

Hamilton's Principle

Classical Dynamics

Problem Sheet

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1. Hamilton's principle basics

- (a) State Hamilton's principle and explain how it leads to the Euler-Lagrange equations.
- (b) Show explicitly that requiring $\delta S = 0$ for

$$S = \int_{t_1}^{t_2} L(x, \dot{x}, t) dt$$

leads to

$$\frac{\delta}{\delta t} \left(\frac{\delta L}{\delta \dot{x}} \right) - \frac{\delta L}{\delta x} = 0.$$

2. Simple harmonic oscillator

A particle of mass m attached to a spring of stiffness k has Lagrangian

$$L = \frac{1}{2}m\dot{x}^2 - \frac{1}{2}kx^2.$$

- (a) Derive the equations of motion using Hamilton's principle.
- (b) Verify that $x(t) = A \cos(\omega t) + B \sin(\omega t)$ solves the equation of motion. What is ω ?

3. Geodesics on a sphere

A particle constrained to move on the surface of a sphere of radius R moves freely (no potential). Its Kinetic energy is given, in spherical coordinates (r, θ, ϕ) , by

$$T = \frac{1}{2}m \left(R^2 \dot{\theta}^2 + R^2 \sin^2 \theta \dot{\phi}^2 \right).$$

- (a) Use Hamilton's principle to derive the geodesic equations.
Remember that for motion on the sphere, $r = R$ (constant), so the kinetic energy depends only on θ and ϕ .