



Chapter 10: Storage and File Structure

Database System Concepts, 6th Ed.

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Chapter 10: Storage and File Structure

- Overview of Physical Storage Media
- Magnetic Disks
- RAID
- Tertiary Storage
- Storage Access
- File Organization
- Organization of Records in Files
- Data-Dictionary Storage



Classification of Physical Storage Media

- Speed with which data can be accessed
- Cost per unit of data
- Reliability
 - data loss on power failure or system crash
 - physical failure of the storage device
- Can differentiate storage into:
 - **volatile storage:** loses contents when power is switched off
 - **non-volatile storage:**
 - ▶ Contents persist even when power is switched off.
 - ▶ Includes secondary and tertiary storage, as well as battery-backed up main-memory.



Physical Storage Media

- **Cache** – fastest and most costly form of storage; volatile; managed by the computer system hardware.
- **Main memory:**
 - fast access (10s to 100s of nanoseconds; 1 nanosecond = 10^{-9} seconds)
 - generally too small (or too expensive) to store the entire database
 - ▶ capacities of up to a few Gigabytes widely used currently
 - ▶ Capacities have gone up and per-byte costs have decreased steadily and rapidly (roughly factor of 2 every 2 to 3 years)
- **Volatile** — contents of main memory are usually lost if a power failure or system crash occurs.



Physical Storage Media (Cont.)

□ Flash memory

- Data survives power failure
- Data can be written at a location only once, but location can be erased and written to again
 - ▶ Can support only a limited number (10K – 1M) of write/erase cycles.
 - ▶ Erasing of memory has to be done to an entire bank of memory
- Reads are roughly as fast as main memory
- But writes are slow (few microseconds), erase is slower
- Widely used in embedded devices such as digital cameras, phones, and USB keys



Physical Storage Media (Cont.)

□ Magnetic-disk

- Data is stored on spinning disk, and read/written magnetically
- Primary medium for the long-term storage of data; typically stores entire database.
- Data must be moved from disk to main memory for access, and written back for storage
 - ▶ Much slower access than main memory (more on this later)
- **direct-access** – possible to read data on disk in any order, unlike magnetic tape
- Capacities range up to roughly 1.5 TB as of 2009
 - ▶ Much larger capacity and cost/byte than main memory/flash memory
 - ▶ Growing constantly and rapidly with technology improvements (factor of 2 to 3 every 2 years)
- Survives power failures and system crashes
 - ▶ disk failure can destroy data, but is rare



Physical Storage Media (Cont.)

□ Optical storage

- non-volatile, data is read optically from a spinning disk using a laser
- CD-ROM (640 MB) and DVD (4.7 to 17 GB) most popular forms
- Blu-ray disks: 27 GB to 54 GB
- Write-one, read-many (WORM) optical disks used for archival storage (CD-R, DVD-R, DVD+R)
- Multiple write versions also available (CD-RW, DVD-RW, DVD+RW, and DVD-RAM)
- Reads and writes are slower than with magnetic disk
- **Juke-box** systems, with large numbers of removable disks, a few drives, and a mechanism for automatic loading/unloading of disks available for storing large volumes of data



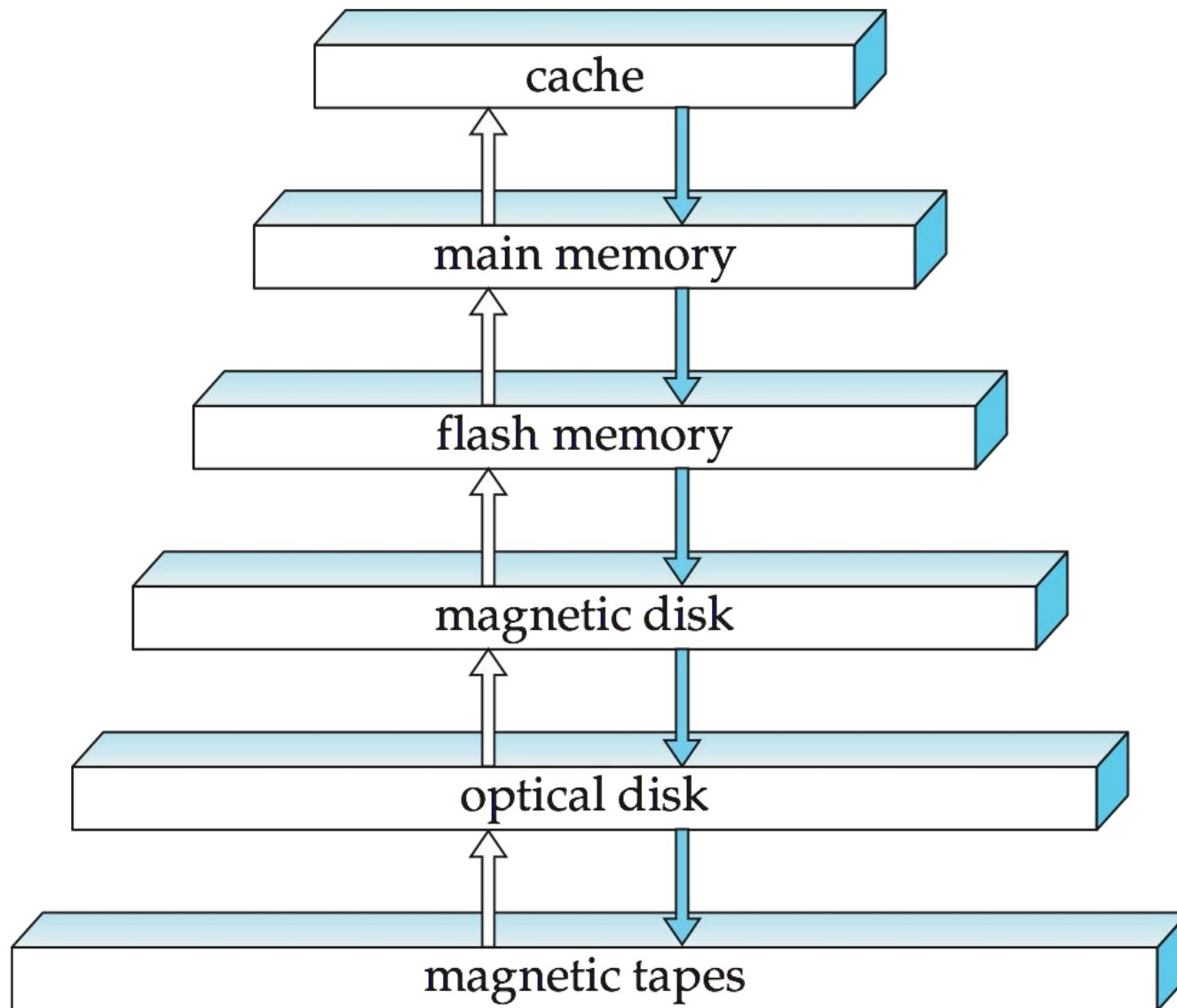
Physical Storage Media (Cont.)

□ Tape storage

- non-volatile, used primarily for backup (to recover from disk failure), and for archival data
- **sequential-access** – much slower than disk
- very high capacity (40 to 300 GB tapes available)
- tape can be removed from drive \Rightarrow storage costs much cheaper than disk, but drives are expensive
- Tape jukeboxes available for storing massive amounts of data
 - ▶ hundreds of terabytes (1 terabyte = 10^9 bytes) to even multiple **petabytes** (1 petabyte = 10^{12} bytes)



Storage Hierarchy





Storage Hierarchy (Cont.)

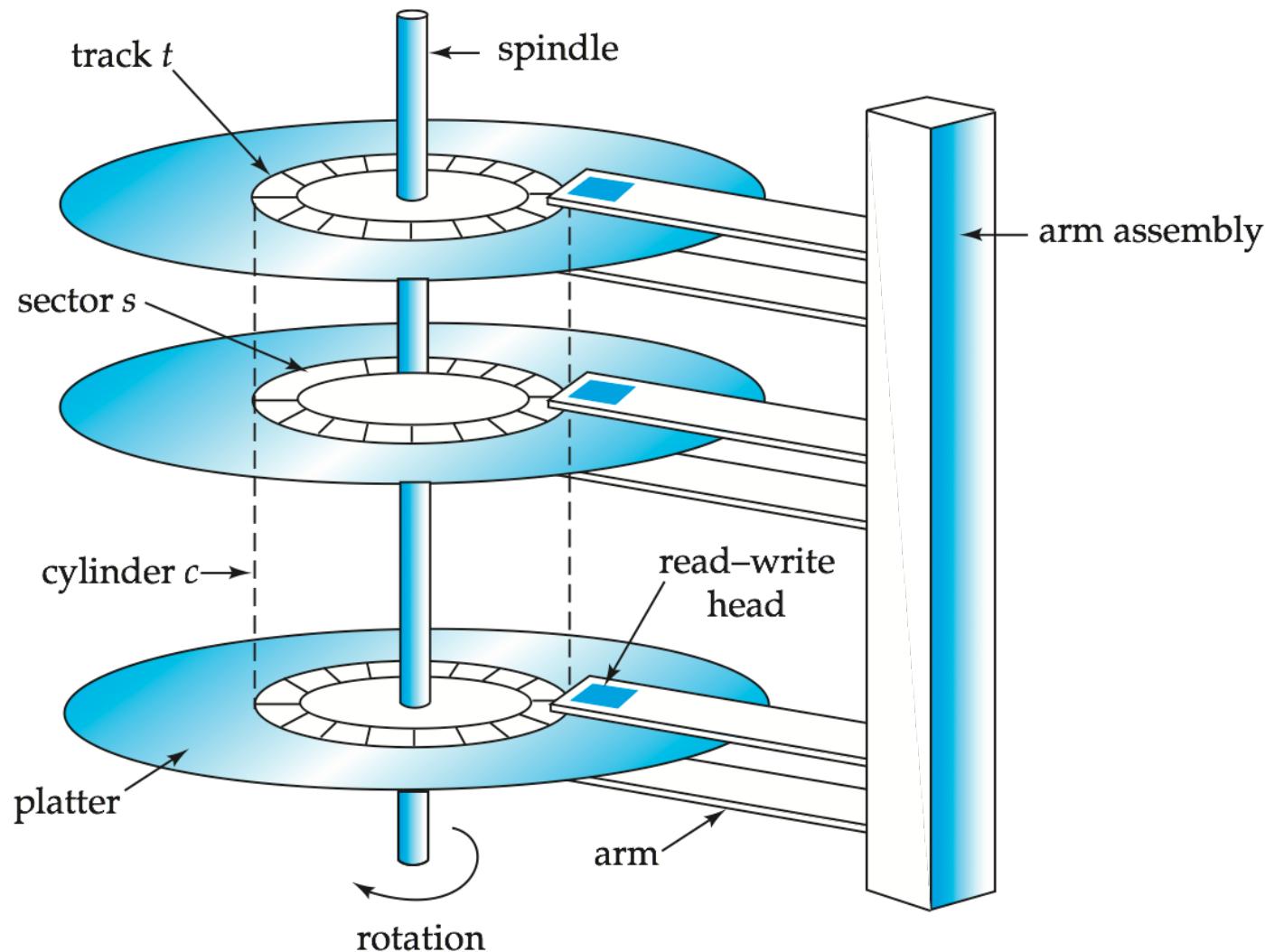
- **primary storage:** Fastest media but volatile (cache, main memory).
- **secondary storage:** next level in hierarchy, non-volatile, moderately fast access time
 - also called **on-line storage**
 - E.g. flash memory, magnetic disks
- **tertiary storage:** lowest level in hierarchy, non-volatile, slow access time
 - also called **off-line storage**
 - E.g. magnetic tape, optical storage



Magnetic Hard Disk Mechanism

Surface of platter divided into circular **tracks**

Each track is divided into **sectors**.



NOTE: Diagram is schematic, and simplifies the structure of actual disk drives



Magnetic Disks

- **Read-write head**
 - Positioned very close to the platter surface (almost touching it)
 - Reads or writes magnetically encoded information.
- Surface of platter divided into circular **tracks**
 - Over 50K-100K tracks per platter on typical hard disks
- Each track is divided into **sectors**.
 - A sector is the smallest unit of data that can be read or written.
 - Sector size typically 512 bytes
 - Typical sectors per track: 500 to 1000 (on inner tracks) to 1000 to 2000 (on outer tracks)
- To read/write a sector
 - disk arm swings to position head on right track
 - platter spins continually; data is read/written as sector passes under head
- Head-disk assemblies
 - multiple disk platters on a single spindle (1 to 5 usually)
 - one head per platter, mounted on a common arm.
- **Cylinder** i consists of i^{th} track of all the platters

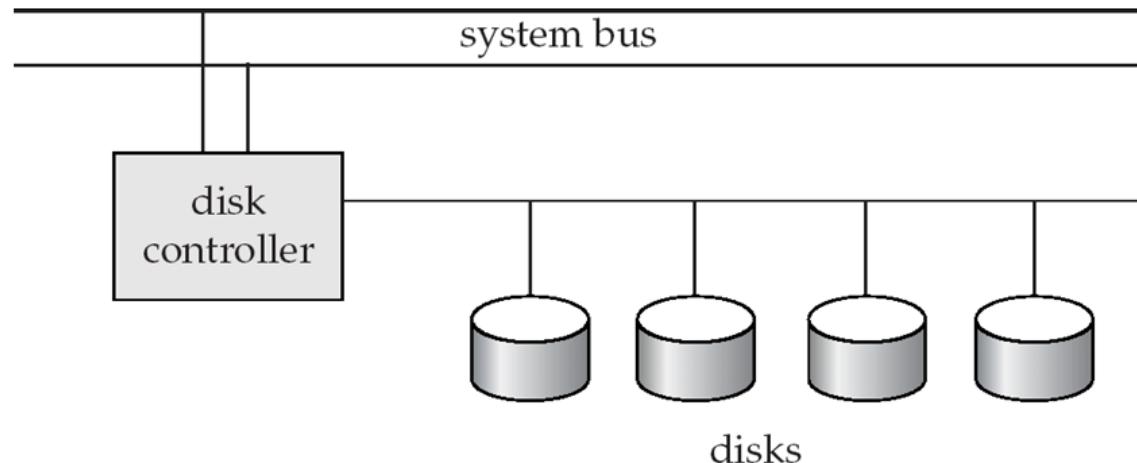


Magnetic Disks (Cont.)

- Earlier generation disks were susceptible to head-crashes
 - Surface of earlier generation disks had metal-oxide coatings which would disintegrate on head crash and damage all data on disk
 - Current generation disks are less susceptible to such disastrous failures, although individual sectors may get corrupted
- **Disk controller** – interfaces between the computer system and the disk drive hardware.
 - accepts high-level commands to read or write a sector
 - initiates actions such as moving the disk arm to the right track and actually reading or writing the data
 - Computes and attaches **checksums** to each sector to verify that data is read back correctly
 - ▶ If data is corrupted, with very high probability stored checksum won't match recomputed checksum
 - Ensures successful writing by reading back sector after writing it
 - Performs **remapping of bad sectors**



Disk Subsystem



- Multiple disks connected to a computer system through a controller
 - Controllers functionality (checksum, bad sector remapping) often carried out by individual disks; reduces load on controller
- Disk interface standards families
 - ATA (AT adaptor) range of standards
 - SATA (Serial ATA)
 - SCSI (Small Computer System Interconnect) range of standards
 - SAS (Serial Attached SCSI)
 - Several variants of each standard (different speeds and capabilities)



Disk Subsystem

- Disks usually connected directly to computer system
- In **Storage Area Networks (SAN)**, a large number of disks are connected by a high-speed network to a number of servers
- In **Network Attached Storage (NAS)** networked storage provides a file system interface using networked file system protocol, instead of providing a disk system interface



Performance Measures of Disks

- **Access time** – the time it takes from when a read or write request is issued to when data transfer begins. Consists of:
 - **Seek time** – time it takes to reposition the arm over the correct track.
 - ▶ Average seek time is 1/2 the worst case seek time.
 - Would be 1/3 if all tracks had the same number of sectors, and we ignore the time to start and stop arm movement
 - ▶ 4 to 10 milliseconds on typical disks
 - **Rotational latency** – time it takes for the sector to be accessed to appear under the head.
 - ▶ Average latency is 1/2 of the worst case latency.
 - ▶ 4 to 11 milliseconds on typical disks (5400 to 15000 r.p.m.)
- **Data-transfer rate** – the rate at which data can be retrieved from or stored to the disk.
 - 25 to 100 MB per second max rate, lower for inner tracks
 - Multiple disks may share a controller, so rate that controller can handle is also important
 - ▶ E.g. SATA: 150 MB/sec, SATA-II 3Gb (300 MB/sec)
 - ▶ Ultra 320 SCSI: 320 MB/s, SAS (3 to 6 Gb/sec)
 - ▶ Fiber Channel (FC2Gb or 4Gb): 256 to 512 MB/s



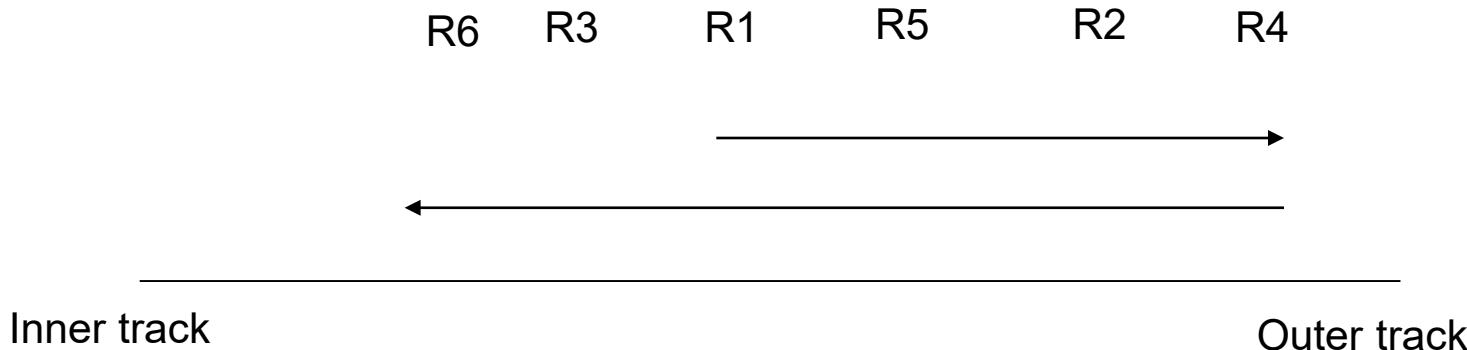
Performance Measures (Cont.)

- **Mean time to failure (MTTF)** – the average time the disk is expected to run continuously without any failure.
 - Typically 3 to 5 years
 - Probability of failure of new disks is quite low, corresponding to a “theoretical MTTF” of 500,000 to 1,200,000 hours for a new disk
 - ▶ E.g., an MTTF of 1,200,000 hours for a new disk means that given 1000 relatively new disks, on an average one will fail every 1200 hours
 - MTTF decreases as disk ages



Optimization of Disk-Block Access

- **Block** – a contiguous sequence of sectors from a single track
 - data is transferred between disk and main memory in blocks
 - sizes range from 512 bytes to several kilobytes
 - ▶ Smaller blocks: more transfers from disk
 - ▶ Larger blocks: more space wasted due to partially filled blocks
 - ▶ Typical block sizes today range from 4 to 16 kilobytes
- **Disk-arm-scheduling** algorithms order pending accesses to tracks so that disk arm movement is minimized
 - **elevator algorithm:**





Optimization of Disk Block Access (Cont.)

- **File organization** – optimize block access time by organizing the blocks to correspond to how data will be accessed
 - E.g. Store related information on the same or nearby cylinders.
 - Files may get **fragmented** over time
 - ▶ E.g. if data is inserted to/deleted from the file
 - ▶ Or free blocks on disk are scattered, and newly created file has its blocks scattered over the disk
 - ▶ Sequential access to a fragmented file results in increased disk arm movement
 - Some systems have utilities to **defragment** the file system, in order to speed up file access



Optimization of Disk Block Access (Cont.)

- **Nonvolatile write buffers** speed up disk writes by writing blocks to a non-volatile RAM buffer immediately
 - Non-volatile RAM: battery backed up RAM or flash memory
 - Even if power fails, the data is safe and will be written to disk when power returns
 - Controller then writes to disk whenever the disk has no other requests or request has been pending for some time
 - Database operations that require data to be safely stored before continuing can continue without waiting for data to be written to disk
 - *Writes can be reordered to minimize disk arm movement*
- **Log disk** – a disk devoted to writing a sequential log of block updates
 - Used exactly like nonvolatile RAM
 - Write to log disk is very fast since no seeks are required
 - No need for special hardware (NV-RAM)
- File systems typically reorder writes to disk to improve performance
 - **Journaling file systems** write data in safe order to NV-RAM or log disk
 - Reordering without journaling: risk of corruption of file system data



Flash Storage

- NOR flash vs NAND flash
- NAND flash
 - used widely for storage, since it is much cheaper than NOR flash
 - requires page-at-a-time read (page: 512 bytes to 4 KB)
 - transfer rate around 20 MB/sec
 - **solid state disks**: use multiple flash storage devices to provide higher transfer rate of 100 to 200 MB/sec
 - erase is very slow (1 to 2 millisecs)
 - ▶ erase block contains multiple pages
 - ▶ **remapping** of logical page addresses to physical page addresses avoids waiting for erase
 - **translation table** tracks mapping
 - » also stored in a label field of flash page
 - remapping carried out by **flash translation layer**
 - ▶ after 100,000 to 1,000,000 erases, erase block becomes unreliable and cannot be used
 - **wear leveling**



RAID

- **RAID: Redundant Arrays of Independent Disks**
 - disk organization techniques that manage a large numbers of disks, providing a view of a single disk of
 - ▶ **high capacity** and **high speed** by using multiple disks in parallel,
 - ▶ **high reliability** by storing data redundantly, so that data can be recovered even if a disk fails
- The chance that some disk out of a set of N disks will fail is much higher than the chance that a specific single disk will fail.
 - E.g., a system with 100 disks, each with MTTF of 100,000 hours (approx. 11 years), will have a system MTTF of 1000 hours (approx. 41 days)
 - Techniques for using redundancy to avoid data loss are critical with large numbers of disks
- Originally a cost-effective alternative to large, expensive disks
 - I in RAID originally stood for ``inexpensive''
 - Today RAIDs are used for their higher reliability and bandwidth.
 - ▶ The “I” is interpreted as independent



Improvement of Reliability via Redundancy

- **Redundancy** – store extra information that can be used to rebuild information lost in a disk failure
- E.g., **Mirroring** (or **shadowing**)
 - Duplicate every disk. Logical disk consists of two physical disks.
 - Every write is carried out on both disks
 - ▶ Reads can take place from either disk
 - If one disk in a pair fails, data still available in the other
 - ▶ Data loss would occur only if a disk fails, and its mirror disk also fails before the system is repaired
 - Probability of combined event is very small
 - » Except for dependent failure modes such as fire or building collapse or electrical power surges
- **Mean time to data loss** depends on mean time to failure, and **mean time to repair**
 - E.g. MTTF of 100,000 hours, mean time to repair of 10 hours gives mean time to data loss of $500 \cdot 10^6$ hours (or 57,000 years) for a mirrored pair of disks (ignoring dependent failure modes)



Improvement in Performance via Parallelism

- Two main goals of parallelism in a disk system:
 1. Load balance multiple small accesses to increase throughput
 2. Parallelize large accesses to reduce response time.
- Improve transfer rate by striping data across multiple disks.
- **Bit-level striping** – split the bits of each byte across multiple disks
 - In an array of eight disks, write bit i of each byte to disk i .
 - Each access can read data at eight times the rate of a single disk.
 - But seek/access time worse than for a single disk
 - ▶ Bit level striping is not used much any more
- **Block-level striping** – with n disks, block i of a file goes to disk $(i \bmod n) + 1$
 - Requests for different blocks can run in parallel if the blocks reside on different disks
 - A request for a long sequence of blocks can utilize all disks in parallel

See the def of Seek time
book page 435 10.2.2
Performance Measures
of Disks



RAID Levels

- Schemes to provide redundancy at lower cost by using disk striping combined with parity bits
 - Different RAID organizations, or RAID levels, have differing cost, performance and reliability characteristics
- **RAID Level 0:** Block striping; non-redundant. (2 or more disks)
 - Used in high-performance applications where data loss is not critical.
 - Striping at the level of blocks
 - Data split across drives resulting in higher data throughput
 - Performance is very good but the failure of any disk in the array results in data loss
 - RAID 0 commonly referred to as striping
 - Reliability Problems
 - No mirroring or parity bits



RAID Level 0

- **Performance**
- A RAID 0 array of n drives provides data read and write transfer rates up to n times higher than the individual drive rates, but with no data redundancy. As a result, RAID 0 is primarily used in applications that require high performance and are able to tolerate lower reliability, such as in scientific computing or computer gaming.





RAID Level 1

- RAID Level 1: Mirrored disks with block striping
 - RAID 1 consists of an exact copy (or mirror) of a set of data on two or more disks; a classic RAID 1 mirrored pair contains two disks.
 - This configuration offers no parity, striping, or spanning of disk space across multiple disks, since the data is mirrored on all disks belonging to the array, and the array can only be as big as the smallest member disk.
 - Classic RAID 1 mirrored pair contains two disks (see diagram), which increases reliability geometrically over a single disk.
 - The array will continue to operate so long as at least one member drive is operational.
 - Popular for applications such as storing log files in a database system.



RAID Levels

□ Performance

- Any read request can be serviced and handled *by any drive in the array*; thus, depending on the nature of I/O load, random read performance of a RAID 1 array may equal up to the sum of each member's performance, while the write performance remains at the level of a single disk. However, if disks with different speeds are used in a RAID 1 array, overall write performance is equal to the speed of the slowest disk





RAID Levels (Cont.)

□ RAID Level 2: Bit-Interleaved Parity

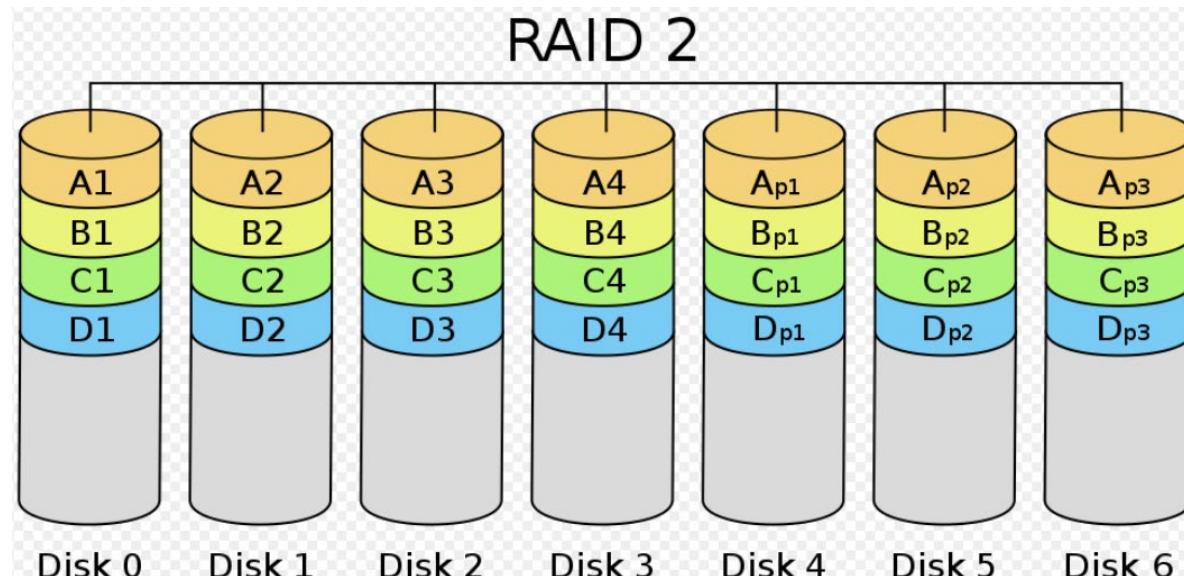
- **RAID 2**, which is rarely used in practice, stripes data at the bit (rather than block) level,
- Known as memory-style error-correcting-code (ECC) organization, employs parity bits.
- Memory systems have long used parity bits for error detection and correction. Each byte in a memory system may have a parity bit associated with it that records whether the numbers of bits in the byte that are set to 1 is even (parity = 0) or odd (parity = 1). If one of the bits in the byte gets damaged (either a 1 becomes a 0, or a 0 becomes a 1), the parity of the byte changes and thus will not match the stored parity. Similarly, if the stored parity bit gets damaged, it will not match the computed parity.
- Thus, all 1-bit errors will be detected by the memory system. Error-correcting schemes store 2 or more extra bits, and can reconstruct the data if a single bit gets damaged.



RAID Levels (Cont.)

□ RAID Level 2: Bit-Interleaved Parity

- Figure in below shows the level 2 scheme. The disks labeled *P* store the error correction bits. If one of the disks fails, the remaining bits of the byte and the associated error-correction bits can be read from other disks, and can be used to reconstruct the damaged data. It shows an array of size 4; note RAID level 2 requires only three disks' overhead for four disks of data, unlike RAID level 1, which required four disks' overhead.





RAID Levels (Cont.)

□ RAID Level 3

- RAID 3, which is rarely used in practice, consists of byte-level striping with a dedicated parity disk.
- Subsumes Level 2 (provides all its benefits, at lower cost).
- Consists of **byte-level striping** with a dedicated parity disk.
- It uses **disk controllers**, unlike memory systems, can detect whether a sector has been read correctly, so a **parity** can be used for error correction, as well as for detection.
- The idea is as follows: If one of the sectors gets damaged, the system knows exactly which sector it is, and, for each bit in the sector, the system can figure out whether it is a 1 or a 0 by computing the parity of the corresponding bits from sectors in the other disks. If the parity of the remaining bits is equal to the stored parity, the missing bit is 0; otherwise, it is 1.



RAID Levels (Cont.)

□ RAID Level 3

- RAID level 3 is as good as level 2, but is less expensive in the number of extra disks (it has only a one-disk overhead), so level 2 is not used in practice. Figure in below shows the level 3 scheme.

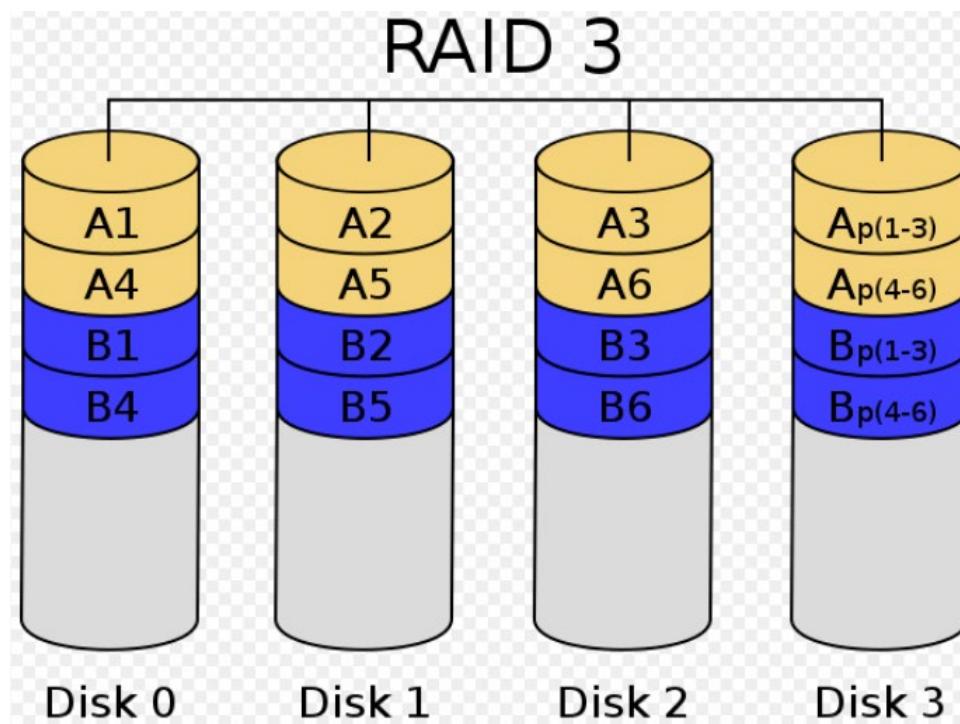


Diagram of a RAID 3 setup of six-byte blocks and two parity bytes, shown are two blocks of data in different colors.



RAID Levels (Cont.)

□ RAID Level 3

- RAID level 3 has two benefits over level 1. It needs only one parity disk for several regular disks, whereas level 1 needs one mirror disk for every disk, and thus level 3 reduces the storage overhead.
- Since reads and writes of a byte are spread out over multiple disks, with N-way striping of data, the transfer rate for reading or writing a single block is N times faster than a RAID level 1 organization using N-way striping.
- On the other hand, RAID level 3 supports a lower number of I/O operations per second, since every disk has to participate in every I/O request.
- Because the parity information is on a separate disk, RAID 3 does not perform well when tasked with numerous small data requests. RAID 3 is a better choice for applications that have long sequential data transfers, such as streaming media, graphics and video editing.



RAID Levels (Cont.)

□ RAID Level 4

- RAID 4 consists of block-level striping with a dedicated parity disk.
- **Block-interleaved parity organization**, uses block-level striping, like RAID 0, and in addition keeps a parity block on a separate disk for corresponding blocks from N other disks.
- If one of the disks fails, the parity block can be used with the corresponding blocks from the other disks to restore the blocks of the failed disk.
- A block read accesses only one disk, allowing other requests to be processed by the other disks. Thus, the data-transfer rate for each access is slower, but multiple read accesses can proceed in parallel, leading to a higher over all I/O rate. The transfer rates for large reads is high, since all the disks can be read in parallel; large writes also have high transfer rates, since the data and parity can be written in parallel.



RAID Levels (Cont.)

□ RAID Level 4 (Cont.)

- Small independent writes, on the other hand, cannot be performed in parallel. A write of a block has to access the disk on which the block is stored, as well as the parity disk, since the parity block has to be updated. Moreover, both the old value of the parity block and the old value of the block being written have to be read for the new parity to be computed. Thus, a single write requires four disk accesses: two to read the two old blocks, and two to write the two blocks.

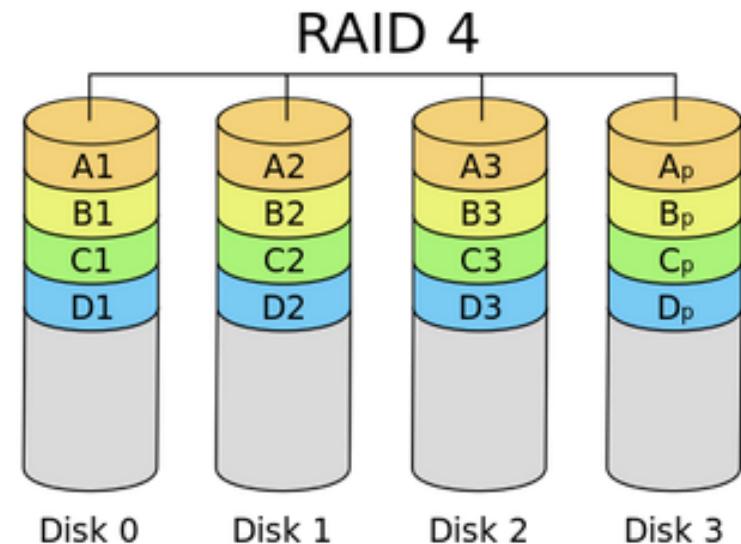


Diagram 1: A RAID 4 setup with dedicated parity  disk with each color representing the group of blocks in the respective parity block (a stripe)



RAID Levels (Cont.)

- RAID Level 5: Block-Interleaved Distributed Parity; block-interleaved distributed parity (same as RAID Level 5)
- It improves on level 4 by partitioning data and parity among all N+1 disks, instead of storing data in N disks and parity in one disk.
- In level 5, all disks can participate in satisfying read requests, unlike RAID level 4, where the parity disk cannot participate, so level 5 increases the total number of requests that can be met in a given amount of time.
- For each set of N logical blocks, one of the disk stores the parity, and the other N disks store the blocks..

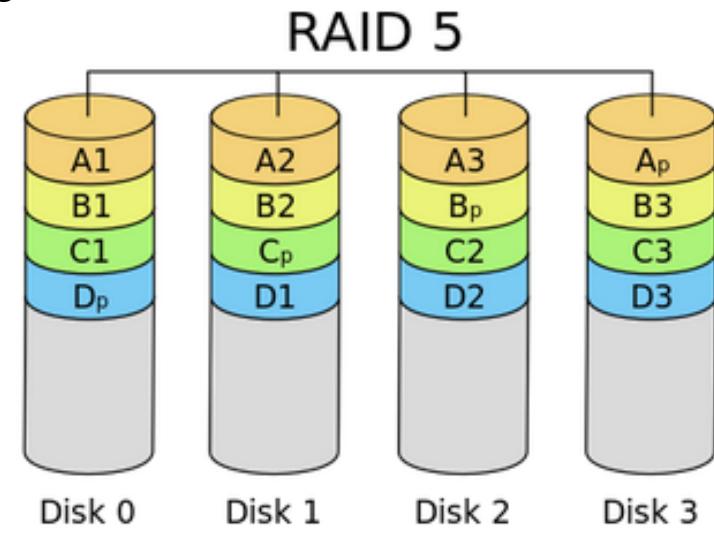


Diagram of a RAID 5 setup with distributed parity with each color representing the group of blocks in the respective parity block (a stripe). This diagram shows left asymmetric algorithm



RAID Levels (Cont.)

□ RAID Level 5 (Cont.)

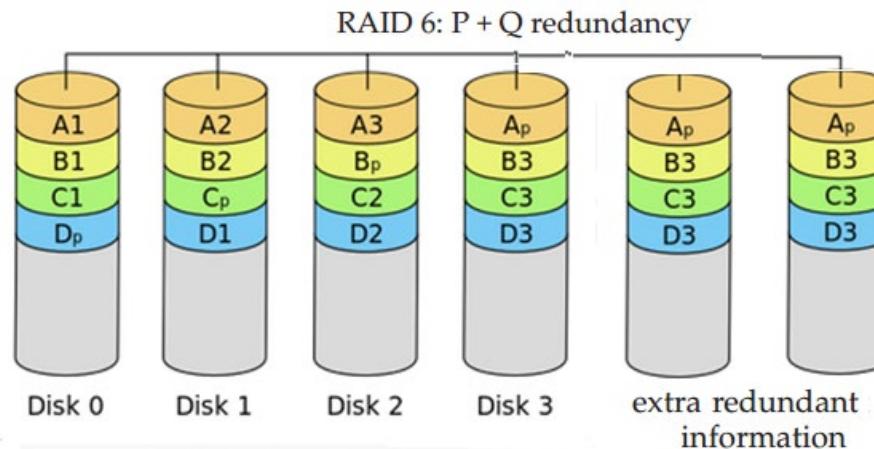
- Below shows the setup. The P's are distributed across all the disks. For example, with an array of 5 disks, the parity block, labeled P_k , for logical blocks $k, 4k+1, 4k+2, 4k+3$ is stored in disk $k \bmod 5$; the corresponding blocks of the other four disks store the 4 data blocks $4k$ to $4k+3$. The following table indicates how the first 20 blocks, numbered 0 to 19, and their parity blocks are laid out. The pattern shown gets repeated on further blocks.
- Note that a parity block cannot store parity for blocks in the same disk, since then a disk failure would result in loss of data as well as of parity, and hence would not be recoverable.
- Level 5 subsumes level 4, since it offers better read –write performance at the same cost, so level 4 is not used in practice.

P0	0	1	2	3
4	P1	5	6	7
8	9	P2	10	11
12	13	14	P3	15
16	17	18	19	P4



RAID Levels (Cont.)

- **RAID Level 6: P+Q Redundancy** scheme; similar to Level 5, but stores extra redundant information to guard against multiple disk failures.
 - the P + Q redundancy scheme, is much like RAID level 5, but stores extra redundant information to guard against multiple disk failures.
 - Instead of using parity, level 6 uses error-correcting codes such as the Reed–Solomon codes.
 - In the scheme, 2 bits of redundant data are stored for every 4 bits of data—unlike 1 parity bit in level 5—and the system can tolerate two disk failures..





Choice of RAID Level

- Factors in choosing RAID level
 - Monetary cost
 - Performance: Number of I/O operations per second, and bandwidth during normal operation
 - Performance during failure
 - Performance during rebuild of failed disk
 - ▶ Including time taken to rebuild failed disk
- RAID 0 is used only when data safety is not important
 - E.g. data can be recovered quickly from other sources
- Level 2 and 4 never used since they are subsumed by 3 and 5
- Level 3 is not used anymore since bit-striping forces single block reads to access all disks, wasting disk arm movement, which block striping (level 5) avoids
- Level 6 is rarely used since levels 1 and 5 offer adequate safety for most applications



Choice of RAID Level (Cont.)

- Level 1 provides much better write performance than level 5
 - Level 5 requires at least 2 block reads and 2 block writes to write a single block, whereas Level 1 only requires 2 block writes
 - Level 1 preferred for high update environments such as log disks
- Level 1 had higher storage cost than level 5
 - disk drive capacities increasing rapidly (50%/year) whereas disk access times have decreased much less (x 3 in 10 years)
 - I/O requirements have increased greatly, e.g. for Web servers
 - When enough disks have been bought to satisfy required rate of I/O, they often have spare storage capacity
 - ▶ so there is often no extra monetary cost for Level 1!
- Level 5 is preferred for applications with low update rate, and large amounts of data
- Level 1 is preferred for all other applications



Hardware Issues

- **Software RAID:** RAID implementations done entirely in software, with no special hardware support
- **Hardware RAID:** RAID implementations with special hardware
 - Use non-volatile RAM to record writes that are being executed
 - Beware: power failure during write can result in corrupted disk
 - ▶ E.g. failure after writing one block but before writing the second in a mirrored system
 - ▶ Such corrupted data must be detected when power is restored
 - Recovery from corruption is similar to recovery from failed disk
 - NV-RAM helps to efficiently detect potentially corrupted blocks
 - » Otherwise all blocks of disk must be read and compared with mirror/parity block



Hardware Issues (Cont.)

- **Latent failures:** data successfully written earlier gets damaged
 - can result in data loss even if only one disk fails
- **Data scrubbing:**
 - continually scan for latent failures, and recover from copy/parity
- **Hot swapping:** replacement of disk while system is running, without power down
 - Supported by some hardware RAID systems,
 - reduces time to recovery, and improves availability greatly
- Many systems maintain **spare disks** which are kept online, and used as replacements for failed disks immediately on detection of failure
 - Reduces time to recovery greatly
- Many hardware RAID systems ensure that a single point of failure will not stop the functioning of the system by using
 - Redundant power supplies with battery backup
 - Multiple controllers and multiple interconnections to guard against controller/interconnection failures



Optical Disks

- Compact disk-read only memory (CD-ROM)
 - Removable disks, 640 MB per disk
 - Seek time about 100 msec (optical read head is heavier and slower)
 - Higher latency (3000 RPM) and lower data-transfer rates (3-6 MB/s) compared to magnetic disks
- Digital Video Disk (DVD)
 - DVD-5 holds 4.7 GB , and DVD-9 holds 8.5 GB
 - DVD-10 and DVD-18 are double sided formats with capacities of 9.4 GB and 17 GB
 - Blu-ray DVD: 27 GB (54 GB for double sided disk)
 - Slow seek time, for same reasons as CD-ROM
- Record once versions (CD-R and DVD-R) are popular
 - data can only be written once, and cannot be erased.
 - high capacity and long lifetime; used for archival storage
 - Multi-write versions (CD-RW, DVD-RW, DVD+RW and DVD-RAM) also available



Magnetic Tapes

- Hold large volumes of data and provide high transfer rates
 - Few GB for DAT (Digital Audio Tape) format, 10-40 GB with DLT (Digital Linear Tape) format, 100 GB+ with Ultrium format, and 330 GB with Ampex helical scan format
 - Transfer rates from few to 10s of MB/s
- Tapes are cheap, but cost of drives is very high
- Very slow access time in comparison to magnetic and optical disks
 - limited to sequential access.
 - Some formats (Accelis) provide faster seek (10s of seconds) at cost of lower capacity
- Used mainly for backup, for storage of infrequently used information, and as an off-line medium for transferring information from one system to another.
- Tape jukeboxes used for very large capacity storage
 - Multiple petabytes (10^{15} bytes)



File Organization, Record Organization and Storage Access



File Organization

- The database is stored as a collection of *files*. Each file is a sequence of *records*. A record is a sequence of fields.
 - One approach:
 - assume record size is fixed
 - each file has records of one particular type only
 - different files are used for different relations
- This case is easiest to implement; will consider variable length records later.



Fixed-Length Records

- Simple approach:
 - Store record i starting from byte $n * (i - 1)$, where n is the size of each record.
 - Record access is simple but records may cross blocks
 - ▶ Modification: do not allow records to cross block boundaries

- Deletion of record i : alternatives:
 - move records $i + 1, \dots, n$ to $i, \dots, n - 1$
 - move record n to i
 - do not move records, but link all free records on a *free list*

record 0	10101	Srinivasan	Comp. Sci.	65000
record 1	12121	Wu	Finance	90000
record 2	15151	Mozart	Music	40000
record 3	22222	Einstein	Physics	95000
record 4	32343	El Said	History	60000
record 5	33456	Gold	Physics	87000
record 6	45565	Katz	Comp. Sci.	75000
record 7	58583	Califieri	History	62000
record 8	76543	Singh	Finance	80000
record 9	76766	Crick	Biology	72000
record 10	83821	Brandt	Comp. Sci.	92000
record 11	98345	Kim	Elec. Eng.	80000



Deleting record 3 and compacting

record 0	10101	Srinivasan	Comp. Sci.	65000
record 1	12121	Wu	Finance	90000
record 2	15151	Mozart	Music	40000
record 4	32343	El Said	History	60000
record 5	33456	Gold	Physics	87000
record 6	45565	Katz	Comp. Sci.	75000
record 7	58583	Califieri	History	62000
record 8	76543	Singh	Finance	80000
record 9	76766	Crick	Biology	72000
record 10	83821	Brandt	Comp. Sci.	92000
record 11	98345	Kim	Elec. Eng.	80000



Deleting record 3 and moving last record

record 0
record 1
record 2
record 11
record 4
record 5
record 6
record 7
record 8
record 9
record 10

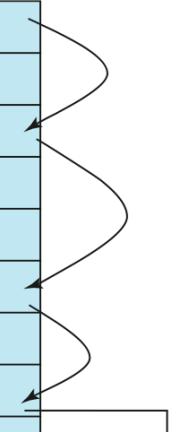
10101	Srinivasan	Comp. Sci.	65000
12121	Wu	Finance	90000
15151	Mozart	Music	40000
98345	Kim	Elec. Eng.	80000
32343	El Said	History	60000
33456	Gold	Physics	87000
45565	Katz	Comp. Sci.	75000
58583	Califieri	History	62000
76543	Singh	Finance	80000
76766	Crick	Biology	72000
83821	Brandt	Comp. Sci.	92000



Free Lists

- Store the address of the first deleted record in the file header.
- Use this first record to store the address of the second deleted record, and so on
- Can think of these stored addresses as **pointers** since they “point” to the location of a record.
- More space efficient representation: reuse space for normal attributes of free records to store pointers. (No pointers stored in in-use records.)

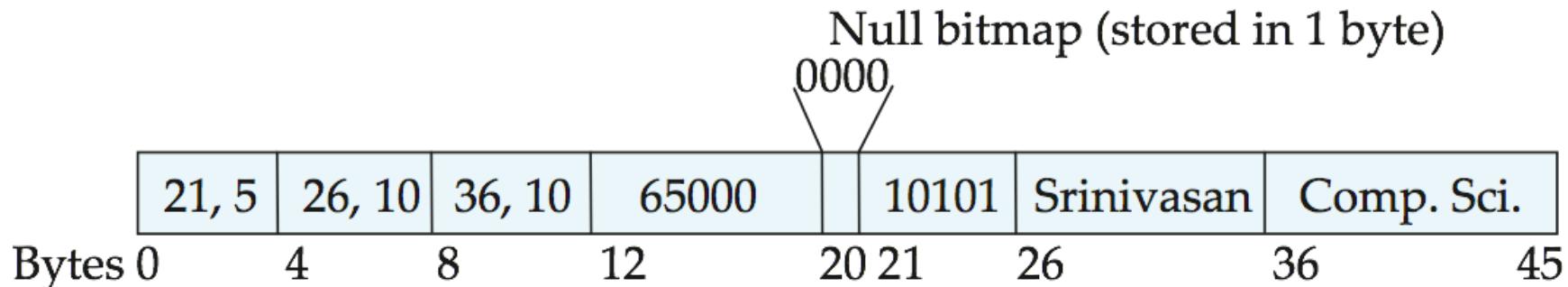
header				
record 0	10101	Srinivasan	Comp. Sci.	65000
record 1				
record 2	15151	Mozart	Music	40000
record 3	22222	Einstein	Physics	95000
record 4				
record 5	33456	Gold	Physics	87000
record 6				
record 7	58583	Califieri	History	62000
record 8	76543	Singh	Finance	80000
record 9	76766	Crick	Biology	72000
record 10	83821	Brandt	Comp. Sci.	92000
record 11	98345	Kim	Elec. Eng.	80000





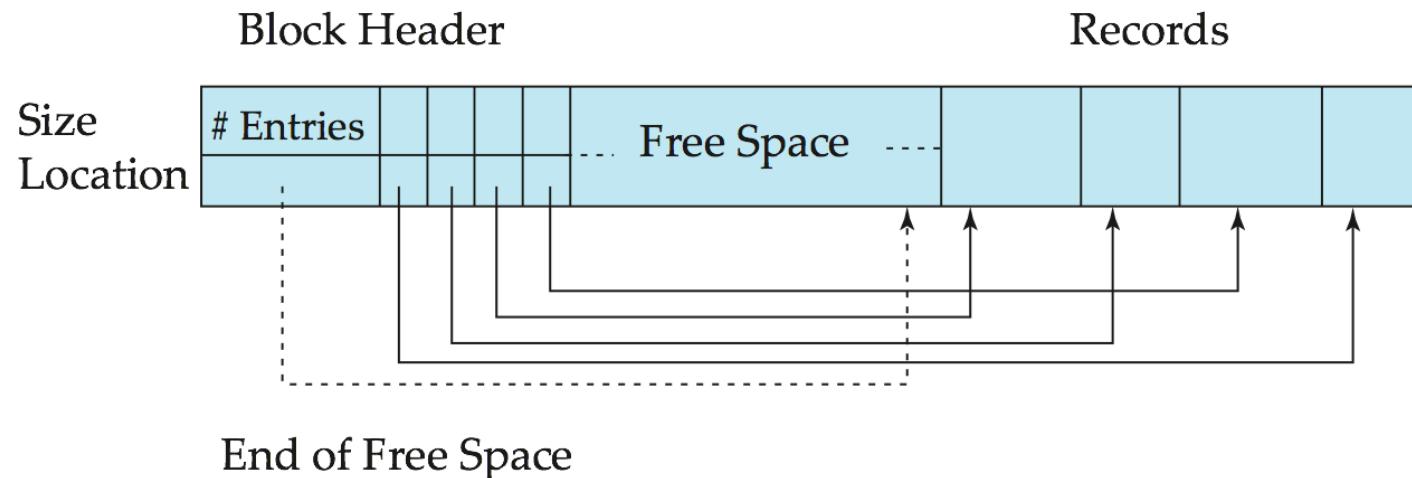
Variable-Length Records

- Variable-length records arise in database systems in several ways:
 - Storage of multiple record types in a file.
 - Record types that allow variable lengths for one or more fields such as strings (**varchar**)
 - Record types that allow repeating fields (used in some older data models).
- Attributes are stored in order
- Variable length attributes represented by fixed size (offset, length), with actual data stored after all fixed length attributes
- Null values represented by null-value bitmap





Variable-Length Records: Slotted Page Structure



- **Slotted page** header contains:
 - number of record entries
 - end of free space in the block
 - location and size of each record
- Records can be moved around within a page to keep them contiguous with no empty space between them; entry in the header must be updated.
- Pointers should not point directly to record — instead they should point to the entry for the record in header.



Organization of Records in Files

- **Heap** – a record can be placed anywhere in the file where there is space
- **Sequential** – store records in sequential order, based on the value of the search key of each record
- **Hashing** – a hash function computed on some attribute of each record; the result specifies in which block of the file the record should be placed
- Records of each relation may be stored in a separate file. In a **multitable clustering file organization** records of several different relations can be stored in the same file
 - Motivation: store related records on the same block to minimize I/O



Sequential File Organization

- ❑ Suitable for applications that require sequential processing of the entire file
- ❑ The records in the file are ordered by a **search-key**

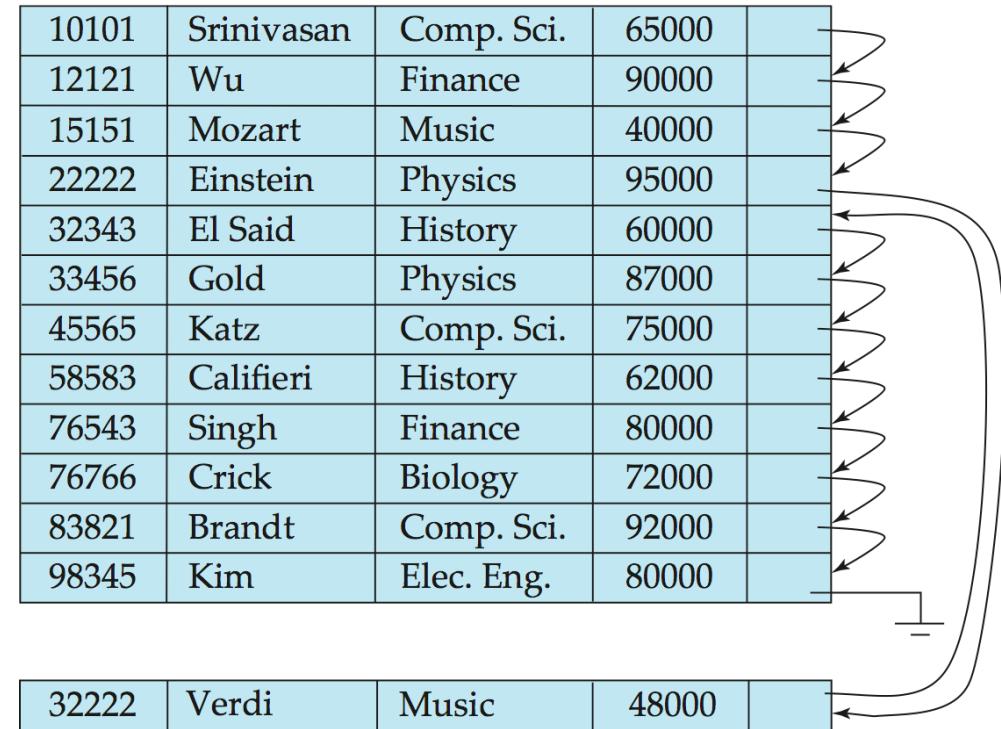
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12121	Wu	Finance	90000	
15151	Mozart	Music	40000	
22222	Einstein	Physics	95000	
32343	El Said	History	60000	
33456	Gold	Physics	87000	
45565	Katz	Comp. Sci.	75000	
58583	Califieri	History	62000	
76543	Singh	Finance	80000	
76766	Crick	Biology	72000	
83821	Brandt	Comp. Sci.	92000	
98345	Kim	Elec. Eng.	80000	

A diagram illustrating sequential access to the file. A vertical line of arrows points from the right edge of each row towards the left, indicating the sequence of reading the records. The last arrow in the sequence points to the bottom of the last row, with a horizontal line extending to the left from its tip.



Sequential File Organization (Cont.)

- Deletion – use pointer chains
- Insertion – locate the position where the record is to be inserted
 - if there is free space insert there
 - if no free space, insert the record in an **overflow block**
 - In either case, pointer chain must be updated
- Need to reorganize the file from time to time to restore sequential order





Multitable Clustering File Organization

Store several relations in one file using a **multitable clustering** file organization

department

<i>dept_name</i>	<i>building</i>	<i>budget</i>
Comp. Sci.	Taylor	100000
Physics	Watson	70000

instructor

<i>ID</i>	<i>name</i>	<i>dept_name</i>	<i>salary</i>
10101	Srinivasan	Comp. Sci.	65000
33456	Gold	Physics	87000
45565	Katz	Comp. Sci.	75000
83821	Brandt	Comp. Sci.	92000

multitable clustering
of *department* and
instructor

Comp. Sci.	Taylor	100000
45564	Katz	75000
10101	Srinivasan	65000
83821	Brandt	92000
Physics	Watson	70000
33456	Gold	87000



Multitable Clustering File Organization (cont.)

- good for queries involving *department* \bowtie *instructor*, and for queries involving one single department and its instructors
- bad for queries involving only *department*
- results in variable size records
- Can add pointer chains to link records of a particular relation

Comp. Sci.	Taylor	100000	
45564	Katz	75000	
10101	Srinivasan	65000	
83821	Brandt	92000	
Physics	Watson	70000	
33456	Gold	87000	





Data Dictionary Storage

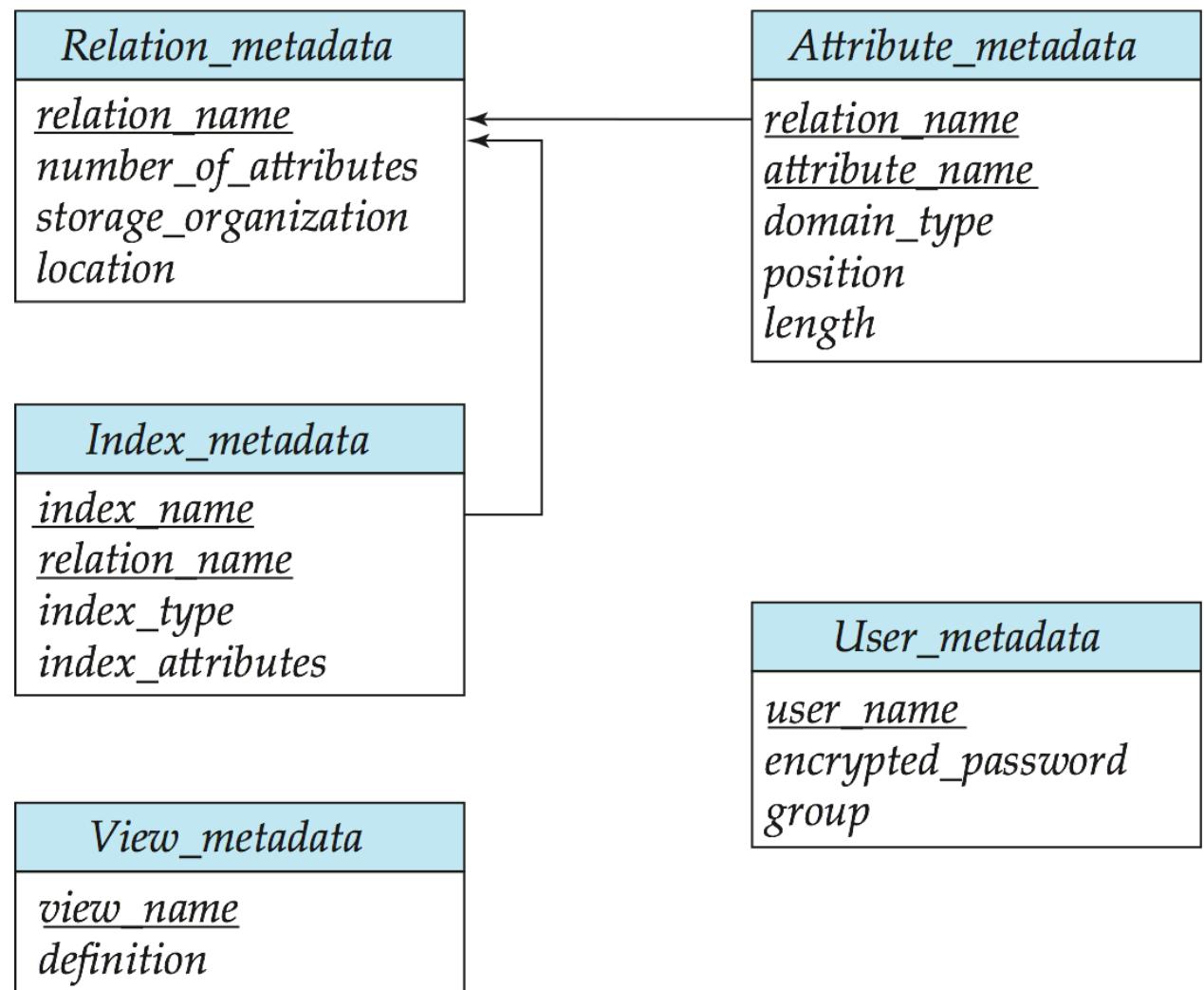
The **Data dictionary** (also called **system catalog**) stores **metadata**; that is, data about data, such as

- Information about relations
 - names of relations
 - names, types and lengths of attributes of each relation
 - names and definitions of views
 - integrity constraints
- User and accounting information, including passwords
- Statistical and descriptive data
 - number of tuples in each relation
- Physical file organization information
 - How relation is stored (sequential/hash/...)
 - Physical location of relation
- Information about indices (Chapter 11)



Relational Representation of System Metadata

- Relational representation on disk
- Specialized data structures designed for efficient access, in memory





Storage Access

- A database file is partitioned into fixed-length storage units called **blocks**. Blocks are units of both storage allocation and data transfer.
- Database system seeks to minimize the number of block transfers between the disk and memory. We can reduce the number of disk accesses by keeping as many blocks as possible in main memory.
- **Buffer** – portion of main memory available to store copies of disk blocks.
- **Buffer manager** – subsystem responsible for allocating buffer space in main memory.



Buffer Manager

- Programs call on the buffer manager when they need a block from disk.
 1. If the block is already in the buffer, buffer manager returns the address of the block in main memory
 2. If the block is not in the buffer, the buffer manager
 1. Allocates space in the buffer for the block
 1. Replacing (throwing out) some other block, if required, to make space for the new block.
 2. Replaced block written back to disk only if it was modified since the most recent time that it was written to/fetched from the disk.
 2. Reads the block from the disk to the buffer, and returns the address of the block in main memory to requester.



Buffer-Replacement Policies

- Most operating systems replace the block **least recently used (LRU strategy)**
- Idea behind LRU – use past pattern of block references as a predictor of future references
- Queries have well-defined access patterns (such as sequential scans), and a database system can use the information in a user's query to predict future references
 - LRU can be a bad strategy for certain access patterns involving repeated scans of data
 - ▶ For example: when computing the join of 2 relations r and s by a nested loops
 - for each tuple tr of r do
 - for each tuple ts of s do
 - if the tuples tr and ts match ...
 - Mixed strategy with hints on replacement strategy provided by the query optimizer is preferable



Buffer-Replacement Policies (Cont.)

- **Pinned block** – memory block that is not allowed to be written back to disk.
- **Toss-immediate** strategy – frees the space occupied by a block as soon as the final tuple of that block has been processed
- **Most recently used (MRU) strategy** – system must pin the block currently being processed. After the final tuple of that block has been processed, the block is unpinned, and it becomes the most recently used block.
- Buffer manager can use statistical information regarding the probability that a request will reference a particular relation
 - E.g., the data dictionary is frequently accessed. Heuristic: keep data-dictionary blocks in main memory buffer
- Buffer managers also support **forced output** of blocks for the purpose of recovery (more in Chapter 16)



End of Chapter 10

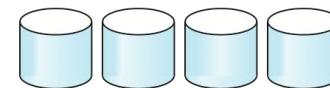
Database System Concepts, 6th Ed.

©Silberschatz, Korth and Sudarshan

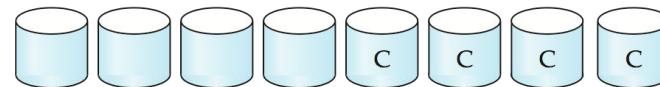
See www.db-book.com for conditions on re-use



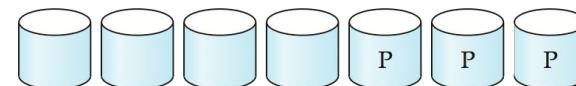
Figure 10.03



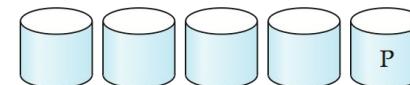
(a) RAID 0: nonredundant striping



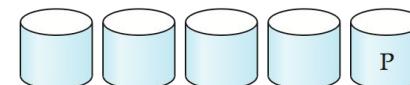
(b) RAID 1: mirrored disks



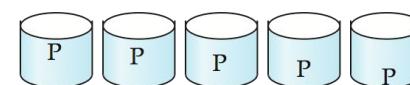
(c) RAID 2: memory-style error-correcting codes



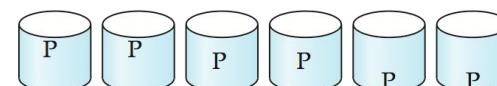
(d) RAID 3: bit-interleaved parity



(e) RAID 4: block-interleaved parity



(f) RAID 5: block-interleaved distributed parity



(g) RAID 6: P + Q redundancy



Figure 10.18

Disk 1	Disk 2	Disk 3	Disk 4
B_1	B_2	B_3	B_4
P_1	B_5	B_6	B_7
B_8	P_2	B_9	B_{10}
:	:	:	:



Figure in-10.1

P0	0	1	2	3
4	P1	5	6	7
8	9	P2	10	11
12	13	14	P3	15
16	17	18	19	P4