

Embedded Software

CMPE244

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Sept. 29 (Wed) 4:00-8:00pm.

Zoom Link To Be Used for the Entire Semester

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Grading Policy:

1st Projects & Assignment 30%

2nd mandatory Projects, $10\% \times 2 = 20\%$

1 Semester-Long Project 10%

2nd Midterm: 30%

3rd Final: 40%

Organization of the Course

1. CPU Architecture, memory map.

Special Purpose Registers for the init & config of Peripheral Controller. Firmware Development. (~3 weeks)

2. Kernel (O.S) Source Distribution

I.D.E (Integrated Development Environment), To be able to optimize kernel image, to be able to modify existing Device Drivers. to write your own Device Driver. (~3 weeks)

3. Integration & Development of O.S. kernel + Device Driver + Sensors/Actuators

Stepper Motor Drive

Sensors LSM303

P.I.D Controller.

Fourier Transform.

Web Server (GUI)

OpenCV, OpenGL

Introduction

1. Development Setup

Target Board

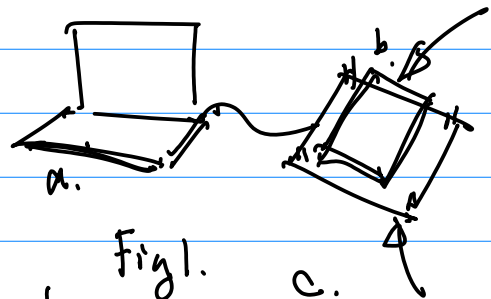


Fig 1.

Wire Wrapping Board

a. Host PC/Laptop, Linux Ubuntu 18.04

Virtual Box Installed, then install Linux on top of it.

b. Target platform (To Be determined)

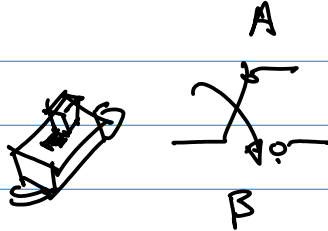
c. Wire Wrapping Board

~3 1/2" x 4" physical dimension through holes with metal coating.

(2) 4 mounting Holes @ the corners, 4 stand-offs (Legs)

(3) LED Red/Green Current $\leq 10\text{mA}$
Resistors $V_{LED} \approx 1.8\text{VDC}$
 $200 \sim 500\Omega$

(4) Toggle switch



2. OS Architecture

3. Selection & Evaluation of A Target platform

Linux D.S. Support

ARM (RISC — Reduced Instruction Set Computer)

Most Efficient Computation Density per Unit Power

Reduced Instruction Set

(Smaller collection of Machine Code Instructions)

→ Better Optimization of compiler

Forward Looking — Longer Life Cycle

User Space

Kernel space

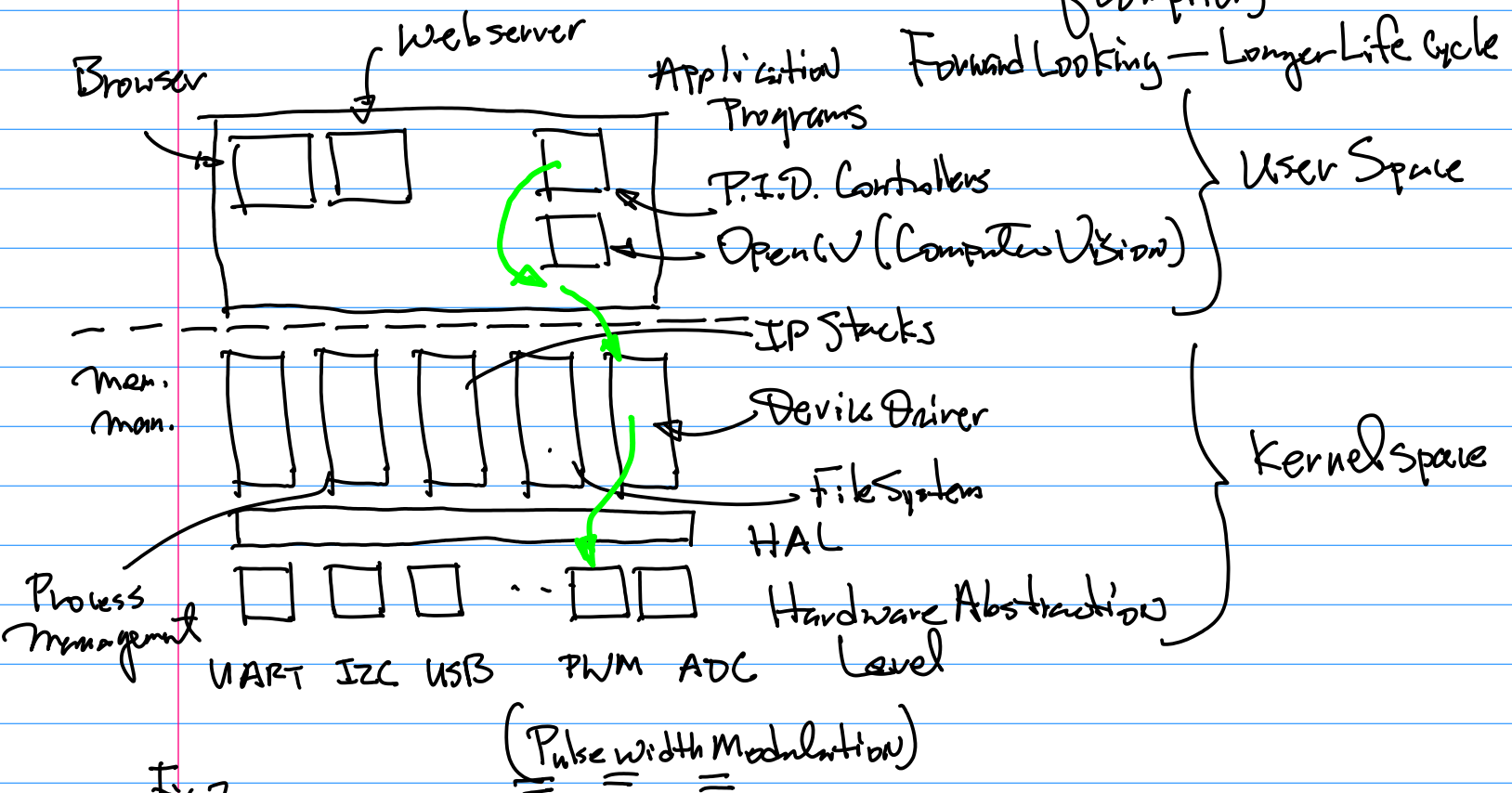


Fig. 2

(Pulse width Modulation)

1. NXP LPC17xx, 1769

Clock Rate: $\sim 200\text{MHz} - 400\text{MHz}$

No Linux

Ref: git ~ 2021F-107b- . .

Architecture well Documented.

Memory map well Documented

Example: Sch of LPC1769.

LPCXpresso	
QND	
VIN (4.5-5.5V)	
VB (battery supply)	
RESET_N	
P0.9	MOSI
P0.8	MISO
P0.7	CLK
P0.6	SSSEL
P0.0	TXD0/SDA
P0.1	RXD0/SL
P0.18	MOSI
P0.17	MISO
P0.15	TXD1/CLK
P0.16	RXD1/SSSEL
P0.23	AD0.0
P0.24	AD0.1
P0.25	AD0.2
P0.26	AD0.3/AOUT
P1.30	AD0.4
P1.31	AD0.5
P0.2	
P0.3	
P0.21	
P0.22	
P0.27	
P0.28	
P2.13	

(Serial Peripheral Interface)

(Serial Peripheral Interface)

UART3 Tx Transmission / Multiplexed
 UART3 Rx Receiving SDA:
 SPI0 / UART4 SCL:

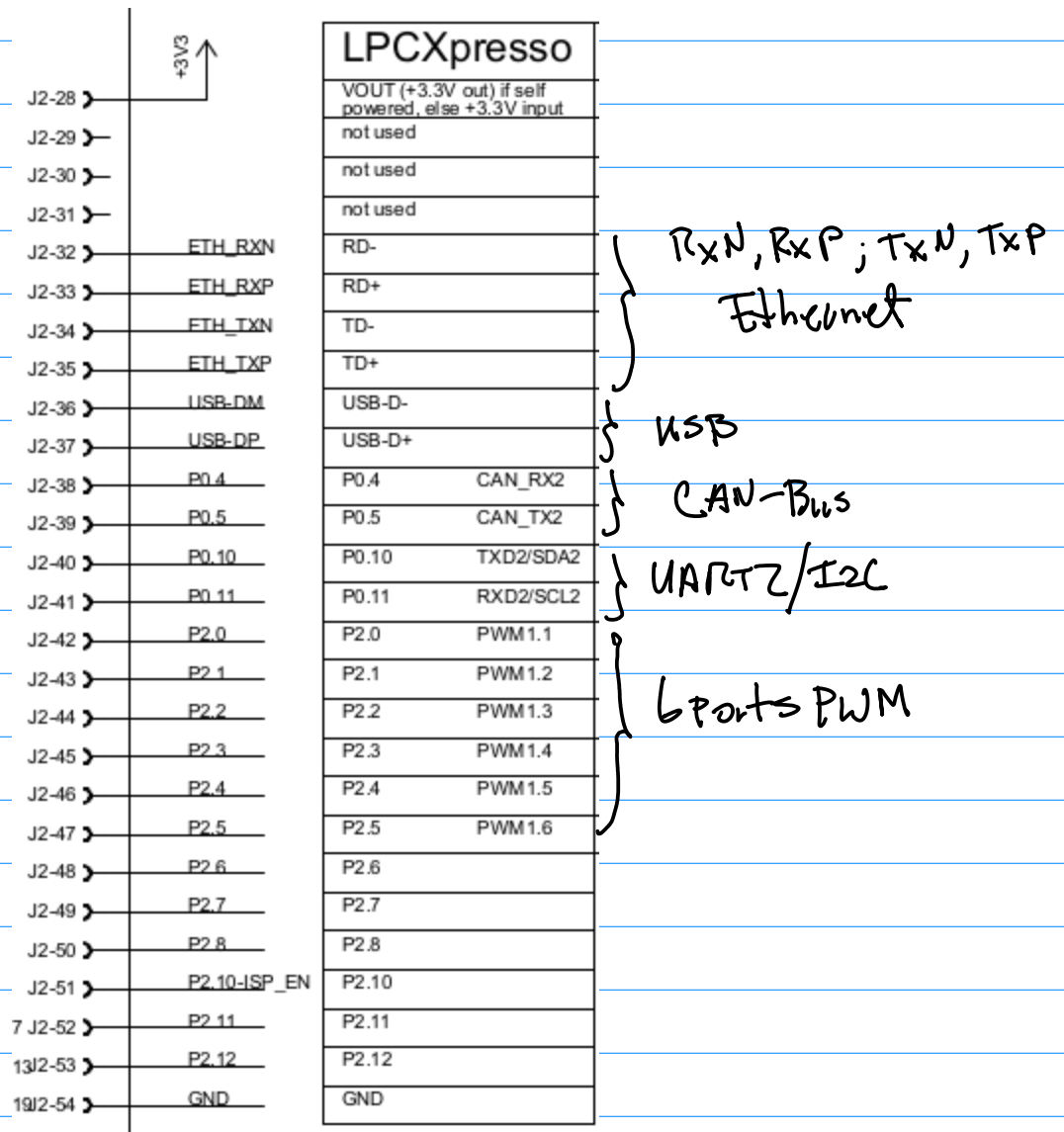
SP10/WART1

SDA: Serial Data

SCL: Serial CLK

6 ADC (AD - Analog to Digital Conversion) I2C

↳ GPP (GPIO: General Purpose Port I/O)



Optimal Target platform: FPGA. Future Electronics.

FPGA Igho2: RISC-V.

Superset of ARM Architecture

IP Core: Open Source. Supports RTOS

Limitations: No Unix/Linux O.S.

Smaller Gate Counts. → Less

Computational Capability.

Pie. Broadcom BCM

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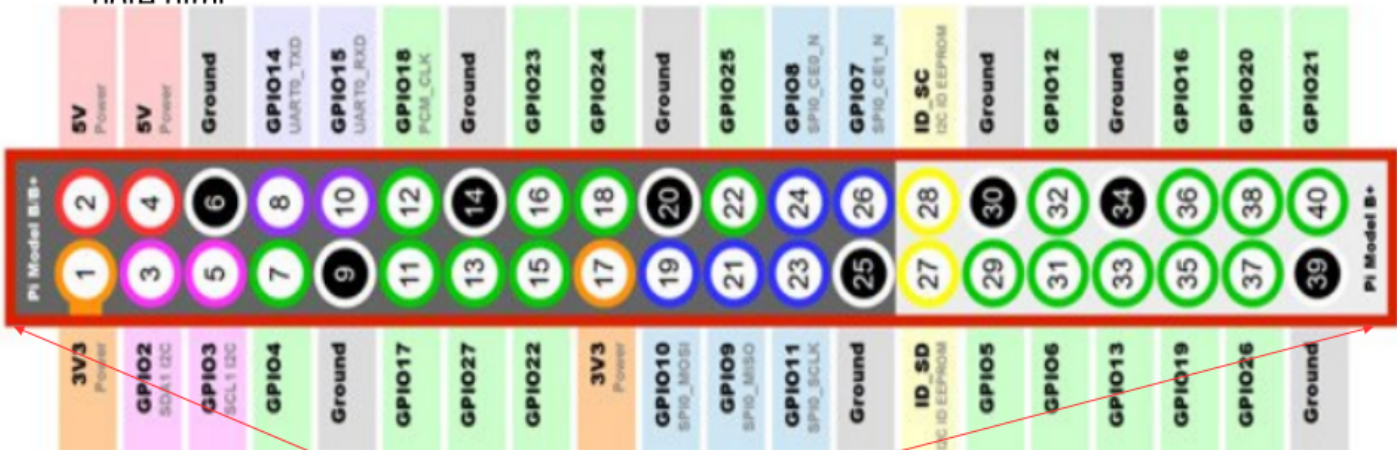
5

Features: Support Linux/Ubuntu.

Provides machine/Computer Vision Capability; OpenCV.
Yolo (You Only Look Once) → Deep Learning, No AOC

Pie-3 Version B GPIO Pins

<https://www.jameco.com/Jameco/workshop/circuitnotes/raspberry-pi-circuit-note.html>



Plus: CPU Datasheet

CPU Architecture

↓
Device
Driver
Development.

↙ memory map
Peripheral Controllers, G.E. (Graphics Engine)

Option: ARM-11 Samsung. CPU: S3C6410x

CPU Datasheet: Architecture Block Diagram — well Document
600-800MHz memory map, well Designed, documented

Support Linux, well Document/Sample code for Driver Development.

State-of-the-Art Feature: Graphics Processing Engine — GPU

LPC17xx, NO; FPGA RISC-V, NO; BCM-Pie G.E. yes

ARM-11. Video Codec, Marginal

Option: NVDA — Jetson TX2 6 CPUs + 256 GPU in a Single Package

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Supports Linux/Ubuntu, I/O Interface is limited; (LPC17xx has the Best I/O I/F Support); ~\$700 Dev. Kit. Well Documented Datasheet.

Sign up as a developer⁶ at nxp website

www.nxp.com

MCU Xpresso

Option: NVIDIA Jetson Nano. Ubuntu Linux Support.
Multiple Bus + 128 GPU

I/O (Limited)
[Datasheet — Not As Detailed as other platform]

Developer forum is very Active and it gives a good references.

Homework: 1st Form 2-4 person team

By Next week;

2nd Choose Target Platform

3rd Bring Wirewrapping Board/
Prototype Board to the Class
for show & Tell;

4th Sign up @ Nvidia website

as a developer → kernel
(Ubuntu)

Source Distribution

[Jetpack