UNIVERSITY OF ASIA PACIFIC DEP F OF CSE

HASAN TAMSIN RAFSAN A SECTION 4PH YEAR 1ST SEMESTER CLASS TEST - 3 CSE-403 Ans!

Markov model is a stochastic model used to model possible trandomly changing system. which assumes butwe states depended and on the current state. This assumption enables transoning Se computition with the model

Here, value of n det. 9 given time could stated

parameters: called transition phobabilies of dynamics specifies how the state envolves over time. Stationary assumption: transition probabilities the same at all times.

Joint distribution

P(x1, x2, x3,x4) = P(x1) P(x2/x1) P(x3/x2) P(x4/x)

Chain Rule: /P (x1; x2, x3, xw = P(x1) P(x2/x1) P(x3/x);

x2) P(x4/x1, x2, x3)

Implied conditional of Independencies.

X3 IL ×11×2 20 ×4 IL ×1, ×21×3

These are those assumption to make
movilsor model possible

NO 0003

Ani 2 12 = 1801009

last 2 dig = 09

So, here.

A = 09/100 = 0.09

1 - 0.09 = 0.91

\$ = 59Rt (09)/10=0.3

c = 1-0.3 = 0.7.

- P-4 WO Was table Pero balatly (wed) Tue 8.09 solvedy aloudy 0.91 not cloudy- 1 cloudy not cloudy cloudy 0.3 not cloudy not cloudy 0.3 cloudy not cloudy 0.09 0.91

> let, $x_1 = \text{true}$. $x_2 = \text{wed}$.

Need To cole = P(X 2 = not close)

1501009 morror chin we get P(wed) (0.09 × 0.91) + (0.3 × 0.7) 0,081970.21=0,2919 PCAN = rotated - X 2 = 40 P(x2=cloudy) x2 = cloudy P(x1 = cloudy)+ P(12=cloudy /x1=notcloudy)=P(29= not cloudy)

(0.09 + 0.91) + (0.3 * 0.7) = 0.2919 (And) p(x2 = Not cloudy) = 0.2917 (Am)