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1. (2)

取参数化

$$\vec{r}(t) = (a \cos t, b \sin t) \quad (0 \leq t \leq 2\pi)$$

$$s(t) = \int_0^t |\vec{r}'(t)| dt = \int_0^t \sqrt{a^2 \sin^2 t + b^2 \cos^2 t} dt$$

$$= a \int_0^t \sqrt{1 - e^2 \sin^2 t} dt \quad e = \sqrt{1 - \frac{b^2}{a^2}} \text{ 为离心率}$$

$$\text{弧长为 } s(2\pi) = a \int_0^{2\pi} \sqrt{1 - e^2 \sin^2 t} dt$$

$$= 4a \int_0^{\frac{\pi}{2}} \sqrt{1 - e^2 \sin^2 t} dt =: 4a E(e)$$

$E(e)$  为熟知的第二类完全椭圆积分

$$\frac{ds}{dt} = \sqrt{a^2 \sin^2 t + b^2 \cos^2 t}$$

$$\vec{T} = \frac{d\vec{r}}{dt} \cdot \frac{dt}{ds} = \frac{(-a \sin t, b \cos t)}{\sqrt{a^2 \sin^2 t + b^2 \cos^2 t}}$$

$$\Rightarrow \vec{n} = \frac{(-b \cos t, -a \sin t)}{\sqrt{a^2 \sin^2 t + b^2 \cos^2 t}}$$

$$\vec{t} = \frac{d\vec{T}}{ds} = \frac{d\vec{T}}{dt} \cdot \frac{dt}{ds}$$

$$= \frac{1}{\sqrt{a^2 \sin^2 t + b^2 \cos^2 t}} \cdot \frac{ab(-b \cos t, a \sin t)}{(a^2 \sin^2 t + b^2 \cos^2 t)^{\frac{3}{2}}}$$

$$K = \frac{\vec{t}}{\vec{n}} = \frac{ab}{(a^2 \sin^2 t + b^2 \cos^2 t)^{\frac{3}{2}}}$$

$$(3) \vec{r}(t) = (a \cosh t, b \sinh t)$$

$$s(t) = \int_0^t |\vec{r}'(t)| dt = \int_0^t \sqrt{a^2 \sinh^2 t + b^2 \cosh^2 t} dt$$

(-y, x)

$\begin{pmatrix} x \\ y \end{pmatrix}$

$$\frac{ds}{dt} = \sqrt{a^2 \sinh^2 t + b^2 \cosh^2 t}$$

$$\vec{t} = \frac{d\vec{r}}{s} = \frac{d\vec{r}}{dt} \cdot \frac{dt}{ds} = \frac{(a \sinh t, b \cosh t)}{\sqrt{a^2 \sinh^2 t + b^2 \cosh^2 t}}$$

$$\vec{n} = \frac{(-b \cosh t, a \sinh t)}{\sqrt{a^2 \sinh^2 t + b^2 \cosh^2 t}}$$

$$\begin{aligned} \dot{\vec{t}} &= \frac{d\vec{t}}{ds} = \frac{d\vec{t}}{dt} \cdot \frac{dt}{ds} = \frac{1}{\sqrt{a^2 \sinh^2 t + b^2 \cosh^2 t}} \cdot \frac{ab(b \cosh t, -a \sinh t)}{(a^2 \sinh^2 t + b^2 \cosh^2 t)^{\frac{3}{2}}} \\ &= \frac{ab(b \cosh t, -a \sinh t)}{(a^2 \sinh^2 t + b^2 \cosh^2 t)^2} \end{aligned}$$

$$k = \frac{\dot{\vec{t}}}{\vec{n}} = - \frac{ab}{(a^2 \sinh^2 t + b^2 \cosh^2 t)^{\frac{3}{2}}}$$

$$2. \text{ 证: } s(t) = \int_0^t \sqrt{(x'(t))^2 + (y'(t))^2} dt$$

$$\frac{ds}{dt} = \sqrt{(x'(t))^2 + (y'(t))^2} =: \sqrt{(x')^2 + (y')^2}$$

$$\vec{t} = \frac{d\vec{r}}{ds} = \frac{d\vec{r}}{dt} \cdot \frac{dt}{ds} = \frac{(x'(t), y'(t))}{\sqrt{(x')^2 + (y')^2}}$$

$$\vec{n} = \frac{(-y'(t), x'(t))}{\sqrt{(x')^2 + (y')^2}}$$

$$\dot{\vec{t}} = \frac{d\vec{t}}{ds} = \frac{d\vec{t}}{dt} \cdot \frac{dt}{ds} = \frac{1}{\sqrt{(x')^2 + (y')^2}} \cdot \frac{(x'(t)y''(t) - x''(t)y'(t))(-y'(t), x'(t))}{((x')^2 + (y')^2)^{\frac{3}{2}}}$$

$$k(t) = \frac{\dot{\vec{t}}}{\vec{n}} = \frac{x'(t)y''(t) - x''(t)y'(t)}{[(x')^2 + (y')^2]^{\frac{3}{2}}}$$

$$3. \text{ 证: 作变换 } \begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases}$$

$$\Rightarrow \vec{r}(\theta) = (f(\theta) \cos \theta, f(\theta) \sin \theta)$$

$$\text{由 Z. } K(\theta) = \frac{x'(\theta)y''(\theta) - x''(\theta)y'(\theta)}{[(x')^2 + (y')^2]^{\frac{3}{2}}}$$

$$x' = f'(\theta)\cos\theta - f(\theta)\sin\theta \quad y' = f'(\theta)\sin\theta + f(\theta)\cos\theta$$

$$x'' = f''(\theta)\cos\theta - 2f'(\theta)\sin\theta - f(\theta)\cos\theta$$

$$y'' = f''(\theta)\sin\theta + 2f'(\theta)\cos\theta - f(\theta)\sin\theta$$

$$\begin{aligned} &= \frac{(f'(\theta)\cos\theta - f(\theta)\sin\theta)(f''(\theta)\sin\theta + 2f'(\theta)\cos\theta) - f(\theta)\sin\theta}{[(f'(\theta)\cos\theta - f(\theta)\sin\theta)(f''(\theta)\cos\theta - 2f'(\theta)\sin\theta - f(\theta)\cos\theta)]^{\frac{3}{2}}} \\ &= \frac{f^2(\theta) + 2(f'(\theta))^2 - f(\theta)f''(\theta)}{[f^2(\theta) + (f'(\theta))^2]^{\frac{3}{2}}} = \frac{f^2(\theta) + 2\left(\frac{df}{d\theta}\right)^2 - f(\theta)\frac{d^2f}{d\theta^2}}{[f^2(\theta) + \left(\frac{df}{d\theta}\right)^2]^{\frac{3}{2}}} \end{aligned}$$

5. 证:  $s(t) = \int_0^t |\vec{r}'(u)| du$

$$\frac{ds}{dt} = |\vec{r}'(t)|$$

$$\vec{t}(t) = \frac{d\vec{r}}{ds} = \frac{d\vec{r}}{dt} \cdot \frac{dt}{ds} = \frac{\vec{r}'(t)}{|\vec{r}'(t)|}$$

$$K(t) = \left| \frac{d\vec{t}}{dt} \cdot \frac{dt}{ds} \right| = \frac{1}{|\vec{r}'(t)|} \cdot \left| \frac{d\vec{r}'(t)}{dt} \right|$$

$$\frac{d\frac{\vec{r}'(t)}{|\vec{r}'(t)|}}{dt} = \frac{(y(\ddot{x}\dot{y} - \dot{x}\ddot{y}) - z(\ddot{x}\dot{z} - \dot{x}\ddot{z}), \dot{z}(\ddot{y}\dot{z} - \dot{y}\ddot{z}) - \dot{x}(\ddot{y}\dot{x} - \dot{y}\ddot{x}), \dot{x}(\ddot{z}\dot{x} - \dot{z}\ddot{x}) - \dot{y}(\ddot{z}\dot{y} - \dot{z}\ddot{y}))}{|\vec{r}'(t)|^3}$$

取拉 K, 即有  $\left| \frac{d\frac{\vec{r}'(t)}{|\vec{r}'(t)|}}{dt} \right| = \frac{|\vec{r}' \wedge \vec{r}''|}{|\vec{r}'|^3}$  过于难算了, 感觉可以不用算.

$$\Rightarrow K(t) = \frac{|\vec{r}' \wedge \vec{r}''|}{|\vec{r}'|^3}$$

$$\vec{t}(t) = \frac{d(\vec{r}'(t) \cdot \frac{dt}{ds})}{ds} = \vec{r}''(t) \cdot \left(\frac{dt}{ds}\right)^2 + \vec{r}'(t) \cdot \frac{d^2t}{ds^2}$$

$$\vec{n}(t) = \frac{1}{K(t)} \vec{t}(t)$$

$$\vec{b}(t) = \vec{t}(t) \wedge \vec{n}(t) = (\vec{r}'(t) \cdot \frac{dt}{ds}) \wedge \left( \frac{1}{K(t)} \cdot (\vec{r}''(t) \left(\frac{dt}{ds}\right)^2 + \vec{r}'(t) \cdot \frac{d^2t}{ds^2}) \right)$$

$$= \frac{1}{K(t)} \cdot \left(\frac{dt}{ds}\right)^3 \vec{r}'(t) \wedge \vec{r}''(t)$$

$$\text{又 } |\vec{b}| = 1$$

$$\Rightarrow K(t) = \left( \frac{dt}{ds} \right)^3 \left| \vec{r}'(t) \wedge \vec{r}''(t) \right| = \frac{|\vec{r}' \wedge \vec{r}''|}{|\vec{r}'|^3}$$

聪明多了

$$\vec{\tau}(t) = K(t) \vec{n}(t)$$

$$\begin{aligned}\ddot{\vec{r}}(t) &= \dot{K}(t) \vec{n}(t) + K(t) \dot{\vec{n}}(t) = \dot{K}(t) \vec{n}(t) + K(t) (-K(t) \vec{\tau}(t) + T(t) \vec{b}(t)) \\ &= -K^2(t) \vec{\tau}(t) + \dot{K}(t) \vec{n}(t) + K(t) T(t) \vec{b}(t)\end{aligned}$$

$$\Rightarrow K(t) T(t) = \langle \ddot{\vec{r}}(t), \vec{b}(t) \rangle$$

$$\ddot{\vec{r}}(t) = \frac{d(\dot{\vec{r}}(t))}{ds} = \vec{r}'''(t) \cdot \left( \frac{dt}{ds} \right)^3 + 3 \cdot \vec{r}''(t) \cdot \frac{dt}{ds} \cdot \left( \frac{d^2 t}{ds^2} \right) + \vec{r}'(t) \cdot \frac{d^3 t}{ds^3}$$

$$\langle \ddot{\vec{r}}(t), \vec{b}(t) \rangle$$

$$= \langle \vec{r}'''(t) \cdot \left( \frac{dt}{ds} \right)^3 + 3 \cdot \vec{r}''(t) \cdot \frac{dt}{ds} \cdot \left( \frac{d^2 t}{ds^2} \right) + \vec{r}'(t) \cdot \frac{d^3 t}{ds^3}, \frac{1}{K(t)} \cdot \left( \frac{dt}{ds} \right)^3 \vec{r}'(t) \wedge \vec{r}''(t) \rangle$$

$$= \frac{1}{K(t)} \cdot \left( \frac{dt}{ds} \right)^6 (\vec{r}', \vec{r}''(t), \vec{r}'''(t))$$

$$\Rightarrow T(t) = \frac{1}{K^2(t)} \left( \frac{dt}{ds} \right)^6 (\vec{r}', \vec{r}''(t), \vec{r}'''(t))$$

$$= \frac{(\vec{r}', \vec{r}'', \vec{r}''')}{|\vec{r}' \wedge \vec{r}''|^2}$$

$$b. \quad |\vec{r}'(s)| = \sqrt{\frac{1+s}{4} + \frac{1-s}{4} + \frac{1}{2}} = 1 \quad (\text{验证 } s \text{ 为弧长参数})$$

$$\vec{r}'(s) = \left( \frac{\sqrt{1+s}}{2}, -\frac{\sqrt{1-s}}{2}, \frac{1}{\sqrt{2}} \right)$$

$$\vec{r}''(s) = \left( \frac{1}{4\sqrt{1+s}}, \frac{1}{4\sqrt{1-s}}, 0 \right)$$

$$\vec{r}'''(s) = \left( -\frac{1}{8(1+s)^{\frac{3}{2}}}, \frac{1}{8(1-s)^{\frac{3}{2}}}, 0 \right)$$

$$K(t) = \frac{|\vec{r}' \wedge \vec{r}''|}{|\vec{r}'|^3} = \left| \left( \frac{1}{4\sqrt{2}(1-s)}, \frac{1}{4\sqrt{2}(1+s)}, \frac{1}{4\sqrt{(1-s)(1+s)}} \right) \right| = \frac{1}{2\sqrt{2(1-s^2)}}$$

$$T(t) = \frac{(\vec{r}', \vec{r}'', \vec{r}''')}{|\vec{r}' \wedge \vec{r}''|^2} = \frac{\frac{1}{16\sqrt{2}(1-s^2)^{\frac{3}{2}}}}{\frac{1}{8(1-s^2)}} = \frac{1}{2\sqrt{2(1-s^2)}}$$

$$\text{而 } \vec{t}(s) = \frac{\vec{r}'(s)}{|\vec{r}'(s)|} = \vec{r}'(s) = \left( \frac{\sqrt{1+s}}{2}, -\frac{\sqrt{1-s}}{2}, \frac{1}{\sqrt{2}} \right)$$

$$\vec{n}(s) = \frac{\vec{r}''(s)}{|\vec{r}''(s)|} = \left( \sqrt{\frac{1-s}{2}}, \sqrt{\frac{1+s}{2}}, 0 \right)$$

$$\vec{b}(s) = \frac{\vec{r}' \wedge \vec{r}''}{|\vec{r}' \wedge \vec{r}''|} = \left( -\frac{\sqrt{1+s}}{2}, \frac{\sqrt{1-s}}{2}, \frac{1}{\sqrt{2}} \right)$$

Frenet 框架为  $\{\vec{r}(s); \vec{t}(s), \vec{n}(s), \vec{b}(s)\}$

7. (1) 要证  $\vec{r}(t)$  是一条正则曲线，只需证  $\vec{r}(t)$  在  $t=0$  处是  $C^\infty$  的。

$$\text{记 } \vec{r}(t) = (x(t), y(t), z(t))$$

当  $t \neq 0$  时， $x(t), y(t), z(t)$  显然都是  $C^\infty$  的。

$$\text{而容易证明: } (e^{-\frac{t}{k}})^{(k)} = \frac{P_k(t)}{t^{n_k}} \cdot e^{-\frac{t}{k}}, n_k \text{ 为正整数}$$

$$\text{证明: 归纳法 } k=1 \text{ 时, } (e^{-\frac{t}{1}})' = \frac{2}{t^2} e^{-\frac{t}{1}}$$

$$P_1(t)=2 \quad n_1=3$$

设  $k=n$  时成立。

$$\text{则 } (e^{-\frac{t}{k}})^{(k+1)} = \left( \frac{P_k(t)}{t^{n_k}} e^{-\frac{t}{k}} \right)'$$

$$\begin{aligned} & 2P_k(t) + t^3 P'_k(t) \\ & - n_k t^2 P_k(t) = \frac{\left( \frac{2P_k(t)}{t^3} + P'_k(t) \right) e^{-\frac{t}{k}} \cdot t^{n_k} - n_k t^{n_k-1} P_k(t) \cdot e^{-\frac{t}{k}}}{(t^{n_k})^2} \\ & = \frac{(2-n_k t) P_k(t) + t^3 P'_k(t)}{t^{n_k+3}} e^{-\frac{t}{k}} \end{aligned}$$

$$P_{k+1}(t) = (2-n_k t) P_k(t) + t^3 P'_k(t) \quad n_{k+1} = n_k + 3 = \dots = 3(k+1)$$

①  $t < 0$  时 故  $\vec{r}'(t) = \left( \frac{2}{t} e^{-\frac{t}{k}}, 1, 0 \right) \neq 0$  #.

$$\vec{r}^{(k)}(t) = \left( \frac{P_k(t)}{t^{3k}} \cdot e^{-\frac{t}{k}}, 0, 0 \right) \neq 0 \quad k \geq 2$$

②  $t > 0$  时,  $\vec{r}'(t) = (0, 1, \frac{2}{t} e^{-\frac{t}{k}}) \neq 0$

$$\vec{r}^{(k)}(t) = (0, 0, \frac{P_k(t)}{t^{3k}} \cdot e^{-\frac{t}{k}}) \neq 0$$

故当  $t \neq 0$  时,  $r(t)$  是光滑的, 且  $r'(t) \neq 0$ , 故是正则的。

当  $t=0$  时,  $y(t)$  是  $C^\infty$  的, 只需证明  $x(t)$  与  $z(t)$  光滑。

$$Z^{(k)}(t) = \frac{P_k(t)}{t^{k+1}} e^{-\frac{1}{t}}, t > 0$$

$$Z^{(k)}(t) = 0, t < 0$$

显然  $t=0$  处各阶左导数  $Z^{(k)}_-(t) = 0$

下面计算各阶右导数

$$Z'_+(0) = \lim_{t \rightarrow 0^+} \frac{Z(t) - 0}{t} = \lim_{t \rightarrow 0^+} \frac{e^{-\frac{1}{t}}}{t} = \lim_{u \rightarrow +\infty} \frac{u}{e^{u^2}} = \lim_{u \rightarrow +\infty} \frac{1}{2ue^{u^2}} = 0 = Z'_-(0)$$

$$\text{类似地, } Z''_+(0) = \lim_{t \rightarrow 0^+} \frac{Z^{(k-1)}(t) - Z^{(k-1)}(0)}{t} = \lim_{t \rightarrow 0^+} \frac{\frac{P_{k-1}(t)}{t^{3k-1}} e^{-\frac{1}{t}}}{t} = \lim_{u \rightarrow +\infty} \frac{P'_{k-1}(u)}{e^{u^2}} = 0 = Z''_-(0)$$

(因为  $\deg P_k = 2(k-1)$ ,  $P'_{k-1}$  也是一个多项式)

故  $Z(t)$  在  $t=0$  处也光滑

类似地,  $\gamma(t)$  在  $t=0$  处也光滑

$t=0$  时, 有  $\vec{r}'(0) = (0, 1, 0)$

$$\vec{r}''(0) = (0, 0, 0)$$

$$\Rightarrow k(0) = \frac{|\vec{r}'(0) \times \vec{r}''(0)|}{|\vec{r}'(0)|^3} = 0 \quad \#.$$

(2)

$$\vec{t}(t) = \frac{\vec{r}'(t)}{|\vec{r}'(t)|} = \begin{cases} \frac{1}{(1 + \frac{4}{t^6} e^{-\frac{2}{t^2}})^{\frac{1}{2}}} \left( \frac{2}{t^3} e^{-\frac{1}{t^2}}, 1, 0 \right), & t < 0 \\ \frac{1}{(1 + \frac{4}{t^6} e^{-\frac{2}{t^2}})^{\frac{1}{2}}} \left( 0, 1, \frac{2}{t^3} e^{-\frac{1}{t^2}} \right), & t > 0 \end{cases}$$

判断  $\vec{t}(t)$  方向变化, 判断  $\vec{n}(t)$ , 有

$$\vec{n}(t) = \begin{cases} \frac{1}{(1 + \frac{4}{t^6} e^{-\frac{2}{t^2}})^{\frac{1}{2}}} \left( \operatorname{sgn}(-6t^2+4), \frac{2\operatorname{sgn}(6t^2-4)}{t^3} e^{-\frac{1}{t^2}}, 0 \right), & t < 0 \\ \frac{1}{(1 + \frac{4}{t^6} e^{-\frac{2}{t^2}})^{\frac{1}{2}}} \left( 0, \frac{2\operatorname{sgn}(6t^2-4)}{t^3} e^{-\frac{1}{t^2}}, \operatorname{sgn}(-6t^2+4) \right), & t > 0 \end{cases}$$

$$\vec{b}(t) = \vec{t}(t) \times \vec{n}(t) = \begin{cases} (0, 0, \operatorname{sgn}(6t^2-4)), & t < 0 \\ (\operatorname{sgn}(-6t^2+4), 0, 0), & t > 0 \end{cases}$$

Frenet 手架即为  $(\vec{r}(t), \vec{t}(t), \vec{n}(t), \vec{b}(t))$

当  $t \rightarrow 0^-$  时, Frenet 手架的极限为  $(\vec{r}(0^-) = 0, \vec{t}(0^-), \vec{n}(0^-), \vec{b}(0^-))$

$$\vec{t}(0^-) = (0, 1, 0) \quad \vec{n}(0^-) = (1, 0, 0) \quad \vec{b}(0^-) = (0, 0, -1)$$

当  $t \rightarrow 0^+$  时, Frenet 框架的极限为  $\{\vec{r}(0^+), \vec{t}(0^+), \vec{n}(0^+), \vec{b}(0^+)\}$

$$\vec{t}(0^+) = (0, 1, 0) \quad \vec{n}(0^+) = (0, 0, 1) \quad \vec{b}(0^+) = (1, 0, 0)$$

9. (1) 证: 设曲线  $C$  的方程为  $\vec{r}(s)$ ,  $s$  为弧长参数  
定点为  $P_0$

$$有 \quad \vec{r}(s) - \vec{P}_0 = \lambda(s) \vec{t}(s)$$

$$\text{其中 } \lambda(s) = \langle \vec{r}(s) - \vec{P}_0, \vec{t}(s) \rangle$$

两边对  $s$  求导, 有

$$\begin{aligned} \vec{t}(s) &= \lambda'(s) \vec{t}(s) + \lambda(s) \vec{t}'(s) \\ &= \lambda'(s) \vec{t}(s) + \lambda(s) K(s) \vec{n}(s) \end{aligned}$$

由于  $\vec{t}$  与  $\vec{n}$  线性无关

$$\text{故 } \lambda'(s) = 1 \quad \lambda(s) K(s) = 0$$

$$\Rightarrow \lambda(s) \text{ 不恒为零 (至多一处)} \quad K(s) = 0$$

又由  $K(s)$  连续性,  $\Rightarrow K(s) \equiv 0$

$\Rightarrow C$  为直线

(2) 证: 设  $C$  曲线方程为  $\vec{r}(s)$

$$\vec{r}(s) - \vec{P}_0 = \lambda(s) \vec{n}(s)$$

$$\lambda(s) = \langle \vec{r}(s) - \vec{P}_0, \vec{n}(s) \rangle$$

对两边求导

$$-\lambda(s) \vec{n}'(s)$$

$$\begin{aligned} \vec{t}(s) &= \lambda'(s) \vec{n}(s) + \lambda(s) \vec{n}'(s) && + T(s) \vec{b}(s) \\ &= -\lambda(s) K(s) \vec{t}(s) + \lambda'(s) \vec{n}(s) + \lambda(s) T(s) \vec{b}(s) \end{aligned}$$

$$\Rightarrow -\lambda(s) K(s) = 1$$

$$\lambda'(s) = 0 \quad \lambda(s) T(s) = 0$$

$\lambda \neq 0$  (常数) 若  $\lambda(s) = c \neq 0$ , 则  $C$  为  $P_0$  点, 不是曲线

RJ  $\lambda(s) \neq 0$ ,  $\Rightarrow \tau(s) \equiv 0$

$\Rightarrow C$  在某个平面中

$$K(s) = -\frac{1}{\lambda(s)} = -\frac{1}{C} \neq 0 \quad K(s) \text{ 为常数 } -\frac{1}{C} (\neq 0)$$

$\Rightarrow C$  为以  $P_0$  为圆心, 半径为  $|C|$  的圆