V(Vx, Vz), a (ax, ay, az)

to Replace Pi, Pin

Stepl. Generate A Ray Cast Squation

2021F-101b-notes-cmpe240-2021-12-1.pdf

References:

Assume a (nx, ny, nz) is a Known Vector; And V(VxV,1/2) is unknown, But

an arbitrary Point on the plane T.

hence, Egnle) becomes

N. (V-A)=0 ... (2*)

Now, find the intersection point defined By the Ray Egn (1). In order to that, we will need to find &

Since the intersection point Pi is the Common Point By the Ray and theplane T. we have

n(nx,ny,nz), Normal Vector

has to be known,

a (ax, ay, az) is known on T.

Starting from the plane Egn (36).

n. (V-a) =0

where V= R,e,g.

 $n \cdot (v - \vec{n})$ $v = \vec{R} = 0$ (4)

 $|R - \overline{R}| = 0$ $|R - \overline{R}| + |R - \overline{R}|$ $|R - \overline{R}| + |R - \overline{R}|$ $|R - \overline{R}| + |R - \overline{R}|$ $|R - \overline{R}| + |R - \overline{R}|$

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\n. (P_3-P_1) = n. n- n. P_1

n. 2- n. Pi

 $=\frac{\overrightarrow{n\cdot(\overrightarrow{a-P_i})}}{\overrightarrow{n\cdot(\overrightarrow{P_s-P_i})}}...(5)$

Note Lis Not the intersection Pt. it allows us to use Ray Egn (1) to find the intersection.

P_S
P_S
P_S
V

use Eqn(5) to find more than one intersection

 $\lambda = \frac{\overrightarrow{n} \cdot (\overrightarrow{a} - \overrightarrow{P_i})}{\overrightarrow{n} \cdot (\overrightarrow{P_s} - \overrightarrow{P_i})} \dots (5)$ where n= (0,0,0), Hence, for Coding λ= <u>- n.ρ.;</u> <u>n.(p.-ρ.)</u> =- hxxx+ hy yx+nzz; nx(x5-x1)+n,(y5-y;)+n2(25-2:) From the given Condition n (0,0,1), Therefore N= - 1/2. (23-21) =- 2/3-21 $=-\frac{110}{200-110}=-\frac{110}{90}=-\frac{11}{9}$ Now, back to the Ray Equation R=Pi+2(Ps-Pi)

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CMPEZYO APILT, ZZ
    R= (100,100,110) - 11 (-20-100,
                      110-lov, 200-110)
               =(100,100,10)-\frac{11}{9}(-120,10,90)
             = \left(\frac{1100 \times 120}{9} - \left(100 - \frac{110}{9}\right) \cdot 110 - 110\right)
              = \left(\frac{1/000 \times 1200 \times 110}{9}, \frac{10}{9}, \frac{10
please finish this calculation.
       Now, Goding Part. Same Code on github.
                                                                                                                                                                 A. Define Normal vector in for Xwyw plane
                                     world.X[47] = 0; world.Y[47] = 0; world.Z[47] = 1;
                                                                                                                                                                    b. Note the typedef stind "for Defining
                                                                                                                                                                              30 Points.
                                    float X[UpperBD], Y[UpperBD], Z[UpperBD];
          41
                        } pworld;
                                                                                                                                           NOW, & Calculation. Egn (5)
                                                                                                                                                                                          hxxx+hyyx+nzzi
                                                                                                                                                                 5nv(x5-xi)+ny(y5-y;)+n2(25-2;)
                                   //-----<mark>lam</mark>bda for <mark>W</mark>tersection pt on xw-yw plans
      171
                                   float temp = (world.X[47](world.X[46]-world.X[45])
      172
                                                                      +(world, Y[47]*(world, Y[46]-world, Y[45]))
      173
      174
                                                                      +(world(Z[47]*(world.Z[46]-world.Z[45]));
                                   float lambda = temp / ((world.X[47]*(world.X[45]-world.X[7]))
      175
                                                                                                      +(world.Y[47]*(world.Y[45]-world.Y[7]))
      176
                                                                                                      +(world.Z[47]*(world.Z[45]-world.Z[7])));
      177
      178
                                   float lambda_2 = temp / ((world.X[47]*(world.X[45]-world.X[6]))
                                                                                                            +(world.Y[47]*(world.Y[45]-world.Y[6]))
      180
                                                                                                            +(world.Z[47]*(world.Z[45]-world.Z[6])));
```

(MOEato April 7,22 Note, Substitute 2 to Ray Equation to find the intersection point world.X[48] = world.X[45] + lambda*(world.X[45] - world.X[7]); // Intersection pt p7 world.Y[48] = world.Y[45] + lambda*(world.Y[45] - world.Y[7]); // Intersection pt p7 world.Z[48] = 0.0;186 world.X[49] = world.X[45] + lambda_2*(world.X[45] - world.X[6]); //intersection pt p6 world.Y[49] = world.Y[45] + lambda_2*(world.Y[45] - world.Y[6]); //intersection pt p6 R=アナン(を一下) カリーリットン(りょーリット) Assignment in-Class Shows Tell. Implement Intersection Computation on LYC 1769, Show+ Tell' Demo in Class On April 11 (Monday) To Be Able to Display 37 Graphics On 20 Display Devics. Let's Define Transformation Pipeline. 1. Define World-Coordinate System. Right Hand Xw-Yw-Zw Syntam 3D Transformation Pipeline Technique Using EGA or VGA Card Z. Viewer Coodinate Syptem XV-M-50 Left-Hand Systim Step 2. Perspective Projection Step 1. World-to-viewer transform 3. Virtual $x_p = x_e \left(\frac{D}{z_e}\right)$ $-\sin\theta$ $\cos \theta$ Cancura is $-\cos\phi\cos\theta$ $-\cos\phi\sin\theta$ $\sin \phi$

 $-\sin\phi\cos\theta$ $-\sin\phi\cos\theta$ $-\cos\phi$

(exeyez)

 $y_p = y_e$

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