Day 3: Overfitting and Generalization Summer STEM: Machine Learning

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Outline

- 1 Leftovers from Day 2
- 2 Polynomial Regression
- 3 Train and Test Error, Overfitting
- 4 Regularization



Least Square Solution

■ Model:

$$f(x) = w_0 + w_1 x$$

Loss:

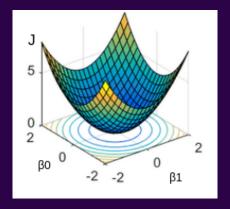
$$J(w_0, w_1) = \frac{1}{N} \sum_{i=1}^{N} \|y_i - f(x_i)\|^2$$

■ Optimization: find w_0 , w_1 such that $J(w_0, w_1)$ is the least possible value (hence the name "least square").



Loss Landscape

Plot the loss against the parameters:





Linear Regression

- Linear models: For scalar-valued feature x, this is $f(x) = w_1x + w_0$
- One of the simplest machine learning model, yet very powerful.
- Two ways to get the solution, we will show them later.



Least Square Solution: Using Statistics

■ Solution:

$$f(x) = \bar{y} + \frac{\sigma_{xy}}{\sigma_y^2}(x - \bar{x})$$

$$w_1 = \frac{\sigma_{xy}}{\sigma_x^2}, \quad w_0 = \bar{y} - w_1 \bar{x}$$

Prediction:

$$f(x) = w_0 + w_1 x$$



Least Square Solution: Using Pseudo-Inverse

■ For N data points (x_i, y_i) we have,

$$y_1 \approx w_0 + w_1 x_1$$

$$y_2 \approx w_0 + w_1 x_2$$

$$\vdots$$

$$y_N \approx w_0 + w_1 x_N.$$



Linear Regression

■ In matrix form we have,

$$\begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{bmatrix} \approx \begin{bmatrix} 1 & x_1 \\ 1 & x_2 \\ \vdots & \vdots \\ 1 & x_N \end{bmatrix} \begin{bmatrix} w_0 \\ w_1 \end{bmatrix}$$

- We can write it as $Y \approx X$ w. We call X the design matrix.
- Exercise: verify $||Y X\mathbf{w}||^2 = \sum_{i=1}^{N} ||y_i (w_0 + w_1x_i)||^2$



Linear Least Square

- Using the psuedo-inverse (only square matrices have an inverse),

$$Y = X\mathbf{w}$$

$$X^{T}Y = X^{T}X\mathbf{w}$$

$$(X^{T}X)^{-1}X^{T}Y = (X^{T}X)^{-1}X^{T}X\mathbf{w}$$

$$(X^{T}X)^{-1}X^{T}Y = \mathbf{w}.$$



Linear Regression

- What if we have multivariate data with **x** being a vector?
- $\mathbf{v} = \mathbf{w}^T \mathbf{x}$, here both \mathbf{w} and \mathbf{x} are vectors.
- Ex: $\mathbf{x}_i = [1, x_{i1}, x_{i2}]^T$ and $\mathbf{w} = [w_0, w_1, w_2]^T$ $y_1 \approx w_0 + w_1 x_{11} + w_2 x_{12}, \cdots$
- In matrix-vector form

$$\begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} \approx \begin{bmatrix} 1 & x_{11} & x_{12} \\ 1 & x_{21} & x_{22} \\ \vdots & \vdots & \vdots \\ 1 & x_n & x_{n2} \end{bmatrix} \begin{bmatrix} w_0 \\ w_1 \\ w_2 \end{bmatrix}$$

- Solution remains the same $(X^TX)^{-1}X^TY = \mathbf{w}$
- Exercise: open demo_multilinear.ipynb

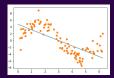


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- We have been using linear model to fit our data. But it doesn't work well every time
- Some data have more complex relation that cannot be fitted well using a straight line
 - Ex: Projectile motion, Coulomb's law, Exponential growth/decay, ...



- Linear model does not look like a good fit for this data
- Can we use some other model to fit this data?



- Can we use a polynomial to fit our data?
- Polynomial: A sum of different powers of a variable

■ Examples:
$$y = x^2 + 2$$
, $y = 5x^3 - 3x^2 + 4$



■ Polynomial Model: $y = w_0 + w_1 x + w_2 x^2 + w_3 x^3 + ...$



- Polynomial Model: $y = w_0 + w_1 x + w_2 x^2 + w_3 x^3 + ...$
- The process of fitting a polynomial is similar to linearly fitting multivariate data
- Recall the linear model for multivariable
- - Where x_1 , x_2 , x_3 ... are different features
- If we treat x^2 as our second feature, x^3 as our third feature, x^4 as our fourth feature.... We can use the same procedure in multivariate regression for linear fit!



Design matrix with the original feature:

$$X = \begin{vmatrix} 1 & x_1 \\ 1 & x_2 \\ \vdots & \vdots \\ 1 & x_N \end{vmatrix}$$

■ Design matrix with augmented polynomial features:

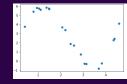
$$\Phi(X) = \begin{bmatrix} 1 & x_1 & x_1^2 & \cdots & x_1^D \\ 1 & x_2 & x_2^2 & \cdots & x_2^D \\ \vdots & & \ddots & & \vdots \\ 1 & x_N & x_N^2 & \cdots & x_N^D \end{bmatrix}$$

■ For the polynomial fitting, we just added columns of features that are powers of the original feature



Demo: Fit a polynomial

■ You are given the data set below with x and y values



- Try to fit the data using a polynomial with a certain degree
- Calculate mean square error between the sample y and your predicted y
- Try different polynomial degree and see if you can improve the mse
- Plot your polynomial over the data points



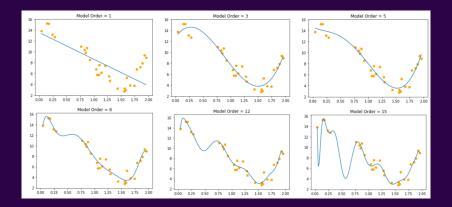
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- We learned how to fit our data using polynomials of different order
- With a higher model order, we can fit the data with increasing accuracy
- As you increase the model order, at certain point it is possible find a model that fits your data perfectly (ie. zero error)
- What could be the problem?

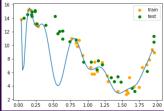




■ Which of these model do you think is the best? Why?

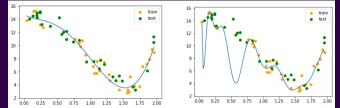


- The problem is that we are only fitting our model using data that is given
- Data usually contains noise
- When a model becomes too complex, it will start to fit the noise in the data
- What happens if we apply our model to predict some data that the model has never seen before? It will not work well.
- This is called over-fitting





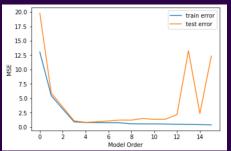
- Split the data set into a train set and a test set
- Train set will be used to train the model
- The test set will not be seen by the model during the training process
- Use test set to evaluate the model when a model is trained



■ With the training and test sets shown, which one do you think is the better model now?

Train and Test Error

- Plot of train error and test error for different model order
- Initially both train and test error go down as model order increase
- But at a certain point, test error start to increase because of overfitting





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■ **Regularization**: methods to prevent overfitting



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- Is there another way? Talk among your classmates.

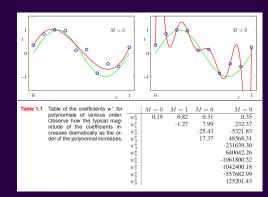


- **Regularization**: methods to prevent overfitting
 - We just covered regularization by model order selection
- Is there another way? Talk among your classmates.
 - Solution: We can change our cost function.



Weight Based Regularization

- Looking back at the polynomial overfitting
- Notice that weight-size increases with overfitting





New Cost Function

$$J = \sum_{i=1}^{N} (y_i - \hat{y}_i)^2 + \lambda \sum_{j=1}^{D} (w_j)^2$$

- Penalize complexity by simultaneously minimizing weight values.
- We call λ a **hyper-parameter**
 - lacktriangle λ determines relative importance

Table 1.2	Table of the coefficients \mathbf{w}^* for $M=9$ polynomials with various values for negularization parameter λ . Note that the property of the polynomial property of the prope	w_0^{\star} w_1^{\star} w_2^{\star} w_3^{\star} w_4^{\star} w_5^{\star} w_6^{\star} w_8^{\star}	0.35 232.37 -5321.83 48568.31 -231639.30 640042.26 -1061800.52 1042400.18 -557682.99	$\ln \lambda = -18$ 0.35 4.74 -0.77 -31.97 -3.89 55.28 41.32 -45.95 -91.53	$ \begin{array}{c} 0.13 \\ -0.05 \\ -0.06 \\ -0.05 \\ -0.03 \\ -0.02 \\ -0.01 \\ -0.00 \\ 0.00 \end{array} $
		w_8^* w_9^*	125201.43	72.68	0.00



Tuning Hyper-parameters

- Motivation: never determine a hyper-parameter based on training data
- **Hyper-Parameter**: a parameter of the algorithm that is not a model-parameter solved for in optimization.
 - **E**x: λ weight regularization value vs. model weights (**w**)
- Solution: split dataset into three
 - Training set: to compute the model-parameters (w)
 - Validation set: to tune hyper-parameters (λ)
 - **Test set**: to compute the performance of the algorithm (MSE)

