{matrix}$$

Example :  $R_2 \rightarrow R_2 + (-3)R_1$  for  $I_3$  gives  $E_{21}(-3) = \begin{bmatrix} 1 & 0 & 0 \\ -3 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ .

# Proposition 1

Let  $A$  be an  $m \times n$  matrix. If  $\tilde{A}$  is obtained from  $A$  by an elementary row operation, and  $E$  is the corresponding  $m \times m$  elementary matrix, then  $EA = \tilde{A}$ .

lets check for matrix

$$A = \begin{bmatrix} a & b & c \\ d & e & f \\ l & m & n \end{bmatrix}$$

case I

$A \xrightarrow[R_{23}]{\text{Interchange of Rows}} \begin{bmatrix} a & b & c \\ l & m & n \\ d & e & f \end{bmatrix} = \tilde{A}$ , then corresponding Elementary matrix is  $E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \in$  (derived by change  $R_{23}$  in Idem matrix)

Now

$$EA = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} a & b & c \\ d & e & f \\ l & m & n \end{bmatrix} = \begin{bmatrix} a & b & c \\ l & m & n \\ d & e & f \end{bmatrix} = \tilde{A}$$

Hence  $EA = \tilde{A}$

Case II, multiply by constant no. to some row  
non-zero.

$$A = \begin{bmatrix} a & b & c \\ d & e & f \\ l & m & n \end{bmatrix} \xrightarrow{7R_2} \begin{bmatrix} a & b & c \\ 7d & 7e & 7f \\ l & m & n \end{bmatrix} = \tilde{A}$$

Corresponding  $E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 7 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\text{obtained by } 7 \times R_1} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} = E$

Now  $E A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 7 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} a & b & c \\ d & e & f \\ l & m & n \end{bmatrix} = \begin{bmatrix} a & b & c \\ 7d & 7e & 7f \\ l & m & n \end{bmatrix} = \tilde{A}$ .

Case III

$$A \xrightarrow{R_2 + 5R_1} \tilde{A}$$

Find corresponding "E" elementary Matrix to verify  
 $EA = \tilde{A}$ .

# Reduced Row Echelon form contd.

1  $[A]_{m \times n}$   
Row operation  
 $\downarrow$   
 $I$   
 $II$   
 $III$   
Convert  
 $\downarrow$   
Be Row Echelon form

corresponding  
Elementary  
matrices  
 $\rightarrow$   
 $E_1$   
 $E_2$   
 $E_3$   
 $A$   
 $E_{m \times n}$

$$B =$$
  
$$B = E_3 E_2 E_1 A$$

Exercise: Let  $A$  be an  $m \times n$  matrix. There exist elementary matrices  $E_1, E_2, \dots, E_N$  of order  $m$  such that the product  $E_N \cdots E_2 E_1 A$  is a row echelon form of  $A$ .

$B$

$$B = E_N E_{N-1} \cdots E_2 E_1 A$$

# Summary

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