Objects and Classes

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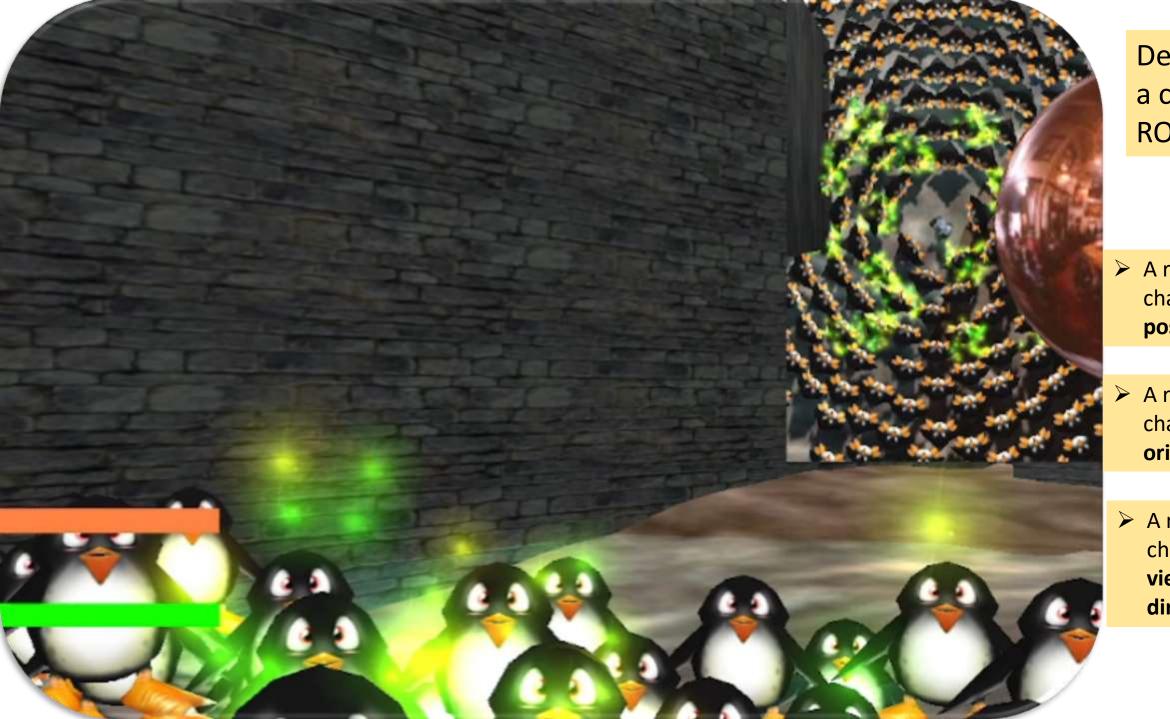
Hsinchu, Taiwan

Intended Learning Outcomes

- Name the features of a class
- Identify the scopes of variables (local or global)
- Distinguish between accessors and mutators
- List the features of class abstraction and encapsulation
- List the benefits of class abstraction and encapsulation

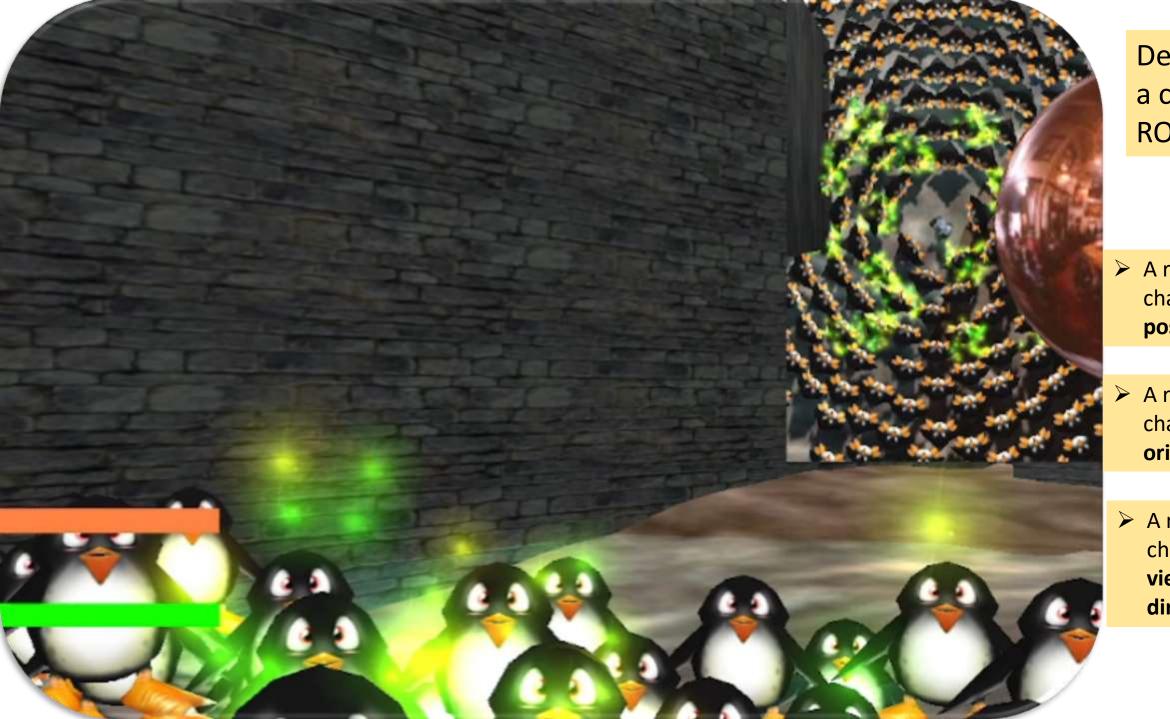
Content

- Classes vs objects
- State, behavours
- Unified Modeling Language
- Constructors
- Constant object names
- Anonymous objects
- Class is a data type
- Class definition and implementation
- Preventing multiple Inclusions
- Scopes
- Attribute modifiers: public, protected, private



Design a class ROBOT

- A robot can change its position.
- A robot can change its orientation.
- A robot can change its viewing direction.



Design a class ROBOT

- A robot can change its position.
- A robot can change its orientation.
- A robot can change its viewing direction.

```
class ROBOT {
 protected:
    Vector3 pos;
                       // position
                    // movement direction
    Vector3 dir;
    Vector3 speed;
 public:
    ROBOT();
    void stop( );
    void walkForward( );
    void backward( );
    void setDirection(const Vector3 & dir);
    void setPosition(const Vector3 & pos);
    void setSpeed( const Vector3 & speed);
    void update( double dt ); // simulation step size
```

```
ROBOT r1, r2; // create two ROBOT objects
ROBOT *robotA = nullptr; // one pointer
// instantiate a robot object
robotA = new ROBOT;
ROBOT *robots[NUM]; // an array of pointers
for (int I = 0; i < NUM; ++1) {
 robots[ i ] = new ROBOT;
```

```
class ROBOT {
 protected:
    Vector3 pos;
                        // position
    Vector3 dir;
                      // movement direction
    Vector3 speed;
 public:
    ROBOT();
    void stop( );
    void walkForward( );
    void backward( );
    void setDirection(const Vector3 & dir);
    void setPosition(const Vector3 & pos);
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    void update( double dt ); // simulation step size
```

```
ROBOT r1, r2; // create two ROBOT objects
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// instantiate a robot object
robotA = new ROBOT;
ROBOT *robots[NUM]; // an array of pointers
for (int I = 0; i < NUM; ++1) {
 robots[ i ] = new ROBOT;
```

```
An object has a A1 identity, state, and a set of A2 (implemented as A3).
```

```
class ROBOT {
 protected:
    Vector3 pos;
                        // position
    Vector3 dir;
                       // movement direction
    Vector3 speed;
 public:
    ROBOT();
    void stop( );
    void walkForward( );
    void backward( );
    void setDirection(const Vector3 & dir);
    void setPosition(const Vector3 & pos);
    void setSpeed( const Vector3 & speed);
    void update( double dt ); // simulation step size
```

```
ROBOT r1, r2; // create two ROBOT objects

ROBOT *robotA = nullptr; // one pointer
// instantiate a robot object
robotA = new ROBOT;

ROBOT *robots[NUM]; // an array of pointers
for (int I = 0; i < NUM; ++I) {
  robots[i] = new ROBOT;
```

- ➤ An object has a unique identity, state, and a set of behaviors (implemented as methods).
- ➤ Objects can be A1 identified.

```
class ROBOT {
 protected:
    Vector3 pos;
                        // position
    Vector3 dir;
                      // movement direction
    Vector3 speed;
 public:
    ROBOT();
    void stop( );
    void walkForward( );
    void backward( );
    void setDirection(const Vector3 & dir);
    void setPosition(const Vector3 & pos);
    void setSpeed( const Vector3 & speed);
    void update( double dt ); // simulation step size
```

```
ROBOT r1, r2; // create two ROBOT objects

ROBOT *robotA = nullptr; // one pointer

// instantiate a robot object
robotA = new ROBOT;

ROBOT *robots[NUM]; // an array of pointers

for (int I = 0; i < NUM; ++I) {
    robots[i] = new ROBOT;
```

- ➤ An object has a unique identity, state, and a set of behaviors (implemented as methods).
- ➤ Objects can be distinctly identified.

```
class ROBOT {
 protected:
    Vector3 pos;
                        // position
    Vector3 dir;
                       // movement direction
    Vector3 speed;
 public:
    ROBOT();
    void stop( );
    void walkForward( );
    void backward( );
    void setDirection(const Vector3 & dir);
    void setPosition(const Vector3 & pos);
    void setSpeed( const Vector3 & speed);
    void update( double dt ); // simulation step size
```

```
class ROBOT {
 protected:
    Vector3 pos;
                       // position
    Vector3 dir;
                     // movement direction
    Vector3 speed;
 public:
    ROBOT();
    void stop( );
    void walkForward( );
    void backward( );
    void setDirection(const Vector3 & dir);
    void setPosition(const Vector3 & pos);
    void setSpeed( const Vector3 & speed);
    void update( double dt ); // simulation step size
                                           11
```

ROBOT r1, r2; // create two ROBOT objects

```
r1 {
 pos = Vector3(1, 1, 0)
 dir = Vector3(0, 1, 0)
 speed = 1.7
r2 {
 pos = Vector3(0, 0, 0)
 dir = Vector3(1, 0, 0)
 speed = 1.7
```

State: A set of data fields (or properties) with their current values

State of object r2

```
class ROBOT {
 protected:
    Vector3 pos;
                        // position
    Vector3 dir;
                       // movement direction
    Vector3 speed;
 public:
    ROBOT();
    void stop( );
    void walkForward( );
    void backward( );
    void setDirection(const Vector3 & dir);
    void setPosition(const Vector3 & pos);
    void setSpeed( const Vector3 & speed);
    void update( double dt ); // simulation step size
                                            12
```

ROBOT r1, r2; // create two ROBOT objects

```
r1 {
                                State: A set of data
 pos = Vector3(1, 1, 0)
                                fields (or properties)
 dir = Vector3(0, 1, 0)
                                with their current
 speed = 1.7
                                values
r2 {
 pos = Vector3(0, 0, 0)
                                  State
 dir = Vector3(1, 0, 0)
                                  of object r2
 speed = 1.7
```

```
class ROBOT {
 protected:
    Vector3 pos;
                        // position
    Vector3 dir;
                       // movement direction
    Vector3 speed;
 public:
    ROBOT();
    void stop( );
    void walkForward( );
    void backward( );
    void setDirection(const Vector3 & dir);
    void setPosition(const Vector3 & pos);
    void setSpeed( const Vector3 & speed);
    void update( double dt ); // simulation step size
```

ROBOT r1, r2; // create two ROBOT objects

```
r1 {
 pos = Vector3(1, 1, 0)
 dir = Vector3(0, 1, 0)
 speed = 1.7
r2 {
 pos = Vector3(0, 0, 0)
 dir = Vector3(1, 0, 0)
 speed = 1.7
```

Behavior: a set of functions (methods)

```
class ROBOT {
 protected:
                       // position
    Vector3 pos;
    Vector3 dir;
                      // movement direction
    Vector3 speed;
 public:
    ROBOT();
    void stop( );
    void walkForward( );
    void backward( );
    void setDirection(const Vector3 & dir);
    void setPosition(const Vector3 & pos);
    void setSpeed( const Vector3 & speed);
    void update( double dt ); // simulation step size
                                           14
```

```
class ROBOT {
                 protected:
                    Vector3 pos;
                                        // position
  A1
                    Vector3 dir;
                                        // movement direction
                    Vector3 speed;
                 public:
 A2
                    ROBOT();
                    void stop( );
                    void walkForward( );
                    void backward( );
                    void setDirection(const Vector3 & dir);
A3
                    void setPosition(const Vector3 & pos);
                    void setSpeed( const Vector3 & speed);
                    void update( double dt ); // simulation step size
                                                            15
```

```
class ROBOT {
                     protected:
                         Vector3 pos;
                                             // position
     Data
                         Vector3 dir;
                                             // movement direction
     Fields
                         Vector3 speed;
Constructor(s)
                     public:
                         ROBOT();
                         void stop( );
                         void walkForward( );
                         void backward( );
 Functions
                         void setDirection(const Vector3 & dir);
 (methods)
                         void setPosition(const Vector3 & pos);
                         void setSpeed( const Vector3 & speed);
                         void update( double dt ); // simulation step size
                                                                16
```

```
class ClassName {
          Data Fields
          Constructors
          Functions
};
```

```
Data
     Fields
Constructor(s)
 Functions
 (methods)
```

```
class ROBOT {
 protected:
    Vector3 pos;
                        // position
                        // movement direction
    Vector3 dir;
    Vector3 speed;
 public:
    ROBOT();
    void stop( );
    void walkForward( );
    void backward( );
    void setDirection(const Vector3 & dir);
    void setPosition(const Vector3 & pos);
    void setSpeed( const Vector3 & speed);
    void update( double dt ); // simulation step size
                                            17
```

```
class ClassName {
          Data Fields
          Constructors
          Functions
};
```

```
class Circle {
  public:
    Circle() { radius = 0.0; } //Constructor
    double getArea() const; //Function
    double radius; //Data Field(s)
};
```

```
Circle Object1
Data field:
Object1.radius = 13.0
```

```
Circle Object2
Data field:
Object2.radius = 12.0
```

Circle Object3
Data field:
Object3.radius = 15.0

```
class Circle {
public:
    Circle() { radius = 0.0; } //Constructor
    double getArea() const; //Function
    double radius; //Data Field(s)
};
```

Circle Object1
Data field:
Object1.radius = 13.0

Circle Object2 Data field: Object2.radius = 12.0

Circle Object3
Data field:
Object3.radius = 15.0

State of a circle: A1 A2 of the circle

Behavior of a circle: A3

```
class Circle {
public:
    Circle() { radius = 0.0; } //Constructor
    double getArea() const; //Function
    double radius; //Data Field(s)
};
```

Circle Object1
Data field:
Object1.radius = 13.0

```
Circle Object2
Data field:
Object2.radius = 12.0
```

Circle Object3
Data field:
Object3.radius = 15.0

State of a circle: radius value of the circle

- Classes are constructs that define objects of the same type.
- Data fields: variables
- Behaviors: functions
- Constructors: they are invoked to construct objects from the class.

```
class Circle {
  public:
    Circle() { radius = 0.0; } //Constructor
    double getArea() const; //Function
    double radius; //Data Field(s)
};
```

```
Circle Object2
Data field:
Object2.radius = 12.0
```

Circle Object3
Data field:
Object3.radius = 15.0

State of a circle: radius value of the circle

- Classes are constructs that define objects of the same type.
- Data fields: variables
- Behaviors: functions
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```
class Circle {
  public:
    Circle() { radius = 0.0; } //Constructor
    double getArea() const; //Function
    double radius; //Data Field(s)
};
```

```
Circle Object2
Data field:
Object2.radius = 12.0
```

Circle Object3
Data field:
Object3.radius = 15.0

State of a circle: radius value of the circle

Behavior of a circle: getArea

The state of an object is the set of the data field

A1

- Classes are constructs that define objects of the same type.
- Data fields: variables
- Behaviors: functions
- Constructors: they are invoked to construct objects from the class.

```
class Circle {
  public:
    Circle() { radius = 0.0; } //Constructor
    double getArea() const; //Function
    double radius; //Data Field(s)
};
```

```
Circle Object2
Data field:
Object2.radius = 12.0
```

Circle Object3
Data field:
Object3.radius = 15.0

State of a circle: radius value of the circle

Behavior of a circle: getArea

The state of an object is the set of the data field values.

- Classes are constructs that define objects of the same type.
 - Data fields: variables
 - Behaviors: functions
- Constructors: they are invoked to construct objects from the class.

```
class Circle {
  public:
    Circle() { radius = 0.0; } //Constructor
    double getArea() const; //Function
    double radius; //Data Field(s)
};
```



Circle Object3

State of a circle: radius value of the circle

Circle Object2

- Classes are constructs that define objects of the same type.
- Data fields: variables
 - Behaviors: functions
- Constructors: they are invoked to construct objects from the class.

```
class Circle {
  public:
    Circle() { radius = 0.0; } //Constructor
    double getArea() const; //Function
    double radius; //Data Field(s)
};
```

Circle Object3

State of a circle: radius value of the circle

- Classes are constructs that define objects of the same type.
- Data fields: variables
- Behaviors: functions
 - Constructors: they are invoked to construct objects from the class.

```
class Circle {
  public:
    Circle() { radius = 0.0; } //Constructor
    double getArea() const; //Function
    double radius; //Data Field(s)
};
```

Circle Object2

Circle Object3

State of a circle: radius value of the circle

- Classes are constructs that define objects of the same type.
- Data fields: variables
- > Behaviors: functions
- Constructors: they are invoked to construct objects from the class.

Circle Object2

Circle Object3

State of a circle: radius value of the circle

Classes

```
class Circle {
public:
  double radius;
                                          //Data Fields. Variables
public:
                                          //Constructor. To construct an object
 Circle() {
        radius = 1.0;
  Circle( double newRadius ) {
                                          //Constructor. To construct an object
        radius = newRadius;
  double getArea( ) const {
                                          // behavior
     return radius*radius*3.141592654;
Circle a, b(12.5), c(21);
                                          // a, b, and c are of the same type.
```

After a, b, and c are constructed, what are their states?

a.radius =?
b.radius = ?
c.radius = ?

Classes

// a, b, and c are of the same type.

```
class Circle {
public:
  double radius;
                                          //Data Fields. Variables
public:
 Circle() {
                                          //Constructor. To construct an object
        radius = 1.0;
  Circle( double newRadius ) {
                                         //Constructor. To construct an object
        radius = newRadius;
  double getArea( ) const {
                                          // behavior
     return radius*radius*3.141592654;
```

Circle a, b(12.5), c(21);

The state of an object is the set of the data field values.

After a, b, and c are constructed, what are their states?

Classes

```
class Circle {
public:
  double radius;
                                          //Data Fields. Variables
public:
 Circle() {
                                          //Constructor. To construct an object
        radius = 1.0;
  Circle( double newRadius ) {
                                          //Constructor. To construct an object
                                                                                      b.getArea();
        radius = newRadius;
  double getArea( ) const {
                                          // behavior
     return radius*radius*3.141592654;
Circle a, b(12.5), c(21);
                                          // a, b, and c are of the same type.
```

To invoke a function: obj.funcName a.getArea();

c.getArea();

The access operator: the dot operator (.)

UML Class Diagram

```
class Circle {
public:
  double radius;
public:
  Circle() {
        radius = 1.0;
  Circle( double newRadius ) {
        radius = newRadius;
  double getArea( ) const {
     return radius*radius*3.141592654;
Circle a, b(12.5), c(21);
```

```
Circle
+radius: double
+Circle()
+Circle(newRadius: double)
+getArea() const: double
```

← Class name

← Data fields

Constructors and Functions

+: means public

-: means protected or private

a: Circle radius = 1.0 b: Circle radius = 12.5 c: Circle radius = 21.0

UML: Unified Modeling Language

Constructors

```
class Circle {
public:
  double radius;
public:
  Circle() {
                          // no-arg constructor
        radius = 1.0;
  Circle( double newRadius ) { // constructor
        radius = newRadius;
  double getArea( ) const {
     return radius*radius*3.141592654;
Circle a, b(12.5), c(21);
```

- The constructor has the same name as the class name.
- A no-arg or no-argument constructor does not have any arguments
- Constructors can be overloaded. They have the same name but with different signatures. They initialize data members. They do not return a value (no void).

Constructors

```
class Circle {
public:
  double radius;
public:
  Circle()
                          // no-arg constructor
        radius = 1.0;
  Circle( double newRadius ) { // constructor
        radius = newRadius:
  double getArea( ) const {
     return radius*radius*3.141592654;
Circle a, b(12.5), c(21);
```

- The constructor has the same name as the class name.
- A no-arg or no-argument constructor does not have any arguments
- Constructors can be **overloaded**. They have the same name but with different signatures. They initialize data members. They do not return a value (no void).
- If a class does not have any constructors, a default constructor is implicitly declared (by compiler). It is a noarg constructor with an empty body.

Parameters

```
class Circle {
public:
  double radius;
public:
  Circle() {
        radius = 1.0;
  Circle( double radius) { // newRadius
        this->radius = radius;
  double getArea( ) const {
     return radius*radius*3.141592654;
```

Circle	Class name
+radius: double	← Data fields
+Circle()	Constructors and
+Circle(radius : double)	Functions
+getArea() const: double	

- +: means public
- -: means protected or private

a: Circle radius = 1.0 b: Circle radius = 12.5 c: Circle radius = 21.0

Circle a, b(12.5), c(21);

UML: Unified Modeling Language

Class as a Data Type

```
class Circle {
public:
  double radius;
public:
  Circle() {
        radius = 1.0;
  Circle( double radius) { // newRadius
        this->radius = radius;
  double getArea( ) const {
     return radius*radius*3.141592654;
Circle a, b(12.5), c(21);
```

➤ Use class names to declare object names.

>A class is a data type.

➤ Use primitive data types to declare variables.

Constant Object Name

Square mySquare;

➤Once an object name is declared, it represents an object.

➤ It cannot be reassigned to represent another object.

An object name is a constant.

The contents of the object may change.

- Use it once.
- Do not refer to it later.

```
void f( A x );

void g( ) {
   f( A( ) );
}
```

```
void f( A *x ); // forward declaration

void g() {
  f( new A );

f( new A());
}
// may have the memory leak problem
```

- Use it once.
- Do not refer to it later.

```
void f( A x );
void g( ) {
  f( A( ) );
}
```

```
void f( A *x ); // forward declaration

void g() {
  f( new A );

f( new A() );
}
// may have the memory leak problem
```

```
void f( A *x ) {
    ...
    delete x;
    ...
}
```

- Use it once.
- Do not refer to it later.

```
void f( A x );

void g( ) {
   f( A( ) );
}
```

```
void f( A *x ); // forward declaration

void g() {
  f( new A );

f( new A());
}
// may have the memory leak problem
```

- Use it once.
- Do not refer to it later.

```
void f( A x );

void g( ) {
   f( A( ) );
}
```

```
Address of the memory space
```

```
void f( A *x ); // forward declaration

void g() {
  f( new A );

f( new A() );
}
// may have the memory leak problem
```

RAM

- Use it once.
- Do not refer to it later.

```
void f( A x );

void g( ) {
   f( A( ) );
}
```

X
Address of the memory space

```
void f( A *x ); // forward declaration

void g() {
  f( new A );

f( new A());
}
// may have the memory leak problem
```

- Use it once.
- Do not refer to it later.

```
void f( A x );

void g( ) {
   f( A( ) );
}
```

X
Address of the memory space

```
void f( A *x ); // forward declaration

void g() {
  f( new A );

f( new A());
}
// may have the memory leak problem
```

Anonymous Object

> When we create an object and use it once, we do not need to name it.

```
// create an anonymous object using the no-arg constructor
ClassName();
```

// create an anonymous object using the constructor with argument
ClassName(arguments);

new ClassName(arguments); // must be careful for memory leak

Anonymous Object as a Time Reporter

```
#pragma once
#include <ctime>
#include <iostream>
class FUNC_PROFILE {
private:
  clock_t start;
  double duration;
public:
  FUNC_PROFILE() {
    start = clock();
  ~FUNC_PROFILE() {
    duration = (clock() - start) / (double) CLOCKS_PER_SEC;
    std::cout << "duration:" << duration << std::endl;
```

Anonymous Object as a Time Reporter

```
#pragma once
#include <ctime>
#include <iostream>
class FUNC_PROFILE {
private:
  clock_t start;
  double duration;
public:
  FUNC_PROFILE() {
    start = clock();
  ~FUNC_PROFILE() {
    duration = (clock() - start) / (double) CLOCKS_PER_SEC;
    std::cout << "duration:" << duration << std::endl;
```

```
void foo() {
    // create and
    // destroy at the end of
    // the function call.
    FUNC_PROFILE a;
    ......
}
```

Anonymous Object as a Time Reporter

```
#pragma once
#include <ctime>
#include <iostream>
class FUNC_PROFILE {
private:
  clock_t start;
  double duration;
public:
  FUNC_PROFILE() {
    start = clock();
  ~FUNC_PROFILE() {
    duration = (clock() - start) / (double) CLOCKS_PER_SEC;
    std::cout << "duration:" << duration << std::endl;
```

```
void foo() {
    // create and
    // destroy at the end of
    // the function call.
    FUNC_PROFILE a;
    ......
}
```

```
void foo() {
    //create and destroy at once
    FUNC_PROFILE();
    ......
}
```

Class and Structure

```
struct Record {
   char id[16];
   char phoneNumber[16];
   int age;
};

Need to implement functions to handle the
   structure objects.
```

```
class Record {
  protected:
    string id;
    string phoneNumber;
  int age;
  public:
    void printf() const;
    void setID(const string &id);
};
```

Class and Structure

- >A structure and a class defines data members.
- >A class has methods.
- ➤ A structure does not have any methods.

```
struct Record {
   char id[16];
   char phoneNumber[16];
   int age;
};

Need to implement functions to handle the
   structure objects.
```

```
class Record {
   protected:
     string id;
     string phoneNumber;
   int age;
   public:
     void printf() const;
     void setID(const string &id);
};
```

Copy the content of one object to another

```
Square x, y;
 x = y; // use the A1
```

The data members of y are copied to their counterparts in object x.

Copy the content of one object to another Square x, y; x = y; // use the assignment copy

The data members of y are copied to their counterparts in object x.

Copy the content of one object to another Square x, y; x = y; // use the assignment copy

The data members of y are copied to their counterparts in object x.

```
class Square {
    public:
    double side;
    double area;
};
```

Copy the content of one object to another Square x, y; x = y; // use the assignment copy

The data members of y are copied to their counterparts in object x.

```
class Square {
    public:
    double side;
    double area;
};
```

```
x = y;
```

Same as

```
x.side = y.side;
x.area = y.area;
```

Copy the content of one object to another Square x, y; x = y; // use the assignment copy

The data members of y are copied to their counterparts in object x.

```
class Square {
    public:
    double side;
    double area;
    int *arr;
};
```

```
x = y;
```

Same as

```
x.side = y.side;
x.area = y.area;
x.arr = y.arr;
```

```
class Record {
  protected:
    string id;
  string phoneNumber;
  int age;
  public:
    Record();
  void printf() const;
  void setID(const string &id);
};
```

```
class Record {
  protected:
    string id;
  string phoneNumber;
  int age;
  public:
    Record();
  void printf() const;
  void setID(const string &id);
};
```

Record.h

Class declaration

```
class Record {
   protected:
      string id;
      string phoneNumber;
   int age;
   public:
      Record();
      void printf() const;
      void setID(const string &id);
};
```

Record.h

Class declaration

```
Record::Record() { id=""; age=... }
void Record::printf() const { ... }
void setID(const string &id) {
   this->id = id;
}
.....
```

```
class Record {
   protected:
      string id;
      string phoneNumber;
   int age;
   public:
      Record();
      void printf() const;
      void setID(const string &id);
};
```

Record.h

Class declaration

```
Record::Record() { id=""; age=... }
void Record::printf() const { ... }
void setID(const string &id) {
   this->id = id;
}
.....
```

Record.cpp

Class Implementation

Define content

Class definition: describe the contract of the class.

Class declaration: simply list all the data fields, constructor prototypes, and the function prototypes.

Class implementation: implement the contract, including constructors and functions.

- ➤ The class declaration and implementation are in two separate files.
- ➤ Both files should have the same name, but with different extension names.
- Class declaration file: the extension name is .h.
- Class implementation file: the extension name is .cpp

```
class Record {
   protected:
      string id;
      string phoneNumber;
   int age;
   public:
      Record();
      void printf() const;
      void setID(const string &id);
};
```

Record.h

Class declaration

```
Record::Record() { id=""; age=...}

void Record::printf() const { ... }

void setID(const string &id) {

this->id = id;
}
.....
```

Record.cpp

Class Implementation

Define content

Inline Declaration in a class

Inline function may improve the execution time and speed of the program.

```
class A {
    ......

// foo is defined inside the class body of A
    int foo( int a, int b) { return a + b; }

// A1 method
}
```

Inline Declaration in a class

Inline function may improve the execution time and speed of the program.

```
class A {
    ......

// foo is defined inside the class body of A
    int foo( int a, int b); // declaration
}
```

int A::foo(int a, int b) { return a + b; } // A2 method

Inline Declaration in a class

Inline function may improve the execution time and speed of the program.

```
class A {
 // foo is defined inside the class body of A
 int foo( int a, int b); // declaration
inline int A::foo(int a, int b) { return a + b; } // inline method
```

```
class Record_N {
   public:
     string id;
     string phoneNumber;
   int age;
   public:
     Record();
     void printf() const;
     void setID(const string &id);
};
```

```
void main() {
   Record_N r;
   r.id = "012345678"; // ok
   r.age = 18;
}
```

main is the client of Record_N

```
class Record_N {
   public:
     string id;
     string phoneNumber;
   int age;
   public:
     Record();
     void printf() const;
     void setID(const string &id);
};
```

```
class Record {
  protected:
    string id;
  string phoneNumber;
  int age;
  public:
    Record();
    void printf() const;
    void setID(const string &id);
};
```

```
void main() {
   Record_N r;
   r.id = "012345678"; // ok
   r.age = 18;
}
```

main is the **client** of Record_N and Record.

Non-hidden data members

- ➤ Clients can access them directly.
- ➤ There are potential problems.
- They can be modified directly from outside.

Potential problems

- Data may be tampered.
- It makes the class difficult to maintain.
- It is vulnerable to bugs.
- Clients may modify the data members. Subsequently, the state of an object can be wrong.

```
class Record_N {
   public:
     string id;
     string phoneNumber;
   int age;
   public:
     Record();
     void printf() const;
     void setID(const string &id);
};
```

```
class Record {
  protected:
    string id;
    string phoneNumber;
  int age;
  public:
    Record();
    void printf() const;
    void setID(const string &id);
};
```

```
void main() {
   Record_N r;
   r.id = "012345678"; // ok
   r.age = 18;
}
```

main is the **client** of Record_N and Record.

Non-hidden data members

- ➤ Clients can access them directly.
- ➤ There are potential problems.
- They can be modified directly from outside.

Potential problems

- Data may be tampered.
- It makes the class difficult to maintain.
- It is vulnerable to bugs.
- Clients may modify the data members. Subsequently, the state of an object can be wrong.

```
class Record_N {
    public:
    int num;
    int *arr;

public:
        Record();
        void printf() const;
        void setID(const string &id);
};
```

```
class Record {
    protected:
    int num;
    int *arr;

public:
       Record();
       void printf() const;
      void setID(const string &id);
};
```

```
void main() {
    Record_N r;

    r.arr = (int*) 1234;
}
```

```
void main() {
  Record r;

r.arr = (int*) 1234;  // error
}
```

main is the **client** of Record_N and Record.

```
class Record {
public:
   string getID() const;
   int getAge( ) const;
   bool isMale( ) const;
   bool isFemale( ) const;
   void setID( const string &id );
   void setAge( int age );
public:
   Record();
   void printf() const;
protected:
   string id;
   string phoneNumber;
   int age;
   GENDER gender;
```

```
get functions
get functions return a
       bool data type
         set function
```

```
class Record {
public:
   string getID() const;
   int getAge( ) const;
   bool isMale( ) const;
   bool isFemale( ) const;
   void setID( const string &id );
   void setAge( int age );
public:
   Record();
   void printf() const;
protected:
   string id;
   string phoneNumber;
   int age;
   GENDER gender;
```

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get functions
get functions return a
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class Record {
public:
   string getID() const;
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   void setID( const string &id );
   void setAge( int age );
public:
   Record();
   void printf() const;
protected:
   string id;
   string phoneNumber;
   int age;
   GENDER gender;
```

```
>A get function: a getter (or accessor)
➤ A set function: a setter (or mutator)
                                                 get functions
The signature of a get function:
                                        get functions return a
            getPropertyName( )
                                               bool data type
    A1
The get function returns a bool data type
                                                 set function
 A2 isPropertyName()
The signature of a set function:
    A3
setPropertyName(dataType propertyValue)
```

```
class Record {
public:
   string getID() const;
   int getAge( ) const;
   bool isMale( ) const;
   bool isFemale( ) const;
   void setID( const string &id );
   void setAge( int age );
public:
   Record();
   void printf() const;
protected:
   string id;
   string phoneNumber;
   int age;
   GENDER gender;
```

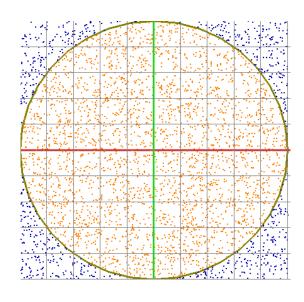
```
➤ A get function: a getter (or accessor)
➤ A set function: a setter (or mutator)
                                                 get functions
The signature of a get function:
                                        get functions return a
returnType getPropertyName( )
                                               bool data type
The get function returns a bool data type
                                                 set function
bool isPropertyName()
The signature of a set function:
public void
setPropertyName(dataType propertyValue)
```

```
class Record {
public:
   string getID() const;
   int getAge( ) const;
   bool isMale( ) const;
   bool isFemale( ) const;
   void setID( const string &id );
   void setAge( int age );
public:
   Record();
   void printf() const;
protected:
   string id;
   string phoneNumber;
   int age;
   GENDER gender;
```

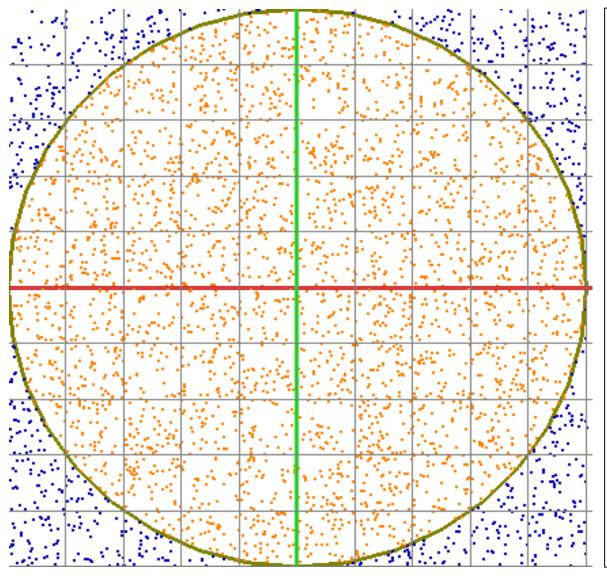
- ➤ When we decide to implement accessors and mutators for data members with different attributes, we need to think A1
- The modifications of data members do not lead to a A2
- ➤ Use the right attribute modifiers for declaring the data members: private, A3

Accessor and Mutator

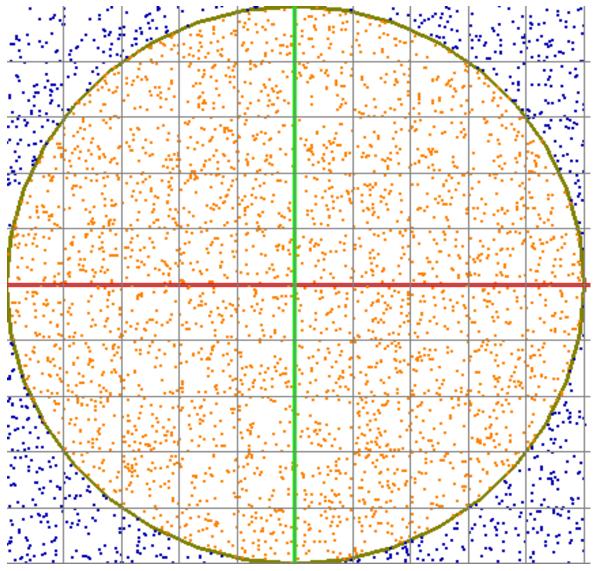
- ➤ When we decide to implement accessors and mutators for data members with different attributes, we need to think carefully.
- The modifications of data members do not lead to a mistake.
- ➤ Use the right attribute modifiers for declaring the data members: private, protected, public



```
class MONTE_CARLO_SYSTEM {
protected:
 double mRadius;
 int mNumSamples; // number of sample points
 vector<float> mX; // x-coordinate
 vector<float> mY; // y-coordinate
 void generateUniformSamples( );
public:
 MONTE_CARLO_SYSTEM();
 void askForInput( );
 void reset();
 double computePI() const;
 double getRadius() const;
 int getNumSamples() const; // get the number of samples
 bool getSample(
   int sampleIndex, float &x, float &y) const;
```



```
class MONTE_CARLO_SYSTEM {
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 MONTE_CARLO_SYSTEM( );
 void askForInput( );
 void reset();
 double computePI() const;
 double getRadius() const;
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public:
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 MONTE_CARLO_SYSTEM();
                                need to know how
 void askForInput( );
                                the sample points
 void reset();
 double computePI() const;
                                are stored.
 double getRadius() const;
 int getNumSamples() const; // get the number of samples
 bool getSample(
   int sampleIndex, float &x, float &y) const;
```

Class abstraction: separate

A1 from A2

```
class MONTE_CARLO_SYSTEM {
protected:
 double mRadius:
 int mNumSamples; // number of sample points
 vector<float> mX; // x-coordinate
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 void generateUniformSamples( );
public:
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 MONTE_CARLO_SYSTEM();
                                need to know how
 void askForInput( );
                                the sample points
 void reset();
 double computePI() const;
                                are stored.
 double getRadius( ) const;
 int getNumSamples() const; // get the number of samples
 bool getSample(
   int sampleIndex, float &x, float &y) const;
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 void reset();
 double computePI() const;
                                are stored.
 double getRadius() const;
 int getNumSamples() const; // get the number of samples
 bool getSample(
   int sampleIndex, float &x, float &y) const;
```

Class abstraction: separate class implementation from the use of the class.

The creator of the class **provides a** of the class.

```
class MONTE_CARLO_SYSTEM {
protected:
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 int mNumSamples; // number of sample points
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 void generateUniformSamples( );
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 void askForInput( );
                                the sample points
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Class abstraction: separate class implementation from the use of the class.

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```

Class abstraction: separate class implementation from the use of the class.

- The creator of the class **provides a** description of the class.
- Let the user know how the class can

A1

```
class MONTE_CARLO_SYSTEM {
protected:
 double mRadius:
 int mNumSamples; // number of sample points
 vector<float> mX; // x-coordinate
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 void generateUniformSamples( );
public:
                                The client does not
 MONTE_CARLO_SYSTEM();
                                need to know how
 void askForInput( );
                                the sample points
 void reset();
 double computePI() const;
                                are stored.
 double getRadius( ) const;
 int getNumSamples() const; // get the number of samples
 bool getSample(
   int sampleIndex, float &x, float &y) const;
```

- The creator of the class **provides a** description of the class.
- ➤ Let the user know how the class can be used.
- The user of the class does not need to know how the class A1

```
class MONTE_CARLO_SYSTEM {
protected:
 double mRadius:
 int mNumSamples; // number of sample points
 vector<float> mX; // x-coordinate
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 void generateUniformSamples( );
public:
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 MONTE_CARLO_SYSTEM();
                                need to know how
 void askForInput( );
                                the sample points
 void reset();
 double computePI() const;
                                are stored.
 double getRadius() const;
 int getNumSamples() const; // get the number of samples
 bool getSample(
   int sampleIndex, float &x, float &y) const;
```

- The creator of the class **provides a** description of the class.
- Let the user know how the class can be used.
- The user of the class does not need to know how the class is implemented.
- The detail of implementation is and A2 from the user.

```
class MONTE_CARLO_SYSTEM {
protected:
 double mRadius;
 int mNumSamples; // number of sample points
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 void generateUniformSamples( );
public:
                                The client does not
 MONTE_CARLO_SYSTEM();
                                need to know how
 void askForInput( );
                                the sample points
 void reset();
 double computePI() const;
                                are stored.
 double getRadius() const;
 int getNumSamples() const; // get the number of samples
 bool getSample(
   int sampleIndex, float &x, float &y) const;
```

- The creator of the class **provides a** description of the class.
- Let the user know how the class can be used.
- The user of the class does not need to know how the class is implemented.
- The detail of implementation is encapsulated and hidden from the user.

```
class MONTE_CARLO_SYSTEM {
protected:
 double mRadius:
 int mNumSamples; // number of sample points
 vector<float> mX; // x-coordinate
 vector<float> mY; // y-coordinate
 void generateUniformSamples( );
public:
                                The client does not
 MONTE_CARLO_SYSTEM();
                                need to know how
 void askForInput( );
                                the sample points
 void reset();
 double computePI() const;
                                are stored.
 double getRadius() const;
 int getNumSamples() const; // get the number of samples
 bool getSample(
   int sampleIndex, float &x, float &y) const;
```

Intended Learning Outcomes

- Name the features of a class
- Identify the scopes of variables (local or global)
- Distinguish between accessors and mutators
- List the features of class abstraction and encapsulation
- List the benefits of class abstraction and encapsulation

Supplemental Materials

Where can you find a variable?

```
void foo ( int a ) {
 int r;
 r = 12.0;
void main() {
 int r;
 foo(10);
```

```
void foo ( int a ) {
 int r;
 r = 12.0;
void main() {
 int r;
 foo(10);
```

```
double r;
void foo ( int a ) {
 int r;
 r = 12.0;
void main() {
 double r;
 foo(10);
```

```
void foo ( int a ) {
 int r;
 r = 12.0;
void main() {
 int r;
 foo(10);
```

```
double r;
void foo ( int a ) {
 int r;
 r = 12.0;
void main() {
 double r;
 foo(10);
```

```
double r;
void foo ( int a ) {
 int r;
 r = 12.0;
 for (int i = 0; i < 10; ++i) {
    double r = 0.0;
    r += i;
void main() {
 double r;
 foo(10);
                          92
```

 The (lexical) scope of a binding: visibility of an entity

```
void foo ( int a ) {
 int r;
 r = 12.0;
void main() {
 int r;
 foo(10);
```

```
double r;
void foo ( int a ) {
 int r;
 r = 12.0;
void main() {
 double r;
 foo(10);
```

```
double r;
void foo ( int a ) {
 int r;
 r = 12.0;
 for (int i = 0; i < 10; ++i) {
    double r = 0.0;
    r += i;
void main() {
 double r;
 foo(10);
```

Global variables

- > they are declared A1 all functions
- they are accessible to scope functions in its
- The scope of a global variable: from its declaration and to

 A3

```
double r;
void foo ( int a ) {
  int r;
  r = 12.0;
  for (int i = 0; i < 10; ++i) {
    double r = 0.0;
    r += i;
void main() {
 double r;
 foo(10);
                          94
```

Global variables

- they are declared outside all functions
- they are accessible to all functions in its scope
- The scope of a global variable: from its declaration and to the end of the program.

```
double r;
void foo ( int a ) {
 int r;
 r = 12.0;
 for (int i = 0; i < 10; ++i) {
    double r = 0.0;
    r += i;
void main() {
 double r;
 foo(10);
```

Global variables

- > they are declared outside all functions
- they are accessible to all functions in its scope
- > The scope of a global variable: from its declaration and to the end of the program.

- They are defined A1 functions
- The scope of a local variable: from its declaration and continues to the A2 containing the variable.

```
double r;
void foo ( int a ) {
 int r;
 r = 12.0;
 for (int i = 0; i < 10; ++i) {
    double r = 0.0;
    r += i;
void main() {
 double r;
 foo(10);
```

Global variables

- > they are declared outside all functions
- they are accessible to all functions in its scope
- The scope of a global variable: from its declaration and to the end of the program.

- They are defined inside functions
- The scope of a local variable: from its declaration and continues to the end of the block containing the variable.

```
double r;
void foo ( int a ) {
  int r;
  r = 12.0;
 for (int i = 0; i < 10; ++i) {
    double r = 0.0;
    r += i;
void main() {
 double r;
 foo(10);
                          97
```

Global variables

- > they are declared outside all functions
- they are accessible to all functions in its scope
- The scope of a global variable: from its declaration and to the end of the program.

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- The scope of a local variable: from its declaration and continues to the end of the block containing the variable.

```
double r;
void foo ( int a )<sub>i</sub>{
 int r;
  r = 12.0;
  for (int i = 0; i < 10; ++i) {
    double r = 0.0;
    r += i;
void main() {
  double r;
  foo(10);
```

Global variables

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```
double r;
void foo ( int a )<sub>i</sub>{
 int r;
 r = 12.0;
 for (int i = 0; i < 10; ++i) {
    double r = 0.0;
    r += i;
void main(){
 double r;
 foo(10);
```

Global variables

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```
double r;
void foo (int a) [
 int r;
 r = 12.0;
 for (int i = 0; i < 10; ++i) {
 \checkmark double r = 0.0;
    r += i;
void main()/{
 double r;
 foo(10);
                          100
```

Global variables

- > they are declared outside all functions
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- > The scope of a global variable: from its declaration and to the end of the program.

- They are defined inside functions
- The scope of a local variable: from its declaration and continues to the end of the block containing the variable.

```
double r;
void foo (int a) {
 int r;
  r = 12.0;
  for (int i = 0; i < 10; ++i)/{\frac{1}{2}}
  \checkmark double r = 0.0;
    r += i;
void main() {
 double r;
  foo(10);
                            101
```

Global variables

- > they are declared outside all functions
- they are accessible to all functions in its scope
- The scope of a global variable: from its declaration and to the end of the program.

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- The scope of a local variable: from its declaration and continues to the end of the block containing the variable.

```
double r;
void foo ( int a ) {
  int r;
  r = 12.0;
 for (int i = 0; i < 10; ++i) {
    double r = 0.0;
    r += i;
void main() {
 double r;
 foo(10);
                         102
```

The Scope of Data Members (Data Fields)

Data fields can be accessible by all methods, constructors, and the destructor.

Data fields and functions can be declared in any order in a class.

```
class Rectangle {
    private:
        double side1, side2;
    public:
        Rectangle();
        double getSide1() const;
};
```

The Scope of Data Members (Data Fields)

Data fields can be accessible by all methods, constructors, and the destructor. Data fields and functions can be declared in any order in a class.

```
class A {
private:
 int a; // data member( data field)
public:
 void foo() {
   int a; // local variable has the same name as a data field
   a = 5; // 5 is assigned to the local variable. Higher precedence
```

Data Encapsulation

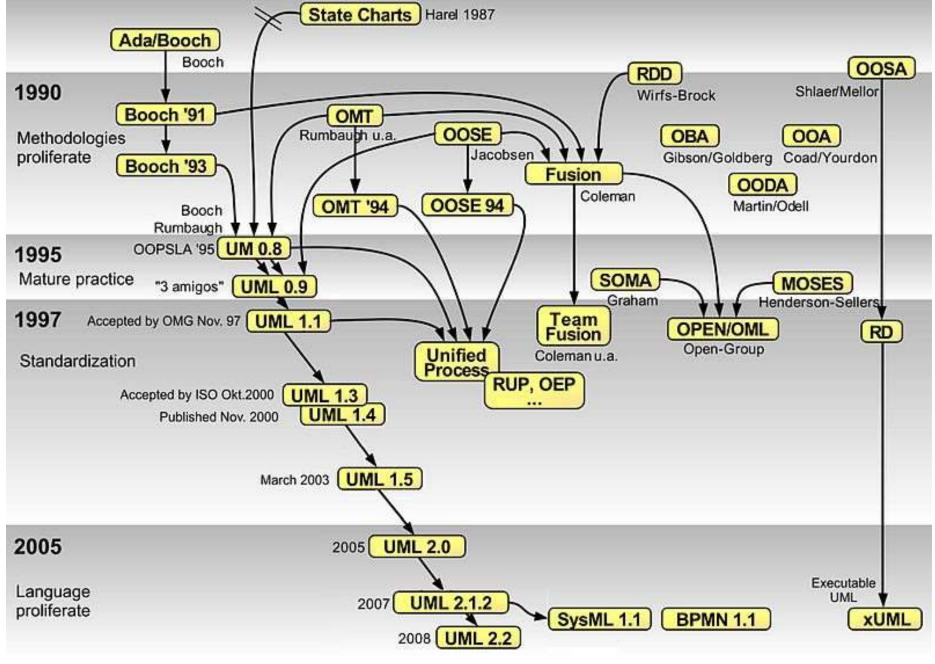
```
    Data hiding

class Circle {
       private:
              double radius; // the client needs not to know what it is.
```

Circle c; c.radius = 10.1; // not allowed

Object-Oriented Programming (OOP) Concepts

- We use objects in implementing programs.
- An object represents an entity in the real world.
- An object has a unique identity, state, and a set of behaviors (implemented as methods).
- Objects can be distinctly identified.
- The state of an object consists of a set of data fields (or properties) with their current values.
- The behavior of an object is defined by a set of functions.



https://en.wikipedia.org/wiki/Unified_Modeling_Language#/media/File:OO_Modeling_languages_history.jpg

Object Names

Assign a name when we create an object.

A constructor is invoked when an object is created.

ClassName objectName; // Create an object using the no-arg constructor

For example, SQUARE sq;

Constructing an object with arguments

// Declare an object using a constructor with arguments

ClassName objectName(arguments);

For example,

SQUARE sq(3.2); TRIANGLE triangle(1.2, 1., .8);

Access Operator

- ➤ The access operator: the dot operator (■)
- >We can use this operator to access data members and methods.

objectName.dataField: reference a data field in the object.

objectName.function(arguments): invoke a function on the object.

Naming Objects and Classes

Capitalize the first letter of each word in a class name;

Examples: Circle, Square

inline functions

The binary code of the function is copied to the position that the function is invoked.

```
inline void g( int a, int b ) { ......}
void foo() {
    g( 1, 4);
    g( 3, 6);
}
cache
```

Rectangle Class

Rectangle

```
side1: double
side2: double
area: double
perimeter: double
+Rectangle()
+Rectangle( double len1, double len2 )
+getSide1()
+getSide2()
+setSide1(side1: double): void
+setSide2(side2: double): void
+getArea()
+getPerimeter()
+computeArea()
...
```