



Transferable End-to-End Aspect-based Sentiment Analysis with Selective Adversarial Learning

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- | Background & Motivation
 - ▶ E2E-ABSA
 - ▶ Transferable E2E-ABSA
- | Method
- | Experiments
- | Future Works



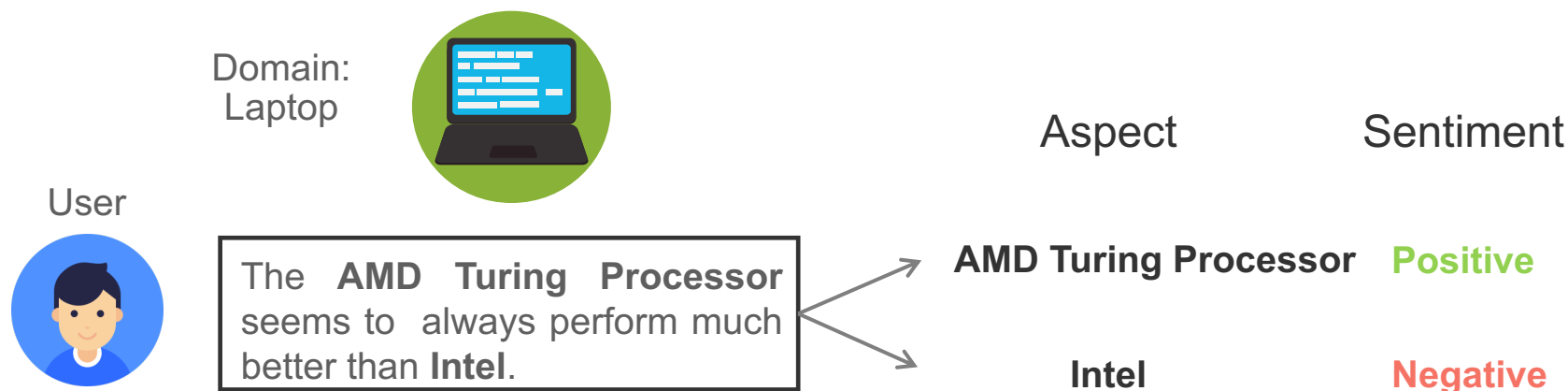
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End-to-End Aspect-based Sentiment Analysis

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E2E-ABSA: joint extraction of aspects and their sentiments from user reviews.



Two subtasks:

- Aspect detection (**AD**): extract the aspect terms from user reviews.
- Aspect sentiment (**AS**) classification: Given a review sentence and an aspect term, predict the sentiment towards the aspect.



Unified Formulation (single domain)

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Formulation: coupling two subtasks as a unified sequence labeling problem.

- **Unified tag** = **aspect boundary tag** {B, I, E, O, S} + **sentiment tag** {POS, NEG, NEU}
- **NER tag** = **entity boundary tag** {B, I, E, O, S} + **entity type tag** {PER, ORG, LOC, ...} (*Similar*)

Input	The	AMD	Turin	Processor	seems	to	always	perform	much	better	than	Intel	.
Joint	O	B	I	E	O	O	O	O	O	O	O	S	O
	O	POS	POS	POS	O	O	O	O	O	O	O	NEG	O
Unified	O	B-POS	I-POS	E-POS	O	O	O	O	O	O	O	S-NEG	O

Li et al., 2019 A unified model for opinion target extraction and target sentiment prediction AAAI

Pros:

- End-to-end manner
- Alleviate accumulated errors across two highly-correlative sub-tasks.

Cons:

- Lack of sufficient labeled data in a wide range of domains.
- Manual labeling for sequence data is expensive and time-consuming.



Transferable E2E-ABSA

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Source domain
(Train): Laptop



User



The [AMD Turing Processor]_POS seems to always perform much better than [Intel]_NEG.

Cross-domain:

- leverage knowledge from a labeled source domain to improve the **sequence learning** (unified tag prediction) in an unlabeled target domain.

User



Target domain:
(Test) : Restaurant



Great salmon but the waitress is so rude.

Aspect

Sentiment



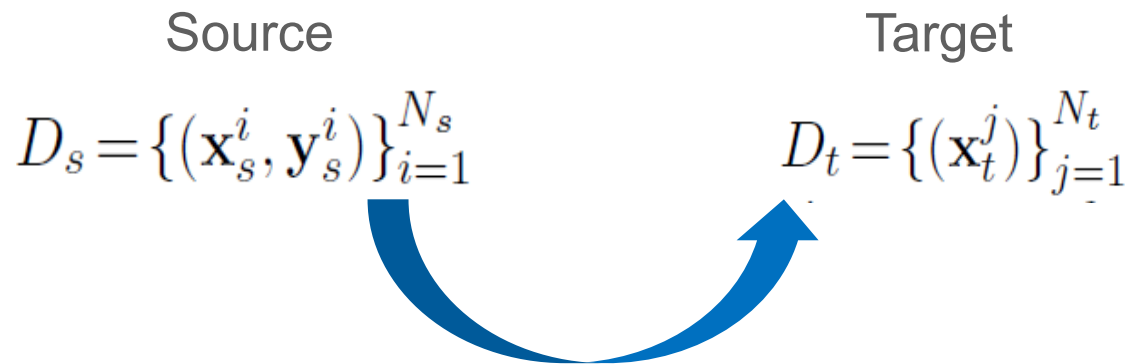


Unified Formulation (cross domain)

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Input: a sequence of words $\mathbf{x} = \{w_1, w_2, \dots, w_n\}$

Output: a unified tag sequence $\mathbf{y} = \{y_1, y_2, \dots, y_n\}$



Sequence Transfer Learning (unsupervised)



Challenges

What to transfer?

- There exists a **large domain shift** between domains since aspect terms in different domains are usually disjoint.
e.g., “salmon” in the Restaurant domain and “mouse” in the Laptop domain.

How to transfer?

- Unlike domain adaptation in traditional sentiment classification that learns shared sentence or document representations, we need to learn **fine-grained** (word-level) representations to be domain-invariant for **sequence prediction**.




What to transfer?

Prior work: highly depends on common syntactic relations between aspect and opinion words

- manually-designed rules
- external linguistic resources (dependency parsers)

RuleID	Rule	Example
R1	$O \xrightarrow{amod} T$	They have nice dessert. (nice \xrightarrow{amod} dessert)
R2	$T \xrightarrow{nsubj} O$	Its camera is great. (camera \xrightarrow{nsubj} great)
R3	$T \xrightarrow{dobj} O$	I love their fries. (fries \xrightarrow{dobj} love)
R4	$T \xrightarrow{nsubj} H \xleftarrow{amod} O$	iPhone is the best cellphone. (iPhone \xrightarrow{nsubj} phone \xleftarrow{amod} best)
ER1	$W \xrightarrow{amod} T$	I like Indian food. (Indian \xrightarrow{amod} food)
ER2	$W \xrightarrow{nn} T$	Their spring roll is great. (spring \xrightarrow{nn} roll)
ER3	$W_2 \xrightarrow{pobj} W_1 \xrightarrow{prep} T$	I like the design of iPhone. (iPhone \xrightarrow{pobj} of \xrightarrow{prep} design)



I love tuna sandwich very much.



I love the design of iPhone 7

Ding et al., 2017. Recurrent neural networks with auxiliary labels for cross-domain opinion target extraction. AAAI

Ours: automatically capture the latent relations among aspect and opinion words as transferable knowledge.



How to transfer?

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straightforward solution: apply domain adaption methods to align all words within the sentence. (**no significant improvements**).

Reason: Only a small number of words are informative words that are not tagged with “O”.

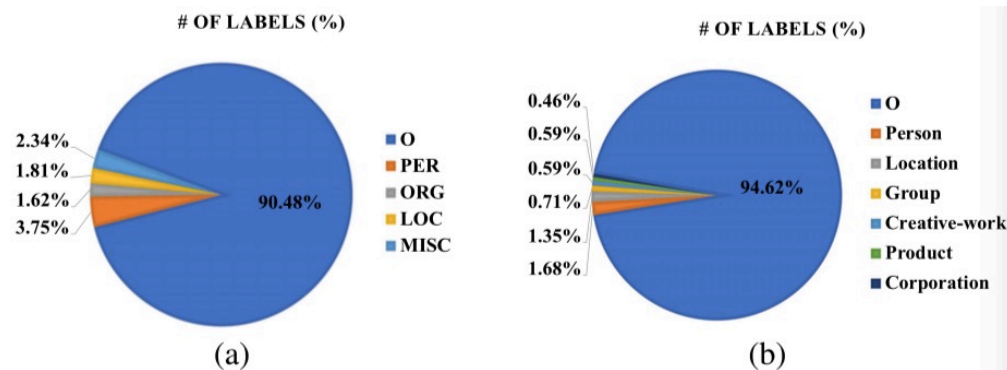


Fig. 2. Label statistics on CoNLL-2002 Dutch NER and WNUT-2017 English Twitter NER train set. The label type “O” is dominant in different data sets. (a) CoNLL-2002 Dutch. (b) WNUT-2017 English Twitter.

TABLE I
F1 SCORE OF BiLSTM-CNNs-CRF MODEL
ON WNUT-2017 DEVELOPMENT SET

Label Type	Precision (%)	Recall (%)	F1 Score (%)
O	95.56	99.46	97.47
Person	78.75	49.23	60.59
Location	51.02	46.73	48.78
Group	19.23	7.81	11.11
Creative-work	32.94	11.76	17.34
Product	33.33	7.69	12.50
Corporation	18.18	21.74	19.80

Zhou et al., Roseq: Robust sequence labeling. TNNLS 2019

Ours: selectively align the informative words within the sentence.



Method



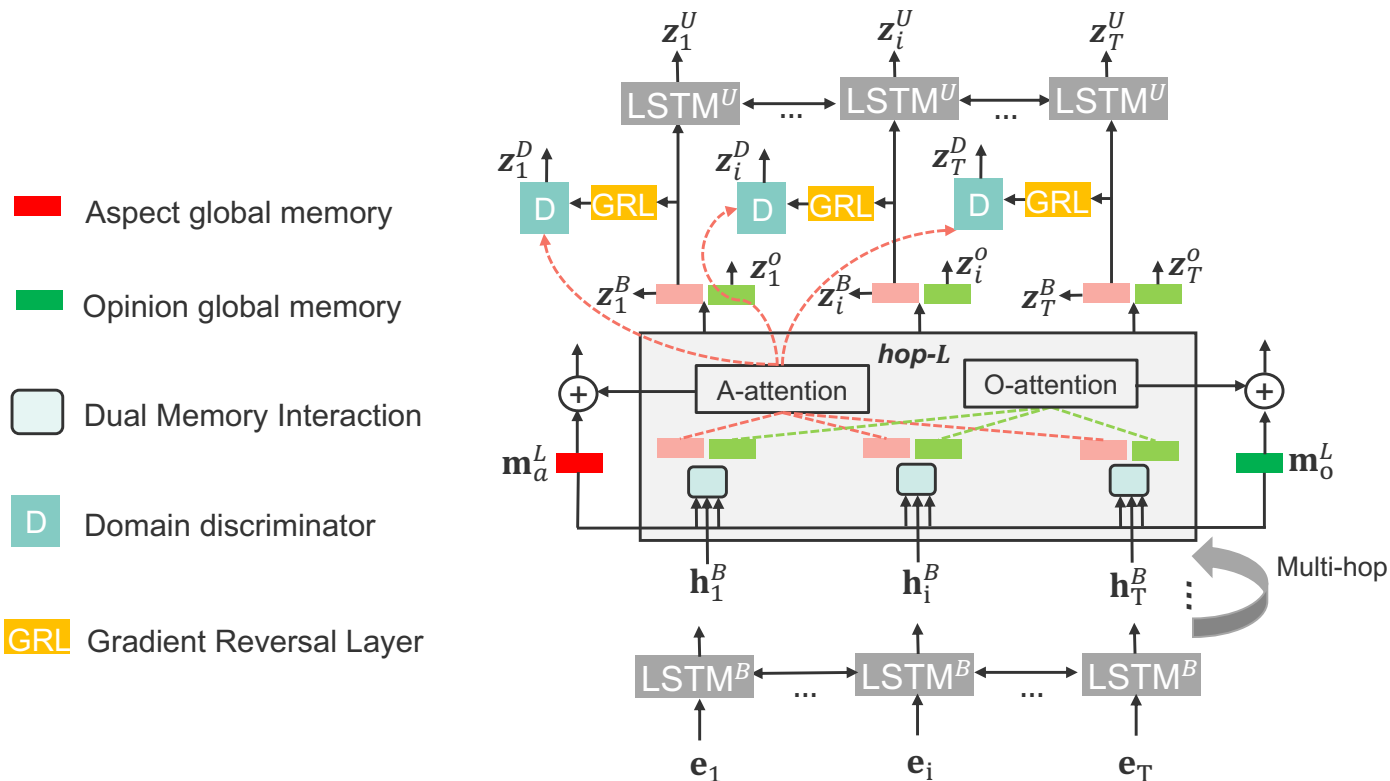
Experiments



Future Works



Framework



Upper LSTM^U:
unified tag

SAL: how to transfer

DMI: what to transfer

Lower LSTM^B:
aspect boundary tag

Embedding layer



Base Model

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Two stacked Bi-LSTMs:

- Aspect boundary information can be used as the guidance

$$\mathbf{h}_i^{\mathcal{B}} = [\overrightarrow{\text{LSTM}}^{\mathcal{B}}(\mathbf{e}_i); \overleftarrow{\text{LSTM}}^{\mathcal{B}}(\mathbf{e}_i)],$$
$$\mathbf{h}_i^{\mathcal{U}} = [\overrightarrow{\text{LSTM}}^{\mathcal{U}}(\mathbf{h}_i^{\mathcal{B}}); \overleftarrow{\text{LSTM}}^{\mathcal{U}}(\mathbf{h}_i^{\mathcal{B}})].$$

Low-level AD $\mathbf{z}_i^{\mathcal{B}} = \mathbf{p}(\mathbf{y}_i^{\mathcal{B}} | \mathbf{h}_i^{\mathcal{B}}) = \text{Softmax}(\mathbf{W}_{\mathcal{B}}\mathbf{h}_i^{\mathcal{B}} + \mathbf{b}_{\mathcal{B}}).$

High-level ADS $\mathbf{z}_i^{\mathcal{U}} = \mathbf{p}(\mathbf{y}_i^{\mathcal{U}} | \mathbf{h}_i^{\mathcal{U}}) = \text{Softmax}(\mathbf{W}_{\mathcal{U}}\mathbf{h}_i^{\mathcal{U}} + \mathbf{b}_{\mathcal{U}}).$

Primary loss:

$$\mathcal{L}_{\mathcal{M}} = \sum_{D_s} \sum_{Q \in \{\mathcal{B}, \mathcal{U}\}} \sum_{i=1}^T \ell(\mathbf{z}_i^Q, \mathbf{y}_i^Q).$$

AD: Aspect Detection (aspect boundary tags)

ADS: Aspect Detection and Sentiment Classification (unified tags)



What to transfer: Global-Local Memory Interaction (GLMI)

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GLMI: basic operation for computing the correlations between two objects (local & global memory).

Local Memory: LSTM hidden states

$$\text{GLMI: } f(\overbrace{\mathbf{h}_i^{\mathcal{B}}}^{\text{Local Memory}}, \underbrace{\mathbf{m}}_{\text{Global Memory}}; \Theta, \mathbf{G})$$

Global Memory: commonly-used in memory networks

1) Residual transformation

$$\tilde{\mathbf{h}}_i^{\mathcal{B}} = \mathbf{h}_i^{\mathcal{B}} + \text{ReLU}(\mathbf{W}[\mathbf{h}_i^{\mathcal{B}} : \mathbf{m}] + \mathbf{b}),$$

2) Multi-dimensional Bilinear Transformation

$$\mathbf{r}_i = \mathbf{m}^T \underbrace{\mathbf{G}}_{\text{Global Memory}} \tilde{\mathbf{h}}_i^{\mathcal{B}},$$

$\mathbf{G} \in \mathbb{R}^{K \times \dim_h^{\mathcal{B}} \times \dim_h^{\mathcal{B}}}$ models K kinds of latent relations



What to transfer: Dual Memory Interaction (DMI)

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DMI: models the correlations between aspect and opinions for aspect and opinion co-detection.

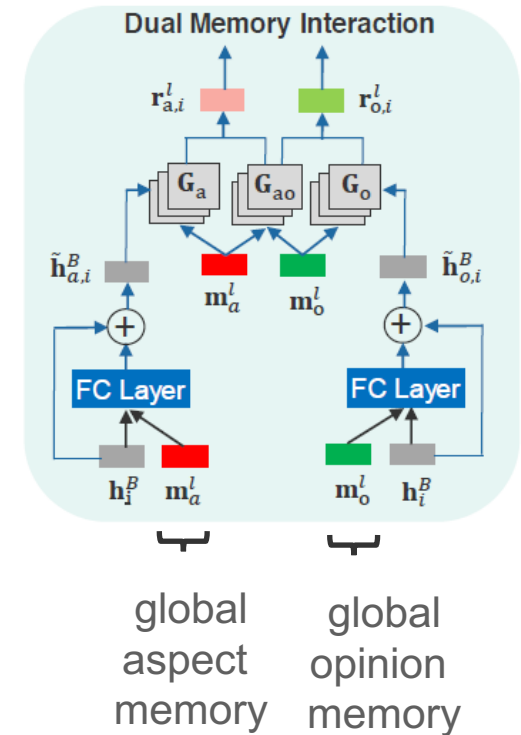
$$\begin{array}{l}
 \text{aspect } \mathbf{r}_{a,i}^l = \underbrace{[f(\mathbf{h}_i^{\mathcal{B}}, \mathbf{m}_a^l; \Theta_a, \mathbf{G}_a)]}_{\text{o \& o}} : \underbrace{[f(\mathbf{h}_i^{\mathcal{B}}, \mathbf{m}_o^l; \Theta_o, \mathbf{G}_{ao})]}_{\text{o \& a}}, \\
 \text{opinion } \mathbf{r}_{o,i}^l = \underbrace{[f(\mathbf{h}_i^{\mathcal{B}}, \mathbf{m}_o^l; \Theta_o, \mathbf{G}_o)]}_{\text{o \& o}} : \underbrace{[f(\mathbf{h}_i^{\mathcal{B}}, \mathbf{m}_a^l; \Theta_a, \mathbf{G}_{ao}^T)]}_{\text{o \& a}},
 \end{array}$$

opinion detection is used as a auxiliary task to link the different aspect across domains.

$$\mathcal{L}_{\mathcal{O}} = \sum_{D_s \cup D_t} \ell(\mathbf{z}_i^{\mathcal{O}}, \mathbf{y}_i^{\mathcal{O}})$$

A-attention (aspect) & O-attention (opinion)

$$\alpha_{p,i}^l = \frac{\exp(\mathbf{u}_p \mathbf{r}_{p,i}^l)}{\sum_{j=1}^T \exp(\mathbf{u}_p \mathbf{r}_{p,j}^l)}. \quad p \in \{a, o\}$$





How to transfer: Selective Adversarial Learning (SAL)

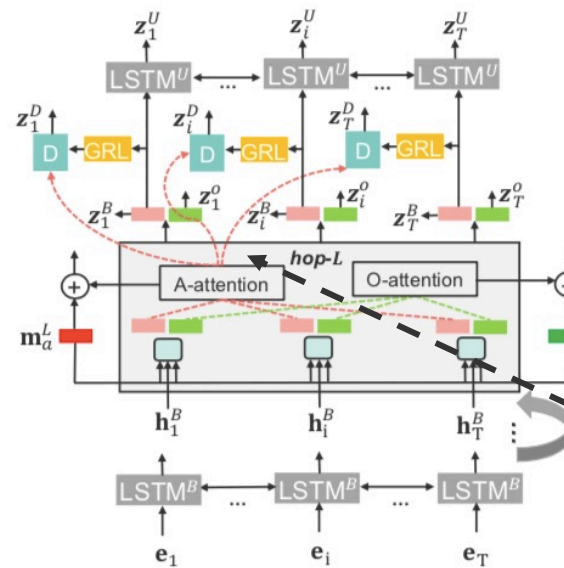
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Gradient Reversal Layer: (Ganin et al., 2016)

$$R_\lambda(\mathbf{x}) = \mathbf{x}$$

$$\frac{\partial R_\lambda(\mathbf{x})}{\partial \mathbf{x}} = -\lambda \mathbf{I}$$

- Aspect global memory
- Opinion global memory
- Dual Memory Interaction
- D Domain discriminator
- GRL Gradient Reversal Layer



Domain discriminator

$$\mathbf{z}_i^D = \mathbf{p}(\mathbf{y}_i^D | \mathbf{r}_{a,i}^L) = \text{Softmax}(\mathbf{W}_D R_\lambda(\mathbf{r}_{a,i}^L) + \mathbf{b}_D)$$

Selective adversarial loss:

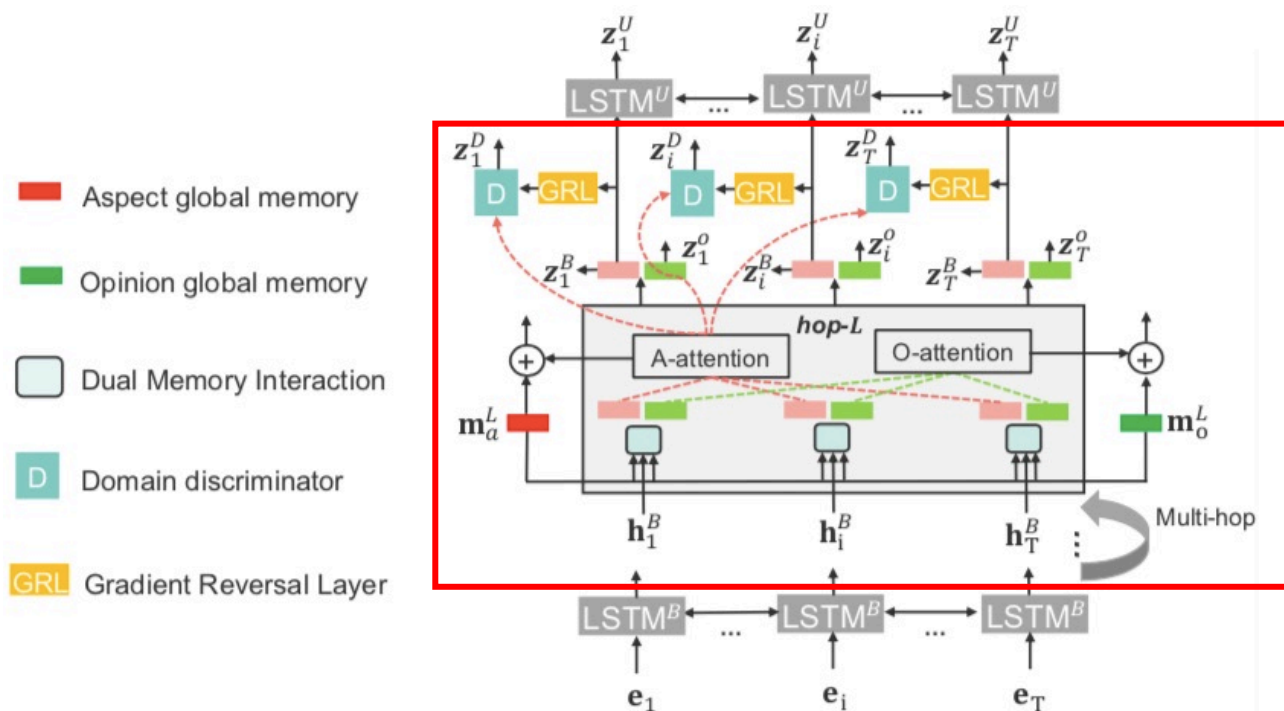
$$\mathcal{L}_D = \sum_{D_s \cup D_t} \sum_{i=1}^T \underbrace{\alpha_{a,i}^L}_{\text{A-attention dynamically controls the selectivity}} \ell(\mathbf{z}_i^D, \mathbf{y}_i^D).$$

A-attention dynamically controls the selectivity



How to transfer: Selective Adversarial Learning (SAL)

- Why do we choose low-level neural layer features (e.g., SAL on the low-level AD task) for transfer?



Existing studies (Yosinski et al., 2014; Mou et al., 2016) have already shown some evidence that low-level neural layer features (i.e., low-level task) are more easily transferred to different tasks or domains.

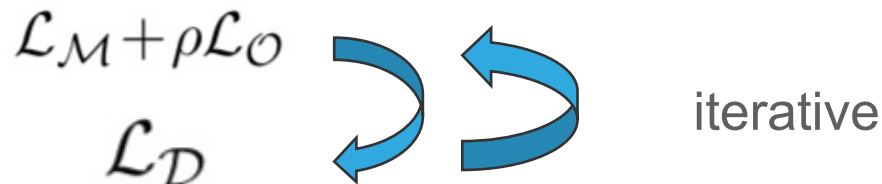


Training Strategy

Joint training: (unstable, too many objectives)

$$E = \mathcal{L}_{\mathcal{M}} + \rho \mathcal{L}_{\mathcal{O}} + \gamma \mathcal{L}_{\mathcal{D}}$$

Alternating training: (more unstable, two-stage optimization)



$$(\hat{\theta}_f^{(1)}, \hat{\theta}_w) = \arg \min_{\theta_f, \theta_w} \mathcal{L}_{\mathcal{M}} + \rho \mathcal{L}_{\mathcal{O}} \quad \textbf{discriminative stage}$$

$$(\hat{\theta}_f^{(2)}, \hat{\theta}_d) = \arg \min_{\theta_d} \max_{\theta_f} \mathcal{L}_{\mathcal{D}}. \quad \textbf{domain-invariant stage}$$

$\theta_f, \theta_w, \theta_d$ The parameters for feature learning of each word, word predictions for AD, ADS and opinion detection tasks, and domain classification, respectively.



Method



Experiments



Future Works



Experiment Setup

Datasets

L: Laptop domain (Pontiki et al., 2014)

R: Restaurant domain (Pontiki et al., 2014,2015,2016)

D: Device domain (Hu and Liu, 2004)

S: Service domain (Toprak et al., 2010)

L and **R** are from SemEval ABSA challenge 2014, 2015, 2016

Dataset	Domain	Sentences	Training	Testing
L	Laptop	1,869	1,458	411
R	Restaurant	3,900	2,481	1,419
D	Device	1,437	954	483
S	Service	2,153	1,433	720



Experiment Setup

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Setting

4 different domains, 10 transfer pairs (without two easy pairs $L \rightarrow D$, $D \rightarrow L$)

For each pair e.g., **source** A \rightarrow **target** B:

Training: Labeled training data from A, unlabeled training data from B

Validation: testing data from A

Testing: testing data from B

Baselines

- **TCRF:** (Jakob and Gurevych, 2010): Transferable CRF
- **RAP:** (Li et al., 2012): cross-domain Relational Adaptive Bootstrapping
- **Hier-Joint:** (Ding et al., 2017): RNN with manually designed rule-based auxiliary tasks based on common syntactic relations
- **RNSCN:** (Wang and Pan, 2018): a recursive neural structural correspondence network

Extended versions:

- **Hier-Joint+ & RNSCN+:** original version with the proposed stacking architecture



Main Results

Transfer Pair	TCRF		RAP		Hier-Joint		Hier-Joint ⁺		RNSCN		RNSCN ⁺		Ours	
	AD	ADS	AD	ADS	AD	ADS	AD	ADS	AD	ADS	AD	ADS	AD	ADS
S→R	-	14.84	-	25.41	-	32.81	46.39	31.10	-	30.56	48.89	33.21	52.05	41.03
L→R	-	16.06	-	31.05	-	31.90	48.61	33.54	-	31.85	52.19	35.65	56.12	43.04
D→R	-	17.05	-	28.37	-	30.03	42.96	32.87	-	31.41	50.39	34.60	51.55	41.01
R→S	-	15.20	-	13.17	-	15.20	27.18	15.56	-	23.31	30.41	20.04	39.02	28.01
L→S	-	12.34	-	13.72	-	15.33	25.22	13.90	-	16.73	31.21	16.59	38.26	27.20
D→S	-	13.49	-	16.80	-	18.74	29.28	19.04	-	18.93	35.50	20.03	36.11	26.62
R→L	-	14.59	-	15.69	-	19.17	34.11	20.72	-	25.54	47.23	26.63	45.01	34.13
S→L	-	9.56	-	12.38	-	21.80	33.02	22.65	-	19.15	34.03	18.87	35.99	27.04
R→D	-	19.84	-	17.50	-	22.91	34.81	24.53	-	32.43	46.16	33.26	43.76	35.44
S→D	-	13.43	-	15.74	-	20.04	35.00	23.24	-	19.98	32.41	22.00	41.21	33.56
Average	-	14.64	-	18.98	-	22.79	35.66	23.72	-	24.99	40.84	26.09	43.91[†]	33.71[†]
(Δ)	-	(19.07)	-	(14.73)	-	(10.92)	(8.25)	(9.99)	-	(8.72)	(3.07)	(7.62)	-	-

Table 2: Main results (%). Δ refers to the improvements of the full model over baseline methods. The marker [†] means that our model significantly outperforms the best baseline **RNSCN⁺** with p -value < 0.01 .



Ablation Variants

- | | | |
|------------------|---|---|
| What to transfer | { | <ul style="list-style-type: none">• Base Model (SO / TO): two stacked Bi-LSTMs. SO (Source Only) and TO (Target Only). We usually refer to them as a lower bound and an upper bound, respectively.• Base Model + DMI: two stacked Bi-LSTMs with a DMI between them. |
| How to transfer | | <ul style="list-style-type: none">• AD-AL: pure adversarial learning (removing the selective weight from the adversarial loss) for the low-level AD task .• ADS-SAL: selective adversarial learning on each word representations for the high-level ADS task.• AD-SAL (Full model): selective adversarial learning for the low-level AD task . |

Note: The backbones of the **AD-AL** **ADS-SAL** and **AD-SAL** are all based on the **Base Model +DMI**



No DMI v.s. DMI

Transfer Pair	No DMI		DMI									
	Lower bound		Ablation Models				Full Model		Upper bound			
	Base Model (SO)		Base Model+DMI		AD-AL		ADS-SAL		AD-SAL		Base Model (TO)	
	AD	ADS	AD	ADS	AD	ADS	AD	ADS	AD	ADS	AD	ADS
S→R	30.32	19.74	45.68	37.10	48.28	37.65	51.29	41.03	52.05	41.03	81.84	67.26
L→R	33.99	28.34	46.25	36.49	51.79	38.63	55.50	42.00	56.12	43.04		
D→R	31.59	27.25	46.56	36.89	46.39	37.34	46.43	38.35	51.55	41.01		
R→S	15.63	8.61	21.88	16.85	25.13	18.61	37.11	25.84	39.02	28.01	68.28	41.12
L→S	22.45	16.07	28.67	21.53	28.18	20.74	30.35	23.73	38.26	27.20		
D→S	16.79	9.49	31.91	22.14	32.88	24.89	32.51	21.45	36.11	26.62		
R→L	38.45	23.40	42.27	30.52	40.52	28.77	44.56	33.34	45.01	34.13	75.95	52.62
S→L	24.69	14.48	36.38	27.48	32.96	25.16	33.87	24.22	35.99	27.04		
R→D	34.87	25.79	36.90	27.71	41.61	31.88	43.97	34.50	43.76	35.44	70.37	57.62
S→D	27.73	17.73	38.03	31.21	39.54	32.28	40.40	33.26	41.21	33.56		
Average (Δ)	27.65 (16.26)	19.09 (14.62)	37.45 (6.46)	28.79 (4.92)	38.73 (5.18)	29.60 (4.11)	41.60 (2.31)	31.77 (1.94)	43.91[†] -	33.71[†] -	74.11 -	54.66 -

Table 3: Ablation results (%). Δ refers to the improvements of the full model over ablation methods. The marker [†] means that the full model significantly outperforms the best ablation model **ADS-SAL** with p -value < 0.01 .



No SAL v.s. SAL

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Transfer Pair	No SAL								SAL			
	Lower bound		Ablation Models						Full Model		Upper bound	
	Base Model (SO)		Base Model+DMI		AD-AL		ADS-SAL		AD-SAL		Base Model (TO)	
	AD	ADS	AD	ADS	AD	ADS	AD	ADS	AD	ADS	AD	ADS
S→R	30.32	19.74	45.68	37.10	48.28	37.65	51.29	41.03	52.05	41.03	81.84	67.26
L→R	33.99	28.34	46.25	36.49	51.79	38.63	55.50	42.00	56.12	43.04		
D→R	31.59	27.25	46.56	36.89	46.39	37.34	46.43	38.35	51.55	41.01		
R→S	15.63	8.61	21.88	16.85	25.13	18.61	37.11	25.84	39.02	28.01	68.28	41.12
L→S	22.45	16.07	28.67	21.53	28.18	20.74	30.35	23.73	38.26	27.20		
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R→L	38.45	23.40	42.27	30.52	40.52	28.77	44.56	33.34	45.01	34.13	75.95	52.62
S→L	24.69	14.48	36.38	27.48	32.96	25.16	33.87	24.22	35.99	27.04		
R→D	34.87	25.79	36.90	27.71	41.61	31.88	43.97	34.50	43.76	35.44	70.37	57.62
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Table 3: Ablation results (%). Δ refers to the improvements of the full model over ablation methods. The marker [†] means that the full model significantly outperforms the best ablation model **ADS-SAL** with p -value < 0.01 .



No Selectivity v.s. Selectivity

Transfer Pair	No Selectivity								Selectivity			
	Lower bound		Ablation Models						Full Model		Upper bound	
	Base Model (SO)		Base Model+DMI		AD-AL		ADS-SAL		AD-SAL		Base Model (TO)	
	AD	ADS	AD	ADS	AD	ADS	AD	ADS	AD	ADS	AD	ADS
S→R	30.32	19.74	45.68	37.10	48.28	37.65	51.29	41.03	52.05	41.03	81.84	67.26
L→R	33.99	28.34	46.25	36.49	51.79	38.63	55.50	42.00	56.12	43.04		
D→R	31.59	27.25	46.56	36.89	46.39	37.34	46.43	38.35	51.55	41.01		
R→S	15.63	8.61	21.88	16.85	25.13	18.61	37.11	25.84	39.02	28.01	68.28	41.12
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Average (Δ)	27.65 (16.26)	19.09 (14.62)	37.45 (6.46)	28.79 (4.92)	38.73 (5.18)	29.60 (4.11)	41.60 (2.31)	31.77 (1.94)	43.91[†] -	33.71[†] -	74.11 -	54.66 -

Table 3: Ablation results (%). Δ refers to the improvements of the full model over ablation methods. The marker [†] means that the full model significantly outperforms the best ablation model **ADS-SAL** with p -value < 0.01 .



Low-level v.s. High-level

High-level Low-level

Transfer Pair	Lower bound		Ablation Models						Full Model		Upper bound	
	Base Model (SO)		Base Model+DMI		AD-AL		ADS-SAL		AD-SAL		Base Model (TO)	
	AD	ADS	AD	ADS	AD	ADS	AD	ADS	AD	ADS	AD	ADS
S→R	30.32	19.74	45.68	37.10	48.28	37.65	51.29	41.03	52.05	41.03	81.84	67.26
L→R	33.99	28.34	46.25	36.49	51.79	38.63	55.50	42.00	56.12	43.04		
D→R	31.59	27.25	46.56	36.89	46.39	37.34	46.43	38.35	51.55	41.01		
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L→S	22.45	16.07	28.67	21.53	28.18	20.74	30.35	23.73	38.26	27.20		
D→S	16.79	9.49	31.91	22.14	32.88	24.89	32.51	21.45	36.11	26.62		
R→L	38.45	23.40	42.27	30.52	40.52	28.77	44.56	33.34	45.01	34.13	75.95	52.62
S→L	24.69	14.48	36.38	27.48	32.96	25.16	33.87	24.22	35.99	27.04		
R→D	34.87	25.79	36.90	27.71	41.61	31.88	43.97	34.50	43.76	35.44	70.37	57.62
S→D	27.73	17.73	38.03	31.21	39.54	32.28	40.40	33.26	41.21	33.56		
Average (Δ)	27.65 (16.26)	19.09 (14.62)	37.45 (6.46)	28.79 (4.92)	38.73 (5.18)	29.60 (4.11)	41.60 (2.31)	31.77 (1.94)	43.91[†] -	33.71[†] -	74.11 -	54.66 -

Table 3: Ablation results (%). Δ refers to the improvements of the full model over ablation methods. The marker [†] means that the full model significantly outperforms the best ablation model **ADS-SAL** with p -value < 0.01 .



Case studies

No Adaptation Adversarial Selective Adversarial

Input: (Target domain \mathbb{L})	Base model+DMI		AD-AL		AD-SAL	
	AD	ADS	AD	ADS	AD	ADS
1. This laptop has only 2 [<i>usb ports</i>] _{NEG} , and they are both on the same side .	<i>ports</i> (X), <i>side</i> (X)	NONE(X)	NONE(X)	NONE(X)	<i>usb ports</i>	[<i>usb ports</i>] _{NEG}
2. It is very easy to integrate [<i>bluetooth devices</i>] _{POS} , and [<i>usb devices</i>] _{POS} are recognized almost instantly .	<i>devices</i> (X), <i>devices</i> (X)	[<i>devices</i>] _{POS} (X), [<i>devices</i>] _{POS} (X)	NONE(X)	NONE(X)	<i>bluetooth devices</i> , <i>usb devices</i>	[<i>bluetooth devices</i>] _{POS} , [<i>usb devices</i>] _{POS}
3. I also wanted [<i>windows 7</i>] _{POS} , which this one has .	NONE(X)	NONE(X)	NONE(X)	NONE(X)	<i>windows 7</i>	[<i>windows 7</i>] _{POS}
4. The [<i>speed</i>] _{POS} , the [<i>simplicity</i>] _{POS} , the [<i>design</i>] _{POS} it is lightyears ahead of any pc i have ever owned .	<i>speed</i> , <i>design</i>	[<i>speed</i>] _{POS} , [<i>design</i>] _{POS}	<i>speed</i> , <i>design</i> , <i>pc</i> (X)	[<i>speed</i>] _{POS} , [<i>design</i>] _{POS} , [<i>pc</i>] _{POS} (X)	<i>speed</i> , <i>design</i> , <i>simplicity</i>	[<i>speed</i>] _{POS} , [<i>design</i>] _{POS} , [<i>simplicity</i>] _{POS}
6. The [<i>battery life</i>] _{POS} is excellent , the [<i>display</i>] _{POS} is excellent and [<i>downloading apps</i>] _{POS} is a breeze .	<i>battery</i> (X), <i>display</i> , <i>apps</i> (X)	[<i>battery</i>] _{POS} (X), [<i>display</i>] _{POS} , [<i>apps</i>] _{POS} (X)	<i>battery</i> (X), <i>display</i> , <i>apps</i> (X)	[<i>battery</i>] _{POS} (X), [<i>display</i>] _{POS} , [<i>apps</i>] _{POS} (X)	<i>battery life</i> , <i>display</i> , <i>downloading apps</i>	[<i>battery life</i>] _{POS} , [<i>display</i>] _{POS} , [<i>downloading apps</i>] _{POS}

Table 4: Case analysis for the $\mathbb{R} \rightarrow \mathbb{L}$ pair. Note that we only show the sentiment part of the unified labels (i.e., POS, NEG, and NEU) and use brackets to indicate the boundary. The marker **X** denotes an incorrect prediction.



Method



Experiments



Future Works



Future Works

- Potentially, extend the proposed SAL method to other domain adaptation methods.
- Apply the SAL on more general sequence labeling tasks including NER, POS, Chunking and so on.



Thank You!

Questions?

- Our code is open source and publicly available at the github:
<https://github.com/hsqmlzno1/Transferable-E2E-ABSA>



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