Exam Preparation

Multiple Choice Question

- Definition
- · What does it mean? and how it fuction and work
- · Concepts

Short Answer Question

- · Question like write fomula
- figures

Studying Content

What is optimization (Mathematical Programming)?

- WINIDOUIA, 2021

Solving problems about how to best (optimally) use limited resources (people, machines, money, time, land)

Elements of an optimization model:

Decisions: Variables whose values the decision maker can choose

Objective: Value that is optimized (maximized or minimized)

Constraints: Requirements that must be met

Widely applicable for both organizations and individuals:

Organizations

Optimal mix of products or services, location of facilities, resource allocation, scheduling, hiring best workers based on multiple criteria

Minimizing costs (production, transportation, inventory management)

Maximizing profits, value of advertising

Individuals

Career choices, time usage

Where optimization can be used?

- Operation: factory layout, scheduling, logistics, supply-chain management, product development, resource allocation, sourcing, risk management and mitigation, inverstment decisions.
- Marketing : Production pricing, product configuration, revenue Management
- · Economics: supply-demand models, managerial economics
- Finance : portfolio selection, risk management
- · Statistics: parameter estimation in curve fitting, optimal sample sizes, pattern recognition
- · Alrspace: cost models, satellite component selection, spacecraft design
- Engineering: chemical equilibriums, product designs
- · Government: military operations, fund allocations

History of Optimization - little note

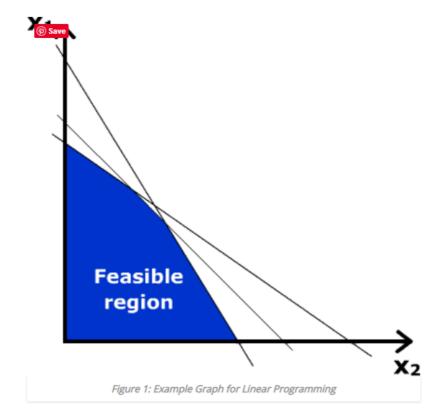
WW2 : military problems that were too complex to address using intuition (직관적) / experience ex) deployment of radars, organizing convoy, bombing, antisubmarine, mining operations

benefits of Optimization

- · understanding of data (big data, and business analytics)
- allows to deal with complex otherwise intractable (아주 다루기 힘든) problems
- Can incorporate (포함하다) uncertainty in outcomes
- to build insights to the problem and develop a plan how to utilize the available resources

Major types of mathematical programming

- LP Linear Programs; continuous variables and linear objective and constraints
- · NLP Nonlinear Programs : continuous variables with nonlinear terms in either the objective or the constraint



The basic components of linear programming are as follows.

Decision variables - Quantities to determine

Objective Function – Describes how each decision variable affect the property that should be optimized

Constraints - Represents how each decision variable would use limited amounts of resources

Data – Explains the relationships between the objective function and the constraints

Basic components of LP

Mathematical Programming: General Form

Mathematical Programming: General Form

 $x_1, x_2, ..., x_n$ are the *n* decision variables

max (or min): $f_0(x_1, x_2, ..., x_n)$

Objective function

Left-hand-side (LHS) functions for the constraints

subject to:

 $f_i(x_1, x_2, ..., x_n) \le b_i, \forall i \in M_1$

Right-hand-side (RHS) values for the constraints

 $f_i(x_1, x_2, ..., x_n) = b_i, \forall i \in M_3$

 M_3 is the index set of constraints of the = type.

 $x_i \ge 0, \forall j \in N_1$

 $x_i \le 0, \forall j \in N_2$ x_i unrestricted, $\forall j \in N_3$ ∀ denotes "for all"

 M_1 is the index set of constraints of the \leq type.

 M_2 is the index set $f_i(x_1, x_2, ..., x_n) \ge b_i, \forall i \in M_2 \longleftarrow \text{of constraints of}$ the \geq type.

> N_1 , N_2 and N_3 and are the index sets of nonnegative, nonpositive and unrestricted variables, respectively.

> > 27

LP in General Form

Objective function cost min (or max) $c_1x_1 + c_2x_2 + ... + c_nx_n$ coefficients $a_{i1}x_1 + a_{i2}x_2 + ... + a_{in}x_n \le b_i, \forall i \in M_1$ subject to $a_{i1}x_1 + a_{i2}x_2 + ... + a_{in}x_n \ge b_i, \forall i \in M_2$ Constraints' coefficients $a_{i1}x_1 + a_{i2}x_2 + ... + a_{in}x_n = b_i, \forall i \in M_3$ $x_i \ge 0, \forall j \in N_1$ $x_i \leq 0, \forall j \in N_2$ x_i unrestricted, $\forall j \in N_3$

Linear objective function and linear constraints

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LP General Form: Using Summation Notation

$$\begin{aligned} & \text{min (or max)} \sum_{j \in N_1 \cup N_2 \cup N_3} c_j x_j \\ & \text{subject to} & \sum_{j \in N_1 \cup N_2 \cup N_3} a_{ij} x_j \leq b_i, \forall i \in M_1 \\ & \sum_{j \in N_1 \cup N_2 \cup N_3} a_{ij} x_j \geq b_i, \forall i \in M_2 \\ & \sum_{j \in N_1 \cup N_2 \cup N_3} a_{ij} x_j = b_i, \forall i \in M_3 \\ & x_j \geq 0, \forall j \in N_1 \\ & x_j \leq 0, \forall j \in N_2 \\ & x_j \text{ unrestricted, } \forall j \in N_3 \end{aligned}$$

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History of LP

Founders

• Kantorovich : Develop LP problem 1939

• Danzig: develop and simplx solution method 1947

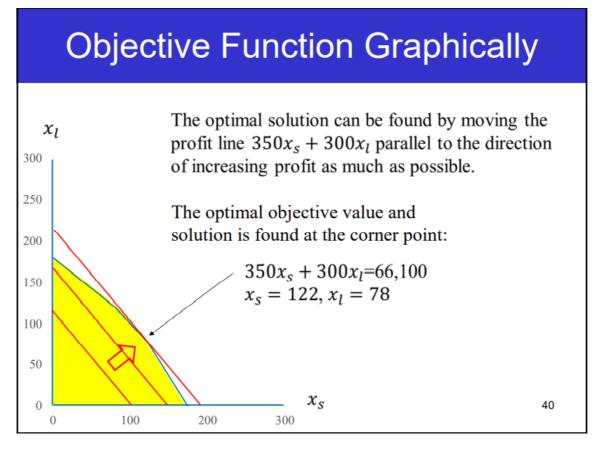
· Von Neumann: develop the theory of duality 1947

Terminology

- Feasible solution : any vector x of decision variables that satisfies all the constraints
- · Feasible Region : the set of all feasible solutions
- Infeasible solution: a solution where at least one constraint is not satisfied
- Optimal solution : x* is the feasible solution which depending on the problem type either maximizes or minimizes the objective function
- Optimal Objective value : value of the objective function corresponding to the optimal solution \mathbf{x}^{\star}

Solve a LP Problem with Graph

•



limit of the Graph Approach to solve a LP problem

- · very difficulty to aplly for 3 variables models
- Can not applied if there are more than 3 variables due to humans limitations to visualized beyond three dimensions
- the approach is cumbersome and slow for problems with many constraints

Summary of solving LP Problem with Graph

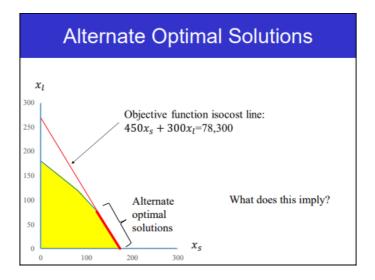
- LP Problems can be solved graphically up to three decision variables
- · This approach relies on
 - drawing the feasible region as defined by the constraints and finding the optimal objective value and decisions by moving along the isocost lines of the objective function to the direction of increasing objective function

Anomalies (변칙) in LP Models

Redundant Constraint

이미 전 constraint에서 제한을 둔 부분 그 이상의 부분에 (<u>즉 영향이 없는 부분에</u>) 한번더 constraints를 거는것을 redundant constraints 라고 한다.

Alternate Optimal Solution



위 이미지에서, 저 두꺼운 빨간색이 쳐진곳들이 다 alternate optimal solution이다. 저 부분에 있는 모든 지점들이 could be optimal solution.

Unbounded Solution

unbounded solution is a situation where objective function is infinite.

- unboundedness occurs when the objective function can improve indefinitely by varying one or more variables
- · should not occur in realistic models
- · Why it causes?
 - o if unboundedness occurs, either wrong input data was entered or relevant constraints was omitted.

No feasible Solution

no area that colored.

- · two reasons why
 - o mistake in the model (some data is entered incorrectly
- the feasible region is empty

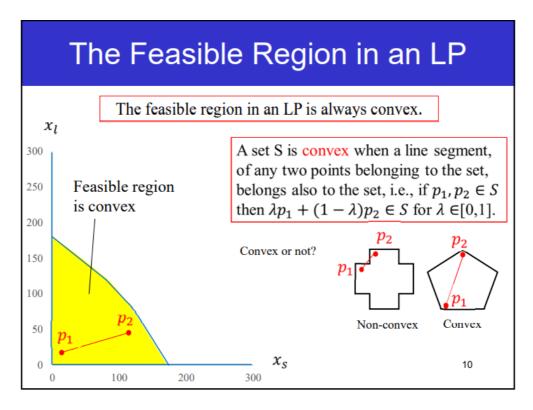
Logic behind simplex Algorithm

existence of an Optimal solution

A bounded and non-empty feasible region has an optimal solution

the feasible region in an LP

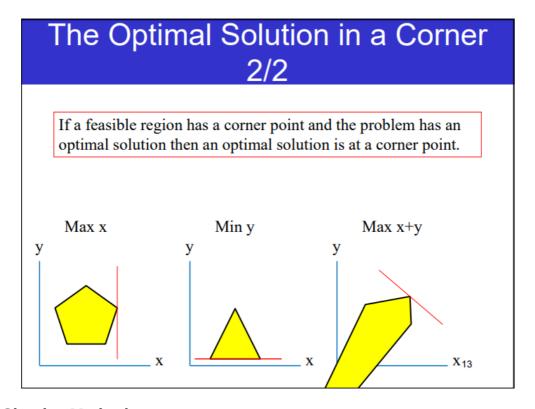
the feasible region in an LP is always convex (볼록한)



Corner Points are only defined for convex sets

a corner point is a point in the feasible region that is not mid point of any other two points in the feasible region.

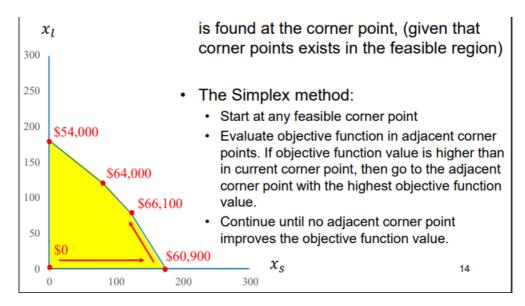
If a feasible region has a corner point and the problem has an optimal solution then an optimal solution is at a corner point.



The Simplex Method

The Optimal solution is found at the corner point, (given that corner points exists in the feasible region).

- · Start at any feasible corner point
- Evaluate objective function is adjacent corner points. If objective function value is higher than in current corner point, then go to the adjacent corner point with the highest objective function value.
- Continue until no adjacent corner point improves the objective function value.



History

- was developed in 1947 by George Dantzig
- · It is very fast for solving large practical problem
- Identifies if the LP is infeasible, finds the optimal solution if such exists, and checks for unboundedness

LP Problem Manipulation (교모한 처리, 조작)

Equivalence of minimization and maximization problems

$$\min 2x$$
 is equivalent to $\max -2x$
 $ax \ge b$ $ax \ge b$

 Absolute value in a minimization (maximization) objective function with positive (negative) coefficients for decision variables:

$$\min 2|x| \qquad \Longrightarrow \qquad \min 2y \qquad \text{Redundant if } x>0$$

$$ax \ge b \qquad \qquad y \ge x, y \ge -x$$

• Absolute value in an inequality constraint: Redundant if x<0

$$\begin{array}{ccc}
\min x \\
ax \ge b \\
|x| \le 3
\end{array}
\qquad \qquad \begin{array}{c}
\min x \\
ax \ge b \\
x \le 3, -x \le 3
\end{array}$$

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Linearizing Problems with Absolute Values

Linearizing Minmax Problem VS Linearizing Maxmin Problem

• The minimization of a max of piecewise linear convex function: $\min x = \max \left\{ -x + \frac{5}{2}, -\frac{2}{5}x + 2, 1/2x \right\}$ $\max z = \sum x \ge b$ $z \ge -x + \frac{5}{2},$ $z \ge -\frac{2}{5}x + 2,$ $z \ge 1/2x$ A piecewise linear convex function approximated by a piecewise line

Minmax : Objective 가 min 일때, constraints 들은 greater than equal to의 constraints 가지고 있다.

The maximization of a min of piecewise linear concave function:

$$\max \min \left\{ x, 1, -\frac{1}{4}x + 5 \right\}$$

$$ax \ge b$$

$$z \le x,$$

$$z \le 1,$$

$$z \le -\frac{1}{4}x + 5$$

Maxmin : Objective 가 max이지만, constraints 는 less than eqaul to 의 constraints를 가지고있다.

Linearizing ratio Constraints

It can be work if denominator is positive for all possible values of the decision variables (for negative denominator the inequality sign would change)

Duality (이중성, 이원성) in LP

LP Standard Form

· LP standard form:

subject to
$$\begin{aligned} \min(or \ max) \ c^T x \\ Ax &= b & A \in \mathbb{R}^{m \times n} \\ x &\geq 0 & x \in \mathbb{R}^n \end{aligned}$$

Define:

$$\mathbf{x} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$$
 (n,1) vector of decision variables
$$\mathbf{c} = \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{pmatrix}$$
 (n,1) vector of objective function coefficients

$$\mathbf{A} = \begin{pmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \cdots & a_{mn} \end{pmatrix} \qquad \begin{array}{c} \text{(m,n) matrix of} \\ \text{coefficients for} \\ \text{constraints} \end{array} \qquad \mathbf{b} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{pmatrix} \qquad \begin{array}{c} \text{(m,1) vector of} \\ \text{coefficients for} \\ \text{constraints' right hand} \\ \text{side} \\ \end{array}$$

Any LP Problem can be converted to the Standard Form Above

LP Standard Form

subject to $\begin{aligned} & \min(or \ max) \ c^T x \\ & Ax = b & A \in \mathbb{R}^{m \times n} \\ & x \ge 0 & x \in \mathbb{R}^n \end{aligned}$

The Rule of Conversion from LP Problem to LP Standard Form

LP Problem:

 $\begin{array}{l}
 min2x_1 - 3x_2 \\
 3x_1 + 4x_2 & 4 \\
 2x_1 + x_2 & 1 \\
 x_1 \ge 0, x_2 \le 0
 \end{array}$

1. \leq 일때는 새로운 값의 value를 더하고 (+), \geq 일떄는 새로운 값의 value를 빼고 (-)

Convert inequality constraints to equality constraints by adding distinct, nonnegative, slack variables in every \leq inequality and subtracting such slack variables in every \geq inequality

2. nonpositive variable를 없애기 위해, 새로운 variable로 대채한다.

Eliminate nonpositive variables by substituting new variables equal to their negatives

3. unrestricted variables 를 없애기 위해, 다른 두개의 non-negative variables로 대채한다.

Eliminate unrestricted variables by substituting the difference of two new nonnegative variables

Example of Conversion from LP problem to LP standard Form

For example:

The Importance of Dual Solution

The optimal dual variables p* (Shadow Price) can provide intuitive interpretation (직감적 설명), namely:

- · penalty of breaking a constraint
- · marginal cost
- · fair prices

Excel Solver

Sensitivity Report

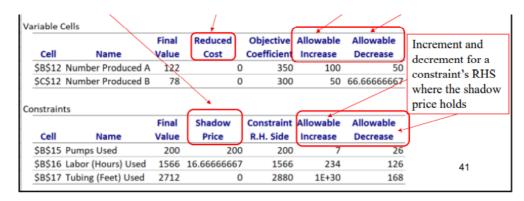
Reduced Cost: The increase in the optimal objective function value per unit increase in the constraint on the decision variables

Reduced Cost - Allowable Increase / Decrease : Increments and decrements allowed for objective coefficients (in this example unit profits) where the solved optimal values hold

Shadow Price: The increase in the optimal objective function value per unit increase in the right hand side of the constraints.

Shadow Price - Allowable Increase / Decrease: Increment and decrement for a constraint's RHS where the shadow price holds.

To Understand Sensitivity Report



Variable Cells

- Final Value : 최적값 나온거..
 - o Solver 돌려서 122, 78이 나왔습니다. A는 122개 생산, B는 78개 생산이 최고입니다.
- Reduced Cost : 손해, 이익이라 생각할수있는데, 예를들어서 reduce cost 가 -2가 나오면 1개의 생산을 할때마다, 2불의 손해를 보고 생산합니다.
- Objective Coefficient : A의 Profit은 350불입니다. B의 Profit은 300불입니다.
- Allowable Increase : 350불에서 100불을 더한값인 450불까지올라도 최적값은 변하지 않습니다.
- Allowable Decrease: 350불에서 50불을 뺀 300불까지 내려가도 최적값은 변하지 않습니다.

Constraints

- Final Value : variable 의 최적값에 따른 constraint의 값입니다. 즉
 - o pump: 200개 사용했습니다. (참고: Constraint 최대값이 200이였음)
 - Labor Used: 1566시간 했습니다 (Constraint 최대값 1566)
 - o Tubing Used: 2712 길이를 사용했습니다. (Constraint 최대값 2712)
- Shadow Price (잠재 가격 / 기대 수익):
 - pump : 펌프 한개 사용의 잠재 가격은 200입니다. 즉 이것보다 비싸게 사면 손해..
 - o labor used : 인건비는 16.667입니다.
 - tubing used :
- Constraint R.H.Side 제한조건: 200개까지 사용이 가능합니다.
- · Allowable Increase :
 - o pump: 200개 사용이 가능한데, 여기서 207개 까지 사용해도 최적값이 변하지않고
- · Allowable Decrease :
 - o pmup: 200개 뺴기 26 174개의 펌프 사용해도 최적값은 변하지 않습니다.

Why Sensitivity Analysis of Results?

The curse of Optimization: "Being perfectly wrong or approximately correct"

Model parameters (한도) are at best estimated of what might happen in reality

There is uncertainty in demand, resource requirements, prices, profit, margins

Therefore, We Want to understand how sensitive

the value of the objective function is to the changes in input parameters

the optimal decision is to the changes in input parameters

Why can't we just solve the problem many times?

Takes too long

- Sensitivity analysis gives bounds for the parameters where the result hold rather than just solving for a single
 instance of the problem.
 - sensitivity analysis는 경계의 제한치를 줘서, 결과가 뒤죽박죽이지 않게 해준다.

Limit Report



Lower Limit: is the smallest value that a variable can take while satisfying the constraints and holding all of the other variables constant

Upper Limit: the largest value that variable can take under these circumstance.

Scaling Issues in Excel's Solver

When model is **Well-Scaled** : similar magnitude (= orders of magnitude 자릿수)

constant term in the constraints are 1~1000, and objective function coefficient is between 0.00001~0.0000001 it is **ill-scaled**.

If it is ill-scaled,

memory storage accuracy may force the computer to use approximation of the actual numbers that may be inaccurate.

E.g: 예시

각 숫자를 최대한 공통의 수로 만들고, 최대한 0 (숫자 0)을 줄여야한다.

Let's say that the objective function coefficients for some model are in \$'s and range between \$25,000,000 and \$100,000,000, RHS values reflect various resource availabilities and vary between 500 and 5000, and constraint coefficients represent unit resource consumptions and vary between 10 and 250

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What is Multiobjective Optimization

Occurs when we have to make tradeoffs(거래,교환) among conflicting objectives

Objective 1: Profit	\$18.67	→Maximize	Objective 1 results \$18.67	Objective 2 results \$11.90	Objective 3 results \$11.90	Note that minimizing either the 2nd or 3rd objective results in the same values for the three objective.			
Objective 2: Capital-Adequacy	0.94	→Minimize	0.94	0.61	0.61	,			
Objective 3: Risk Assets	7.10	→Minimize	7.10	5.00	5.00				

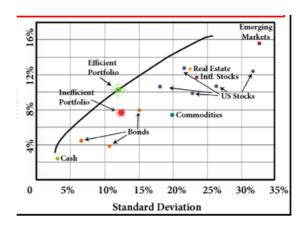
Above Image is the example of 3 Object Model —> Create equation for Objective of profit.

and equtions for objective 2 and 3. choose object 1 to solve and copy the result on the right —> Do same thing as object 2 and 3.

Pareto Optimal

- 💡 한정된 자원이 가장 효율적으로 배분된 상태
- 먼저 생산의 효율에 대해서는 어떤 한 재화의 생산량을 증가시키기 위해서는 다른 재화의 생산량을 감소 시키지 않으면 안 된다는 것
- 교환의 효율에 대해서는 한사람의 효용을 증가시키기 위해 다른 소비자의 효용을 감소시키지 않으면 안된다는것이 파레토 효율 또는 파레토 최적의 기본 전제이다.

Efficient frontier of multi-objective optimization model is the set of all efficient points for the model.



저기있는 검은색 라인이 efficient frontier 이고 efficient point는 저기있는 efficient portfolio 같은 하나의 점이다.

Example, Three Bank

다른 2개의 objectives를 constraints으로 만들어서 solver를 돌린다.

Preemptive Optimization

one of multiobjective optimization

Pareto-optimal is efficient point for multiobjective model.

첫번째 Goal을 달성하고 그다음 Goal을 달성한다.

Example, Three Bank

일단 우선순위를 정한다. 1. min illiquid risk asset 2. max profit 3. min capital adequacy ratio

Use solver: for 1st one (min illiquid risk asset

the result came out

put it into constraitns for second one.

결과 나오면 3번재 object 풀때, constarint으로 넣는다.

Objective 1: Profit	\$17.21	→Maximize					
Objective 2: Capital-Adequacy	0.89	→Minimize					
Objective 3: Risk Assets	5.00	→Minimize					
Objective 3: Risk Assets	5.00	→Minimize					
	Optimal solution	on:					
	Invesment						
	1	\$100.00					
	2	\$12.50 \$12.50					
	3						
	4	\$12.50					
	5	\$12.50					
	6	\$12.50					
	7	\$12.50					
	8	\$75.00					
	Value for objectives:						
	1	\$11.90					
	2	0.61					
	3	5.00					
Objective 1: Profit	¢17.01	→Maximize					
Objective 1. Front	\$17.21	→ividXIITIIZE					
	Added constraint to retain objective 3 at its optimal value:						
	5.00	<=	5.00				

Goal Programming

specify set up the level of goals (objective)

Goal Programming is a solution in which goal are achieved may not be efficient.

To fix problem: add small positive(negative) multiplier of each of the original minimization (maximization) objective functions.

Deficiency Variables

Let,

 d_1^- = amount profit *falls short of* its goal

 d_2^+ = amount capital-adequacy ratio **exceeds** its goal

 d_3^+ = amount risk-asset ratio **exceeds** its goal

The three goals can then be written as:

(1) Profit goal:

$$0.040x_2 + 0.045x_3 + 0.055x_4 + 0.070x_5 + 0.105x_6 + 0.085x_7 + 0.092x_8 + d_1 \ge 18.5$$



NOTE:

 d_i^+ and d_i^- .

An objective (i) that

a goal will need two

deficiency variables:

requires exactly meeting

(2) Capital-adequacy ratio goal:

$$\frac{1}{20} \left(0.005x_2 + 0.040x_3 + 0.050x_4 + 0.075x_5 + 0.100x_6 + 0.100x_7 + 0.100x_8 \right) - d_2^{\frac{1}{2}} \le 0.8$$

(3) Illiquid risk assets/capital ratio goal:

$$\frac{1}{20}(x_6 + x_7 + x_8) \left(d_3^+\right) \le 7.0$$

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deficiency variables를 만든후, need make it objective

Objective

$$\min d_1^- + d_2^+ + d_3^+ \longrightarrow$$

 $\min d_1^- + d_2^+ + d_3^+ \longrightarrow$ Minimize the sum of the deficiency variables to try to meet all three goals

If weights can be assessed for the relative importance of not meeting the three goals, then a weighted objective function can be used:

$$\min w_1^- d_1^- + w_2^+ d_2^+ + w_2^+ d_3^+$$

where,

 w_1^- – penalty per unit violation of goal 1

 w_2^+ = penalty per unit violation of goal 2

 w_3^+ = penalty per unit violation of goal 3

Goal Programming Formulation 3/3

Complete Formulation

$$\min d_1^- + d_2^+ + d_3^+$$

Subject to:

$$0.040x_2 + 0.045x_3 + 0.055x_4 + 0.070x_5 + 0.105x_6 + 0.085x_7 + 0.092x_8 + d_1^- \ge 18.5$$

$$\frac{1}{20} \left(0.005x_2 + 0.040x_3 + 0.050x_4 + 0.075x_5 + 0.100x_6 + 0.100x_7 + 0.100x_8 \right) - d_2^+ \le 0.8$$

$$\frac{1}{20} \left(x_6 + x_7 + x_8 \right) - d_3^+ \le 7.0$$

$$x_1 + x_2 + x_3 + x_4 + x_5 + x_6 + x_7 + x_8 = 20 + 150 + 80$$

$$x_1 \ge 0.14(150) + 0.04(80)$$

$$1.00x_1 + 0.995x_2 + 0.960x_3 + 0.900x_4 + 0.850x_5 \ge 0.47(150) + 0.36(80)$$

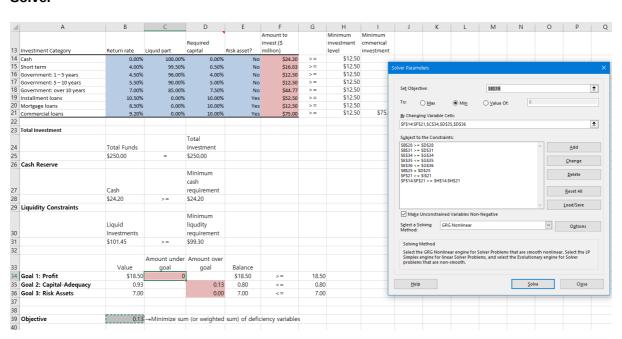
$$x_i \ge 0.05(20+150+80)$$
 for all $j = 1,...,8$

$$x_8 \ge 0.30(20+150+80)$$

$$x_1,...,x_8,d_1^-,d_2^+,d_3^+ \ge 0$$

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Solver



Goal Programming vs preemptive optimization

Goal Programming은 Goal을 달성하기위해 구축을한다 objectives to be optimized 보다 중요하다.

Preemptive optimization은 중요도에 따라 Goal 을 한개씩 생각한다. one at a time

Preemptive Goal Programming

First goal (profit ≥18.5):

- Solve for: min d_1^-
- The solution is: $d_1^- = 0$
- · This implies that the profit goal can be achieved

Second goal "capital-adequacy ratio" ≤0.8:

- Solve for: min d⁺₂
- Add constraint on 1st goal's deficiency variable: $d_1 \le 0$
- The solution is: $d_2^+ = 0.12$
- This implies that the capital-adequacy ratio is violated by 0.12

Third goal "risk-asset ratio ≤7:

- Solve for: min d⁺₃
- Add constraints on 1st and 2nd goals' deficiency variables: $d_1 \le 0$, $d_2 \le 0.12$
- The solution is: $d_3^+ = 0.14$
- This implies that the risk-asset ratio is violated by 0.14

Solution

The optimal solution will now be:

$$x_1^* = 24.20, x_2^* = 19.37, x_3^* = 12.50, x_4^* = 12.53$$

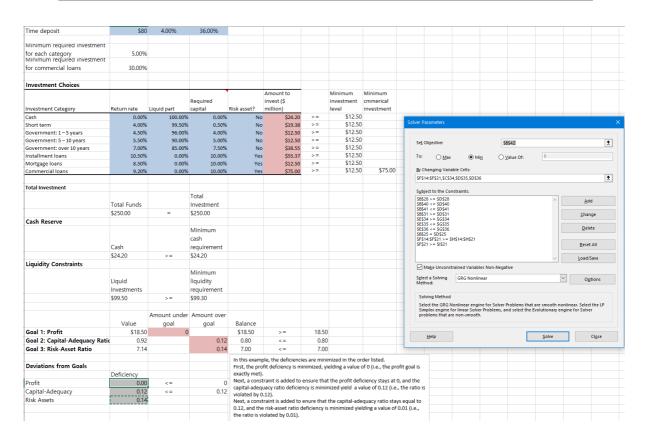
$$x_5^* = 38.52, x_6^* = 55.38, x_7^* = 12.50, x_8^* = 75.00$$

The corresponding values for the three goals are: Goal 1 (Profit) = \$18.5 million

Goal 2 (Capital Adequacy Ratio) = 0.92

Goal 3 (Risk-Asset Ratio) = 7.14

See "Multiobjective Optimization.xlsx" and "Preemptive Goal Programming" tab.



Weighted-Sum of Objective Approach

similar with Goal Programming

Multiple functions are combined into a single objective function by applying weights to the individual objectives.

Only an efficient point can be optimal

Assessing weight

- · The Swing Method
- The analytics hierarchy Process
- · Utility Function

Networks

Networks in Real life

Transporation of physical goods

Communication networks

Electricity and water netwroks

read railroad airline networks

sicial networks

biological networks

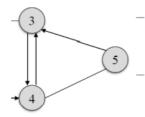
Terminlogoy

Graph: to model travel, flow and adjacency () patterns

nodes or verticies: entities (), intersections and points of transfer

flows or movement: nodes that connected by flows

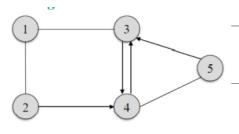
arc: linked directed (one way)



 For an arc, the direction of flow matters; e.g., arc (3, 4) is not the same as arc (4, 3).

For an edge, such as (1, 3) the relationship between the two nodes is *independent* of direction.

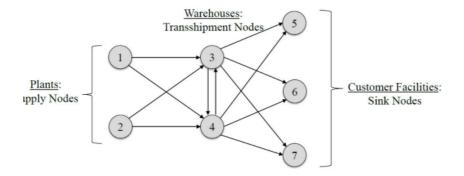
Edge: linked undirected (two way)



For an arc, the direction of flow matters; e.g., arc (3, 4) is not the same as arc (4, 3).

For an edge, such as (1, 3) the relationship between the two nodes is *independent* of direction.

Network Flow models: graphs with only directed graphs



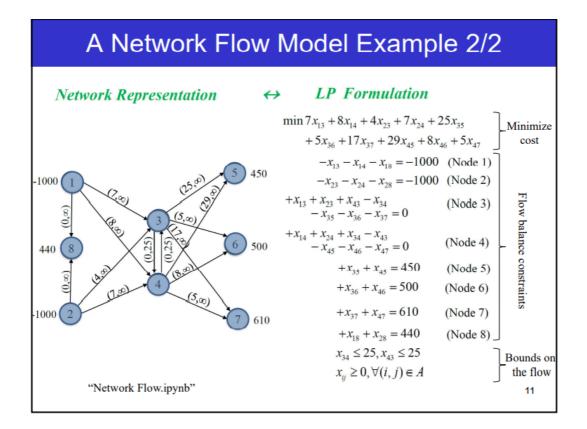
source or supply node : create flow sink or demand node : consume flow transshipment node : pass along flow

Network Flow model Example

• Unit cost and capacity indicated next to each other arc as (cij,uij)

• Source Node have their maximum supply amount next to them

• Sink Node have their demand amount next to them



Most network flow models can be formulated and solved as Linear Programming using simplex algorithm minimum network flow model can be solved LP **WHEN** 1. supplies, 2. demand, 3. capacities are all integer valued