



Kissipo Learning for Deep Learning

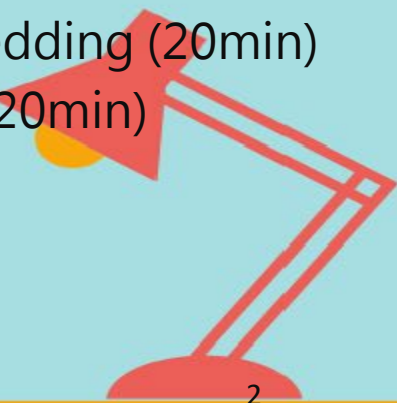
Topic 13: RNN with TensorFlow (20min)

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KLDL-W4-T11

Topics

- Topic 01: Introduction to Deep Learning (20min)
- Topic 02: KISS Learning for Deep Learning (20min)
- Topic 03: Python quick tutorial (20min)
- Topic 04: Numpy quick tutorial (15min)
- Topic 05: Pandas quick tutorial (15min)
- Topic 06: Scikit-learn quick tutorial (15min)
- Topic 07: OpenCV quick tutorial (15min)
- Topic 08: Image Processing basics (20min)
- Topic 09: Machine Learning basics (20min)
- Topic 10: Deep Learning basics (20min)
- Topic 11: TensorFlow overview (20min)
- Topic 12: CNN with TensorFlow (20min)
- Topic 13: RNN with TensorFlow (20min)
- Topic 14: PyTorch overview (20min)
- Topic 15: CNN with PyTorch (20min)
- Topic 16: RNN with Pytorch (20min)
- Topic 17: Introduction to AOI (20min)
- Topic 18: AOI simple Pipeline (A) (20min)
- Topic 19: AOI simple Pipeline (B) (20min)
- Topic 20: Introduction to Object detection (20min)
- Topic 21: YoloV5 Quick Tutorial (20min)
- Topic 22: Using YoloV5 for RSD (20min)
- Topic 23: Introduction to NLP (20min)
- Topic 24: Introduction to Word Embedding (20min)
- Topic 25: Name prediction project (20min)

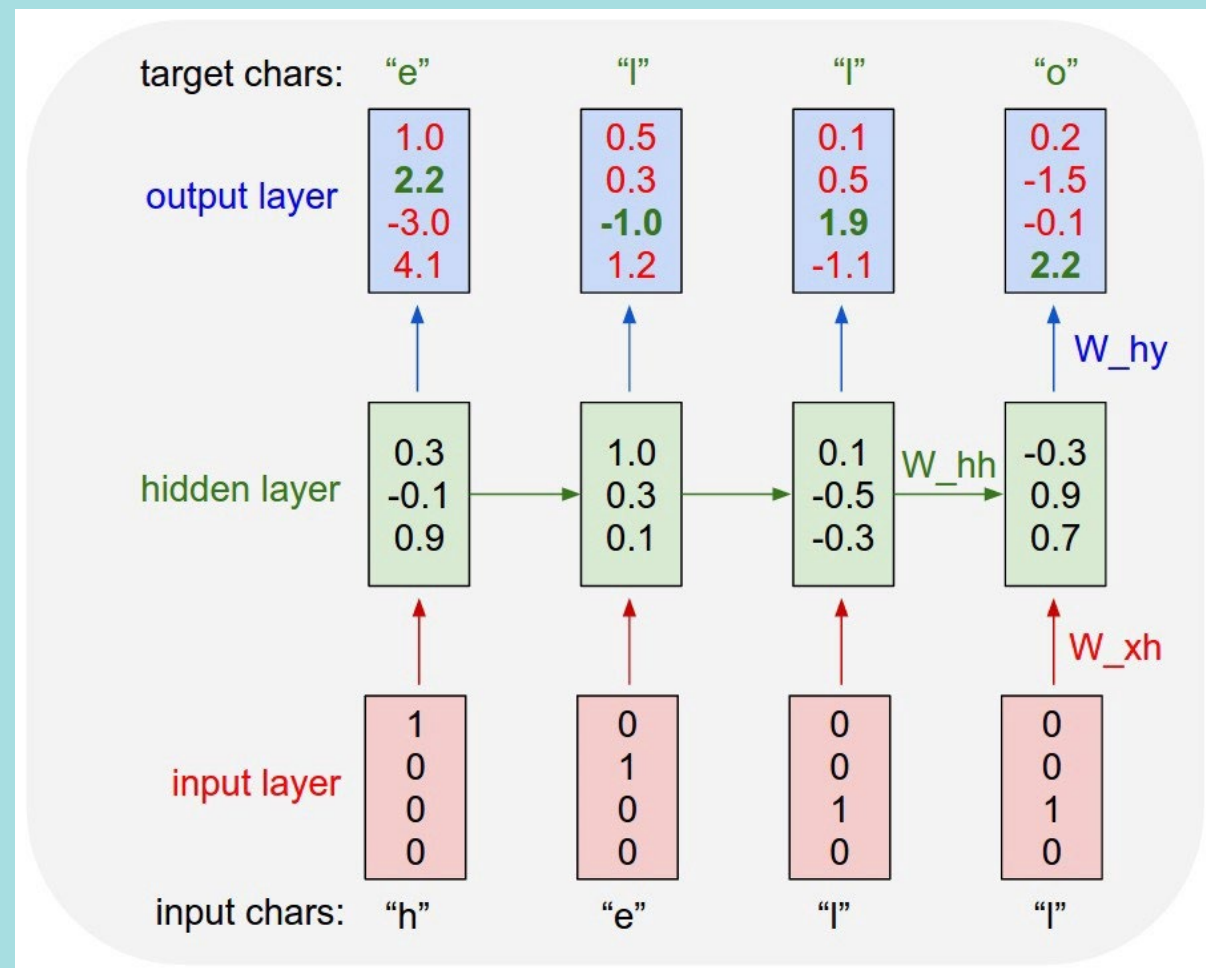
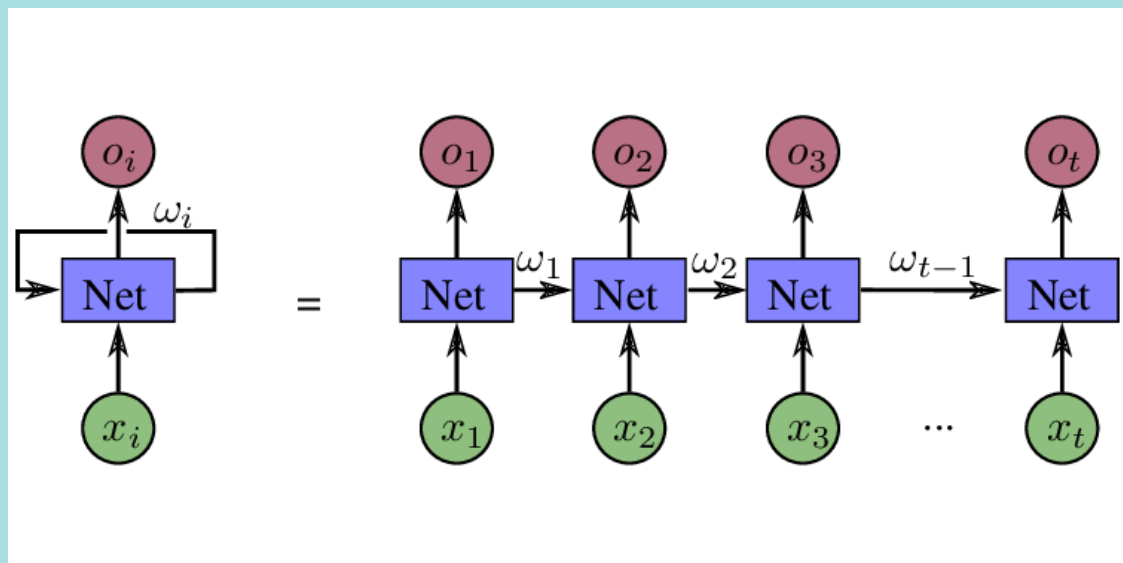


Content

- Topic 13: RNN with TensorFlow (20min)
 - Introduction to RNN
 - Types of RNN



Recurrent Neural Network (RNN)

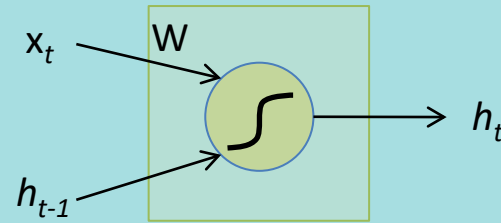


Types of RNN

- Vanilla RNN
- LSTM- Long-Short Term Memory
- GRU-Gated Recurrent Unit
- Bi-directional RNNs



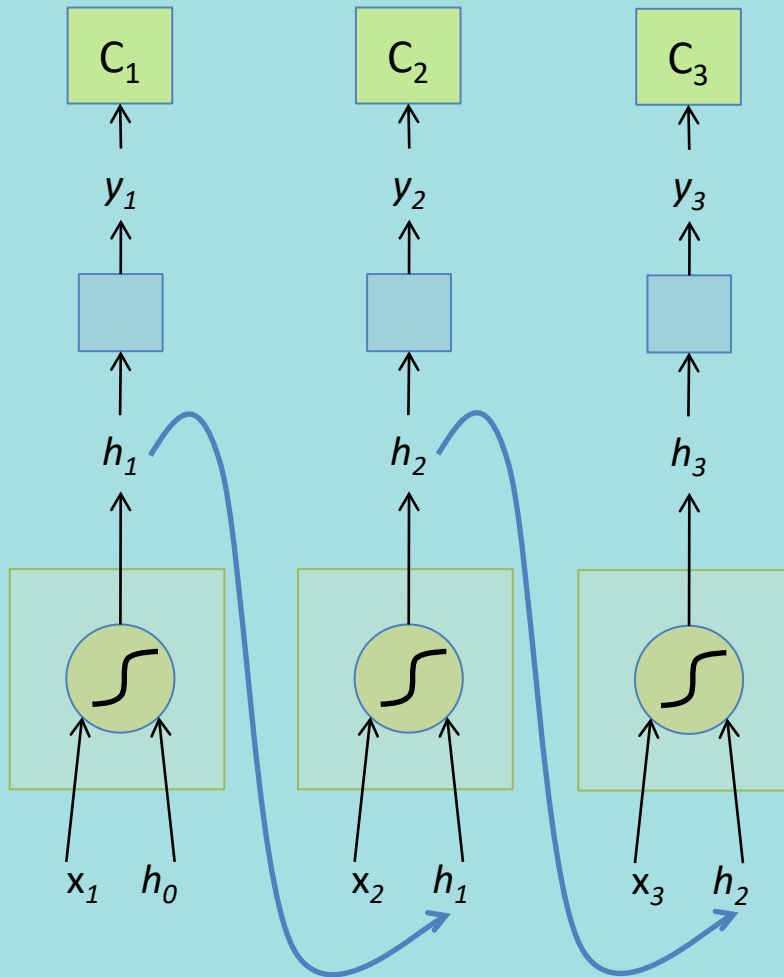
The Vanilla RNN Cell



$$h_t = \tanh W \begin{pmatrix} x_t \\ h_{t-1} \end{pmatrix}$$



The Vanilla RNN Forward



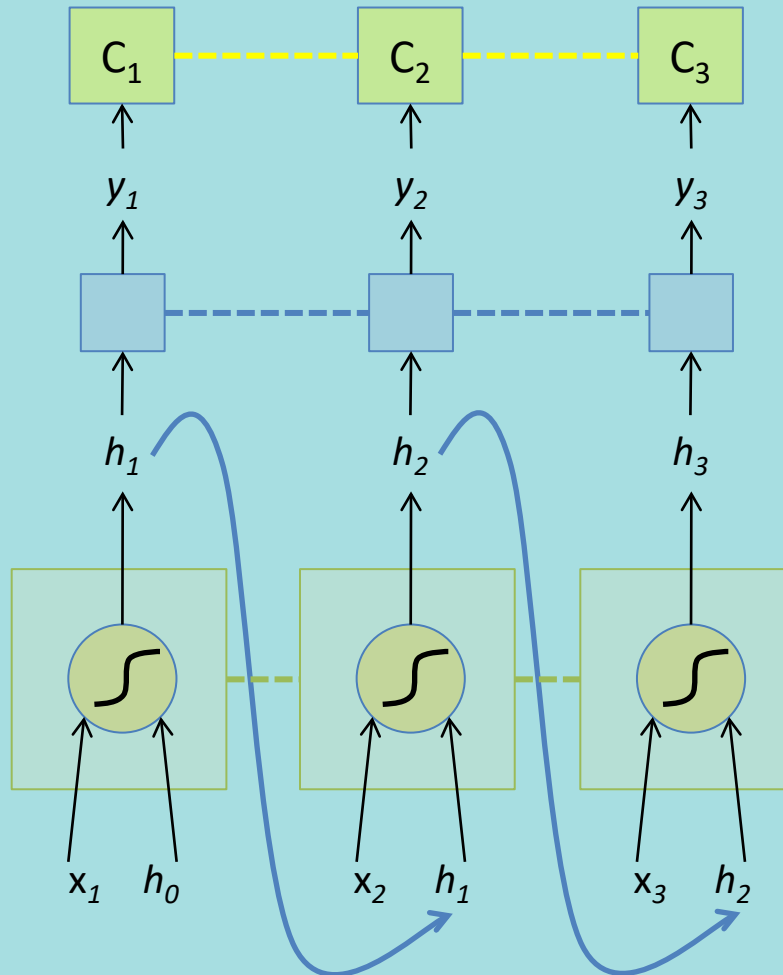
$$h_t = \tanh W \begin{pmatrix} x_t \\ h_{t-1} \end{pmatrix}$$

$$y_t = F(h_t)$$

$$C_t = \text{Loss}(y_t, GT_t)$$



The Vanilla RNN Forward



$$h_t = \tanh W \begin{pmatrix} x_t \\ h_{t-1} \end{pmatrix}$$

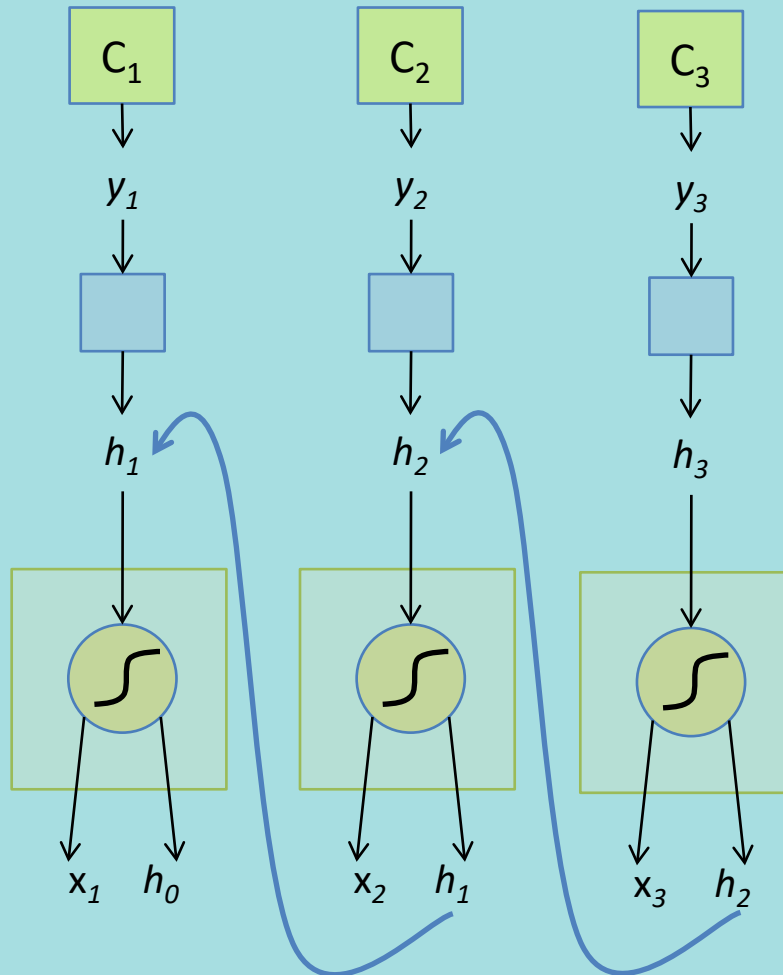
$$y_t = F(h_t)$$

$$C_t = \text{Loss}(y_t, \text{GT}_t)$$

----- indicates shared weights



The Vanilla RNN Backward



$$h_t = \tanh W \begin{pmatrix} x_t \\ h_{t-1} \end{pmatrix}$$

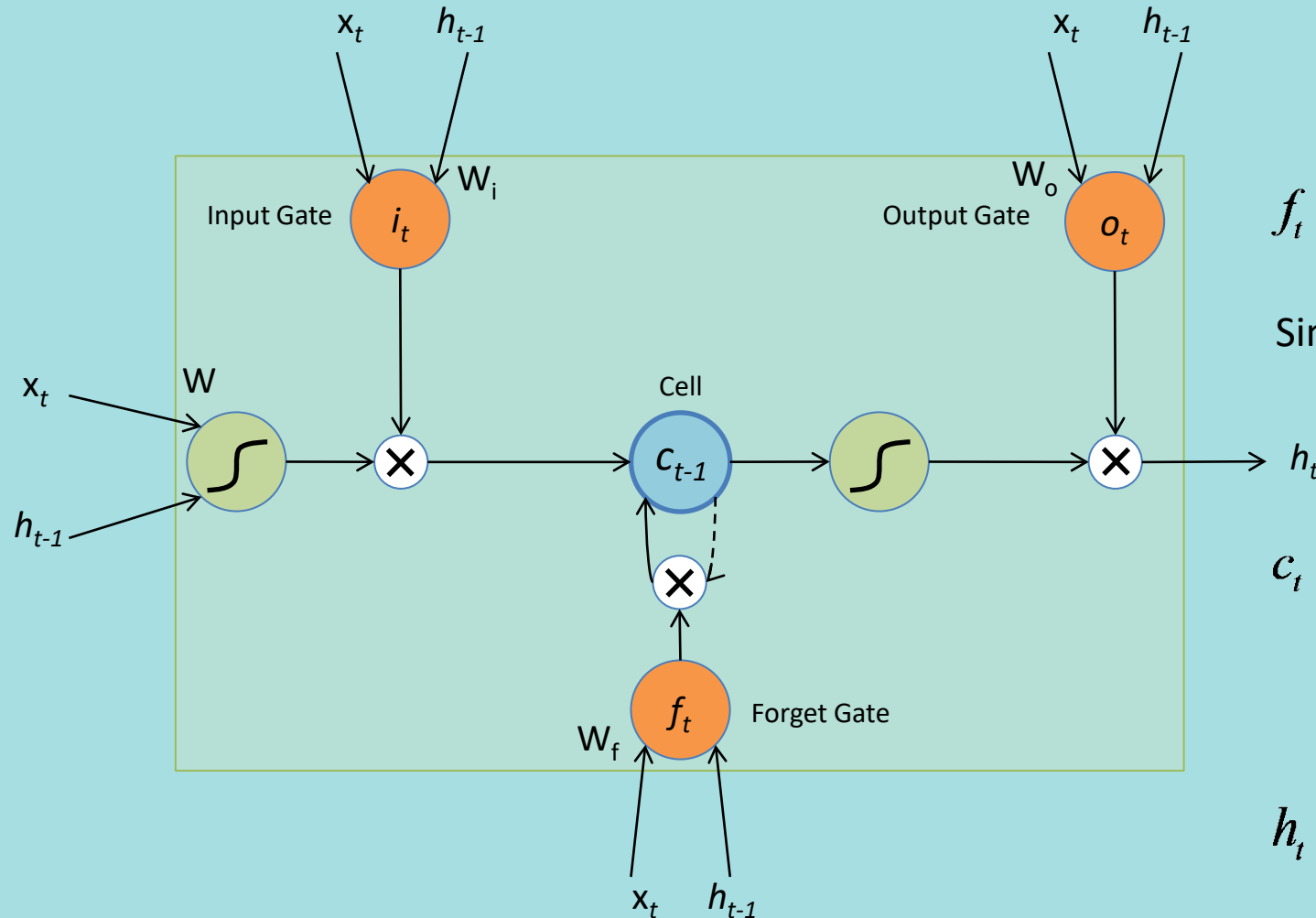
$$y_t = F(h_t)$$

$$C_t = \text{Loss}(y_t, \text{GT}_t)$$

$$\frac{\partial C_t}{\partial h_1} = \left(\frac{\partial C_t}{\partial y_t} \right) \left(\frac{\partial y_t}{\partial h_1} \right)$$

$$= \left(\frac{\partial C_t}{\partial y_t} \right) \left(\frac{\partial y_t}{\partial h_t} \right) \left(\frac{\partial h_t}{\partial h_{t-1}} \right) \cdots \left(\frac{\partial h_2}{\partial h_1} \right)$$

The Popular LSTM Cell



$$f_t = \sigma \left(W_f \begin{pmatrix} x_t \\ h_{t-1} \end{pmatrix} + b_f \right)$$

Similarly for i_t, o_t

$$c_t = f_t \otimes c_{t-1} +$$

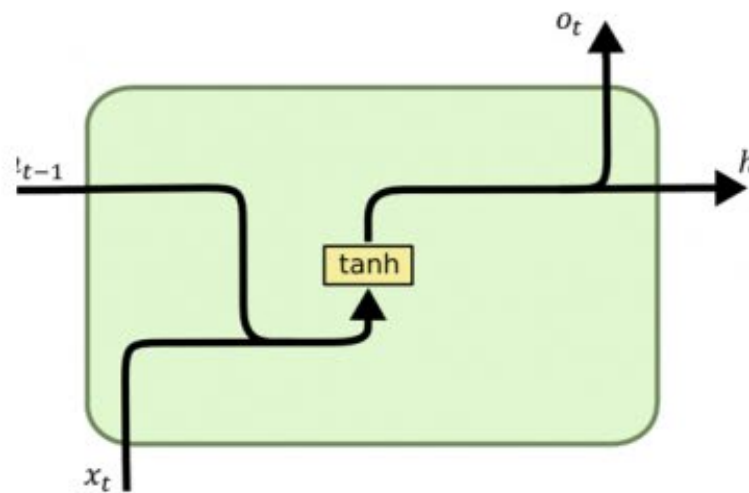
$$i_t \otimes \tanh W \begin{pmatrix} x_t \\ h_{t-1} \end{pmatrix}$$

$$h_t = o_t \otimes \tanh c_t$$

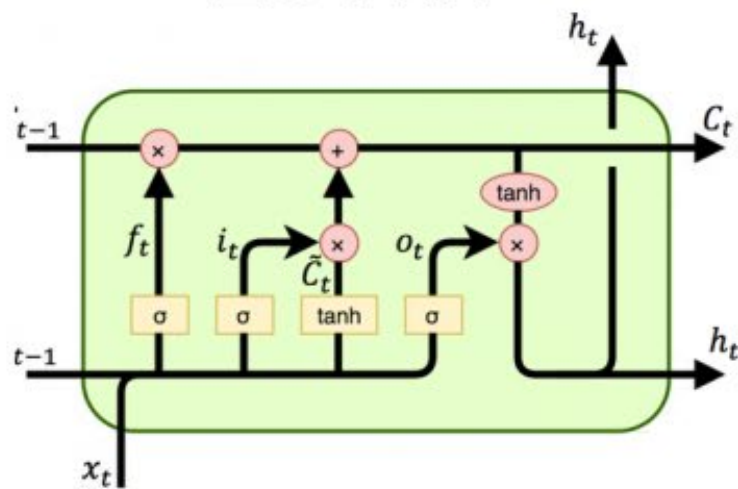
* Dashed line indicates time-lag

GRU RNNs

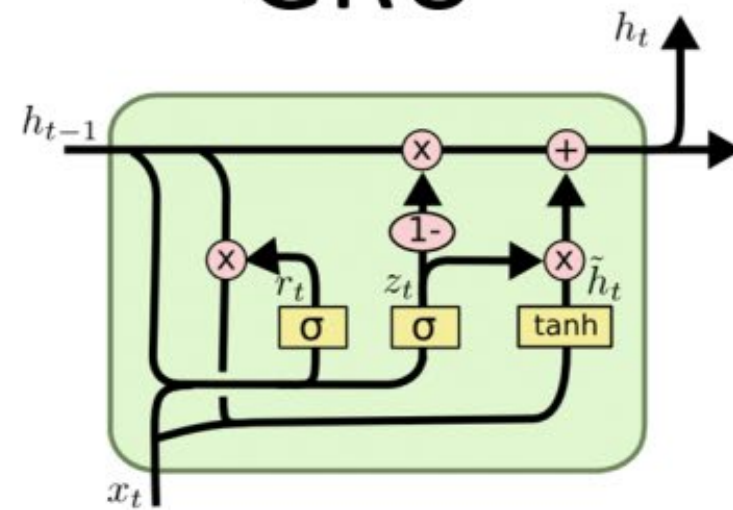
RNN



LSTM

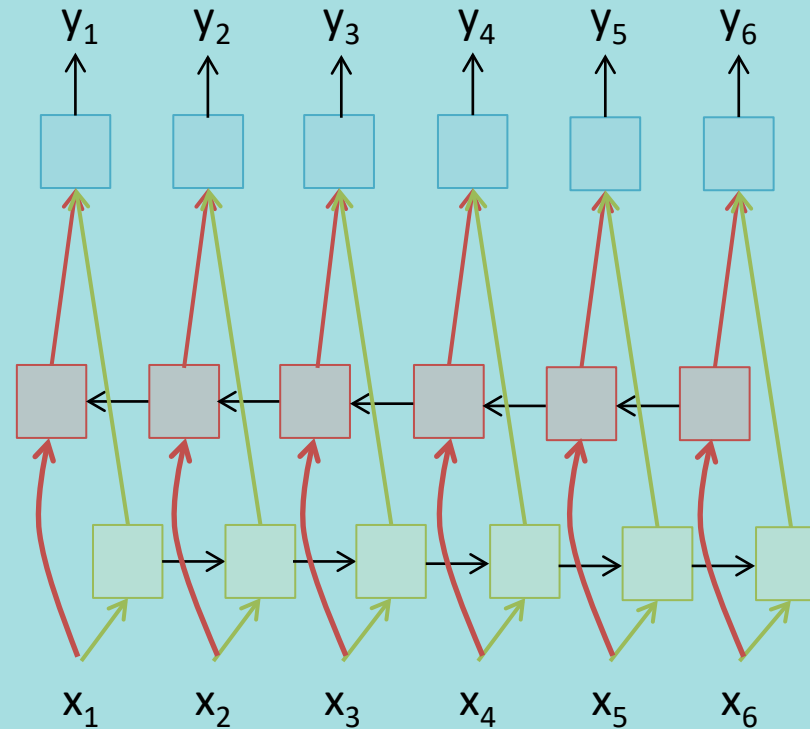


GRU



Bi-directional RNNs

- RNNs can process the input sequence in forward and in the reverse direction



- Popular in speech recognition



Thanks!

Q&A

