

Hw #6 MA 232 ~

For Eigen - "to play my game by
have asked by the

#1)
$$\begin{bmatrix} 1 & -2 & 4 \\ 1 & -1 & 1 \\ 1 & 0 & 0 \\ 1 & 1 & 1 \\ 1 & 2 & -1 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} \Rightarrow A\vec{x} = \vec{b} \Rightarrow A^T \cdot A\vec{x} = A^T \vec{b}$$
 Solving for system

$$\begin{bmatrix} 1 & 1 & 1 & 1 & 1 \\ -2 & -1 & 0 & 1 & 2 \\ 4 & 1 & 0 & 1 & 4 \end{bmatrix} \begin{bmatrix} 1 & -2 & 4 \\ 1 & -1 & 1 \\ 1 & 0 & 0 \\ 1 & 1 & 1 \\ 1 & 2 & -1 \end{bmatrix} \vec{x} = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 5 & 0 & 5 \\ 0 & 10 & 0 \\ 10 & 0 & 34 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 5 & 0 & 5 & | & 1 \\ 0 & 1 & 0 & | & 0 \\ 0 & 0 & 24 & | & -2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 1 & | & 1/5 \\ 0 & 1 & 0 & | & 0 \\ 0 & 0 & 1 & | & -1/12 \end{bmatrix} \rightarrow$$

$$\Rightarrow \begin{bmatrix} 1 & 0 & 0 & | & 17/60 \\ 0 & 1 & 0 & | & 0 \\ 0 & 0 & 1 & | & -1/12 \end{bmatrix} \quad C = 17/60, D = 0, E = -1/12$$

Check:

$$\text{error} = \vec{b} - A\vec{x}$$

Act. Pred.

$$= \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} - \begin{bmatrix} -3/60 \\ 10/60 \\ 17/60 \\ 0/60 \\ -3/60 \end{bmatrix} = \begin{bmatrix} 3/60 \\ -10/60 \\ 17/60 \\ 0/60 \\ 3/60 \end{bmatrix} = \begin{bmatrix} 1/20 \\ -1/6 \\ 17/60 \\ 0 \\ 1/20 \end{bmatrix} = \begin{bmatrix} 5/12 \end{bmatrix}$$

$$\hat{q}_1 = \frac{1}{3} \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix}$$

$$\hat{q}_2 = \frac{C_2 - \hat{q}_1(C_2 \cdot \hat{q}_1)}{\|C_2 - \hat{q}_1(C_2 \cdot \hat{q}_1)\|}$$

$$= \frac{\begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix} - \frac{1}{3} \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix} \left(\begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix} \cdot \frac{1}{3} \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix} \right)}{\left\| \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix} - \frac{1}{3} \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix} \right\|}$$

$$= \frac{\begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix} - \frac{1}{3} \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix} (-9)}{\left\| \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix} - \frac{1}{3} \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix} \right\|}$$

$$= \frac{\begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix} + \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix}}{\left\| \begin{bmatrix} 2 \\ 2 \\ -4 \end{bmatrix} \right\|} = \frac{1}{3} \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}$$

#2) Step 1: For convenience, simplify A.

$$A = \begin{bmatrix} 1 & 1 \\ 2 & -1 \\ -2 & 4 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 \\ 0 & -3 \\ 0 & 6 \end{bmatrix} \begin{matrix} R_1 \\ R_2 - 2R_1 \\ R_3 + 2R_1 \end{matrix} \rightarrow \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{matrix} R_1 - R_2 / -3 \\ R_2 / -3 \\ R_3 + 2R_2 \end{matrix}$$

$$\Rightarrow q_1 \times q_2 = \begin{vmatrix} \hat{q}_1 & \hat{q}_2 & \hat{q}_3 \\ 1/3 & 1/3 & 1/3 \\ 1/3 & 1/3 & 1/3 \\ 1/3 & 1/3 & 1/3 \end{vmatrix} = \begin{bmatrix} 1/3 \\ 1/3 \\ -1/3 \end{bmatrix} = \hat{q}_3$$

$$\|\hat{q}_3\| = \sqrt{1/9 + 1/9 + 1/9} = 1$$

$$q_3 \cdot q_1 = \begin{bmatrix} 1/3 \\ 1/3 \\ -1/3 \end{bmatrix} \cdot \begin{bmatrix} 1/3 \\ 1/3 \\ 1/3 \end{bmatrix} = 0$$

$$q_3 \cdot q_2 = \begin{bmatrix} 1/3 \\ 1/3 \\ -1/3 \end{bmatrix} \cdot \begin{bmatrix} 1/3 \\ 1/3 \\ 2/3 \end{bmatrix} = 0$$

#1

#3) $U = \begin{bmatrix} 1 & 4 & 6 \\ 0 & 2 & 5 \\ 0 & 0 & 3 \end{bmatrix}$ Determinant gives scaling factor of Linear transformation.

$$|U| = 1 \cdot 2 \cdot 3 = 6 \leftarrow \text{Scale}$$

$$|U^{-1}| = 1 \cdot \frac{1}{2} \cdot \frac{1}{3} = \frac{1}{6} \leftarrow \text{Inverse scale}$$

$$|U^2| = 1 \cdot 2^2 \cdot 3^2 = 36 \leftarrow \text{Scale}^2$$

ii) $U = \begin{bmatrix} a & b \\ 0 & 0 \end{bmatrix}$

$$|U| = a \cdot b = ab$$

$$|U^{-1}| = \frac{1}{a} \cdot \frac{1}{b} = \frac{1}{ab}$$

$$|U^2| = a^2 \cdot b^2 = a^2 b^2 = (ab)^2$$

#4) Suppose A^{-1} DNE. (Assume A is square matrix, & B)

$$\rightarrow \det(A) = 0$$

$$\text{Since } \det(A \cdot B) = \det(A) \cdot \det(B)$$

$$\rightarrow \forall B, \det(A \cdot B) = \det(A) \cdot \det(B) = 0 \cdot \det(B) = 0$$

$$\rightarrow (AB)^{-1} \text{ does not exist.}$$

#5) $A = \begin{bmatrix} 5 & -6 & -6 \\ -1 & 4 & 2 \\ 3 & -6 & -4 \end{bmatrix} \begin{matrix} R_1 \\ R_2 \\ R_3 \end{matrix}$ $\det(A) = 5 \begin{vmatrix} 4 & 2 \\ -6 & -4 \end{vmatrix} + 1 \begin{vmatrix} -6 & -6 \\ -6 & -4 \end{vmatrix} + 3 \begin{vmatrix} -6 & -6 \\ 4 & 2 \end{vmatrix}$

$$= 5(-16 + 12) + (-12) + 3(12)$$
$$= 5(-4) - 12 + 36 = \boxed{4}$$

Thus A^{-1} exists. $\rightarrow A$ has dimension 3.

(#2)

$$A = \begin{bmatrix} -1 & 4 & 2 \\ 5 & -6 & -6 \\ 3 & -6 & -4 \end{bmatrix} \begin{matrix} R_2 \\ R_1 \\ R_3 \end{matrix} \rightarrow \begin{bmatrix} -1 & 4 & 2 \\ 0 & 14 & -2 \\ 0 & 6 & 2 \end{bmatrix} \begin{matrix} R_1 \\ R_2 - 5R_1 \\ R_3 - 3R_2 \end{matrix} \rightarrow \begin{bmatrix} -1 & 4 & 2 \\ 0 & 14 & -2 \\ 0 & 0 & 40/14 \end{bmatrix} \begin{matrix} R_1 \\ R_2 \\ R_3 - R_2 \cdot \frac{5}{14} \end{matrix}$$

Since every value in the values on the diagonal are unique, there will be 3 unique eigenvectors spanning the eigenbasis of $A \rightarrow A$ is diagonalizable.

#6) $A = \begin{bmatrix} -4 & 2 & 2 \\ 2 & -4 & 2 \\ 2 & 2 & -4 \end{bmatrix}$

Find eigenvectors:

$$\begin{aligned} \det(A - \lambda I) &= (4-\lambda) \begin{vmatrix} 4-\lambda & 2 \\ 2 & 4-\lambda \end{vmatrix} - 2 \begin{vmatrix} 2 & 2 \\ 2 & 4-\lambda \end{vmatrix} + 2 \begin{vmatrix} 2 & 2 \\ 4-\lambda & 2 \end{vmatrix} \\ &= (4-\lambda)((4-\lambda)^2 - 4) - 2(2(4-\lambda) - 4) + 2(4 - 2(4-\lambda)) \\ &= (4-\lambda)^3 - 4(4-\lambda) - 4(4-\lambda) + 8 + 8 - 4(4-\lambda) \\ &= (4-\lambda)^3 - 12(4-\lambda) + 16 \\ &= -\lambda^3 + 3 \cdot 4 \lambda^2 - 3 \cdot 4^2 \lambda + 64 - 48 + 12\lambda + 16 \\ &= -\lambda^3 + 12\lambda^2 - 36\lambda + 32 = 0 \\ &\rightarrow \lambda^3 - 12\lambda^2 + 36\lambda - 32 = 0 \\ &\quad (1-8) \quad (1^2 - 4\lambda + 4) = 0 \\ &\quad (1-8) \quad (1-2)^2 = 0 \\ &\lambda = 8, 2 \end{aligned}$$

$$\begin{array}{r|rrrr} 8 & 1 & -12 & 36 & -32 \\ & & 8 & -32 & 32 \\ \hline & 1 & -4 & 4 & 0 \end{array}$$

#6) $A = \begin{bmatrix} -4 & 2 & 2 \\ 2 & -4 & 2 \\ 2 & 2 & -4 \end{bmatrix} \rightarrow \det(A - \lambda I) =$

$$= (-4-\lambda) \begin{vmatrix} -4-\lambda & 2 \\ 2 & -4-\lambda \end{vmatrix} - 2 \begin{vmatrix} 2 & 2 \\ 2 & -4-\lambda \end{vmatrix} + 2 \begin{vmatrix} 2 & 2 \\ -4-\lambda & 2 \end{vmatrix}$$

$$= (-4-\lambda)((-4-\lambda)^2 - 4) - 2(-8 - 2\lambda - 4) + 2(4 - 2(-4-\lambda))$$

$$= -(4+\lambda)((\lambda^2 + 8\lambda + 16) - 4) + 16 + 4\lambda + 8 + 8 + 16 + 4\lambda$$

$$= -(4+\lambda)(\lambda^2 + 8\lambda + 12) + 48 + 8\lambda$$

$$= -((\lambda^3 + 8\lambda^2 + 12\lambda) + 4\lambda^2 + 32\lambda + 48) + 48 + 8\lambda$$

$$= -(\lambda^3 + 12\lambda^2 + 44\lambda + 48) + 48 + 8\lambda$$

$$= -\lambda^3 - 12\lambda^2 - 36\lambda = -\lambda(\lambda+6)^2 \rightarrow \lambda = 0, -6$$

$\lambda = -6$

$$\begin{bmatrix} 2 & 2 & 2 \\ 2 & 2 & 2 \\ 2 & 2 & 2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{matrix} x_1 = -x_2 - x_3 \\ x_2 = x_2 \\ x_3 = x_3 \end{matrix} \rightarrow N(A_{\lambda=-6}) = \left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \right\}$$

$\lambda = 0$

$$\begin{bmatrix} -4 & 2 & 2 \\ 2 & -4 & 2 \\ 2 & 2 & -4 \end{bmatrix} \rightarrow \begin{bmatrix} -2 & 1 & 1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{bmatrix} \xrightarrow{\substack{R_3 \\ R_2 \\ R_1}} \begin{bmatrix} 1 & 1 & -2 \\ 1 & -2 & 1 \\ -2 & 1 & 1 \end{bmatrix} \xrightarrow{\substack{R_1 \\ R_2 - R_1 \\ R_3 + 2R_1}} \begin{bmatrix} 1 & 1 & -2 \\ 0 & -3 & 3 \\ 0 & 3 & -3 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 1 & 1 & -2 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix} \xrightarrow{\substack{R_1 \\ R_2/3 \\ R_3 - 3R_2}} \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix} \rightarrow N(A_{\lambda=0}) = \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}$$

Orthonormalize

$$\frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} = \hat{v}_1 \rightarrow \hat{v}_2 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} - \text{proj}_{\hat{v}_1} \hat{v}_2 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} - \left(\begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \cdot \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} \right) \left(\frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} \right)$$

$$= \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} - \frac{1}{\sqrt{2}} \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} -\frac{1}{2} \\ 0 \\ \frac{1}{2} \end{bmatrix}$$

$$\hat{v}_2 = \frac{\sqrt{6}}{2} \begin{bmatrix} -\frac{1}{2} \\ 0 \\ \frac{1}{2} \end{bmatrix}$$

$$\hat{v}_3 = \frac{1}{\sqrt{3}} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

$$Q^{-1} A Q = D = Q^T A Q$$

$$Q = \begin{bmatrix} 1/\sqrt{2} & -\sqrt{6}/4 & 1/\sqrt{3} \\ -1/\sqrt{2} & -\sqrt{6}/4 & 1/\sqrt{3} \\ 0 & \sqrt{6}/2 & 1/\sqrt{3} \end{bmatrix}$$

$$\rightarrow 2 \begin{bmatrix} 1/\sqrt{2} & -1/\sqrt{2} & 0 \\ -\sqrt{6}/4 & -\sqrt{6}/4 & \sqrt{6}/2 \\ 1/\sqrt{3} & 1/\sqrt{3} & 1/\sqrt{3} \end{bmatrix} \begin{bmatrix} -2 & 1 & 1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{bmatrix} \begin{bmatrix} 1/\sqrt{2} & -\sqrt{6}/4 & 1/\sqrt{3} \\ -1/\sqrt{2} & -\sqrt{6}/4 & 1/\sqrt{3} \\ 0 & \sqrt{6}/2 & 1/\sqrt{3} \end{bmatrix}$$

$$= 2 \begin{bmatrix} -3/\sqrt{2} & 3/\sqrt{2} & 0 \\ 3\sqrt{6}/4 & 3\sqrt{6}/4 & -6\sqrt{6}/4 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1/\sqrt{2} & -\sqrt{6}/4 & 1/\sqrt{3} \\ -1/\sqrt{2} & -\sqrt{6}/4 & 1/\sqrt{3} \\ 0 & \sqrt{6}/2 & 1/\sqrt{3} \end{bmatrix}$$

$$= 2 \begin{bmatrix} -3 & 0 & 0 \\ 0 & -3 & 0 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow D = \begin{bmatrix} -6 & 0 & 0 \\ 0 & -6 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

#7) QOQ^T is possible when A is symmetric.

→ $b = 1$

ii) $A = SDS^{-1}$ is impossible if eigenbasis has smaller dimension than rank of A . The only way this can happen is if there exists a non-unique eigenvalue for a 2×2 .

→ $\begin{bmatrix} 2 & b \\ 1 & 0 \end{bmatrix} - I\lambda = (2-\lambda)(-\lambda) - b$ let $b = 1$
 $= \lambda^2 - 2\lambda - b = 0 \rightarrow$
 $(\lambda - 1)^2 = 0 \quad \lambda = 1 \text{ (x2)}$

→ $\left[\begin{array}{cc|c} 1 & -1 & 0 \\ 1 & -1 & 0 \end{array} \right] = \left[\begin{array}{cc|c} 1 & -1 & 0 \\ 0 & 0 & 0 \end{array} \right] \Rightarrow x_1 = x_2 \Rightarrow \vec{x} = \begin{Bmatrix} 1 \\ 1 \end{Bmatrix} < \dim(\lambda = 1)$
 → $b = -1$ makes this 2
 A nondiagonalizable.

iii) A^{-1} DNE if $\det(A) = 0 \rightarrow b = 0$

#8)*

$A = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & 2 \\ 0 & 2 & 8 \end{bmatrix} \rightarrow \begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 4 \end{bmatrix} \begin{matrix} R_1 \\ R_2 \\ R_3 - R_2 \cdot 2 \end{matrix}$

$D = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 4 \end{bmatrix}$

→ $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & 2 \\ 0 & 2 & 8 \end{bmatrix} = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 4 \end{bmatrix}$

→ $A = E^{-1} D (E^{-1})^T$ ← Since $A = A^T$

$E^{-1} = \begin{bmatrix} 1 & 0 & 0 & | & 1 & 0 & 0 \\ 0 & 1 & 0 & | & 0 & 1 & 0 \\ 0 & -2 & 1 & | & 0 & 0 & 1 \end{bmatrix}$

→ $A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 2 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 4 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix}$
 $E^{-1} \quad D \quad (E^{-1})^T$

$= \begin{bmatrix} 1 & 0 & 0 & | & 1 & 0 & 0 \\ 0 & 1 & 0 & | & 0 & 1 & 0 \\ 0 & 0 & 1 & | & 0 & 2 & 1 \end{bmatrix}$

$= (E^{-1} (\sqrt{D}) (\sqrt{D}) (E^{-1})^T)$

$= \left(\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 2 & 1 \end{bmatrix} \begin{bmatrix} \sqrt{2} & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix} \right) \left(\begin{bmatrix} \sqrt{2} & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix} \right)$

$= \begin{bmatrix} 3 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 2 & 2 \end{bmatrix} \cdot \begin{bmatrix} 3 & 0 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 2 \end{bmatrix} = C C^T$

#6