```
import numpy as np
import matplotlib.pyplot as plt
import math
from timeit import timeit
from scipy.stats import binom
from collections import deque
```

Q1

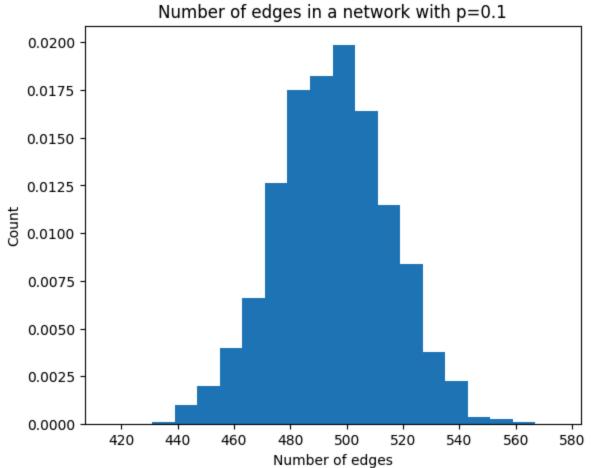
```
In [ ]: class Network():
            def __init__(self,num_nodes):
                 self.adj = {i:set() for i in range(num_nodes)}
                 self.num\_edge = 0
            def add_edge(self,i,j):
                 self.adj[i].add(j)
                 self.adj[j].add(i)
                 self.num_edge+=1
            def neighbors (self,i):
                 return self.adj[i]
            def edge_list(self):
                 return [(i,j) for i in self.adj for j in self.adj[i] if i<j]</pre>
In [ ]: class Bernoulli_Network(Network):
            def __init__(self, num_nodes,prob):
                 super().__init__(num_nodes)
                 for i in range(num nodes):
                     for j in range(i+1, num_nodes):
                         if np.random.binomial(1,prob):
                             self.add_edge(i,j)
In [ ]: np.random.seed(1)
        n = 100 #number of nodes
        probs = [0.1, 0.3, 0.5, 0.7, 0.9]
        sample_size = 1000
        fig, ax = plt.subplots(nrows=len(probs),ncols=1)
        fig.set_figheight(30)
        m_arrays=[] #for Q2
        for i,prob in enumerate(probs):
            m_array=[]
            for _ in range(sample_size):
```

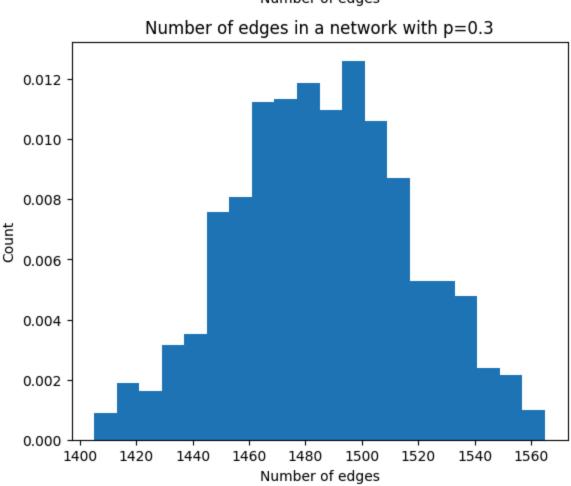
```
network = Bernoulli_Network(n,prob)
    m_array.append(network.num_edge)

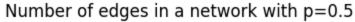
m_arrays.append(m_array)

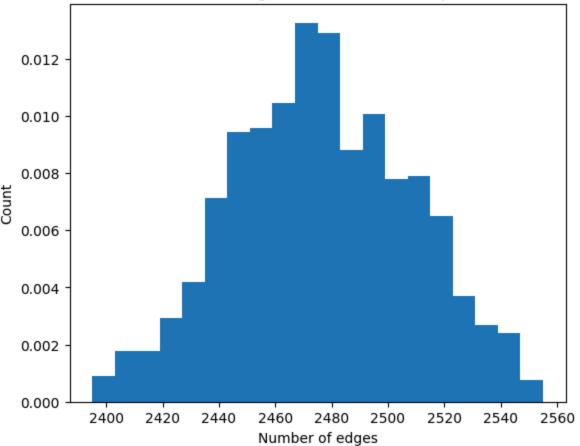
ax[i].hist(m_array,bins=20,range=(prob*math.comb(n,2)-80,prob*math.comb(n,2)+80
ax[i].set_xlabel('Number of edges')
ax[i].set_ylabel('Count')
ax[i].set_title('Number of edges in a network with p={}'.format(prob))

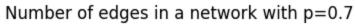
plt.show()
```

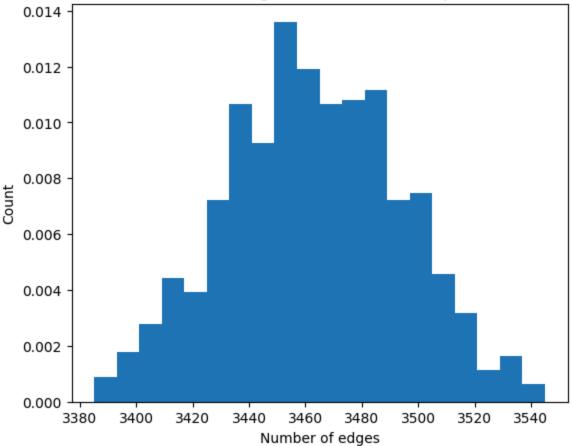


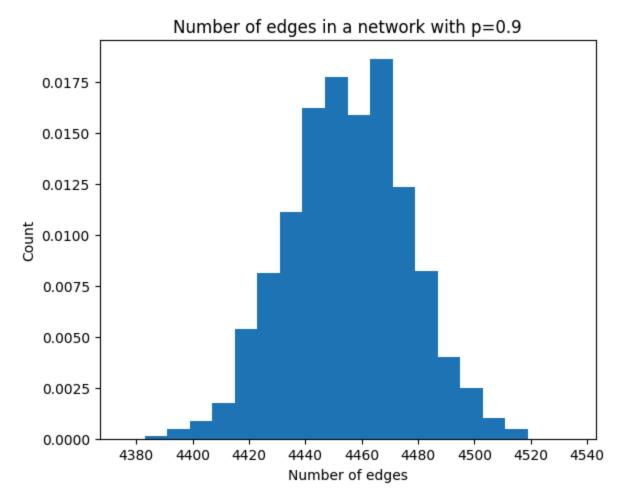












For probability p and number of edge $0 \le m \le (nC2)$. Plot probability P(m)

Q2

```
fig.set_figheight(30)
for i,prob in enumerate(probs):
   m_range = [m for m in range(total_edge+1)]
   p_m = pmf_num_edge(n,prob)
   ax[i].plot(m_range,p_m,color='r',label='Theoretical PMF')
   ax[i].hist(m arrays[i],bins=20,density=True, label='Histogram/Sampled PMF')
   ax[i].set_xlabel('number of edges m')
   ax[i].set_ylabel('probability')
   ax[i].set_title('PMF of m edges with n={} and p={}'.format(n,prob))
   ax[i].set_xlim([prob*math.comb(n,2)-150,prob*math.comb(n,2)+150])
   ax[i].legend(loc='upper right')
   mn = mean(m_range,p_m)
   s_mn = np.mean(m_arrays[i])
   var = variance(m_range,p_m,mn)
   s_var = np.var(m_arrays[i])
   print('For p = {}: theoretical mean = {:.2f}, theoretical variance = {:.2f}, sa
plt.show()
```

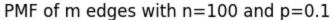
```
For p = 0.1: theoretical mean = 495.00, theoretical variance = 445.50, sample mean = 494.51, sample variance = 396.51

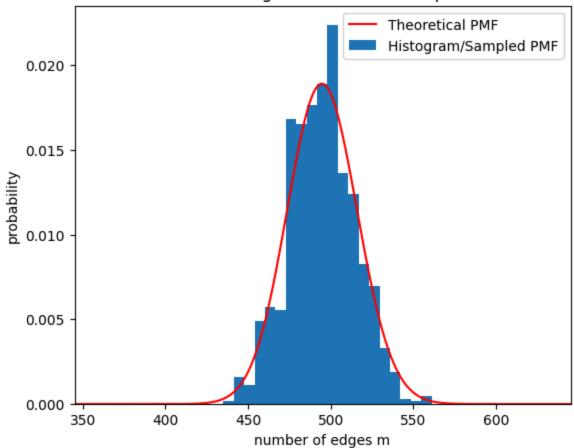
For p = 0.3: theoretical mean = 1485.00, theoretical variance = 1039.50, sample mean = 1486.02, sample variance = 1053.66

For p = 0.5: theoretical mean = 2475.00, theoretical variance = 1237.50, sample mean = 2476.08, sample variance = 1161.90

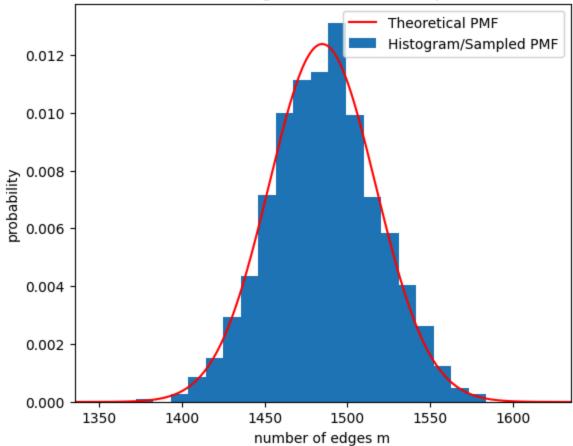
For p = 0.7: theoretical mean = 3465.00, theoretical variance = 1039.50, sample mean = 3462.69, sample variance = 1058.74

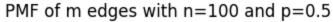
For p = 0.9: theoretical mean = 4455.00, theoretical variance = 445.50, sample mean = 4454.70, sample variance = 456.17
```

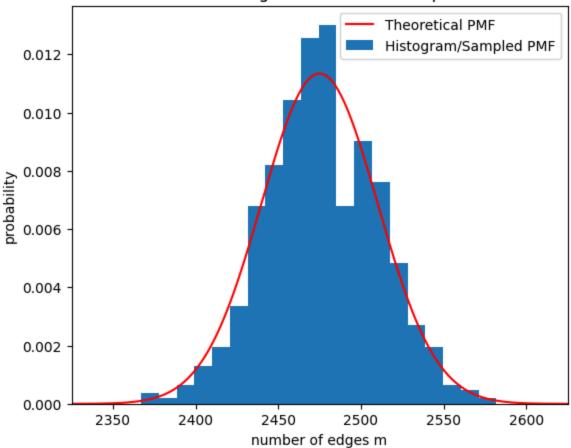


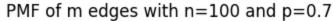


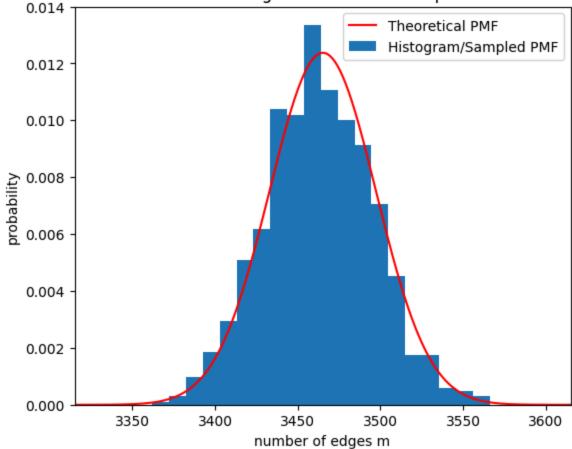
PMF of m edges with n=100 and p=0.3

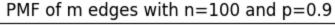


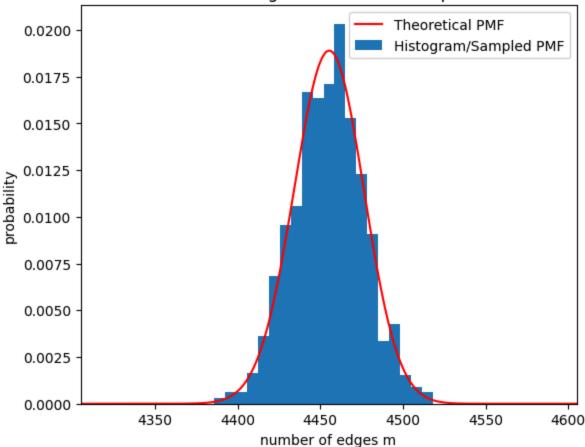












Q3 Computing degree distribution P(k) where k is the degree of a node.

For a graph of G(n,p), 0 <= k <= n-1

$$P(k) = (n-1)C_k * p^k * (1-p)^{n-1-k}$$

```
In []: def degree_distribution(prob,num_nodes):
    k_range = [k for k in range(num_nodes)]
    return binom.pmf(k_range,num_nodes-1,prob)

In []: probs = [0.1,0.3,0.5,0.7,0.9]
    n = 100

    fig, ax = plt.subplots(nrows=len(probs),ncols=1)
    fig.set_figheight(30)

for i,prob in enumerate(probs):
    k_range = [k for k in range(n)]
    p_k = degree_distribution(prob,n)

    ax[i].plot(k_range,p_k)
    ax[i].set_xlabel('degree k')
    ax[i].set_ylabel('probability')
```

```
ax[i].set_title('PMF of degree distribution k with n={} and p={}'.format(n,prob
mn = mean(k_range,p_k)
var = variance(k_range,p_k,mn)
print('For p = {}: mean = {:.2f}, variance = {:.2f}'.format(prob,mn,var))
plt.show()
```

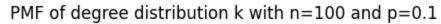
```
For p = 0.1: mean = 9.90, variance = 8.91

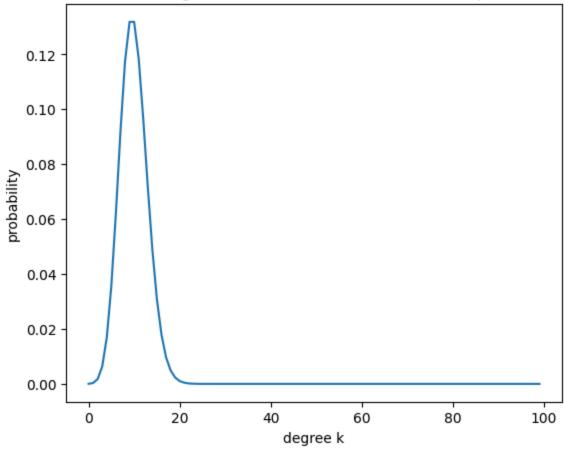
For p = 0.3: mean = 29.70, variance = 20.79

For p = 0.5: mean = 49.50, variance = 24.75

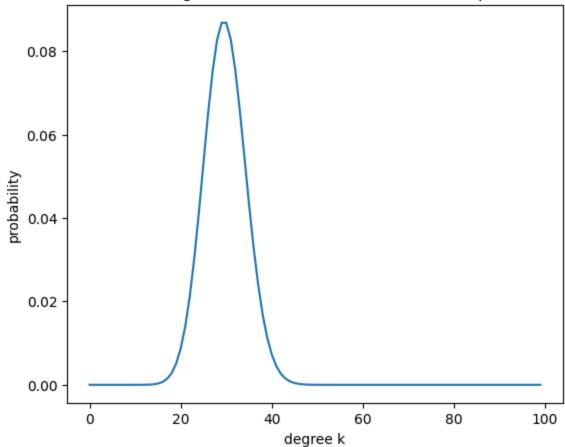
For p = 0.7: mean = 69.30, variance = 20.79

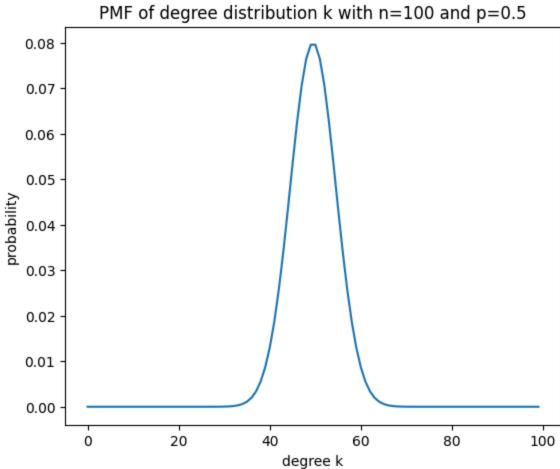
For p = 0.9: mean = 89.10, variance = 8.91
```

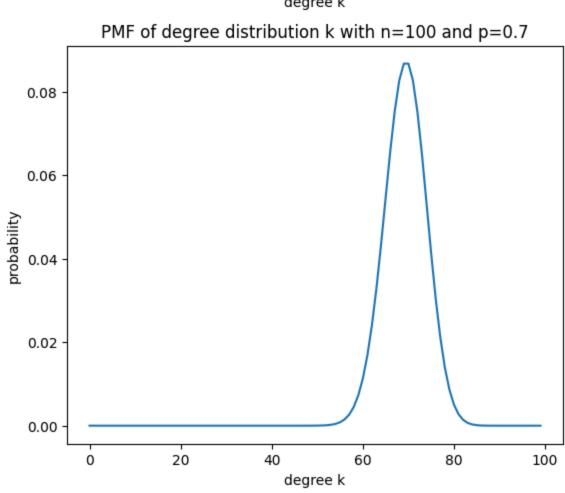




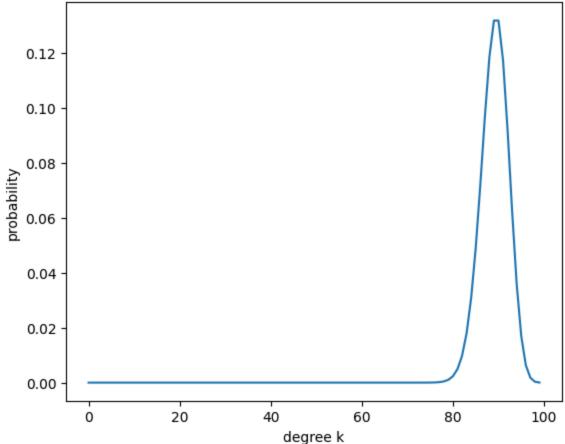
PMF of degree distribution k with n=100 and p=0.3











Q4

Now we let $p=rac{\lambda}{n-1}$ i.e

$$G(n, \frac{\lambda}{n-1})$$

For some constant λ .

Investigate how the PMF, mean and variance changes as n increases.

Investigate what happens in the limit as

$$n \backslash rarr \infty$$

Using expression in Q3, we obtain

$$P(k) = (n-1)C_k * p^k * (1-p)^{n-1-k}$$
 $= (n-1)C_k * \frac{\lambda}{n-1}^k * (1 - \frac{\lambda}{n-1})^{n-1-k}$

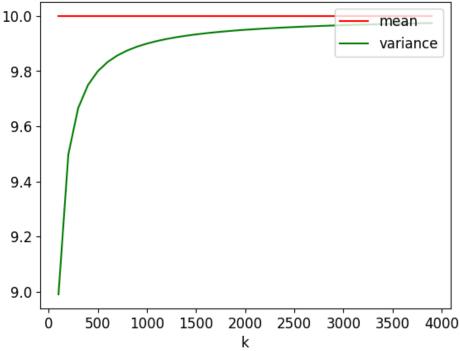
```
In [ ]: lmbda = 10
    n_range = [n for n in range(100,4000,100)]
    means = []
    vars = []
```

```
for n in n_range:
    prob = lmbda/(n-1)
    k_range=[k for k in range(n)]
    p_k = degree_distribution(prob,n)

    mn = mean(k_range,p_k)
    means.append(mn)
    vars.append(variance(k_range,p_k,mn))

plt.rcParams.update({'font.size': 12})
    plt.plot(n_range,means,label='mean',color='r')
    plt.plot(n_range,vars,label='variance',color='g')
    plt.xlabel('k')
    plt.title(r'Mean and variance of degree distribution k as a function of n and $\lamplt.legend(loc='upper right')
    plt.show()
```

Mean and variance of degree distribution k as a function of n and $\lambda=10$



We observe that mean is always constant and equal to λ . However, as n increase, p decreases and variance increases but appears to reach an asymptote of λ .

Q5, two stage algorithm.

For a graph

G(n,p)

Stage 1:

Generate value m, number of edges according to PMF in Q3.

https://compphys.notes.dmaitre.phyip3.dur.ac.uk/lectures/lecture-5/probability-distributions/#:~:text=By%20inverting%20the%20cumulative%20function,making%20these%20v%20tau%20*%20numpy.

^ If interested in applying monte carlo rejection sampling etc.

Stage 2:

Add m edges uniformly to the network.

```
In []: class Two_Stage_Network(Network):

    def __init__(self, num_nodes,prob):
        super().__init__(num_nodes)

    #stage 1
        total_edge = math.comb(num_nodes,2)
        m = np.random.binomial(total_edge,prob)

#stage 2
    while self.num_edge!=m:

        i, j = np.random.randint(0, num_nodes,2)

        if i!=j and j not in self.neighbors(i):
              self.add_edge(i,j)
```

Q6

For

$$n^k: k = 6, 7, \dots, 10$$

Generate graphs

according to Q1, a naive algo and Q4, sampling m then generating graph\$

Then time the two algorithms

```
In [ ]: pows = 2**np.array(range(6,11))
lmbda = 10
timer_runs = 50
time_naive_list = []
time_two_stage_list = []
```

```
for n in pows:
    p = lmbda/(n-1)

total_edges = math.comb(n,2)
    m_range = [m for m in range(total_edges+1)]

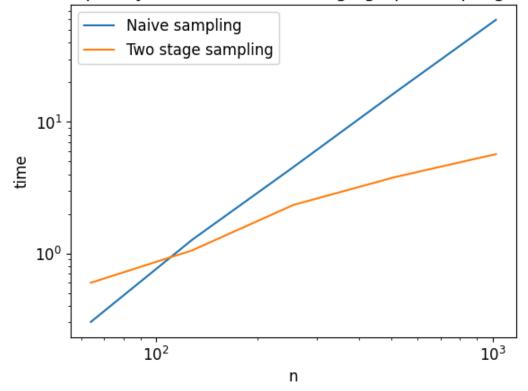
#Naive generation
time_naive = timeit(lambda: Bernoulli_Network(n,p), number=timer_runs)

#Alternate generation
time_two_stage = timeit(lambda: Two_Stage_Network(n,p),number=timer_runs)

#taking logs of power2
time_naive_list.append(time_naive)
time_two_stage_list.append(time_two_stage)
```

```
In [ ]: plt.loglog(pows,time_naive_list,label='Naive sampling')
    plt.loglog(pows,time_two_stage_list, label='Two stage sampling')
    plt.title('Time complexity of naive and two stage graph sampling methods')
    plt.xlabel('n')
    plt.ylabel('time')
    plt.legend()
    plt.show()
```

Time complexity of naive and two stage graph sampling methods



07

Investigating the size of component as a function of p.

Let n=4096 and p=[0,0.001]. Plot how the average size of the component containing node 1 changes as p varies, especially when $p \approx \frac{1}{n-1}$

- 1. First we generate sample according to alternate generation
- 2. Then carry our Breadth First Search to find all nodes reachable from node 1, which will be the size of the component containing node 1
- 3. Repeat step 1,2 by varying p and plot a graph of component size against p
- 4. Mark x axis where $p pprox rac{1}{n-1}$

```
In []: n = 4096
        probs = np.linspace(0,0.001,num=15)
        runs = 50
        comp_size_array_avg = []
        for prob in probs:
            component_size_array=[]
            for _ in range(runs):
                 graph = Two_Stage_Network(n,prob)
                component_size = 0
                visited=set()
                 q=deque([0])
                while q:
                    curr = q.popleft()
                    visited.add(curr)
                    for adj in graph.neighbors(curr):
                         if adj not in visited:
                             component_size+=1
                             q.append(adj)
                 component_size_array.append(component_size)
            comp_size_array_avg.append(np.mean(component_size_array)/n)
```

```
In []: plt.plot(probs,comp_size_array_avg)
   plt.axvline(1/(n-1),color='r',label='p ~ 1/(n-1)')
   plt.title('Component size as a function of p')
   plt.ylabel('Component size')
   plt.xlabel('p')
   plt.legend()
   plt.show()
```

