

2D Compressible MHD Code for Tearing Mode

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Abstract

To get more experience on coding fluid codes, I try to write this 2D compressible MHD code for tearing mode (magnetic reconnection).

In fact, I wrote the first version of this code in June 2010. Unfortunately, it doesn't work well. The framework of this code is from [Fu1995], section 7.4 and Appendix 2.

1 2D Compressible MHD Equations

All variables are in (x, z) plane, $\partial/\partial y=0$.

1.1 Original equations

Original equations (no Hall term, η, γ, ν constants):

$$\begin{aligned}\frac{\partial \rho}{\partial t} &= -\mathbf{u} \cdot \nabla \rho - \rho \nabla \cdot \mathbf{u}, \\ \frac{\partial p}{\partial t} &= -\mathbf{u} \cdot \nabla p - \gamma p \nabla \cdot \mathbf{u}, \\ \rho \frac{\partial \mathbf{u}}{\partial t} &= -\rho \mathbf{u} \cdot \nabla \mathbf{u} - \nabla p - \frac{1}{\mu_0} \nabla \frac{B^2}{2} + \frac{1}{\mu_0} \mathbf{B} \cdot \nabla \mathbf{B} + \nu \nabla^2 \mathbf{u}, \\ \frac{\partial \mathbf{B}}{\partial t} &= \underbrace{\nabla \times (\mathbf{u} \times \mathbf{B})}_{-\mathbf{u} \cdot \nabla \mathbf{B} - \mathbf{B} \cdot \nabla \mathbf{u} + \mathbf{B} \cdot \nabla \mathbf{u}} - \underbrace{\nabla \times [\eta (\nabla \times \mathbf{B})]}_{\eta \nabla^2 \mathbf{B}}.\end{aligned}\tag{0.1}$$

Where, we have used,

$$\begin{aligned}\nabla \times \mathbf{E} &= -\frac{\partial \mathbf{B}}{\partial t}, \\ \mathbf{J} &= \nabla \times \mathbf{B}, \\ \mathbf{E} &= -\mathbf{u} \times \mathbf{B} + \eta \mathbf{J}.\end{aligned}\tag{0.2}$$

Here, considering that $\nabla \cdot \mathbf{B}=0$, we use A_y instead of \mathbf{B} , i.e.,

$$\mathbf{B} = \nabla \times \mathbf{A} = \nabla \times (0, A_y, 0) = (-\partial A_y / \partial z, 0, \partial A_y / \partial x).\tag{0.3}$$

And the last equation in (0.1) changes to,

$$\nabla \times \left(\frac{\partial \mathbf{A}}{\partial t} \right) = \nabla \times \left\{ \mathbf{u} \times (\nabla \times \mathbf{A}) - \eta [\nabla \times (\nabla \times \mathbf{A})] \right\}, \quad (0.4)$$

Or,

$$\frac{\partial \mathbf{A}}{\partial t} = \mathbf{u} \times (\nabla \times \mathbf{A}) - \eta [\nabla \times (\nabla \times \mathbf{A})]. \quad (0.5)$$

Rewrite (0.1) and (0.5) to explicit form in 2D (with normalization),

$$\begin{aligned} \frac{\partial \rho}{\partial t} &= -u_x \frac{\partial \rho}{\partial x} - u_z \frac{\partial \rho}{\partial z} - \rho \left(\frac{\partial u_x}{\partial x} + \frac{\partial u_z}{\partial z} \right), \\ \frac{\partial p}{\partial t} &= -u_x \frac{\partial p}{\partial x} - u_z \frac{\partial p}{\partial z} - \gamma p \left(\frac{\partial u_x}{\partial x} + \frac{\partial u_z}{\partial z} \right), \\ \frac{\partial u_x}{\partial t} &= -u_x \frac{\partial u_x}{\partial x} - u_z \frac{\partial u_x}{\partial z} - \frac{1}{\rho} \frac{\partial}{\partial x} \left(p + \frac{B^2}{2} \right) + \frac{1}{\rho} \left(B_x \frac{\partial B_x}{\partial x} + B_z \frac{\partial B_x}{\partial z} \right) + \frac{1}{\rho} v_m \left(\frac{\partial^2 u_x}{\partial x^2} + \frac{\partial^2 u_x}{\partial z^2} \right), \\ \frac{\partial u_z}{\partial t} &= -u_x \frac{\partial u_z}{\partial x} - u_z \frac{\partial u_z}{\partial z} - \frac{1}{\rho} \frac{\partial}{\partial z} \left(p + \frac{B^2}{2} \right) + \frac{1}{\rho} \left(B_x \frac{\partial B_z}{\partial x} + B_z \frac{\partial B_z}{\partial z} \right) + \frac{1}{\rho} v_m \left(\frac{\partial^2 u_z}{\partial x^2} + \frac{\partial^2 u_z}{\partial z^2} \right), \\ \frac{\partial A_y}{\partial t} &= -u_x \frac{\partial A_y}{\partial x} - u_z \frac{\partial A_y}{\partial z} + \eta_m \left[\frac{\partial^2 A_y}{\partial x^2} + \frac{\partial^2 A_y}{\partial z^2} \right]. \end{aligned} \quad (0.6)$$

1.2 Normalization

In (0.6), the normalization for density, pressure, length, magnetic field, velocity and time are $\rho_0, p_0, L_0, B_0, u_A = B_0 / \sqrt{\mu_0 \rho_0}, \tau_A = L_0 / u_A$, respectively.

Parameters are

$$v_m \rightarrow \frac{v}{u_A L_0 \rho_0}, \quad \eta_m \rightarrow \frac{\eta}{u_A L_0} \quad (0.7)$$

Lundquist number $S = 1 / \eta_m$.

1.3 Discrete

In the right hand side of (0.6), for spatial derivative, we use

$$\begin{aligned} \frac{\partial f}{\partial x} &\rightarrow \frac{f_{i+1} - f_{i-1}}{2\Delta x}, \\ \frac{\partial f}{\partial z} &\rightarrow \frac{f_{j+1} - f_{j-1}}{2\Delta z}, \\ \frac{\partial^2 f}{\partial x^2} &\rightarrow \frac{f_{i+1} + f_{i-1} - 2f_i}{\Delta x^2}, \\ \frac{\partial^2 f}{\partial z^2} &\rightarrow \frac{f_{j+1} + f_{j-1} - 2f_j}{\Delta z^2}. \end{aligned} \quad (0.8)$$

In the left hand side, for time derivative, we use 4-th order Runge-Kutta scheme.

2 Code Structure

Variables array $x(ni,nj,5)$, for ρ, p, u_x, u_z, A_y , respectively.

3 Simulation Results

4 References

[Fu1995] 傅竹风 & 胡友秋, 空间等离子体数值模拟, 安徽科学技术出版社, 1995.

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