

MA 232 HW #4

Younis Zahiri

#1)

$$\begin{bmatrix} 1 & -2 \\ 1 & -1 \\ 1 & 0 \\ 1 & 1 \\ 1 & 2 \end{bmatrix} \vec{x} = \begin{bmatrix} 4 \\ 2 \\ -1 \\ 0 \\ 0 \end{bmatrix} \rightarrow$$

$$A^T A \vec{x} = A^T \vec{b}$$

$$\begin{bmatrix} 5 & 0 \\ 0 & -10 \end{bmatrix} \vec{x} = \begin{bmatrix} 5 \\ 10 \end{bmatrix}$$

- I pledge my Honor, I have abided by the Student Honor Code

$$\rightarrow e = \vec{b} - A \vec{x}$$

\uparrow Actual - \uparrow predicted

$$\Rightarrow \begin{cases} C = 1 \\ D = -1 \end{cases}$$

$$= \begin{bmatrix} 4 \\ 2 \\ -1 \\ 0 \\ 0 \end{bmatrix} - \begin{bmatrix} 3 \\ 2 \\ 1 \\ 0 \\ -1 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ -2 \\ 0 \\ -1 \end{bmatrix} \leftarrow \sum_{i=1}^5 x_i = 0 \checkmark$$

#2) $\vec{a} = \begin{bmatrix} 1 \\ -1 \\ 0 \\ 0 \end{bmatrix} \rightarrow A = \hat{\vec{a}} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \\ 0 \\ 0 \end{bmatrix} =$

$$\vec{b} = \begin{bmatrix} 0 \\ +1 \\ -1 \\ 0 \end{bmatrix} \rightarrow B = (\vec{b} - \text{proj}_{\hat{\vec{a}}} \vec{b}) = \begin{bmatrix} 0 \\ -1 \\ -1 \\ 0 \end{bmatrix} - (\vec{b} \cdot \hat{\vec{a}}) \hat{\vec{a}}$$

$$C = \begin{bmatrix} 0 \\ 0 \\ 1 \\ -1 \end{bmatrix} \Rightarrow C = \vec{c} - \text{proj}_{\hat{\vec{a}}} \vec{b} - \text{proj}_{\hat{\vec{b}}} \vec{c}$$

$$= \begin{bmatrix} 0 \\ 1 \\ -1 \\ 0 \end{bmatrix} - \frac{(-1)}{2} \begin{bmatrix} 1 \\ -1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1/2 \\ 1/2 \\ -1 \\ 0 \end{bmatrix}$$

$$\Rightarrow \hat{\vec{b}} = \frac{\sqrt{2}}{\sqrt{3}} \begin{bmatrix} 1/2 \\ 1/2 \\ -1 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} 0 \\ 0 \\ 1 \\ -1 \end{bmatrix} - \begin{bmatrix} 1/2 \\ -1/2 \\ 0 \\ 0 \end{bmatrix} + \frac{2}{3} (+1) \begin{bmatrix} 1/2 \\ 1/2 \\ -1 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} -1/2 \\ 1/2 \\ 1 \\ -1 \end{bmatrix} + \begin{bmatrix} 1/3 \\ 1/3 \\ -2/3 \\ 0 \end{bmatrix} =$$

#3) Q_1 & Q_2 are orthonormal.

$$\Rightarrow Q_1^T Q_1 = I_n$$

$$Q_2^T Q_2 = I_n$$

Notice this implies

$$Q_2^T = Q_2^{-1} \Rightarrow Q_2^T \cdot Q_2 = Q_2 \cdot Q_2^T$$

$$\text{Thus, } Q_1^T Q_1 Q_2 Q_2^T = I_n$$

$$Q_1 Q_2 Q_2^T = Q_1$$

$$Q_1 Q_2 Q_2^T Q_1^T = I_n$$

$$Q_1 Q_2 (Q_1 Q_2)^T = I_n$$

$$\text{Thus } (Q_1 Q_2)^T = (Q_1 Q_2)^{-1} \Rightarrow Q_1 Q_2 \text{ is orthonormal.}$$

#4) Counter example: $A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$ \leftarrow All non invertible matrices have $\det = 0$

$$B = O_{2 \times 2}$$

$$C = O_{2 \times 2}$$

$$D = I_2$$

$$\Rightarrow \det \begin{vmatrix} 1 & 1 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{vmatrix} = \det (1(I_3) + (I_3)) = (1+1) = 2$$

$$\text{But } \det(A) = 0 \Rightarrow \det(A) \det(D) - \det(B) \det(C) = 0 \neq 2$$

Thus Contradiction.

#5)

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 2 \\ 1 & 2 & 3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 1 & 2 \end{bmatrix} \begin{matrix} R_1 \\ R_2 - R_1 \\ R_3 - R_1 \end{matrix} \rightarrow \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{matrix} R_1 \\ R_2 \\ R_3 - R_2 \end{matrix} = U$$

$$\Rightarrow \boxed{\det(A) = 1 = 1 \cdot 1 \cdot 1 = 1}$$