

GROUP 17



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Group 17 presents

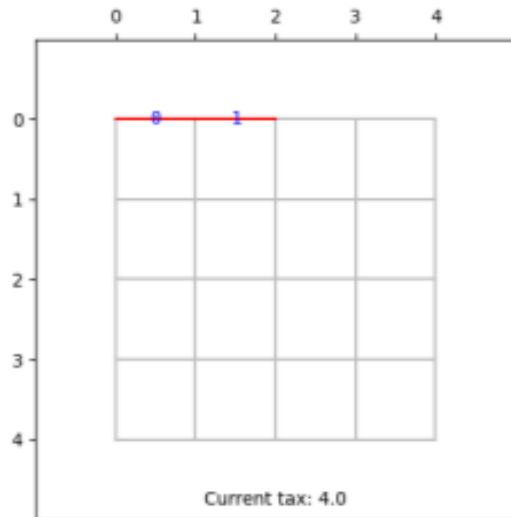


THE PENNILESS PILGRIM RIDDLE

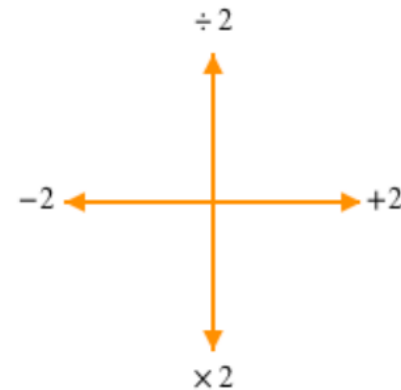
An Introduction to AI group project

PROBLEM DESCRIPTION

- Inspired by [this TED-ED video](#)
- There's a strange tax in this city
- Can you find your way to goal without having to pay?



The initial state of the game in the video

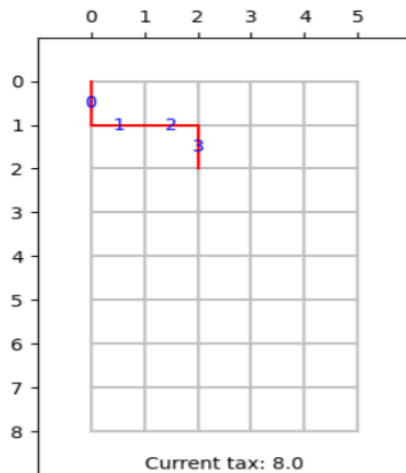


The tax fluctuate differently based on direction

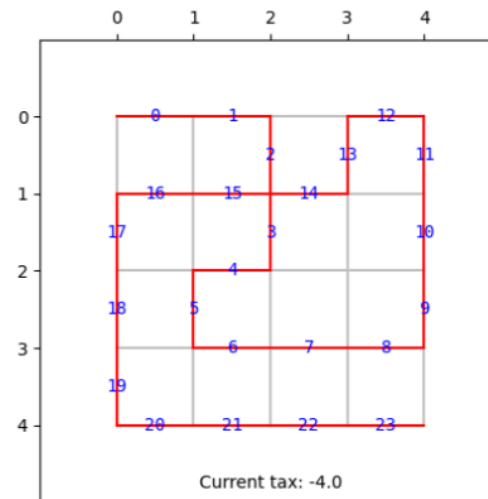


PROBLEM FORMULATION

- Single-state problem, solving by searching
- Randomized initial board sizes: 4 to 8 each side
- 4 available actions: U, D, L, R
- Output: time complexity, space complexity



One of the randomized initial states



Example solution



DEPTH-FIRST SEARCH (DFS)

- Depth-first Search vs. Breadth-first Search:

Averaging/assuming two branches per node, $c = m \cdot n$ nodes with depth $d = c/2$

	DFS	BFS
Principle	Expand nodes of the same branch, until depth reached.	Expand all nodes of the same depth.
Space complexity (Theory)	$O(2 \times c)$	$O(2^{d+1})$
Space complexity (Practice)	$O(2 \times (m - 2) \times (n - 1))$	$O(2^{d+1})$
Time complexity (Theory)	$O(2^c)$	$O(2^{d+1})$
Time complexity (Practice)	$O(2^{(m-2)(n-1)})$	$O(2^{d+1})$

- However, DFS never reaches worst-case for space and time complexity, no guarantee for BFS

⇒ DFS more suitable



DFS IMPLEMENTATION

- t_limit: 10 seconds
- Simple recursive DFS implementation

```
#!/pseudo/code
func dfs(curr) -> None:
    if time_limit_reached(): exit();
    for move in curr.available_moves_list():
        temp = copy(curr)
        temp.move_to(move)

        if temp.current_pos == START.current_pos and \
            temp.current_tax >= START.current_tax:
            save_path();
            exit();

        temp.path = copy(curr.path);
        dfs(temp);

main:
    dfs(GOAL);
```

- Difficulties: No setbacks aside from needing decent CPU and plenty of RAM.



A-STAR SEARCH (A^*)

- Heuristic problem: none actually worked for majority of boards => “bending” definition
- Implementing code
- Difficulties in implementing:

- Finding a solution to the heuristic problem:

For the sake of simple heuristic, understandable in a peek, without over-arching presentation time limit, we settled on a simple heuristic instead, accepting that solution is imperfect.

- Dropping optimal path searching:

Cannot design true heuristic within the time available

- Simple formula, space-friendly, not optimal, can be pessimistic, guides A^* to solution



RECURSIVE BEST-FIRST SEARCH (RBFS)

- Applying RBFS algorithm
- Some difficulties:
 - Estimating heuristic unlikely to be correct because non-uniformly changing path cost
 - Can be stuck in infinite loop
 - Not good enough heuristic leads to skipping some branches, not finding the ideal solution
 - Difficult balancing time and space complexity
 - Data samples may be unsolvable, not easy to prove

Recursive best-first search algorithm

```
function RECURSIVE-BEST-FIRST-SEARCH(problem) return a solution or failure
  return RFBS(problem, MAKE-NODE(INITIAL-STATE[problem]), ∞)
```

```
function RFBS(problem, node, f_limit) return a solution or failure and a new f-cost limit
  if GOAL-TEST[problem](STATE[node]) then return node
  successors ← EXPAND(node, problem)
  if successors is empty then return failure, ∞
  for each s in successors do
    f[s] ← max(g(s) + h(s), f[node])
  repeat
    best ← the lowest f-value node in successors
    if f[best] > f_limit then return failure, f[best]
    alternative ← the second lowest f-value among successors
    result, f[best] ← RBFS(problem, best, min(f_limit, alternative))
  if result ≠ failure then return result
```


COMPARING ALGORITHMS' RESULTS

Algorithms	DFS	RBFS	A* Search
Board solved (out of 49)	28	49	47
Total Number of Iterations	70808	150951	45049
Total Running Time for solved Boards (s)	111.3305	57.5106	252.1998
Average Algorithm Memory Consumption (GB)	0.2	0.3	0.1
Peak Algorithm Memory Consumption (GB)	0.4	0.4	0.2
Peak CPU usage (%)	67	100	45
Average CPU usage (%)	40	100	38
Peak CPU Clock-speed (GHz)	3.65	2.87	3.81

Recap:

- Did it find a solution? : $RBFS > A^* > DFS$
- How fast?: $RBFS > DFS > A^*$
- Space-efficient?: $A^* > DFS > RBFS$



CONCLUSION

- Search algorithms:

- RBFS most suitable
- A* not suitable due to having to take into account unpredictable cost up to the expanding node
- DFS finds solution quickly if expanded from goal; however, it fails on all boards that start only has one way to reach goal, and adjacent node has less than 3 possible moves

- Possible extensions:

Road removal, path length limit, random modifiers, time constraint, etc.



REFERENCES AND ADDITIONAL LINKS

- TED-ED's video: <https://youtu.be/6sBB-gRhfiE>
- Demo program:
https://github.com/PySimpleGUI/PySimpleGUI/blob/master/DemoPrograms/Demo_Matplotlib_Embedded_Toolbar.py
- GitHub repository: : <https://github.com/htnminh/Al-intro-project>
- Project website: <https://htnminh.github.io/Al-intro-project/>
- Report notion page: <https://htnminh.notion.site/The-Penniless-Pilgrim-Riddle-e3bbfaf5d7b949fdadf5a898df1f8883>

