# 第三周上机

### 一、问题叙述

分别用追赶法和平方根法(Cholesky分解)求解 线性方程组 Ax = b,其中

$$A = \begin{bmatrix} 2 & -1 & 0 & 0 & 0 \\ -1 & 2 & -1 & 0 & 0 \\ 0 & -1 & 2 & -1 & 0 \\ 0 & 0 & -1 & 2 & -1 \\ 0 & 0 & 0 & -1 & 2 \end{bmatrix} \qquad b = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{bmatrix}$$

## 二、追赶法(Thomas)

代码如下:

```
import numpy as np
A = np.array([[2,-1,0,0,0],\
             [-1,2,-1,0,0],\
             [0,-1,2,-1,0],\
             [0,0,-1,2,-1],\
             [0,0,0,-1,2]])
A_dimension = A.shape[0]
f = np.array([[1], [2], [3], [4], [5]], dtype=float)
a = np.diagonal(A, -1)
b = np.diagonal(A)
c = np.diagonal(A, 1)
#use fomula of Thomas algorithm to get 'beta' in matrix 'U'
beta = np.zeros(A_dimension-1)
beta[0] = c[0]/b[0]
for i in range(1, A_dimension-1):
beta[i] = c[i]/(b[i]-a[i]*beta[i-1])
```

### 输出结果如下:

# 三、Cholesky 分解

### 代码如下:

```
import numpy as np
A = np.array([[2,-1,0,0,0],\
             [-1,2,-1,0,0],\
             [0,-1,2,-1,0],\
             [0,0,-1,2,-1],\
             [0,0,0,-1,2]])
A_dimension = A.shape[0]
f = np.array([[1], [2], [3], [4], [5]], dtype=float)
def Cholesky(matrix):
    dimension = matrix.shape[0]
                                                #calculate the dimension of A
    C = np.zeros((dimension, dimension))
                                              #initialize a new matrix
    for i in range(dimension):
        C[i,i] = (matrix[i,i] - np.dot(C[i,:i],C[i,:i].T))**0.5
        for j in range(i+1, dimension):
            C[j,i] = (matrix[j,i] - np.dot(C[j,:i],C[i,:i].T)) / C[i,i]
    return C
L = Cholesky(A)
```

```
#use foward elimination to get 'y'
y = np.zeros(A_dimension)
y[0] = f[0]/L[0][0]
for i in range(1, A_dimension):
    sum = 0
    for j in range(i):
        sum += L[i][j]*y[j]
    y[i] = (f[i]-sum) / L[i][i]
#use backward elimination to get 'x'
x = np.zeros(A_dimension)
x[4] = y[4]/L[4][4]
for i in range(A_dimension-2, -1, -1):
    sum = 0
    for j in range(A_dimension-1, i, -1):
        sum += L[j][i] * x[j]
    x[i] = (y[i]-sum) / L[i][i]
print(x.reshape((5,1)))
```

输出结果如下:

## 四、改进的 Cholesky 分解

为了避免开方运算,可以将利用改进的 Cholesky 分解使得  $A = LDL^{T}$ 。在编程过程中利用 numpy 自带的矩阵运算进行求逆和求转置等操作,省去了原本手动计算的过程。

代码如下:

```
import numpy as np
     A = np.array([[2,-1,0,0,0], \]
                  [-1,2,-1,0,0],\
                  [0,-1,2,-1,0],\
                  [0,0,-1,2,-1],\
                  [0,0,0,-1,2]])
     f = np.array([[1], [2], [3], [4], [5]], dtype=float)
     #revise the method of Cholesky decomposition by avoiding square root
     def Cholesky_revise(matrix):
         dimension = matrix.shape[0]
         L = np.zeros((dimension, dimension))
         for i in range(dimension):
             L[i,i] = 1
         D = np.zeros((dimension, dimension))
         for i in range(dimension):
19
             D[i,i] = matrix[i,i] - np.dot(np.dot(L[i,:i],D[:i,:i]), L[i,:i].T)
             for j in range(i+1, dimension):
                 L[j,i] = (matrix[j,i] - np.dot(np.dot(L[j,:i],D[:i,:i]), L[i,:i].T)) / D[i,i]
         return L, D
23
24
     L, D = Cholesky_revise(A)
25
     y = np.linalg.inv(L) @ f
     x = np.linalg.inv(D @ L.T) @ y # X = (D*L.T)^-1 * Y
    print(x)
```

输出如下:

# 五、结果分析

三种方法计算的结果都一致,事实上只有在精确到小数点后 16 位时(python 的浮点精度),才会有细微的差别,可见通过追赶法和 Cholesky 分解求解的精度都非常高。