UCSD Embedded C Final Assignment

By

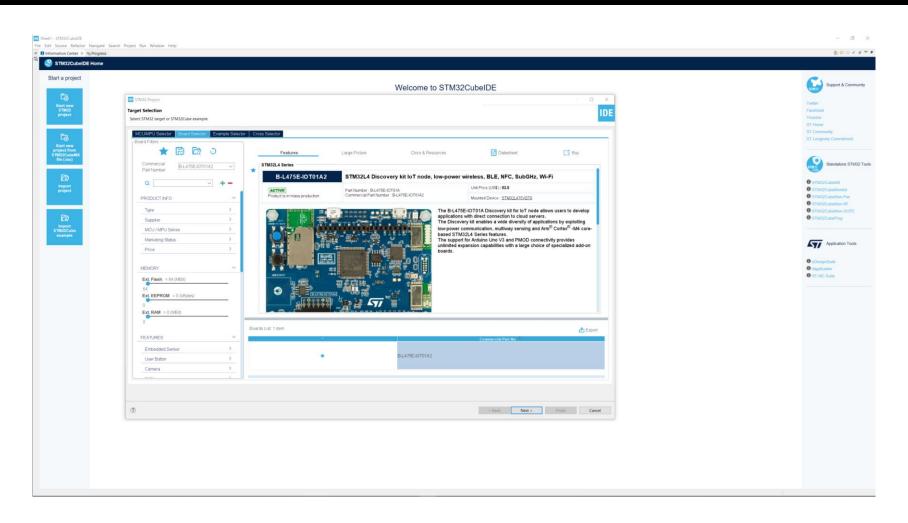
Hsuankai Chang

hsuankac@umich.edu

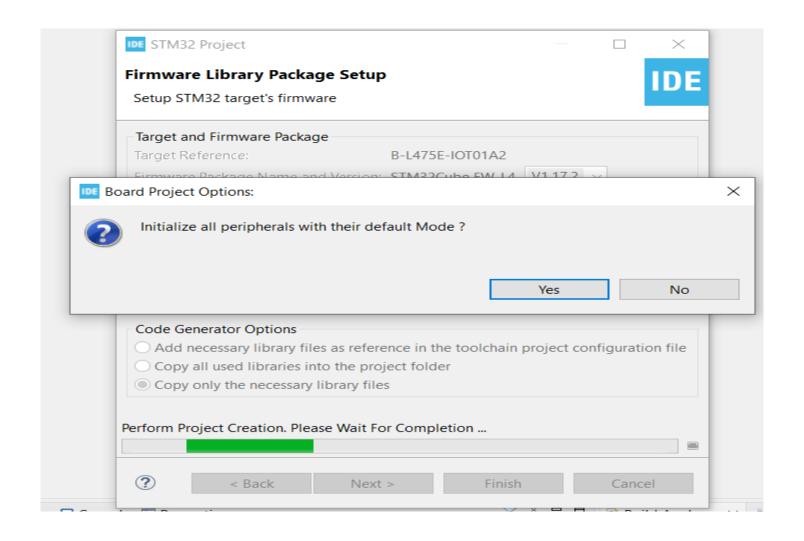
Step 1. Startup STM32CubeIDE and create new STM32 project



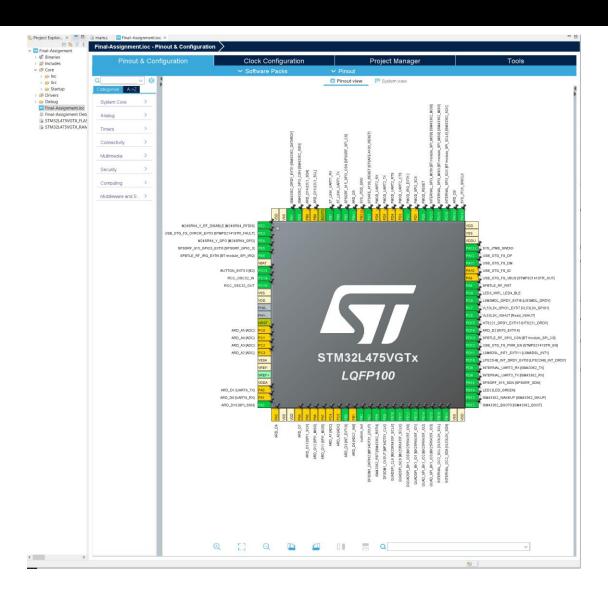
Step 2. Access board selector and type in the board you use, enter project name and click Next



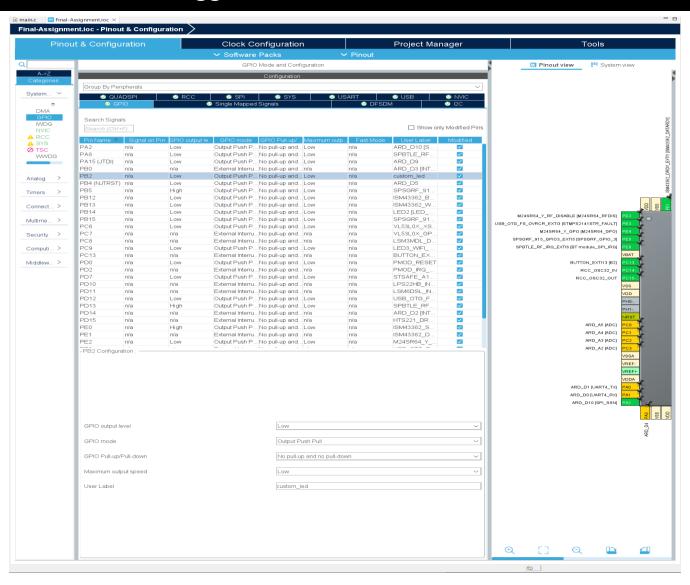
Step 3. Click yes to initialize all peripherals to default



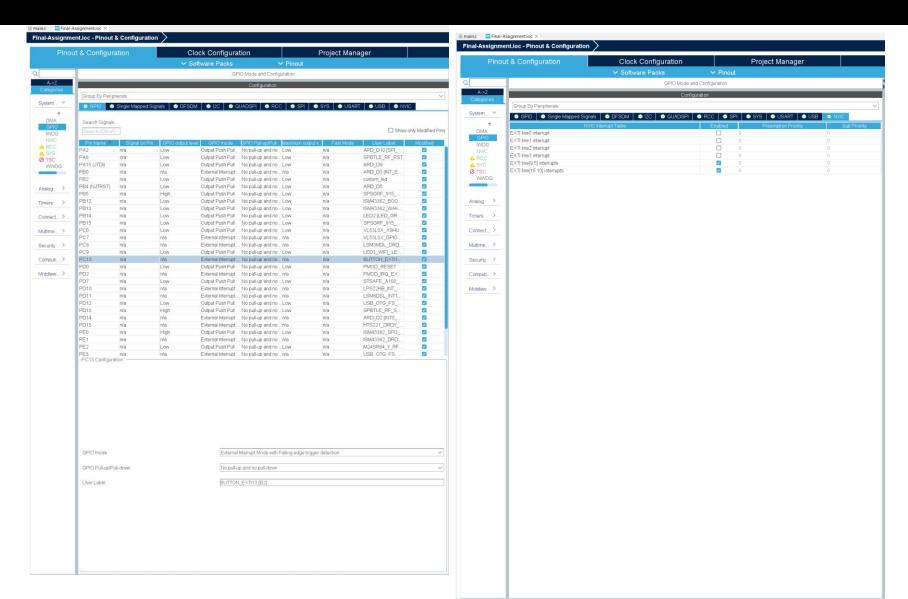
Step 4. When in .ioc file, view the overall default settings



Step 5. Click GPIO and set PB2 pin as custom_led output push pull pin, we will use this pin to toggle external LED for demo 4



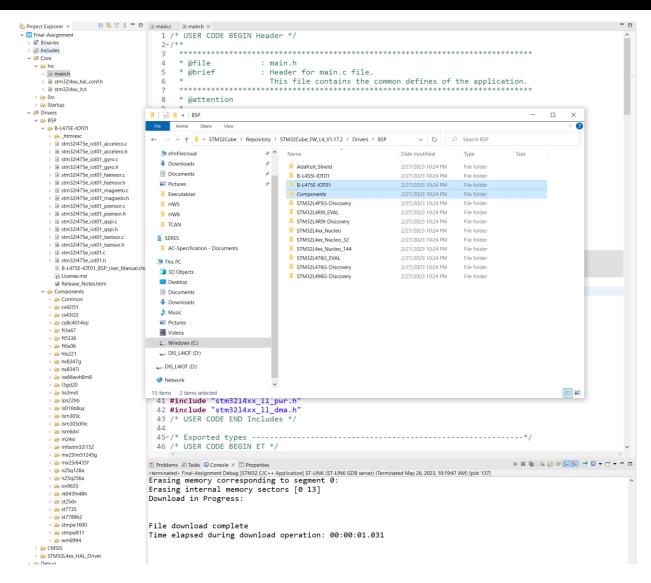
Step 6. Confirm that blue button has set up as external interrupt trigger



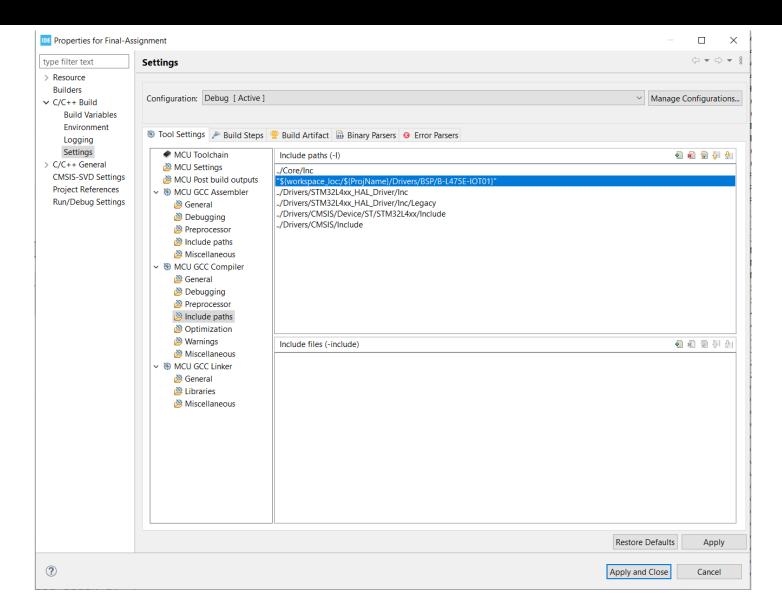
Step 7. Generate the code, and in main.h file, and the required low layer header file for use in demo 1

```
main.c main.h ×
 1 /* USER CODE BEGIN Header */
    * @brief
                : Header for main.c file.
                 This file contains the common defines of the application.
    * @attention
    * Copyright (c) 2023 STMicroelectronics.
    * All rights reserved.
 12
    * This software is licensed under terms that can be found in the LICENSE file
    * in the root directory of this software component.
    * If no LICENSE file comes with this software, it is provided AS-IS.
    ************************
18 */
 19 /* USER CODE END Header */
 21 /* Define to prevent recursive inclusion -----*/
 22 #ifndef MAIN H
 23 #define MAIN H
25 #ifdef __cplusplus
26 extern "C" {
 27 #endif
 29 /* Includes -----*/
 30 #include "stm3214xx hal.h"
 31
 32⊕/* Private includes -----*/
 33 /* USER CODE BEGIN Includes */
 34 #include "stm3214xx 11 system.h"
 35 #include "stm3214xx 11 gpio.h"
 36 #include "stm3214xx 11 exti.h"
 37 #include "stm3214xx 11 bus.h"
 38 #include "stm3214xx_11_cortex.h"
 39 #include "stm3214xx 11 rcc.h"
 40 #include "stm3214xx_11_utils.h"
 41 #include "stm3214xx 11 pwr.h"
 42 #include "stm3214xx 11 dma.h"
 43 /* USER CODE END Includes */
 45@/* Exported types -----*/
 46 /* USER CODE BEGIN ET */
```

Step 8. Create BSP folder under Drivers folder, and copy and paste the local Components and B-L475E-IOT01 folder to it. This is for using BSP package for temp sensor in demo 3



Step 9. Add the BSP folder to the include path



Step 10. In main.c file, add the required header files

```
i main.c × i main.h
 1 /* USER CODE BEGIN Header */
 4 * @file
               : Main program body
 9 * Copyright (c) 2023 STMicroelectronics.
 10 * All rights reserved.
12 * This software is licensed under terms that can be found in the LICENSE file
 * in the root directory of this software component.
* If no LICENSE file comes with this software, it is provided AS-IS.
15 *
180/* USER CODE END Header */
19 /* Includes -----*/
 20 #include "main.h"
22=/* Private includes -----*/
 23 /* USER CODE BEGIN Includes */
24 #include <string.h>
25 #include <stdio.h>
 26 #include <math.h>
27 #include "stm321475e_iot01.h"
 28 #include "stm321475e_iot01_tsensor.h"
 29 /* USER CODE END Includes */
31=/* Private typedef -----*/
 32 /* USER CODE BEGIN PTD */
34 /* USER CODE END PTD */
 36@/* Private define -----*/
 37 /* USER CODE BEGIN PD */
39 /* USER CODE END PD */
42 /* USER CODE BEGIN PM */
44 /* USER CODE END PM */
46 /* Private variables -----*/
47 DFSDM_Channel_HandleTypeDef hdfsdm1_channel1;
49 I2C_HandleTypeDef hi2c2;
51 QSPI_HandleTypeDef hqspi;
 53 SPI HandleTypeDef hspi3;
55 UART_HandleTypeDef huart1;
EG HADT WandlaTypoDof huanta.
```

Step 11. In main.c, add the needed variables

```
37 /* USER CODE BEGIN PD */
39 /* USER CODE END PD */
41®/* Private macro -----*/
42 /* USER CODE BEGIN PM */
43
44 /* USER CODE END PM */
46 /* Private variables -----*/
47 DFSDM Channel HandleTypeDef hdfsdm1 channel1;
49 I2C_HandleTypeDef hi2c2;
51 QSPI HandleTypeDef hqspi;
53 SPI_HandleTypeDef hspi3;
55 UART HandleTypeDef huart1;
56 UART_HandleTypeDef huart3;
58 PCD_HandleTypeDef hpcd_USB_OTG_FS;
60 /* USER CODE BEGIN PV */
61 uint8 t demo0 count = 0;
62 uint8_t demo1_count = 0;
63 uint8_t demo_count = 0;
64 char buf[100];
65 /* USER CODE END PV */
67 /* Private function prototypes -----*/
68 void SystemClock_Config(void);
69 static void MX_GPIO_Init(void);
70 static void MX_DFSDM1_Init(void);
71 static void MX I2C2 Init(void);
72 static void MX QUADSPI Init(void);
73 static void MX SPI3 Init(void);
74 static void MX USART1 UART Init(void);
75 static void MX_USART3_UART_Init(void);
76 static void MX_USB_OTG_FS_PCD_Init(void);
77 /* USER CODE BEGIN PFP */
78
79 /* USER CODE END PFP */
81®/* Private user code -----*/
82 /* USER CODE BEGIN 0 */
84 /* USER CODE END 0 */
85
* @brief The application entry point.
88 * @retval int
89 */
90 int main(void)
91 {
     /* HEED CODE DECTN 1 */
```

Step 12. Add the function definition for EXTI call back function

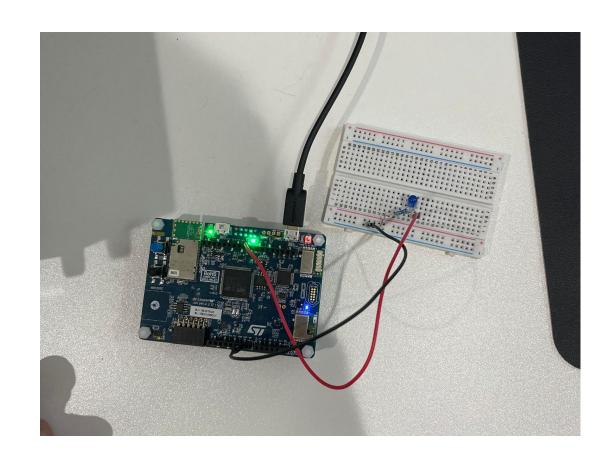
```
/ LO
719 /* USER CODE BEGIN 4 */
720 void HAL GPIO EXTI Callback(uint16 t GPIO Pin)
721 {
722
        if(GPIO Pin == BUTTON EXTI13 Pin)
723
            demo_count = (demo_count + 1) % 4;
724
            if(demo_count == 0){
725
                demo0 count = 0;
726
            }else if (demo count == 1){
727
                demo1 count = 0;
728
729
            sprintf(buf, "UART1: current demo is: %d\r\n", demo_count + 1);
730
731
            HAL UART Transmit(&huart1, (uint8 t*)buf, strlen(buf), HAL MAX DELAY);
732
733 }
734 /* USER CODE END 4 */
735
7369/**
```

Step 13. Add the code for demo 1 to demo 4

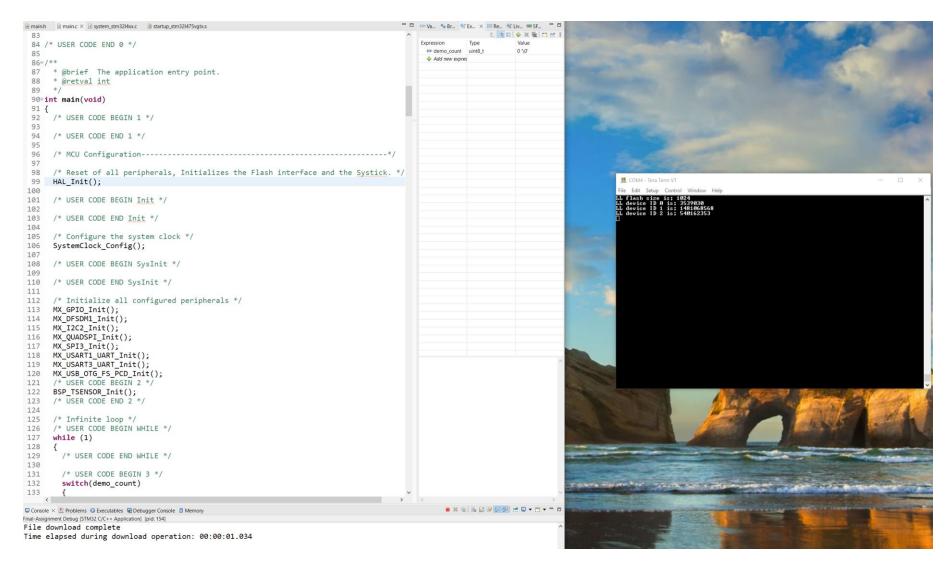
```
while (1)
128
129
        /* USER CODE END WHILE */
130
131
        /* USER CODE BEGIN 3 */
132
        switch(demo count)
133
134
            case 0:
135
136
                if(demo0_count == 0)
137
138
                    uint32 t flashSize = LL GetFlashSize();
139
                    uint32_t deviceID0 = LL_GetUID_Word0();
140
                    uint32 t deviceID1 = LL GetUID Word1();
141
                    uint32_t deviceID2 = LL_GetUID_Word2();
142
                    sprintf(buf, "LL flash size is; %lu\r\n", flashSize);
143
                    HAL UART Transmit(&huart1, (uint8 t*)buf, strlen(buf), HAL MAX DELAY);
144
                    sprintf(buf, "LL device ID 0 is; %lu\r\n", deviceID0);
145
                    HAL UART Transmit(&huart1, (uint8 t*)buf, strlen(buf), HAL MAX DELAY);
146
                    sprintf(buf, "LL device ID 1 is; %lu\r\n", deviceID1);
147
                    HAL UART Transmit(&huart1, (uint8 t*)buf, strlen(buf), HAL MAX DELAY);
148
                    sprintf(buf, "LL device ID 2 is; %lu\r\n", deviceID2);
149
                    HAL_UART_Transmit(&huart1, (uint8_t*)buf, strlen(buf), HAL_MAX_DELAY);
                    demo0_count++;
150
151
152
                LL_GPIO_TogglePin(LED2_GPIO_Port, LED2_Pin);
153
                HAL Delay(1000);
154
                break;
155
156
            case 1:
157
158
                if(demo1 count == 0)
159
160
                    uint32_t DeviceID = HAL_GetDEVID();
161
                    uint32 t deviceUID0 = HAL GetUIDw0();
162
                    uint32_t deviceUID1 = HAL_GetUIDw1();
163
                    uint32 t deviceUID2 = HAL GetUIDw2();
164
165
                    sprintf(buf, "HAL device ID is; %lu\r\n", DeviceID);
166
                    HAL_UART_Transmit(&huart1, (uint8_t*)buf, strlen(buf), HAL_MAX_DELAY);
167
                    sprintf(buf, "HAL unique device ID 0 is; %lu\r\n", deviceUID0);
168
                    HAL_UART_Transmit(&huart1, (uint8_t*)buf, strlen(buf), HAL_MAX_DELAY);
169
                    sprintf(buf, "HAL unique device ID 1 is; %lu\r\n", deviceUID1);
170
                    HAL_UART_Transmit(&huart1, (uint8_t*)buf, strlen(buf), HAL_MAX_DELAY);
171
                    sprintf(buf, "HAL unique device ID 2 is; %lu\r\n", deviceUID2);
172
                    HAL UART Transmit(&huart1, (uint8 t*)buf, strlen(buf), HAL MAX DELAY);
173
                    demo1_count++;
174
175
                HAL_GPIO_TogglePin(LED2_GPIO_Port, LED2_Pin);
176
                HAL Delay(2000);
177
                break;
178
```

```
179
            case 2:
180
                float temp = BSP_TSENSOR_ReadTemp();
181
182
                int tempInt1 = temp;
183
                float tempFrac = temp - tempInt1;
184
                int tempInt2 = trunc(tempFrac * 100);
185
                sprintf(buf, "Temperature is : %d.%02d\r\n", tempInt1, tempInt2);
                HAL UART Transmit(&huart1, (uint8 t*)buf, strlen(buf), HAL MAX DELAY);
186
                BSP_LED_Toggle(LED2);
187
188
                HAL Delay(3000);
189
                break:
190
191
            case 3:
192
193
                HAL_GPIO_TogglePin(custom_led_GPIO_Port, custom_led_Pin);
194
                HAL_Delay(4000);
195
                break;
196
197
            default:
198
                break;
199
200
      /* USER CODE END 3 */
202 }
203
```

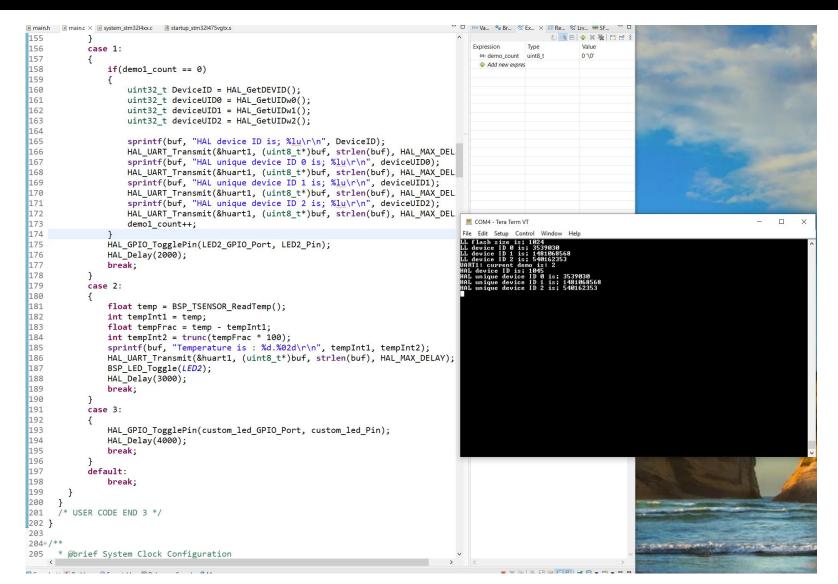
Step 14. Setup the wire connection for demo 4 LED blinking



Step 15. Compile and run the code in debug mode, open tera term and test from demo 1. test is successful, print the flash size and device ID once when entering demo 1 code, and continue blinking LED2 at 1 second interval

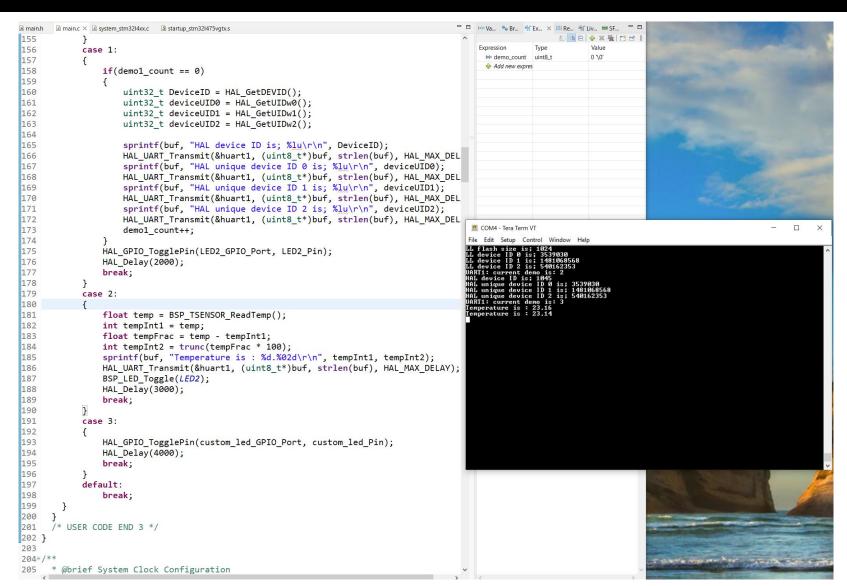


Step 16. Press the user button, we will see HAL device ID and unique ID only print once, and continue blinking LED for 2 seconds interval. Demo 2 success

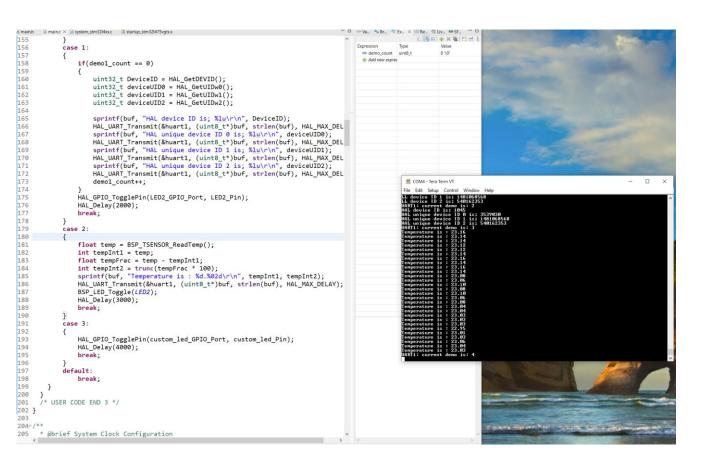


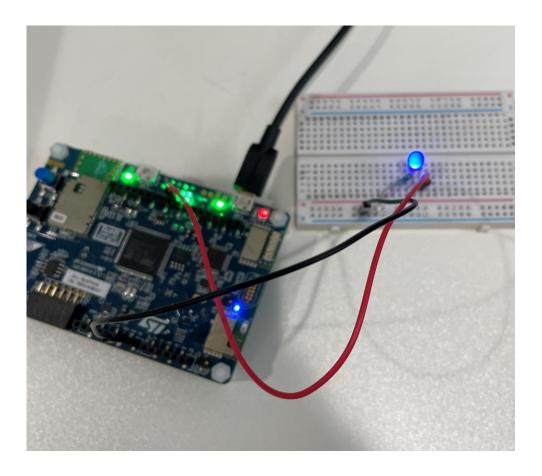
Step 17. Press the user button again, now we can read the temp value and send it through UART1.

Demo 3 success



Step 18. Press the user button again, we can see the external LED blinking at 4 seconds interval. Demo 4 success





Step 19. Press the user button again, it will loop back to demo 1

