

# Day 2: Linear Regression

## Summer STEM: Machine Learning

Department of Electrical and Computer Engineering  
NYU Tandon School of Engineering  
Brooklyn, New York

# Outline

1 Leftovers from Day 1

2 Introduction to Machine Learning

3 Lab: Simple Linear Model

4 Lab: Goodness of Fit

5 Statistics Basics

6 Least Squares Solution

# Exercises: Matrix Multiplication

$$(AB)_{ij} = \sum_{k=1}^N A_{ik} B_{kj} \quad (A^T)_{ij} = A_{ji}$$

■  $X = \begin{bmatrix} 1 & 2 & -1 \\ 1 & 0 & 1 \end{bmatrix}$   $Y = \begin{bmatrix} 3 & 1 \\ 0 & -1 \\ -2 & 3 \end{bmatrix}$   $Z = \begin{bmatrix} 1 \\ 4 \\ 6 \end{bmatrix}$

■ Calculate  $\underline{XY}$ ,  $\underline{YX}$ ,  $\underline{Z^T Y}$

$$Z^T = [ 1 \ 4 \ 6 ]$$

$$Z^T Y = [ 1 \ 4 \ 6 ] \begin{bmatrix} 3 & 1 \\ 0 & -1 \\ -2 & 3 \end{bmatrix} = [ 3 + (-12) \ 1 - 4 + 18 ] = [ -9 \ 15 ]$$

$\left[ \begin{array}{cc} 1 & 2 \\ 3 & 5 \end{array} \right]^{-1} = \begin{bmatrix} 5 \\ 13 \end{bmatrix}$

# Matrix Inverse

A m by n matrix

$$A^{-1}A = AA^{-1}$$

m has to be equal to n

- Analogy: Reciprocal of a number  $\frac{1}{a}a = 1$
- Matrix inverse only defined for square matrix (# rows = # cols)
- $(A^{-1}A = AA^{-1} = I)$ .  $I$  is called the identity matrix, whose diagonal elements are 1 and other elements are 0.
- Hard to compute by hand, but for 2 by 2 matrix, it is identity

$$[a]^{-1} = \left[ \frac{1}{a} \right]$$

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \end{bmatrix}$$

Ex: 2 by 2

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

- Even for a square matrix, the matrix inverse does not always exist. Can you tell when that is the case for 2 by 2 matrices based on the formula given above?

$$ad - bc = 0$$

# Matrix Inverse

When is matrix inverse useful? We can use it to solve systems of linear equations!

- Consider the following equations

$$\begin{cases} x + 2y = 5 \\ 3x + 5y = 13 \end{cases} \quad \text{Ex: } \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} u_1 + 0 \\ 0 + u_2 \end{bmatrix} = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

- In matrix-vector form

$$\begin{aligned} & \begin{bmatrix} 1 & 2 \\ 3 & 5 \end{bmatrix}^{-1} \quad \begin{bmatrix} 1 & 2 \\ 3 & 5 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 5 \\ 13 \end{bmatrix} \\ &= \frac{1}{5 \times 1 - 2 \times 3} \begin{bmatrix} 5 & -2 \\ -3 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 3 & 5 \end{bmatrix}^{-1} \begin{bmatrix} 1 & 2 \\ 3 & 5 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 3 & 5 \end{bmatrix}^{-1} \begin{bmatrix} 5 \\ 13 \end{bmatrix} \\ &= \begin{bmatrix} -5 & 2 \\ 3 & -1 \end{bmatrix} \underbrace{\begin{bmatrix} 1 & 2 \\ 3 & 5 \end{bmatrix}}_{I} \begin{bmatrix} x \\ y \end{bmatrix} = \underbrace{\begin{bmatrix} 1 & 2 \\ 3 & 5 \end{bmatrix}^{-1}}_{\{}} \begin{bmatrix} 5 \\ 13 \end{bmatrix} \end{aligned}$$

# Demo and Exercises: NumPy

Open `demo_vectors_matrices.ipynb`

- Your task: use NumPy functions to compute the exercises we did earlier this morning. Compare the results.

# Demo: Plotting Functions

- Generate and plot the following functions in Python:
  - Scatter plot of points:  $(0,1), (2,3), (5,2), (4,1)$
  - Straight Line:  $y = mx + b$
  - Sine-wave  $y = \sin(x)$
  - Polynomial e.g.  $y = x^3 + 2$
  - Exponential e.g.  $y = e^{-2x}$
  - Choose a function of your own
- Use Wikipedia and Numpy Documentation to search for mathematical formulas and python functions

# Looking at our ice-breaker data in spreadsheets

- Columns have labels in the first row
- Collected data (numbers, words) follow below
- Let's export it to a Comma-Separated Values (CSV) file and open it

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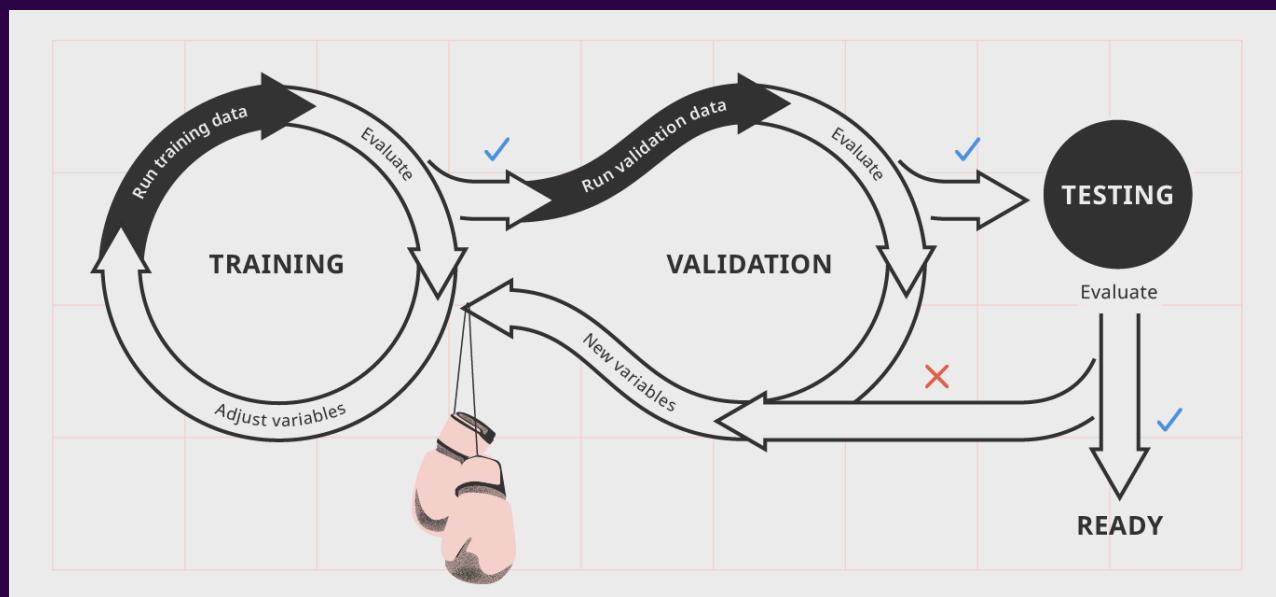
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# What is Machine Learning

- Recognize patterns from data
- Make predictions based on the learnt patterns
- A very effective tool where human expertise is not available

# Machine Learning Pipeline

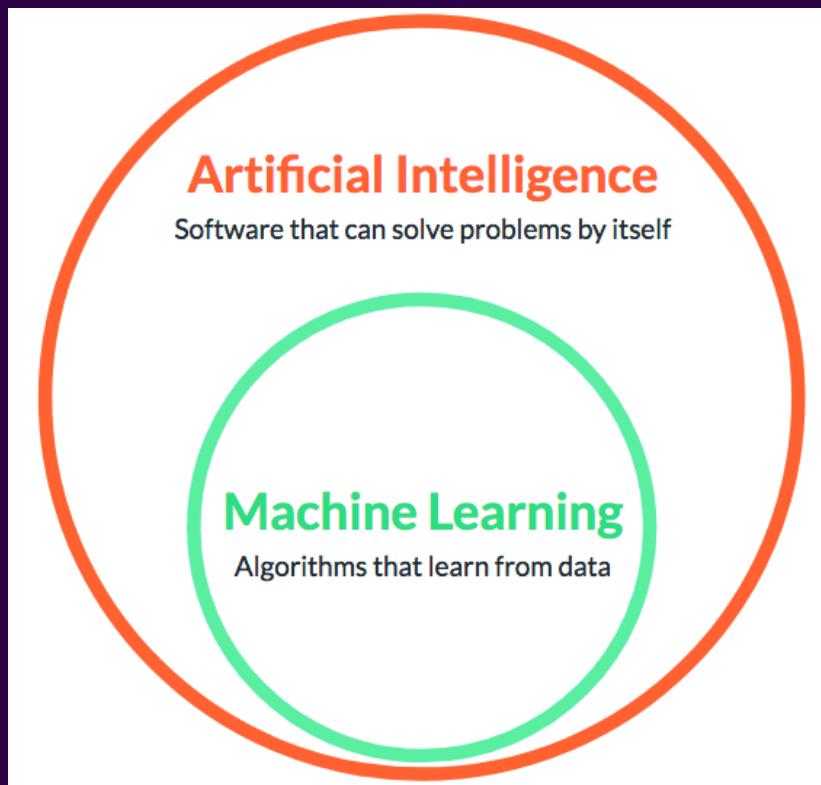


<https://lionbridge.ai/articles/how-does-ai-training-work/>

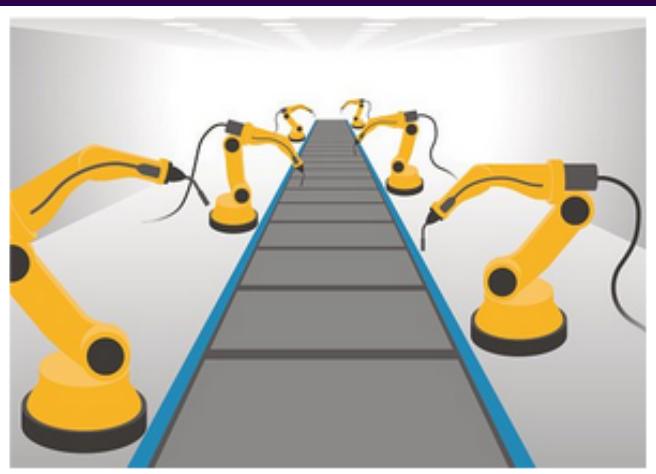
# Artificial Intelligence

- Search
- Reasoning and Problem Solving
- Knowledge Representation
- Planning
- Learning
- Perception
- Natural Language Processing
- Motion and Manipulation
- Social and General Intelligence

# Machine Learning



# Autonomous vs. Automated



# Autonomous Example: Self-driving car



## ■ Waymo Video

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<https://www.tesmanian.com/blogs/tesmanian-blog/tesla-autopilot-full-self-driving-fsd-improvements-video>

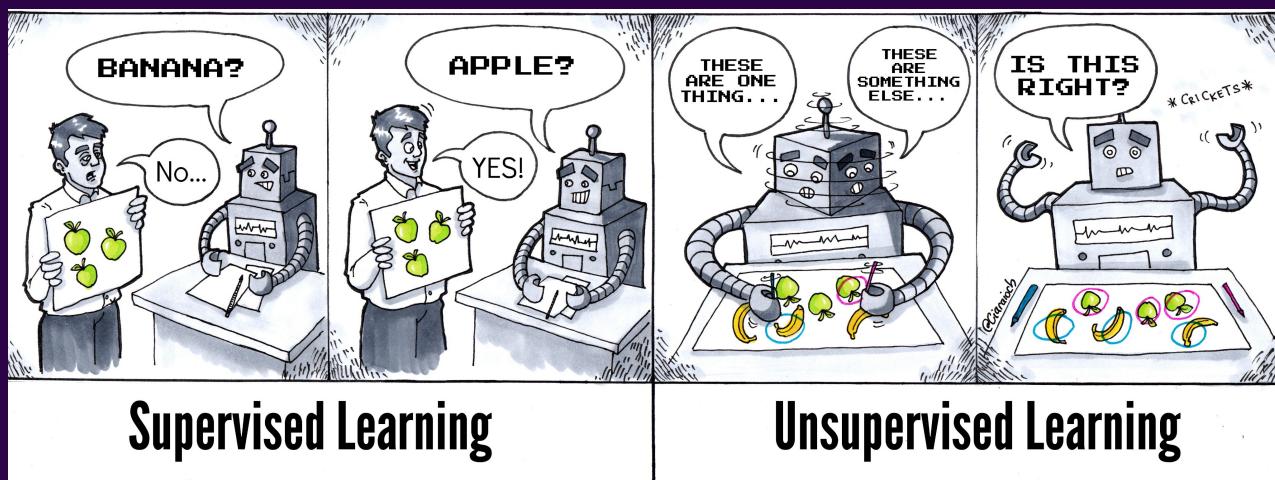
# Why is Machine Learning so Prevalent?

- Database mining
- Medical records
- Computational biology
- Engineering
- Recommendation systems
- Understanding the human brain

# Why Now?

- Big Data
  - Massive storage. Large data centers
  - Massive connectivity
  - Sources of data from internet and elsewhere
- Computational advances
  - Distributed machines, clusters
  - GPUs and hardware

# Supervised Vs. Unsupervised Learning

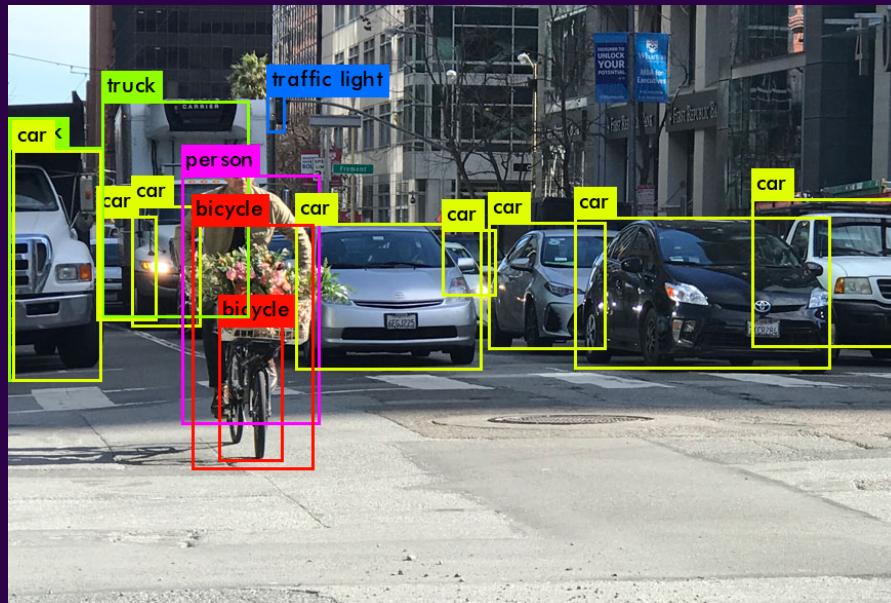


[twitter.com/athena\\_schools/status/1063013435779223553/photo/1](https://twitter.com/athena_schools/status/1063013435779223553/photo/1) 

# Supervised Vs. Unsupervised Learning

- The main difference between supervised and unsupervised learning is the existence of a supervisor, which in many cases is in the form of a data label.
- The label of the data is what we want the machine learning algorithm to predict.

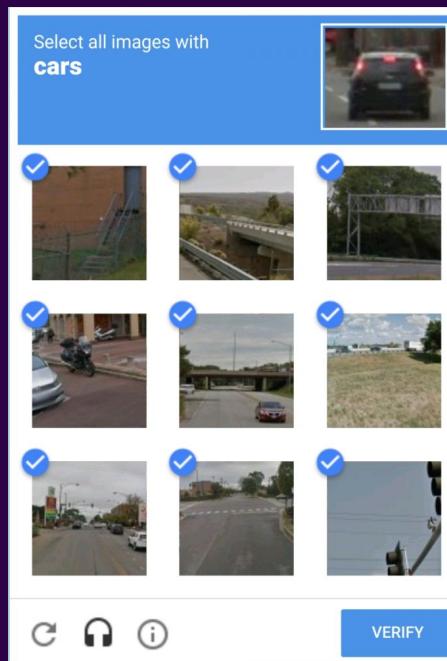
# Labelled Data



## ■ YOLO v2

<https://towardsdatascience.com/yolo-you-only-look-once-17f9280a47> NYU TANDON SCHOOL OF ENGINEERING

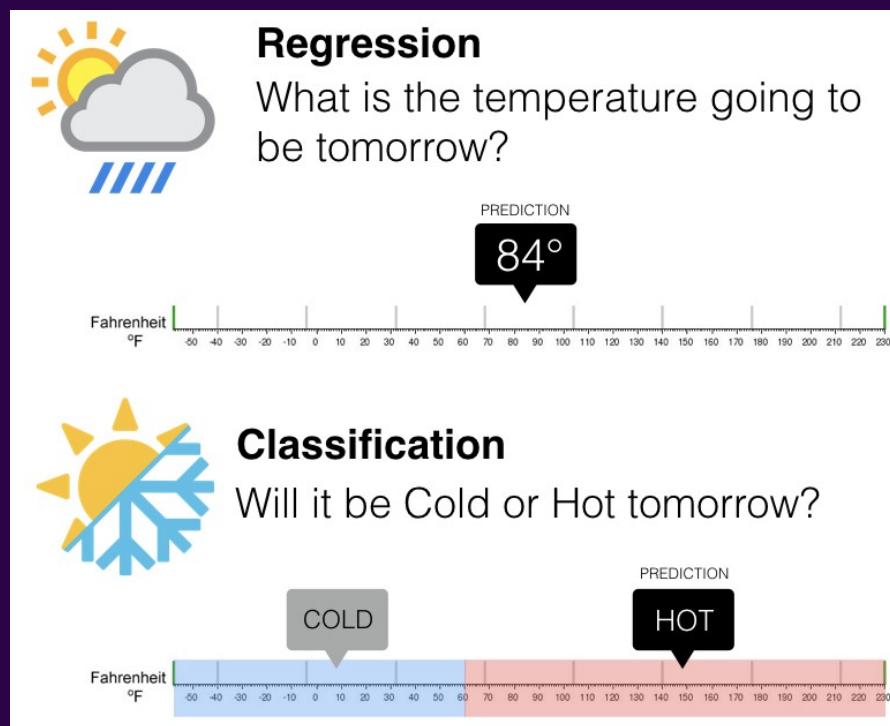
# How labels are generated



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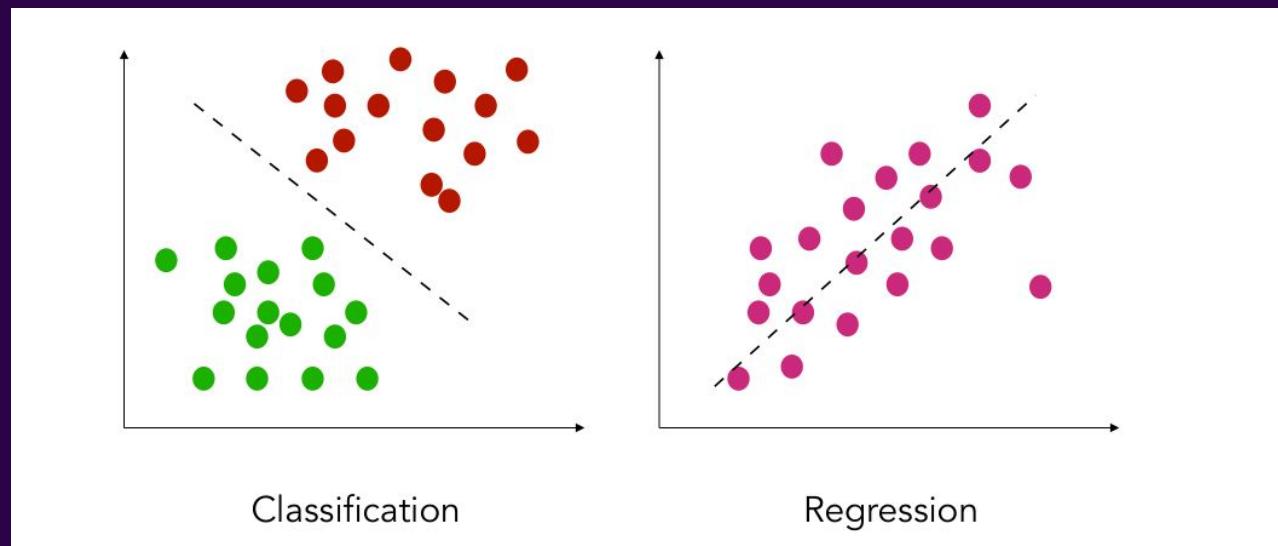
<https://devrant.com/rants/1758134/select-all-images-with-cars-i-did-and-its-not-correct-why-not>

# Classification Vs. Regression

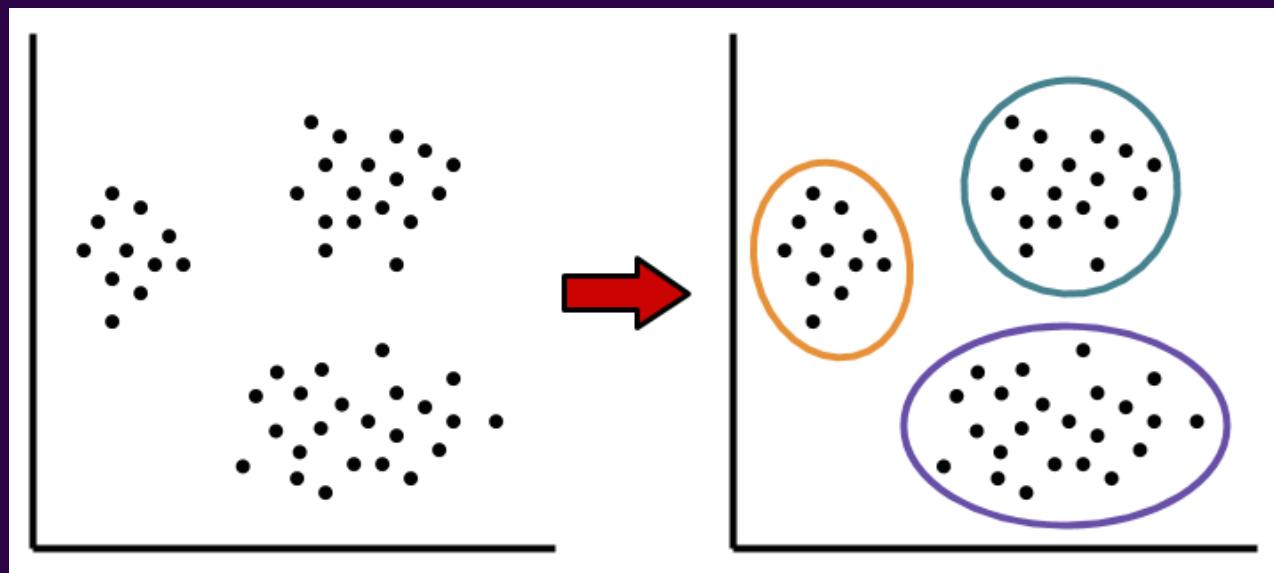


<https://www.pinterest.com/pin/672232681855858622/?lp=true>

# Classification Vs. Regression



# Unsupervised Learning

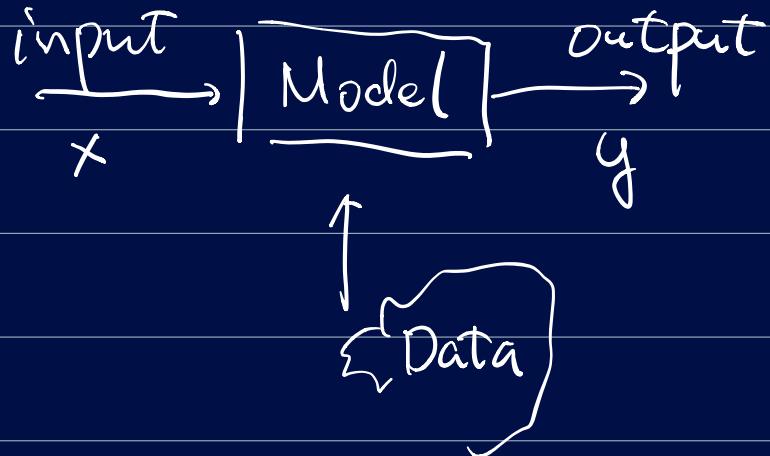


source: the dish on science

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# Machine Learning



Ex:  $x$  : movie genre

$y$  : IMDB score

Dataset:  $\underbrace{(x_i, y_i)}_{\text{a sample}} \quad i = 1, 2, \dots N$

We also call  $x$  features,  $y$  labels

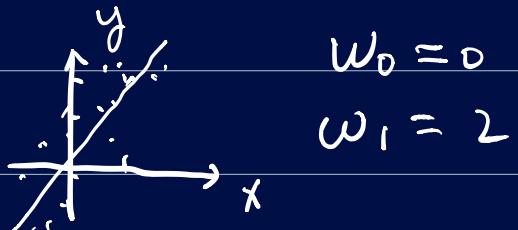
Task: to find a model  $f(x)$  to predict

$$\hat{y} = f(x)$$

$(\hat{y}$ : "y hat", denotes the prediction given by the model)

$$Ex: \hat{y} = f(x) = \underline{\omega_1}x + \underline{\omega_0}$$

"linear model"



$\omega_0, \omega_1$ : parameters of the model

Cost functions: measure how well the model fits the data

$$MSE: \frac{1}{N} \sum_{i=1}^N \| y_i - \hat{y}_i \|^2$$

$y_i$ : the labels in the dataset  
"ground truth" label

$\hat{y}_i = f(x_i)$  predictions

Compute MSE in NumPy

$$y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{bmatrix} \quad \hat{y} = \begin{bmatrix} \hat{y}_1 \\ \vdots \\ \hat{y}_N \end{bmatrix} \quad \text{MSE: } \frac{1}{N} \sum_{i=1}^N (y_i - \hat{y}_i)^2$$

$$y - \hat{y} = \begin{bmatrix} y_1 - \hat{y}_1 \\ y_2 - \hat{y}_2 \\ \vdots \\ y_N - \hat{y}_N \end{bmatrix}$$

In NumPy,  $z = (y - \hat{y}) ** 2$ , this will square

every element  $\begin{bmatrix} (y_1 - \hat{y}_1)^2 \\ \vdots \\ (y_N - \hat{y}_N)^2 \end{bmatrix}$  In our exercise  
 $N = 506$

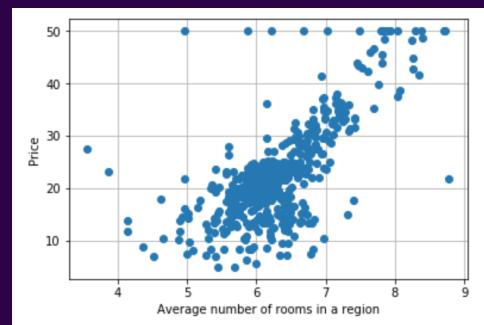
$\text{np.mean}(z)$  will give  $\frac{1}{N} \sum_{i=1}^N (y_i - \hat{y}_i)^2$

For a vector  $z$  with  $N$  elements  
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# Linear Model

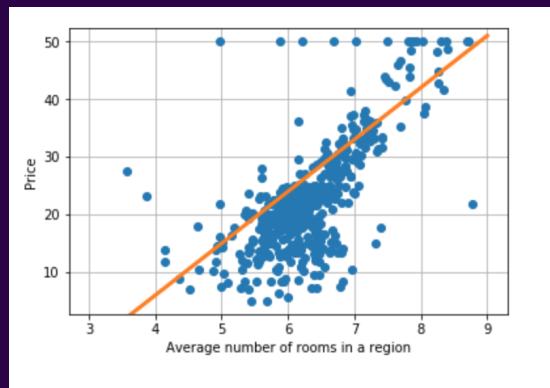
## ■ Data Representation:

- $y$  = variable you are trying to predict. Also referred to as: Dependent variable, response variable, target variable etc.
- $x$  = what you are using to predict. Also referred to as: Independent variable, attribute, predictor etc.
- Set of points,  $(x_i, y_i)$ ,  $i = 1, \dots, n$ . Each data point is called a sample.
- An efficient way to visualize the data is by plotting  $y$  vs  $x$  in a scatter plot.



# Linear Model

- Assume a linear relationship  $y = b + wx$ 
  - $b$  = intercept
  - $w$  = slope
- $\mathbf{w} = (b, w) = (w_0, w_1)$  are the parameters of the model



- Let's go to the lab to understand this further.

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# Is Your Model a Good Fit?

- How would you determine if your model is a good fit or not?
- Talk with your classmates next to you to see whose model fits the data the best
  - How will you determine this?
  - Is there a quantitative way?
  - Write python code if so.

# Error Functions

- An **error function** quantifies the discrepancy between your model and the data.
  - They are non-negative, and go to zero as the model gets better.
- Common Error Functions:
  - Mean Squared Error:  $MSE = \frac{1}{N} \sum_{i=1}^N (y_i - \hat{y}_i)^2$
  - Mean Absolute Error:  $MAE = \frac{1}{N} \sum_{i=1}^N |y_i - \hat{y}_i|$
- In later units, we will refer to these as **cost functions** or **loss functions**.
- Compute MSE on your model
- How do we interpret MSE? MAE?
  - RMSE?

# General Steps to Solve a Machine Learning Problem

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- Find parameters that minimize the error function
  - Select  $b, w$  to minimize the error function

# Least Squares Fit

- The **Least Squares Fit** is characterized by the minimization of the MSE error function:

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- Find the parameters,  $\mathbf{w} = (b, w) = (w_0, w_1)$ , that give the smallest MSE
- MSE is a useful metric because there exists an analytic solution to find the optimal parameters  $b$  and  $w$

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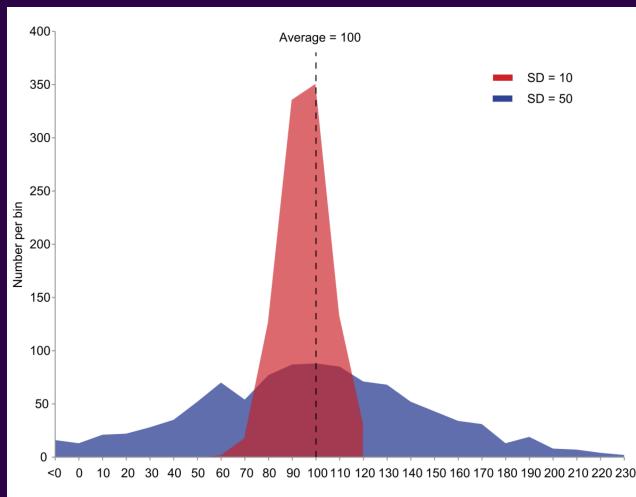
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# Basic Concepts

- **Mean** (average value):  $\bar{x} = \frac{1}{N} \sum_{i=1}^N x_i$
- **Variance** describes the spread of the data with respect to the mean.
- **Covariance** describes the relationship between two variables.

# Variance

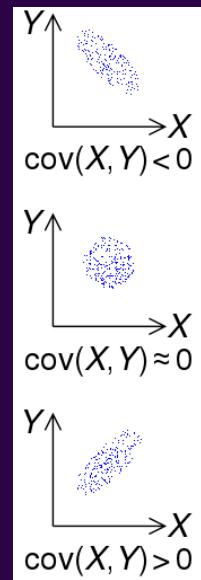
$$\blacksquare \text{ Variance: } \sigma_x^2 = \frac{1}{N} \sum_{i=1}^N (x_i - \bar{x})^2$$



<https://en.wikipedia.org/wiki/Variance>

# Covariance

■ Covariance:  $\sigma_{xy} = \frac{1}{N} \sum_{i=1}^N (x_i - \bar{x})(y_i - \bar{y})$



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# Mean, Variance, and Covariance, Correlation Coefficient

- Given feature-target data  
 $(x_i, y_i), i = 1, 2, \dots, N$

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- Variance:

$$\sigma_x^2 = \frac{1}{N} \sum_{i=1}^N (x_i - \bar{x})^2, \quad \sigma_y^2 = \frac{1}{N} \sum_{i=1}^N (y_i - \bar{y})^2$$

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- Covariance:

$$\sigma_{xy} = \frac{1}{N} \sum_{i=1}^N (x_i - \bar{x})(y_i - \bar{y})$$

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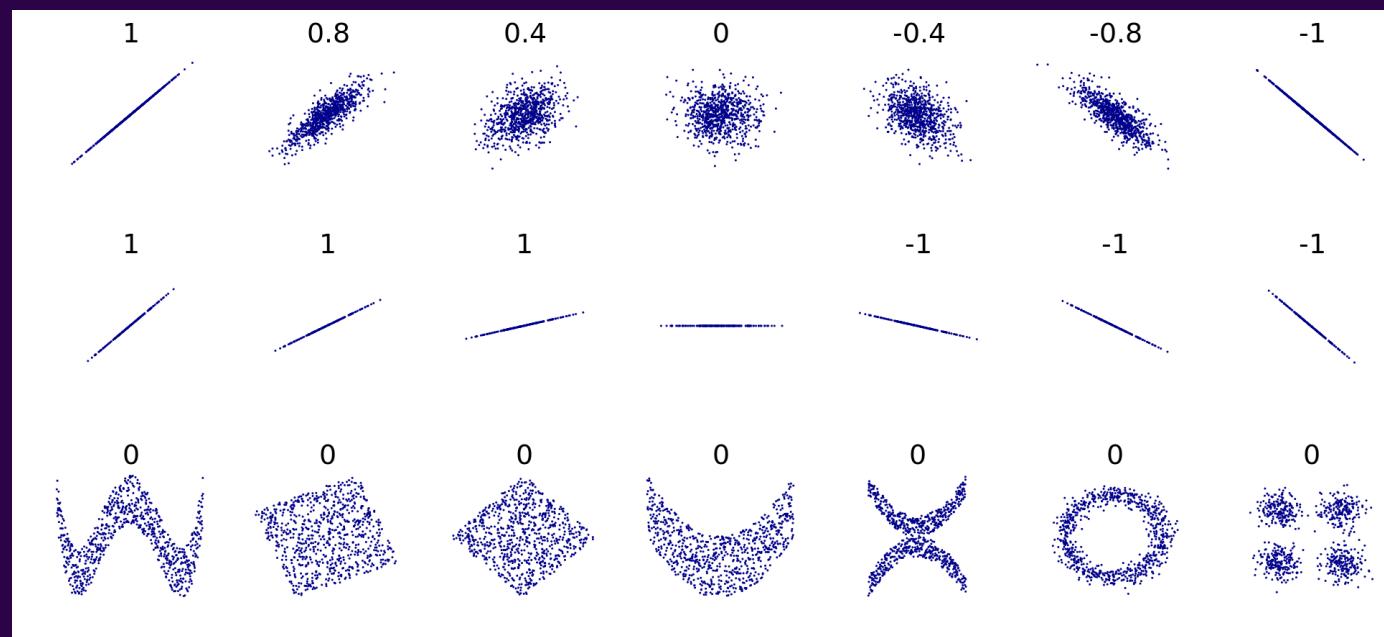
- Covariance:

$$\sigma_{xy} = \frac{1}{N} \sum_{i=1}^N (x_i - \bar{x})(y_i - \bar{y})$$

- Correlation Coefficient:

$$\rho = \frac{\sigma_{xy}}{\sigma_x \sigma_y}$$

# Lab: Gaining Intuition



[https://en.wikipedia.org/wiki/Pearson\\_correlation\\_coefficient](https://en.wikipedia.org/wiki/Pearson_correlation_coefficient)

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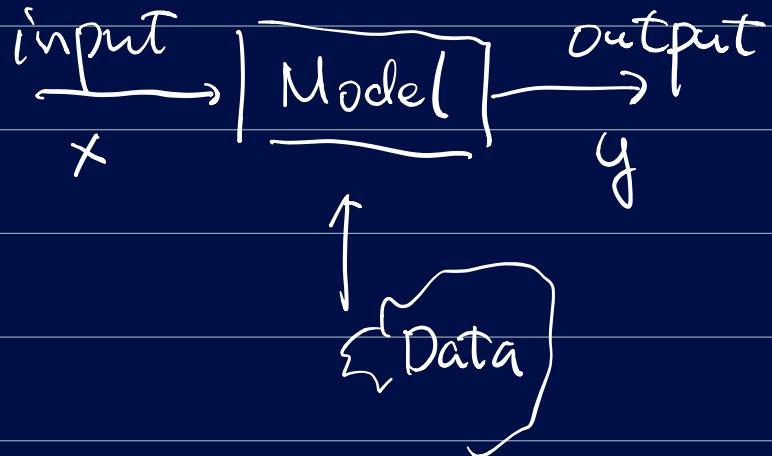
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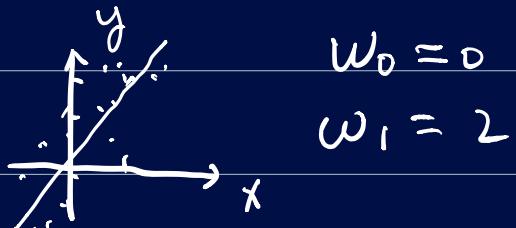
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Compute MSE in NumPy

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$$\hat{y} = \bar{y} + \rho \frac{\sigma_y}{\sigma_x} (x - \bar{x})$$

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$$w = \rho \frac{\sigma_y}{\sigma_x}, \quad b = \bar{y} - w\bar{x}$$

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- Prediction:

$$y_{new} = b + wx_{new}$$

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- Prediction:

$$y_{new} = b + wx_{new}$$

- Compute the LS fit model

# Linear Regression

- Today: linear models! In 1D, this is  $f(x) = w_1x + w_0$
- One of the simplest machine learning model, yet very powerful.
- Rewrite the set of linear equations into matrix form.

# Linear Regression

- For  $N$  data points  $(x_i, y_i)$  we have,

$$y_1 \approx w_0 + w_1 x_1$$

$$y_2 \approx w_0 + w_1 x_2$$

$$\vdots$$

$$y_N \approx w_0 + w_1 x_N.$$

# Linear Regression

- In matrix form we have,

$$\begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{bmatrix} \approx \begin{bmatrix} 1 & x_1 \\ 1 & x_2 \\ \vdots & \vdots \\ 1 & x_N \end{bmatrix} \begin{bmatrix} w_0 \\ w_1 \end{bmatrix}$$

- We can write it as  $Y \approx X\mathbf{w}$ . We call  $X$  the design matrix.
- Exercise: verify  $\|Y - X\mathbf{w}\|^2 = \sum_{i=1}^N \|y_i - (w_0 + w_1 x_i)\|^2$

# Linear Least Square

- $\min_{\mathbf{w}} \frac{1}{N} \|Y - X\mathbf{w}\|^2$
- Using the psuedo-inverse (only square matrices have an inverse),

$$Y = X\mathbf{w}$$

$$X^T Y = X^T X\mathbf{w}$$

$$(X^T X)^{-1} X^T Y = (X^T X)^{-1} X^T X\mathbf{w}$$

$$(X^T X)^{-1} X^T Y = \mathbf{w}.$$

- Exercise: open `demo_boston_housing_1d.ipynb`. Use the formula above and compare the results.

# Linear Regression

- What if we have multivariate data with  $\mathbf{x}$  being a vector?
- $y = \mathbf{w}^T \mathbf{x}$ , here both  $\mathbf{w}$  and  $\mathbf{x}$  are vectors.
- Ex:  $\mathbf{x}_i = [1, x_{i1}, x_{i2}]^T$  and  $\mathbf{w} = [w_0, w_1, w_2]^T$   
 $y_1 \approx w_0 + w_1 x_{11} + w_2 x_{12}, \dots$
- In matrix-vector form

$$\begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} \approx \begin{bmatrix} 1 & x_{11} & x_{12} \\ 1 & x_{21} & x_{22} \\ \vdots & \vdots & \vdots \\ 1 & x_n & x_{n2} \end{bmatrix} \begin{bmatrix} w_0 \\ w_1 \\ w_2 \end{bmatrix}$$

- Solution remains the same  $(X^T X)^{-1} X^T Y = \mathbf{w}$
- Exercise: open `demo_multilinear.ipynb`