SiamMask++: More accurate object tracking through layer wise aggregation in Visual Object Tracking

Hyunbin Choi^a, Yungseop Lee^b and Changwon Lim^a

- a. Department of Applied Statistics, Chung-Ang University
 - b. Department of Statistics, Dongguk University

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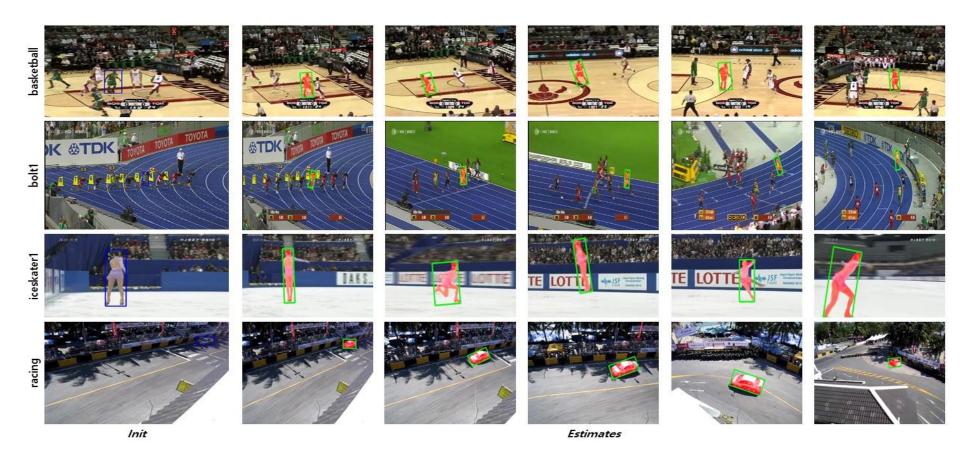
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- Problem. Track an arbitrary object with the sole input of a single bounding box in the first frame of the video
- Challenge: we need to be class-agnostic

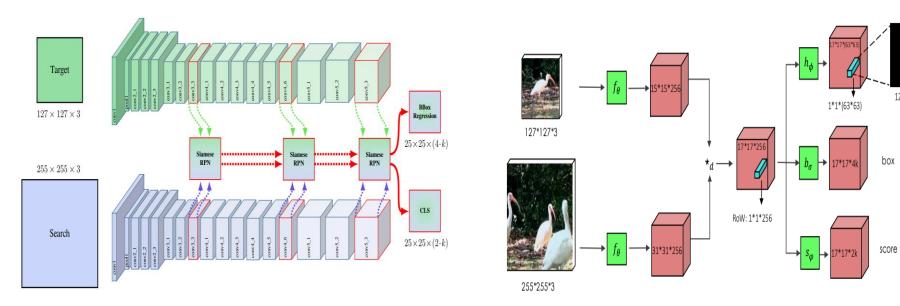


Example of the VOT2019 datasets and tracking results of our model, SiamMask++.





- SiamFC (Bertinetto et al., 2016): Introducing Siamese Network for the first time as a VOT task
- SiamRPN (Li et al., 2018): To achieve better performance, they apply the RPN module used for object detection to SiamFC
- SiamRPN++ (Li et al., 2019): Upgraded SiamRPN with the introduction of Deep Network and the introduction of layer-wise aggregation method
- **SiamMask** (Wang et al., 2019): MASK module was introduced for more sophisticated object tracking based on SiamRPN, and **mask** (segmentation) based tracking was introduced in VOT



The proposed framework of SiamRPN++. (Li et al., 2019)

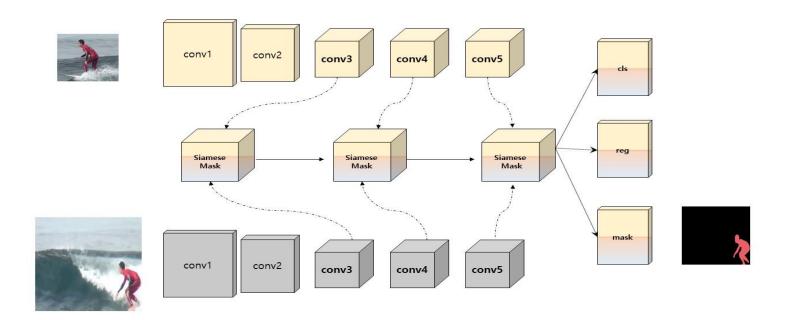
Schematic illustration of SiamMask variants. (Wang et al., 2019)





- SiamMask, a mask (segmentation) based tracker that is required in the future, is used as a benchmarking model
- Layer-wise aggregation and application of methodologies introduced in SiamRPN++
- Can explain the effectiveness of methodologies introduced by ablation experiments



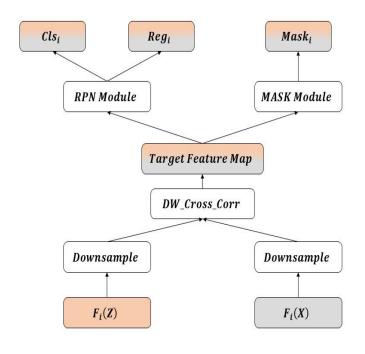


Our proposed framework (SiamMask++). Given target image and search image, the network fusion the outputs from several SiamMask blocks to output dense predictions

- Note that the roles played by each layer in CNN are different
- layer-wise aggregation introduced in SiamRPN++ is applied to SiamMask
- Introducing multi-RPN module and multi-MASK module







$$Cls = \sum_{i=3}^{5} \alpha_{i} \times Cls_{i}$$

$$Reg = \sum_{i=3}^{5} \beta_j \times Reg_i$$

$$Mask = \sum_{i=3}^{5} \gamma_j \times Mask_i$$

Details of each SiamMask block in SiamMask++.

 Features of conv3, conv4, and conv5 are individually supplied as inputs of the multi-RPN module and the multi-MASK module





- In the RPN module, we select the loss used by Faster R-CNN (Ren et al., 2015) and SiamRPN
- The classification branch adopts the cross-entropy loss
- The regression branch adopts the smooth L₁ loss

$$\alpha[0] = \frac{N_{x} - n_{x}}{n_{w}} \qquad \alpha[1] = \frac{N_{x} - n_{y}}{n_{h}} \qquad \alpha[2] = \log \frac{N_{w}}{n_{w}} \qquad \alpha[3] = \log \frac{N_{h}}{n_{h}}$$

$$smooth_{L_{1}}(x, \omega) = \begin{cases} 0.5\omega^{2}x^{2} & , & |x| < \frac{1}{\omega^{2}} \\ |x| - \frac{1}{2\omega^{2}} & , & |x| \ge \frac{1}{\omega^{2}} \end{cases}$$

$$L_{reg} = \sum_{i=0}^{3} smooth_{L_{1}} (\alpha[i], \omega)$$

• In the MASK module, we select the loss used by SiamMask

$$L_{mask} = \sum_{n} \left(\frac{1+c_n}{2wh} \sum_{ij} log \left(1 + e^{-q_n^{ij} m_n^{ij}} \right) \right).$$

The final loss function is as follows:

Loss function =
$$A \times L_{cls} + B \times L_{reg} + C \times L_{mask}$$





- Training dataset: ImageNet DET (Russakovsky et al., 2015), ImageNet VID, COCO (Lin et al., 2014) and Youtube VOS (Xu et al., 2018)
- Warm up while increasing the learning rate at a constant rate from 0.001 to 0.005 during the first 5epoch. Then end to end training slowly decreasing from 0.005 to 0.0025 for 15 epochs
- **Test dataset**: VOT2016 (Kristan et al., 2016), VOT2018 (Kristan et al., 2018) and VOT 2019 (Kristan et al., 2019)
- In the VOT challenge, the evaluation methods are accuracy, robustness, and the represent ative evaluation metric, **EAO**



- In all respects, SiamMask++ is superior to SiamMask
- The in-depth analysis of SiamMask and SiamMask++ is shown in the tables below:

Tracker	VOT2016			
Таскег	accuracy	robustness	EAO	
SiamMask + mask binary upsapling	0.637	0.280	0.385	
OURS + mask binary upsampling (bi_SiamMask++)	0.632	0.266	0.406 (+5.45%)	
SiamMask + mask refine module	0.626	0.289	0.403	
OURS + mask refine module (re_SiamMask++)	0.653	0.252	0.435(+7.94%)	
Tuo alson	VOT2018			
Tracker	accuracy	robustness	EAO	
SiamMask + mask binary upsapling	0.612	0.417	0.297	
OURS + mask binary upsampling (bi_SiamMask++)	0.603	0.318	0.366(+23.23%)	
SiamMask + mask refine module	0.601	0.417	0.321	
OURS + mask refine module (re_SiamMask++)	0.626	0.262	0.398(+23.99%)	
Tracker	VOT2019			
Tracker	accuracy	robustness	EAO	
SiamMask + mask binary upsapling	0.593	0.657	0.254	
OURS + mask binary upsampling (bi_SiamMask++)	0.593	0.547	0.283(+11.42%)	
SiamMask + mask refine module	0.600	0.647	0.262	
OURS + mask refine module (re_SiamMask++)	0.618	0.482	0.3(+14.50%)	



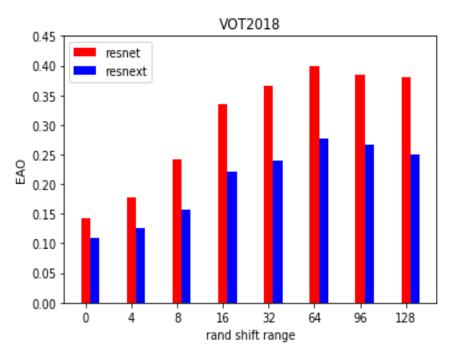


Year	Trackers	EAO			
		VOT2016	VOT2018	VOT2019	
2016	SiamFC (Bertinetto et al., 2016)	0.235	0.188		
2018	SA-Siam (He et al., 2018)	0.291			
2018	SiamRPN (Li et al., 2018)	0.344	0.244		
2018	DaSiamRPN (Zhu et al., 2018)	0.411	0.326		
2018	SA-Siam R (He et al., 2018)		0.337		
2019	SiamFC+ (Zhang & Peng, 2019)	0.303	0.270	0.242	
2019	SiamRPN+ (Zhang & Peng, 2019)	0.376	0.301		
2019	SiamRPN++ (Li et al., 2019)	0.464	0.414	0.282	
2019	SiamMask	0.403	0.321	0.262	
2020	ACSiamRPN (Qin et al., 2020)	0.397		0.240	
2020	SiamFC++ (Xu et al., 2020)	0.460	0.385		
2021	SE-SiamFC (Sosnovik et al., 2021)	0.360			
2021	SiamMask++	0.435	0.398	0.300	

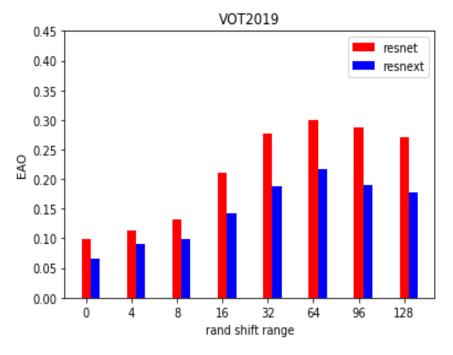
- Ranked 3rd in VOT2016 among trackers based on Siamese Network
- Ranked 2nd in VOT2018 among trackers based on Siamese Network
- Ranked 1st in VOT2019 among trackers based on Siamese Network
 - The more difficult the data set becomes, the better the performance will be relatively







EAO at VOT2018 of SiamMask++ with ResNet and ResNext as the backbone according to the increase in shift.



EAO at VOT2019 of SiamMask++ with ResNet and ResNext as the backbone according to the increase in shift.

- Shift range performs best at 64
- ResNet-50 performs better than ResNext-50





- Depth-wise cross correlation shows better performance than up-channel correlation
- Pretrained backbone shows better performance than non-pretrain backbone
- Using all convolutional blocks shows better performance than individual blocks or two block
- A table of experiments with various combinations of backbones, layers, and correlations is shown below:

BackBone	conv3	conv4	conv5	Finetune	corr	VOT2016	VOT2018	VOT2019
ResNext-50	V	V	V	V	DW	0.330	0.276	0.231
ResNet-50	V	V	V		UP	0.349	0.315	0.255
	V	V	V	V	UP	0.399	0.357	0.268
ResNet-50	V			V	$\mathbf{D}\mathbf{W}$	0.365	0.298	0.242
		V		V	\mathbf{DW}	0.403	0.321	0.262
			V	V	\mathbf{DW}	0.301	0.268	0.223
	v	<i>v</i>		V	\mathbf{DW}	0.378	0.329	0.261
	V		V	V	$\mathbf{D}\mathbf{W}$	0.366	0.293	0.244
		<i>v</i>	V	V	\mathbf{DW}	0.398	0.336	0.268
ResNet-50	v	V	V		DW	0.387	0.368	0.277
	v	<i>v</i>	V	V	DW	0.435	0.398	0.300





- Applying the method proven in SiamRPN++ to the SiamMask model to propose a new model for tracking mask (segmentation) based objects
- In-depth analysis of factors affecting performance through experiments
- Proven to be superior to SiamMask in all respects using the same dataset
- The proposed algorithm can be used as a base model for not only VOT but also segmentation-based work.
- The proposed algorithm can be applied to various performance enhancement methodologies introduced in the subsequent work of SiamMask, such as SiamMask_E (Chen et al., 2019)





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Thank you!