Stepl. Generate A Ray Cast / Equation

2021F-101b-notes-cmpe240-2021-12-1.pdf

V(VX, Vy, VZ), a (ax, ay, az) to Replace Pi, Pin

Assume a (nx, ny, nz) is a Known Vector; And V(VxV,1/2) is unknown, But

an arbitrary Point on the plane T.

hence, Egnle) becomes

N. (V-A)=0 ... (2\*)

Now, find the intersection point defined By the Ray Egn (1). In order to that, we will need to find &

Since the intersection point Pi is the Common Point By the Ray and theplane T. we have

n(nx,ny,nz), Normal Vector

has to be known,

a (ax, ay, az) is known on T.

Starting from the plane Egn (36).

n. (V-a) =0

where V= R,e,g.

 $n \cdot (v - \vec{n})$   $v = \vec{R} = 0$  (4)

 $|R - \overline{R}| = 0$   $|R - \overline{R}| + |R - \overline{R}|$   $|R - \overline{R}| + |R - \overline{R}|$   $|R - \overline{R}| + |R - \overline{R}|$   $|R - \overline{R}| + |R - \overline{R}|$ 

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\n. (P\_3-P\_1) = n. n- n. P\_1

n. 2- n. Pi 

 $=\frac{\overrightarrow{n\cdot(\overrightarrow{a-P_i})}}{\overrightarrow{n\cdot(\overrightarrow{P_s-P_i})}}...(5)$ 

Note Lis Not the intersection Pt. it allows us to use Ray Egn (1) to find the intersection.

P\_S
P\_S
P\_S
V

use Eqn(5) to find more than one intersection

where n= (0,0,0), Hence, for Coding λ= <u>- n.ρ.;</u> <u>n.(p.-ρ.)</u> =- hxxx+hyy+nzz; nx(x5-x1)+n,(y5-y;)+n2(25-2:) From the given Condition n (0,0,1), Therefore N= - 1/2. (25-21) =- 2/3-21  $=-\frac{110}{200-110}=-\frac{110}{90}=-\frac{11}{9}$ Now, back to the Ray Equation R=Pi+2(Ps-Pi)

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CMPEZYO APILT, ZZ
    R= (100,100,110) - 11 (-20-100,
                      110-lov, 200-110)
               =(100,100,10)-\frac{11}{9}(-120,10,90)
             =\left(\frac{1100\times120}{9}-\left(100-\frac{110}{9}\right),110-110\right)
              = \left(\frac{1/000 \times 1200 \times 110}{9}, \frac{10}{9}, \frac{10
please finish this calculation.
       Now, Goding Part. Same Code on github.
                                                                                                                                                                    A. Define Normal vector in for Xwyw plane
                                      world.X[47] = 0; world.Y[47] = 0; world.Z[47] = 1;
                                                                                                                                                                       b. Note the typedef stind "for Defining
                                                                                                                                                                                  30 Points.
                                     float X[UpperBD], Y[UpperBD], Z[UpperBD];
          41
                         } pworld;
                                                                                                                                              \lambda = \frac{\overrightarrow{N} \cdot (\overrightarrow{A} - \overrightarrow{P_1})}{(5)} \cdot \cdots \cdot (5)
           NOW, & Calculation. Egn (5)
                                                                                                                                                                                               hxxx+hyyx+nzzi
                                                                                                                                                                    5nv(x5-xi)+ny(y5-y;)+n2(25-2;)
                                    //-----<mark>lam</mark>bda <u>for</u> tersection pt on xw-yw plans
      171
                                    float temp = (world.X[47](world.X[46]-world.X[45])
      172
                                                                        +(world(Y[47])*(world.Y[46]-world.Y[45]))
      173
      174
                                                                        +(world(Z[47]*(world.Z[46]-world.Z[45]));
                                    float lambda = temp / ((world.X[47]*(world.X[45]-world.X[7]))
      175
                                                                                                        +(world.Y[47]*(world.Y[45]-world.Y[7]))
      176
                                                                                                        +(world.Z[47]*(world.Z[45]-world.Z[7])));
      177
      178
                                    float lambda_2 = temp / ((world.X[47]*(world.X[45]-world.X[6]))
                                                                                                               +(world.Y[47]*(world.Y[45]-world.Y[6]))
      180
                                                                                                               +(world.Z[47]*(world.Z[45]-world.Z[6])));
```

## (MOEato April 7,22 Note, Substitute 2 to Ray Equation to find the intersection point world.X[48] = world.X[45] + lambda\*(world.X[45] - world.X[7]); // Intersection pt p7 world.Y[48] = world.Y[45] + lambda\*(world.Y[45] - world.Y[7]); // Intersection pt p7 world.Z[48] = 0.0;186 world.X[49] = world.X[45] + lambda\_2\*(world.X[45] - world.X[6]); //intersection pt p6 world.Y[49] = world.Y[45] + lambda\_2\*(world.Y[45] - world.Y[6]); //intersection pt p6 マーアントン(キューアン) カリーリットン(リャーリン) マーマントン(マェーアン) Assignment in-Class Shows Tell. Implement Intersection Computation on LYC 1769, Show+ Tell' Demo in Class On April 11 (Monday) To Be Able to Display 37 Graphics On 20 Display Devics. Let's Define Transformation Pipeline. 1. Define World-Coordinate System. Right Hand Xw-Yw-Zw Syntam 3D Transformation Pipeline Technique Using EGA or VGA Card Z. Viewer Coordinate Syptem XV-M-50 Left-Hand System Step 2. Perspective Projection Step 1. World-to-viewer transform 3. Virtual $x_p = x_e \left(\frac{D}{z_e}\right)$ $-\sin\theta$ $\cos \theta$ Cancon is $-\cos\phi\cos\theta$ $-\cos\phi\sin\theta$

 $\sin \phi$ 

 $-\sin\phi\cos\theta$   $-\sin\phi\cos\theta$   $-\cos\phi$ 

(exeyez)

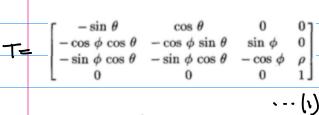
 $y_p = y_e$ 

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Example: Display Shadows on 20 Display Device.

Assume E(xe, ye, 7e) = (200, 200, 200) Physical meaning of Transformation Mutrix T.

Step. World To Viewer Transform.



O: Angle from the dash line on twy plane w.v.t positive xw-axis 4: Angle Between Zw & Ze.

A (rho): P= 1 x2+y2+7e -.. (z) distance from E to the origin o of XW-YW-ZW.

Suppose Etzogzugzwo) is given, Find wso, sind, cost, sind for T-matrix.

Everything is defined in the Would Goordinate System Xw-1w-Zw including a Virtual Camera.

+ (xe, ye, ze), Xe-ye-Ze Viewer

Coordinate System.

Given Ti(xiy: ti) in Xu-yw-Zu world Coordinate, Tepresent this point p: X-ye-Ze Coordinate System.

$$= \begin{bmatrix} -\sin\theta & \cos\theta & 0 & 0 \\ -\cos\phi\cos\theta & -\cos\phi\sin\theta & \sin\phi & 0 \\ -\sin\phi\cos\theta & -\sin\phi\cos\theta & -\cos\phi & \rho \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

CMPEDID ATIMINIZZ Draw A Line Passing through E Perpendicular to Xw/w. > Form an intersection point. Draw A line Passing through the intersection point on Xw-Ywplane on the plane and Perpendicular to Xw-axis. Draw Aline Presing E(xeye, Ze) Fig.4 E(xe,ye.ze) Terpendicular to Zw. axis 200 = J3/3 20/3 We can form a trimple on Xw-yw plane, as in Fig. 4, hence  $COSO = \frac{Xe}{\sqrt{X_{c}^{2}+y_{c}^{2}}} = \frac{ZOO}{2} = \frac{\sqrt{Z}}{2}$ 

Similarly, Sind= Ye Zoo = Jz Homework: Due April 18th (Marday)

Sind= 1 xe+ye = 200/2 \[ \frac{\frac{2}{xe+ye} + ye}{xe+ye+7e} = \frac{200\sqrt{2}}{200\sqrt{3}} \] = Jz.J3 = Nb

t (xe, ye, ze)

1. Draw Aworld Coordinate System Xw-yw-Zwaxis, with Xw Ted, yw Green, Zw Blue

(Marday)

2 Draw A cube, Size Length = 100, On to 20 Display Device, like bloods 10 unit Above Xw-yn plane. CO.
In other word Fi (100,100,110);

3. Draw a point light Source
Ps (-20,110, 200), And PayCast
to Connect Ps to Pri; use breen

4. Compute the Shadow point Pi,

Draw the intersection Print to link

Po - Pi - Pi

Note: Youmay want to Adjust the
TS Position, So this Pi (Intusection

Point) Can be visible on your Display

Step Z. Perspective Projection

$$x_p = x_e \left(\frac{D}{z_e}\right)$$

$$y_p = y_e \left(\frac{D}{z_e}\right)$$
(3)

Janishing Pt Prizvn