

April 4 (Monday).

Topics: 1. 3D GE focused on Shadow Computation.

Example: Given

1. $x_w-y_w-z_w$ world coordinate

Right Hand System. $\vec{P}_i + \lambda(\vec{P}_s - \vec{P}_i)$ Between Ray $\vec{R}(x,y)$, and x_w-y_w plane.

\vec{R}

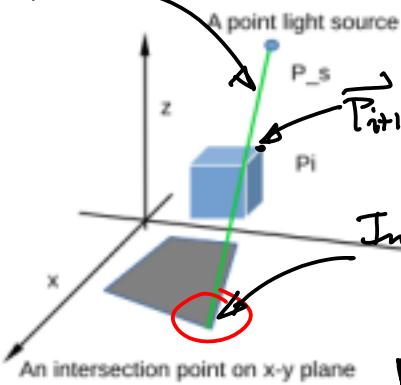


Fig. 1

2. A given Cube $\{\vec{P}_i(x_i, y_i, z_i) | i=1, 2, \dots, N\}$

Counter Clockwise.

3. A given Point Light Source

$\vec{P}_s(x_s, y_s, z_s)$

4. Generate Ray Equation / Ray Cast

x_w-y_w plane, Produces Shadow if Blocked by the Cube.

References:

2021F-101b-notes-cmpe240-2021-12-1.pdf

Step 1. Generate A Ray Cast / Equation

$$\vec{R} = \vec{P}_i + \lambda(\vec{P}_s - \vec{P}_i) \dots (1)$$

Starting from \vec{P}_s , passing through \vec{P}_i :
 $\vec{J}(x, y) = \vec{P}_s - \vec{P}_i \dots (1b)$

Intersection Point: \vec{P}_i'

Between Ray $\vec{R}(x, y)$, and x_w-y_w plane.

Step 2. To find the intersection Point on x_w-y_w plane

Define a plane equation.

a. Define A Normal Vector

$$\vec{n}(n_x, n_y, n_z)$$

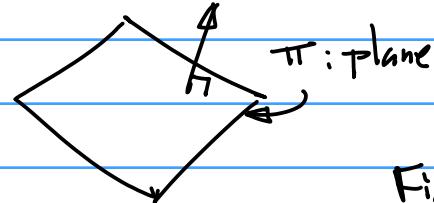


Fig. 2

use the normal vector to define the plane π .

b. Form a vector (on a plane) from \vec{P}_i and \vec{P}_{i+1} , $(\vec{P}_{i+1} - \vec{P}_i)$ a line

$$\vec{n} \cdot (\vec{P}_{i+1} - \vec{P}_i) = 0 \dots (2)$$

Take

$\vec{v}(v_x, v_y, v_z)$, $\vec{a}(a_x, a_y, a_z)$
 to Replace \vec{P}_i , \vec{P}_{i+1}

Assume $\vec{a}(a_x, a_y, a_z)$ is a Known Vector; And $\vec{v}(v_x, v_y, v_z)$ is unknown, But an arbitrary Point on the plane π .

Hence, Eqn(2) becomes

$$\vec{n} \cdot (\vec{v} - \vec{a}) = 0 \quad \dots (2*)$$

Now, find the intersection point defined by the Ray Eqn(1). In order to that, we will need to find λ .

Since, the intersection point $\vec{P_i}$ is the common Point By the Ray and the plane π . we have

$$\begin{cases} \vec{R} = \vec{P_i} + \lambda(\vec{P_s} - \vec{P_i}) & \dots (3a) \\ \vec{n} \cdot (\vec{v} - \vec{a}) = 0 & \dots (3b) \end{cases}$$

$\vec{n}(n_x, n_y, n_z)$, Normal Vector

has to be known,

$\vec{a}(a_x, a_y, a_z)$ is known on π .

Starting from the plane Eqn(3b).

$$\vec{n} \cdot (\vec{v} - \vec{a}) = 0$$

where $\vec{v} = \vec{R}$, e.g.

$$\vec{n} \cdot (\vec{v} - \vec{a}) \Big|_{\vec{v} = \vec{R}} = 0 \quad \dots (4)$$

$$\vec{n} \cdot (\vec{R} - \vec{a}) = 0$$

$$\vec{n} \cdot (\vec{P_i} + \lambda(\vec{P_s} - \vec{P_i}) - \vec{a}) = 0$$

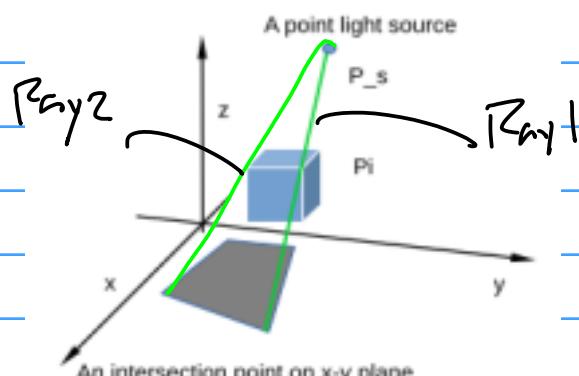
$$\vec{n} \cdot \vec{P_i} + \lambda \vec{n} \cdot (\vec{P_s} - \vec{P_i}) - \vec{n} \cdot \vec{a} = 0$$

$$\lambda \vec{n} \cdot (\vec{P_s} - \vec{P_i}) = \vec{n} \cdot \vec{a} - \vec{n} \cdot \vec{P_i}$$

$$\lambda = \frac{\vec{n} \cdot \vec{a} - \vec{n} \cdot \vec{P_i}}{\vec{n} \cdot (\vec{P_s} - \vec{P_i})}$$

$$= \frac{\vec{n} \cdot (\vec{a} - \vec{P_i})}{\vec{n} \cdot (\vec{P_s} - \vec{P_i})} \quad \dots (5)$$

Note λ is Not the intersection pt. it allows us to use Ray Eqn(1) to find the intersection.



use Eqn(5) to find more than one intersection

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Example: Ref (see pp. 1. github

Lecture Notes, 2021F-101b-n)

Given $\vec{P}_s(-20, 110, 200)$, A

Vertex of a given Cube

$\vec{P}_i(100, 100, 110)$. Find the intersection

pt to draw shadow.

$$\lambda = \frac{\vec{n} \cdot (\vec{a} - \vec{P}_i)}{\vec{n} \cdot (\vec{P}_s - \vec{P}_i)} \dots (5)$$

where $\vec{a} = (0, 0, 0)$, Hence,

$$\lambda = \frac{-\vec{n} \cdot \vec{P}_i}{\vec{n} \cdot (\vec{P}_s - \vec{P}_i)}$$

Sol First, Ray Equation, Eqn(1): Now, hand Calculation, also

$$\vec{R} = \vec{P}_i + \lambda (\vec{P}_s - \vec{P}_i) \dots (1)$$

for Coding

then, plane Eqn for $x_w - y_w$ plane

$$\lambda = \frac{-\vec{n} \cdot \vec{P}_i}{\vec{n} \cdot (\vec{P}_s - \vec{P}_i)}$$

$$\vec{n} \cdot (\vec{v} - \vec{a}) = 0 \rightarrow$$

Find \vec{n} ,

$$\vec{n}$$



$$\vec{v}_1 \times \vec{v}_2 = \vec{n}$$

... (2)

$$\text{Let } \vec{v}_1 = x_w \hat{i}, \vec{v}_2 = y_w \hat{j}$$

$$\vec{n} = x_w \hat{i} \times y_w \hat{j}$$

$$= (0, 0, 1)$$

Then, 2nd find λ for the Ray Equation, from Eqn.

$$= - \frac{n_x x_i + n_y y_i + n_z z_i}{n_x (x_s - x_i) + n_y (y_s - y_i) + n_z (z_s - z_i)}$$

From the given Condition

$$\vec{n} = (0, 0, 1), \text{ Therefore}$$

$$\lambda = \frac{-n_z z_i}{n_x (z_s - z_i)} = - \frac{z_i}{z_s - z_i}$$

$$= - \frac{110}{200 - 110} = - \frac{110}{90} = - \frac{11}{9}$$

Now, back to the Ray Equation

$$\vec{R} = \vec{P}_i + \lambda (\vec{P}_s - \vec{P}_i)$$

$$\begin{aligned}
 \vec{r} &= (100, 100, 100) - \frac{11}{9} (-20, 10, 10) \\
 &= (100, 100, 100) - \frac{11}{9} (-120, 10, 10) \\
 &= \left(\frac{1100 + 120}{9}, -\left(100 - \frac{110}{9}\right), 100 - 110 \right) \\
 &= \left(\frac{1100 + 120}{9}, \frac{110}{9} - 100, 0 \right) = (246.7, 8.8, 0)
 \end{aligned}$$

Please finish this calculation.

Now, Coding Part. Same code on github.

Note:

2018F-116-11diffuse20181114.cpp

169 world.X[47] = 0; world.Y[47] = 0; world.Z[47] = 1; // normal vector for x-y plane

```

39  typedef struct {
40      float X[UpperBO], Y[UpperBO], Z[UpperBO];
41  } pworld;
42
72  pworld world;
73  viewer viewer;

```

Now, λ Calculation. Eqn (5)

a. Define Normal vector \vec{n} for x_w-y_w plane

b. Note the "typedef struct" for defining 3D points.

$$\lambda = \frac{\vec{n} \cdot (\vec{a} - \vec{P}_i)}{\vec{n} \cdot (\vec{P}_s - \vec{P}_i)} \dots (5)$$

$$= - \frac{n_x x_i + n_y y_i + n_z z_i}{n_x x_s + n_y y_s + n_z z_s}$$

$$n_x(x_s - x_i) + n_y(y_s - y_i) + n_z(z_s - z_i)$$

```

171 //-----lambda for intersection pt on xw-yw plane-----*
172 float temp = (world.X[47]*(world.X[46]-world.X[45])) +
173     +(world.Y[47]*(world.Y[46]-world.Y[45])) +
174     +(world.Z[47]*(world.Z[46]-world.Z[45]));
175 float lambda = temp / ((world.X[47]*(world.X[45]-world.X[7])) +
176     +(world.Y[47]*(world.Y[45]-world.Y[7])) +
177     +(world.Z[47]*(world.Z[45]-world.Z[7])));
178 float lambda_2 = temp / ((world.X[47]*(world.X[45]-world.X[6])) +
179     +(world.Y[47]*(world.Y[45]-world.Y[6])) +
180     +(world.Z[47]*(world.Z[45]-world.Z[6])));

```

Note, Substitute λ to Ray Equation to find the intersection point

```

182 //-----ray equation to find intersection pts-----
183 world.X[48] = world.X[45] + lambda*(world.X[45] - world.X[7]); // Intersection pt p7
184 world.Y[48] = world.Y[45] + lambda*(world.Y[45] - world.Y[7]); // Intersection pt p7
185 world.Z[48] = 0.0;
186
187 world.X[49] = world.X[45] + lambda_2*(world.X[45] - world.X[6]); //intersection pt p6
188 world.Y[49] = world.Y[45] + lambda_2*(world.Y[45] - world.Y[6]); //intersection pt p6
189 world.Z[49] = 0.0;

```

$$\vec{R} = \vec{P}_i + \lambda (\vec{P}_s - \vec{P}_i) \Rightarrow \begin{aligned} x &= x_i + \lambda(x_s - x_i) \\ y &= y_i + \lambda(y_s - y_i) \\ z &= z_i + \lambda(z_s - z_i) \end{aligned}$$

Assignment in-Class Show&Tell. Implement Intersection Computation on LEC 17b9, "Show+Tell" Demo in Class. On April 11 (Monday),

To Be Able to Display 3D Graphics
On 2D Display Devs. Let's Define

Transformation Pipeline. 1. Define World-Coordinate System; Right Hand System

3D Transformation Pipeline Technique

Reference: H. Li Three-Dimensional Computer Graphics
Using EGA or VGA Card
SIGARTICLES ON EDUCATION, VOL. 35, NO. 1, FEBRUARY 1992

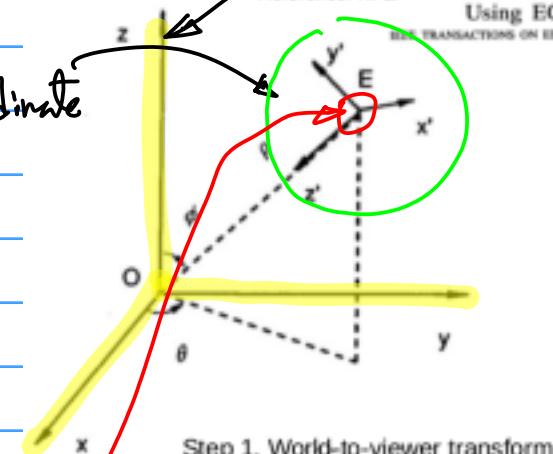
2. Viewer Coordinate System
 $x_v - y_v - z_v$

Left-Hand System

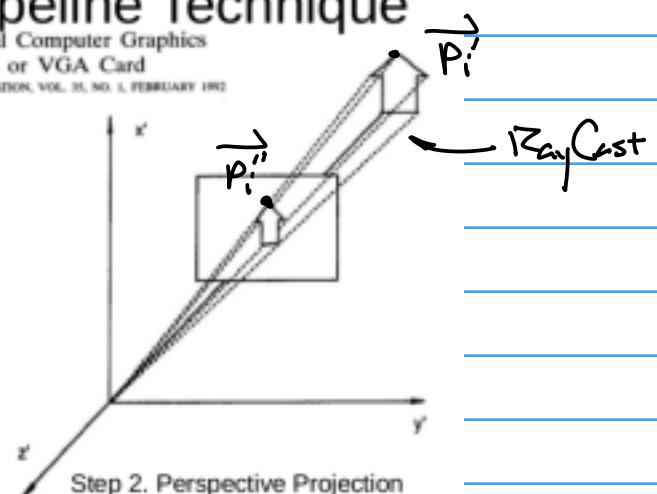
3. Virtual

Camera is
located E

(e_x, e_y, e_z)



$$T = \begin{bmatrix} -\sin \theta & \cos \theta & 0 & 0 \\ -\cos \phi \cos \theta & -\cos \phi \sin \theta & \sin \phi & 0 \\ -\sin \phi \cos \theta & -\sin \phi \sin \theta & -\cos \phi & \rho \\ 0 & 0 & 0 & 1 \end{bmatrix}$$



$$x_p = x_e \left(\frac{D}{z_e} \right)$$

$$y_p = y_e \left(\frac{D}{z_e} \right)$$

Example: Display Shadows
on 2D Display Device.

Assume $\vec{E}(x_e, y_e, z_e) = (200, 200, 200)$

Physical meaning of Transformation Matrix T .

Step 1. World To Viewer Transform.

$$T = \begin{bmatrix} -\sin \theta & \cos \theta & 0 & 0 \\ -\cos \phi \cos \theta & -\cos \phi \sin \theta & \sin \phi & 0 \\ -\sin \phi \cos \theta & -\sin \phi \cos \theta & -\cos \phi & \rho \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

... (1)

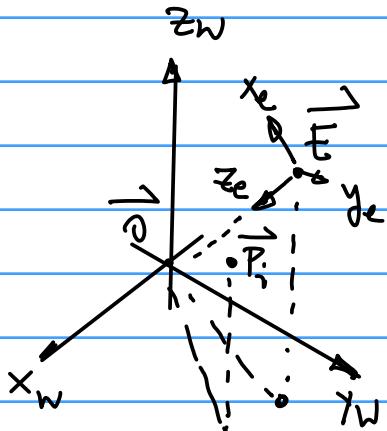


Fig. 1.

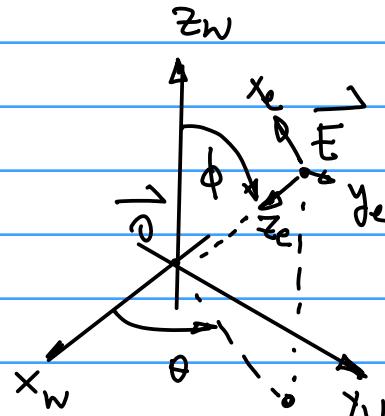


Fig. 2

θ : Angle from the dash line on x_w-y_w plane w.r.t positive x_w -axis

ϕ : Angle Between z_w & z_e .

$$\rho (\text{rho}): \rho = \sqrt{x_e^2 + y_e^2 + z_e^2} \dots (2)$$

Distance from \vec{E} to the origin \vec{O} of $x_w-y_w-z_w$.

Suppose $\vec{E}(x_e, y_e, z_e)$ is given,
Find $\cos \theta, \sin \theta, \cos \phi, \sin \phi$ for
 T -matrix.

Everything is defined in the
World Coordinate System $x_w-y_w-z_w$
including a Virtual Camera.
 $\vec{E}(x_e, y_e, z_e)$, $x_e-y_e-z_e$ "Viewer"
Coordinate System.

Given $\vec{P}_i(x_i, y_i, z_i)$ in $x_w-y_w-z_w$
World Coordinate, Represent this point
in $x_e-y_e-z_e$ Coordinate System.

\vec{P}_i

$$\begin{bmatrix} x_i \\ y_i \\ z_i \end{bmatrix} = \begin{bmatrix} -\sin \theta & \cos \theta & 0 & 0 \\ -\cos \phi \cos \theta & -\cos \phi \sin \theta & \sin \phi & 0 \\ -\sin \phi \cos \theta & -\sin \phi \cos \theta & -\cos \phi & \rho \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_i \\ y_i \\ z_i \\ 1 \end{bmatrix}$$

... (1-b)

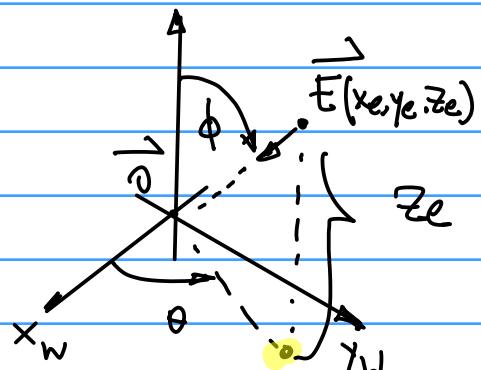


Fig. 3

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Draw A Line Passing through $\vec{E}(x_e, y_e, z_e)$ Find cos ϕ . z_w

Perpendicular to $x_w - y_w$: \rightarrow Form an intersection point.

Draw A Line Passing through the intersection point on $x_w - y_w$ plane on the plane and Perpendicular to x_w -axis.

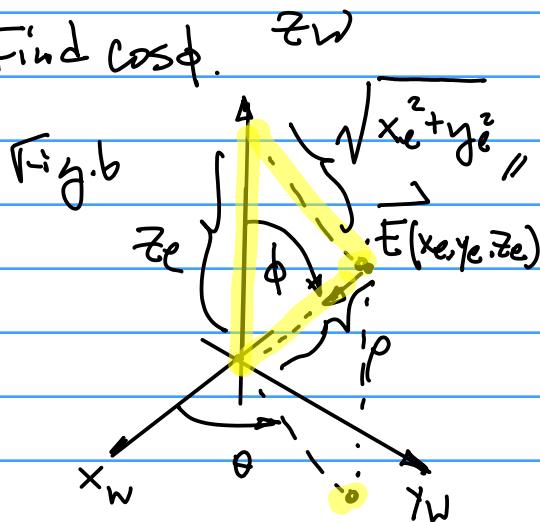
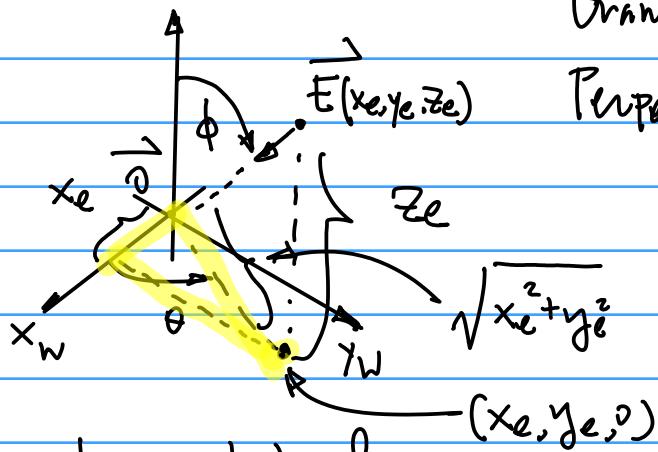


Fig.4

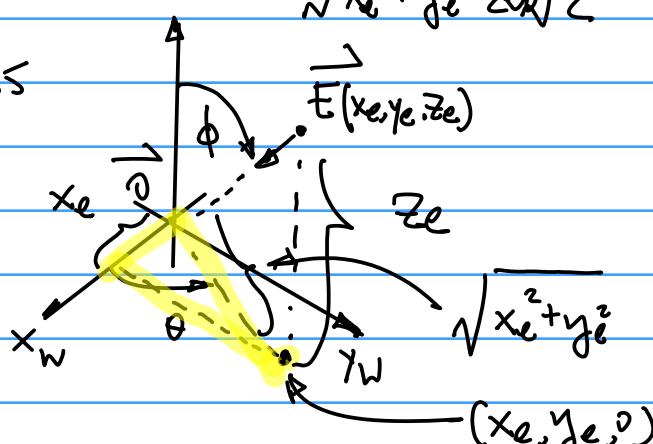


We can form a triangle on $x_w - y_w$ plane, as in Fig.4, hence

$$\cos\theta = \frac{x_e}{\sqrt{x_e^2 + y_e^2}} = \frac{200}{200\sqrt{2}} = \frac{\sqrt{2}}{2}$$

$$\text{Similarly, } \sin\theta = \frac{y_e}{\sqrt{x_e^2 + y_e^2}} = \frac{200}{200\sqrt{2}} = \frac{\sqrt{2}}{2}$$

Fig.5



Draw A Line Passing $\vec{E}(x_e, y_e, z_e)$
Perpendicular to z_w -axis

$$\begin{aligned} \cos\phi &= \frac{z_e}{p} = \frac{z_e}{\sqrt{x_e^2 + y_e^2 + z_e^2}} \\ &= \frac{200}{200\sqrt{3}} = \frac{1}{\sqrt{3}} \end{aligned}$$

$$\begin{aligned} \sin\phi &= \frac{\sqrt{x_e^2 + y_e^2}}{\sqrt{x_e^2 + y_e^2 + z_e^2}} = \frac{200\sqrt{2}}{200\sqrt{3}} \\ &= \frac{\sqrt{2}\cdot\sqrt{3}}{3} = \frac{\sqrt{6}}{3} \end{aligned}$$

Homework: Due April 18th
(Monday)

1. Draw A world Coordinate System $x_w - y_w - z_w$ axis, with x_w Red, y_w Green, z_w Blue

2. Draw A cube, size length = 100,
floats 10 unit Above x_w-y_w plane.
in other word $\vec{P}_i(100, 100, 110)$;

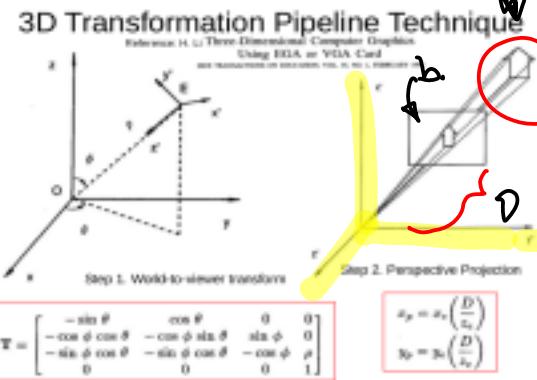
onto 2D display Device, like
LCD.

ATM113 (Wcd)

3. Draw a point light Source
 $\vec{P}_s(-20, 110, 200)$, And RayCast
to Connect \vec{P}_s to \vec{P}_i ; use Green
Color.

Topics: 1° Perspective Projection
2° Diffuse Reflection

4. Compute the Shadow point \vec{P}_i' ,
Draw the intersection Point to Link
 $\vec{P}_s - \vec{P}_i - \vec{P}_i'$



Note: You may want to Adjust the
 \vec{P}_s position, So this \vec{P}_i' (Intersection
Point) can be Visible on your Display.

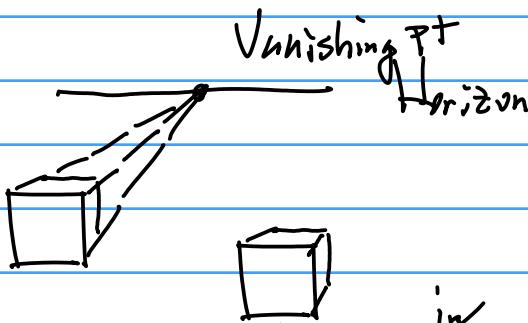
Note: $x_v-y_v-z_v$ is Left Hand
System.

Step 2. Perspective Projection

$$x_p = x_e \left(\frac{D}{z_e} \right)$$

$$y_p = y_e \left(\frac{D}{z_e} \right)$$

... (3)

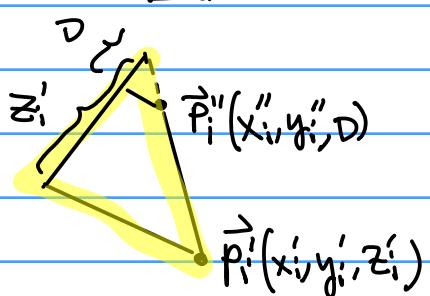
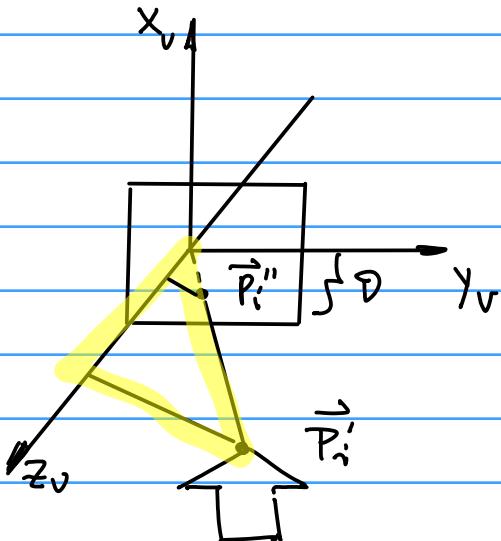


Eqn(3) project a point $\vec{P}_i(x_i, y_i, z_i)$ in
 $x_w-y_w-z_w$

- a. It is a 3D object
- b. projectionPlane, distance
to the Viewer Coordinate
System $(0, 0, 0) \rightarrow (x_e, y_e, z_e)$
- D is the
distance.

- c. Origin of $x_v-y_v-z_v$. \rightarrow
Camera Location, Camera
is modeled as "pin-Hole"
model.

Projection is formulated By
using Similar Triangles in Fig.1



$$x_p = \frac{D}{z_e} x_e \text{ from Eqn (3).}$$

Or,

$$x_i'' = \frac{D}{z_i'} x_i'$$

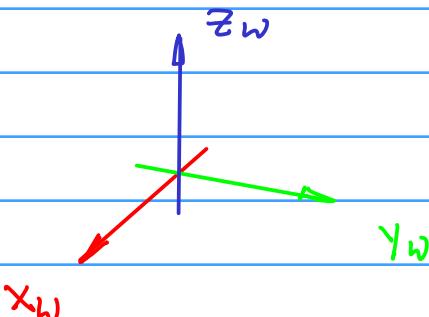
Similarly,

$$y_p = \frac{D}{z_e} y_e \text{ or}$$

$$y_i'' = \frac{D}{z_i'} y_i'$$

Homework, Due A week from Today
April 20th

1. Draw a World Coordinate System, x_w : Red, y_w : Green, z_w : Blue, Design the size ($x_w, y_w, z_w, 50$ units)



2. Design By Defining Dimension of a Cube.

(Example: length = 100)

$$\vec{P}_i(x_i, y_i, z_i) = (100, 100, 110)$$

Elevate the cube by 10 units.

3. Draw the Cube on the LCD

4. Submission:

- a. Screen Capture of your 0.5 Xpresso Screen, which ^{PT} Shows your Name (Folder Name) And your Program (Partial)

- b. Take a photo of your display.

- 0.5 pt. With Entire Prototype System of your own

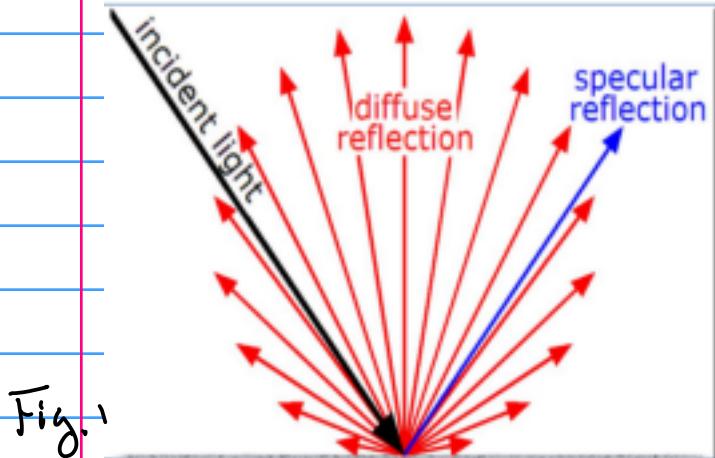
5. Submission to CANVAS.

Note: You will need transform from a virtual coordinate system to physical coordinate system

Consider Diffuse Reflection.

2. Color Space. R, G, B

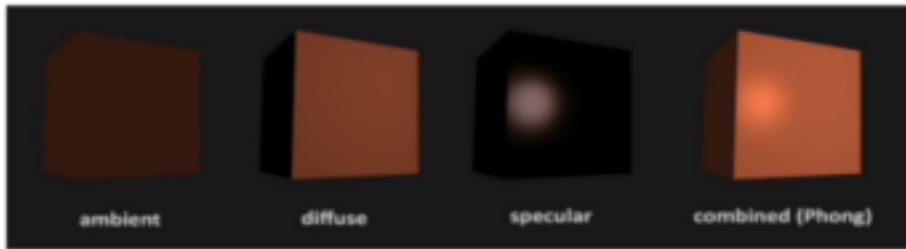
2018S-23-lec7-DiffuseReflection-v6-2018-4-25.pdf



https://en.wikipedia.org/wiki/Diffuse_reflection

Definition: A reflection from an object

Surface uniformly in all directions.



1. Define Reflectivity, A property of An Object Surface.

$$\vec{k}_r = (k_r, k_g, k_b) = (r, g, b) \dots l$$

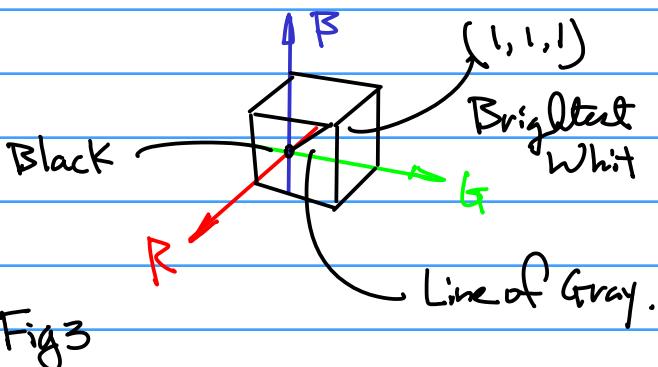
$$0 \leq r, g, b \leq 1$$

Note: for a black object,

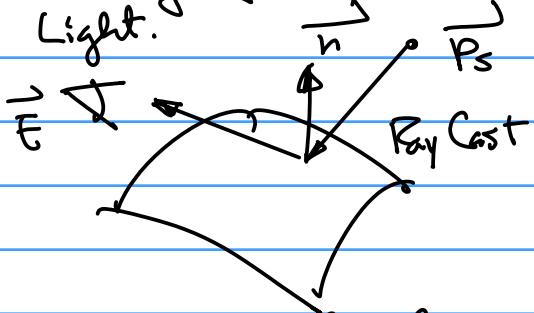
$$r=0, g=0, b=0$$

for a green leaf.

$$r \approx 0; g \neq 0, 0 < g; b \approx 0$$

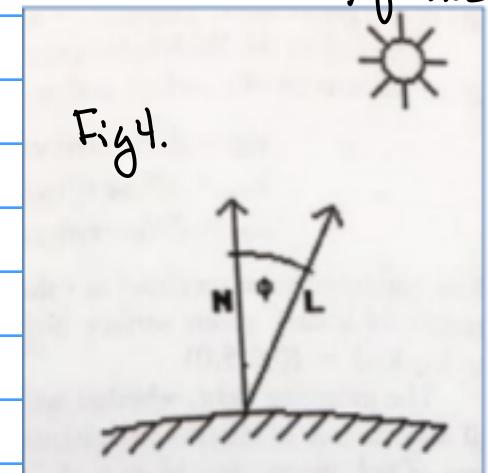


3. Viewing Angle v.s. Incident Light.



a. Perceived color is independent of viewing angle.

b. Normal Vector \vec{n} and incident Light \vec{L} (\vec{R} Ray Cast) form an angle ϕ , the color intensity follows



$\cos\phi$ function.

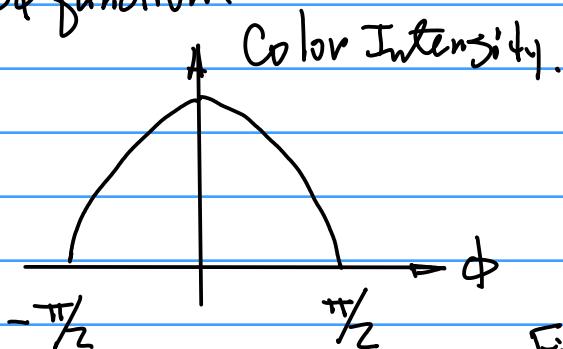


Fig 5.

$\phi=0$, $\cos\phi=1$, Strongest Reflection.
Highest Intensity.

$\phi=\pi/2$, $\cos\phi=0$, No Reflection,
frame, no color.

Example: Given $\vec{P}_s(x_s, y_s, z_s)$ And A
Cube.

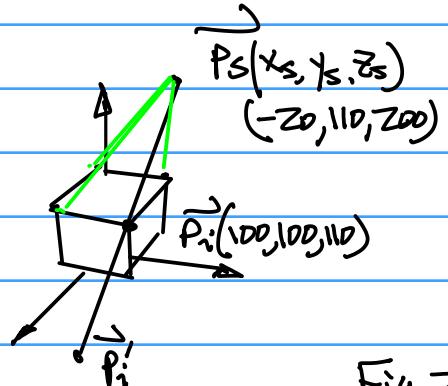


Fig. 2

\vec{P}_i' : Shadow Point.

Find Diffuse Reflection at $\vec{P}_i(x_i, y_i, z_i)$

Sol: Formulation.

4. Distance.

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Topics: Continue on Diffuse Reflection.

Light Intensity Satisfies the
relationship Below.

$$\text{Intensity} \sim \frac{1}{\|\vec{r}\|^2} \dots (1)$$

\vec{r} Ray Equation.

$$\vec{r} = \vec{P}_i + \lambda (\vec{P}_s - \vec{P}_i)$$

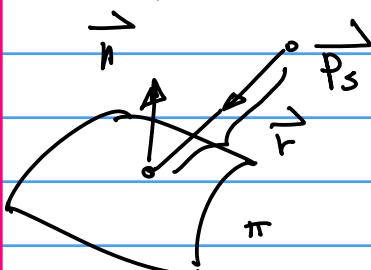


Fig. 1

$$\vec{I}_{\text{diff}}(x, y, z) = (I_{\text{diff}, r}(x, y), I_{\text{diff}, g}(x, y), I_{\text{diff}, b}(x, y))$$

$$\vec{K}_d = (K_r, K_g, K_b) \dots (2)$$

$$0 \leq K_r, K_g, K_b \leq 1$$

Note: For Simplicity, we will focus on
one type of Reflectivity for Now; "r" red

$$I_r = K_{dr} \frac{\vec{n} \cdot \vec{r}}{\|\vec{n}\| \|\vec{r}\| \|\vec{r}\|^2} \quad \dots (3)$$

Reflectivity
for "r"

$$\cos\phi = \frac{\vec{n} \cdot \vec{r}}{\|\vec{n}\| \|\vec{r}\|}$$

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$$\|\vec{r}\|_2 = \sqrt{(x_s - x_i)^2 + (y_s - y_i)^2 + (z_s - z_i)^2} \quad \dots (4)$$

$$\begin{aligned} \text{Therefore } \cos\phi &= \frac{|110-200|}{\sqrt{\Delta}} \\ &= \left\| \frac{-90}{\sqrt{\Delta}} \right\| = \frac{90}{\sqrt{\Delta}} \cdot \frac{1}{\sqrt{\Delta}} \ll 1. \end{aligned}$$

$$\|\vec{r}\|_2^2 = (x_s - x_i)^2 + (y_s - y_i)^2 + (z_s - z_i)^2$$

$$\text{Suppose } \vec{P}_s(-20, 110, 200), \vec{P}_i(100, 100, 110)$$

$$\text{Assume: } K_{dr} = 0.8$$

Find Normal vector for the Cube Surface.

\vec{n} Defined By Vector Cross Product

$$\vec{n} = \vec{A} \times \vec{B}$$

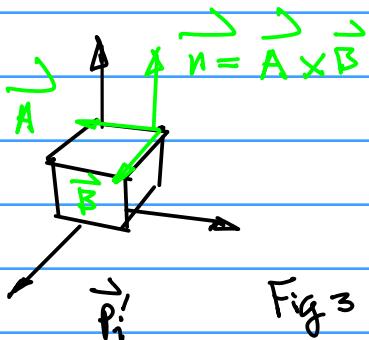


Fig 3

But the Surface of the Cube is parallel with x_w-y_w plane.

$$\therefore \vec{n} (0, 0, 1)$$

Now, find

$$\cos\phi = \frac{\vec{n} \cdot \vec{r}}{\|\vec{n}\| \|\vec{r}\|}$$

Directional
vector of
 \vec{r}

$$= \frac{(n_x, n_y, n_z) \cdot (x_i - x_s, y_i - y_s, z_i - z_s)}{\sqrt{n_x^2 + n_y^2 + n_z^2} \sqrt{(x_i - x_s)^2 + (y_i - y_s)^2 + (z_i - z_s)^2}}$$

$$\sqrt{n_x^2 + n_y^2 + n_z^2} \sqrt{(x_i - x_s)^2 + (y_i - y_s)^2 + (z_i - z_s)^2}$$

Substitute the given condition, so

$$\cos\phi = \frac{z_i - z_s}{\sqrt{(100+20)^2 + 10^2 + 90^2}} = \frac{110-200}{\sqrt{\Delta}} \rightarrow \text{take Absolute Value.}$$

And the distance from \vec{P}_s to \vec{P}_i

$$\begin{aligned} \|\vec{r}\|_2^2 &= (x_s - x_i)^2 + (y_s - y_i)^2 + (z_s - z_i)^2 \\ &= 120^2 + 10^2 + 90^2 \end{aligned}$$

Therefore, we have

$$I_{diff} = 0.8 \times \frac{90}{\sqrt{\Delta}} \times \frac{1}{\sqrt{120^2 + 10^2 + 90^2}}$$

Note: Very Small! Need Post Processing for Better Visualization.

$$= 0.8 \times \frac{90}{\sqrt{120^2 + 10^2 + 90^2}} \times \frac{1}{\sqrt{120^2 + 10^2 + 90^2}} =$$

Since the result is very small, we need to perform Post Processing.
 2.12×10^{-5}

Note: Directional vector $\vec{P}_i - \vec{P}_s$ gives Negative Value, $\vec{P}_s - \vec{P}_i$ Positive

Objective: To Scale up the result in Eqn(3) to match the entire dynamic range of the displaying device.

1. Dynamic Range of the Display Device \rightarrow 8 bits for Each Primitive Color.

$$2^8 = 256, \text{ Dynamic Range}$$

$[0, 255]$

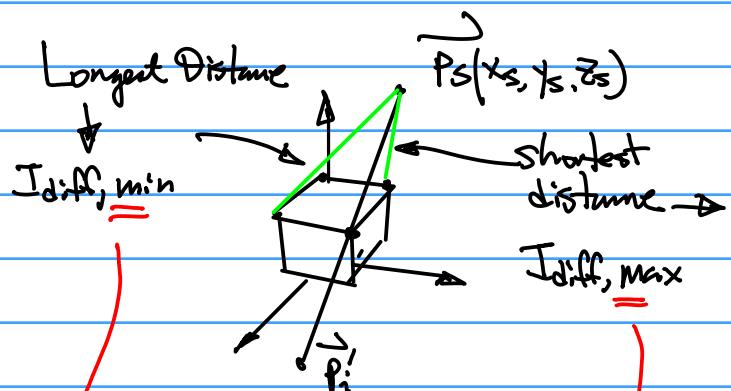
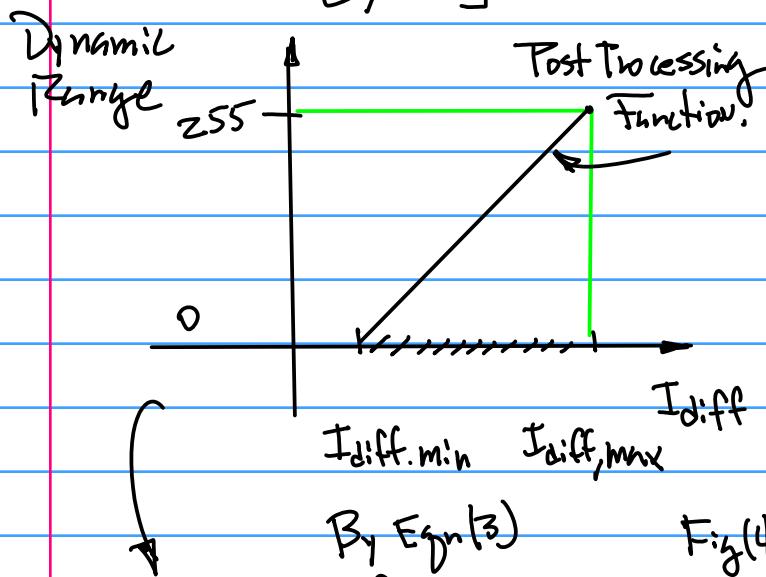
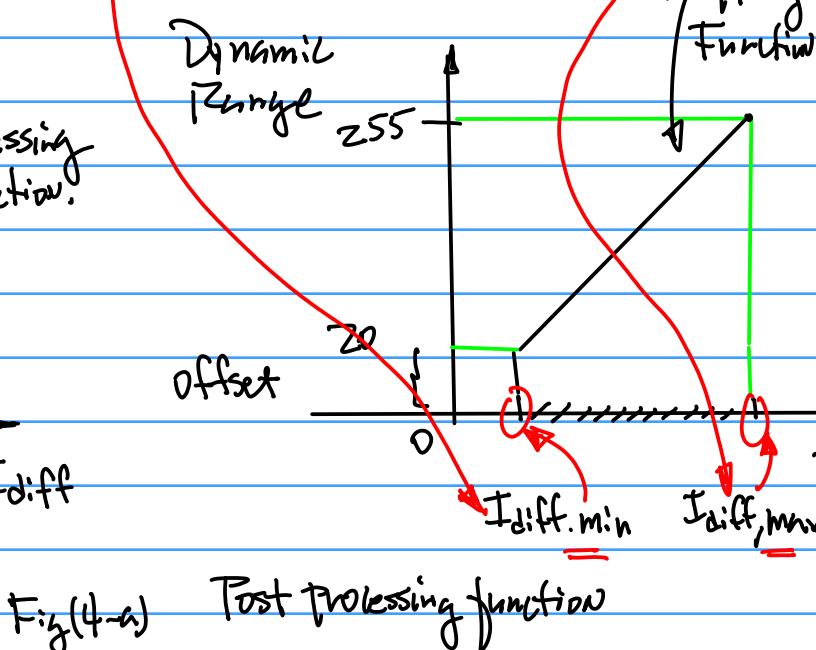
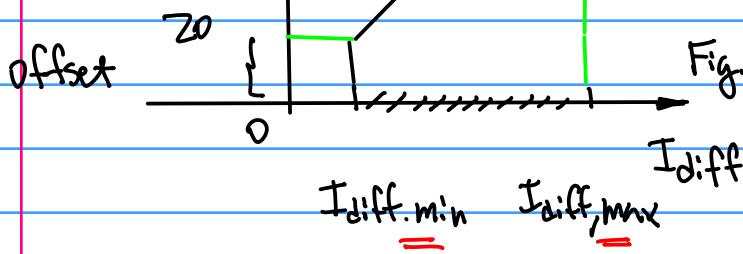


Fig. 5



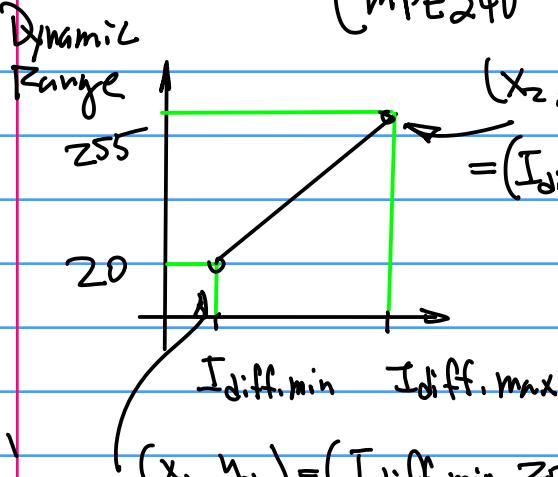
Add An offset to this function



$$\frac{x - x_2}{y - y_2} = \frac{x_i - x_2}{y_i - y_2} \dots (5)$$

April 20 (Wed)

Example: Post Processing Technique
From Fig 5, And Eqn (5).



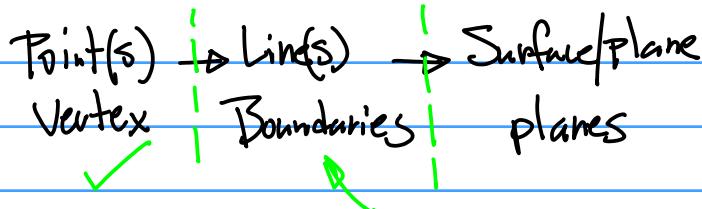
Project on Diffuse Reflection
Due May 8th, (Sunday)

Compute Diffuse Reflection.

You can work the Diffuse Reflection on 4 corners of the Cube.

Make Sure post processing is Implemented good.

General Guide for Diffuse Reflection



$$\frac{x-x_2}{y-y_2} = \frac{x_i-x_2}{y_i-y_2}$$

$$\frac{y_1-y_2}{x_1-x_2} = \frac{y-y_2}{x-x_2}$$

$$y = y_2 + \frac{y_2-y_1}{x_2-x_1}(x-x_2)$$

$$y = \frac{y_2-y_1}{x_2-x_1}x - \frac{y_2-y_1}{x_2-x_1}x_2 + y_2$$

... (1)

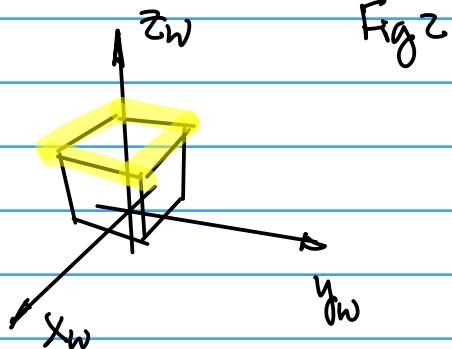
$$a y = b x + c, \quad y = \frac{b}{a} x + \frac{c}{a} \quad \dots (2)$$

$$\frac{b}{a} = \frac{y_2-y_1}{x_2-x_1} \quad \dots (2-b)$$

$$\frac{c}{a} = -\frac{y_2-y_1}{x_2-x_1}x_2 + y_2 \quad \dots (2-c)$$

Substitute $(I_{\text{diff}, \min}, z_0)$, $(I_{\text{diff}, \max}, 255)$

$$I_{\text{dyn}} = \frac{255-z_0}{I_{\text{diff}, \max}-I_{\text{diff}, \min}} x - \frac{255-z_0}{I_{\text{diff}, \max}-I_{\text{diff}, \min}} I_{\text{diff}, \max} + 255$$



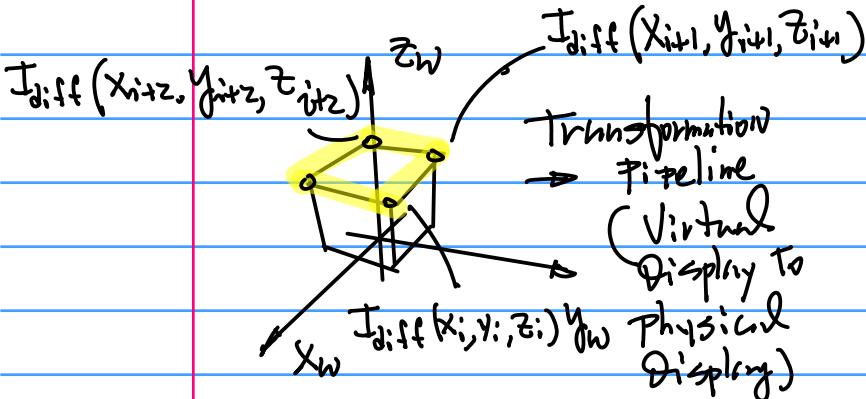
Two Phased Approach

Phase I: Compute Diffuse Reflection After Transformation Pipeline

Phase II: Map the Diffuse Reflection Result in Phase I to Actual Hardware Display Device

Example: Phong I Computation

In x_w, y_w, z_w



Display Device

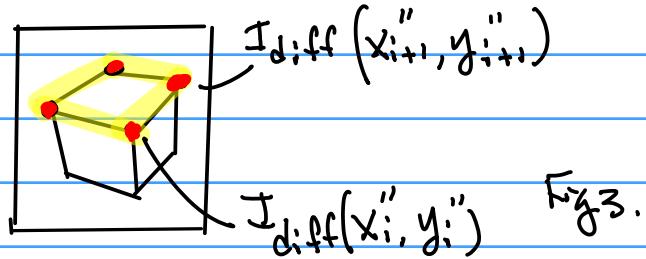


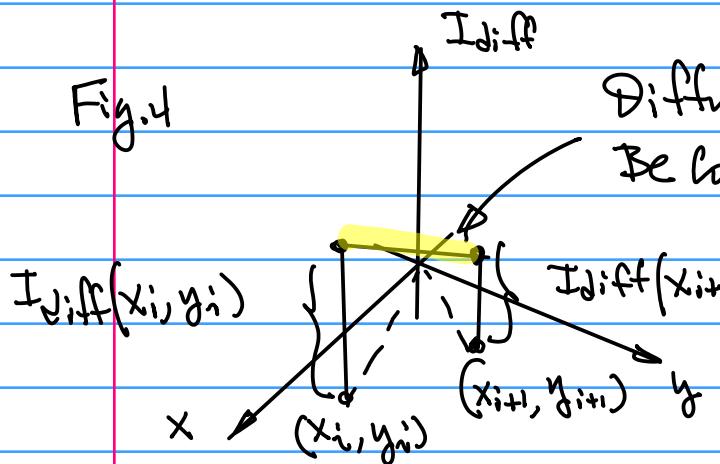
Fig.3.

Diffuse Reflections
on 4 corners Are Computed
Already.

For Simplicity Purpose, with the
understanding of working on the
physical display, we use (x_i, y_i)
not (x_i'', y_i'') .

/ 2018F / 2020S-APL29-BilinearDiff1.jpg

Fig.4



x, y are from the Display Device

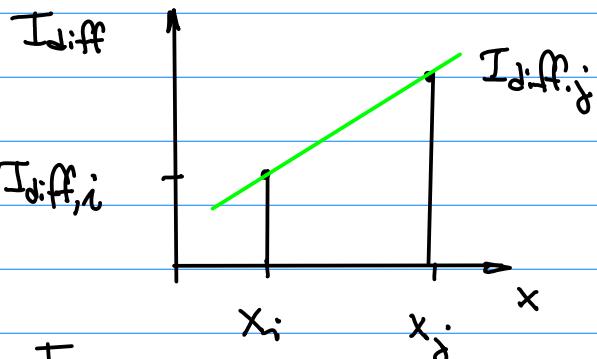
Diffuse Reflection to Be Computed, on the Bounding line with $P_{ij}(I_{diff}, i)$ and $T_{i+1}(I_{diff}, i+1)$ as Starting & Ending point.

/ 2018F / 2020S-APL27-Bilinear1.jpg

Project the "yellow line" to $x-z$ plane in Fig.4. \rightarrow Similarly, project the "yellow line" to $y-z$ plane, as function of y .
So it is just a function of x , then Compute Diffuse Reflection.
 \downarrow
Combine both By Average Operation.

April 25 (Monday)

Topic: Boundary Line

Computation for 3D G.E.
Design.Example: Formulation of
Bilinear Interpolation toCompute Boundary Line (yellow)
in Fig. 4.Project the "yellow" Line onto
 $x_w - z$ (I_{diff}) axisTake care of the Diffuse Reflection
on the Boundary Line w.r.t. x variable

From,

$$\frac{x - x_2}{y - y_2} = \frac{x_i - x_2}{y_i - y_2} \dots (5)$$

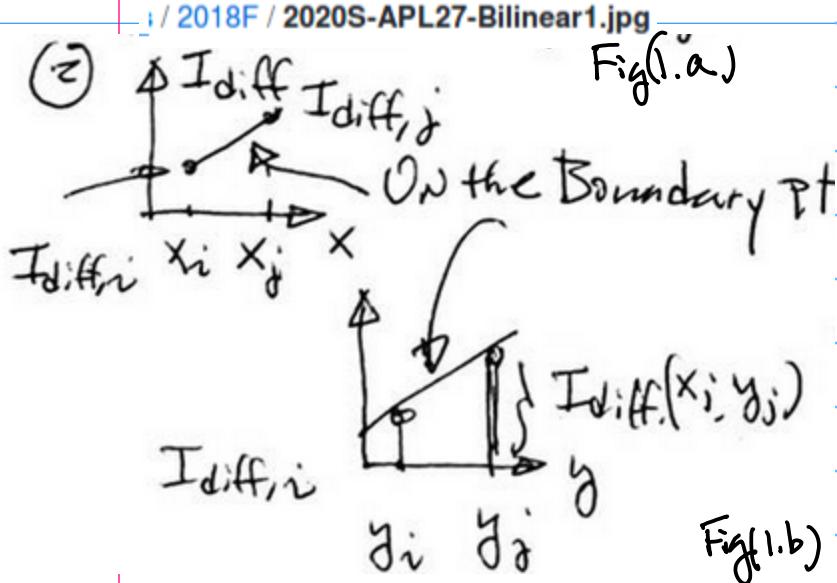
then, derived the following Equations

$$y = \frac{y_2 - y_1}{x_2 - x_1} x - \frac{y_2 - y_1}{x_2 - x_1} x_2 + y_2 \quad \dots (1)$$

$$a y = b x + c, \quad y = \frac{b}{a} x + \frac{c}{a} \quad \dots (2)$$

$$\frac{b}{a} = \frac{y_2 - y_1}{x_2 - x_1} \quad \dots (2-b)$$

$$\frac{c}{a} = -\frac{y_2 - y_1}{x_2 - x_1} x_2 + y_2 \quad \dots (2-c)$$



Once the diffuse reflection(s) with respect to
x independent variable is Computed, then
the diffuse reflection with respect to
y independent variable is Computed, then

From 1-c.

 $(x_1, y_1) :$

$x_1 = x_i$

$y_1 = I_{\text{diff},i}$

and

$$\text{Actual Single pt. Diff. Ref.} = \frac{1}{2} (I_{\text{diff},x} + I_{\text{diff},y}) \quad x_2 = x_j, y_2 = I_{\text{diff},j}$$

Therefore.

2020S-APL29-BilinearDiff2.jpg

$$I_{\text{diff},x} = \frac{I_{\text{diff},j} - I_{\text{diff},i}}{x_j - x_i} x - \frac{I_{\text{diff},j} - I_{\text{diff},i}}{x_j - x_i} x_j + I_{\text{diff},j} \dots (3)$$

For I_{diff} w.r.t y , we have (Symmetric)

$$I_{\text{diff},y} = \frac{I_{\text{diff},j} - I_{\text{diff},i}}{y_j - y_i} y - \frac{I_{\text{diff},j} - I_{\text{diff},i}}{y_j - y_i} y_j + I_{\text{diff},j} \dots (4)$$

Finally, put them together,

$$I_{\text{diff}} = \frac{1}{2} (I_{\text{diff},x} + I_{\text{diff},y}) \dots (5)$$

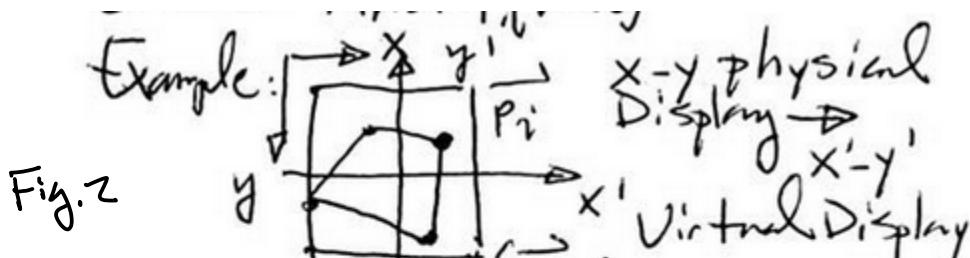


Fig. 2

Diffine Refl. $P_j (P_{i+3})$ $I_{\text{diff}}(x_i, y_i)$

$$I_{\text{diff}}(x_{i+3}, y_{i+3}) = I_{\text{diff}}(x_j, y_j)$$

$$(x_i, y_i) = (10, 12), (x_j, y_j) = (8, -14)$$

Given $\vec{I}_{\text{diff}}(10, 12) = (100, 0, 0)$,

$$\underline{I_{\text{diff}}(8, -14) = (80, 0, 0)}.$$

Find $I_{\text{diff}}(x, y)$ on the Boundary Line

Now, DDA Algorithm.

(Digital Differential Algorithm)

Display Device has finite resolution. \rightarrow "Gaps" Problem

Example: For A finite Resolution

Display Device Below,

Suppose $y = 4x + 1$ is given

for $x=0, y=1$ starting

Point. Let draw a

Straight line for $x=0, 1, 2, \dots, k$

Note: Diffuse Reflection on

the Boundary Lines is Carried

After Transformation Pipeline.

Observation: The "gap" is

due to the slope of a $y = bx + c$
($\text{Slope } \frac{b}{a}$) is greater than 1.

$$\left| \frac{b}{a} \right| > 1$$

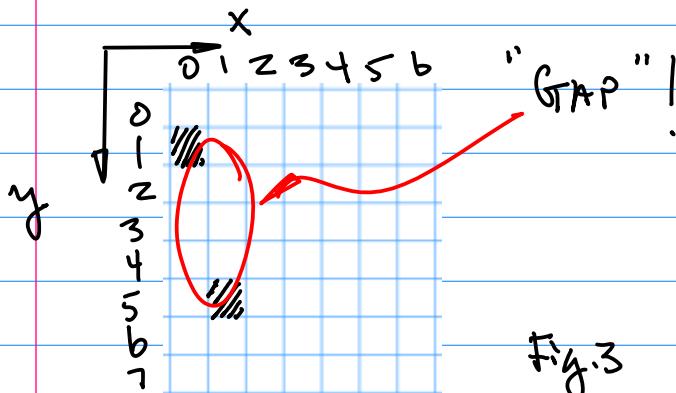
Increment x by 1 will lead to increment y by a value greater than 1.

To solve this problem, we rewrite the equation as follows

Given $ay = bx + c \dots (1)$

$$bx = ay - c$$

$$x = \frac{a}{b}y - \frac{c}{b} \dots (2)$$



$$\text{for } x=1, y=4x+1 \Big|_{x=1} = 5$$

Group I Classes

April 27, wed

Group I Classes

Group I classes are those classes which meet M, W, F, MTW, MWR, MTWF, MWRF, MTWRF, MW, WF, MWF, MF, TW, WR, MT.

Regular Class Start Times	Final Examination Days	Final Examination Time
7:00 through 8:25 AM	Wednesday, May 18	7:15-9:30 AM
8:30 through 9:25 AM	Friday, May 20	7:15-9:30 AM
9:30 through 10:25 AM	Tuesday, May 24	7:15-9:30 AM
10:30 through 11:25 AM	Thursday, May 19	9:45 AM-12:00 PM
11:30 AM through 12:25 PM	Monday, May 23	9:45 AM-12:00 PM
12:30 through 1:25 PM	Wednesday, May 18	12:15-2:30 PM
1:30 through 2:25 PM	Friday, May 20	12:15-2:30 PM
2:30 through 3:25 PM	Tuesday, May 24	12:15-2:30 PM
3:30 through 4:25 PM*	Thursday, May 19	2:45-5:00 PM
4:30* through 5:25 PM*	Monday, May 23	2:45-5:00 PM

$\therefore \text{Slope of } ay = bx + c :$

$\frac{b}{a}$ whose Absolute value is $|\frac{b}{a}| > 1$

$\therefore \text{Slope of Eqn}(z), \frac{a}{b}$ whose Absolute value $|\frac{a}{b}| < 1$

The Algorithm (D.D.A: Digital Differential Algorithm) is Based on the Absolute Value of the Slope must be less or Equal 1.

For the absolute value of the

Slope ≤ 1 , e.g.

For $ay = bx + c$ and

$|\frac{b}{a}| \leq 1$, then

$$x_{k+1} = x_k + 1 \quad \dots (3-a)$$

$$y_{k+1} = y_k + |\frac{b}{a}| \quad \dots (3-b)$$

from $ay = bx + c$

$$y = \frac{b}{a}x + \frac{c}{a}$$

$$\text{Let } x = x_k, \quad y_k = \frac{b}{a}x_k + \frac{c}{a}$$

$$y_k = \frac{b}{a}x_k + \frac{c}{a}$$

for $x_{k+1} = x_k + 1$, hence

$$\begin{aligned} y_{k+1} &= \frac{b}{a}(x_k + 1) + \frac{c}{a} \\ &= \frac{b}{a}x_k + \frac{c}{a} + \frac{b}{a} \\ &= y_k + \frac{b}{a} = y_k + |\frac{b}{a}| \end{aligned}$$

For the slope $|\frac{b}{a}| > 1$

From Eqn(z),

$$x = \frac{a}{b}y - \frac{c}{b}$$

$$|\frac{a}{b}| < 1$$

Therefore, $x = \frac{a}{b}y - \frac{c}{b}$ can be dealt with by the same approach.

e.g.

$$\begin{cases} y_{k+1} = y_k + 1 & (4-a) \\ x_{k+1} = x_k + |\frac{a}{b}| & (4-b) \end{cases}$$

Example: Given a pair of Starting Point and Ending Point draw a straight line by using D.D.A.

CMPE240, April 21, 22

20

Sol. From the Starting point \vec{P}_i

And ending Point \vec{P}_{i+1} , we
can find line equation as
follows

$$y = 4x + 1$$

Since, the Slope $|4| > 1$, then

$$x = \frac{a}{b}y - \frac{c}{b}$$

where $a=1$, $b=4$, $c=1$

$$\frac{a}{b} = \frac{1}{4} \text{ whose } |\frac{a}{b}| = |\frac{1}{4}| < 1$$

For $y_k = 1$ (Starting point $x=0$)

$$x_k = \frac{1}{4}y_k - \frac{1}{4} \Big|_{y_k=1} = 0$$

For $y_{k+1} = y_k + 1 = 1 + 1 = 2$

$$x_{k+1} = x_k + \frac{1}{4} = 0 + \frac{1}{4} = \frac{1}{4} = 0.25$$

≈ 0

For $y_{k+2} = y_{k+1} + 1 = 2 + 1 = 3$

$$x_{k+2} = x_{k+1} + \frac{1}{4} = \frac{1}{4} + \frac{1}{4} = \frac{1}{2} = 0.5$$

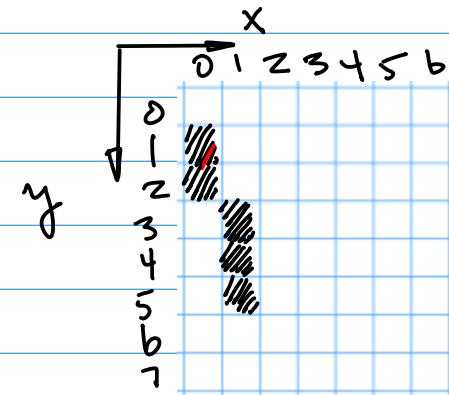
≈ 1

For $y_{k+3} = y_{k+2} + 1 = 3 + 1 = 4$

$$x_{k+3} = x_{k+2} + \frac{1}{4} = \frac{1}{2} + \frac{1}{4} = \frac{3}{4} = 0.75 \approx 1$$

For $y_{k+4} = y_{k+3} + 1 = 4 + 1 = 5$

$$x_{k+4} = x_{k+3} + \frac{1}{4} = \frac{3}{4} + \frac{1}{4} = 1$$



Programming / Implementation.

2018F-116-11diffuse20181114.cpp

2018F-117-12ddal.cpp

2018F-118-13diffuseInterpolation20181127.cpp

$$E(x_e, y_e, z_e), \rho = \sqrt{x_e^2 + y_e^2 + z_e^2}, D_{\text{focal}}$$

```

34 float Xe = 200.0f, Ye = 200.0f, Ze = 250.0f; //virtual camera
35 float Rho = sqrt(pow(Xe, 2) + pow(Ye, 2) + pow(Ze, 2));
36 float D_focal = 100.0f;
37 // point light source defined in line 160

```

TypeDef struct for the points in

$x_w - y_w - z_w$, $x_e - y_e - z_e$, Perspective Projection

```

39 typedef struct {
40     float X[UpperBD], Y[UpperBD], Z[UpperBD];
41 } pworld;
42
43 typedef struct {
44     float X[UpperBD], Y[UpperBD], Z[UpperBD];
45 } pviewer;
46
47 typedef struct {
48     float X[UpperBD], Y[UpperBD];
49 } pperspective;

```

Now, define diffuse Reflection intensity

```

55 typedef struct {
56     float r[UpperBD], g[UpperBD], b[UpperBD];
57 } pt_diffuse;

```

CmpE240 April 27, Wed, 22

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Note: The Attendance of the Class is required/Mandatory.
Next Monday there will be Attendance Checking. Please inform the other students.

$$\vec{K_s} = (K_r, K_g, K_b)$$

```
159 //-----diffuse reflection-----*
160 pt_diffuse diffuse; //diffuse.r[3]
161
162 //-----reflectivity coefficient-----*
163 #define Kdr 0.8
164 #define Kdg 0.0
165 #define Kdb 0.0
166
167
168
169
170 //-----compute distance-----*
171 float distance[UpperBD];
172 for (int i=48; i<=49; i++) {
173     distance[i] = sqrt(pow((world.X[i]-world.X[45]),2)+           //intersect pt p7
174                         pow((world.Y[i]-world.Y[45]),2)+           //pt p7
175                         pow((world.Z[i]-world.Z[45]),2) );
176     //std::cout << "distance[i] " << distance[i] << std::endl;
177 }
178
179 for (int i=4; i<=5; i++){
180     distance[i] = sqrt(pow((world.X[i]-world.X[45]),2)+           //pt p4 of projection plane
181                         pow((world.Y[i]-world.Y[45]),2)+           //pt p4
182                         pow((world.Z[i]-world.Z[45]),2) );
183     //std::cout << "distance[i] " << distance[i] << std::endl;
184 }
```

$$\|\vec{r}\| = \|\vec{p_s} - \vec{p_i}\| = \sqrt{(x_s - x_i)^2 + (y_s - y_i)^2 + (z_s - z_i)^2}$$

$\vec{n} \cdot (\vec{P_s} - \vec{P_i})$ (Note $\vec{P_i} - \vec{P_s}$ vs Ray Eqn)
See Part-II, Pg.1.

```

187     //-----compute angle-----
188     float angle[UpperBD], tmp_dotProd[UpperBD], tmp_mag_dotProd[UpperBD];
189
190     for (int i=48; i<=49; i++){
191     /*
192         tmp_dotProd[i] = (world.X[i]-world.X[45])*world.X[47]+ //...[47] for normal vector
193             (world.Y[i]-world.Y[45])*world.Y[47]+ //...[45] for pt light source
194             (world.Z[i]-world.Z[45])*world.Z[47];
195
196     */
197     tmp_dotProd[i] = world.Z[i]-world.Z[45];
198     std::cout << " tmp_dotProd[i] " << tmp_dotProd[i] << std::endl;
199
200     tmp_mag_dotProd[i] = sqrt(pow((world.X[i]-world.X[45]),2)+ // [45] pt light source
201                             pow((world.Y[i]-world.Y[45]),2) +
202                             pow((world.Z[i]-world.Z[45]),2) );
203     std::cout << " tmp_mag_dotProd[i] 1 " << tmp_mag_dotProd[i] << std::endl;
204
205     angle[i] = tmp_dotProd[i]/ tmp_mag_dotProd[i];

```

Converts color Intensity in $x_w-y_w-z_w$

```

227     //compute color intensity
228     diffuse.r[i] = Kdr * angle[i] / pow(distance[i],2) ;
229     diffuse.g[i] = Kdg * angle[i] / pow(distance[i],2) ;
230     diffuse.b[i] = Kdb * angle[i] / pow(distance[i],2) ;
231

```

Post Processing: Adding offset value \rightarrow Range
full Dynamic

```

474     for (int i=4; i<=5; i++) {
475         r = display_scaling*diffuse.r[i]+display_shifting;
476         g = diffuse.g[i]; b = diffuse.b[i];
477     }

```

$I_{diff,x}$

```

514 // y - v1 = (y2-v1)/(x2-x1) (x-x1)
515 // for x direction
516 // independent variable is .X and function y is diffuse reflection intensity
517 newx_rDiff_Pt = rDiff_Point[4] +
518     (rDiff_Point[5] - rDiff_Point[4])/(perspective.X[5]-perspective.X[4])*  

519     (mid_x - perspective.X[4]);
520 newx_gDiff_Pt = 0.0; newx_bDiff_Pt = 0.0;
521 // for y direction
522 // independent variable is .Y and function y is diffuse reflection intensity
523 newy_rDiff_Pt = rDiff_Point[4] +
524     (rDiff_Point[5] - rDiff_Point[4])/(perspective.Y[5]-perspective.Y[4])*  

525     (mid_y - perspective.Y[4]);
526 newy_gDiff_Pt = 0.0; newy_bDiff_Pt = 0.0;
527
528  $I_{diff} = \frac{1}{2}(I_{diff,x} + I_{diff,y})$ 
529 // combination of both
530 new_rDiff_Pt = (newx_rDiff_Pt + newy_rDiff_Pt)/2.0;
531 new_gDiff_Pt = 0.0; new_bDiff_Pt = 0.0;

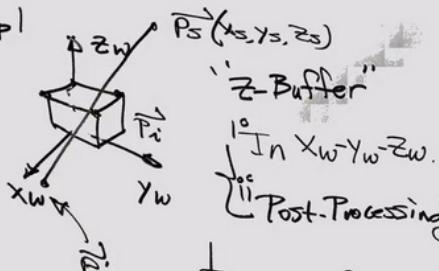
```

CNPE240
May 2nd 22

i) Final Exam In-Person.

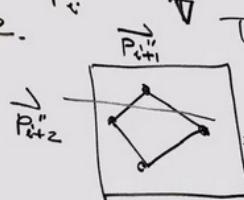
Please Bring Your Laptop
& Prototype Board.

Step 1



"Post-Processing Technique"

Step 2.



Transformation Pipeline

Boundary Diffuse Reflection.
i) Bilinear Interpolation for
Diffuse Reflection.
ii) D.D.A.

$$ay = bx + c$$

$$y = \frac{b}{a}x + \frac{c}{a}$$

Full Adder { Half Adders

Carry Look-Ahead

32 bits.

$$\begin{array}{r} a_3 a_2 \dots a_1 a_0 \\ \times x_3 x_2 \dots x_1 x_0 \\ \hline a_4 a_3 \dots \end{array}$$

First, Find A pair of Intersection

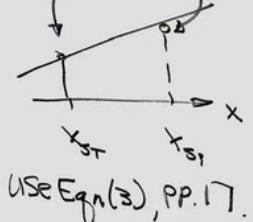
Points. Then Define the
Starting P_s^T & Ending Point.

$\vec{P}_{sr}, \vec{P}_{sp}$

Secondly, Find the
Diffuse Reflection from
the previous calculation.

NO

$I_{diff,ST}, I_{diff,SP}$



Step 3. Interior Point

