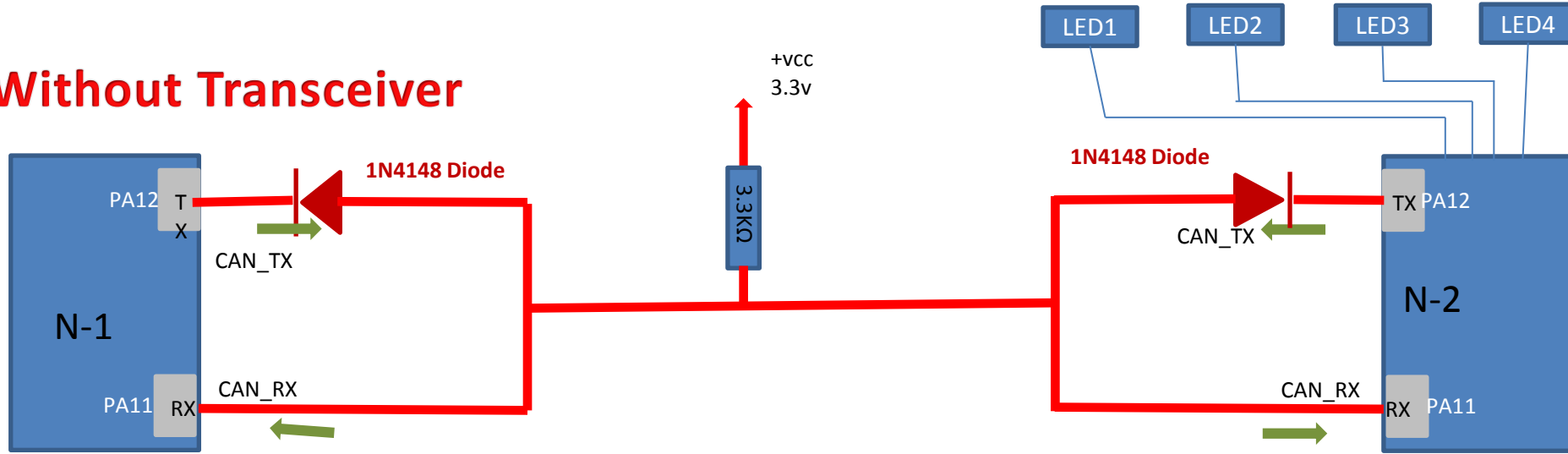# CAN Normal Mode

Without Transceiver

- N1 sends a message(led number) using Data Frame for every 1sec to N2
- After the reception of message(led number) N2 has to glow the corresponding LED
- N1 also sends a Remote frame to request 2 bytes of data for every 4sec
- N2 upon receiving the Remote frame should send back 2 bytes of data using Data Frame
- Use Interrupt driven Code