

Lecture 03

Rank of Matrix & Elementary Metrics

MAT 121 - Introduction to Linear Algebra

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- Systems of linear equations
- Homogeneous and non-homogeneous system
- Solution
- Consistent and Inconsistent System
- Gauss Elimination Method
- Elementary Row operations
- Row Echelon form

Outline of lecture

- Reduced Row Echelon form
- Rank of Matrix
- Elementary matrix

Any matrix after a sequence of elementary row operations gets reduced to what is known as a *Row Echelon form*.

[Row-Echelon Form (REF)] A matrix is said to be in a **row echelon form** (or to be a row echelon matrix) if it has a staircase-like pattern characterized by the following properties:

- (a) The all-zero rows (if any) are at the bottom.
- (b) The first nonzero entry in a nonzero row is called a **pivot**. The pivot in any row is farther to the right than the pivots in rows above.
- (c) All entries in a column below a leading entry (pivot) is zero.

The

first non-zero entry in the j^{th} row is known as the j^{th} pivot.

The matrix $\begin{bmatrix} 3 & 2 & 1 & 3 \\ 0 & 1 & -1 & 6 \\ 0 & 0 & 0 & 12 \\ 0 & 0 & 0 & 0 \end{bmatrix}$ is in REF. The three pivots are indicated.

The matrix $\begin{bmatrix} 3 & 2 & 1 & 3 \\ 0 & 1 & -1 & 6 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 12 \end{bmatrix}$ is NOT in REF.

Reduced REF

- A matrix in REF can be further row-operated upon to ensure that (i) each pivot becomes 1 and (ii) all the entries above each pivot become 0. This is the *reduced* REF and it is unique.
- Reduced REF is mainly of theoretical interest only.

1
$$\begin{bmatrix} 2 & 3 & -2 & 4 \\ 0 & -9 & 7 & -8 \\ 0 & 0 & 0 & 20 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$
 is in REF, whereas

2
$$\begin{bmatrix} 1 & 0 & 0 & 4 \\ 0 & 1 & 0 & -8 \\ 0 & 0 & 1 & 20 \end{bmatrix}$$
 is in RREF.

Reduced REF

- The all-zero rows (if any) are at the bottom.
- The first nonzero entry in a nonzero row is called a **pivot** and each pivot becomes 1. The pivot in any row is farther to the right than the pivots in rows above.
- All entries in a column below and above of the pivot is zero

Note that: Reduced REF is mainly of theoretical interest only.

Ex. Reduce following matrix in RREF

①
$$\begin{bmatrix} 5 & 3 & 1 & 4 \\ 0 & -1 & 4 & -8 \\ 3 & 2 & 1 & 20 \end{bmatrix}$$
 is in RREF.

More Examples - REF, RREF

Determine whether the following matrices in REF, RREF :

① $\begin{bmatrix} 1 & 2 & 3 & 4 & 5 \\ 0 & 0 & 1 & -1 & 2 \\ 0 & 0 & 0 & 1 & 5 \end{bmatrix}$ REF not RREF.

② $\begin{bmatrix} 1 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 2 \\ 0 & 0 & 0 & 1 & 3 \end{bmatrix}$ is in RREF. Is it in REF?? YES.

③ The matrix $\begin{bmatrix} 2 & -1 & 2 & 1 & 5 \\ 0 & 1 & 1 & -3 & 3 \\ 0 & 2 & 0 & 0 & 5 \\ 0 & 0 & 0 & 3 & 2 \end{bmatrix}$ is NOT in REF.

④ $\begin{bmatrix} 1 & 0 & 0 & 1/2 & 0 & 1 \\ 0 & 0 & 1 & -1/3 & 0 & 2 \\ 0 & 0 & 0 & 0 & 1 & 3 \end{bmatrix}$ is in RREF and hence in REF.

Note that the left side of a matrix in RREF need not be identity matrix.

Remarks

- ① Any reduced row-echelon matrix is also a row-echelon matrix.
- ② Any nonzero matrix may be row reduced into more than one matrix in echelon form. But the reduced row echelon form that one obtains from a matrix is unique.
- ③ A pivot is a nonzero number in a pivot position that is used as needed to create zeros with the help of row operations.
- ④ Different sequences of row operations might involve a different set of pivots.
- ⑤ Given a matrix A , its REF is NOT unique. However, the position of each of its pivots is unalterable.

A quick quiz!

Determine whether the following statements are true or false.

- ① If a matrix is in row echelon form, then the leading entry of each nonzero row must be 1.
- ② If a matrix is in reduced row echelon form, then the leading entry of each nonzero row is 1.
- ③ Every matrix can be transformed into one in reduced row echelon form by a sequence of elementary row operations.
- ④ If the reduced row echelon form of the augmented matrix of a system of linear equations contains a zero row, then the system is consistent.
- ⑤ If the only nonzero entry in some row of an augmented matrix of a system of linear equations lies in the last column, then the system is inconsistent.
- ⑥ If the reduced row echelon form of the augmented matrix of a consistent system of m linear equations in n variables contains r nonzero rows, then its general solution contains r basic variables.
(number of free variables = $n - r$).

Observation from last Lecture: Examples = system \rightarrow RE form

$[A|B] \rightarrow$ Row Echelon forms were (suppose - diagonal x are some non-zero entries)

$$\left[\begin{array}{ccc|c} x & x & x & x \\ 0 & x & x & x \\ 0 & 0 & x & x \end{array} \right]$$

\Downarrow
Unique solⁿ

$$\left[\begin{array}{ccc|c} x & x & x & x \\ 0 & x & x & x \\ 0 & 0 & 0 & 0 \end{array} \right]$$

\Downarrow
Infinitely many solⁿ

$$\left[\begin{array}{ccc|c} x & x & x & x \\ 0 & x & x & x \\ 0 & 0 & 0 & x \end{array} \right]$$

no solution

$$A_{m \times n} X_{n \times 1} = B_{m \times 1}$$

The $m \times n$ coefficient matrix A of the linear system $A\mathbf{x} = \mathbf{b}$ is thus reduced to an $(m \times n)$ row echelon matrix U and the augmented matrix $[A|\mathbf{b}]$ is reduced to

$$[U|\mathbf{c}] = \left[\begin{array}{cccccccccccc|c} 0 & \dots & p_1 & * & * & * & * & * & * & * & \dots & * & c_1 \\ 0 & \dots & 0 & \dots & p_2 & * & * & * & * & * & \dots & * & c_2 \\ 0 & \dots & 0 & 0 & 0 & \dots & p_3 & * & * & * & \dots & * & c_3 \\ \vdots & & \vdots & \vdots & \vdots & 0 & 0 & \dots & \vdots & \vdots & & \vdots & \vdots \\ 0 & \dots & 0 & 0 & 0 & 0 & 0 & 0 & p_r & * & \dots & * & c_r \\ 0 & \dots & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & \dots & 0 & c_{r+1} \\ \vdots & & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & & \vdots & \vdots \\ 0 & \dots & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & \dots & 0 & c_m \end{array} \right].$$

The entries denoted by $*$ and the c_i 's are real numbers; they may or may not be zero. The p_i 's denote the pivots; they are non-zero. Note that there is exactly one pivot in each of the first r rows of U and that any column of U has at most one pivot. Hence $r \leq m$ and $r \leq n$.

Consistent & Inconsistent Systems

If $r < m$ (the number of non-zero rows is less than the number of equations) and $c_{r+k} \neq 0$ for some $k \geq 1$, then the $(r+k)$ th row corresponds to the self-contradictory equation $0 = c_{r+k}$ and so the system has **no solutions** (inconsistent system).

If (i) $r = m$ or (ii) $r < m$ and $c_{r+k} = 0$ for all $k \geq 1$, then there exists a solution of the system (consistent system).

Definition (Basic & Free Variables)

If the j th column of U contains a pivot, then x_j is called a **basic variable**; otherwise x_j is called a **free variable**. (non-pivotal)

In fact, there are $n - r$ free variables, where n is the number of columns (unknowns) of A (and hence of U).

Rank of matrix

Definition (Rank)

Let A be an $m \times n$ matrix and \hat{A} be any of its row echelon forms. The rank of A is the number of pivots in \hat{A} .

This definition is ad-hoc and not rigorously justified since REF is not unique.

The justification will be given in due course. We will denote the rank of A by $\text{rank}(A)$. Immediate to observe that

$$\text{rank}(A) \leq m \text{ and } \text{rank}(A) \leq n.$$

Observation from last lecture: Examples = system \rightarrow R.E form

$[A|b] \rightarrow$ Row Echelon forms were (suppose - diagonal x are some non-zero entries)

$$\left[\begin{array}{ccc|c} x & x & x & x \\ 0 & x & x & x \\ 0 & 0 & x & x \end{array} \right]$$

\Downarrow
Unique solution

$$\left[\begin{array}{ccc|c} x & x & x & x \\ 0 & x & x & x \\ 0 & 0 & 0 & 0 \end{array} \right]$$

\Downarrow
Infinitely many solutions

$$\left[\begin{array}{ccc|c} x & x & x & x \\ 0 & x & x & x \\ 0 & 0 & 0 & \neq 0 \end{array} \right]$$

\Downarrow
No solution

$$\text{Rank } A = 3$$

$$\text{Rank } [A|b] = 3$$

$$\text{Rank } A = 2$$

$$\text{Rank } [A|b] = 2$$

$\swarrow \quad \searrow$
Consistent

$$\text{Rank } A = 2$$

$$\text{Rank } [A|b] = 3$$

\Downarrow
Inconsistent

$$A_{m \times n} X_{n \times 1} = B_{m \times 1}$$

$\text{Rank}[A|b] > \text{Rank}[A]$
 or $\text{Rank}[A|b] \neq \text{Rank}[A]$
 System is Inconsistent
 (No solⁿ case)

$\text{Rank}[A] = \text{Rank}[A|b]$
 (Consistent) solⁿ exist

$\text{Rank}(A) = \text{Rank}[A|b] = n$
no. of variable
Unique solⁿ

$\text{Rank}(A) = \text{Rank}[A|b] < n$
 $< \text{no. of variable}$
Infinitely many solⁿ
 No. Free variable = $n - r$
 $r = \text{Rank}$

Homo. System

$$\underline{A_{m \times n} X_{n \times 1} = 0}$$

$$\text{Rank } A = \text{Rank } [A|0]$$

(always consistent)

Rank $A = n$
Unique solⁿ
 \Rightarrow trivial solⁿ

Rank $A < n$
Infinitely many
solⁿ.

Solvability of a linear system

Theorem

Let $A\mathbf{x} = \mathbf{b}$ be a given system of linear equations. Let $A^+ = [A|\mathbf{b}]$ denote the augmented matrix.

- ① *(Existence)* The solution set is non-empty if and only if $\text{rank}(A) = \text{rank}(A^+)$.
- ② *(Uniqueness)* The system has a unique solution if and only if $\text{rank}(A) = \text{rank}(A^+) = n$.
- ③ *(Non-uniqueness)* The system has infinitely many solutions if and only if $\text{rank}(A) = \text{rank}(A^+) < n$.
- ④ *(Gauss elimination or Completeness)* If $\text{rank}(A) = \text{rank}(A^+)$, Gauss elimination method gives the complete set of solutions.

Proof of the theorem

Let $A^+ = [A|\mathbf{b}]$ be the augmented matrix and \widehat{A}^+ be a row-echelon form of A^+ . Then $\widehat{A}^+ = [\widehat{A}|\widehat{\mathbf{b}}]$ where perforce, \widehat{A} is a REF of A .

1. **(Existence):** If $\text{rank}(A^+) = \text{rank}(A)$, then there can be no pivot in the last column (augmented part) and we can solve the system by back substitutions.

Conversely, if $\text{rank}(A^+) \neq \text{rank}(A)$, then perforce $\text{rank}(A^+) = \text{rank}(A) + 1$ and the last pivot is in the augmented column. The corresponding equation will read

$$0 = \text{last pivot} \neq 0$$

and hence the system is inconsistent.

Proof of the theorem contd.

2. (Uniqueness): If $\text{rank}(A) = \text{rank}(A^+) = n$, then since the number of columns in A is n , the reduced REF will look like $\widehat{A}^+ = \left[\begin{array}{c|c} \mathbf{I}_n & \widehat{\mathbf{b}} \\ \hline [\mathbf{0}] & \mathbf{0} \end{array} \right]$ and the unique solution is $\mathbf{x} = \widehat{\mathbf{b}}$. In the obvious notations, $x_j = \widehat{b}_j$.

3. (Non-uniqueness): If $\text{rank}(A) = \text{rank}(A^+) = r < n$, $n - r$ variables out of x_1, \dots, x_n will be free to take any values, thereby giving infinitely many solutions (non-uniqueness).

The $(n - r)$ free variables correspond to the pivot-free columns.

4. (Gauss elimination or completeness): Since each row operation is reversible, the system in REF is equivalent to the original. Hence we get all the solutions by GEM.

Solvability

Let $A\mathbf{x} = \mathbf{b}$ be a given system of linear equations. Let $A^+ = [A|\mathbf{b}]$ denote the $m \times (n+1)$ augmented matrix.

Rank A	Rank $[A b]$	Cases	Solution set
r	$r+1$		Empty
r	r	$r < n$	Infinite set
r	r	$r = n$	Singleton set
r	r	$r > n$????

[1.5]

Elementary Matrices

An $m \times m$ elementary matrix is a matrix obtained from the $m \times m$ identity matrix I_m by one of the elementary operations; namely,

- 1 interchange of two rows,
- 2 multiplying a row by a non-zero constant,
- 3 adding a constant multiple of a row to another row.

That is, an elementary matrix is a matrix which differs from the identity matrix by one single elementary row operation.

Ex. Elementary Matrix

① $E_{23} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$

$\xleftarrow{R_{23}} \begin{bmatrix} 0 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \xleftarrow{\substack{\text{Interchange} \\ R_2 + R_3}} I = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

② $E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 7 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

$\xleftarrow{\substack{7 \times R_2 \\ \text{one} \\ \text{row}}} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

③ $E = \begin{bmatrix} 1 & 0 & 0 \\ 5 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

$\xleftarrow{R_2 + 5R_1} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = I$

1. Row Switching Operation

Interchange of two rows - $R_i \leftrightarrow R_j$.

The elementary matrix P_{ij} corresponding to this operation on I_m is obtained by swapping row i and row j of the identity matrix.

$$P_{ij} = \begin{matrix} & \begin{matrix} C_1 & \dots & C_i & \dots & C_j & \dots & C_m \end{matrix} \\ \begin{matrix} R_1 \\ \vdots \\ R_i \\ \vdots \\ R_j \\ \vdots \\ R_m \end{matrix} & \left(\begin{array}{cccccc} 1 & & & & & \\ & \ddots & & & & \\ & & 0 & \dots & 1 & \\ & & & \ddots & & \\ & & 1 & \dots & 0 & \\ & & & & & \ddots \\ & & & & & & 1 \end{array} \right) \end{matrix}$$

Example : Consider I_3 . $R_1 \leftrightarrow R_2$ gives $P_{12} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$.

2. Row Multiplying Transformation

Multiplying a row by a non-zero constant - $R_i \longrightarrow kR_i$. The elementary matrix $M_i(k)$ corresponding to this operation on I_m is obtained by multiplying row i of the identity matrix by a non-zero constant k .

$$M_i(k) = \begin{matrix} & \begin{matrix} C_1 & C_2 & \dots & C_i & \dots & C_m \end{matrix} \\ \begin{matrix} R_1 \\ R_2 \\ \vdots \\ R_i \\ \vdots \\ R_m \end{matrix} & \begin{pmatrix} 1 & & & & & \\ & 1 & & & & \\ & & \ddots & & & \\ & & & k & & \\ & & & & \ddots & \\ & & & & & 1 \end{pmatrix} \end{matrix}$$

Example : Consider I_3 . $R_3 \rightarrow 7R_3$ gives $M_3(7) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 7 \end{bmatrix}$.

3. Row Addition Transformation

$R_i \longrightarrow R_i + kR_j$: The elementary matrix $E_{ij}(k)$ corresponding to this operation on I_m is obtained by multiplying row j of the identity matrix by a non-zero constant k and adding with row i .

$$E_{ij}(k) = \begin{matrix} & \begin{matrix} C_1 & \dots & C_i & \dots & C_j & \dots & C_m \end{matrix} \\ \begin{matrix} R_1 \\ \vdots \\ R_i \\ \vdots \\ R_j \\ \vdots \\ R_m \end{matrix} & \begin{pmatrix} 1 & & & & & & \\ & \ddots & & & & & \\ & & 1 & & k & & \\ & & & \ddots & & & \\ & & & & 1 & & \\ & & & & & \ddots & \\ & & & & & & 1 \end{pmatrix} \end{matrix}$$

Example : $R_2 \rightarrow R_2 + (-3)R_1$ for I_3 gives $E_{21}(-3) = \begin{bmatrix} 1 & 0 & 0 \\ -3 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$.

Proposition 1

Let A be an $m \times n$ matrix. If \tilde{A} is obtained from A by an elementary row operation, and E is the corresponding $m \times m$ elementary matrix, then $EA = \tilde{A}$.

lets check for matrix

$$A = \begin{bmatrix} a & b & c \\ d & e & f \\ l & m & n \end{bmatrix}$$

case I

$$A \xrightarrow[\text{Interchange of Rows}]{R_{23}} \begin{bmatrix} a & b & c \\ l & m & n \\ d & e & f \end{bmatrix} = \tilde{A}, \text{ then corresponding Elementary}$$

$$E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \in \left(\begin{array}{l} \text{derived} \\ \text{by} \\ \text{change} \\ R_{23} \text{ in Idem} \\ \text{matrix} \end{array} \right)$$

Now

$$EA = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} a & b & c \\ d & e & f \\ l & m & n \end{bmatrix} = \begin{bmatrix} a & b & c \\ l & m & n \\ d & e & f \end{bmatrix} = \tilde{A}$$

Hence

$$EA = \tilde{A}$$

Case II, multiply by constant no. to some row
non-zero.

$$A = \begin{bmatrix} a & b & c \\ d & e & f \\ l & m & n \end{bmatrix} \xrightarrow{\tau R_2} \begin{bmatrix} a & b & c \\ \tau d & \tau e & \tau f \\ l & m & n \end{bmatrix} = \tilde{A}$$

Corresponding $E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \tau & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\begin{matrix} \text{obtained by} \\ \tau \times R_2 \end{matrix}} \begin{bmatrix} \text{ } \\ \tau \times R_2 \\ \text{ } \end{bmatrix} E$

Now

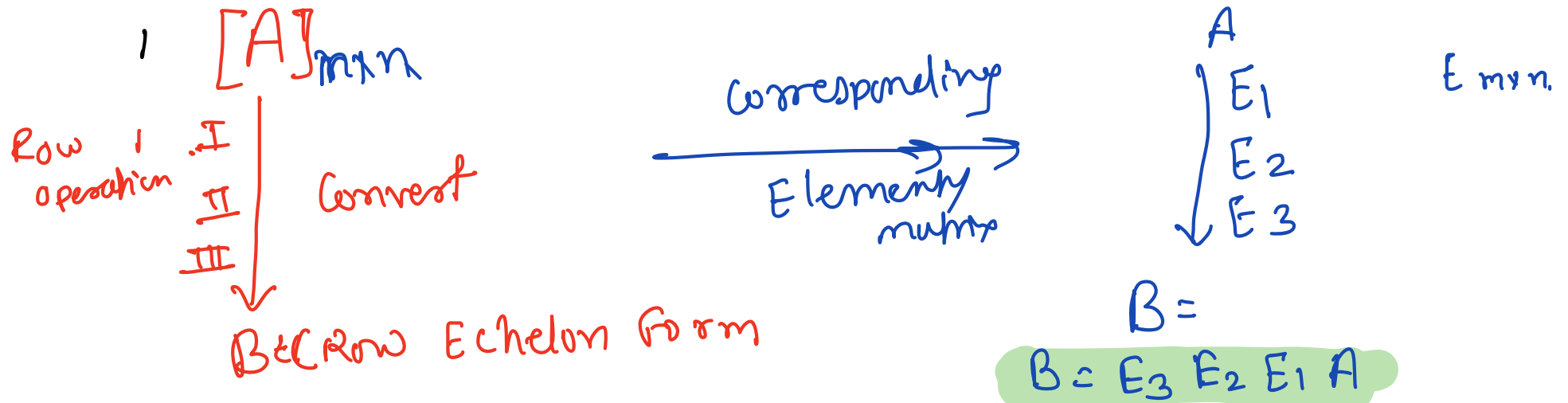
$$E A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \tau & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} a & b & c \\ d & e & f \\ l & m & n \end{bmatrix} = \begin{bmatrix} a & b & c \\ \tau d & \tau e & \tau f \\ l & m & n \end{bmatrix} = \tilde{A}$$

Case III

$$A \xrightarrow{R_2 + 5R_1} \tilde{A}$$

Find corresponding "E" elementary matrix E verify
 $EA = \tilde{A}$.

Reduced Row Echelon form contd.



Exercise: Let A be an $m \times n$ matrix. There exist elementary matrices E_1, E_2, \dots, E_N of order m such that the product $E_N \cdots E_2 E_1 A$ is a row echelon form of A .

\overline{B}

$$B = E_N E_{N-1} \cdots E_2 E_1 A$$

Summary

1

2

3

4