Optimization I

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Anomalies in LP Models

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Anomalies in LP Models

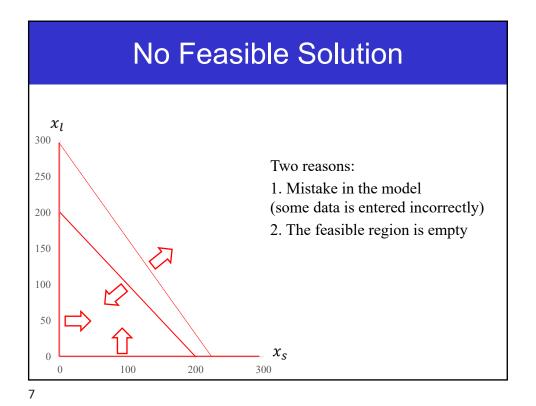
- · Redundant constraints
- · Alternate optimal solutions
- Unbounded solutions
- · No feasible solution

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Let's assume a new constraint (on red) is added. What is its impact?

Alternate Optimal Solutions x_l Objective function isocost line: $450x_s + 300x_l = 78,300$ x_s

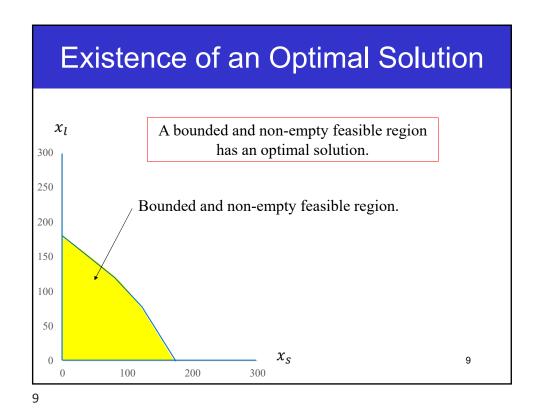
Unbounded Solutions
Unboundedness occurs when the objective function can improve indefinitely by varying one or more variables
Should not occur in realistic models, "real-life" constraints should prevent this
If unboundedness occurs, either wrong input data was entered or a relevant constraint was omitted



Logic Behind Simplex Algorithm

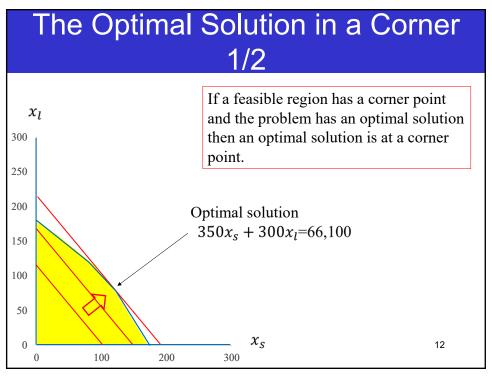
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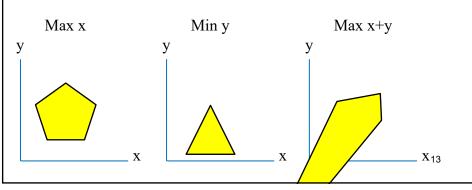
The Feasible Region in an LP The feasible region in an LP is always convex. x_l A set S is convex when a line segment, 300 of any two points belonging to the set, Feasible region 250 belongs also to the set, i.e., if $p_1, p_2 \in S$ is convex then $\lambda p_1 + (1 - \lambda)p_2 \in S$ for $\lambda \in [0,1]$. 200 150 100 50 x_s 0 10 100 300

Corner Points Are only Defined for Convex Sets x_l A corner point is a point in the feasible region that is not the mid point of any other two points in the feasible region. Corner points of the feasible region x_s



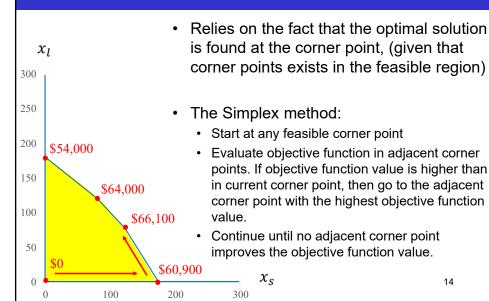
The Optimal Solution in a Corner

If a feasible region has a corner point and the problem has an optimal solution then an optimal solution is at a corner point.



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The Simplex Method



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The Simplex Method

- Was developed in 1947 by George Dantzig

- · It is still widely used
- Identifies if the LP is infeasible, finds the optimal solution if such exists, and checks for unboundedness
- · Very fast for solving large practical problems

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LP Problem Manipulations

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Equivalence of Minimization and Maximization Problems

$$\min 2x$$
 is equivalent to $\max ax \ge b$

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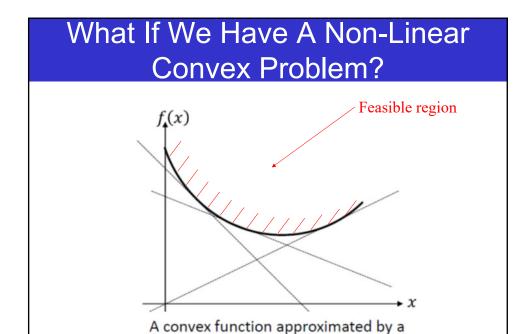
Linearizing Problems with Absolute Values

 Absolute value in a minimization (maximization) objective function with positive (negative) coefficients for decision variables:

$$\begin{array}{ccc}
\min 2|x| & & & \min \\
ax \ge b & & ax \ge b
\end{array}$$

• Absolute value in an inequality constraint:

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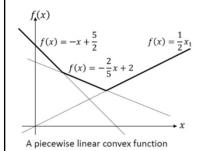


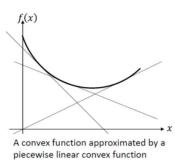
Linearized Version of the Problem

piecewise linear convex function

The minimization of a max of piecewise linear convex function:

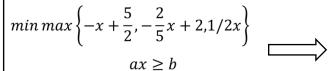
$$min \max \left\{ -x + \frac{5}{2}, -\frac{2}{5}x + 2, 1/2x \right\}$$
$$ax \ge b$$

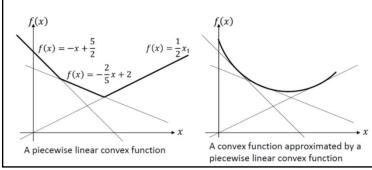




Linearizing Minmax Problems

The minimization of a max of piecewise linear convex function:





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Similarly Linearizing Maxmin Problems

The maximization of a min of piecewise linear concave function:

$$\max \min \left\{ x, 1, -\frac{1}{4}x + 5 \right\} \qquad \qquad \max z \\ ax \ge b$$

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Linearizing Ratio Constraints

Duality in Linear Programming

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LP in Standard Form, Vector Notation

· LP standard form:

subject to
$$\begin{aligned} & \min(or \ max) \ c^T x \\ & Ax = b & A \in \mathbb{R}^{m \times n} \\ & x \ge 0 & x \in \mathbb{R}^n \end{aligned}$$

Define:

$$\mathbf{x} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$$
 $(n,1)$ vector of decision variables $\mathbf{c} = \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{pmatrix}$ $(n,1)$ vector of objective function coefficients

$$\mathbf{A} = \begin{pmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \cdots & a_{mn} \end{pmatrix} \qquad \begin{array}{c} \text{(m,n) matrix of} \\ \text{coefficients for} \\ \text{constraints} \end{array} \qquad \mathbf{b} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{pmatrix} \qquad \begin{array}{c} \text{(m,1) vector of} \\ \text{coefficients for} \\ \text{constraints' right hand} \\ \text{side} \end{array}$$

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LP in Standard Form

• Any LP problem can be converted to the standard form:

subject to
$$\begin{aligned} & \min(or \ max) \ c^T x \\ & Ax = b & A \in \mathbb{R}^{m \times n} \\ & x \ge 0 & x \in \mathbb{R}^n \end{aligned}$$

- The tricks to do the conversion are as follows:
 - 1. Convert inequality constraints to equality constraints by adding distinct, nonnegative, slack variables in every ≤ inequality and subtracting such slack variables in every ≥ inequality
 - · 2. Eliminate nonpositive variables by substituting new variables equal to their negatives
 - 3. Eliminate unrestricted variables by substituting the difference of two new nonnegative variables

For example:

$$\begin{array}{c} min2x_1 - 3x_2 \\ 3x_1 + 4x_2 \le 4 \\ 2x_1 + x_2 \ge 1 \\ x_1 \ge 0, x_2 \le 0 \end{array}$$

Derivation of Dual Problem 1/3

• Let's start with the LP in the standard form and call this primal (P)

(P)
$$z = minc^{T}x$$

subject to $Ax = b$ $A \in \mathbb{R}^{m \times n}$
 $x \ge 0$ $x \in \mathbb{R}^{n}$

• We define a relaxed problem $P(\mathbf{p})$ where the constraints can be violated at a fixed cost or price p_i

$$z(p) = minc^{T}x + p^{T}(b - Ax)$$
subject to
$$x \ge 0 \quad x \in \mathbb{R}^{n}$$

$$p_{1}(b_{1} - a_{1}x) + \dots + p_{m}(b_{m} - a_{m}x)$$

Note that $z(p) \le z$ for any p. This is because $b - Ax^* = 0$ for x^* that is optimal for P and otherwise b - Ax < 0.

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Derivation of Dual Problem 2/3

- Therefore, z(p) is the lower bound on the optimal value of P
- A price vector p^* such that $z(p^*)=z$ is equivalent of solving the dual problem (D)

(D)
$$\max_{\boldsymbol{p} \in \mathbb{R}^m} [z(\boldsymbol{p})] \qquad \longleftrightarrow \quad \max_{\boldsymbol{p} \in \mathbb{R}^m} \left[\min_{\boldsymbol{x} \geq \boldsymbol{0}} \boldsymbol{c}^T \boldsymbol{x} + \boldsymbol{P}^T (\boldsymbol{b} - \boldsymbol{A}\boldsymbol{x}) \right]$$

- The objective of the dual problem (D) is to find a vector \mathbf{p} of prices that makes violating the constraints of P as inconvenient as possible
- The dual problem (D) is not linear but it can be reformulated as such

Derivation of Dual Problem 3/3

• We can rewrite $\max_{\boldsymbol{p} \in \mathbb{R}^m} \left[\min_{\boldsymbol{x} \geq \boldsymbol{0}} \boldsymbol{c}^T \boldsymbol{x} + \boldsymbol{P}^T (\boldsymbol{b} - \boldsymbol{A}\boldsymbol{x}) \right]$ as follows

$$\max_{\boldsymbol{p} \in \mathbb{R}^{m}} \left\{ \boldsymbol{p}^{T} \boldsymbol{b} + \left[\min_{\boldsymbol{x} \geq \boldsymbol{0}} (\boldsymbol{c}^{T} - \boldsymbol{p}^{T} \boldsymbol{A}) \boldsymbol{x} \right] \right\}$$

$$\max_{\boldsymbol{p} \in \mathbb{R}^{m}} \left[\boldsymbol{p}^{T} \boldsymbol{b} + \begin{cases} 0 & \text{if } \boldsymbol{c}^{T} - \boldsymbol{p}^{T} \boldsymbol{A} \geq 0 \\ -\infty & \text{otherwise} \end{cases} \right]$$

• Since, the objective function is a maximization, the constraint $c^T - p^T A \ge 0$ is optimal to impose, resulting in

subject to
$$\mathbf{c}^T - \mathbf{p}^T \mathbf{A} \ge 0$$
 (D) $\max \mathbf{p}^T \mathbf{b}$ subject to $\mathbf{c}^T - \mathbf{p}^T \mathbf{A} \ge 0$ $\mathbf{p} \in \mathbb{R}^m$

- The dual (D) is now a linear programming problem
- The components of \boldsymbol{p} are dual variables

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The Importance of Dual Solution

- The optimal dual variables p^* (aka shadow prices) can provide intuitive interpretations, namely:
 - · Penalty of breaking a constraint
 - Marginal cost
 - Fair prices

Formulating and Solving LP Models

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To Start Consider Using Excel's Solver

- · It is provided by Frontline Systems
- It is a good choice for a smaller problem as Excel is commonly available in any workplace
- However,
 - the problems that Solver can deal with are limited by their size up to 200 variables and 200 constraints
 - Also, Solver does not perform very well on challenging mathematical programming problems
- To improve the Solver's performance, it is possible to purchase a license to Frontline System's Solver (removes the size limitations and allows to invoke Gurobi solver, which is an industrial scale solver)

Guidelines for Formulating Optimization Models in Excel

- 1. Organize the data for the model in the spreadsheet.
- 2. Reserve separate cells in the spreadsheet for each decision variable in the model.
- 3. Create a formula in a cell in the spreadsheet that corresponds to the objective function.
- 4. For each constraint, create a formula in a separate cell in the spreadsheet that corresponds to the left-hand side (LHS) of the constraint.

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How Solver Views the Model

- Target cell The cell in the spreadsheet that represents the objective function
- Changing cells The cells in the spreadsheet representing the decision variables
- Constraint cells The cells in the spreadsheet representing the LHS formulae for the constraints

Example Excel Formulation 1/2

Decision variables:

 x_s =number of standard hot tubs to produce x_l =number of luxury hot tubs to produce

Objective function:

$$Max 350x_s + 300x_l$$

Constraints:

pumps: $x_s + x_l \le 200$ labor: $9x_s + 6x_l \le 1566$ tubing: $12x_s + 16x_l \le 2880$

non-negativity: $x_s \ge 0$

 $x_l \ge 0$

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Example Excel Formulation 2/2 Product Mix Model - Hot Tubs Resources Required (per Tub) **Tub Type** В Pumps Labor (Hours) 9 6 Tubing (Feet) 12 16 Unit Profit \$350 \$300 **Production Mix Decisions Hot Tub Type** В **Number Produced** 0 Available **Resource Constraints** Used Pumps 200 **NOTE**: The <= text entries are Labor (Hours) 1,566 not required. They are added to Tubing (Feet) 2,880 enhance readability. Financial Summary Hot Tub Type Total Profit \$0.00 \$0.00 \$0.00 36 "Product Mix – Hot Tubs.xlsx"

Importance of Standalone Commercial Solvers

- Excel even with Gurobi solver is not capable to efficiently deal with largescale optimization problems (faced in big data problems):
 - The size of the data can make it inefficient (or impossible) to import and manipulate the problem in Excel
 - Fast enough updating of data in Excel may not be possible for dynamic problems
 - Custom algorithms may be required to efficiently solve complex optimization models (e.g., multi-objective, challenging integer, non-linear, or stochastic programming models)
 - Efficient processing of data to generate the model and the output report might not be possible in Excel and requires the use of a programming language, e.g., Python or Java
- Therefore, after solving the first few examples with Solver, we will formulate and solve mathematical programming models using Python and Gurobi!

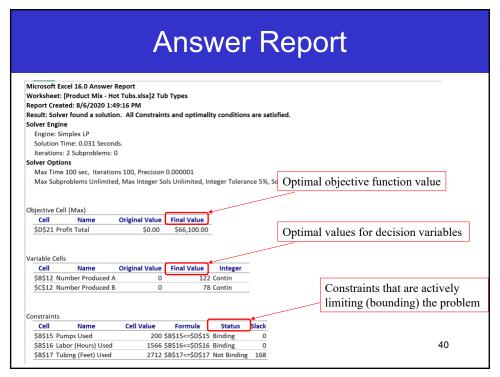
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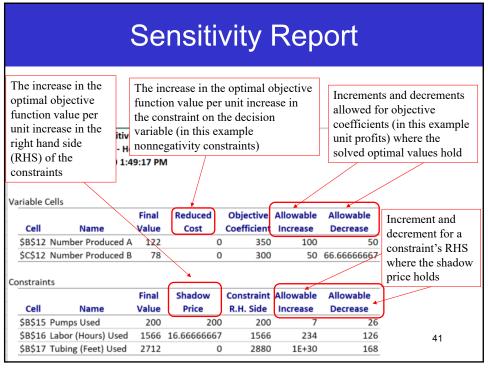
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Interpreting the Results of Excel's Solver

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Product Mix Model - Hot Tubs							
Todace Wilk Woder - Hot Tubs							
Resources Required (per Tub)							
Гub Туре	Α	В					
Pumps	1	1					
abor (Hours)	9	6					
Tubing (Feet)	12	16					
Jnit Profit	\$350	\$300					
Production Mix Decisions							
Hot Tub Type	Α	В					
Number Produced	0	0					
Resource Constraints	Used		Available				
Pumps	0	<=	200	NO	NOTE: The <= text entries are		
abor (Hours)	0	<=	1,566	not required. They are added to enhance readability.			
Tubing (Feet)	0	<=	2,880				
Financial Summary							
Hot Tub Type	Α	В	Total				
Profit	\$0.00	\$0.00	\$0.00				

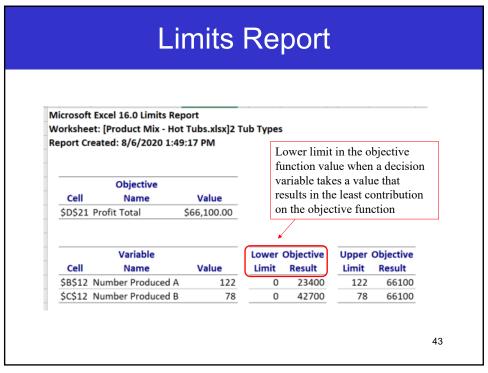




Why Sensitivity Analysis of Results?

- The curse of optimization: "Being perfectly wrong or approximately correct"
- Model parameters are at best estimates of what might happen in reality (e.g., there is uncertainty in demand, resource requirements, prices, profit margins)
- Therefore, we want to understand how sensitive
 - · (i) the value of the objective function is to the changes in input parameters and
 - (ii) the optimal decision is to the changes in input parameters
- Why can't we just solve the problem many times?
 - Takes too long time for large problems
 - Also, the sensitivity analysis (or sensitivity report) gives bounds for the
 parameters where the results hold rather than just solving for a single instance of
 the problem

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Scaling Issues in Excel's Solver

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Scaling Issues 1/3

- For a model to be well-scaled, the constant terms in the model should be of "similar magnitude":
 - Terms should not be different by many "orders of magnitude"
 - E.g. if all the constant terms in the constraints are between 1 and 1,000, but the objective function coefficients are between 0.000001 and 0.000000001, then the model is *ill-scaled*
- As the solution algorithm runs, intermediate calculations are made that make coefficients larger or smaller.
- If a problem is ill-scaled, memory storage accuracy may force the computer to use approximations of the actual numbers (round-off errors) that may be inaccurate.

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Scaling Issues 2/3

- Most problems can be formulated in a way to minimize scaling errors through appropriate definition of the decision variables. E.g.,
 - Let's say that the objective function coefficients for some model are in \$'s and range between \$25,000,000 and \$100,000,000, RHS values reflect various resource availabilities and vary between 500 and 5000, and constraint coefficients represent unit resource consumptions and vary between 10 and 250.
 - Restating the objective function coefficients in \$ millions makes their range (25 to 100) much closer in magnitude to the rest of the coefficients thus making the model "well-scaled."

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Scaling Issues 3/3

- Scaling & Excel's solver:
- Scaling problems sometimes prevents Excel's solver from being able to solve the problem accurately.
 - · Solver may complain that the model is nonlinear.
 - This either means you have inadvertently added a nonlinearity, or the problem is ill-scaled.
- If necessary, you can also change the "Constraint Precision" level in Solver's Options dialog box (e.g., from 0.00001 to 0.0000001).

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Summary

- When solving an LP model, the outcome can be one of the following:
 - Unique optimal solution
 - · Alternate optimal solutions
 - · Unbounded solutions
 - There are no feasible solution
- Simplex is a powerful method to solve LP problems
- Many non-linear optimization problems can be linearized, e.g., when we have:
 - Absolute values
 - Minmax and Maxmin problems (that are created to approximate convex and concave non-linear functions)
 - Ratio constraints
- · Dual solution allows to obtain shadow prices to conduct sensitivity analysis
- Use Excel and solver for small problems and Python and Gurobi for large problems

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