

Computer Vision hw_7

By R01922124 許彥彬

1. Intro of this homework:

This assignment is about to do “thining” to “Lena.bmp” with size 64x64.

Thining includes three parts of steps, Yokoi connectivity, pair relationship and connected shrink. I will discuss them in detail respectively. The neighbor is define as the figure shown below.

x_7	x_2	x_6
x_3	x_0	x_1
x_8	x_4	x_5

Last homework I defined three parameters Q, R, and S as 1, 0 and 2. In this homework there are two more parameters, Q_2, P and they are 0 and 1 respectively.

```
#define Q 1
#define R 0
#define S 2

#define P 1
#define Q_2 0
```

This work includes some functions as follows.

```
void pixel_set(Mat &, int, int, int);
uchar pixel_get(Mat &, int, int);
void binary_image(Mat *, int);
void resize(Mat *, int, int);
int F4(int, int, int, int);
int F4(int, int, int, int, int, int);
int H4(int, int, int, int);
void YokoiConnectivityNumber (Mat&, Mat &);
bool ConnectedShrink (const Mat&, Mat&, Mat& );
void PairRelationship ( const Mat&, Mat& );
void Thinning ( const Mat&, Mat& );
```

2. Resize

I. Code:

```
void resize(Mat *p, int rows, int cols){
    Mat res(rows, cols, p->type());
    int row_scale = p->rows/rows;
    int col_scale = p->cols/cols;
    for(int i=0; i<rows; i++){
        for(int j=0; j<cols; j++){
            pixel_set(res, i, j, pixel_get(*p, i*row_scale, j*col_scale));
        }
    }
    *p=res.clone();
}
```

3. Yoikoi connectivity:

I. Formula:

$$a_1 = h(x_o, x_1, x_6, x_2), \quad a_2 = h(x_o, x_2, x_7, x_3), \quad a_3 = h(x_o, x_3, x_8, x_4), \\ a_4 = h(x_o, x_4, x_5, x_1)$$

$$h(b, c, d, e) = \begin{cases} q, & \text{if } b = c \text{ and } (d \neq b \text{ or } e \neq b) \\ r, & \text{if } b = c \text{ and } (d = b \text{ and } e = b) \\ s, & \text{if } b \neq c \end{cases}$$

$$f(a_1, a_2, a_3, a_4) = \begin{cases} 5, & \text{if } a_1 = a_2 = a_3 = a_4 = r \\ n, & \text{where } n = \#\{a_k | a_k = q\}, \text{ otherwise} \end{cases}$$

II. Code:

```
int H4(int b,int c, int d, int e) {
    if ( b==c && ( d!=b || e!=b ) )
        return Q;
    if ( b==c && d==b && e==b )
        return R;
    if ( b!=c )
        return S;
    return -1;
}

int F4(int a1, int a2, int a3, int a4) {
    if ( a1 == a2 && a1 == a3 && a1==a4 && a1==R ) return S;
    int n=0;
    if ( a1 == Q ) n++;
    if ( a2 == Q ) n++;
    if ( a3 == Q ) n++;
    if ( a4 == Q ) n++;
    return n;
}

void YoikoiConnectivityNumber(Mat &image , Mat &res){
    Mat t_image;
    image.copyTo(t_image);
    int mv[8][2] = { 0,1, -1,0, 0,-1, 1,0, 1,1,-1,1, -1,-1, 1,-1 };
    int x[9],a[4];
    int rows = t_image.rows;
    int cols = t_image.cols;
    int tr,tc;

    image.copyTo(res);

    for(int i=0;i<rows;i++){
        for(int j=0;j<cols;j++){
            pixel_set(res,i,j,255);
        }
    }

    for (int i=0;i<rows;i++){
        for (int j=0;j<cols;j++){
            x[0] = pixel_get(t_image,i,j)/255;
            if (x[0] == 0 ) continue;
            for (int k=0;k<8;k++){
                tr = i+mv[k][0];
                tc = j+mv[k][1];
                if (tr< 0||tr>=rows||tc<0||tc>=cols)
                    x[k+1] = 0;
                else
                    x[k+1] = pixel_get(t_image,tr,tc)/255;
            }
            a[0] = H4(x[0],x[1],x[6],x[2]);
            a[1] = H4(x[0],x[2],x[7],x[3]);
            a[2] = H4(x[0],x[3],x[8],x[4]);
            a[3] = H4(x[0],x[4],x[5],x[1]);
            pixel_set(res,i,j,F4(a[0],a[1],a[2],a[3]));
        }
    }
}
```

4. Pair relationship:

I. Formula:

$$h(a, 1) = \begin{cases} 1, & \text{if } a = 1 \\ 0, & \text{otherwise} \end{cases}$$

$$y = \begin{cases} q, & \text{if } \sum_{n=1}^4 h(x_n, 1) < 1 \text{ or } x_0 \neq 1 \\ p, & \text{if } \sum_{n=1}^4 h(x_n, 1) \geq 1 \text{ and } x_0 \neq 1 \end{cases}$$

II. Code:

```
void PairRelationship ( const Mat& src , Mat& dest ){
    Mat t_image;
    src.copyTo(t_image);
    int mv[8][2] = { 0,1, -1,0, 0,-1, 1,0, 1,1,-1,1, -1,-1, 1,-1 };
    int x[9],a[4];
    int rows = t_image.rows;
    int cols = t_image.cols;
    int tr,tc;

    src.copyTo(dest);
    for ( int i=0 ; i<rows ; i++ ) {
        for ( int j=0 ; j<cols ; j++ ) {
            pixel_set(dest,i,j,255);
        }
    }

    for ( int i=0 ; i<rows ; i++ ) {
        for ( int j=0 ; j<cols ; j++ ) {
            x[0] = pixel_get(t_image,i,j);
            if ( x[0] == 255 )
                continue;
            if ( x[0] == 1 ) {
                int k;
                for ( k=0 ; k<4 ; k++ ) {
                    tr = i+mv[k][0];
                    tc = j+mv[k][1];
                    if ( tr>= 0 && tr<rows && tc>=0 && tc<cols && pixel_get(t_image,tr,tc) == 1)
                        break;
                }
                if ( k<4 ){
                    pixel_set(dest,i,j,P);
                    continue;
                }
                pixel_set(dest,i,j,Q_2);
            }
        }
    }
}
```

Note that there is already a Q in Yokoi connectivity, so I define q in here as Q_2 instead.

5. Connected Shrink

I. Formula:

$$h(b, c, d, e) = \begin{cases} 1, & \text{if } b = c \text{ and } (d \neq b \text{ or } e \neq b) \\ 0, & \text{otherwise} \end{cases}$$

$$f(a_1, a_2, a_3, a_4, x) = \begin{cases} g, & \text{if exactly one of } (a_1, a_2, a_3, a_4) = 1 \\ x, & \text{otherwise} \end{cases}$$

Note that the h function is very similar to Yokoi connectivity. So I will use the same function and do a little modify. If the return number from

H4 is 1 assign 1, else assign 0.

II. Code:

```
int F4(int a1, int a2, int a3, int a4, int g, int x){
    if(a1+a2+a3+a4==1)
        return g;
    else
        return x;
}

bool ConnectedShrink (const Mat& src ,Mat& data, Mat& dest){
    Mat t_image;
    src.copyTo(t_image);
    bool flag = false;
    int mv[8][2] = { 0,1, -1,0, 0,-1, 1,0, 1,1,-1,1, -1,-1, 1,-1 };
    int x[9],a[4];
    int rows = t_image.rows;
    int cols = t_image.cols;
    int tr,tc;

    for ( int i=0 ; i<rows ; i++ ) {
        for ( int j=0 ; j<cols ; j++ ) {
            if ( pixel_get(data,i,j) != P )
                continue;
            x[0]=255;
            for ( int k=0 ; k<8 ; k++ ) {
                tr = i+mv[k][0];
                tc = j+mv[k][1];
                if ( tr< 0 || tr>=rows || tc<0 || tc>=cols )
                    x[k+1] = 0;
                else
                    x[k+1] = pixel_get(t_image,tr,tc);
            }
            a[0] = H4(x[0],x[1],x[6],x[2])<1?1:0;
            a[1] = H4(x[0],x[2],x[7],x[3])<1?1:0;
            a[2] = H4(x[0],x[3],x[8],x[4])<1?1:0;
            a[3] = H4(x[0],x[4],x[5],x[1])<1?1:0;
            int t = F4(a[0],a[1],a[2],a[3],0,255);
            if ( t == 0 )
                flag = true;
            pixel_set(t_image,i,j,t);
        }
    }
    t_image.copyTo(dest);
    return flag;
}
```

6. Thinning Operator

I. Idea: Involve the previous three operators.

II. Code:

```
void Thinning(const Mat& src , Mat& dest){
    Mat data;
    Mat t_image = src.clone();
    bool flag = true;
    binary_image(&t_image,128);
    while ( flag ){
        YokoiConnectivityNumber(t_image,data);
        PairRelationship(data,data);
        flag = ConnectedShrink(t_image,data,dest);
        t_image = dest.clone();
    }
}
```

7. Result:



8. Appendix

I. build_all.sh

“sh build_all.sh” will automatically compile the code in terminal.

II. R01922124_HW7.cpp

source code

III. lena.bmp

original lena image

IV. binary_lena.bmp, thinning_lena.bmp

results for this homework

V. R01922124_HW7.pdf

report