# Map Reduce



#### Last Time ...

- ► MPII/O
- Randomized Algorithms
  - ▶ Parallel *k*-Select
  - ▶ Graph coloring
- ► Assignment 2
- ▶ Questions?

# Today ...

- ▶ Map Reduce
  - Overview
  - ► Matrix multiplication
  - ▶ Complexity theory



# MapReduce programming interface

- Two-stage data processing
  - Data can be divided into many chunks
  - A map task processes input data & generates local results for one or a few chunks
  - A reduce task aggregates & merges local results from multiple map tasks
- Data is always represented as a set of key-value pairs
  - Key helps grouping for the reduce tasks
  - ▶ Though key is not always needed (for some applications, or for the input data), a consistent data represent eases the programming interface



#### Motivation & design principles

- ▶ Fault tolerance
  - Loss of a single node or an entire rack
  - ► Redundant file storage
- ► Files can be enormous
- Files are rarely updated
  - Read data, perform calculations
  - Append rather than modify
- Dominated by communication costs and I/O
  - Computation is cheap compared with data access
- Dominated by input size



#### Example

- Count the occurrences of individual words in bunch of web pages
- Map task: find words in one or a few files
  - Input: <key = page url, value = page content>
  - Output: <key = word, value = word count>
- Reduce task: compute total word counts across multiple files
  - Input/output: <key = word, value = word count>



#### Dependency in MapReduce

- Map tasks are independent from each other, can all run in parallel
- A map task must finish before the reduce task that processes its result
- ▶ In many cases, reduce tasks are commutative
- Acyclic graph model



#### Implementations

- Original mapreduce implementation at Google
  - ► Not publicly available
  - ▶ C/C++
- ▶ Hadoop
  - ▶ Open Source Implementation Yahoo!, Apache
  - Java
- ▶ Phoenix++
  - ▶ Open Source Stanford
  - ► C++ Shared memory



#### Applications that don't fit

- MapReduce supports limited semantics
  - ► The key success of MapReduce depends on the assumption that the dominant part of data processing can be divided into a large number of independent tasks
- What applications don't fit this?
  - ► Those with complex dependencies Gaussian elimination, k-means clustering, iterative methods, n-body problems, graph problems, ...



#### MapReduce

- Map: chunks from DFS → (key, value)
  - ▶ User code to determine (k, v) from chunks (files/data)
- Sort: (k, v) from each map task are collected by a master controller and sorted by key and divided among the reduce tasks
- Reduce: work on one key at a time and combine all the values associated with that key
  - Manner of combination is determined by user code



#### MapReduce – word counting

- ▶ Input → set of documents
- ► Map:
  - reads a document and breaks it into a sequence of words  $w_1, w_2, ..., w_n$
  - Generates (k, v) pairs,  $(w_1, 1), (w_2, 1), ..., (w_n, 1)$
- System:
  - ightharpoonup group all (k, v) by key
  - $\blacktriangleright$  Given r reduce tasks, assign keys to reduce tasks using a hash function
- ► Reduce:
  - Combine the values associated with a given key
  - ▶ Add up all the values associated with the word → total count for that word



#### Parallelism

- Reducers
- Reduce Tasks
- Compute nodes
- Skew (load imbalance)

- Easy to implement
- Hard to get performance



#### Node failures

- Master node fails
  - Restart mapreduce job
- Node with Map worker fails
  - Redo all map tasks assigned to this worker
    - ▶ Set this worker as idle
    - ▶ Inform reduce tasks about change of input location
- ▶ Node with Reduce worker fails
  - ▶ Set the worker as idle



#### Matrix-vector multiplication

- $\triangleright$   $n \times n$  matrix M with entries  $m_{ij}$
- Vector  $\boldsymbol{v}$  of length n with values  $v_i$
- We wish to compute

$$x_i = \sum_{j=1}^n m_{ij} v_j$$

- ightharpoonup If  $oldsymbol{v}$  can fit in memory
  - $\blacktriangleright$  Map: generate  $(i, m_{ij}v_i)$
  - $\blacktriangleright$  Reduce: sum all values of i to produce  $(i, x_i)$
- lacktriangle If  $oldsymbol{v}$  is too large to fit in memory? Stripes? Blocks?
- What if we need to do this iteratively?



#### Matrix-Matrix Multiplication

- $P = MN \rightarrow p_{ik} = \sum_{j} m_{ij} n_{jk}$
- ▶ 2 mapreduce operations
  - ▶ Map 1: produce (k,v),  $\left(j,\left(M,i,m_{ij}\right)\right)$  and  $\left(j,\left(N,k,n_{jk}\right)\right)$
  - ▶ Reduce 1: for each  $j \rightarrow (i, k, m_{ij}, n_{jk})$
  - ▶ Map 2: identity
  - $\blacktriangleright$  Reduce 2: sum all values associated with key (i,k)



#### Matrix-Matrix multiplication

- ► In one mapreduce step
- ► Map:
  - ▶ generate  $(k, v) \rightarrow ((i, k), (M, j, m_{ij})) & ((i, k), (N, j, n_{jk}))$
- ▶ Reduce:
  - ▶ each key (i,k) will have values  $\left((i,k),\left(M,j,m_{ij}\right)\right)$  &  $\left((i,k),\left(N,j,n_{jk}\right)\right)$   $\forall j$
  - $\triangleright$  Sort all values by j
  - $\blacktriangleright$  Extract  $m_{ij}$  &  $n_{jk}$  and multiply, accumulate the sum



# Complexity Theory for mapreduce



#### Communication cost

- Communication cost of a task is the size of the input to the task
- We do not consider the amount of time it takes each task to execute when estimating the running time of an algorithm
- The algorithm output is rarely large compared with the input or the intermediate data produced by the algorithm



#### Reducer size & Replication rate

- $\blacktriangleright$  Reducer size (q)
  - Upper bound on the number of values that are allowed to appear in the list associated with a single key
    - ▶ By making the reducer size small, we can force there to be many reducers
      - ► High parallelism → low wall-clock time
    - ▶ By choosing a small q we can perform the computation associated with a single reducer entirely in the main memory of the compute node
      - ▶ Low synchronization (Comm/IO) → low wall clock time
- ightharpoonup Replication rate (r)
  - $\blacktriangleright$  number of (k,v) pairs produced by all the Map tasks on all the inputs, divided by the number of inputs
  - $\triangleright$  r is the average communication from Map tasks to Reduce tasks



# Example: one-pass matrix mult

- $\blacktriangleright$  Assume matrices are  $n \times n$
- ightharpoonup r replication rate
  - ▶ Each element  $m_{ij}$  produces n keys
  - ightharpoonup Similarly each  $n_{jk}$  produces n keys
  - $\blacktriangleright$  Each input produces exactly n keys  $\rightarrow$  load balance
- ▶ q reducer size
  - $\blacktriangleright$  Each key has n values from M and n values from N
  - **▶** 2*n*



#### Example: two-pass matrix mult

- $\blacktriangleright$  Assume matrices are  $n \times n$
- ightharpoonup r replication rate
  - $\blacktriangleright$  Each element  $m_{ij}$  produces 1 key
  - ightharpoonup Similarly each  $n_{jk}$  produces 1 key
  - Each input produces exactly 1 key (2<sup>nd</sup> pass)
- ▶ q reducer size
  - $\blacktriangleright$  Each key has n values from M and n values from N
  - $\triangleright$  2n (1st pass), n (2nd pass)



### Real world example: Similarity Joins

- ▶ Given a large set of elements X and a similarity measure s(x,y)
- ightharpoonup Output: pairs whose similarity exceeds a given threshold t
- $\blacktriangleright$  Example: given a database of  $10^6$  images of size 1MB each, find pairs of images that are similar
- Input:  $(i, P_i)$ , where i is an ID for the picture and  $P_i$  is the image
- ▶ Output:  $(P_i, P_j)$  or simply (i, j) for those pairs where  $s(P_i, P_j) > t$



#### Approach 1

 $\blacktriangleright$  Map: generate (k,v)

$$((i,j),(P_i,P_j))$$

- ▶ Reduce:
  - Apply similarity function to each value (image pair)
  - Output pair if similarity above threshold t
- ▶ Reducer size  $-q \rightarrow 2$  (2MB)
- ▶ Replication rate  $r \rightarrow 10^6 1$
- ▶ Total communication from map→reduce tasks?
  - ▶  $10^6 \times 10^6 \times 10^6$  bytes  $\rightarrow 10^{18}$  bytes  $\rightarrow$  1 Exabyte (kB MB GB TB PB EB)
  - ► Communicate over GigE  $\rightarrow$  10<sup>10</sup> sec  $\rightarrow$  300 years



#### Approach 2: group images

- ▶ Group images into g groups with  $\frac{10^6}{g}$  images each
- $\blacktriangleright$  Map: Take input element  $(i, P_i)$  and generate
  - ▶ (g-1) keys  $(u,v) | P_i \in \mathcal{G}(u), v \in \{1,...,g\} \setminus \{u\}$
  - $\blacktriangleright$  Associated value is  $(i, P_i)$
- ightharpoonup Reduce: consider key (u, v)
  - ▶ Associated list will have  $2 \times \frac{10^6}{g}$  elements  $(j, P_j)$
  - ▶ Take each  $(i, P_i)$  and  $(j, P_j)$  where i, j belong to different groups and compute  $s(P_i, P_j)$
  - Compare pictures belonging to the same group
    - ▶ heuristic for who does this, say reducer for key (u, u + 1)



#### Approach 2: group images

- ▶ Replication rate: r = g 1
- ▶ Reducer size:  $q = 2 \times 10^6/g$
- ▶ Input size:  $2 \times 10^{12}/g$  bytes
- ▶ Say g = 1000,
  - ▶ Input is 2GB
  - ▶ Total communication:  $10^6 \times 999 \times 10^6 = 10^{15}$  bytes → 1 petabyte

