

# Clustering in Block Markov Chains

Fundamental limits and algorithms

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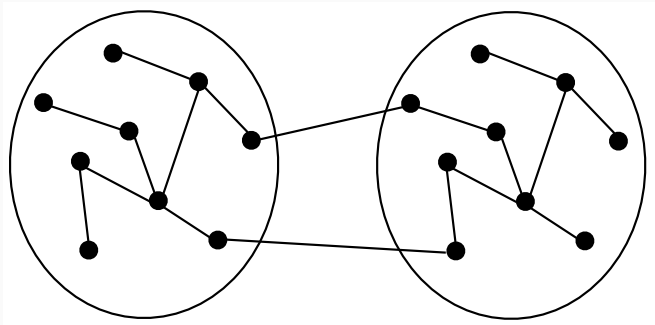
# Introduction

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# Community Detection

## Social networks

- facebook, twitter, .....
- Social graph



- How to find hidden community from the given graph

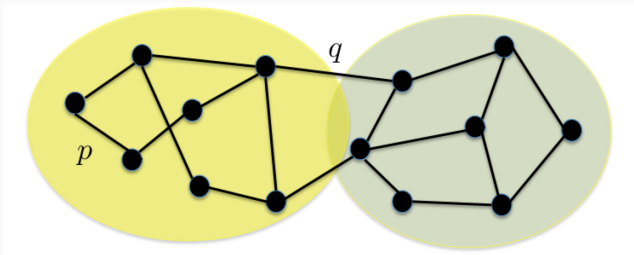
# Stochastic Block Model

## Objective

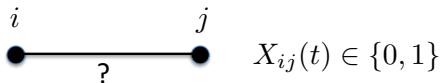
What is the minimum number of misclassified nodes when detecting communities from a graph? [Holland et al, 83],..., [Abbe 18]

## Random Graph Model

All edges are independent.



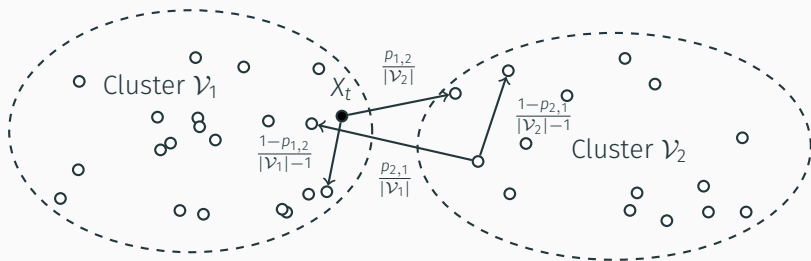
# Stochastic Block Model with Sampling [COLT2014]



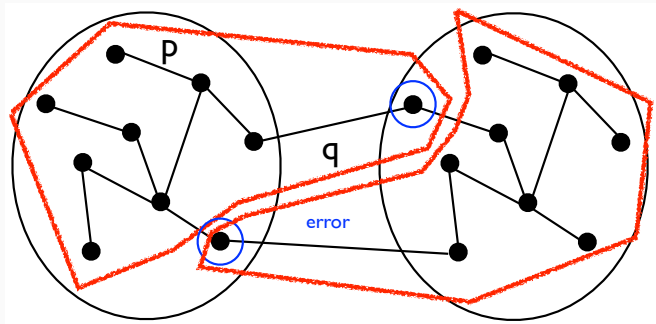
- At round  $t$ , sample node pair  $(i, j)$ , and observe a random independent outcome
- Outcome follows Bernoulli with mean  $p$  if nodes are in the same cluster,  $q$  otherwise with  $q < p$
- Budget:  $T$  observations
- Different sampling strategies: Random sampling and Adaptive sampling
- Remark: talks so far are for random sampling w/o replacement, and  $T = \frac{n(n-1)}{2}$

## Objective

What is the minimum number of misclassified states when detecting communities from a sample path?



# Problem





# SBM Analysis

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## Assumptions:

- $\bar{p} = o(1)$  and  $\bar{p}n = \omega(1)$
- Homogeneity:  $\exists \eta > 0 : \forall i, j, k, \frac{p_{ij}}{p_{ik}} \leq \eta$
- Separation:  $\exists \epsilon > 0 : \forall i \neq j, \sum_k (p_{ik} - p_{jk})^2 \geq \epsilon \bar{p}^2$

## Notations:

- Divergence between  $p(i)$  and  $p(j)$ :

$$D_{L+}(\alpha, p(i), p(j)) = \min_{y \in \mathcal{P}^K} \max_{a \in \{i, j\}} \sum_k \alpha_k \text{KL}(y_k, p_{ak})$$

- Divergence of the model:  $D(\alpha, p) = \min_{i, j: i \neq j} D_{L+}(\alpha, p(i), p(j))$

# Random Sampling

Spectral Algorithm+ [NeurIPS 2016]

**Step 1.** Input: matrices  $A$  ( $A_{vw} = 1$  iff  $(v, w)$  is connected)

1. Trimming + Spectral method (PI+SV thresholding)
2. Output  $S_1, \dots, S_{\hat{K}}$

**Step 2.** Input:  $A$ , and  $S_1, \dots, S_{\hat{K}}$

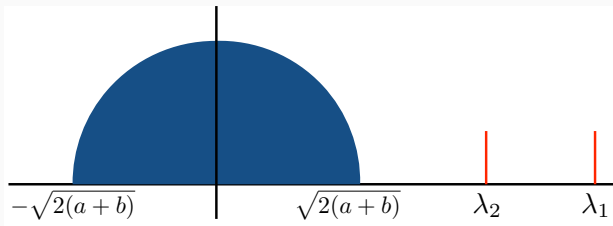
1. Estimate  $p$ :  $\hat{p}_{ij} \leftarrow \frac{\sum_{u \in S_i} \sum_{v \in S_j} A_{uv}}{|S_i||S_j|}$
2.  $\lceil \log(n) \rceil$  improvement iterations: in each iteration, for all  $v$ , assign  $v$  to

$$\arg \max_k \sum_i \sum_{w \in S_i} A_{vw} \log \hat{p}_{ki}$$

# Eigen values of adjacent matrix $A$

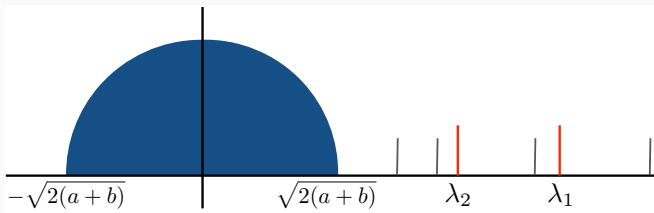
Example: 2 clusters with equal sizes,  $np = a$ ,  $nq = b$ .

- Eigen values of  $A$  and two separated eigen values
  - $z_1 = \frac{1}{2}(a - b) + \frac{a+b}{a-b}$  and  $z_2 = \frac{1}{2}(a + b) + 1$
  - $z_1$  appears only if  $(a - b)^2 > 2(a + b)$
  - Eigen vector of  $z_1$  :  $\frac{\theta}{\sqrt{n}}u + \frac{1-\theta^2}{\sqrt{n}}\mathcal{N}(0, 1)$  where  $\theta^2 = \frac{(a-b)^2 - 2(a+b)}{(a-b)^2}$



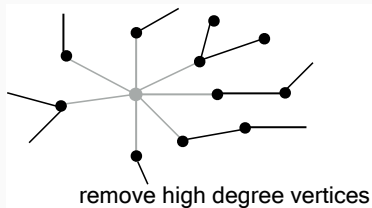
# Noise on eigenvalues

- The case of  $d < \log n$  is more challenging
  - The graph becomes less regular
  - Even if  $a$  and  $b$  are constants, there exists  $\Omega\left(\frac{\log n}{\log \log n}\right)$  degree vertex
  - The largest eigenvalue becomes  $\Omega\left(\sqrt{\frac{\log n}{\log \log n}}\right)$  (the largest eigenvalue of  $n$ -star graph  $\approx \sqrt{n}$ )
  - Impossible to pick  $\lambda_1$  and  $\lambda_2$



# Trimming

- Pre-process (trimming)



- Trimming of Erdős-Rényi graph
  - Consider a ER graph with average degree  $d$
  - Trimming : remove all the vertices of degree greater than  $(1 + \varepsilon)d$
  - Let  $A'$  be the adjacent matrix after trimming

**Theorem (Feige, Ofek '05)**

*The second largest singular value of  $A'$  is less than  $c\sqrt{d}$*

**Theorem 1** *Let  $s = o(n)$ . If  $\liminf_{n \rightarrow \infty} \frac{nD(\alpha, p)}{\log(n/s)} \geq 1$ , then the SP algorithm misclassifies at most  $s$  nodes with high probability.*

**Remark 1:** This result covers exact detection ( $s = 1$ ).

**Remark 2:** SP runs in  $O(\bar{p}n^2 \log(n))$ , and does not need to know  $K$  nor  $(\alpha, p)$

**Proof:** Key ingredients

- The spectral norm of the random observation matrix
- Chernoff-Hoeffding's inequality to understand the number of connections to each cluster
- *i.i.d observations*

## Spectral Analysis

It is very important to understand the spectral norm of  $A - \mathbb{E}[A]$

Some works study  $\sup_{x \in \mathbb{R}^n: \|x\|_2=1} \|(A - \mathbb{E}[A])x\|_\infty$

## Greedy Improvement

Concentration inequalities are very important!



# Inference Limits in the SBM

**Theorem 2** Let  $s = o(n)$ . If there exists a clustering algorithm  $\pi$  such that  $\limsup_{n \rightarrow \infty} \mathbb{E}[\varepsilon^\pi(n)]/s \leq 1$ , then:

$$\liminf_{n \rightarrow \infty} \frac{nD(\alpha, p)}{\log(n/s)} \geq 1$$

Hence, the average number of misclassified nodes should scale at least as  $n \exp(-nD(\alpha, p)(1 + o(1)))$

**Theorem 3** If there exists a clustering algorithm classifying each node correctly with high probability, then:

$$\liminf_{n \rightarrow \infty} \frac{nD(\alpha, p)}{\log(n)} \geq 1$$

# Adaptive Sampling

Adaptive Spectral Algorithm [NeurIPS 2019]

**Step 1.** Randomly sample  $\delta T$  edges with a small  $\delta > 0$  and run the spectral clustering algorithm to extract the first guess  $\mathcal{S}_1, \dots, \mathcal{S}_K$ .

**Step 2.** Estimate SBM parameters  $\alpha$  and  $p$

**Step 3.** Solve the LP  $D^A(p, \alpha) = \max_{x \in \mathcal{X}(\alpha)} D(x, p)$

**Step 4.** Sample edges between  $v \in \mathcal{S}_i$  and  $\mathcal{S}_j$  using  $2(1 - 2\delta)x_{ij}\frac{T}{n}$  budget and classify nodes

**Step 5.** Use the remaining budgets to classify unclear nodes

# New Divergence for Adaptive Sampling

We can control the sampling sequence.

**New Divergence:**

$D^A(\mathbf{p}, \boldsymbol{\alpha})$  is defined as:  $D^A(\mathbf{p}, \boldsymbol{\alpha}) = \max_{\mathbf{x} \in \mathcal{X}(\boldsymbol{\alpha})} D(\mathbf{x}, \mathbf{p})$ ,

with  $D(\mathbf{x}, \mathbf{p}) = \min_{i,j:i \neq j} \sum_{k=1}^K x_{ik} \text{KL}(p_{ik}, p_{jk})$  and

$$\mathcal{X}(\boldsymbol{\alpha}) = \left\{ \mathbf{x} = [x_{ij}] : \alpha_i x_{ij} = \alpha_j x_{ji}, \sum_{i=1}^K \alpha_i \sum_{j=1}^K x_{ij} = 1, \text{ and } x_{ij} \geq 0, \forall i, j \right\},$$

# Inference Limits in the SBM with Adaptive Sampling

**Theorem 4** *Let  $s = o(n)$ . If there exists a clustering algorithm  $\pi$  such that  $\varepsilon^\pi(n) \leq s$  with high probability, then:*

$$\liminf_{n \rightarrow \infty} \frac{2TD^A(\mathbf{p}, \boldsymbol{\alpha})}{n \log(n/s)} \geq 1.$$

**Theorem 5** *Let  $s = o(n)$ . Adaptive Spectral Algorithm guarantee that  $\varepsilon^\pi(n) \leq s$  with high probability, when*

$$\liminf_{n \rightarrow \infty} \frac{2TD^A(\mathbf{p}, \boldsymbol{\alpha})}{n \log(n/s)} \geq 1.$$

# Block Markov Chain

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# Mixing time

Analyzing and bounding the **mixing time** of a BMC is crucial.

Without mixing within  $T$  time steps, we would not expect to be able to cluster.

We define  $d(t) \triangleq \sup_{x \in \mathcal{V}} \{d_{\text{TV}}(P_{x,\cdot}^t, \Pi)\}$  and  $t_{\text{mix}}(\varepsilon) \triangleq \min\{t \geq 0 : d(t) \leq \varepsilon\}$ , where

$$d_{\text{TV}}(\mu, \nu) \triangleq \frac{1}{2} \sum_{x \in \mathcal{V}} |\mu_x - \nu_x|. \quad (1)$$

**Proposition 1** *There exists a strictly positive absolute constant  $c_{\text{mix}}$  such that  $t_{\text{mix}}(\varepsilon) \leq -c_{\text{mix}} \ln \varepsilon$ , for every BMC of finite size  $n \geq K$ .*

# Mixing Time for Block Markov Chain

Let  $\alpha_i n$  is the number of nodes in  $\mathcal{V}_i$ . The transition matrix is

$$P_{x,y} = \frac{p_{\sigma(x),\sigma(y)}}{|V_{\sigma(y)}|} \quad \text{for all } x, y \in \mathcal{V}.$$

Let  $\alpha_{\min} = \min_k \alpha_k$  and  $\eta = \max_{a,b,c} \{p_{b,a}/p_{c,a}, p_{a,b}/p_{a,c}\}$ .

**Proposition 1** For any BMC with  $n \geq 4/\alpha_{\min}$ ,  $t_{\text{mix}}(\epsilon) \leq -c_{\text{mix}} \log \epsilon$ , where  $c_{\text{mix}} = -1/\log(1 - 1/2\eta)$ .

# Information theoretical lower bound

For  $\alpha \in \Delta^{K-1}$  and  $p \in \Delta^{(K-1) \times K}$ , let

$$I(\alpha, p) \triangleq \min_{a \neq b} \left\{ \sum_{k=1}^K \frac{1}{\alpha_a} \left( \pi_a p_{a,k} \ln \frac{p_{a,k}}{p_{b,k}} + \pi_k p_{k,a} \ln \frac{p_{k,a} \alpha_b}{p_{k,b} \alpha_a} \right) + \left( \frac{\pi_b}{\alpha_b} - \frac{\pi_a}{\alpha_a} \right) \right\}. \quad (2)$$

Here  $\pi$  denotes the solution to  $\pi^T p = \pi^T$ .

**Theorem 6** *Let  $s = o(n)$ . If there exists a clustering algorithm  $\pi$  such that  $\limsup_{n \rightarrow \infty} \mathbb{E}[\varepsilon^\pi(n)]/s \geq 1$ , then:*

$$\liminf_{n \rightarrow \infty} \frac{(T/n)I(\alpha, p)}{\log(n/s)} \geq 1$$



The error lower bounds are tight! Spectral Algorithm+ [AOS 2020]

**Step 1.** Input: matrices  $A$

1. Trimming + Spectral method (PI+SV thresholding)
2. Output  $S_1, \dots, S_{\hat{K}}$

**Step 2.** Input:  $A$ , and  $S_1, \dots, S_{\hat{K}}$

1. Estimate  $p$ :  $\hat{p}(i, j) \leftarrow \frac{\sum_{u \in S_i} \sum_{v \in S_j} A_{uv}}{|S_j|}$
2.  $\lceil \log(n) \rceil$  improvement iterations: in each iteration, for all  $v$ , assign  $v$  to

$$\arg \max_c \left\{ \sum_{k=1}^K \left( \hat{N}_{x, \hat{v}_k} \ln \hat{p}(c, k) + \hat{N}_{\hat{v}_k, x} \ln \frac{\hat{p}(k, c)}{\hat{\alpha}_c} \right) - \frac{T}{n} \cdot \frac{\hat{\pi}_c}{\hat{\alpha}_c} \right\}$$

**Theorem 7** Let  $s = o(n)$ . If  $\liminf_{n \rightarrow \infty} \frac{(T/n)I(\alpha, p)}{\log(n/s)} \geq C$  with a constant  $C > 0$ , then the SP algorithm misclassifies at most  $s$  nodes with high probability.

**Remark 1:** This result is not tight. Here,  $C < 1$ .

**Remark 2:** We utilize concentration inequalities for Markov chains, but they are not enough to make the tight result.

$$\sum_{k=1}^K (\hat{N}_{x, \nu_k} \ln p_{c,k} + \hat{N}_{\nu_k, x} \ln \frac{p_{k,c}}{\alpha_c}) - \frac{T}{n} \cdot \frac{\pi_c}{\alpha_c}$$

# Concentration Inequalities for Markov Chains

[D. Paulin, 2015] Let  $X_1, \dots$ , be a Markov chain with transition matrix  $P$ . Let  $\Pi$  be the stationary distribution. Let  $f \in L^2(\Pi)$  with  $|f(x) - \mathbb{E}_\Pi(f)| < C$  for every  $x \in \Omega$  and some constant  $C > 0$ . Let  $V_f$  be the variance of  $f(X)$  when  $X$  follows the stationary distribution  $\Pi$ . Then, for any  $z > 0$ ,

$$\mathbb{P}_\Pi \left( \left| \sum_{t=1}^T f(X_t) - \mathbb{E}_\Pi \left[ \sum_{t=1}^T f(X_t) \right] \right| \geq z \right) \leq 2 \exp \left( - \frac{z^2 \gamma_{ps}}{8(T + 1/\gamma_{ps})V_f + 20zC} \right),$$

where

$$\gamma_{ps} = \max_{i \geq 1} \frac{1 - \lambda((P^*)^i P^i)}{i} \geq \frac{1 - \epsilon}{t_{\text{mix}}(\epsilon/2)} \quad \text{with} \quad P^*(x, y) = \frac{P(x, y)}{\Pi(x)} \Pi(y).$$

The block Markov chain has

$$\gamma_{ps} \geq \frac{1}{2(t_{\text{mix}}(1/4) + 1)} \geq \frac{1}{2(4\eta + 1)}.$$

Therefore, from the concentration inequality for Markov chains by Paulin,

$$\mathbb{P} \left( |\hat{N}_{\mathcal{A}, \mathcal{B}} - N_{\mathcal{A}, \mathcal{B}}| \geq c\sqrt{nT} \right) \leq 2 \exp \left( -\frac{c^2}{16(4\eta + 1)} n(1 + o(1)) \right),$$

which can analyze the accuracy of parameter estimations.

## Conclusion

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- The stochastic block model (SBM) is a natural performance benchmark for community detection.
- We address the finer and more challenging question of determining, under the general LSBM, the minimal number of misclassified items given the parameters of the model.
- We extend our results to the block Markov chain model.
- The results for the block Markov chain model is not tight. To obtain the tightness, it is necessary to derive a much better concentration inequality for the Markov chain sample path.

Thank you!

Questions?