UCSD Embedded C Assignment 7

By

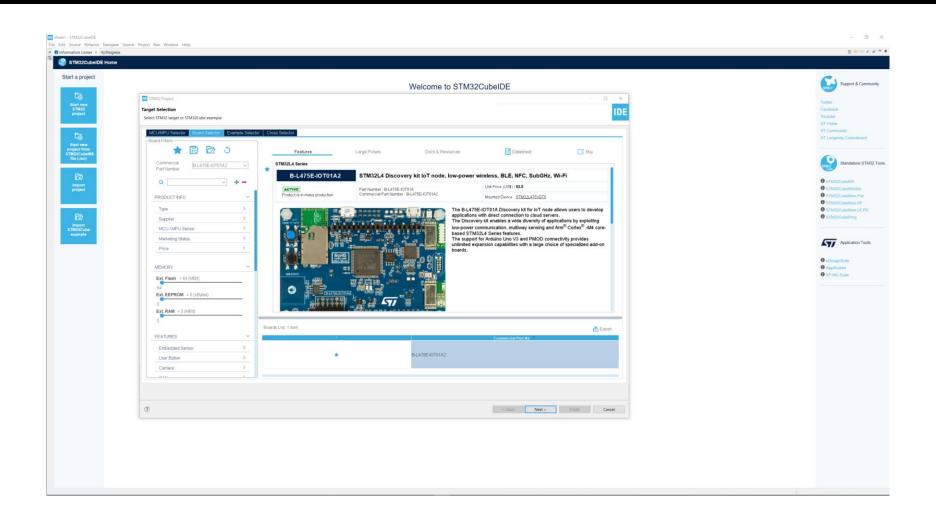
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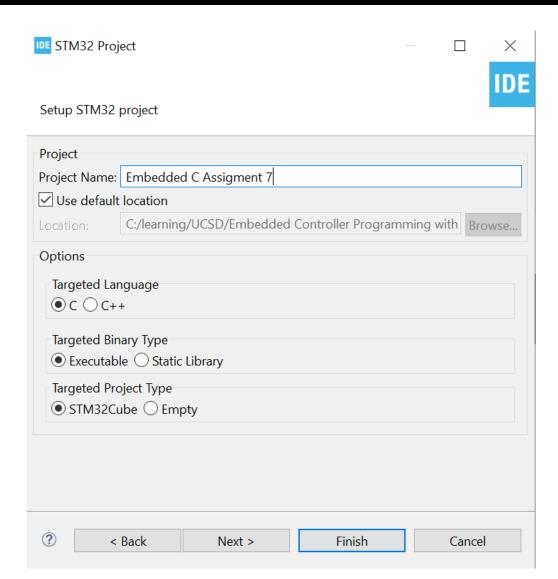
Step 1. Startup STM32CubeIDE and create new STM32 project



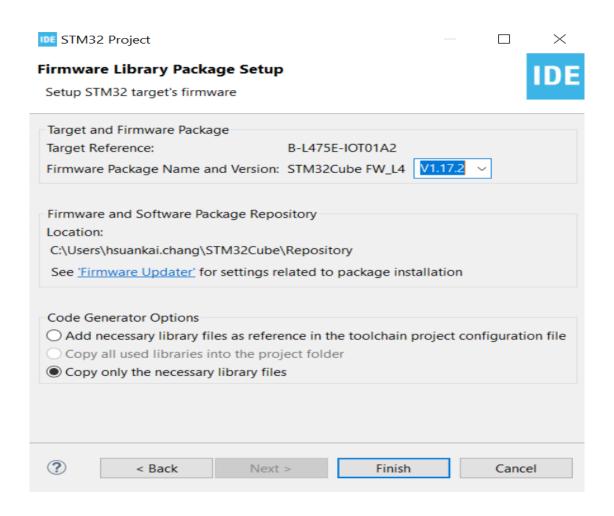
Step 2. Access board selector and type in the board you use, click Next



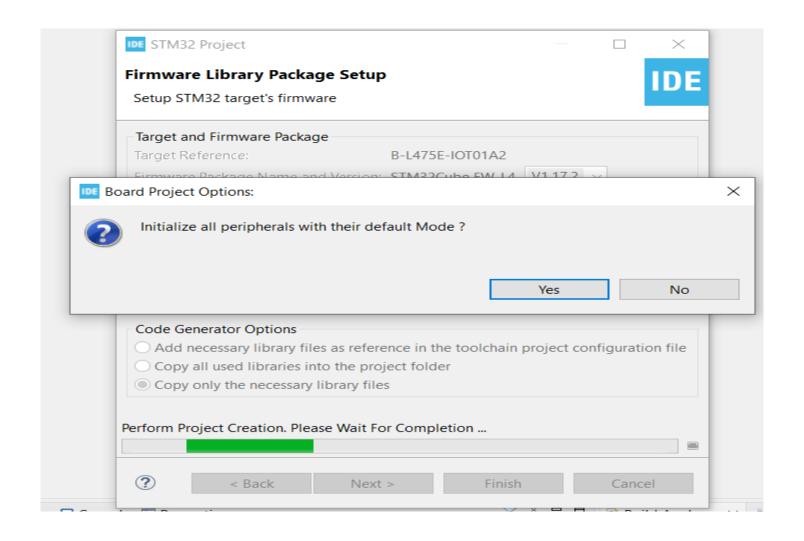
Step 3. Enter the project name then click Next



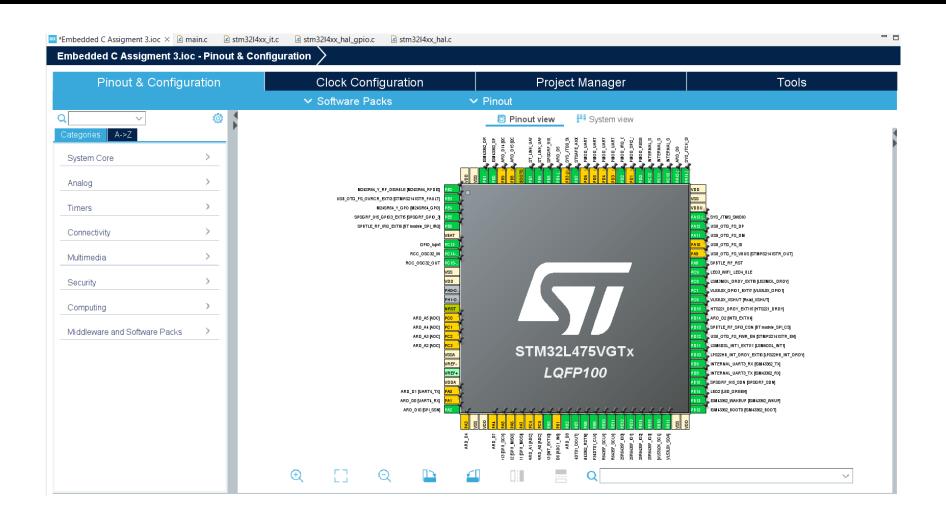
Step 4. See the firmware package name and version



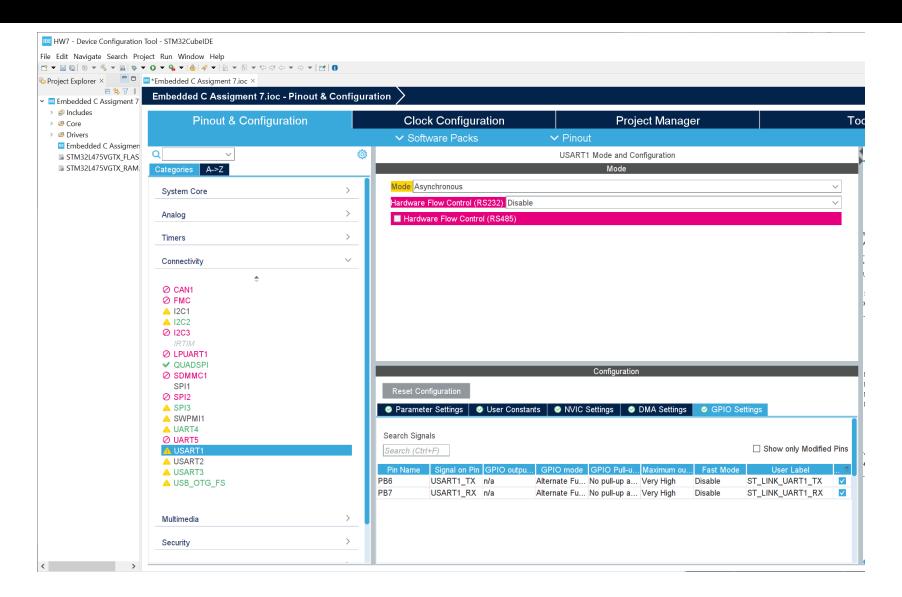
Step 5. Click yes to initialize all peripherals to default



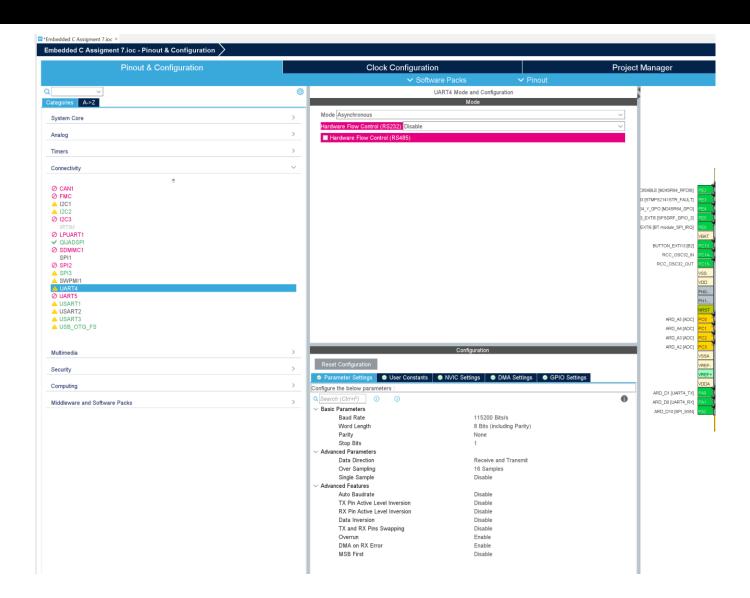
Step 6. When in .ioc file, click Pinout & Configurations



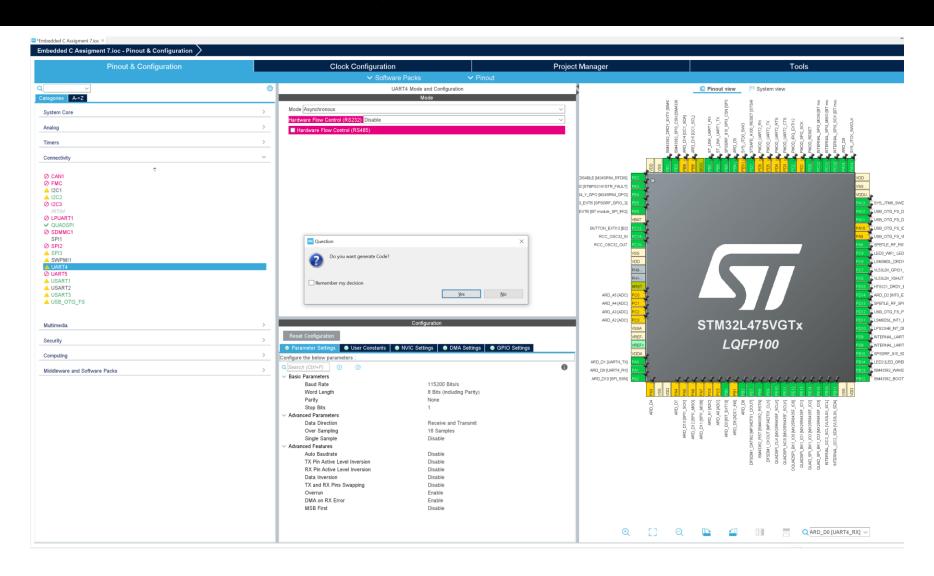
Step 7. Check the setting for USART1



Step 8. Enable UART4 connection



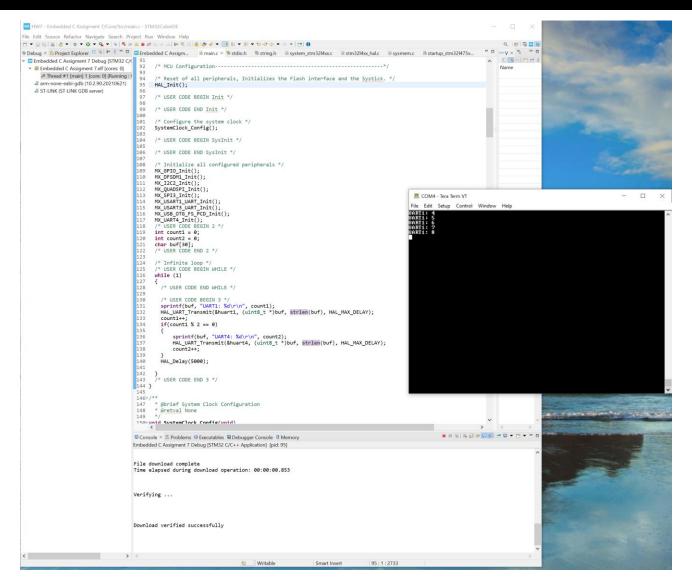
Step 9. Generate code



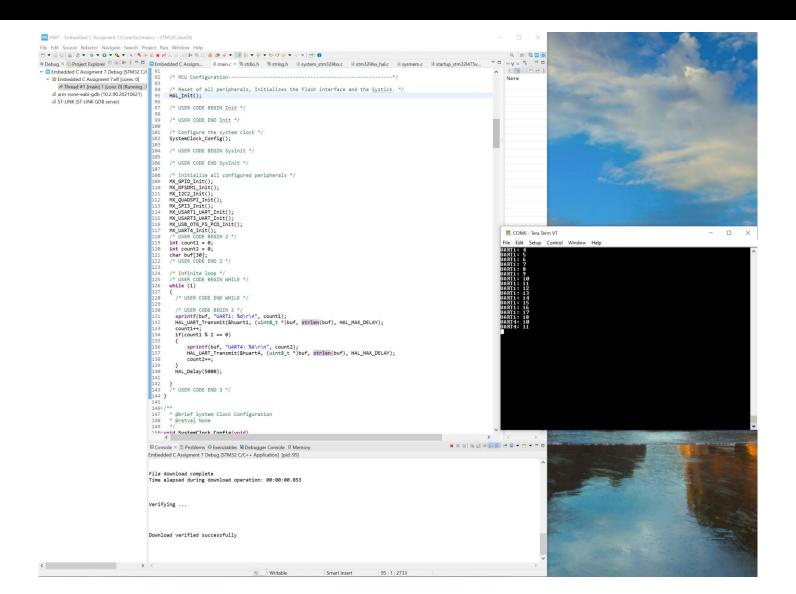
Step 10. In main.c, type the code below to send message to UART1 every 5 second, and to UART4 every 10 seconds

```
/* Reset of all peripherals, Initializes the Flash interface and the Systick. */
 95
     HAL_Init();
 96
 97
     /* USER CODE BEGIN Init */
     /* USER CODE END Init */
100
101
     /* Configure the system clock */
102
     SystemClock_Config();
103
104
    /* USER CODE BEGIN SysInit */
105
106
    /* USER CODE END SysInit */
108
     /* Initialize all configured peripherals */
     MX_GPIO_Init();
109
    MX_DFSDM1_Init();
110
111 MX_I2C2_Init();
112 MX_QUADSPI_Init();
    MX_SPI3_Init();
114 MX USART1 UART Init();
115 MX_USART3_UART_Init();
     MX_USB_OTG_FS_PCD_Init();
117 MX_UART4_Init();
118 /* USER CODE BEGIN 2 */
119 int count1 = 0;
120 int count2 = 0;
121 char buf[30];
     /* USER CODE END 2 */
124
    /* Infinite loop */
     /* USER CODE BEGIN WHILE */
126
      while (1)
       /* USER CODE END WHILE */
128
129
130
       /* USER CODE BEGIN 3 */
       sprintf(buf, "UART1: %d\r\n", count1);
       HAL_UART_Transmit(&huart1, (uint8_t *)buf, strlen(buf), HAL_MAX_DELAY);
133
       count1++;
134
       if(count1 % 2 == 0)
135
136
           sprintf(buf, "UART4: %d\r\n", count2);
137
           HAL_UART_Transmit(&huart4, (uint8_t *)buf, strlen(buf), HAL_MAX_DELAY);
138
           count2++;
139
140
       HAL_Delay(5000);
141
143
      /* USER CODE END 3 */
144 }
145
1469/**
147 * @brief System Clock Configuration
    * @retval None
149
1500 void SystemClock Config(void)
```

Step 11. Build the code, run in debug mode and open Tera Term to see if we can see the UART1 message



Step 12. Switch Teram Term serial port to see if we can UART4 message, test is successful



Appendix. I use USB to UART converter and connect UART4 Rx and Tx to it

