

August 23rd (mon).

CMPE240  
Section 1.

CMPE240

HARRY LI.

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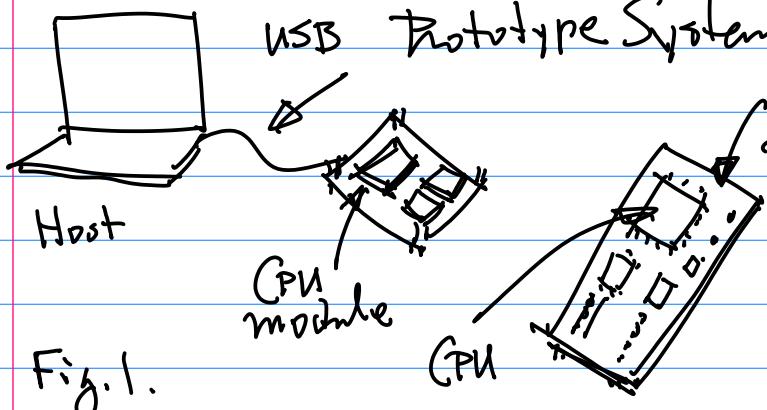
Text message (650) 400-1116

Office hours: M.W. 3:40-4:40 pm.

Advanced Microprocessor Systems

=

Prototype System  
with A CPU module



GPU (Graphics Processing Unit), Array of Processors, Machine Learning, AI.

Autonomous Systems, Nvdia Jetson

Tx2.

Textbooks, References

1° NXP LPC1769 GPU Datasheet  
80+ pages

Homework: Download pdf. Before

Next Monday, Aug. 30th.

2. LPC1769 Schematics  
of the CPU module

3. Nvdia Jetson NA10  
Datasheet on Tx2 (6 CPU + 256 GPU)  
4 front pages. 5% Bonus.  
(optional)

4. RISC-V Open Source  
Architecture, A Super Set  
of ARM, FPGA, Verilog,  
SoC. + RTOS. (optional)

A proposal (One +5%  
paragraph) By Sept. 1st  
(Wed). Submit to my  
Email;

Note: Buy LPC1769 GPU  
module.

digi-key.com,  
monster.com, etc.

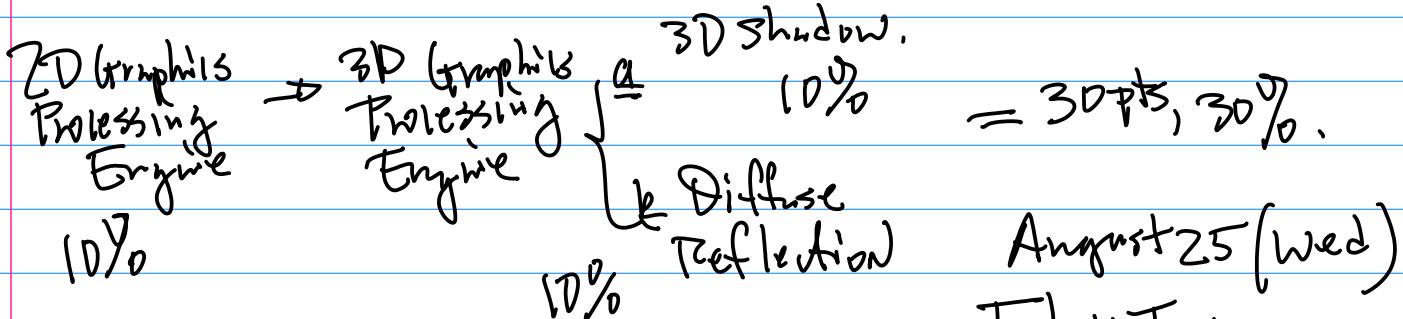
Grading Policy & Projects  
2 projects  
(phase I & II)

2D Graphics  
Processing  
Engine → 3D Graphics  
Processing  
Engine

{ a  
b  
c }

# CmPE240

2.



midterm: 30%, Final 40% (Comprehensive)

Option 1. (5%+) NVDIA NAND

- a. Likely Device Drivers, O.S. C/C++, Python.
- b. I/O Interface: "EdgeAI"

GPIOD, SPI.

Option 2. (5%+) RISC-V Target

SOC, FPGA Board,

Proposal (one paragraph), Submission  
By Sept 1st (Wed) via Email.

Policy On Project Submission.

1° Form 3-4 person Team.

2° No Source Code/Design material

Can be Copied, All Course material has to be completed individually;

3° Late project, 10% per week;

Tool for  
Flashing the  
CPU module

August 25 (Wed)

Today's Topics:

1° Bill of material

Reference: [github/finalisti](https://github/finalisti)  
/Cmpe240/2018F

The B.D.M.

1. CPU module NXP LPC1769

3rd Party (DigitalArt), module  
To Distributors

DigKey.com, Mouser.com

etc. Expecting Delays.  
Lead Time over 8 weeks

Alternative { Re-use the previously  
used module  
Team (4 person)

Each person will need to have  
his/her Board;

Option 1: NAND. @ 440+ pages

"firmware" Datasheet

= Jetpack 4.3 or Higher

→ (O.S. + Libs. + Packages)

## Compendium

c Coding in Both user & Kernel Spaces.  $\rightarrow$  O.S. Distr.

Toolchain, Device Driver Debugging  
2. Development;

Option 2. RTSC-V. verilog, FPGAs.

2. Power Regulator ICs suchs

7812, 7805 ... 1117

$\underbrace{\hspace{1cm}}$

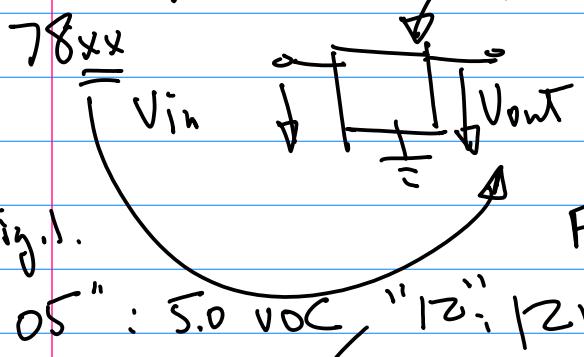


Fig. 1.

"05": 5.0 VDC, "12": 12 VDC

$$V_{in} \geq V_{out} + 1.5 \text{ VDC} \quad \dots \quad (1)$$

DC Voltage Source

a About 7805

1000 mW.

b 7.5 VDC

OR

$$9. VDC \quad (a) 1000 \text{ mW} + 500 \text{ mW} \\ = 1500 \text{ mW}$$

c Why Do we use it?  
Current Rating.

$\hookrightarrow$  Deploy the System.

3. "Glue" Components / Resistors a

c LEDs. (Red, Green) for Debugging purpose, for PWZ.  
(GPIO),  $I_{LED} = 4 \sim 10 \text{ mA}$

d Connectors.

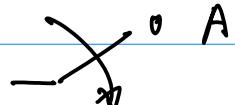
d J1 for Power Input  $\Rightarrow$  pin

d IN-Line pins.

d Breakable

to mount CPU module.

e Switch. S/W1: to toggle PWR.



f Wire for Wirewrapping / Soldering

28-30 AWG

4. Color LCD Display module

a SPI (Serial Peripheral Interface)

b Software Graphics (Driver)  
C/C++ Lib.

to Activate/Initialize LCD.

MCU Xpresso (J.D.E.)

$\downarrow$   
S.T. Lib.

5. "Other" thing.

PJ-45 Connector

Sept. 8 (W)

Topics: 1. "Hello, the World" program

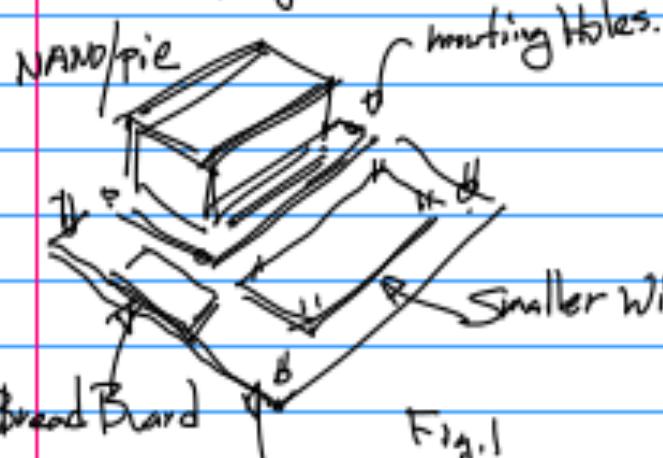
J Hardware Implementation

NXP MC91Xpresso.

a. Installation of MCU  
Xpresso.b. [github.com/hualili/CMPE240/2018/](https://github.com/hualili/CMPE240/2018/)L7C1769 Patch, Import this patch  
to your Xpresso.<https://github.com/hualili/CMPE240-Adv-Microprocessors/blob/master/1769%20patch.zip>Note: Wirewrapping Board with  
"Stand-off's (Legs)

Homework: Next Show-and-tell

Wirewrapping Board;



"Tap Plastic"

On the Board: a) Stand-offs.

b) Connector(s) for External JTAG

Prototyre Board Build Up  
External Power CKT (Red LED should be  
included)

GPP Testing CKT

a. Wirewrapping  
Board (L7C/NANO)  
Pie

b. Stand-offs.

Implementation/Design  
of the CKT.Architecture Aspects,  
CPU Architecture, M. Map.→ PVRIC (7805), with  
Red LED

CPU Architecture :

1. 32-bit Architecture

CPU Architecture

a. ALU 32bit

Arithmetic/Logic  
Unit.

b. Register File,

A Bank of Registers. 32 bits  
GPRs

General Purpose Registers

Those Registers that can  
participate Any meaningful

Arithmetic/Logic Operations. To Define/Determine the Behavior  
of peripheral Special Purpose Registers.

SPIRs 32 bit

Naming Convention: Controllers.  
6 letters

Common Design for SPIRs:

- 1° Central Register(s) per Each Peripheral Controller

$\text{CON}$



- 2° Data Register, DAT

- 3° Pull-up/Down (Electric Characteristics)

- C. Data Bus, Bi-Directional " 32 bits Information Flowing Both Directions.

Address, "Uni-directional" from CPU to the Outside. 32 bits

Notation: 32 bit Register

$\text{GPR}_X[31:0]$

LSB

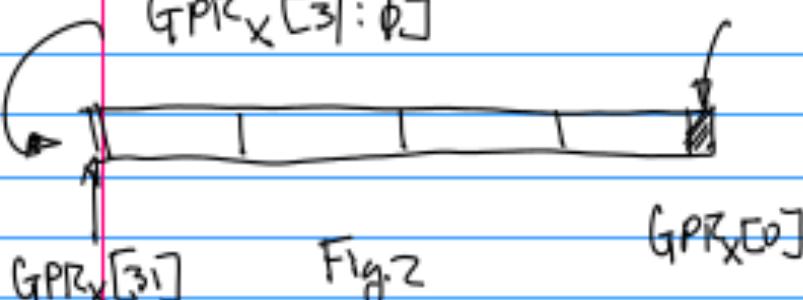
$$2^{32} = 2 \cdot 2^{10} \cdot 2^{10} \cdot 2^{10} \dots (1)$$

$$2^{10} = 1K, 2^{20} = 2^{10} \cdot 2^{10} = 1M \dots (2) \quad \dots (3)$$

$$2^{30} = 1M \cdot 1K = 1\text{ gig} \dots (4)$$

$$2^{32} = 2 \cdot 2^{30} = 4\text{ GB}$$

3. Memory Map.

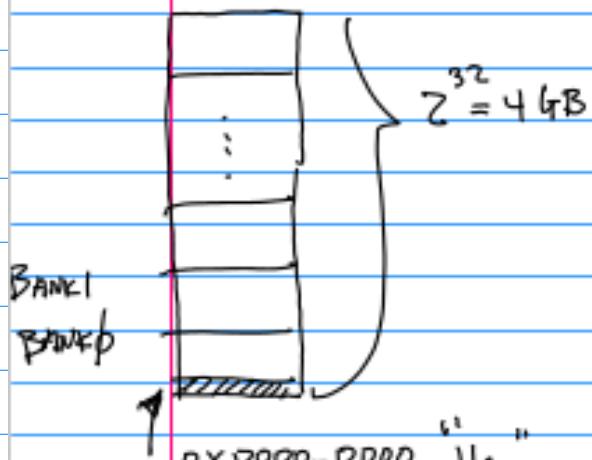


For Address Bus, Addr[31:0] =

$a_3 | a_{30} \dots a_1 | a_0$

## CMPE240

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Define Starting Addr. of Each Bank:

$a_{31}$	$a_{30}$	$a_{29}$	$a_{28}$	
0	0	0	1	<b>BANK0</b>
0	0	1	1	<b>BANK1</b>
0	1	0	1	<b>BANK2</b>

1 1 1 BANK 7

Write the address for Each Bank.  
"Starting" (32 bit)

a. PWR-up Address:

CPU will fetch the 1<sup>st</sup> executable from this memory location.

$\rightarrow 0x0000-0000$

for ARM

Note: for x86, the PWR-up

Address:  $0xFFFF\_FFF0$

For BANK0 :  $0x0000\_0000$

BANK1 :  $0x2000\_0000$

.. 2 :  $0x4000\_0000$

Example: CPU Datasheet pp. 13.

GPIO  $0x2009\_C000$

b. BANKS.

$$2^{32}/8 = 2^{32}/2^3$$

$$= 2^{29} = 2^9 \cdot 2^{20} = 512\text{MB}$$

How many Bits Do we need to uniquely define Each Bank?

3 bits  $\rightarrow a_{31}a_{30}a_{29}$

c. Collection of SPRs are mapped to here, e.g.

Addr. for SPRs are mapped to here

d. Which memory Bank holds

this GPIO? BANK1

whose starting Address is

$0x2009\_C000$

Sept 13 (mon)

1<sup>o</sup> Today's Topics: Integrate Architecture Discussion with Software Development

IDE. Objectives: To

Write first C program for testing purpose

Example: Starting from CPU

Memory map  $\rightarrow$  8 Banks  
PP13

1st 256 kB  
= Flash

0x4003\_0000,

Rest of the Banks, such as  
Mem. Controller, Peripheral  
Controller

$\downarrow$   
Peripheral controllers  $\rightarrow$  SSP1 (SPI)  
on the Mem. map.  
APB  $\neq$  APB  
 $\downarrow$

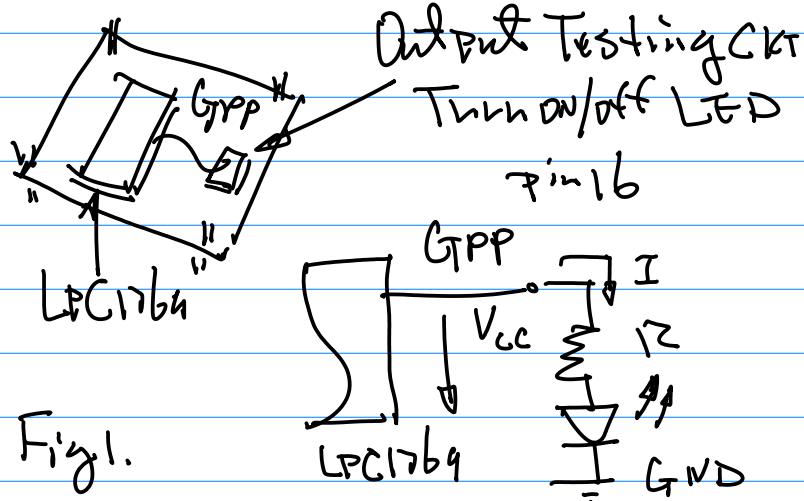
S.P.R.s.  $\leftarrow$  0x4003\_0000  
"Con" 3 Letter  
Size 4000

a Naming conversion Prefix Root + Postscript

"SPICON"  $\rightarrow$  "SPICON001" for Example  $\rightarrow$  C Compiler/C code  
3 letters 3 letters 3 letter

= b Definition: Are those SPRs for the init & Config of a Peripheral Controller.

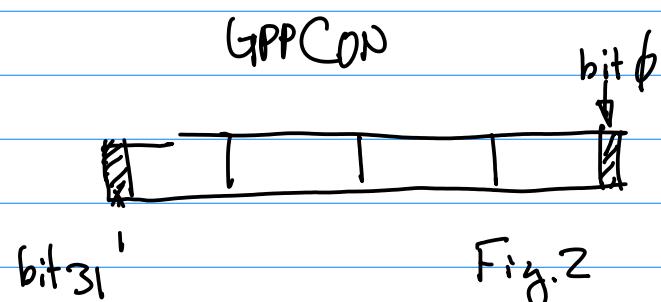
Example. GPP



$$V_{CC} = IR + V_{LED} \quad \dots (1)$$

$$I \approx 8 \text{ mA.} \rightarrow R \approx 2 \text{ k}\Omega \quad 300 \text{ }\mu\text{A}$$

$$V_{LED} \approx 1.8 \text{ VDC}$$



Where to find GPPCON on the  
memory map?  $\rightarrow$  Addv.  
of GPPCON is described on  
CPU Datasheet.

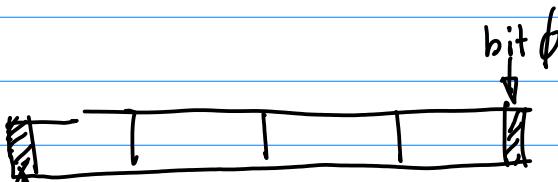
# CmPE240

$2^{32}$  Possible Combinations  
of Init & Config. Feature

GPP (General Purpose Port)

32 pins, Define pin 1/b as output  
pin.

We have to use the following  
init & config pattern:



bit 31      0x F2ff\_ff00

To make pin 1/b as an output.

First, "Port" the Architecture

Compiler to the target

#define GPPCON

then, Copy 0xF2ff\_ff00 into  
this memory location.

Homework: Show + Tell  
By Next Week Installation of mCU  
+ Import LTC17b9.

Sept 15 (W)

Architecture

Today's Topics: GPIO Design

Reference: 1° 2021F-105 ~ On  
ID: UPI0

C-Code for Init & Config  
is required

Example: Make GPP for  
Input & Output  
Testing.

Hardware

Software { NXP MCUXpresso  
Import GPP Sample  
"zip"

Design Step 1.

Identify / Select GPP / GPP-Pins  
P<sub>b</sub>.2, P<sub>b</sub>.3

(Connector → CPU → Selection  
Data Sheet)

Step 2. Define P<sub>b</sub>.2 Asntent ,

P<sub>b</sub>.3 As Input ,

Design the Hardware

Step 3. SPRs (Special  
Purpose Registers) for

the GPP Peripheral  
Controller

Connector → CPU  
J2-21 → Pin → Data  
Sheet  
...  
P<sub>b</sub>.2  
P<sub>b</sub>.3  
↓  
SPRs

Note: SFRs commonly defined / utilized are

GPFCON

where  $x = A, B, C, D, \dots$

GPFCON

GPF DAT (32 bits  $\rightarrow$  32 pins)

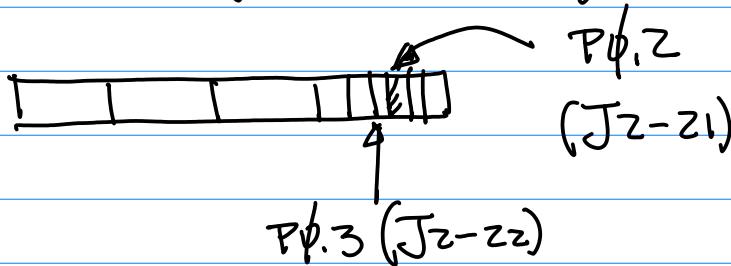
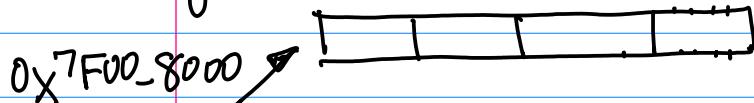


Fig. 1

Find Table on CPU Datasheet to define Pb.2 output, Pb.3 as input.

Example, Samsung Arren II Datasheet  
pp312

Fig. 2



Question: Define Binary Pattern for  
Find GPA CON to make  
its pin 2 as an output?

Sept. 20 (mon) Topics: 1<sup>o</sup> GPF

SFRs, IDE, Sample Code;

2<sup>o</sup> 2D GE.

Example: git(class)

2021F-105-GPP...

i. Naming Convention in C Compiler

LPC\_GPIO0->FIODIR

LPC\_GPIO0->FIOSET

LPC\_GPIO0->FIOCLR

↑  
Target Peripheral Controller (Family)  
↑  
Special purpose Register

From the Example, qit, 2021F-105

From CPU datasheet, GPIOs are configured using the following registers:

1. Power: always enabled.
2. Pins: See Section 8.3 for GPIO pins and their modes.
3. Wake-up: GPIO ports 0 and 2 can be used for wake-up if needed, see (Section 4.8.8).
4. Interrupts: Enable GPIO interrupts in IO0/2IntEnR (Table 115) or IO0/2IntEnF (Table 117). Interrupts are enabled in the NVIC using the appropriate Interrupt Set Enable register.

Chapter 9, pp 129

PINSEL[5:4] for P0,2

PINSEL[5:4] = 00 for I2C

PINSEL[5:4] = 01 for UART  
Tx

pp 133 FIODIR Example,

P0,3 output, Find SPR?

Define bit values  
for the output

Table Look up.

FIODIR

FIOSET, CPU Datasheet  
Look up.

```
void GPIOinitOut(uint8_t portNum,
                  uint32_t pinNum)
```

```
{ if (portNum == 0)
```

```
{ LPC_GPIO0->FIODIR |= (1 <<
pinNum); }
```

```
else if (portNum == 1)
```

```
{ LPC_GPIO1->FIODIR |= (1 <<
pinNum); }
```



pin Num  
Set to  
"1"

$1 \ll \text{pinNum}$  // Set direction  
to pin Num

Logic Operation  
"1" = Bitwise  
"0" = OR  
"?" = ?

Example: Set Pin

```
void setGPIO(uint8_t portNum,
             uint32_t pinNum)
{
    if (portNum == 0)
    {
        LPC_GPIO0->FIOSET = (1 << pinNum); // 1 as output
        printf("Pin 0.%d has been set.\n", pinNum);
    }
}
```

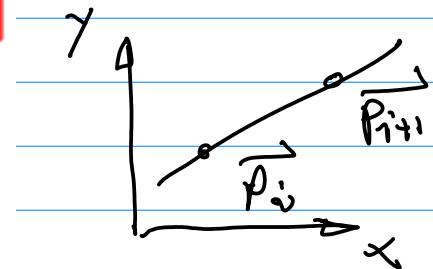
Turn ON LED  
(Output '1')

$\vec{P}(x, y)$  Notation  
 $\vec{P}(x, y) = (x, y)$   
 $\vec{P}_i \rightarrow \vec{P}_i(x_i, y_i) \rightarrow$   
 point(s),  
 vertex, vectors  
 $\vec{P}_i = \vec{P}_i(x_i, y_i) = (x_i, y_i)$

Example: Clear the pin

```
void clearGPIO(uint8_t portNum, uint32_t pinNum)
{
    if (portNum == 0)
    {
        LPC_GPIO0->FIOCLR = (1 << pinNum);
        printf("Pin 0.%d has been cleared.\n", pinNum);
    }
}
```

Formulation for  
a straight line



Now, 2D Vector Graphics

$\vec{P}(x, y)$  a point, vertex, a vector

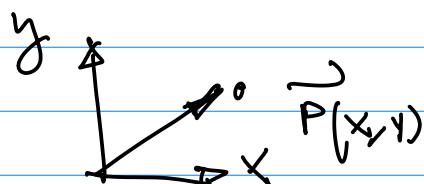
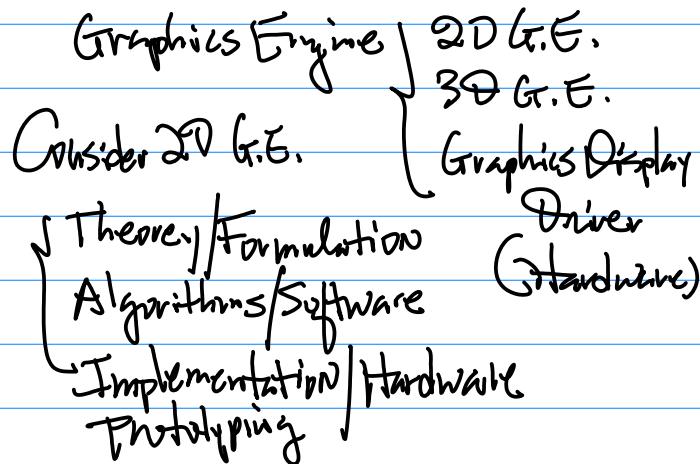


Fig.1

Sept. 22 (W)

Fig.2



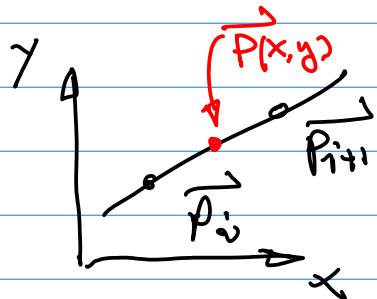


Fig. 2

Note: Need 2 points  $\vec{P}_i, \vec{P}_{i+1}$  to define a line

Let's define a direction vector

$$\vec{D}(x_d, y_d) = \vec{P}_{i+1} - \vec{P}_i$$

$$= \vec{P}_{i+1}(x_{i+1}, y_{i+1}) - \vec{P}_i(x_i, y_i) \quad \text{OR,}$$

In C/C++ Coding, we use the following equation, From Eqn (i), we have

$$\vec{D}(x_d, y_d) = (x_{i+1} - x_i, y_{i+1} - y_i) \quad \dots (1b)$$

Example: Suppose given a starting pt.  $\vec{P}_i(x_i, y_i) = (3, 4.5)$

$$\vec{P}_{i+1}(x_{i+1}, y_{i+1}) = (5.5, 6.3)$$

Find direction vector?

Sol. By Eqn (i), we have

$$\begin{aligned} \vec{D}(x_d, y_d) &= \vec{P}_{i+1} - \vec{P}_i \\ &= ((x_{i+1}, y_{i+1}) - (x_i, y_i)) \\ &= (x_{i+1} - x_i, y_{i+1} - y_i) \end{aligned}$$

Sub. the given condition

$$\begin{cases} x_d = x_{i+1} - x_i \\ y_d = y_{i+1} - y_i \end{cases} \dots (1c)$$

$$\begin{aligned} \text{direction\_x} &= x[i+1] - x[i]; \\ \text{direction\_y} &= y[i+1] - y[i]; \end{aligned}$$

Let's briefly define a line

Need a pt  $\vec{P}_i$ , or  $\vec{P}_{i+1}$ ; and directional vector

$$\vec{P}(x, y) = \vec{P}_i + \lambda (\vec{P}_{i+1} - \vec{P}_i) \quad \dots (2)$$

↑ Starting pt ↑ scalar ↑ Directional Vector

Let

$x=0$ , then  $\vec{P}(x, y) = \vec{P}_i(x_i, y_i)$   
Starting pt.

 $x=1$ , then
$$\vec{P}(x, y) = \vec{P}_{i+1}(x_{i+1}, y_{i+1})$$

$0 < x < 1$ , Any Point  $\vec{P}(x, y)$  Between  
 $\vec{P}_i$  and  $\vec{P}_{i+1}$ .

$x > 1$  Any Pt.  $\vec{P}(x, y)$  Beyond  
 $\vec{P}_{i+1}(x_{i+1}, y_{i+1})$ .

$x < 0$ , Any Point Beneath  
 $\vec{P}_i(x_i, y_i)$ .

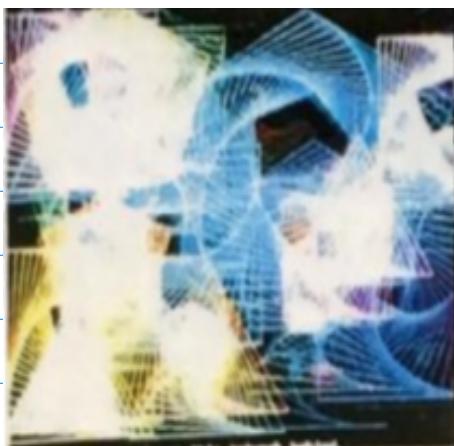


Fig 3a



Fig 3b

Screen Saver Design for LFC

2D G.E.

Rotating Squares And Trees.

Example: Design of Rotating Squares

Step 1. Define 4 vertices/pts

 $\vec{P}_i, i=0, 1, 2, 3$ 
 $\vec{P}_0(x_0, y_0) = (b0, b0), \vec{P}_1(x_1, y_1) = (0, b0)$ 
 $\vec{P}_2(x_2, y_2) = (10, 10), \vec{P}_3(x_3, y_3) = (b0, 10)$ 

Based on the physical display device

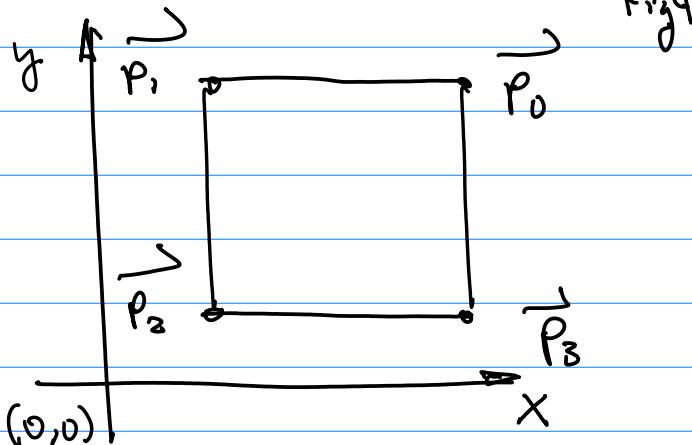


Fig 4

Note: Be sure to arrange  $\vec{P}_i$  in a  
Counter Clockwise direction.  
(for later 3D Hidden Line/Surface  
Removal)

Step 2. Use

$$\vec{P}(x, y) = \vec{P}_i(x_i, y_i) + \lambda (\vec{P}_{i+1}(x_{i+1}, y_{i+1}) - \vec{P}_i(x_i, y_i)) \dots (1)$$

# CmpE240

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Prepric: LCD Soldering on  
the mininwrapping Board,  
Input Single line  
Drawing Project.

Sept. 27 (Mon)

Homework, 2 pts. Due 1 week from Today

[Topics: 2D Screen Saver Design]

Requirements:

a. Build LCD Hardware

Interface;

b. Input Sample code from  
github/finalili/CmpE240

2018S-1D-LCD-DrawLine.

Modify the code to Display 2D

Rotating Squares Using 2D  
Vector equation;

Submission:

c. Project (Zip, Exported)

d. Screenphoto

Submission to CANVAS.

Announcement:

Office hours — The 3:40-4:40 pm.

Due to SJSL off-Campus  
Program.

Example: Continued from pp 15.

Step 2. Use Vector Equation  
to find 4 pts

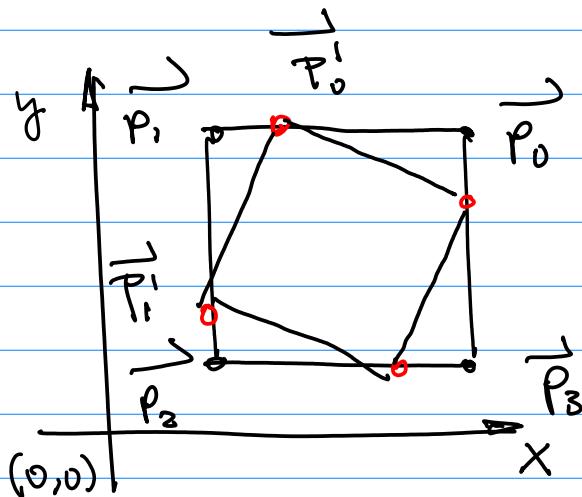


Fig. 1

Let  $\lambda = 0.8$ , for

line 1 ( $\vec{P}_1$  and  $\vec{P}_1'$ ): Eqn(1), pp 15.

Calculate a point  $\vec{P}_0'$

**SuperScript:** the  
level of iteration;  
for line 2, 3, and 4, we do the  
same.

Line 2 ( $\vec{P}_1 \nparallel \vec{P}_2$ ), Line 3 ( $\vec{P}_2 \nparallel \vec{P}_3$ )

Line 4 ( $\vec{P}_3 \nparallel \vec{P}_0$ )

In Homework, level  $\geq 10$ .

Coding:

$$x = x_i + \lambda (x_{i+1} - x_i) \dots (1a)$$

$$y = y_i + \lambda (y_{i+1} - y_i) \dots (1b)$$

## Hardware Implementation of LCD Interface.

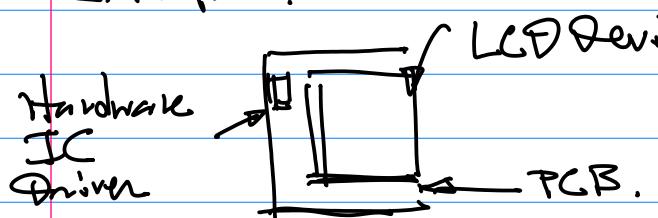


Fig.2



IC Driver

LCD Display

Display module

a. To Drive LCD Display  
To Display a pixel } (x,y) Location

b. To provide feedBack { I(x,y) Intensity, and color  
and Interface to CPU module.

(SPI Interface)

To Establish Interface, SPI (Serial Peripheral Interface)

Hardware pins of SPI : 3+1.

- MOSI (Master Output  
Slave Input)
- MISO (Master Input  
Slave Output)
- SCK (SPI Clock)
- SSEx (SPI Enable)

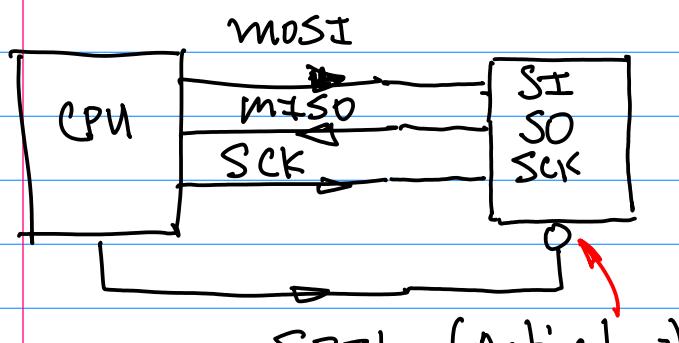


Fig.3.

Note: Mark the Direction of the Signal

Now, Consider the I/F to LCD module.

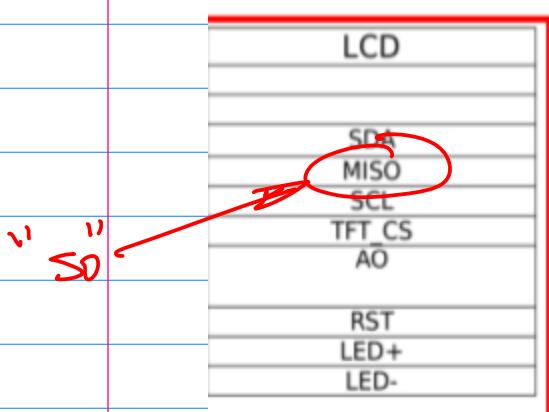
Ref: [github.com/mahili/Cmpe240](https://github.com/mahili/Cmpe240)

Z018S-9-SPILCD...

LPC-1769	
Label	Pin
MOSI	P0.18
MISO	P0.17
SCK	P0.15
CS	P0.16
GPIO-DC (Data / command)	P0.21
GPIO-Reset	P0.22
3.3V	
GND	

a Identify all pins on CPU for SPI I/F;

b Identify all pins on LCD for SPI I/F, Correct matching the host/master and slave



Labels from the LCD Display.

SPI Pins:

SDA, MOSI,
MISO
:

Type: Change MISO on LCD to SD,  
etc.

Note: In addition to SPI interface,  
Identify Command / Data Toggle  
Control pin, the label should be

C/D Depending on the Signal Level, the Communication  
From CPU to LCD is interpreted by LCD either as a Command  
or Data.

Now, Software Part

[github/nihalili/Cmpe240](https://github.com/nihalili/Cmpe240)

2018S-10 - DrawLine

Example: Draw A Line Code

1. Color Definition. hex Digits

2 hexs for Each primitive

color

(red, green, blue)

Primitive Colors: r, g, b

2 hex Digits : min. 0

max: 255

Identify module @ Line 285

Parameters  $(x_0, y_0), (x_1, y_1)$  and

Color

$\overrightarrow{P_0}$  or  $\overrightarrow{P_1}$  or  
 $\overrightarrow{P_i}$  or  $\overrightarrow{P_{int}}$

Match to Expr.(w) & (l<sub>b</sub>)

to Build n Square One  
Line at time.

Sept. 29 (Wed)

Project 1. (10 pts) Due Oct. 18<sup>th</sup>

2 hex  $\Rightarrow$  8 bit  $\Rightarrow$   $2^8 = 256$  Requirements:

2° Bit Arrangement for the primitive colors:  
 $RGB = (2 \text{ hex})(2 \text{ hex})(2 \text{ hex})$  Board, Programs, Report

1° All work including prototype

## CmpE440

However Team work is encouraged.

- 2° Implement Hardware LCD Display.  $\stackrel{a}{=} \text{Rotation of sets of Squares}$ ,  $\stackrel{b}{=} \text{Creates trees to forest}$ ;  $\subseteq 3D$  World Coordinate System Visualization;

Submission:

- 1° Formal written Requirements

Rubrics will be posted on Line.

- 2° Submission on CANVAS.

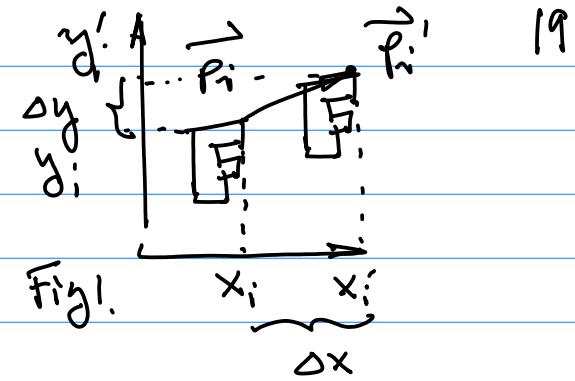
- 3° Source Code/Binary have to Exported Project, in zip.

- 4° Project Report (5 pages) in IEEE format;

- 5° 5 Seconds video

- $\stackrel{a}{=}$  Entire System Setting.  
Frost + Prototype Board;  
 $\stackrel{b}{=}$  Screen of the Animated Display;  $\subseteq$  Show the Prototype Board.

2D Transforms  
Mathematical Formulation



Given 2D pattern  $\{\vec{P}_i(x_i, y_i) | i=0, 1, \dots, N-1\}$

Establish Translation Matrix T.

$\vec{P}_i(x_i, y_i)$  Before;  $\vec{P}'_i(x'_i, y'_i)$  After

$$x'_i \stackrel{?}{=} x_i + \Delta x \quad \text{After} \quad \text{Before} \quad \dots (1)$$

Similarly

$$y'_i = y_i + \Delta y \quad \dots (2)$$

After                      Before

$$\begin{pmatrix} x'_i \\ y'_i \\ 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & \Delta x \\ 0 & 1 & \Delta y \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_i \\ y_i \\ 1 \end{pmatrix} \quad \dots (3)$$

Let's consider Rotation

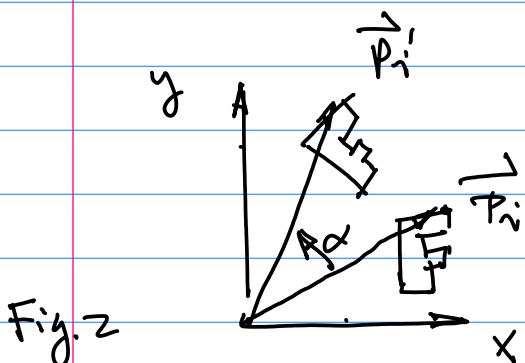


Fig. 2

Note: Counter Clockwise Rotation  
"Positive" Angles

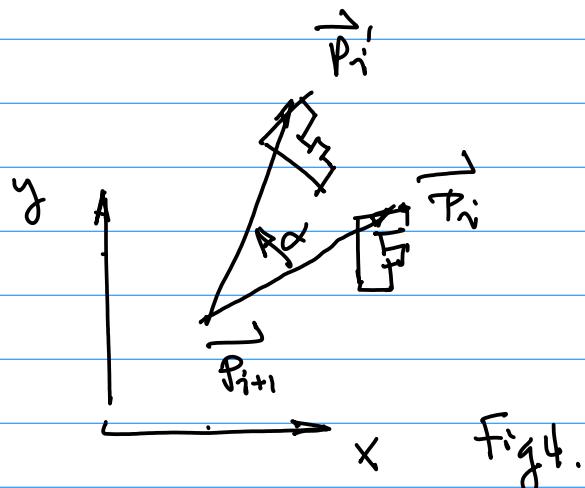


Fig. 4.

After

Before

$$\begin{pmatrix} x'_i \\ y'_i \\ 1 \end{pmatrix} = \begin{pmatrix} \cos\alpha & -\sin\alpha & 0 \\ \sin\alpha & \cos\alpha & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_i \\ y_i \\ 1 \end{pmatrix} \quad \dots (4)$$

Note: for Rotations in Fig 4, we will have to conduct

Pre-processing to Translate the reference point  $P_{i+1}$  to origin(0,0)

Then, Perform Rotation;

Finally, Post-processing. Translate the rotated Pattern Bank to its Original Location

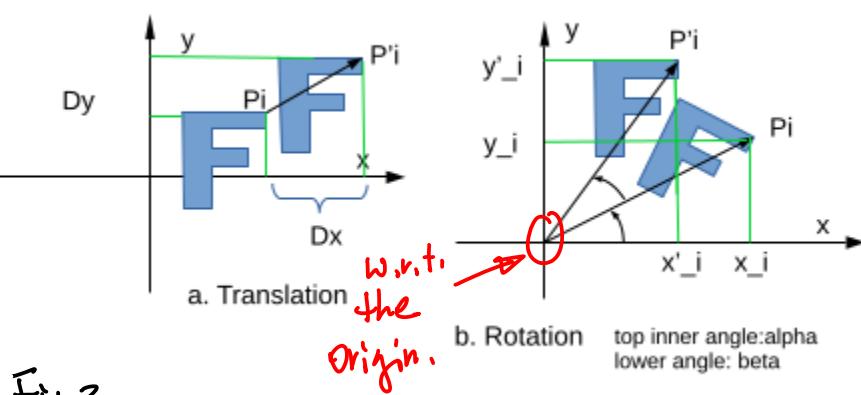


Fig. 3

From Eqn (4)

$$\begin{cases} x'_i = x_i \cos\alpha - y_i \sin\alpha \end{cases} \dots (5a)$$

$$\begin{cases} y'_i = x_i \sin\alpha + y_i \cos\alpha \end{cases} \dots (5b)$$

After

Before

$$\begin{pmatrix} x_i \\ y_i \\ 1 \end{pmatrix} = T^{-1} R T \begin{pmatrix} x'_i \\ y'_i \\ 1 \end{pmatrix} \quad \dots (b)$$

where

$$T^{-1} = \begin{pmatrix} 1 & 0 & -Dx \\ 0 & 1 & -Dy \\ 0 & 0 & 1 \end{pmatrix} \quad \dots (7)$$

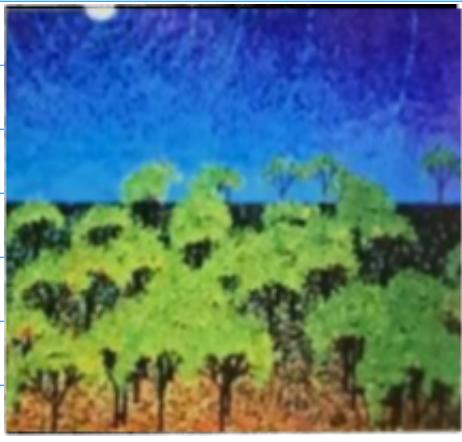


Fig. 5

Example: Use 2D Transforms to Create Trees shown Above

Step 1. Define Initial Points

Points to give a tree trunk.

$$\vec{P}_0(x_0, y_0), \vec{P}_1(x_1, y_1)$$

$$\vec{P}_0(x_0, y_0) = (10, 10), \vec{P}_1(x_1, y_1) = (10, 20)$$

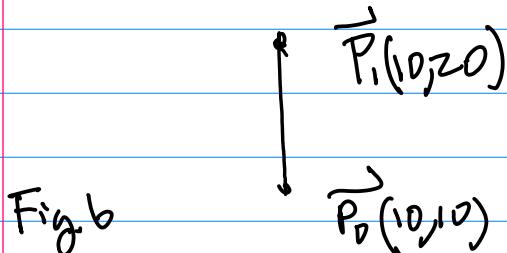


Fig. 6

Step 2. Use Vector Eqn to Create next level major Branch

$\vec{P}_1(x'_1, y'_1)$  as in Fig.

$$\vec{P}_1(x'_1, y'_1) = \vec{P}_0(x_0, y_0) + \lambda (\vec{P}_1(x_1, y_1) - \vec{P}_0(x_0, y_0))$$

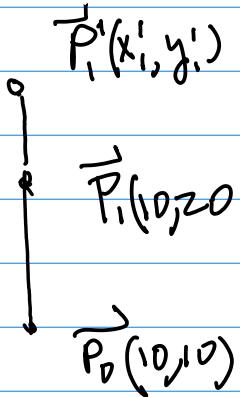


Fig. 7

make  $\lambda = 0.8$ .

Step 3. Rotation of  $\vec{P}_1'$  Counter clockwise to Create Left Branch.

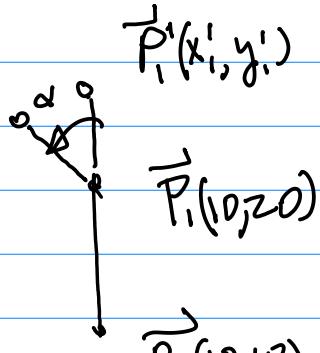


Fig. 8

Oct. 4 (Monday)

Topics : 1° 2D Example for trees  
2° Virtual Display vs.  
Physical Display, Implementation

Example: Continued from Step 3.  
First, Preprocess

Computation

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$$T = \begin{pmatrix} 1 & 0 & DX \\ 0 & 1 & DY \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & +D \\ 0 & 1 & -2D \\ 0 & 0 & 1 \end{pmatrix}$$

Now, Similarly,

Next Rotation,

$$R = \begin{pmatrix} \cos\alpha & -\sin\alpha & 0 \\ \sin\alpha & \cos\alpha & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad \alpha = 30^\circ.$$

Post-Processing:

$$T^{-1} = \begin{pmatrix} 1 & 0 & -DX \\ 0 & 1 & -DY \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 10 \\ 0 & 1 & 20 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & +D \\ 0 & 1 & -2D \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \cos\alpha & -\sin\alpha & 0 \\ \sin\alpha & \cos\alpha & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 10 \\ 36 \\ 1 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 & 10 \\ 0 & 1 & 20 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \cos\alpha & -\sin\alpha & 0 \\ \sin\alpha & \cos\alpha & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ 16 \\ 1 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 & 10 \\ 0 & 1 & 20 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} -b\sin\alpha \\ b\cos\alpha \\ 1 \end{pmatrix}$$

From Eqn(s) (7):

$$\begin{pmatrix} 1 & 0 & 10 \\ 0 & 1 & 20 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \cos\alpha & -\sin\alpha & 0 \\ \sin\alpha & \cos\alpha & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & +D \\ 0 & 1 & -2D \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 10 \\ 20 \\ 1 \end{pmatrix} = \begin{pmatrix} -b\sin\alpha + 10 \\ b\cos\alpha + 20 \\ 1 \end{pmatrix}$$

New X  
New Y

$$= \begin{pmatrix} 1 & 0 & 10 \\ 0 & 1 & 20 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \cos\alpha & -\sin\alpha & 0 \\ \sin\alpha & \cos\alpha & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

Summary: Put Together Eqn (b) to form the Rotation Algorithm.

$$T^{-1} R T =$$

$$= \begin{pmatrix} 1 & 0 & 10 \\ 0 & 1 & 20 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 10 \\ 20 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & -DX \\ 0 & 1 & -DY \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \cos\alpha & -\sin\alpha & 0 \\ \sin\alpha & \cos\alpha & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & DX \\ 0 & 1 & DY \\ 0 & 0 & 1 \end{pmatrix}$$

Then for  $\vec{P}_1(10, 36)$

$$= \begin{pmatrix} 1 & 0 - \Delta X & \cos\theta - \sin\theta & \Delta X \cos\theta - \Delta Y \sin\theta \\ 0 & 1 & -\Delta Y & \sin\theta \cos\theta & \Delta X \sin\theta + \Delta Y \cos\theta \\ 0 & 0 & 1 & 0 & 0 \end{pmatrix}$$

Suppose LCD  
Resolution is  $120 \times 100$

$$= \begin{pmatrix} \cos\theta - \sin\theta & \Delta X \cos\theta - \Delta Y \sin\theta - \Delta X \\ \sin\theta \cos\theta & \Delta X \sin\theta + \Delta Y \cos\theta - \Delta Y \\ 0 & 0 \end{pmatrix}$$

Number of Pixels/Row  
100: Rows.

Therefore

$$\begin{pmatrix} x'_i \\ y'_i \\ 1 \end{pmatrix} = \begin{pmatrix} \cos\theta - \sin\theta & \Delta X \cos\theta - \Delta Y \sin\theta - \Delta X \\ \sin\theta \cos\theta & \Delta X \sin\theta + \Delta Y \cos\theta - \Delta Y \\ 0 & 0 \end{pmatrix} \begin{pmatrix} x_i \\ y_i \\ 1 \end{pmatrix}$$

$x$ : Left To Right  $0, 1, 2, \dots, m-1$

$y$ : Top down  $0, 1, 2, \dots, N-1$

Limitation:

1° No Negative Value  
in the System.

2° Tied to the  
physical Device  
with Resolution  $m \times N$ .

3° Not Portable

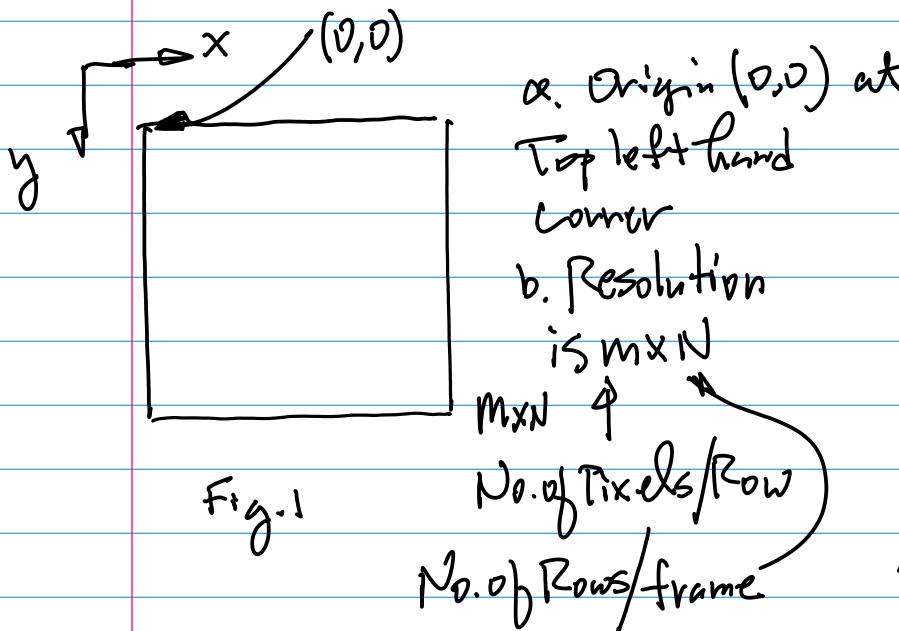
### C/C++ Implementation

$$x'_i = \cos\theta \cdot x_i - \sin\theta \cdot y_i + \Delta X \cos\theta - \Delta Y \sin\theta - \Delta X$$

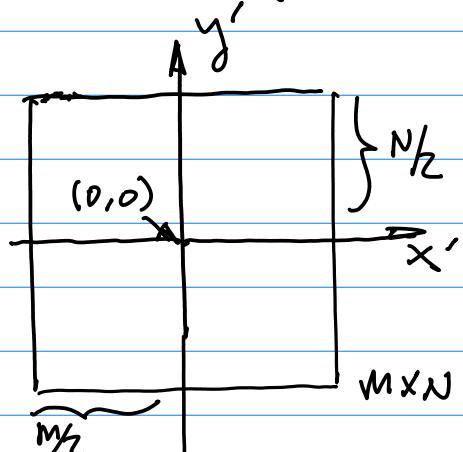
$$y'_i = \sin\theta \cdot x_i + \cos\theta \cdot y_i + \Delta X \sin\theta + \Delta Y \cos\theta - \Delta Y \quad \dots (b*)$$

Physical Display Coordinate

v.s. Virtual Display Coordinate



Now, Virtual Display coordinate



Set  $(0,0)$  at the center of the display device.

Transform physical Display to

# ComPE240

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Virtual Display.

$$\begin{cases} x = x' + \frac{m}{2} & \dots (1) \\ y = -y' + \frac{n}{2} & \dots (2) \end{cases}$$

Note: Verify Eqn(1) & (2).

How to use Eqn(1) and (2).

Conduct Computation in Virtual Coordinate  $(x', y')$ ,

make sure to Scale the result in  $x' \in [-\frac{m}{2}, \frac{m}{2}]$   
in Total No. of Col.

$$y' \in [-\frac{N}{2}, \frac{N}{2}], N : \text{Total}$$

No. of Rows.

Then, use Eqn(1) & (2) map to your physical display.

**Homework** (Due 1 week Oct. 11, Monday) Visit and physical Transform.

1° Write C code to realize Eqn(1) & (2).

2° Prompt the user for input  $(x, y)$  value in

Virtual coordinate System,

Then you compute Eqn(1) & (2)  
to find physical display  
Coordinate, plot (Draw)  $5 \times 5$

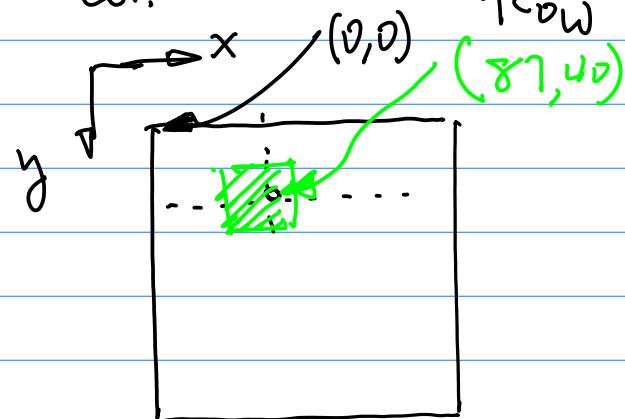
Patch with its center pixel  
Equal to the Computation Result.

Example: Computation Result

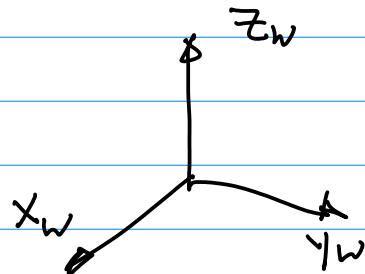
$$(x, y) = (87, 40)$$

Col.

Row



3D Graphics Processing Engine  
Introduction: World Coordinate System



Outlook (Wed)

Fig. 1

Topics: 1° Transformation Pipeline

Note:

1° Affection Update

Posted on bit;

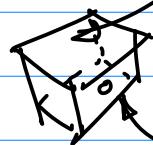
2° Handout on GPIO code,  
please read it, understand  
the code. It is required.

a "pin-Hole" model.

Diameter of the lens ("Hole") is  
very small,  $d \ll s$ .

Enclose to form a virtual  
camera.

Projection Plane  
to form an image



pin-Hole

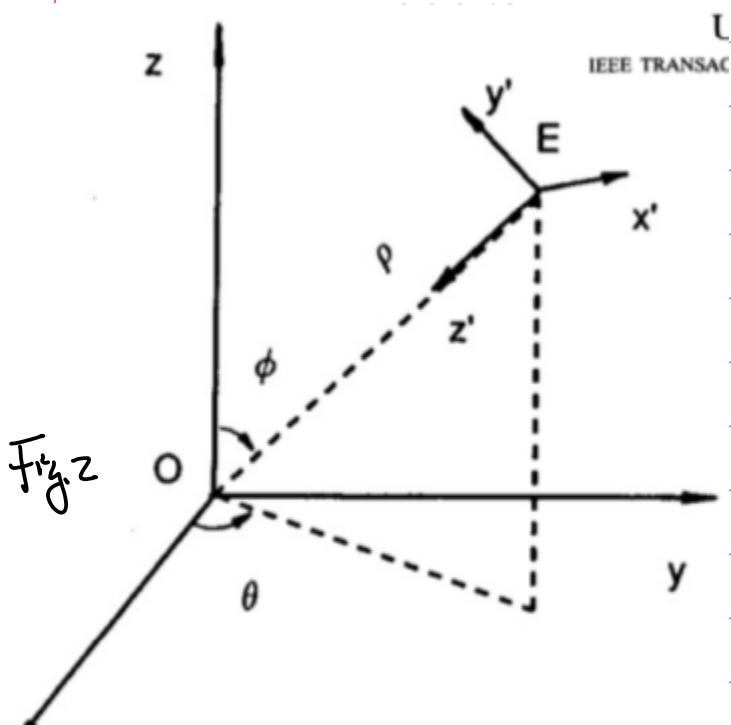
→ ED fixation direction of the  
Virtual Camera

Note: This is just ONE formulation  
Among other 3 Additional  
Possible Formulations

1° Viewer Coordinate System  
 $x_e-y_e-z_e$ , Sub "e" for  
"Eye" / Camera Location;

2° Left Hand System.

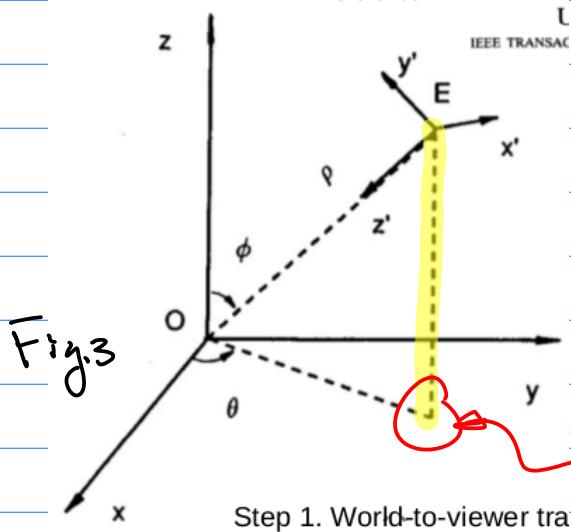
Relationship b/w  $x_w-y_w-z_w$  and  
 $x_e-y_e-z_e$  Systems to Allow  
the Definition of Viewing 3D  
Objects in a different  
Perspective.



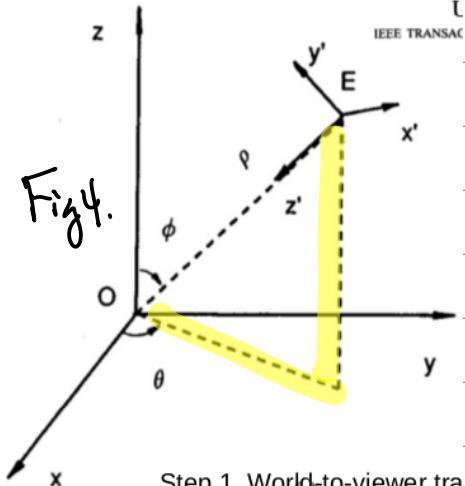
# ComPE40

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Example: Draw A Line, Passes  $E(x_e, y_e, z_e)$   
Perpendicular to  $x_w-y_w-z_w$  Plane



Draw 2nd Line, Passes  $E'$  (on  $x_w-y_w$ )  
to connect to the origin  $(0,0,0)$  of  
 $x_w-y_w-z_w$ . as in Fig



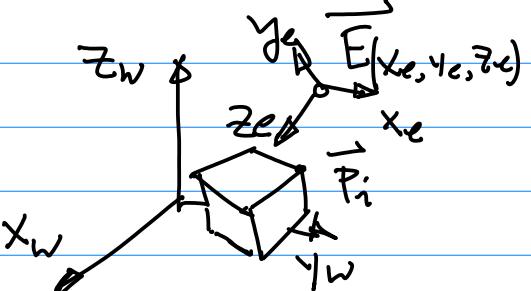
$\theta$ : (Theta) formed Between  
Angle the 2nd Line  
and  $x_w$ .

Angle  $\phi$  (phi): Formed  
Between  $\overrightarrow{OE}$  (Not Exactly  
the  $\overrightarrow{EO}$ ) and  $z_w$

Distance  $\rho$  (rho): from  $E(x_e, y_e, z_e)$   
to the origin  $(0,0,0)$ :

$$\rho = \sqrt{x_e^2 + y_e^2 + z_e^2} \dots (1)$$

Example: A cube given in  
the following figure:



$$T = \begin{bmatrix} -\sin \theta & \cos \theta & 0 & 0 \\ -\cos \phi \cos \theta & -\cos \phi \sin \theta & \sin \phi & 0 \\ -\sin \phi \cos \theta & -\sin \phi \cos \theta & -\cos \phi & \rho \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$\vec{P}_t$  defined in the  $x_w-y_w-z_w$   
 $\vec{P}_i$  defined in the  $x_e-y_e-z_e$  ... (2)

$$\begin{pmatrix} x'_i \\ y'_i \\ z'_i \\ 1 \end{pmatrix} = \begin{bmatrix} -\sin \theta & \cos \theta & 0 & 0 \\ -\cos \phi \cos \theta & -\cos \phi \sin \theta & \sin \phi & 0 \\ -\sin \phi \cos \theta & -\sin \phi \sin \theta & -\cos \phi & \rho \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{pmatrix} x_i \\ y_i \\ z_i \\ 1 \end{pmatrix} \dots (z_b)$$

$\overrightarrow{P'_i}$        $\overrightarrow{P_i}$

After"in  $x_w-y_w-z_w$ "

System Camera

Example: Given A Virtual  
Camera E(200,200,200)

Find Transformation Matrix

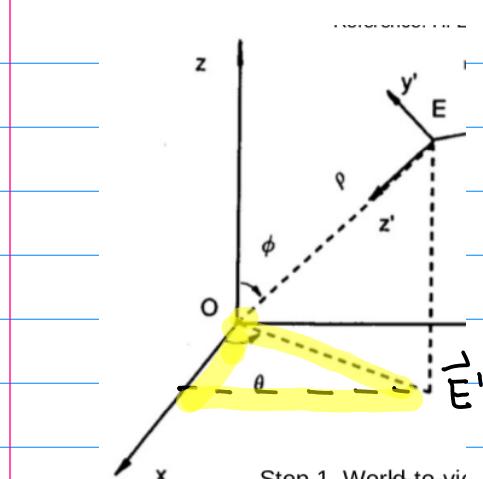
T (World-To-Viewer)

Transform Matrix.

Sol. For  $\theta$  (theta) Angle

$$\cos \theta = \frac{x_e}{\sqrt{x_e^2 + y_e^2}} = \frac{200}{200\sqrt{2}} = \sqrt{2}/2 \dots (3)$$

(From Fig 4, pp. 2b)

Consider  $\sin \theta$ 

Oct. 11 (monday)

Note: 1° 3 Handout material, C  
Program, with 2021F-111x

a) gProg, C ; Architecture →

CPU Block Diagram →  
SPRs → CPU Datasheet  
Init & Config.

b) Drawing C :

Architecture → Write a  
Pixel (location, color/  
Intensity) · Vector Linesubseteq SPC SPI I/F. to Be  
discussed;

Example: Suppose a given

Cub with  $P_i(100, 100, 100)$ ,

And Virtual Camera  $E(200, 200, 200)$

Find Viewer coordinates of

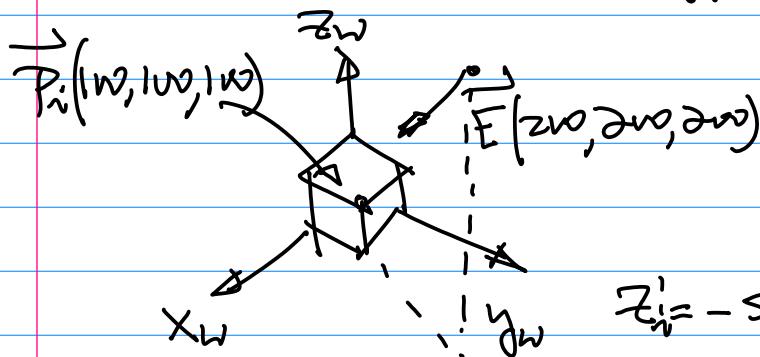
this cub.  $P_i' = ?$

$$y_i' = -\frac{\sqrt{3}}{3} \cdot \frac{\sqrt{2}}{2} \cdot 100 - \frac{\sqrt{3}}{3} \cdot \frac{\sqrt{2}}{2} \cdot 100 + \frac{\sqrt{6}}{3} \cdot 100$$

$$\cos \phi = \frac{\sqrt{3}}{3}, \sin \phi = \frac{\sqrt{6}}{3}$$

$$= 100\sqrt{3}/3$$

$$y_i' = -\cos \phi \cos \theta x_i - \cos \phi \sin \theta y_i + \sin \phi z_i$$



$$z_i' = -\sin \phi \cos \theta x_i - \sin \phi \sin \theta y_i - \cos \phi z_i + p$$

$$= -\frac{\sqrt{6}}{3} \cdot \frac{\sqrt{2}}{2} \cdot 100 - \frac{\sqrt{6}}{3} \cdot \frac{\sqrt{2}}{2} \cdot 100 - \frac{\sqrt{3}}{3} \cdot 100 + 200\sqrt{3}$$

From Eqn (2b) pp. 27

$$\begin{pmatrix} x_i' \\ y_i' \\ z_i' \\ 1 \end{pmatrix} = \begin{bmatrix} -\sin \theta & \cos \theta & 0 & 0 \\ -\cos \phi \cos \theta & -\cos \phi \sin \theta & \sin \phi & 0 \\ -\sin \phi \cos \theta & -\sin \phi \cos \theta & -\cos \phi & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{pmatrix} x_i \\ y_i \\ z_i \\ 1 \end{pmatrix} = \begin{pmatrix} x_i' \\ y_i' \\ z_i' \\ 1 \end{pmatrix} = \left(-\frac{2\sqrt{3}}{3} - \frac{\sqrt{3}}{3}\right) 100 + 200\sqrt{3}$$

$$x_i' = -\sin \theta x_i + \cos \theta y_i = -100\sqrt{3} + 200\sqrt{3} = 100\sqrt{3}$$

$$\begin{cases} y_i' = -\cos \phi \cos \theta x_i - \cos \phi \sin \theta y_i + \sin \phi z_i \\ z_i' = -\sin \phi \cos \theta x_i - \sin \phi \sin \theta y_i - \cos \phi z_i + p \end{cases}$$

$$(x_i', y_i', z_i')$$

$$= (0, 100\sqrt{3}, 100\sqrt{3}),$$

C/C++ Coding Based on Eqn (1).

Optional Homework:

Write C code for Eqn (1).

From the given condition:  $\sin \theta = \cos \theta = \frac{\sqrt{2}}{2}$ ,  $x_i = y_i = z_i = 100$

$$x_i' = \frac{\sqrt{2}}{2} \cdot 100 + \frac{\sqrt{2}}{2} \cdot 100 = 0$$

Handout 2021F-11C SSP.C.  
Regined (Homeworks, Test)

Handout  
SSP.C

```
*****  
* $Id: ssp.c 5804 2010-12-04 00:32:12Z usb00423  
* Project: NXP LPC17xx SSP example  
*  
* Description:
```

Handout 2021F-11Z - ~ Review

2D Vector graphics. to Be posted  
On Line. Question 1 & Question 2.

Homework: UV git hub / CANVAS  
One week from Today 10/18. Submission  
On CANVAS.

Note: Midterm Scheduled  
Tentatively on the 1st week of  
Nov. However, it will be finalized  
Based on the progress in Projects  
and Lecture, a Review (15-20  
min. in Class), b One week Ahead  
Notice.

Format of the lectures.

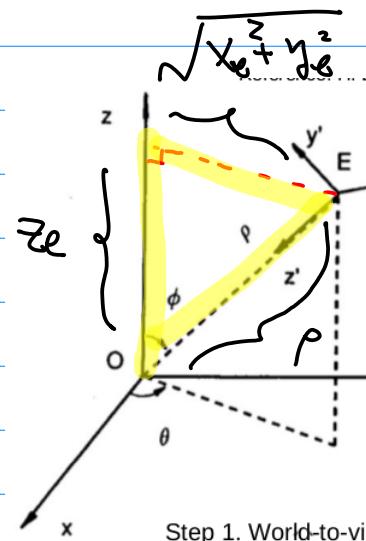
CPU Architectures  $\rightarrow$  CPU Dashed

Coding  
Implementation

And Prototype Implementation

Today's Topics: Transformation

Pipeline.



Step 1. World-to-vit

Note Draw a line pass the  
Vector  $\vec{E}$  location. make  
sure a perpendicular to  $\vec{z}_w$   
b in parallel with the  
line on  $X_w-Y_w$  plane

Example: Continue from previous  
discussion.

$$\begin{aligned} \sin\phi &= \sqrt{x_e^2 + y_e^2} / \rho \\ &= \frac{\sqrt{x_e^2 + y_e^2}}{\sqrt{x_e^2 + y_e^2 + z_e^2}} \quad | \\ &\qquad\qquad\qquad x_e = y_e = z_e = 200 \end{aligned}$$

$$= \frac{200\sqrt{2}}{200\sqrt{3}} = \frac{\sqrt{2}\sqrt{3}}{3} = \sqrt{6}/3$$

$$\cos\phi = \frac{z_e}{\rho} = \frac{200}{200\sqrt{3}} = \sqrt{3}/3$$

2nd Step for Transformation

Pipeline  $\Rightarrow$  Perspective

Projection

Assume the point Before  $\vec{P}_i(x'_i, y'_i, z'_i)$

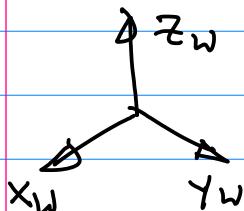
After Perspective Project,

$\vec{P}_i''(x_i'', y_i'')$  (2D pt !)

$$\begin{cases} x_i'' = \frac{D}{z'_i} x'_i & \dots \underline{(a)} \\ y_i'' = \frac{D}{z'_i} y'_i & \dots \underline{(b)} \end{cases}$$

$(x_i'', y_i'')$  ON 2D LCD Display  
With Depth Perception

$D$ : focal length.



$D \approx 20-30$

Draw ON 2D  
Display.

Tree Creation

Oct. 13 (Wed) Class Repo

Ref: <https://github.com/hanli/cmpe240>

Architectural Aspects ON

Display Driver Design (Ref1,  
Ref2)  $\rightarrow$  S.P.I. (Architecture

+ Software Coding, SPRs

(CPU Datasheet)  $\rightarrow$  Handout  
on S.P.I. program.

Road Map Before the midterm

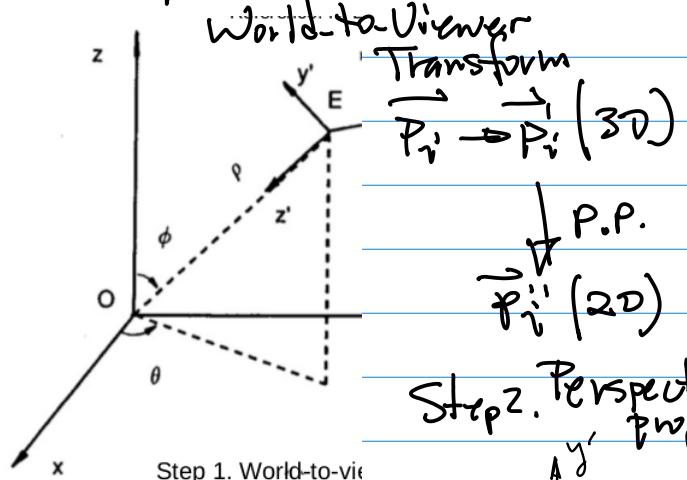
CPU Architecture  $\rightarrow$  GPGPU  $\rightarrow$  2D

Display 2D G.E.  $\leftarrow$  Vector  
Driver  $\leftarrow$  Graphics  
Design Processing Engine

$\uparrow$  Hardware  $\rightarrow$  S.P.I. I/F  
Coding/  
Programming

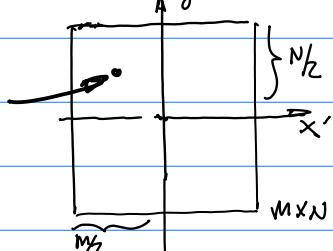
3D  
Introduction

Example:



Step 2. Perspective  
projection

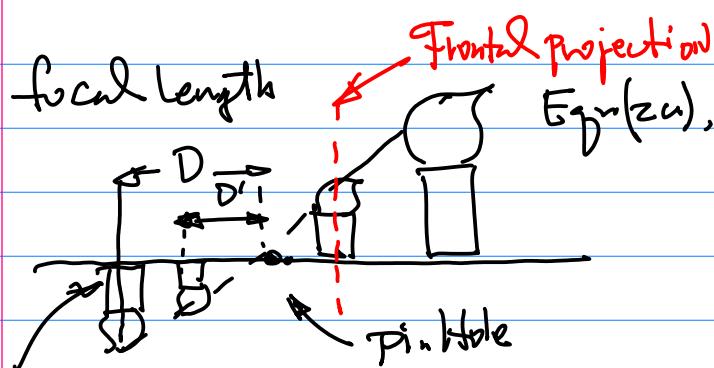
$\vec{P}_i''$   
 $(x_i'', y_i'')$



2021F-113-LCD-TFT (ThinFilmTransistor).jpg

2021F-114-display-NEC-3P5-LCD-68775.pdf

2021S-100-accessible CMPE240-S21-v2-HarryLi.pdf



Back projection plane

Fig. 1.

Compute Perspective projection

Let choose  $D=20$ .

And

$$\begin{aligned} P'_i(x'_i, y'_i, z'_i) = \\ \left(0, 1w\frac{J_6}{3}, 1w\frac{J_3}{3}\right), \text{ PP2.7} \end{aligned}$$

Find Perspective Projection

From Eq (2a)

$$x''_i = \left(\frac{D}{z'_i}\right) x'_i = \left(\frac{20}{z'_i}\right) x'_i$$

$$= \left(\frac{20}{1w\frac{J_3}{3}}\right) \cdot x'_i = \left(\frac{20}{1w\frac{J_3}{3}}\right) \cdot 0 = 0$$

$$y''_i = \left(\frac{D}{z'_i}\right) y'_i = \left(\frac{20}{z'_i}\right) y'_i$$

$$= \left(\frac{20}{1w\frac{J_3}{3}}\right) \cdot 1w\frac{J_6}{2} \quad \text{In Virtual Display Coordinate}$$

Display coordinates  
Transform to find physical display value for your target platform.

## Design of Display Driver Hardware & Architecture

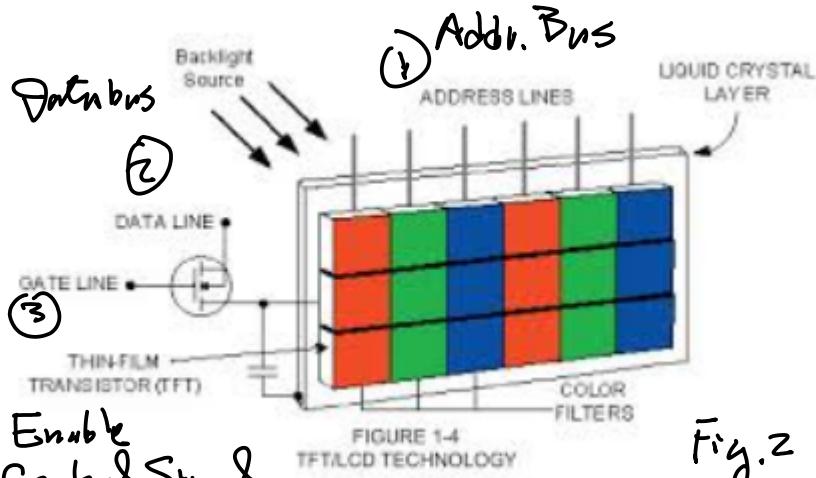
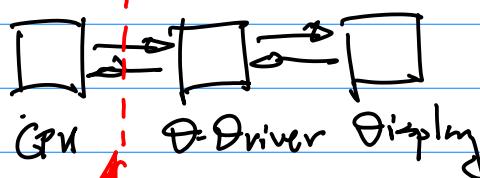
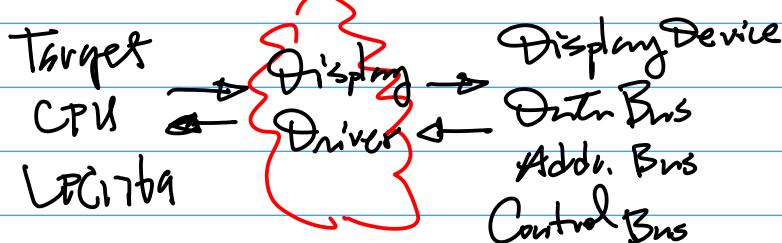


Fig. 2



Interface Part, SPI

Fig. 3

In Virtual Display Coordinate } Hardware "3+1"  
Software }

Step 3. For Implementation.

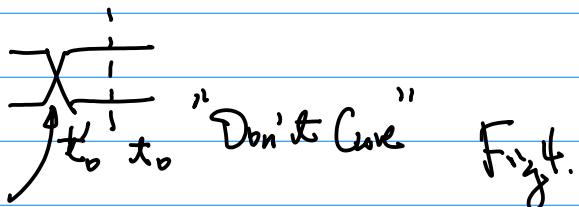
Use Virtual-To-Physical

"3+1" MOSI : Master Out Slave In  
MISO : Master In Slave Out  
SCK : Slave Out

SCK: Serial Clock.

SS<sub>L</sub>: Enable

SPI Waveform (Protocol)



at  $t_0$  time instant, "Changing State".

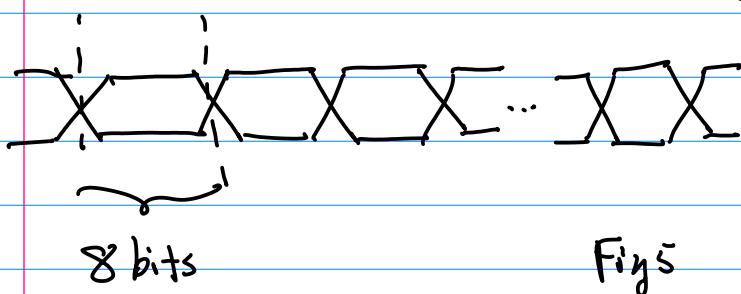
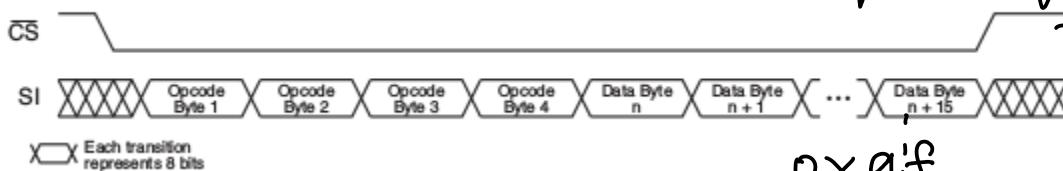


Figure 9-3. Program Sector Protection Register

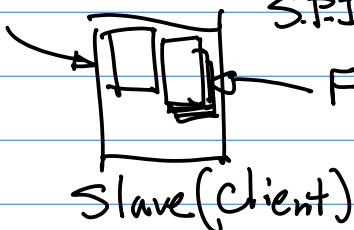


SPI protocol, 3 Fields

- { Opcode : Field 1, Instruction Field
- Address Field, Field 2
- Data (Payload), Field 3, Data Field

Controller (MCU)

Control Register



Depends on Application Need,  
we could have just Instruction  
Field for SPI Communication.  
Or,

We could have complete 3  
Fields, e.g. Opcode (Instruction)  
Field, Addr. Field, and Data Field.

Use Logic Analyzer or DSC.  
to Capture the Waveform for  
Debugging.

Note: Each Field, for Example

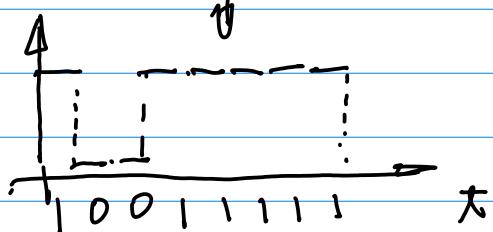
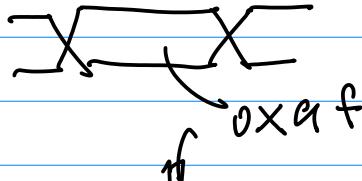
Opcode  
0x9f

To ask for Manufacturer's ID &  
Product ID.

0x9f

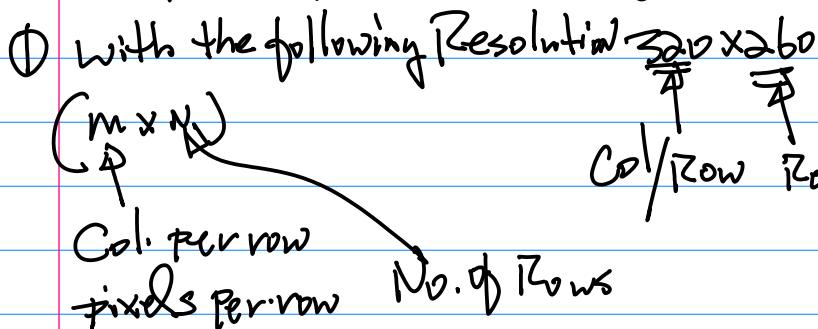
10011111

↓ Waveform



Suppose Display Device

Example: Suppose a Display Device



**NEC** NEC LCD Technologies, Ltd.

## 2. GENERAL SPECIFICATIONS

Display area	53.64 (H) × 71.52 (V) mm
Diagonal size of display	8.9cm (3.5 inches)
Drive system	a-Si TFT active matrix
Display color	262,144 colors
Pixel	240 (H) × 320 (V) pixels
Pixel arrangement	RGB/Red dot Green dot Blue

## Homework Requirements

- ① Read the source code then, from Schematic of the LPC1769 Design, find the proper value to perform init & Config. to make JZ-27 GPIO pin as an input, JZ-23 .. .. .. Output.

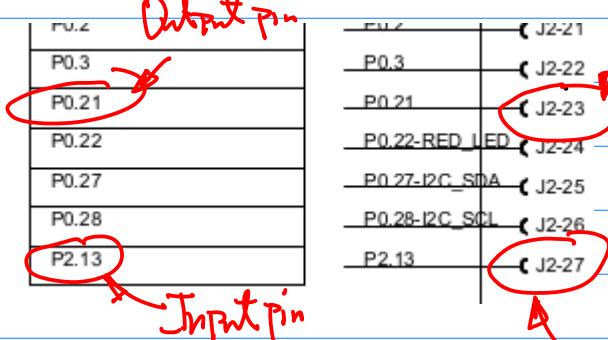
LPCXpresso1769\_CD\_revD(1).pdf

NEC 0.85 LCD 0077E-LK

② And display 30 FPS (Frame/second)

③ pixel depth (color) 24 Bits

V, G, B (red, green, blue) 8 bits each.



Find 1. Bit Rate for SPI Interface?

Submission.

1° Schematic shows GPIO Input & Output Pin

2° Output Testing Ckt (LED, Resistor, Resistor Value)

(Calculation)

3° Show Main program

4° Photo of (GPIO Testing / Output testing Result)

5° Submission to CANVAS.

```
//Initialize the port and pin as outputs.
void GPIOinitOut(uint8_t portNum, uint32_t pinNum)
{
    if (portNum == 0)
    {
        LPC_GPIO0->FIODIR |= (1 << pinNum);
    }
    else if (portNum == 1)
    {
        LPC_GPIO1->FIODIR |= (1 << pinNum);
    }
    else if (portNum == 2)
    {
        LPC_GPIO2->FIODIR |= (1 << pinNum);
    }
}
```

2021F-111-handout-gpio-dotC.pdf

Oct 18 (monday) Homework Due 1 week

Oct 25th

# Cmpe240

34

2. Midterm scheduled on Nov. 10th (Wed). Close Book, Close Notes.

Requirements: a On-Line, Video has to be at all time, b Scan/Take photos of your papers, Convert to One pdf file. c Naming for the midterm paper:

first\\_Last\\_4digitsID\\_mid\\_Cmpe240.pdf

d Submission to CANVAS with Deadline

e Exam is One Home Example.

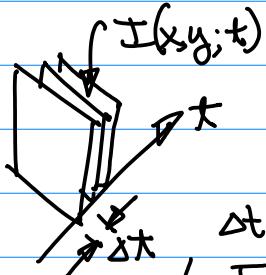
Example: 1° Find SPI Clock Rate (Continued from PP33).

2° Find SFR (Special Purpose

Register) Responsible for Init's Config to fulfill this task?

3° Define the init's Config Binary Pattern, Write/modify C-Code to Realize this function.

So 1° find SPI clock rate?



$\Delta t$  is Related to the FrameRate

Frame rate: 30 FPS (Frame per Second)

$$\Delta t = \frac{1}{f} = \frac{1}{30} = 33.3 \times 10^{-3} \text{ Sec.}$$

SPI Protocol: 3 Fields  $\rightarrow$  Payload (3rd)

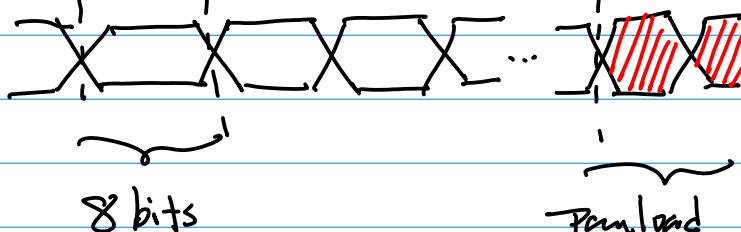


Fig 1.

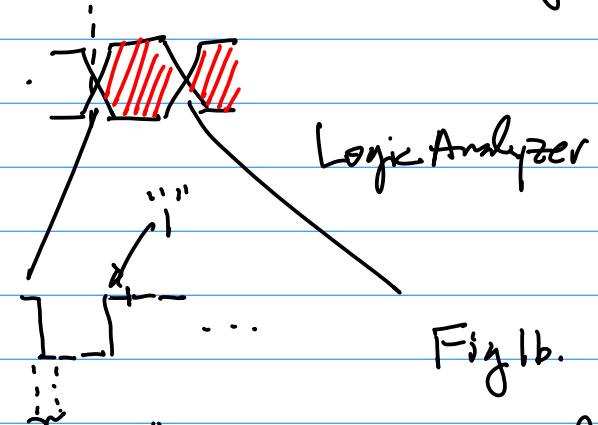


Fig 1b.

1 bit, bit "0"      1 bit transmitted per time needed to fulfill Requirements from 1° to 3°  
So,

$$\underbrace{320 \times 260 \times 30}_{\text{Resolution}} \times \underbrace{30}_{\text{FPS}} \times \underbrace{2^4}_{\text{Color}} = 2^8 \cdot 2^8 \cdot 2^5$$

$$\downarrow \quad \downarrow \quad \downarrow \quad \text{(r, g, b)} \quad 2^{10} \cdot 2^{10} =$$

$$\approx 2^8 \times 2^8 \cdot 2^5$$

$$= 2^6 \cdot \text{Mbps}$$

$$= 64 \text{ Mbps}$$

$1 \text{ meg.}$

( Need to transfer bit mag. bits  
Data to the Display Device)  
from L+CL7ba

From Fig 1b, One bit per clock,

therefore SPI Clock rate :

$$f_{\text{SPI}} = 64 \text{ MHz} \approx 64 \times 10^6 \quad \dots(1)$$

Note: If Resolution is Reduced  
from 360x240 to 160x120 for example  
then Bit Rate Roughly is Reduced to  
its quart of the original.

$$f'_{\text{SPI}} \approx f_{\text{SPI}} / 4 = \frac{64}{4} \text{ MHz} = 16 \text{ MHz}$$

2° Find SCR Responsible, TP431, Datasheet

$$\text{SSPnCR}\phi[3:\phi] = 0111 \quad (\text{B})$$

$$\text{SSPnCR}\phi[5:4] = 00 \quad (\text{B}) \text{ for SPI.}$$

Next 2 Bits are set to  $\phi$  By default.

$$\text{SSPnCR}\phi[6] = \text{SSPnCR}\phi[7] = 0$$

Serial Clock Rate

SCR 8 bits, 256 Different Combinations.

the clock line.

Serial Clock Rate. The number of prescaler-output clocks per bit on the bus, minus one. Given that CPSDVS is the prescale divider, and the APB clock PCLK clocks the prescaler, the bit frequency is  $PCLK / (CPSDVS \times [SCR+1])$ .

Reserved, user software should not write ones to reserved bits. The value read from a reserved bit is not defined.

$$f_{\text{SPI}} = \frac{\text{PCLK}}{\text{CPSDVS} \times (\text{SCR} + 1)}$$

... (4)

Control Register, CR $\phi$

Table 371: SSPn Control Register 0 (SSP0CR0 - address 0x4008 8000, SSP1CR0 - 0x4003 0000) bit description

① SuperSet for SPI

SSP $\phi$  CR $\phi$ : 0x4008-8000  
prefix Root

r $\phi$

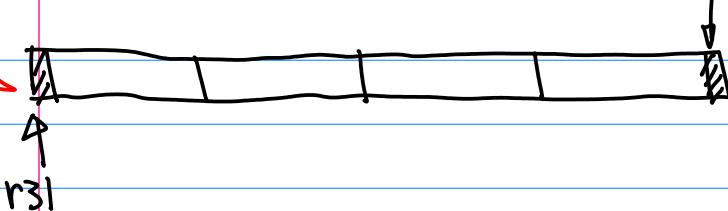


Fig.2

$\text{SSPnCR}\phi[3:\phi]$  : DSS (Data Size Select), 8 bits