

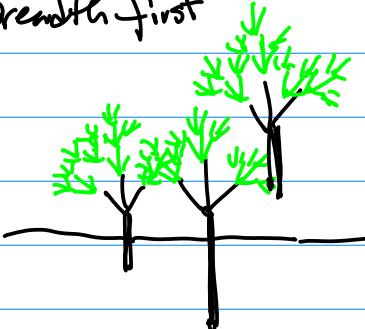
- a A set of Squares Rotation
with One Same Color
b Change location/Color/size

C

Keep the patterns, please
don't remove them!

Part II Once Part I is Done
Switch to Part I.

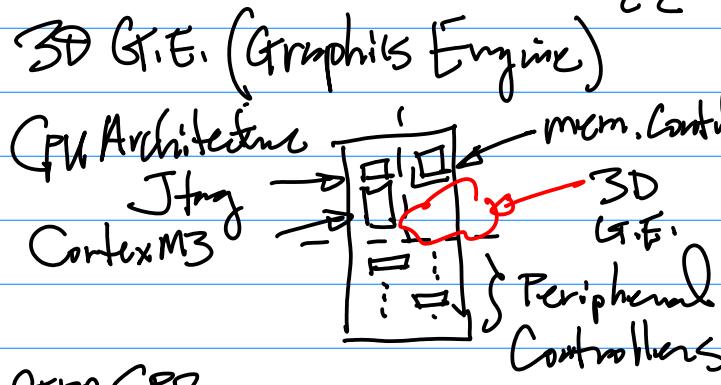
a Breadth first



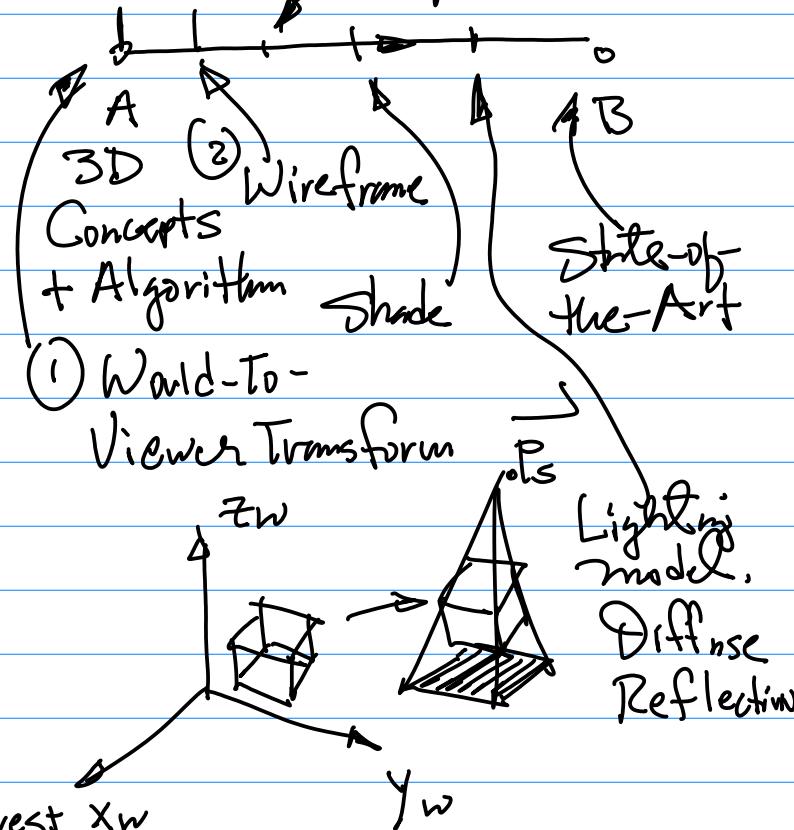
b L>> C Create A patch of Forest
Changing Location/Size

Note: Please Don't freeze the
Drawing Till All the trees
are constructed.

Note: Report Writing.



{ GPP SPRs,
SPI SPRs. Solid Obj.
ITL, HS, Removal



March 15 (Monday)

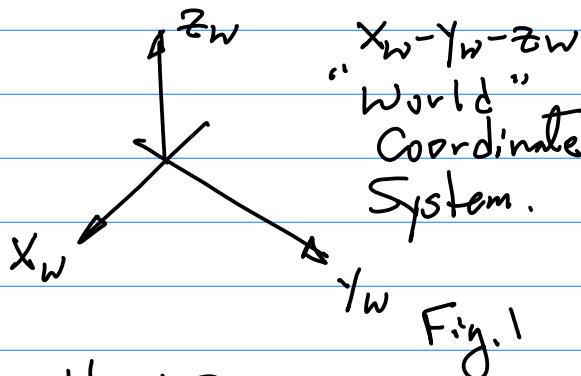
Note: 1st midterm A week from
this Wednesday (March
24th)

2nd Smartphone (Cam Capability)
A piece of Paper to the
Class, Test the Environment

Ref: github : 2018F-114-
3D Graphics

Virtual Camera Location

1°



Right-Hand System,

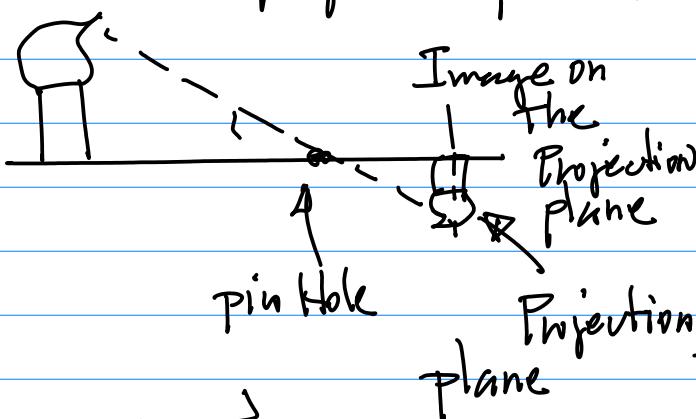
2° Virtual Camera

a Virtual Enclosure

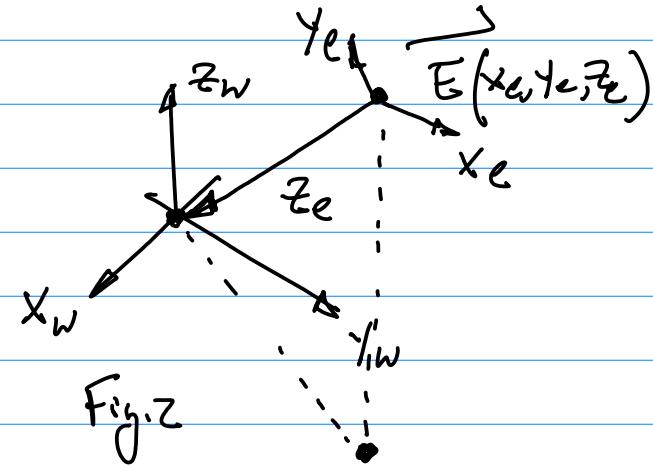
b Optic Lens (Pin Hole)

$\phi_d \approx b$ Very Small diameter

c Projection plane, the plane to form projected Image when light passing through the lens and reaches the projection plane.



3. Denote $E(x_e, y_e, z_e)$ as



Projection of $E(x_e, y_e, z_e)$ On to $X_w - Y_w$ Plane in the $X_w - Y_w - Z_w$ World Coordinate System

4. Viewer Coordinate System

Viewer ~ Virtual Camera

$x_e - y_e - z_e$ Viewer Coordinate System. "Eye"

a $E(x_e, y_e, z_e)$ As the origin.

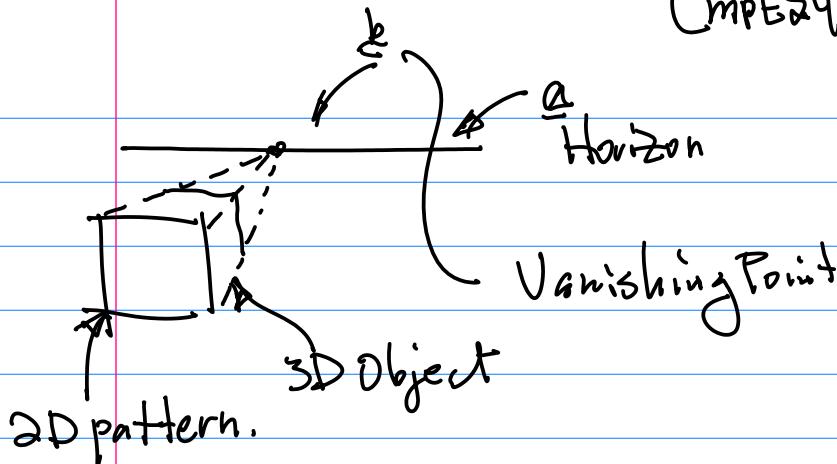
b Left-Hand System.

c z_e -axis points to the origin.

5. Perspective Projection

Complex

24



3D Object formed on 2D plane

7. Transformation Pipeline

To Display 3D object(s) on to 2D LCD Display Screen,

W2V (World-2-Viewer)
Transform
Perspective Projection.

6. Perspective Projection \rightarrow @ the Virtual Camera in X_w - Y_w - Z_w , in X_e - Y_e - Z_e .

Objects in X_w - Y_w - $Z_w \rightarrow$ Viewer Coordinate System X_e - Y_e - Z_e

Projection Plane
form Perspective
Projection

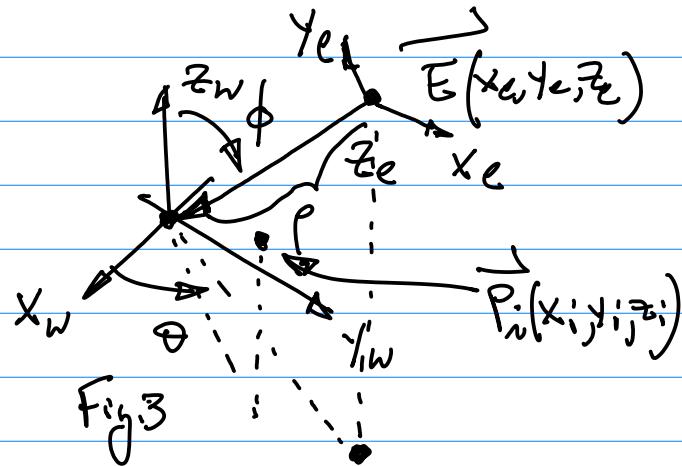


Fig.3

3 parameters:

\hat{a} theta θ Angle

\hat{b} Vector \vec{E} to \vec{O} ,

"roh", Distance

Mathematical Formulation

1. Formula: Transformation $\stackrel{\text{def}}{=} \text{World-to-Viewer}$ Pipeline $\stackrel{\text{def}}{=}$ Transform

\hookrightarrow Z° Foundation

\hookrightarrow Translation

\hookrightarrow Rotations $\left\{ \begin{array}{l} \text{wrt } X_w \text{ and} \\ \dots \text{ wrt } Y_w \\ \dots \text{ wrt } Z_w \end{array} \right.$ wrt Arbitrary Axis

$\stackrel{\text{def}}{=} \text{Perspective Projection} \stackrel{\text{def}}{=} \text{Angle } \theta_w \text{ and } \theta_e \dots (1)$

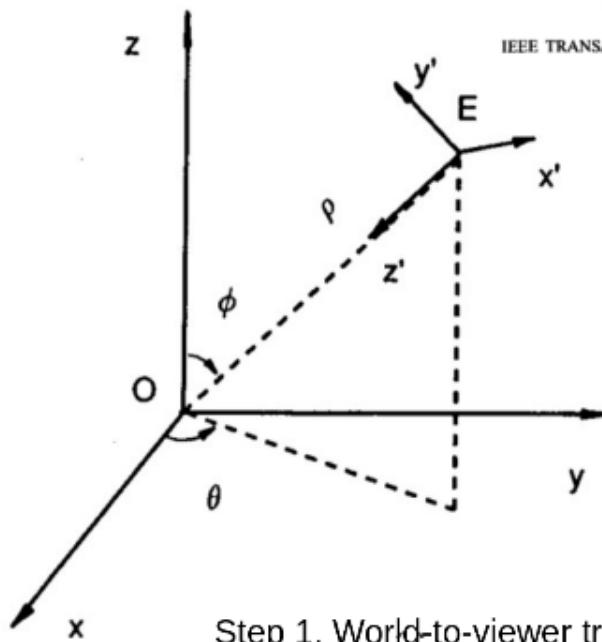
$\stackrel{\text{def}}{=} \text{Angle } \theta_w \text{ and } \theta_e$

World_2_Visitor

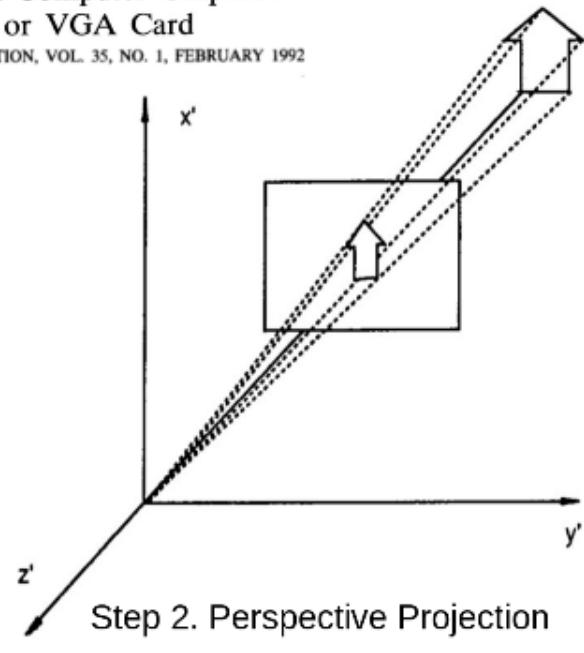
3D Transformation Pipeline Technique

Reference: H. Li Three-Dimensional Computer Graphics
Using EGA or VGA Card

IEEE TRANSACTIONS ON EDUCATION, VOL. 35, NO. 1, FEBRUARY 1992



Step 1. World-to-viewer transform



Step 2. Perspective Projection

$$\mathbf{T} = \begin{bmatrix} -\sin \theta & \cos \theta & 0 & 0 \\ -\cos \phi \cos \theta & -\cos \phi \sin \theta & \sin \phi & 0 \\ -\sin \phi \cos \theta & -\sin \phi \sin \theta & -\cos \phi & \rho \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$x_p = x_e \left(\frac{D}{z_e} \right)$$

$$y_p = y_e \left(\frac{D}{z_e} \right)$$

Harry Li, Ph.D.

Transform, Map P_i from the World-coordinate to Viewer Coordinate.

$$\begin{pmatrix} x'_i \\ y'_i \\ z'_i \end{pmatrix} = T \begin{pmatrix} x_i \\ y_i \\ z_i \\ 1 \end{pmatrix}$$

After
 $x_w - y_w - z_w$

Before
 $x_w - y_w - z_w$

World to Viewer Transform.

March 17 (wed)
Topics : 1° Hardware Architecture 2° Software SPRs Init & Config.

Example: 2D & 3D F.T.
SPI I/F LCD Display to work with LPC1769.

GPIO(GPP) SPI
A set of b_n'

Per. Cont.
System Configuration PWR
CLK
Configuration of the Peripheral Cont. Multi-plexing

$$\begin{pmatrix} \sin\theta & \cos\theta & 0 & 0 \\ \cos\theta & \sin\theta & " & " \\ 0 & 0 & " & " \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Part I.
"θ"

Conjunto to Rotation Matrix

$$\begin{pmatrix} \cos\theta & -\sin\theta & 0 \\ \sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 0 & 0 & 0 \\ \cos\phi & \cos\phi & \sin\phi & " \\ \sin\phi & \sin\phi & -\cos\phi & " \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Part II
"φ"

RTOS
Peripheral Controller { GPP
SPI }

SPI's SPR.

1. Naming Convention

LPC_SC → PCONP

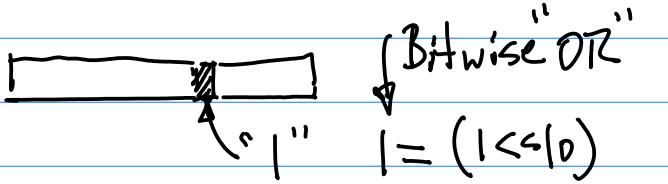
2. Power Up the Selected Peripheral Controller By Setting the Corresponding.

$$\begin{pmatrix} - & - & - & P \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

r_{oh}

CmpE240

26



Tech Spec.

1° 8 bit Transfer,

$$CR\phi[3:\phi] = 0111 = 0x7$$

$$\& = \sim(3 \ll 20)$$

"AND"
"11"
"Negation", "0D"

2° SPI

$$CR\phi[5:4] = 00 \text{ (SPI)}$$

3° Clock f_{SPI}

$$\cong CR\phi[15:8]$$

$$8 \text{ bits } 2^{25} = 2^8$$

Clear
2 Bits



Set 2 bits
as "01"

$$f = \frac{\text{PCLK}}{\text{SPI } (SCR+1) \text{ CPSDVSR}} \dots (1)$$

$$[0, 2^{25}]$$

Much harder.

Today's Topics :

1° Midterm Review

2° SPRs CR ϕ , CR λ
for SPI I/F

Ref:

1° CPU Datasheet.

PP431-433.

Note: $\begin{cases} CR\phi \\ CR\lambda \end{cases}$ LPC_SSP1 \rightarrow CR ϕ
Control Register

Table 57 |



CR ϕ

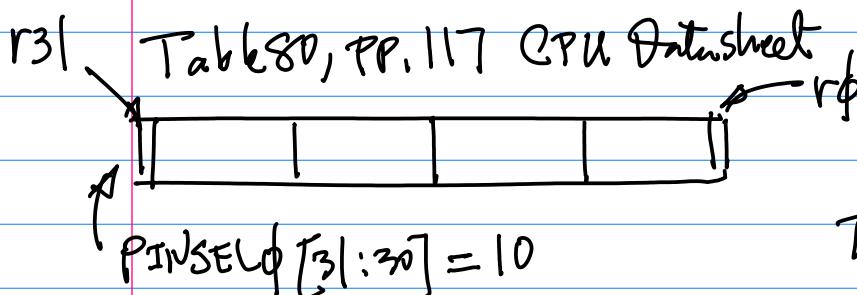
2° Sample code

SPI_init(Draw a
Line)

Example: SSPC Source Code

Walk-Through: 15/-208

Line 162-165 PINSEL0



$$f_{\text{SPI}} = \frac{1 \times 10^6}{(7+1) * \text{DVR}}$$

To find f_{SPI} .

$$2^8 = 256, \text{ SCR } [0, 255]$$

PP. 433, CPSDVSR & [2, 254]

Midterm Review.

1° Video On, Mandatory.

a Submission to CANVAS

15 min. File Uploading

No Late Submission

After the Deadline

Paper will be disqualifed

b If CANVAS Disrupted,

then E-mail Submission

c file in "zip"

Line 173

$\text{CR} = 0x0707 \rightarrow$ Tech

(\rightarrow Spec.)

... ;0000;0111 ;0000;0111

fb upper
Bits all
zeros.

$\text{CR}[5:8]$ SCR $\text{CR}[5:4] = 00$ SPI

= Clock

$$f_{\text{SPI}} = \frac{\text{PCLK}}{(\text{SCR} + 1) * \text{DVR}}$$

$\text{CR}[5:8] = 0 \times 7$

FirstName + 4 Digits + CmPE240
SID mid.zip

2° 3 Questions ±

Hardware { CPU Block Diagram
Memory Map

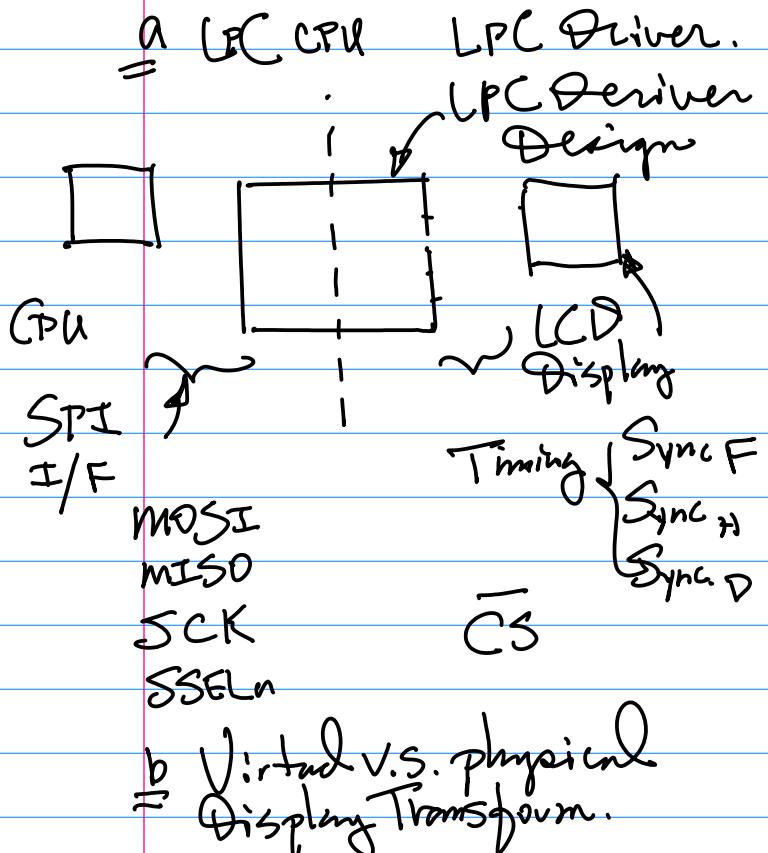
SPRs.

CIC, SCH Design

$\text{CR1}[2] = 0$, Software: Coding
for "Master"

CmpE240

SPR → Boring Pattern
 Coding → for Init & Config
 Debugging Purpose
 Algorithm:
 2D Vector Graphics.
 G.F.
 Tech Spec.



$$\Sigma \vec{P} = \vec{P}_i + \lambda (\vec{P}_{i+1} - \vec{P}_i)$$

Screen Saver. } i. Rotation!
 " } No
 " } w/o Rotation
 " } Matrix
 " } 2D Transforms

Composition of 2D Transform.

$R_{3 \times 3}$
 $T_{3 \times 3}$ → Tree.

Preprocess + $R_{3 \times 3}$ + Post ~

28

Formula: One Page Formula Sheet; is allowed,
 However, No Example, or Verbal
 Explanation is Not allowed,
 Submission of the formula
 Page is required with your
 mid-term paper.
 No multiple choice question.

SCH: Requires All the pins needed
 in the design to have Label;
 Wire: "Arrow" to indicate direction.

Block Diagram: wire(s), Label(s)
 direction(Arrow)

CPU Datasheet will be provided

C Code program will be provided for
 Answering questions, or
 for Redesign.

Calculator is allowed;

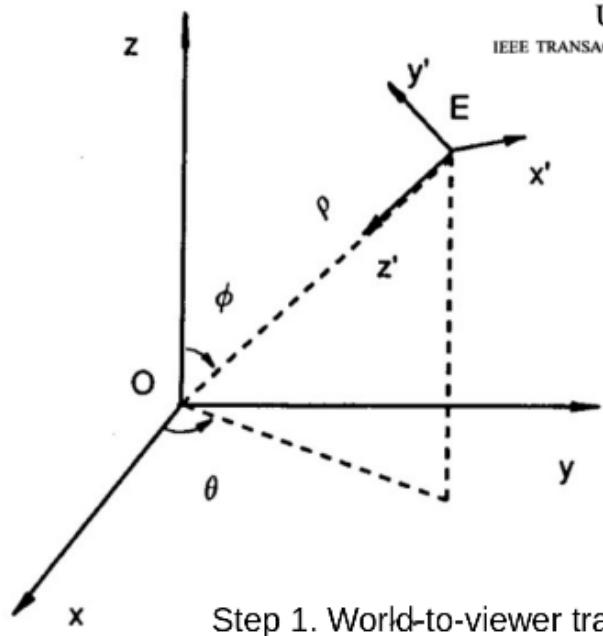
April 5 (Monday)

1. Midterm Key on github, "Key" To search.

3D Transformation Pipeline Technique

Reference: H. Li Three-Dimensional Computer Graphics
Using EGA or VGA Card

IEEE TRANSACTIONS ON EDUCATION, VOL. 35, NO. 1, FEBRUARY 1992



Step 1. World-to-viewer transform

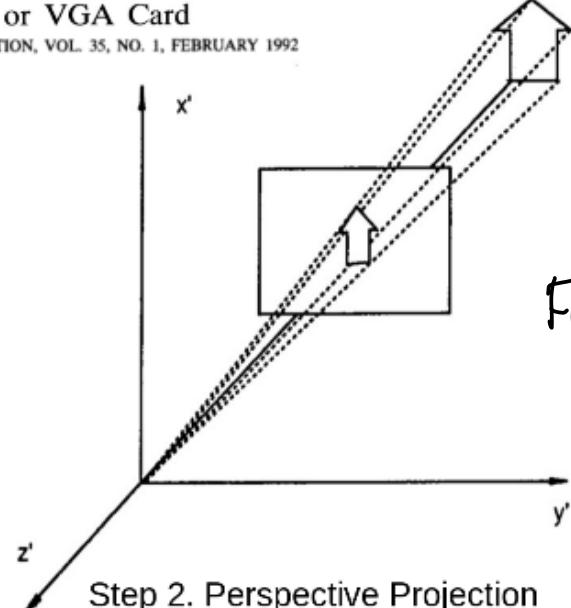


Fig1.

$$\mathbf{T} = \begin{bmatrix} -\sin \theta & \cos \theta & 0 & 0 \\ -\cos \phi \cos \theta & -\cos \phi \sin \theta & \sin \phi & 0 \\ -\sin \phi \cos \theta & -\sin \phi \sin \theta & -\cos \phi & \rho \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

... (1)

$$x_p = x_e \left(\frac{D}{z_e} \right)$$

$$y_p = y_e \left(\frac{D}{z_e} \right)$$

... (2)

mem

Today's Topics: 3D G.E.

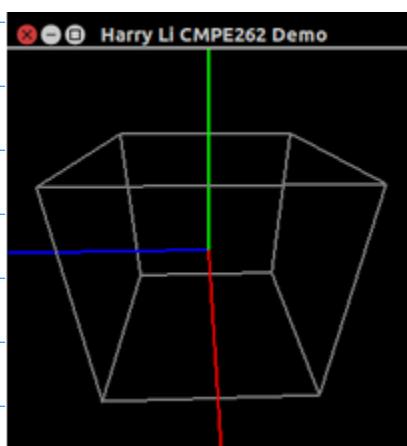


Fig2a

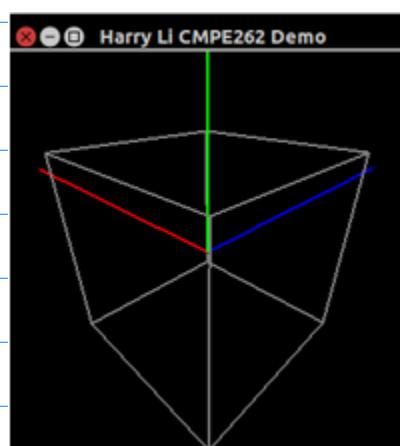
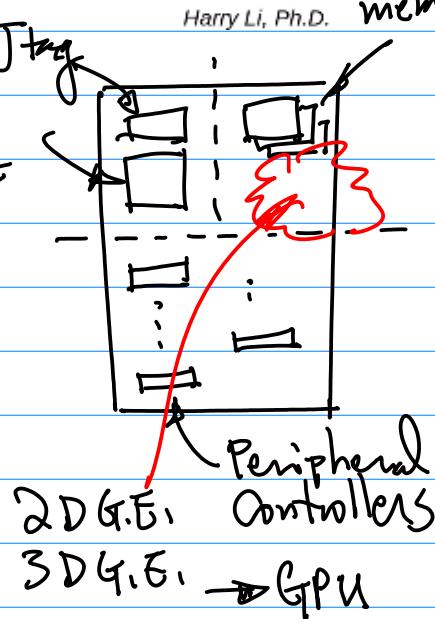


Fig2b



from github. Kang "111a," ...

Note: 2D G.F. { Vector Graphics
Transformation
Primitive Graphics }

{ $\stackrel{a}{=} \text{D.D.A.}$
 $\stackrel{b}{=} \text{line}$
 $\stackrel{c}{=} \text{Arc/circle etc.}$ } Transistor/Gate Level.

Example: 3D wireframe model

First, $X_w-Y_w-Z_w$ World Coordinate System.

$\stackrel{a}{=}$ Right System, r-g-b for X_w, Y_w, Z_w axis
 $\stackrel{b}{=}$ Transformation Pipeline

{ $\stackrel{1st}{=} \text{World-Z-Viewer}$
 $\stackrel{2nd}{=} \text{Perspective Projection}$

$$T_{4 \times 4} : (x_w, y_w, z_w) \rightarrow (x_v, y_v, z_v) \quad \dots (3)$$

Second. Design of Dataset e.g. ... (3b)

4 Vertices for $X_w-Y_w-Z_w$ Axis

$\vec{P}(x, y, z)$ 3D pt. in $X_w-Y_w-Z_w$

Step 1. $\vec{P}(x, y, z) \in \mathbb{R}^3$

for the Origin $\vec{P}_o(x_o, y_o, z_o) = (0, 0, 0)$... (4)

$\vec{P}_x(x_x, y_x, z_x) = (100, 0, 0)$, ... (4-1)

$\vec{P}_y(x_y, y_y, z_y) = (0, 100, 0)$, and ... (4-2)

$\vec{P}_z(x_z, y_z, z_z) = (0, 0, 100)$... (4-3)

Define X_w -axis

Define Z_w -axis

Now, Implementation (Drawing r-g-b axis) \rightarrow AT&T 121m

Homework: Draw r-g-b axis on your CPC Display.
Bring your program Board to the Next Class.

Step 2. World-Z-Viewer

$$T_{4 \times 4} : (x_w, y_w, z_w) \in \mathbb{R}^3 \rightarrow$$

$$(x_v, y_v, z_v) \in \mathbb{R}^3$$

$$\begin{pmatrix} x_v \\ y_v \\ z_v \\ 1 \end{pmatrix} = T_{4 \times 4} \begin{pmatrix} x_w \\ y_w \\ z_w \\ 1 \end{pmatrix} \dots (5)$$

"After"

"Before"

Now, find the X_w -axis in Viewer Coordinate

Step 3. Perspective Projection

$$P: (x_e, y_e, z_e) \in \mathbb{R}^3 \xrightarrow{\text{Proj}} (\underline{x_i}, \underline{y_i}) \in \mathbb{R}^2$$

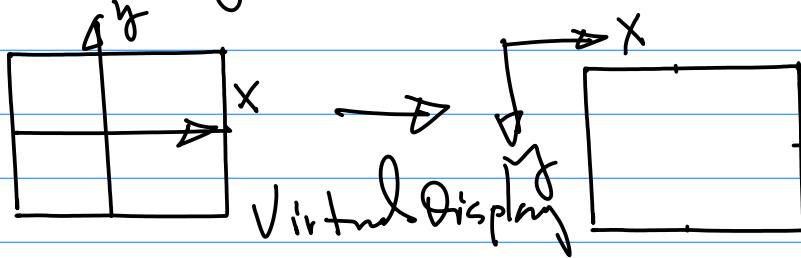
Coordinate on your
LPC1768 Display
Device.

Note:

 $(\underline{x_i}, \underline{y_i})$ is defined on 2D

Virtual Display Coordinate

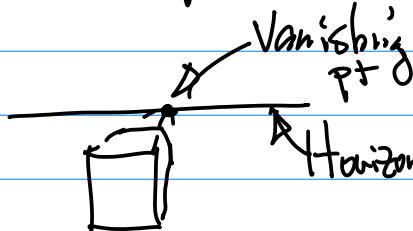
Need to perform Virtual to
Physical Transformation in order
to plot your result.



Back projection plane:
the only light that can
reach the projection plane
is the light passing
through the "pin hole".
(Plane is at the Back)
projection

Frontal projection plane:
move the back projection
plane to the outside of
the virtual camera.

D : Distance from the projection
plane to the "pin hole".



$$\begin{cases} x_p = \frac{D}{z_v} \cdot x_r \\ y_p = \frac{D}{z_v} \cdot y_r \end{cases} \quad \text{(az)} \quad \text{Virtual Cam}$$

(x_p, y_p)
On your 2D
Display

In Homework,
 $D=20$

$$D \approx 20$$

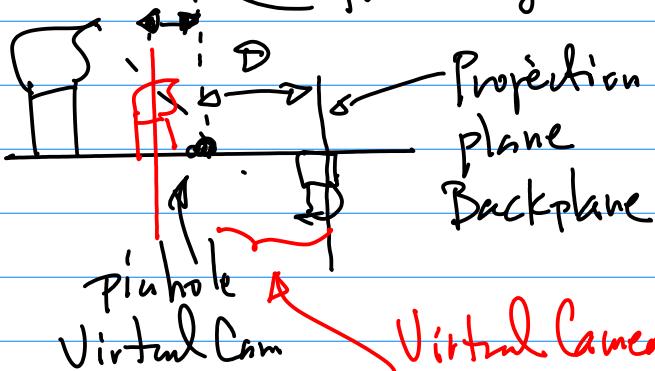
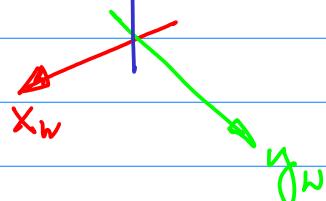
 z_w 

Fig1.



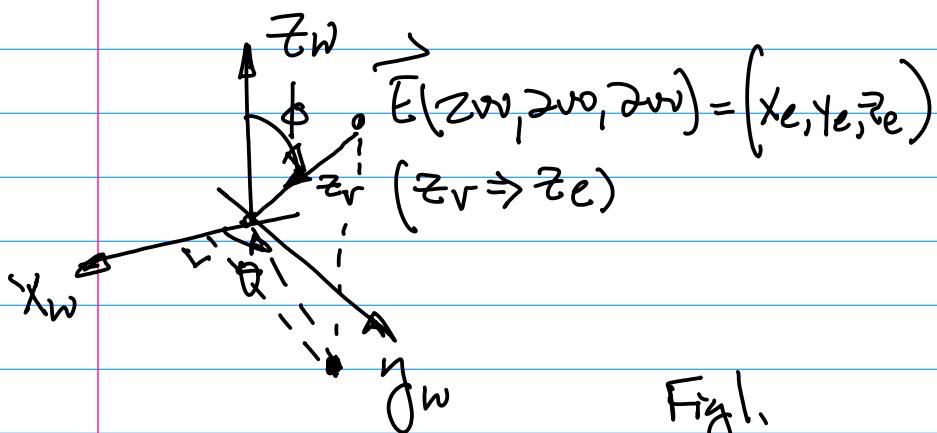


Fig. 1.

$$\sin \theta = \frac{a}{b}$$

a Vector Passing Through \vec{E} , Perpendicular to $X_w - Y_w$ plane, So form an intersection pt.

$$a = y_e = 200$$

$$b = \sqrt{x_e^2 + y_e^2} = 200\sqrt{2}$$

$$\therefore \sin \theta = \frac{200}{200\sqrt{2}} = \frac{\sqrt{2}}{2}$$

$$\cos \theta = \frac{x_e}{b} = \frac{200}{200\sqrt{2}} = \frac{\sqrt{2}}{2}$$

for ϕ (phi)

Note: Angle θ (Theta) on $X_w - Y_w$ plane
wrt Positive X_w -axis And
Counter Clockwise Direction

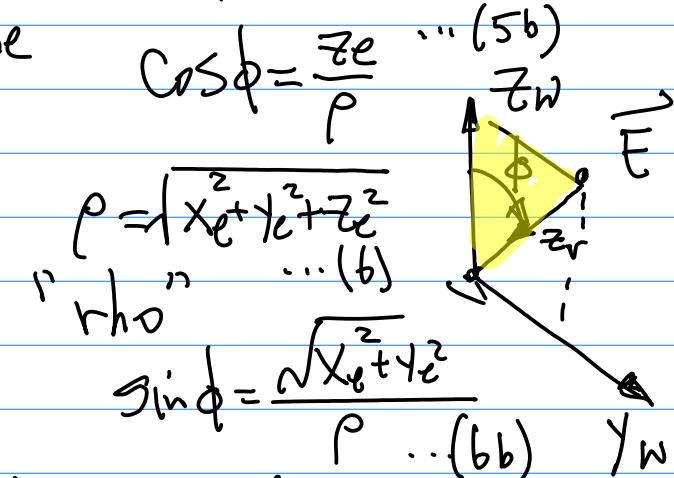
Note: Angle ϕ (phi) on $Z_v - Z_w$
plane,

Now, find each entry on 4×4 matrix, April 7 (Wed)

So World-2d View Transform Note: $X_v - Y_v - Z_v$ Left Hand System
Can be performed.

for Angle θ (Theta)

$\sin \theta$ and $\cos \theta$

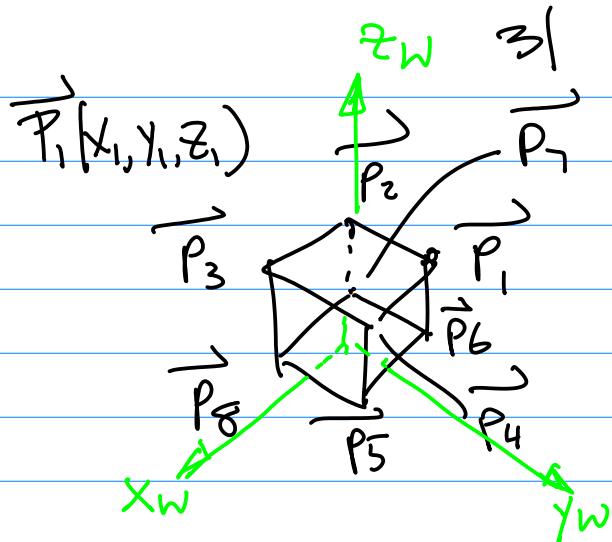


$$\cos \phi = \frac{z_e}{\rho} = \frac{200}{\sqrt{200^2 + 200^2 + 200^2}}$$

$$= \frac{200}{200\sqrt{3}} = \frac{\sqrt{3}}{3}$$

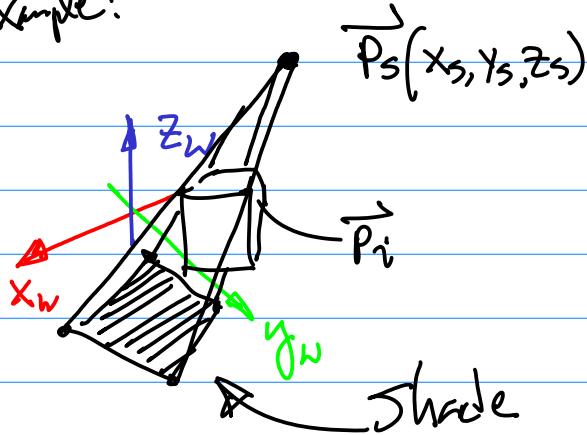
Similarly

$$\sin \phi = \sqrt{x_c^2 + y_c^2} / \rho = \frac{2\sqrt{2}}{2\sqrt{2}\sqrt{3}} = \sqrt{\frac{2}{3}}$$



Consider "Shade" Calculation.

Example:



1. $x_w - y_w - z_w$.

Assignment (Monday)

Note: 1^o Homework Submission (E-mail)

$x_w - y_w - z_w$ Drawing.

Source Code — Photo

(Exported Project) By Wednesday.

2^o Bring your Prototype

Board to each Session for
Inspection, Show & Tell.

Discussion on 3D Shade

Computation

Conditions for this discussion

1^o Define $\{\vec{P}_i(x_i, y_i, z_i) | i=1, 2, \dots, 8\}$

One Side
of the cube Overlapped
with z_w -axis
size of 100.

$\vec{P}_1(0, 100, 110)$
 $\vec{P}_2(0, 0, 110), \vec{P}_3(100, 0, 110)$
 $\vec{P}_4(100, 100, 110)$

Note: P_1, P_2, \dots , are
arranged Counter
Clockwise

$\vec{P}_5(100, 100, 10), \vec{P}_6(0, 100, 10)$

$\vec{P}_7(0, 0, 10), \vec{P}_8(100, 0, 10)$

2. Point Light Source

$\vec{P}_S(150, 100, 200)$

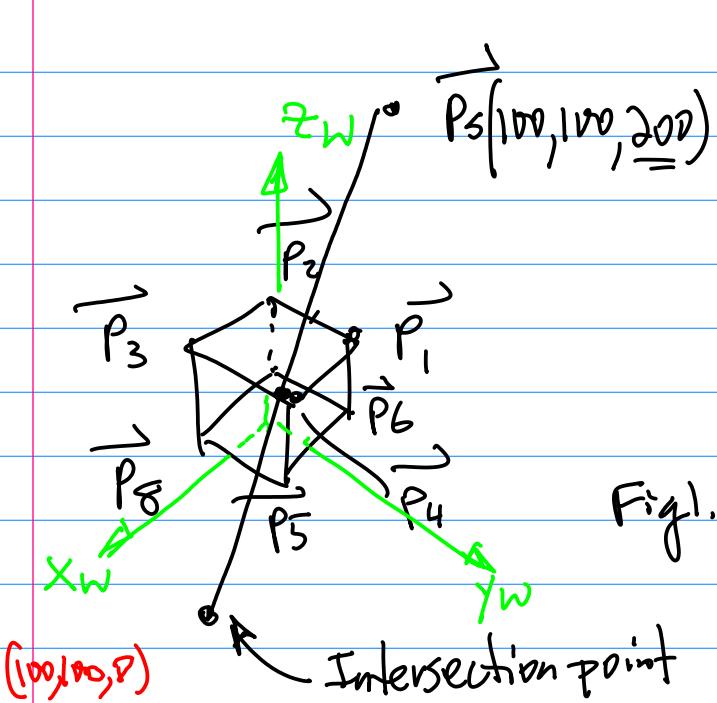


Fig.1.

3. Ray Equation, Connecting

\vec{P}_3 to \vec{P}_4 ,

$$\vec{R} = \vec{P}_3 + \lambda (\vec{P}_4 - \vec{P}_3) \dots (1)$$

$$\vec{P}_w = \vec{P}_4$$

OR,

$$\vec{P} = \vec{P}_3 + \lambda (\vec{P}_w - \vec{P}_3) \dots (1b)$$

Find intersection point on
Xw-Yw plane.

4. Plane Equation

$$\underline{\underline{a}} \text{ Normal Vector } \vec{n} (n_x, n_y, n_z)$$

Perpendicular to the given
plane, Xw-Yw plane

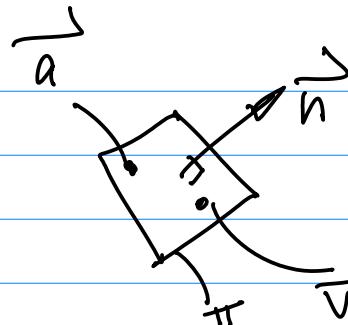


Fig.2

4b. plane π .

An Known, Arbitrary pt
On π denoted
 $\vec{a}(a_x, a_y, a_z)$

An arbitrary point

$$\vec{v}(v_x, v_y, v_z) \text{ on } \pi$$

$$\vec{n} \cdot (\vec{a} - \vec{v}) = 0 \dots (2)$$

OR

$$\vec{n} \cdot (\vec{v} - \vec{a}) = 0 \dots (2-a)$$

↑
Normal Vectn
↑
Line Segment

5. Intersection pt.

$$\vec{R} = \vec{P}_3 + \lambda (\vec{P}_w - \vec{P}_3) \dots (3a)$$

$$\vec{n} \cdot (\vec{v} - \vec{a}) = 0 \dots (3b)$$

From (3b),

$$\vec{n} \cdot (\vec{v} - \vec{a}) = 0$$

$$\vec{v} = \vec{r}, \vec{v} = \vec{p}_S + \lambda(\vec{p}_i - \vec{p}_S)$$

Sub. $\vec{v} = \vec{r}$ above into (3b)

$$\vec{n} \cdot (\vec{v} - \vec{a}) \Big|_{\vec{v} = \vec{r}} = 0$$

$$\vec{n} \cdot (\vec{r} - \vec{a}) \Big|_{\vec{r} = \vec{p}_S + \lambda(\vec{p}_i - \vec{p}_S)} = 0$$

$$\vec{n} \cdot (\vec{p}_S + \lambda(\vec{p}_i - \vec{p}_S) - \vec{a}) = 0$$

$$\vec{n} \cdot \vec{p}_S + \lambda \vec{n} \cdot (\vec{p}_i - \vec{p}_S) - \vec{n} \cdot \vec{a} = 0$$

$$\lambda \vec{n} \cdot (\vec{p}_i - \vec{p}_S) = \vec{n} \cdot \vec{a} - \vec{n} \cdot \vec{p}_S$$

$$\lambda = \frac{\vec{n} \cdot (\vec{a} - \vec{p}_S)}{\vec{n} \cdot (\vec{p}_i - \vec{p}_S)} \dots (4)$$

from Eqn (3a), Ray Egn.

With λ we can find the intersection

Point.

In C/C++ coding.

$$\lambda = \frac{\vec{n} \cdot (\vec{a} - \vec{p}_S)}{\vec{n} \cdot (\vec{p}_i - \vec{p}_S)} = \frac{(n_x, n_y, n_z) \cdot (a_x - x_s, a_y - y_s, a_z - z_s)}{(n_x, n_y, n_z) \cdot (p_{i_x} - p_{s_x}, p_{i_y} - p_{s_y}, p_{i_z} - p_{s_z})}$$

$$= \frac{n_x(a_x - x_s) + n_y(a_y - y_s) + n_z(a_z - z_s)}{n_x(x_i - x_s) + n_y(y_i - y_s) + n_z(z_i - z_s)} \dots (4a)$$

Example: Compute the shade by finding intersection pt formed by \vec{p}_S and \vec{p}_4 .

Sol: from Eqn (3a), we have

$$\vec{r} = \vec{p}_S + \lambda(\vec{p}_4 - \vec{p}_S)$$

$$= (x_s, y_s, z_s) + \lambda(x_4 - x_s, y_4 - y_s, z_4 - z_s)$$

from Eqn (4), where

$$\vec{n}(n_x, n_y, n_z) = (0, 0, 1)$$

$$\vec{a}(a_x, a_y, a_z) = (0, 0, 0)$$

Hence,

$$\lambda = \frac{0 \cdot (a_x - x_s) + 0 \cdot (a_y - y_s) + 1 \cdot (a_z - z_s)}{0 \cdot (x_4 - x_s) + 0 \cdot (y_4 - y_s) + 1 \cdot (z_4 - z_s)}$$

$$= \frac{a_z - z_s}{z_4 - z_s} = \frac{0 - 200}{110 - 200} = \frac{200}{90}$$

$$= 20/9$$

Therefore, Sub λ back to the Ray Egn.

$$\begin{aligned}
 \vec{R} &= \vec{P_s} + \lambda (\vec{P_4} - \vec{P_s}) \Big|_{\lambda = 20/q} \\
 &= (100, 100, 200) + \frac{20}{q} (x_4 - x_s, y_4 - y_s, z_4 - z_s) \\
 &= (100, 100, 200) + \frac{20}{q} (102 - 100, 102 - 100, 110 - 200) \\
 &= (100, 100, 200) + \frac{20}{q} \cdot (0, 0, 10) \\
 &= (100, 100, 200) + (0, 0, -\frac{20}{q} \times 10) \\
 &= (100, 100, 200) + (0, 0, -200) = (100, 100, 0)
 \end{aligned}$$

Note: 1. Finish Last Homework,
then Expand to a Cube.
(Display it).

2. Compute/Implement this
Algorithm, to calculate (Hm)

Each of Every 4 pts of top
Surface of the cube.

Note: Homework Submission Extended to 18th
Sunday, 11:59 pm.
 via e-mail ; Subject:
 FirstName+SID(4 Digits)+CmpE240+HW2
 April 14 (Th).

See the figure Next page

```

float Xe = 200.0f;
float Ye = 200.0f;
float Ze = 200.0f;
float Rho = sqrt(pow(Xe,2) + pow(Ye,2) + pow(Ze,2));
float D_focal = 20.0f;
  
```

```
//define the x-y-z world coordinate
world.X[0] = 0.0; world.Y[0] = 0.0; world.Z[0] = 0.0; // origin
world.X[1] = 50.0; world.Y[1] = 0.0; world.Z[1] = 0.0; // x-axis
world.X[2] = 0.0; world.Y[2] = 50.0; world.Z[2] = 0.0; // y-axis
world.X[3] = 0.0; world.Y[3] = 0.0; world.Z[3] = 50.0; // z-axis
```

for X_w - Y_w - Z_w World-Coordinate System

```
typedef struct {
    float X[UpperBD];
    float Y[UpperBD];
    float Z[UpperBD];
} pworld;
```

for X_v - Y_v - Z_v Viewer (Virtual Camera)

```
typedef struct {
    float X[UpperBD];
    float Y[UpperBD];
    float Z[UpperBD];
} pviewer;
```

for Perspective Projection

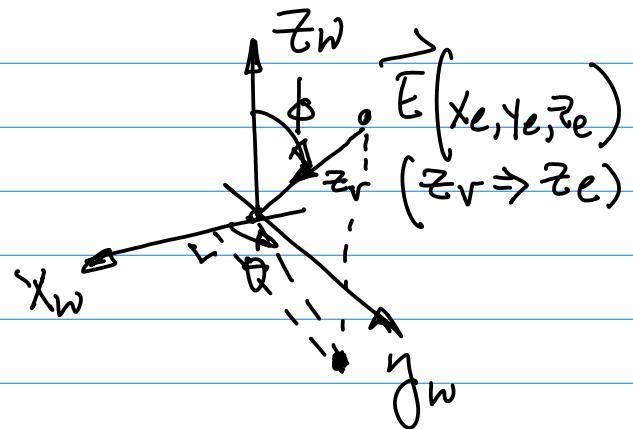
```
typedef struct{
    float X[UpperBD];
    float Y[UpperBD];
} pperspective;
```

Declaration of Each Coordinate System

```
pworld world;
pviewer viewer;
pperspective perspective;
```

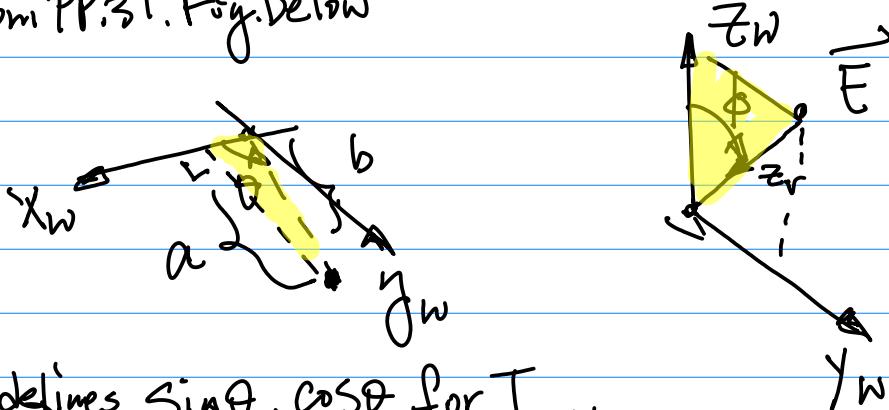
Initialization By Defining 4 vectors

(pts) $\vec{P_1}, \vec{P_2}, \vec{P_3}, \vec{P_4}$ for X_w, Y_w, Z_w
axis



```
//define the x-y-z world coordinate
world.X[0] = 0.0; world.Y[0] = 0.0; world.Z[0] = 0.0; // origin
world.X[1] = 50.0; world.Y[1] = 0.0; world.Z[1] = 0.0; // x-axis
world.X[2] = 0.0; world.Y[2] = 50.0; world.Z[2] = 0.0; // y-axis
world.X[3] = 0.0; world.Y[3] = 0.0; world.Z[3] = 50.0; // z-axis
```

From PP.31. Fig. Below



We defines $\sin\theta, \cos\theta$ for T_{4x4}

World-To-Viewer Transform.

```
float sPhi = Ye / sqrt(pow(Xe,2) + pow(Ye,2));
float cPhi = Xe / sqrt(pow(Xe,2) + pow(Ye,2));
float sTheta = sqrt(pow(Xe,2) + pow(Ye,2)) / Rho;
float cTheta = Ze / Rho;
```

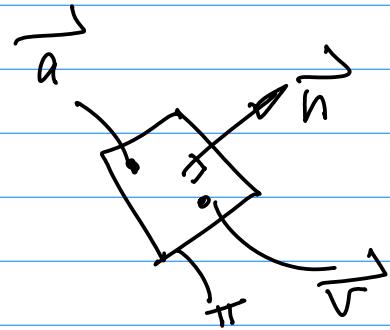
From PP.32

Define plane Equation By

\hat{n} Normal Vector $\vec{n} = (n_x, n_y, n_z) = (0, 0, 1)$

\vec{a} Arbitrary pt $\vec{a} = (0, 0, D)$

Then a point light Source $\vec{Ps} = (x_s, y_s, z_s)$



```
world.X[45] = -200.0; world.Y[45] = 50.0; world.Z[45] = 200.0; // Ps (point source)
world.X[46] = 0; world.Y[46] = 0; world.Z[46] = 0; // arbitrary vector A on x-y plane
world.X[47] = 0; world.Y[47] = 0; world.Z[47] = 1; // normal vector for x-y
```

Now, the Implement for Computing World-to-Viewer By T_{4x4}

CMPED240

37

```
for(int i = 0; i <= UpperBD; i++)
{
    viewer.X[i] = -sPhi * world.X[i] + cPhi * world.Y[i];
    viewer.Y[i] = -cPhi * cPhi * world.X[i]
    - cPhi * sPhi * world.Y[i]
    + sPhi * world.Z[i];
    viewer.Z[i] = -sPhi * cPhi * world.X[i]
    - sPhi * cPhi * world.Y[i]
    -cPhi * world.Z[i] + Rho;
}
```

from TP.29, T_{4x4}

$$\mathbf{T} = \begin{bmatrix} -\sin \theta & \cos \theta & 0 & 0 \\ -\cos \phi \cos \theta & -\cos \phi \sin \theta & \sin \phi & 0 \\ -\sin \phi \cos \theta & -\sin \phi \cos \theta & -\cos \phi & \rho \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\begin{pmatrix} X_v \\ Y_v \\ Z_v \\ 1 \end{pmatrix} = T_{4 \times 4} \begin{pmatrix} X_w \\ Y_w \\ Z_w \\ 1 \end{pmatrix}$$

World-to-
Viewer
Transform

"After" "Before"

Now, Perspective Projection from TP.29

```
perspective.X[i] = D_focal * viewer.X[i] / viewer.Z[i] ;
perspective.Y[i] = D_focal * viewer.Y[i] / viewer.Z[i] ;
```

$$x_p = x_e \left(\frac{D}{z_e} \right)$$

$$y_p = y_e \left(\frac{D}{z_e} \right)$$

For Intersection Computation
 ≡ find x in $X_w - Y_w - Z_w$,
 ≡ find intersection pt(S),
 in $X_w - Y_w - Z_w$

Then, Computer Virtual Display (2D)

to Physical Display ! Then plot the points !

Then Transform
 with pipeline
 then Done !

Ch 10

Diffuse Reflection.

Background / Basic Concepts

1. Objective: To generate realistic looking 3D Graphics

Lighting Models

After Trans.
Pipeline

$$\vec{I}(x,y) = (r(x,y), g(x,y), b(x,y))$$

Graphics (Vector)
Graphics

Primitive ... (1)
Colors,

r, g, b : 8 bit Resolution.

$r, g, b \in [0, 255]$, for 15 bits, or 16 bit

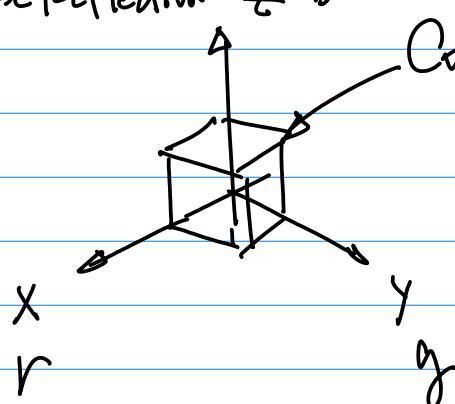
r, g, b. is Common.

2. Color Space

April 19 (Monday)

Diffuse Reflection $\approx b$

Fig 1.



Color Cube

$$\vec{I}(x,y,z) = \vec{I}_1(x,y,z) + \vec{I}_2(x,y,z) + \vec{I}_3(x,y,z) \quad \dots (2)$$

3D Space in $x_w - y_w - z_w$

$\vec{I}_1(x,y,z)$: Diffuse Reflection

Diffuse Reflection (Ref. on \vec{P}_S)

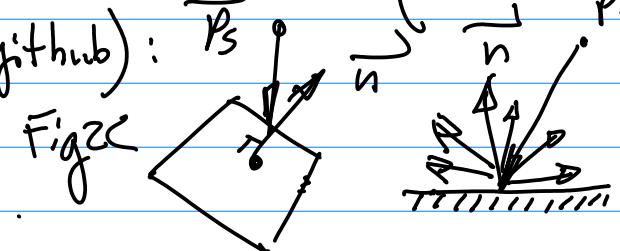


Fig 2C

Note: in r-g-b Color Space,

(255, 0, 0) : Brightest Red

(0, 255, 0) : Brightest Green, etc.

line connecting $(0,0,0)$ to $(1,1,1)$: gray, $(0,0,0)$ Black, $(1,1,1)$ Bright White

3. Color Contribution to Each pixel on a Surface of a given Object in 3D Space.

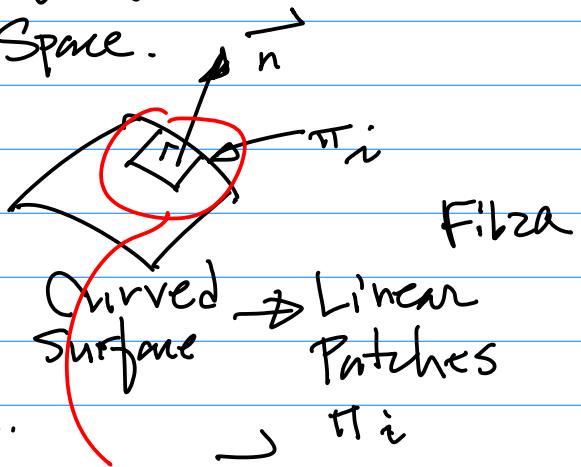
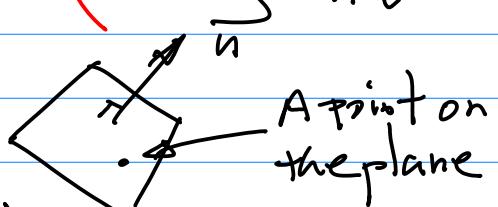


Fig 2b



A point on the plane

$$\vec{I}(x,y,z) = \vec{I}_1(x,y,z) + \vec{I}_2(x,y,z) + \vec{I}_3(x,y,z) \quad \dots (2)$$

Comptext

39

Diffuse Reflection: \curvearrowright that reflects incoming light uniformly in all different directions.

Example: Diffuse Reflection model.

Step 1. $\vec{I}(x, y, z)$ Color on a pt. of a surface in

4. Reflectivity for all 3 different light models (I_r, I_g, I_b)

$\vec{I}(x, y, z) \leftarrow$ 3D Space.
 $(\vec{I}_r(x, y, z), \vec{I}_g(x, y, z),$
 $\vec{I}_b(x, y, z))$

Define $R = (r_r, r_g, r_b) \dots [3]$

Simplify the discussion by focusing on one primitive color

$$0 \leq r_r, r_g, r_b \leq 1$$

$r_r = r_g = r_b = 0$ Black

$r_r = r_g = r_b = 1$ White

$r_r = 0, r_g = 0.75, r_b = 0$: Green

$$I_r(x, y, z)$$

Energy of Photons from the Source reaching the pt. is inversely proportional to the squared distance

Physical Characteristics of the given Surface

Now, Specular Reflection

I_s : Reflection Produces bright light, it is a function of E position.

I_a : Ambient light, from indirect light source, can be simulated by adding constant values to r, g, b .

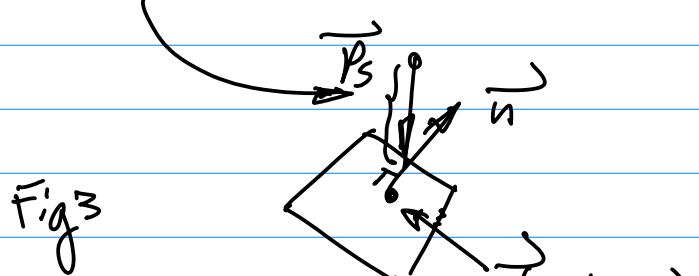
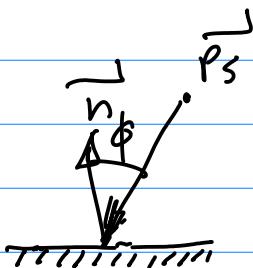


Fig 3

$$\|\vec{P}_s - \vec{P}_i\|^2 = \|\vec{r}\|^2 \dots (4)$$

Ray Equation \vec{r}

$$\vec{I}_r(x, y, z) \sim \frac{1}{\|\vec{r}\|^2} \dots (5)$$



ϕ : phi Angle
of the incoming
light

$\phi = 0$, Strongest incoming light \rightarrow "1"
 $\phi = \frac{\pi}{2}$ photons miss the pt. on the
surface \rightarrow Normalize it.
"0"

Cosphi Rule. Dot Product

$$\vec{n} \cdot (-\vec{P}_s) = \|\vec{n}\| \|\vec{-P}_s\| \cos\phi \dots (5)$$

$$\cos\phi = \frac{\vec{n} \cdot (-\vec{P}_s)}{\|\vec{n}\| \|\vec{-P}_s\|} = -\frac{\vec{n} \cdot \vec{P}_s}{\|\vec{n}\| \|\vec{P}_s\|} \quad \text{From Eqn(5), (10)}$$

... (b)

define $-\vec{P}_s$ as Ray Vector

$$\vec{I}_r(x, y, z) = K_r \frac{\vec{n} \cdot \vec{r}}{\|\vec{n}\| \|\vec{r}\|} \frac{1}{\|\vec{r}\|^2} \dots (11)$$

* $\vec{r} \triangleq \vec{P}_i - \vec{P}_s \dots (i)$

Hence

$$\cos\phi = \frac{\vec{n} \cdot \vec{r}}{\|\vec{n}\| \|\vec{r}\|} \dots (8)$$

where
 $\|\vec{r}\|^2 = \|\vec{P}_i - \vec{P}_s\|^2$

$$\vec{I}_r(x, y, z) \sim \cos\phi \left(= \frac{\vec{n} \cdot \vec{r}}{\|\vec{n}\| \|\vec{r}\|} \right) \dots (9)$$

$$= (x_i - x_s)^2 + (y_i - y_s)^2 + (z_i - z_s)^2$$

$\vec{I}_r(x, y, z) \sim K_r$ Reflectivity for r Preparation for

April 21 (Wed)

Lab (Project) 3D GE, (Diffuse Reflection) Due 2 weeks, May 9th Sunday 11:59 pm.

- a. 2018F-115 - Rubrics
- b. 2018F-116, C++ Sample code
- c. 2018F-117 DDA
- d. 2018F-118 Interpolation

Example: Design/Implementation for Project On Diffuse Reflection.

(See github to find Ref. 2018S ~ Diff)

Step 1. Define Data Points (Vertices,

$\vec{P}_i(x_i, y_i, z_i)$ in the World

Coordinate System)

$\left\{ \vec{P}_i(x_i, y_i, z_i) \mid i=1, 2, \dots, 8 \right\}$ for a Cube,

Only interested in Top Surface

$\left\{ \vec{P}_i(x_i, y_i, z_i) \mid i=1, 2, \dots, 4 \right\}$

Cube with Side of 100, And Elevated by 10.

Only Consider Diffuse Reflection

On the top Surface formed by

$\{ \vec{P}_1, \vec{P}_2, \vec{P}_3, \vec{P}_4 \}$

$$\begin{aligned} \vec{P}_1(0, 100, 110), \vec{P}_2(0, 0, 110) \\ \vec{P}_3(100, 0, 110), \vec{P}_4(100, 100, 110) \end{aligned}$$

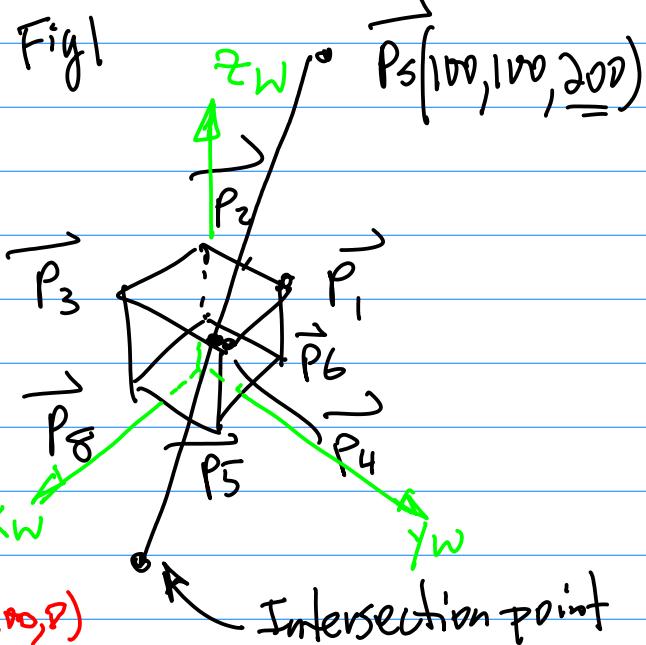
Step 2. Define Point Light

Sample $\vec{P}_s(200, 200, 200)$, white and Reflectivity

$$\vec{K}(K_r, K_g, K_b) = (0.8, 0, 0)$$

Question:

Do we have to perform Transformation Pipeline Computations in order to Compute Diffuse Reflection? No



Chap 24

42

$$I_r(x_4, y_4, z_4) = K_r \frac{\vec{n} \cdot \vec{r}}{\|\vec{n}\| \|\vec{r}\|} = \frac{\vec{n} \cdot \vec{r}}{\|\vec{n}\| \|\vec{r}\|} = \frac{z_4 - z_s}{\sqrt{(x_4 - x_s)^2 + (y_4 - y_s)^2 + (z_4 - z_s)^2}}$$

Since $\vec{P}_s(200, 200, 200)$,

$$\vec{r} \stackrel{\Delta}{=} \vec{P}_i - \vec{P}_s \Big|_{n=1} = \vec{P}_4 - \vec{P}_s$$

$$= (x_4 - x_s, y_4 - y_s, z_4 - z_s) \dots (1)$$

$$\|\vec{r}\|^2 = \left(\sqrt{(x_4 - x_s)^2 + (y_4 - y_s)^2 + (z_4 - z_s)^2} \right)^2$$

$$= (x_4 - x_s)^2 + (y_4 - y_s)^2 + (z_4 - z_s)^2$$

$$= 100^2 + 100^2 + 90^2$$

And $\cos \phi$

$$\vec{n}(n_x, n_y, n_z) = (0, 0, 1)$$

$$\vec{n} \cdot \vec{r} = (0, 0, 1) \cdot (r_x, r_y, r_z)$$

$$= (0, 0, 1) \cdot (x_4 - x_s, y_4 - y_s, z_4 - z_s)$$

$$= 0 \cdot (x_4 - x_s) + 0 \cdot (y_4 - y_s) + 1 \cdot (z_4 - z_s)$$

$$= z_4 - z_s$$

$$\|\vec{n}\| \|\vec{r}\| = \sqrt{n_x^2 + n_y^2 + n_z^2} \cdot \sqrt{r_x^2 + r_y^2 + r_z^2}$$

$$= \sqrt{0^2 + 0^2 + 1^2} \cdot \sqrt{(x_4 - x_s)^2 + (y_4 - y_s)^2 + (z_4 - z_s)^2}$$

$$= 1 \cdot \sqrt{(x_4 - x_s)^2 + (y_4 - y_s)^2 + (z_4 - z_s)^2}$$

$$\sqrt{(x_4 - x_s)^2 + (y_4 - y_s)^2 + (z_4 - z_s)^2}$$

$$= \frac{110 - 200}{\sqrt{100^2 + 100^2 + 90^2}}$$

No! Positive Value
Only

Change Eqn (2) from
 $\vec{P}_i - \vec{P}_s$ to $\vec{P}_s - \vec{P}_i$

Therefore, we have

$$\frac{200 - 110}{\sqrt{100^2 + 100^2 + 90^2}}$$

So, we have Diffuse
Reflection @ Pt. 4 \vec{P}_4

$$I_{\text{diff}} = K_d \frac{200 - 110}{\sqrt{100^2 + 100^2 + 90^2}}$$

0.8

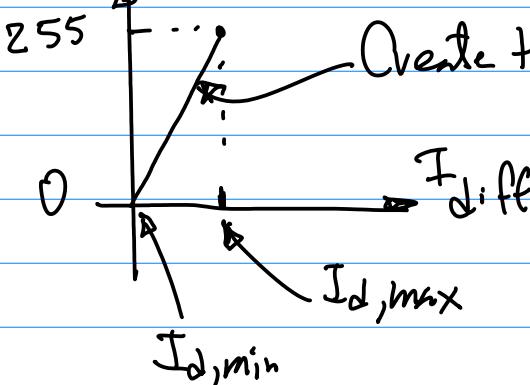
$$\frac{1}{100^2 + 100^2 + 90^2}$$

$$I_{\text{diff}} = 0.8 \frac{200 - 110}{\sqrt{100^2 + 100^2 + 90^2} (100^2 + 100^2 + 90^2)}$$

Note:

1° I_{diff} Computed is Very Small!

You Need Scaling factor to Scale it up for the dynamic Range of your Hardware (LCD) Display Device Scaled for Display



Add Offset 20 to I_{diff} . So it is more visible.

Question: How to Expand the Computation to the Rest of the points on the top Surface?

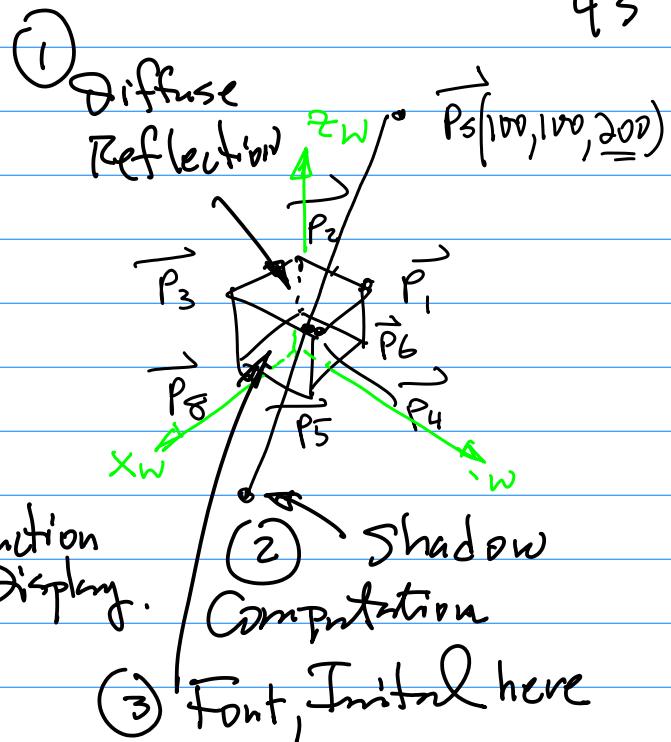
April 26 (mon). Final Exam.

May 19 (wed) [215-1430]

Project Extended to May 12 (wed)

11:59 pm. Written Requirements

Will be posted on CANVAS and on github.



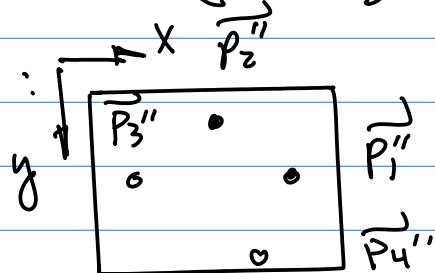
Example:

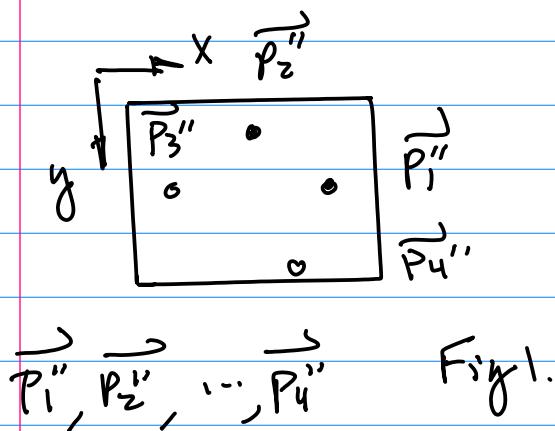
Given the 4 points $(\vec{P}_1, \dots, \vec{P}_4)$
Diffuse Reflection Already
Computed, ($x_w - y_w - z_w$)

Compute the Boundary Diffuse
Reflection (Part I)

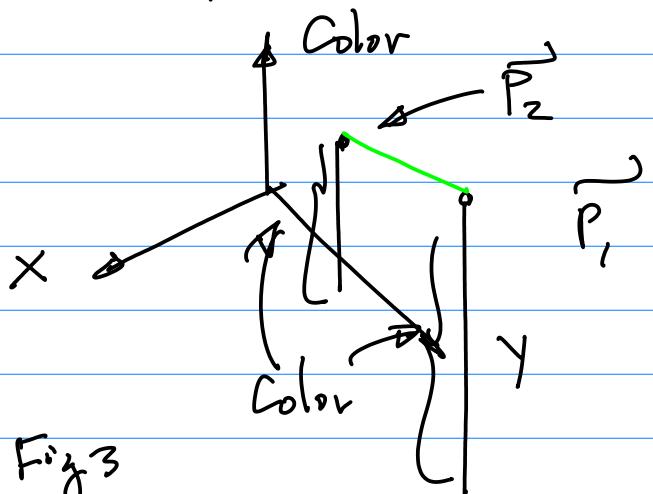
Compute Interior Points of the
Surface defined by the
Boundaries. (Part II)

PART I :

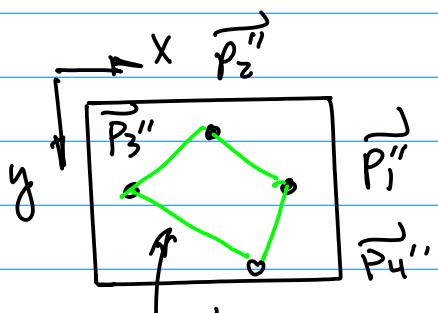




Color Space for Illustration



- 1' Their Location on LCD Display are Computed By Transformation Pipeline
- 2' Their Color & Intensity are Computed in (x_w, y_w, z_w) By Diffuse Reflection Model;



Boundary Color To Be Computed By a Simpler Technique → Interpolation.

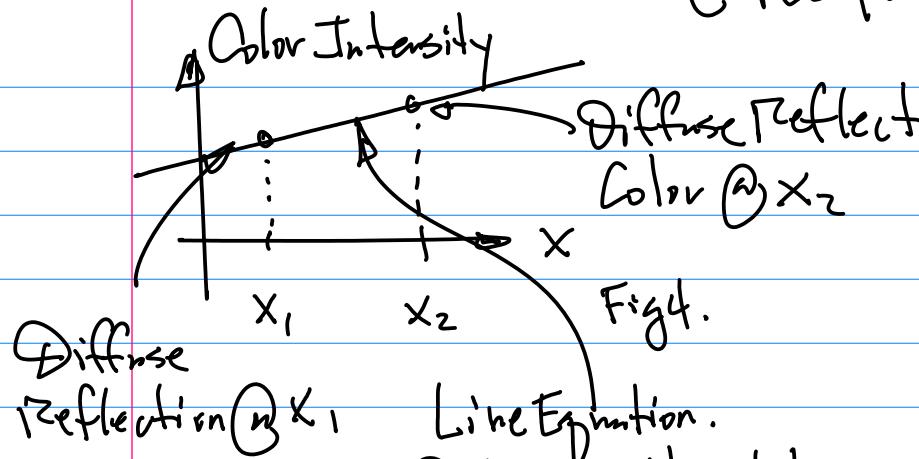
How To Compute Diffuse Reflection from 2 Known pts (Starting & Ending Pt of A Line) ?

Interpolation :
Assume moving from P_1 to P_2
Along "Kine" Line, the Intensity,
e.g. color, is changing as
a function of x and y .

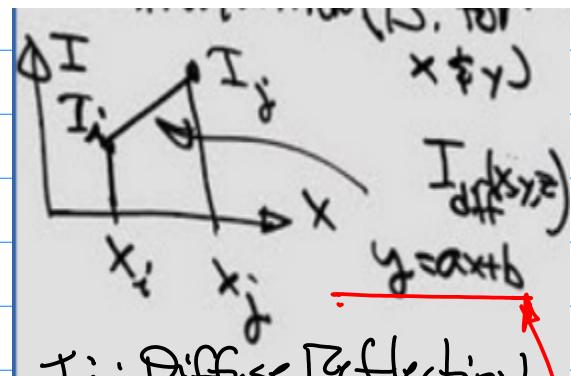
- (1) Contribution from x if color changing
- (2) Contribution of color changing from y

(3) Then the final color is the average of Contribution x and Contribution from y .

Compeacto



Notation from the 45 (github) TRT.

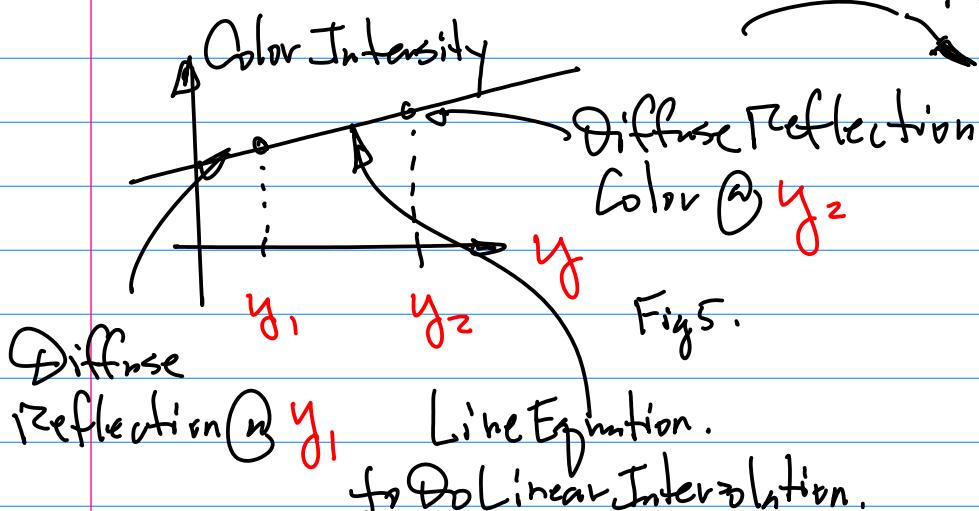


I_i : Diffuse Reflection
@ x_i

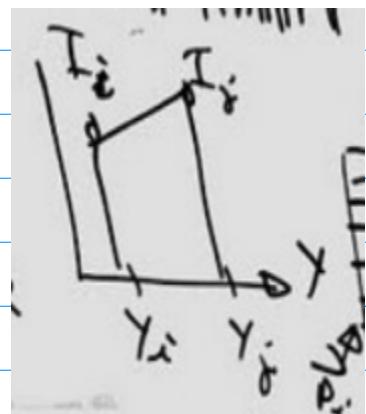
I_j : --- @ x_j

$$\frac{x_2 - x_1}{x - x_1} = \frac{y_2 - y_1}{y - y_1} \dots (1)$$

Similarly for y



From P.P.T for y .



For Fig 5. (for y)

$y \rightarrow x$ (Indep.).

I_{diff} Color/Intensity $\rightarrow y$

$$I_{diff}(y) = \frac{I_{diff}(y_i) - I_{diff}(y_j)}{y_i - y_j} y - \frac{y_j (I_{diff}(y_i) - I_{diff}(y_j)) + I_{diff}(y_i)}{y_i - y_j} \dots (2)$$

$$\frac{x - x_2}{x_1 - x_2} = \frac{y - y_2}{y_1 - y_2}$$

Diffuse Reflection Contributed, $I_{diff}(y_i)$, $I_{diff}(y_j)$ Starting, Ending pt.
by y . Diffuse Reflection, Known. Diff. Value.

April 28.

CmPE240

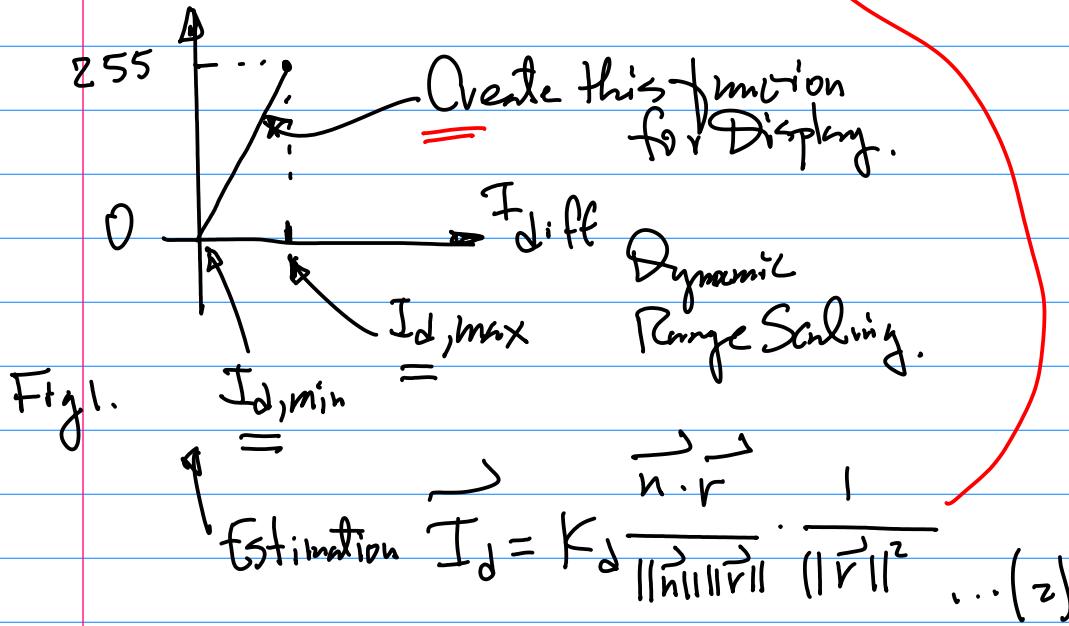
4b

Trajet SD GE. One May 1b (Sun)

Scaling up to the

Example: ① Offset ② Dynamic Range
full

```
240 //compute color intensity
241 diffuse.r[i] = Kdr * angle[i] / pow(distance[i], 2)
242 diffuse.g[i] = Kdg * angle[i] / pow(distance[i], 2)
243 diffuse.b[i] = Kdb * angle[i] / pow(distance[i], 2)
244 }
```



$$\leq K_d \cdot \vec{n} \cdot \vec{r} = K_d (n_x, n_y, n_z) (r_x, r_y, r_z)$$

$$= K_d (1, 0, 1) (r_x, r_y, r_z) = K_d \cdot r_z \quad | \quad K_d = (0.8, 0, 0)$$

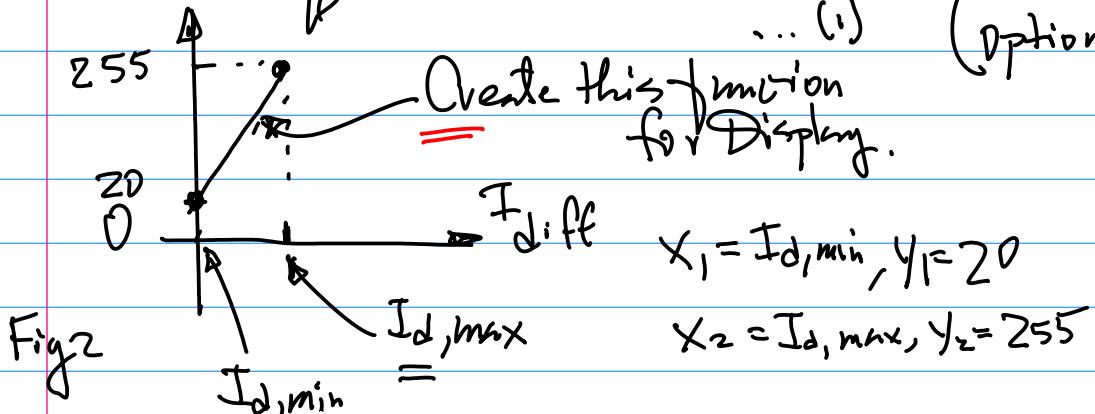
$$= (0.8r_z, 0, 0) \rightarrow I_{d,max}$$

$$I_{d,min} \approx 0$$

Add offset

$$\frac{x - x_1}{x_2 - x_1} = \frac{y - y_1}{y_2 - y_1} \dots \text{linear Mapping function}$$

... (1) (optional)



May 2nd (mon)

```

509     for (int i=4; i<=5; i++) {
510         float r, g, b;
511         r = display_scaling*diffuse.r[i]+display_shifting;

```

↑ Scaling ↑ offset

Example: Given $\vec{P}_i(x_i, y_i) = \vec{P}_i''(100, 50)$
on Fig 3. $I_d(100, 50) = 100$;
 $\vec{P}_j(x_j, y_j) = \vec{P}_j''(50, 25)$, $I_d(50, 25) = 80$?

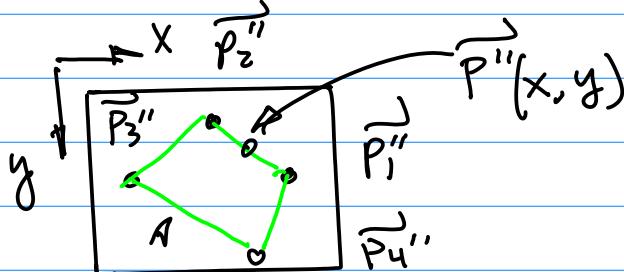


Fig 3.

Find Diffuse Reflection at the Boundary Point $\vec{P}''(x, y)$
 $\vec{P}_3''(75, 50)$, $\vec{P}_1''(75, 30)$, $\vec{P}_4''(50, 30)$, $\vec{P}_2''(50, 50)$
 $I_d(75, 30) = ?$

Note: I_d is always positive
Then, Similarly, Calculate
 I_d from the Contribution
of x ;

Once, Both Contribution of
 x and y are taken care of,
then Calculate the Average
which gives the diffuse

Reflection at this point.

Note: Check Sample code on
the github, Implement diff.
Reflection Computation On LFC.
plot 4 "Small Squares".
5x5

Sol The General Approach

$$\vec{I}_d(75, 30) = \frac{1}{2} \left(\vec{I}_d(x) + \vec{I}_d(y) \right) \quad x=75, \quad y=30,$$

$$= \frac{1}{2} \left(\vec{I}_d(75) + \vec{I}_d(30) \right) \dots (2)$$

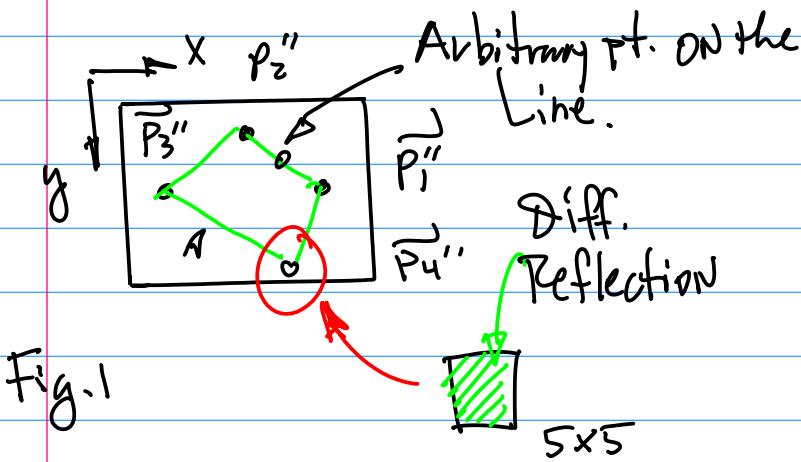
Suppose Solve for

$$\vec{I}_d(y) =$$

$$\vec{I}_{diff}(y) = \vec{I}_{diff}(y_i) - \vec{I}_{diff}(y_j) \quad y - \frac{y_i - y_j}{y_i - y_j} (\vec{I}_{diff}(y_i) - \vec{I}_{diff}(y_j)) + \vec{I}_{diff}(y_j) \dots (2)$$

$$y_i = y_1 = 50, \quad y_j = y_2 = 25$$

$$\vec{I}_{diff}(y) = \frac{\vec{I}_{diff}(y_i) - \vec{I}_{diff}(y_j)}{y_i - y_j} y - \frac{y_i - y_j}{y_i - y_j} (\vec{I}_{diff}(y_i) - \vec{I}_{diff}(y_j)) + \vec{I}_{diff}(y_j) \dots (2)$$



$$\begin{array}{r}
 x_3 x_{30} \dots x_1 x_0 \\
 \times a_{31} a_{30} \dots a_1 a_0 \\
 \hline
 a_0 x_3 a_0 x_{30} \dots a_0 x_0 \\
 a_1 x_3 a_1 x_{30} \dots a_1 x_0 \\
 \vdots \\
 \hline
 \dots a_{31} x_3 a_{30} x_{30} \dots a_0 x_0
 \end{array}$$

DDA Algorithm:
(Digital Differential Algorithm)

To Deal with Finite Resolution of
Display Devices.

Motivation: Reduce AND/OR
Removal of multiplication

$$\left\{
 \begin{array}{l}
 \text{1 "GAPS" Problem } y = ax + b \\
 \text{2 multiplication Needed}
 \end{array}
 \right. \quad \dots (1)$$

ax

multiplication Unit $\rightarrow n$ bit (32 bit)
multiplication

H.A. (Half Adders) \leftarrow Basic Building Blocks of FA
Carry Look-Ahead Circit.

$$\begin{array}{l}
 ax, \quad a = a_{31} a_{30} \dots a_1 a_0 \\
 x = x_3 x_{30} \dots x_1 x_0
 \end{array}$$

Example:
Generate DDA Algorithm

$$\left\{
 \begin{array}{l}
 x_{k+1} = x_k + 1 \quad \dots (1) \\
 y_k = ax_k + b \quad \dots (2)
 \end{array}
 \right.$$

For $k+1$:

$$\begin{aligned}
 y_{k+1} &= ax_{k+1} + b \\
 &= a(x_k + 1) + b \\
 &= ax_k + a + b \quad (\text{for Each } x \text{ increment})
 \end{aligned}$$

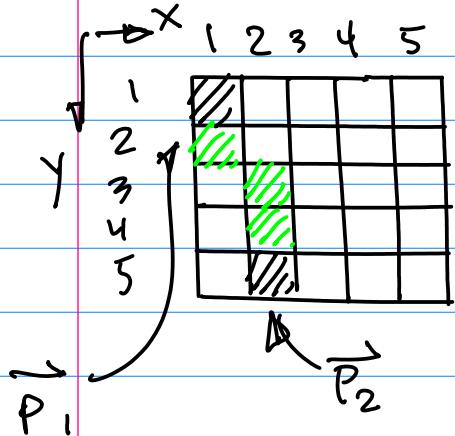
Note: y Increment by a (x increment)
No multiplication Needed;

$$\left\{
 \begin{array}{l}
 x_{k+1} = x_k + 1 \quad \dots (za) \\
 y_{k+1} = y_k + a \quad \dots (zb)
 \end{array}
 \right.$$

49.

Suppose given 2 vertices

$$\vec{P}_1(1,1), \vec{P}_2(2,5)$$



use Eqn (2a), (2b) to plot
a straight line.

$$\text{Step 1. Compute Slope } a \triangleq \frac{y_E - y_S}{x_E - x_S}$$

... (3)

from the given
Condition:

$$a = \frac{5-1}{2-1} = 4.$$

Now, from Eqn (2a), (2b)

$$\text{for } k=1, x_1 = 1, y_1 = 1$$

$$\text{for } k=2, x_{k+1} = x_k + 1$$

$$x_2 = x_1 + 1 = 2$$

$$y_{k+1} = y_1 + a = 1 + 4 = 5$$

The "gap" is due to $a > 1$.

DDA:

Part I: If $|a| < 1$, then

$$y_{k+1} = y_k + a$$

Fig 2.

Part II: if $|a| > 1$, then

swap x and y, y as
independent variable,
x function.

$$y = ax + b$$

$$\frac{1}{a}y = x + \frac{b}{a}$$

$$\therefore x = \frac{1}{a}y - \frac{b}{a}$$

Then Apply the Incremental
Algorithm.

For $a=4$, Let's make $\frac{1}{a} = \frac{1}{4}$

$$y_1 = 1, x_1 = 1 \text{ (given)}$$

$$y_2 = y_1 + 1 = 1 + 1 = 2$$

$$x_2 = x_1 + \left(\frac{1}{a}\right)$$

$$= 1 + \frac{1}{4} \approx 1.25 = 1.$$

$$y_3 = y_2 + 1 = 2 + 1 = 3$$

$$x_3 = x_2 + \left(\frac{1}{a}\right) = x_1 + 2\left(\frac{1}{a}\right)$$

$$= 1 + \frac{2}{4} = 1.5 \approx 2$$

CmpE240

SD

$$\text{for } y_4 = y_3 + 1 = 3 + 1 = 4$$

$$x_4 = x_3 + \left(\frac{1}{a}\right) = x_3 + \frac{3}{4}$$

$$= 1 + \frac{3}{4} = 1.75 \approx 2$$

Please Check my Sample
Code "DDA-C" on github.

Homework: (Optional)

Use Bilinear Interpolation
plus DDA Algorithm to

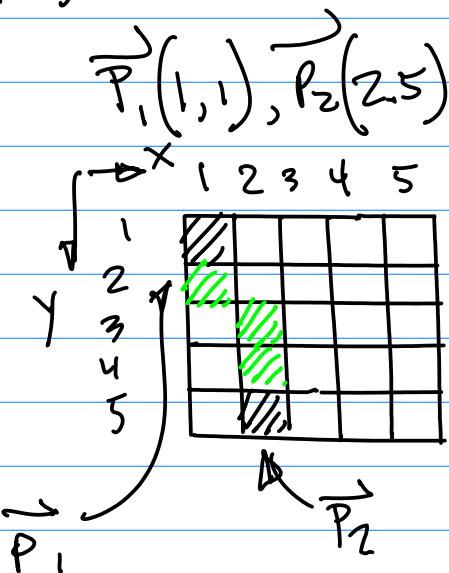
Compute/plot Diff. Reflection
of At least one boundary line.

May 4th (Wed)

Example: Given P_1 and P_2 , and
their Diffuse Reflection Value

$$I_{d1} = 100, I_{d2} = 90$$

(T_{cd})



Find Diffuse Reflection of the
Boundary points ("green").

These points have to be

Computed By using DDA algorithm
(See Example on PP.48-49)

First, find $I_d(1,2) = ?$

Sol:

$$I_d(1,2) = \frac{1}{2} (I_{dx}(1,2) + I_{dy}(1,2))$$

Computation of $I_{dy}(1,2)$ is
given in Eqn(2) PP.47.

$$\frac{I_{di} - I_{dj}}{y_i - y_j} = \frac{I_{d1} - I_{d2}}{y_1 - y_2} = \frac{100 - 90}{1 - 2}$$

$$= -10$$

$$\text{And } y = 2$$

$$\frac{-y_j}{y_i - y_j} (I_{di} - I_{dj}) = -\frac{y_2}{y_1 - y_2} (100 - 90)$$

$$= -\frac{2}{1-2} \cdot 10 = -20$$

$$I_d(1,2) = -10 \cdot 2 - 20 + 90 = 50$$

Similarly, $I_{dx}(1,2)$ can be

$I_{dx}(1,2)$ Can be Computed

Similarly,

$$\therefore I_d(1,2) = \frac{1}{2} (I_{dy}(1,2) + I_{dx}(1,2)) \\ = \frac{1}{2} (SD + I_{dx}(1,2))$$

github/finalisti/Cmpe240

"Diffuse" Sample is provided.

Note: Show + Tell the Prototype Board is Mandatory! No Timely Showing/Completion will have Negative Impact to Entire Course Performance As Stated throughout the Semester.

Consider Diffuse Reflection Inside Boundary Lines.

Example

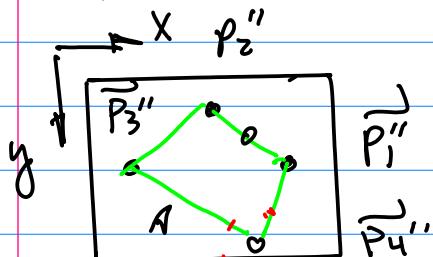


Fig 1.

Conditions:

a Scan the Display Conceptually from the top left corner left to Right, top to Bottom.

b Scanning Line "L" has 2 intersection points (Search Algorithm for Advancing index (i, j)) to match up a point from the Set of pts from DDA)

c Diffuse Reflection on the Boundary has been Computed.

Compute "Green" Line (pts) inside the Boundary Line

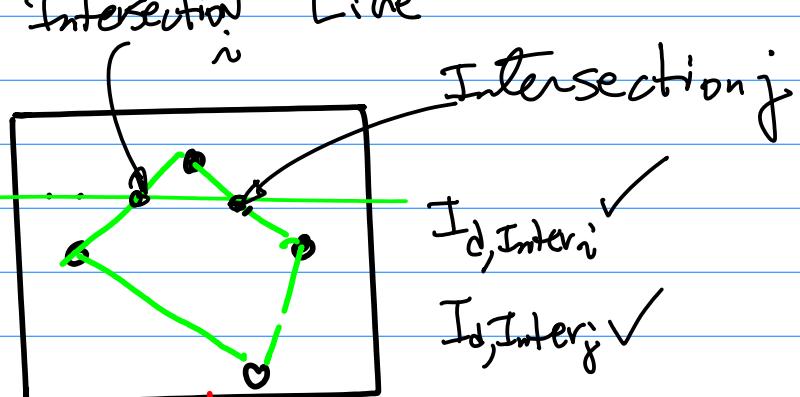


Fig 2

Decorate Any Surfaces (planes)

Algorithm:

Step 1. Define 2D Pattern

$$\{\vec{P}_i(x_i, y_i) \mid i=1, 2, \dots, N\}$$

Step 2. Re-define 2D Pattern(s) in $X_w - Y_w - Z_w$ Space;

Step 3. 3D Transform to Decorate on Plane.

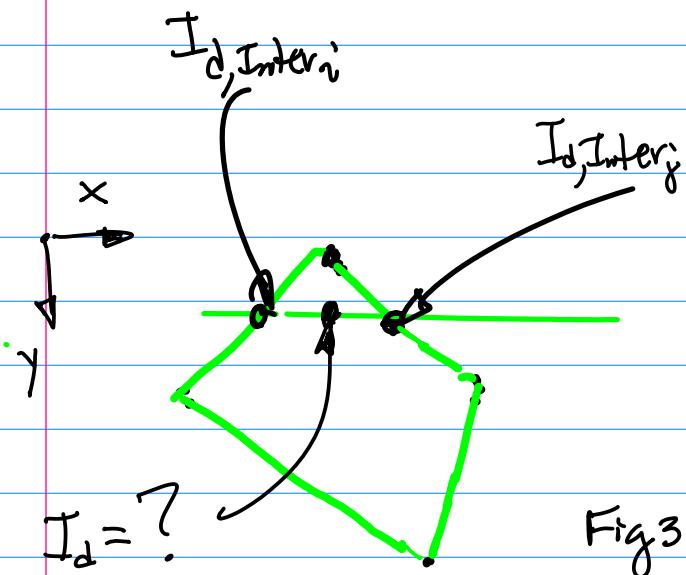


Fig 3

Interpolation Technique to find
 $I_d = ?$

Interpolation w.r.t. X-variable.

Consider "Linear" Decoration

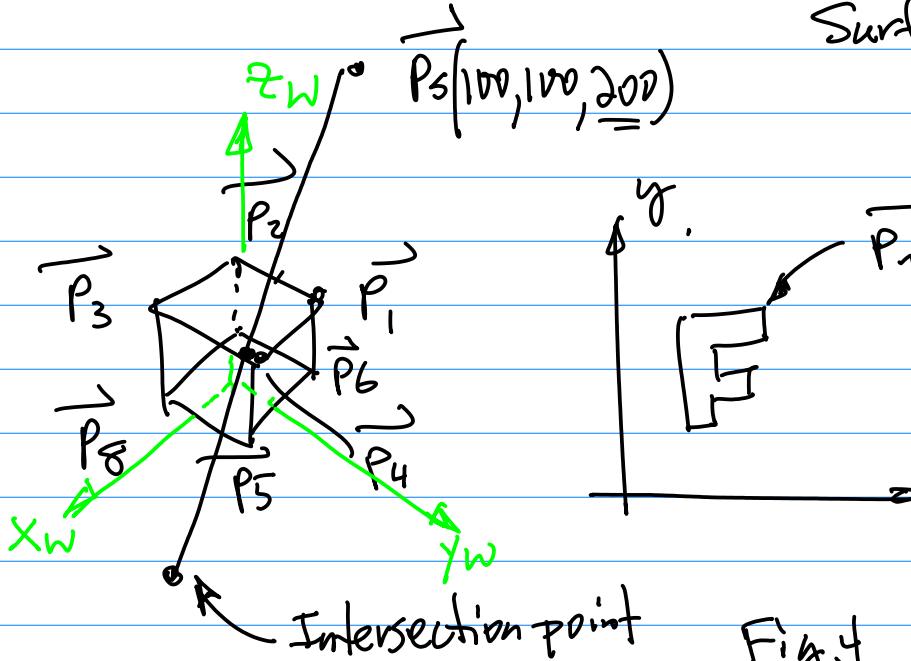


Fig.4

