

# Lecture 18

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Continuing from last lecture, these are the steps that we follow -

1. Change objective to a Lagrangian
2. Equate derivatives wrt  $w$ ,  $b$  to 0
3. Substitute
4. Manipulate the loss equation
5. Rewrite the constraints as KKT Conditions

We performed the above steps in [Lecture 17](#).

For Soft SVM, we got box constraints for the result. Classification with respect to that is as follows -

## Box constraints: Four types of points

- Inside the margin (and correctly classified)
  - $a_n = 0$
- On the margin (and correctly classified)
  - $0 < a_n < C, \xi_n = 0$
- Across the margin and correctly classified
  - $a_n = C, \xi_n \leq 1$
- Across the margin and misclassified
  - $a_n = C, \xi_n > 1$

For Hard SVM, we will have  $C = \infty$ . ([More regularization means smaller C](#))

The hyperparameters in this setting are -

1.  $C$
2. Kernel hyperparameters ( $K$  and  $d$ )

Thus, we conclude the Kernel Methods, Kernelized SVMs.

We now move to begin Neural Networks

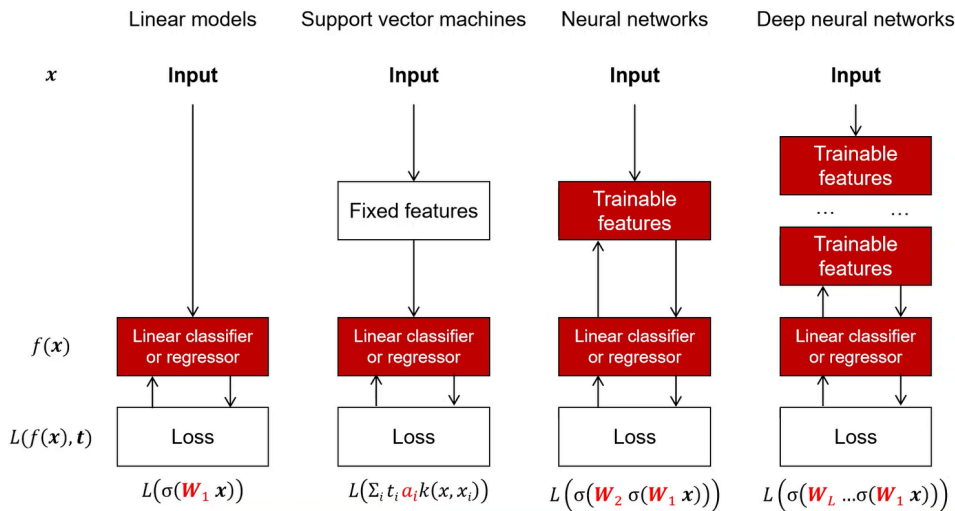
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# Introduction to Neural Networks

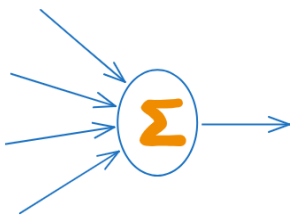
key terms : **hidden layers**, **mathematical modelling**

A very informative representation of all models in order of increasing non-linearity.

## Increasing nonlinearity in models



Tries to mimic the behavior of a biological neuron.



Layered structure of neuron -

$$y = w_3^{Q \times P} \sigma(w_2^{P \times M} \sigma(w_1^{M \times N} \mathbf{w}^{N \times 1}))$$

where  $w_1, w_2, w_3$  represent the weights for the layers 1, 2 and 3 respectively and  $\sigma$  is a non-linear function known as the activation function (since we want to perform non-linear modelling).

Application of chain rule for gradient update/descent is known as back-propagation.

## Importance of hidden layers

The hidden layers iteratively extract the features from the previous stage of features until the desired output stage is reached.

$$f(x) = \sum_{i \in S} w_i k(x, x_i)$$

# Universal Approximation Theorem

The Universal Approximation Theorem states that a neural network with at least one hidden layer of a sufficient number of neurons, and a non-linear activation function can approximate any (Lipschitz) continuous function to an arbitrary level of accuracy, with the approximation error controlled by the Lipschitz constant of the function being approximated.

## Types of activation functions ( $\sigma$ )

- Step
- Sigmoid
- ReLU (Rectified Linear Unit)
- Softmax
- tanh
- Linear

Formally, the standard (unit) softmax function

$\sigma : \mathbb{R}^K \rightarrow (0, 1)^K$ , where  $K \geq 1$ , takes a vector  $\mathbf{z} = (z_1, \dots, z_K) \in \mathbb{R}^K$  and computes each component of vector  $\sigma(\mathbf{z}) \in (0, 1)^K$  with

$$\sigma(\mathbf{z})_i = \frac{e^{z_i}}{\sum_{j=1}^K e^{z_j}}$$

[Softmax Function - Wikipedia](#).

PS: Refer to this [Neural Networks - Harsh S Roniyar](#) amazing link for more such content